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Application note

Using the high-density STM32F10xxx FSMC peripheral to drive external memories

Introduction

This application note describes how to use the High-density STM32F10xxx FSMC (flexible static memory controller) peripheral to drive a set of external memories. To that aim, it gives an overview of the STM32F10xxx FSMC controller. Then it provides memory interfacing examples that include the typical FSMC configuration, the timing computation method and the hardware connection.

This application note is based on memories mounted on the STM3210E-EVAL, which is the evaluation board for High-density STM32F10xxx devices. The used memories are a 16-bit asynchronous NOR Flash memory, an 8-bit NAND Flash memory and a 16-bit asynchronous SRAM.

The STM32F10xxx firmware library, the different memory drivers and examples of use for each of the memory types used in this application note, are available for download from the STMicroelectronics website: www.st.com/mcu.

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1 Overview of the STM32F10xxx flexible static memory controller

The flexible static memory controller (FSMC) is an external memory controller embedded in High-density STM32F10xxx devices. Using it, the STM32F10xxx microcontroller can interface with a variety of memories, including SRAM, NOR Flash and NAND Flash memories.

The FSMC contains two types of controller:

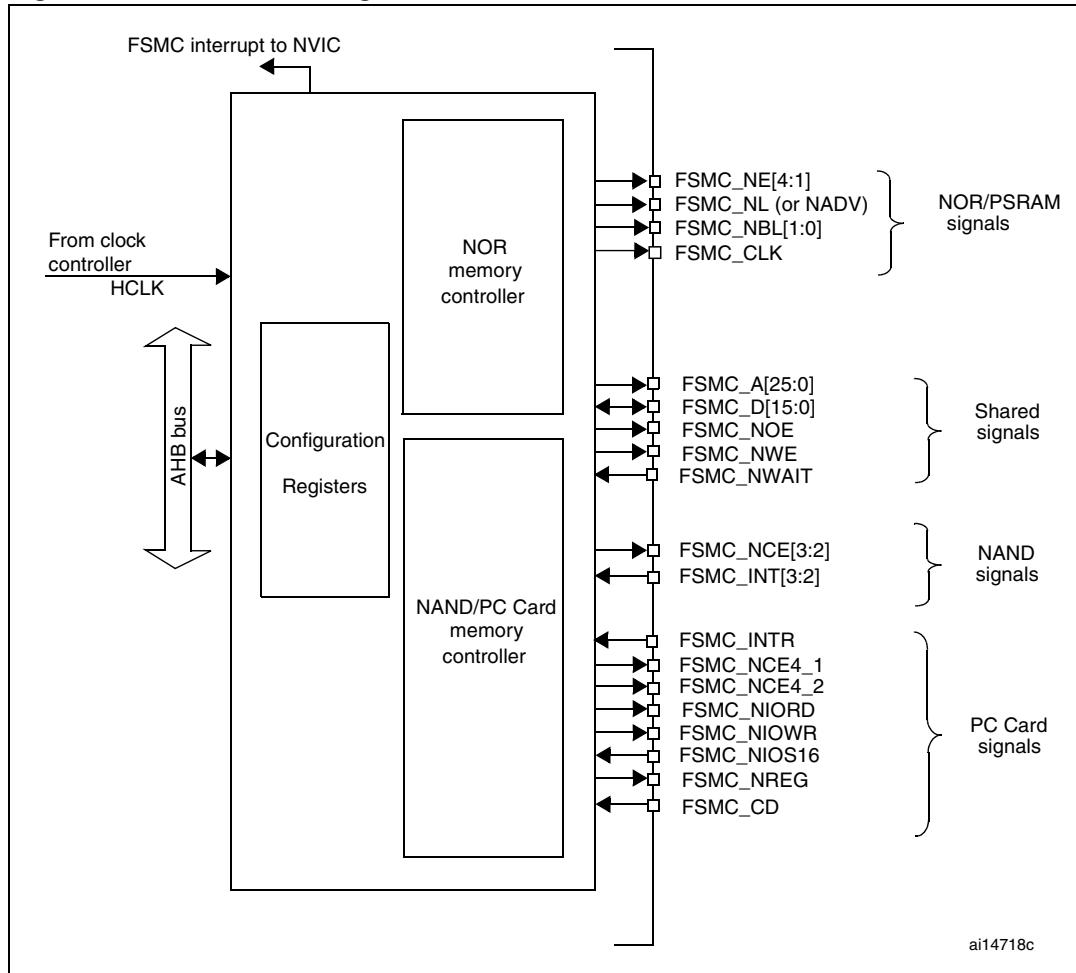
- a NOR Flash/SRAM controller to interface with NOR Flash memories, SRAMs and PSRAMs
- a NAND Flash/PC Card controller to interface with NAND Flash, PC Card, CF and CF+ memories

The controllers generate the appropriate signal timings to drive all these memories:

- 16 data lines to interface with 8-bit or 16-bit memory width
- 26 address lines to interface with up to 64 Mbytes memory size
- 5 independent memory Chip Select pins
- A set of control signals adapted for every type of memory:
 - to control read/ write operations
 - to actively communicate with memories which provide the Ready/Busy signals and the interrupt signals
 - to interface with the PC Card in all possible configurations: PC card memory, PC card I/O, true IDE

Figure 1 illustrates the FSMC block diagram.

Figure 1. FSMC block diagram



From the FSMC point of view, the external memory is divided into four fixed-size banks of 256 Mbytes each, as shown in [Figure 2](#):

- Bank 1 used by the NOR Flash/SRAM controller to address up to 4 memory devices. This bank is split into 4 regions with 4 dedicated Chip Select signals.
- Banks 2 and 3 used by the NAND Flash/PC Card controller to address NAND Flash devices.
- Bank 4 used by the NAND Flash/PC Card controller to address a PC Card device.

For each bank, the type of memory to be used is user-defined in the Configuration register.

Figure 2. FSMC memory banks

| Address | Banks | Supported memory type |
|--------------------------|---------------------|-----------------------|
| 6000 0000h 6FFF FFFFh | Bank 1 4 x 64 MB | NOR / PSRAM |
| 7000 0000h 7FFF FFFFh | Bank 2 4 x 64 MB | NAND Flash |
| 8000 0000h 8FFF FFFFh | Bank 3 4 x 64 MB | |
| 9000 0000h 9FFF FFFFh | Bank 4 4 x 64 MB | PC Card |

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2 Interfacing with a nonmultiplexed, asynchronous 16-bit NOR Flash memory

2.1 FSMC configuration

To control a NOR Flash memory, the FSMC provides the following possible features:

- Select the bank to be used to map the NOR Flash memory: there are 4 independent banks which can be used to interface with NOR Flash/SRAM/PSRAM memories, each bank has a separate Chip Select pin.
- Enable or disable the address/data multiplexing feature
- Select the memory type to be used: NOR Flash/SRAM/PSRAM
- Define the external memory databus width: 8/16 bits
- Enable or disable the burst access mode for synchronous NOR Flash memories
- Configure the use of the wait signal: enable/disable, polarity setting and timing configuration.
- Enable or disable the extended mode: this mode is used to access the memory with a different timing configuration for read and write operations.

As the NOR Flash/PSRAM controller can support asynchronous and synchronous memories, the user should select only the used parameters depending on the memory characteristics.

The FSMC also provides the possibility of programming several parameters to correctly interface with the external memory. Depending on the memory type, some parameters are not used.

In the case where an external asynchronous memory is used, the user has to compute and set the following parameters depending on the information in the memory datasheet:

- ADDSET: address setup time
- ADDHOLD: address hold time
- DATAST: data setup time
- ACCMOD: access mode

This parameter gives the FSMC the flexibility to access a wide variety of asynchronous static memories. There are four extended access modes that allow write access while reading the memory with different timings, if the memory supports this kind of feature.

When the extended mode is enabled, the FSMC_BTR register is used for read operations and the FSMC_BWR register is used for write operations.

In the case where a synchronous memory is used, the user has to compute and set the following parameters:

- CLKDIV: clock divide ratio
- DATLAT: data latency

Note that NOR Flash memory read operations can be synchronous if the memory supports this mode, while write operations usually remain asynchronous.

When programming a synchronous NOR Flash memory, the memory automatically switches between the synchronous and the asynchronous mode, so in this case, all parameters have to be set correctly.

Figure 3 and *Figure 4* show the different timings during a typical NOR Flash memory access.

Figure 3. Asynchronous NOR Flash read access timing

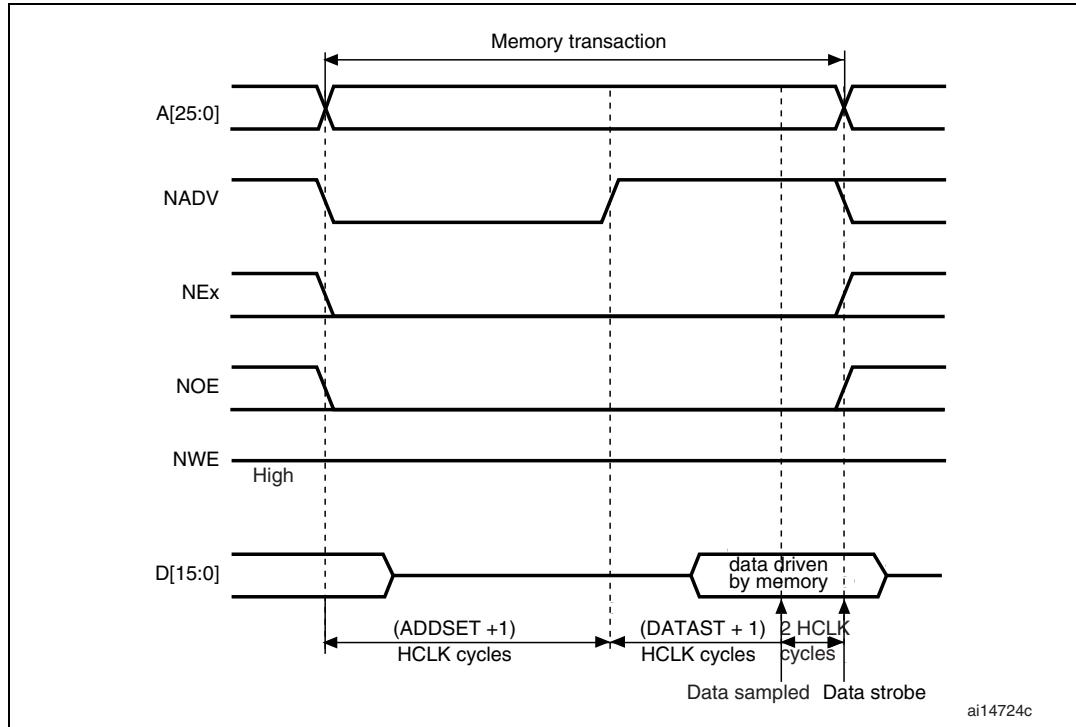
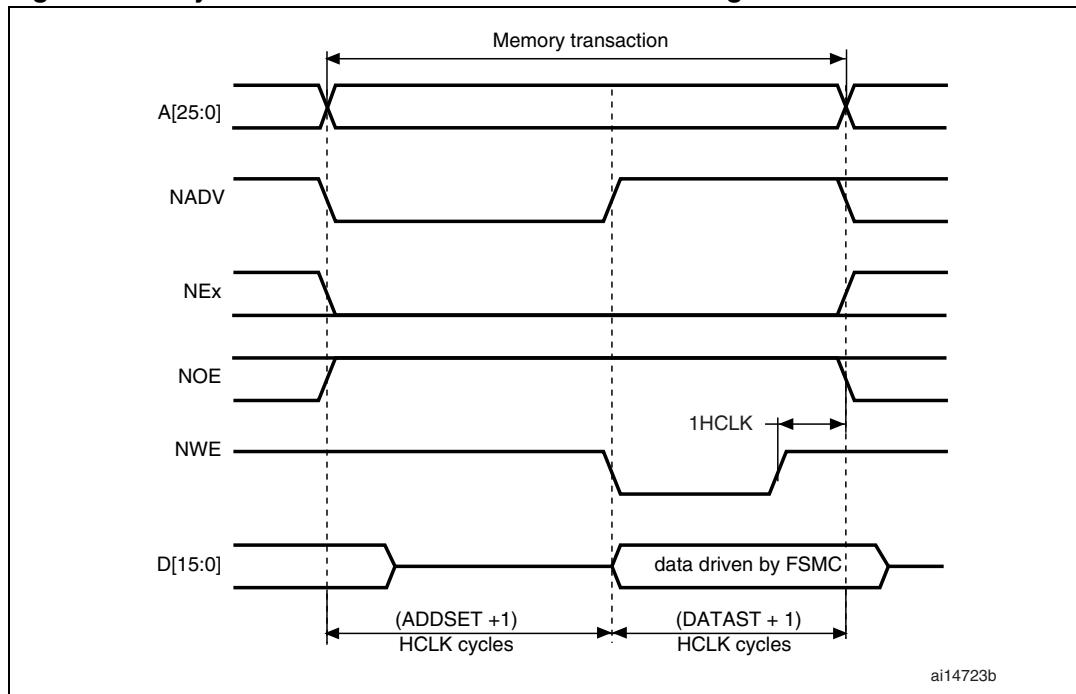


Figure 4. Asynchronous NOR Flash write access timing



2.1.1 Typical use of the FSMC to interface with a NOR Flash memory

The STM32F10xxx FSMC has four different banks of 64 Mbytes to support NOR Flash memories/PSRAMs and similar external memories.

The external memories share the address, data and control signals with the controller. Each external device is accessed by means of a unique Chip Select signal, but the FSMC performs only one access at a time to an external device.

Each bank is configured by means of dedicated registers. Configuration includes the different features and the timing parameters.

In this application note, the M29W128FL memory is used as a reference. The M29W128FL memory is a 16-bit, asynchronous, nonmultiplexed NOR Flash memory. Based on these data, the FSMC is configured as follows:

Bank 2 is selected to support the NOR Flash memory device:

- Bank 2 is enabled: BCR2_MBKEN bit set to '1'
- Memory type is NOR: BCR2_MTYP is set to '10' to select the NOR memory type
- Databus width is 16-bit: BCR2_MWID is set to '01' to select the 16-bit width
- It is a nonmultiplexed memory: BCR2_MUXEN is reset.

All remaining parameters must be kept cleared.

2.2 Timing computation

As described above, for asynchronous NOR Flash-like memories, there are different possible access protocols. The first step is therefore to define the kind of protocol that should be used with the specific memory. The choice depends on the different control signals and the behavior of the memory during read and write transactions.

In the case of an asynchronous NOR Flash memory, the Mode 2 protocol will be used. If the used memory can provide an NADV signal, the Extended ModeB protocol should be used.

With the M29W129FL, we will use the Mode2 protocol. We will therefore not use any extended mode and the timings will be the same for read and write operations. In this case, the NOR memory controller needs three timing parameters: ADDSET, DATAST and ADDHOLD.

These parameters are computed according to the NOR Flash memory characteristics and according to the HCLK clock of the STM32F10xxx.

Based on the NOR Flash memory access timings illustrated in [Figure 3](#) and [Figure 4](#), the following equations are found:

The write or read access time is the time between the falling edge and the rising edge of the memory Chip Select signal. This time is computed as a function of the FSMC timing parameter:

$$\text{Write/Read access time} = ((\text{ADDSET} + 1) + (\text{DATAST} + 1)) \times \text{HCLK}$$

In write operations, the DATAST parameter is measured between the falling edge and the rising edge of the write signal as follows:

$$\text{Write Enable signal low to high} = t_{WP} = \text{DATAST} \times \text{HCLK}$$

To have a correct configuration of the FSMC timings, the timings have to take into account:

- the maximum read/write access time
- the different internal FSMC delays
- the different internal memory delays

Hence, we have:

$$((ADDSET + 1) + (DATAST + 1)) \times HCLK = \max(t_{WC}, t_{RC})$$

$$DATAST \times HCLK = t_{WP}$$

DATAST must verify:

$$DATAST = (t_{AVQV} + t_{su(Data_NE)} + t_{v(A_NE)}) / HCLK - ADDSET - 4$$

Table 1 gives the meanings and values of the NOR Flash memory parameters.

Table 1. NOR Flash memory timings

| Symbols | Parameter | Value | | Unit |
|------------|---|-------------|-------------|------|
| | | M29W128xx70 | S29GL128P90 | |
| t_{WC} | Address valid to next address valid for write operation | 70 | 90 | ns |
| t_{RC} | Address valid to next address valid for read access | 70 | 90 | ns |
| t_{WP} | Write Enable low to Write Enable high | 45 | 35 | ns |
| t_{AVQV} | Address valid to output valid | 70 | 90 | ns |

Table 2. STM32F10xxx parameters

| Symbols | Parameter | Value | Unit |
|-----------------------------------|---|------------------|------|
| HCLK | Internal AHB clock frequency | 72 | MHz |
| $t_{su(Data_NE)} + t_{v(A_NE)}$ | Data to FSMC_NEx high setup time + FSMC_NEx low to FSMC_A valid | $2T_{HCLK} + 32$ | ns |

Using the above described formulas, the memory timings (in *Table 1*) and the STM32F10xxx parameters (in *Table 2*), we have:

- For the M29W128 NOR Flash memory, the timings are:
 - Address setup time: 0x0
 - Address hold time: 0x0
 - Data setup time: 0x6
- For the S29GL128P NOR Flash memory, the timings are:
 - C address setup time: 0x2
 - C address hold time: 0x0
 - C data setup time: 0x5

Note:

The S29GL128P NOR Flash memory timings are also valid for the M29W128 NOR Flash memory.

2.3 Hardware connection

Table 3 gives the correspondence between the NOR Flash memory pins and the FSMC pins and shows the GPIO configuration for each FSMC pin.

In case of an 8-bit NOR Flash memory, the data/address bus is 8-bit wide and D8-D15 should not be connected to the FSMC.

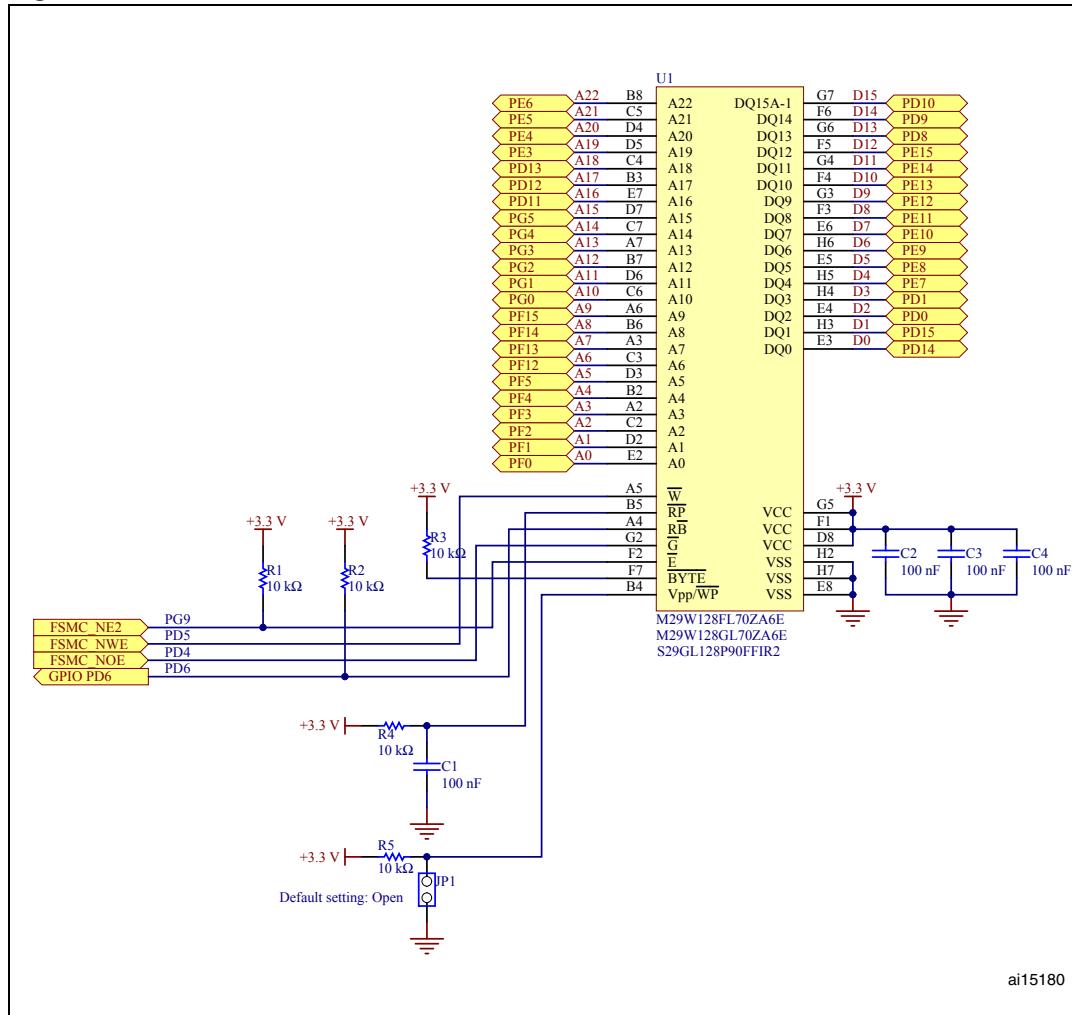
In case of a synchronous memory, the FSMC_CLK pin should be connected to the memory clock pin.

Table 3. M29W128FL signal to FSMC pin correspondence

| Memory signals | FSMC signals | Pin / Port assignment | Pin / Port configuration | Signal description |
|----------------|--------------|-----------------------------|--------------------------|--------------------|
| A0-A22 | A0-A22 | Port F/Port G/Port E/Port D | AF push-pull | Address A0-A22 |
| DQ0-DQ7 | D0-D7 | Port D/Port E | AF push-pull | Data D0-D7 |
| DQ8-DQ14 | D8-D14 | Port D/Port E | AF push-pull | Data D8-D14 |
| DQ15A-1 | D15 | PD10 | AF push-pull | Data D15 |
| \bar{E} | NE2 | PG9 | AF push-pull | Chip Enable |
| \bar{G} | NOE | PD4 | AF push-pull | Output Enable |
| \bar{W} | NWE | PD5 | AF push-pull | Write Enable |

Figure 5 shows a typical connection between an STM32F10xxx microcontroller and the M29W128FL NOR Flash memory. It is an abstract from the schematic of the STM3210E-EVAL (STM32F10xxx evaluation board).

Figure 5. 16-bit NOR Flash: M29W128FL/GL connection to STM32F10xxx



Note:

The GPIO PD6 pin is used to provide a Ready/Busy output signal for NOR Flash memories (in this case the application needs to poll on the state of this pin to guarantee correct operation).

In the example shown below, this pin is not used with the M29W128FL and M29W128GL NOR Flash memories. It is however required for the S29GL128P NOR Flash memory.

A firmware example is available within the STM32F10xxx firmware library provided in the **NOR** directory at the path: *STM32F10xFWLib\FWLib\examples\FSMC\NOR*.

The main goal of this example is to provide the basics of how to use the FSMC firmware library and the associated NOR Flash memory driver to perform erase/read/write operations on the M29W128FL, M29W128GL or S29GL128P NOR Flash memories mounted on the STM3210E-EVAL board.

For the FSMC timings, the FSMC NOR Flash firmware driver uses the highest timing values, that is those of the S29GL128P NOR Flash memory. In this way, the firware driver is able to support all the NOR Flash memories available on the STM3210E-EVAL.

2.4 Code execution from an external NOR Flash memory

The High-density STM32F10xxx devices feature up to 512 KB of internal Flash memory, which is enough for most applications. For systems that need greater Flash memory capacity, an attractive alternative is to use external NOR Flash memory.

This section describes how to use a NOR Flash memory to execute user code. For this, two steps are mandatory:

- Load the user code into the external NOR memory:

This operation requires a special configuration of the development toolchain: in the linker file, you have to specify the NOR Flash memory start address (or any other address) from where the user code is to be programmed.

A specific loader for NOR Flash memories is also required.

- Execute the user code:

Once the user code has been loaded into the NOR Flash memory, a specific program should be loaded into the internal Flash memory in order to configure the FSMC, to jump and execute the user code (from the NOR Flash memory).

A typical example of such an application is provided within the STM32F10xxx firmware library at the following path:

STM32F10xFWLib\FWLib\examples\FSMC\NOR_CodeExecute.

Copy the binary of the GPIO IOToggle example into the NOR Flash memory mounted on the STM3210E-EVAL board, then execute it.

For more details on how to use this example with your development toolchain, please refer to the readme files provided within this directory.

3 Interfacing with a nonmultiplexed, asynchronous 16-bit SRAM

3.1 FSMC configuration

SRAMs and NOR Flash memories share the same FSMC banks. The protocol to be used depends on the selected memory type.

To control an SRAM, the FSMC provides the following possible features:

- Enable or disable the address/data multiplexing feature
- Select the memory type to be used: NOR/SRAM/PSRAM
- Define the external memory databus width: 8/16 bits
- Enable or disable the extended mode: this mode is used to access the memory with a different timing configuration for read and write operations.

Like for NOR Flash memories, the user has to compute and set the following parameters as a function of the information in the SRAM datasheet:

ADDSET: address setup time

ADDHOLD: address hold time

DATASET: data setup time

Figure 6 and *Figure 7* show the different timings for a typical SRAM access.

Figure 6. SRAM asynchronous read access timing

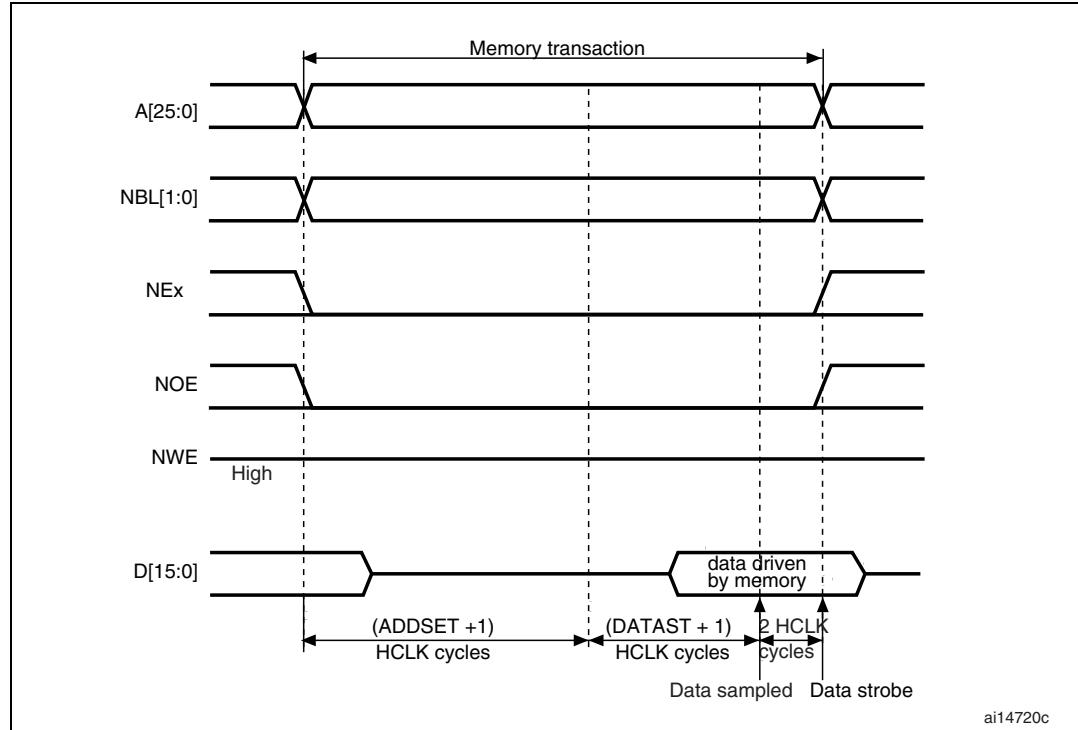
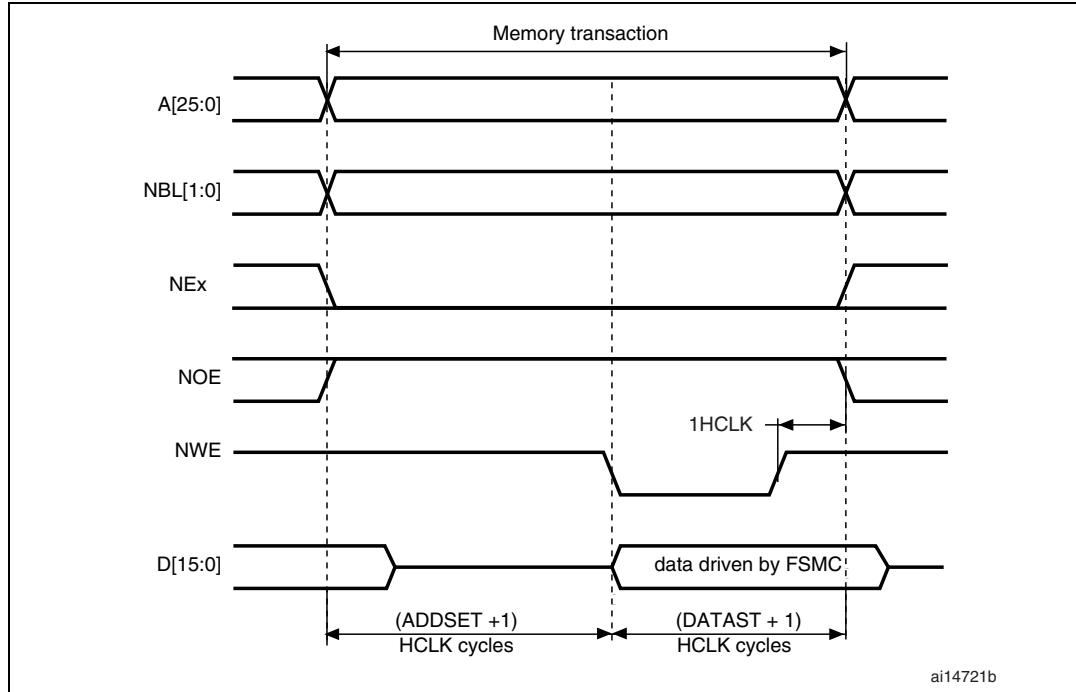


Figure 7. SRAM asynchronous write access timing

3.1.1

Typical use of the FSMC to interface with an SRAM

In this application note, the IS61WV51216BLL memory is used as the reference.

The IS61WV51216BLL memory is a nonmultiplexed, asynchronous, 16-bit memory. Bank3 is selected to support the SRAM device. Based on these data, the FSMC is configured as follows:

- Bank3 is enabled: BCR3_MBKEN bit set to '1'
- Memory type is SRAM: BCR3_MTYP is set to '00' to select the SRAM memory type
- Databus width is 16 bits: BCR3_MWID is set to '01' to select the 16-bit width
- The memory is nonmultiplexed: BCR3_MUXEN is reset

All remaining parameters must be kept cleared.

3.2

Timing computation

The SRAM shares the same banks and configuration register as the NOR Flash memory. As a result, the timing computation method is the same as described in detail in the NOR Flash section ([Section 2.2: Timing computation on page 10](#)).

The FSMC is configured on the basis of the SRAM access timings illustrated in [Figure 6](#) and [Figure 7](#), and taking into account the following:

- the maximum read/write access time
- the different internal FSMC delays
- the different internal memory delays

Hence the following equations:

$$((ADDSET + 1) + (DATAST + 1)) \times HCLK = \max(t_{WC}, t_{RC})$$

$$DATAST \times HCLK = t_{PWE1}$$

DATAST must verify:

$$DATAST = (t_{AA} + t_{su(Data_NE)} + t_{v(A_NE)}) / HCLK - ADDSET - 4$$

Table 4 gives the meanings and values of the SRAM parameters.

Table 4. SRAM timings

| Symbols | Parameter | Value | Unit |
|------------|------------------------------|-------|------|
| t_{WC} | Write cycle time | 12 | ns |
| t_{RC} | Read cycle time | 12 | ns |
| t_{PWE1} | Write Enable low pulse width | 8 | ns |
| t_{AA} | Address access time | 12 | ns |

Using the above described formulas, the memory timings (in *Table 4*) and the STM32F10xxx parameters (in *Table 2*), we have:

- Address setup time: 0x0
- Address hold time: 0x0
- Data setup time: 0x2

3.3 Hardware connection

Table 5 gives the correspondence between SRAM pins and FSMC pins and shows the GPIO configuration for each FSMC pin.

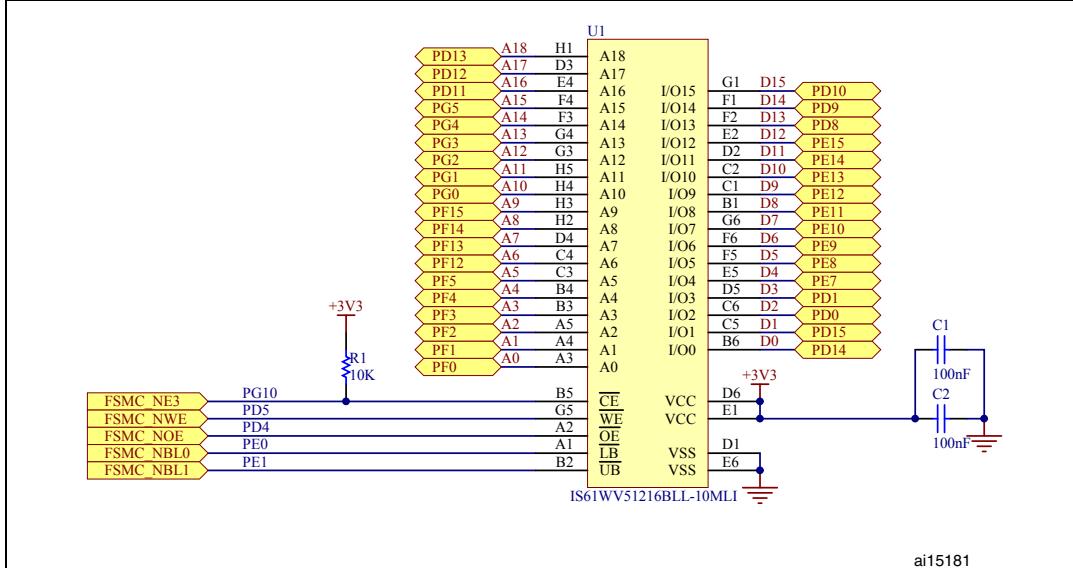
In case of an 8-bit SRAM, the data/address bus is 8 bits wide and D8-D15 should not be connected to the FSMC.

Table 5. IS61WV51216BLL signal to FSMC pin correspondence

| Memory signals | FSMC signals | Pin / Port assignment | Pin / Port configuration | Signal description |
|----------------|--------------|-----------------------------|--------------------------|--------------------|
| A0-A18 | A0-A18 | Port F/Port G/Port E/Port D | AF push-pull | Address A0-A18 |
| I/O0-I/O15 | D0-D15 | Port D/Port E | AF push-pull | Data D0-D15 |
| CE | NE3 | PG10 | AF push-pull | Chip Enable |
| OE | NOE | PD4 | AF push-pull | Output Enable |
| WE | NWE | PD5 | AF push-pull | Write Enable |
| LB | NBL0 | PE0 | AF push-pull | Lower byte control |
| UB | NBL1 | PE1 | AF push-pull | Upper byte control |

Figure 8 shows a typical connection between an STM32F10xxx microcontroller and an IS61WV51216BLL SRAM. It is an abstract from the schematic of the STM32F10xxx evaluation board: STM3210E-EVAL.

Figure 8. 16-bit SRAM: IS61WV51216BLL connection to STM32F10xxx



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A firmware example is available within the STM32F10xxx firmware library provided in the **SRAM** directory at the path: *STM32F10xFWLib\FWLib\examples\FSMC\SRAM*.

The main goal of this example is to provide the basics of how to use the FSMC firmware library and the associate SRAM driver to perform read/write operations on the IS61WV51216BLL SRAM memory mounted on the STM3210E-EVAL board.

3.4

Using the external SRAM as a data memory

The external SRAM mapped on the FSMC can be used as a data memory in several applications where a large R/W data memory is required.

The configuration steps required to use the external SRAM as a data memory depend on the toolchain and hardware being used.

A typical example of such an application is provided within the STM32F10xxx firmware library at the following path:

STM32F10xFWLib\FWLib\examples\FSMC\ SRAM_DataMemory.

This example shows how to use the external SRAM mounted on the STM3210E-EVAL board as a program data memory and, the internal SRAM as stack. For more details on how to use this example with your development toolchain, please refer to the readme file provided within this directory.

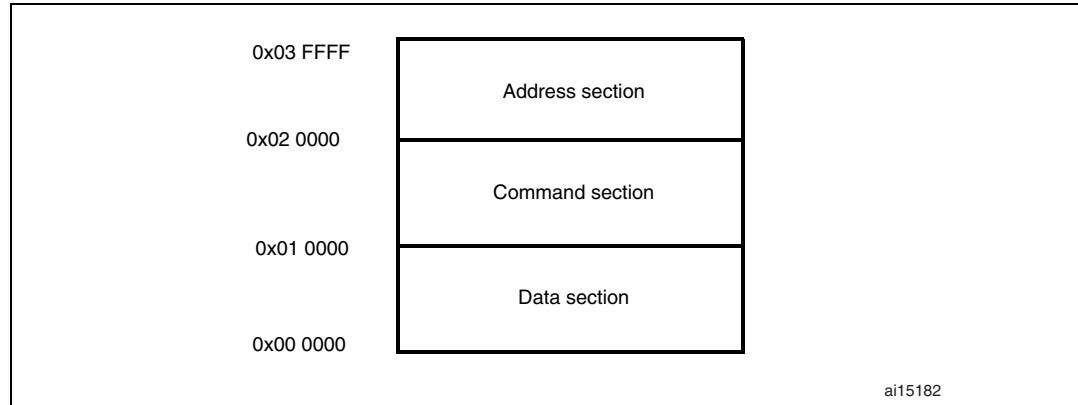
4 Interfacing with an 8-bit NAND Flash memory

NAND Flash memories are accessed in accordance with a specific protocol. To write to or read from the NAND Flash memory, it is necessary to:

1. Send a command to the NAND Flash memory
2. Send the address to write to or read from
3. Read or write the data

The FSMC NAND banks are divided into three sections to allow the user to easily program the NAND Flash memory: data section, address section, and command section.

Figure 9. FSMC NAND bank sections



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In fact, the three sections are the representation of the real NAND Flash memory. By writing to any location in the command section, the user writes the command to the NAND Flash memory. By writing to any location in the address section, the user specifies the address of the read or write operation. Depending on the structure of the used NAND Flash memory, four or five operations are required to write the address. By writing to or reading from any location in the data section, the data are written to or read from the address previously sent to the address section.

4.1 FSMC configuration

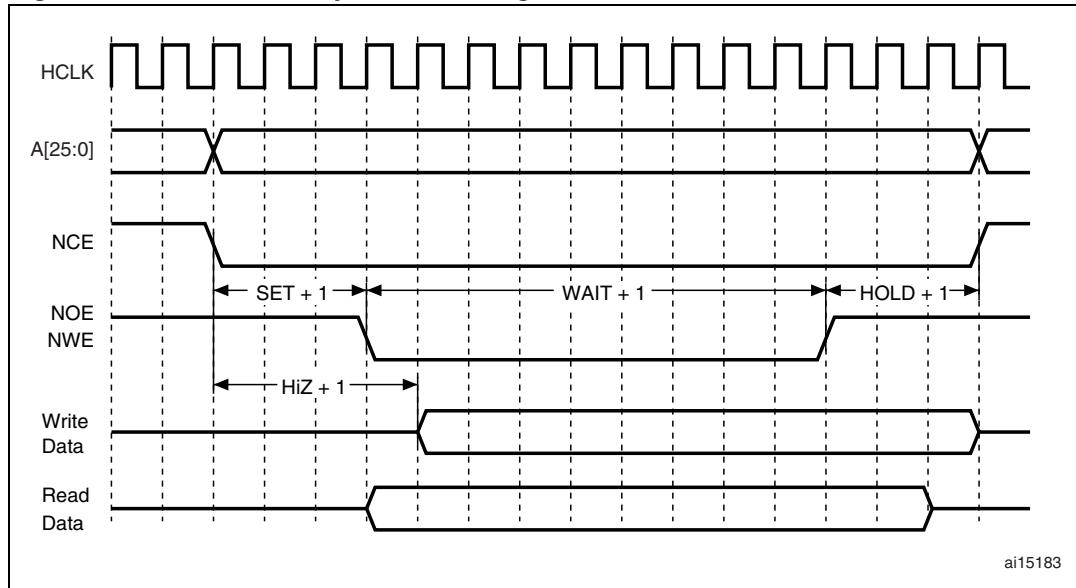
To control a NAND Flash memory, the FSMC provides the following possible features:

- Enable or disable the use of the memory Ready/ $\overline{\text{Busy}}$ signal as the wait input for the FSMC.
- Enable or disable the use of the memory Ready/ $\overline{\text{Busy}}$ signal as the interrupt source for the FSMC: the interrupt can be generated with three possible configurations:
 - on the rising edge of the Ready/ $\overline{\text{Busy}}$ signal: when the memory has just completed an operation and the new status is ready.
 - on the falling edge of the Ready/ $\overline{\text{Busy}}$ signal: when the memory starts the new operation
 - on the high level of the Ready/ $\overline{\text{Busy}}$ signal: when the memory is ready.
- Select the NAND Flash databus width: 8- or 16-bit width.
- Enable or disable the ECC computation logic.
- Specify the ECC page size: it can be 256, 512, 1024, 2048, 4096 or 8192 bytes.

The FSMC also provides the possibility of programming the timings for the different NAND Flash sections separately: common section and attribute section. The timings are the following:

- **Setup time:** it is the time (in HCLK) required to set up the address before the command assertion. That is, It is the time from address valid to the start of the read or write operation.
- **Wait time:** It is the time (in HCLK) required to assert the command. That is, it is the time taken by the NOE and NWE signals to become deasserted.
- **Hold time:** it is the time (in HCLK) during which the address is held after the command deassertion. That is, it is the time between the deassertion of the NOE and NWE signals and the end of the operation cycle.
- **Databus HiZ time:** it is only valid for write operations and corresponds to the time (in HCLK) during which the databus is kept in the high-impedance state after the start of a write access. That is, it is the time from address valid to databus driven.

Figure 10 shows the different timings for a typical NAND Flash memory access.

Figure 10. NAND memory access timing

4.1.1 Typical use of the FSMC to interface with a NAND memory

The STM32F10xxx FSMC NAND Flash controller can configure Bank2 or Bank3 to support NAND Flash memories.

The banks are selected using the Chip Select signals, as each bank is associated with a specific Chip Select.

To enable communication with the NAND Flash devices, the FSMC NAND Flash controller has to be initialized to meet the characteristics of the NAND Flash devices: features, timings, data width, etc.

In this application note, the Numonyx NAND512W3A is used as the reference. This memory has the same access protocol as many other NAND Flash memories on today's market.

NAND512W3A characteristics:

- NAND interface: x8 bus width, multiplexed address/ data
- Page size: x8 device: (512 + 16 spare) bytes
- Page Read/Program timings:
 - Random access: 12 μ s (3 V)/15 μ s (1.8 V) (max)
 - Sequential access: 30 ns (3 V)/50 ns (1.8 V) (min)
 - Page Program time: 200 μ s (typ)

Bank2 is selected to support the NAND Flash device. Based on these data, the FSMC is configured as follows:

- Bank2 is enabled: PCR2_PBKEN bit set to ‘1’
- Memory type is NAND Flash: PCR2_PTYP is set to ‘1’ to select the NAND Flash memory type.
- Databus width is 8 bit: PCR2_PVID is set to ‘00’ to select 8-bit width.
- ECC page size is 512 bytes: PCR2_ECCPS is set to ‘001’ to set the ECC computation page size to 512 bytes.
- ECC hardware calculation on/off as needed: PCR2_ECCEN is set or reset accordingly.
- Wait feature may or not be enabled depending on the user’s application: PCR2_PWAITEN is set or reset as needed.

The Ready/Busy memory signal can be connected to the FSMC_NWAIT pin, and in this case the Wait feature must be used to manage the NAND Flash operations.

When using the NAND Flash memory with the wait feature enabled, the controller waits for the NAND Flash to be ready to become active before starting a new access. While waiting, the controller maintains the NCE signal active (low).

Generally, the Ready/Busy signal is an open-drain output. To connect this signal to the STM32F10xxx microcontroller, the corresponding pin must be configured as input pull-up.

The Ready/Busy signal can be used as an interrupt source for the FSMC and, in this case, the CPU can perform other tasks during NAND Flash operations.

Three FSMC configurations make it possible to use this signal as an interrupt. For that purpose, the IREN, IFEN or ILEN bits in the SR2 register are used to select the rising edge, the falling edge or the high level of the NAND Flash Ready/Busy signal.

4.2 Timing computation

Besides configuring the different features that are to be used with the NAND Flash memory, the user has to initialize the controller to meet the memory timings.

As described in [Section 4.1](#), the FSMC is able to program four different timings for the common space and the attribute space independently: **Setup time**, **Wait time**, **Hold time** and **Databus HiZ time**.

These parameters are computed according to the NAND Flash memory characteristics and the STM32F10xxx HCLK clock.

Based on the NAND Flash memory access timings shown in [Figure 4](#), the following equations are found:

The write or read access time is the time between the falling edge and the rising edge of the NAND Flash memory Chip Select signal. It is computed as a function of the FSMC timing parameter:

$$\text{Write/Read access} = ((\text{SET} + 1) + (\text{WAIT} + 1) + (\text{HOLD} + 1)) \times \text{HCLK}$$

The Wait time is measured between the falling edge and the rising edge of the Write/Read Enable signal:

$$\text{Write/Read Enable signal low to high} = (\text{WAIT} + 1) \times \text{HCLK}$$

For write access, the HiZ parameter is measured between the Chip Select setup time and the data setup time:

$$\text{Chip Select setup time} - \text{data setup time} = \text{HiZ} \times \text{HCLK}$$

The Hold time parameter can be deduced from the first equation. In fact, the datasheet of the NAND Flash memory gives the timing between Chip Enable low and Write Enable high during a write transaction. The Hold time is calculated from it as follows:

$$\text{Chip Select low to Write Enable high} = ((\text{SET} + 1) + (\text{WAIT} + 1)) \times \text{HCLK}$$

To make sure of the correct timing configuration of the FSMC, the timings have to take into consideration:

- the maximum read/write access time
- the different internal FSMC delays
- the different internal memory delays

Hence, we have the following equations:

$$(\text{WAIT} + 1) \times \text{HCLK} = \max(t_{WP}, t_{RP})$$

$$((\text{SET} + 1) + (\text{WAIT} + 1)) \times \text{HCLK} = \max(t_{CS}, t_{ALS}, t_{CLS})$$

$$\text{HOLD} = \max(t_{CH}, t_{ALH}, t_{CLH})/\text{HCLK}$$

The equations below should also be verified:

$$((\text{SET} + 1) + (\text{WAIT} + 1) + (\text{HOLD} + 1)) \times \text{HCLK} = \max(t_{RC}, t_{WC})$$

$$\text{HiZ} = (\max(t_{CS}, t_{ALS}, t_{CLS}) - t_{DS})/\text{HCLK} - 1$$

Considering the different timings in the FSMC and the memory, the equations become:

- WAIT must verify:

$$(\text{WAIT} + 1 + \text{SET} + 1) = ((t_{CEA} + t_{su(Data_NE)} + t_{v(A_NE)})/\text{HCLK})$$

$$\text{WAIT} = ((t_{CEA} + t_{su(Data_NE)} + t_{v(A_NE)})/\text{HCLK}) - \text{SET} - 2$$

- SET must verify:

$$(\text{SET} + 1) = \max((t_{CS}, t_{ALS}, t_{CLS}) - \max(t_{WP}, t_{RP}))/\text{HCLK} - 1$$

$$\text{SET} = (\max(t_{CS}, t_{ALS}, t_{CLS}) - \max(t_{WP}, t_{RP}))/\text{HCLK} - 2$$

Table 6 gives the meanings and values of the NAND Flash memory parameters.

Table 6. NAND Flash memory timings

| Symbol | Parameter | Value | Unit |
|-----------|---------------------------------------|-------|------|
| t_{CEA} | Chip Enable low to output valid | 35 | ns |
| t_{WP} | Write Enable low to Write Enable high | 15 | ns |
| t_{RP} | Read Enable low to Read Enable high | 15 | ns |
| t_{CS} | Chip Enable low to Write Enable high | 20 | ns |
| t_{ALS} | AL setup time | 15 | ns |
| t_{CLS} | CL Setup time | 15 | ns |
| t_{CH} | Ē Hold time | 5 | ns |
| t_{ALH} | AL Hold time | 5 | ns |
| t_{CLH} | CL Hold time | 5 | ns |

Using the above described formulas, the memory timings (in [Table 6](#)) and the STM32F10xxx parameters (in [Table 2](#)), we have:

- Setup time: 0x1
- Wait time: 0x3
- Hold time: 0x2
- HiZ time: 0x1

4.3 Hardware connection

[Table 7](#) gives the correspondence between the NAND Flash memory pins and the FSMC pins and shows the GPIO configuration for each FSMC pin.

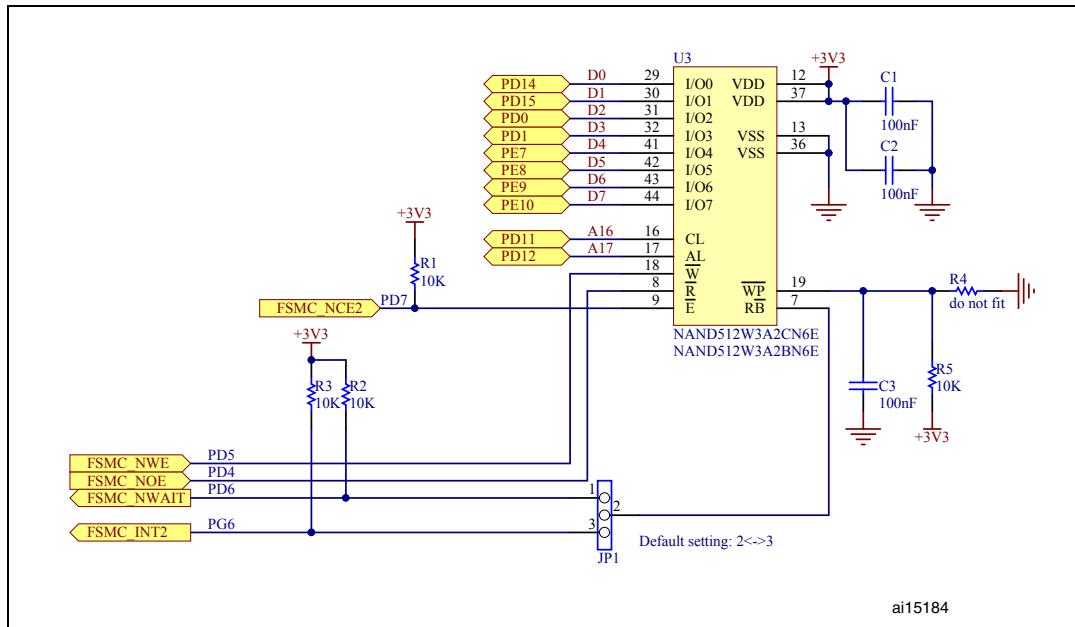
In case of a 16-bit NAND Flash memory, the data/address bus is 16 bits wide and the remaining FSMC data/address bus are used.

Table 7. NAND512W3A signal to FSMC pin correspondence

| Memory signals | FSMC signals | Pin / Port assignment | Pin / Port configuration | Signal description |
|----------------|--------------|-----------------------|--------------------------|----------------------|
| AL | ALE/A17 | PD11 | AF push-pull | Address Latch Enable |
| CL | CLE/A16 | PD12 | AF push-pull | Command Latch Enable |
| I/O0-I/O7 | D0-D7 | Port D/Port E | AF push-pull | Data D0-D7 |
| \bar{E} | NCE2 | PD7 | AF push-pull | Chip Enable |
| \bar{R} | NOE | PD4 | AF push-pull | Output Enable |
| \bar{W} | NWE | PD5 | AF push-pull | Write Enable |
| \bar{RB} | NWAIT/INT2 | PD6/PG6 | Input pull-up | Ready/Busy signal |

[Figure 11](#) illustrates a typical connection between the STM32F10xxx microcontroller and the NAND512W3A memory. It is an abstract from the schematic of the STM32F10xxx evaluation board: STM3210E-EVAL.

Figure 11. 8-bit NAND Flash: NAND512W3A2C/NAND512W3A2B connection to STM32F10xxx



A firmware example is available within the STM32F10xxx firmware library provided in the **NAND** directory at the path: *STM32F10xFWLib\FWLib\examples\FSMC\NAND*.

The main goal of this example is to provide the basics of how to use the FSMC firmware library and the associated NAND Flash memory driver to perform erase/read/write operations using the FSMC wait feature on the NAND512W3A2 memory mounted on the STM3210E-EVAL board.

4.4 Error correction code computation

4.4.1 Error correction code (ECC) computation overview

The FSMC NAND Flash controller includes two pieces of error correction code computation hardware, one for each NAND Flash memory block.

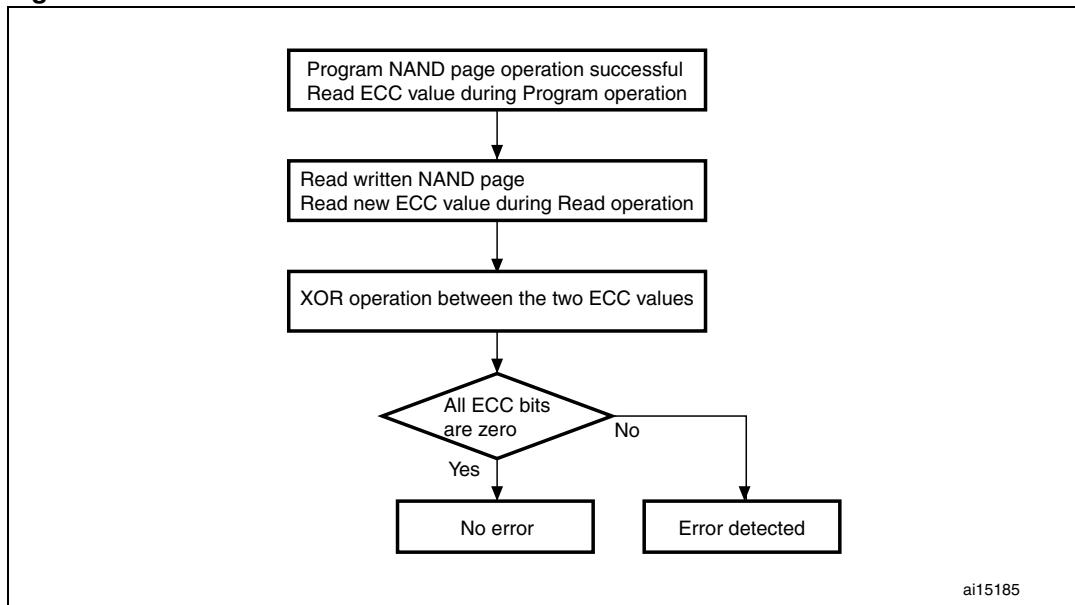
The ECC can be performed for page sizes of 256, 512, 1024, 2048, 4096 or 8192 bytes, depending on the ECC page size configured by the user. Depending on the configured page size, the ECC code will be 22, 24, 26, 28, 30 or 32 bits.

To even improve the error coverage, the user can read/write the NAND Flash page with a reduced ECC page size. This is possible when starting and stopping the ECC computation after the desired number of bytes to check. In this case, the ECC code is only calculated for the bytes written and read.

The error correction code algorithm implemented in the FSMC can perform 1-bit and 2-bit error detection per page read from or written to the NAND Flash memory. It is based on the Hamming algorithm and consists in calculating the row and column parity.

4.4.2 Error detection

Figure 12. Error detection flowchart



When an error occurs during the write operation, this error is either correctable or uncorrectable depending on the ECC XOR operation:

- Case of a correctable error
The ECC XOR operation contains 11-bit data at 1. And each pair parity is 0x10 or 0x01.
- Case of an ECC error
The ECC XOR operation contains only one bit at 1.
- Case of an uncorrectable error
The ECC XOR operation is random data. In this case the page data cannot be corrected.

Based on the flowchart shown in [Figure 12](#), the correction software is easy to implement.

The first step consists in detecting whether an error occurred during the write operation. If that was the case, the second step consists in determining if the error is correctable or not. If it is correctable, then the third step consists in correcting the error.

The error correction is based on the second ECC generated after the read operation. The error location can be identified from this code. Usually, the following data are extracted from the ECC:

P1024, P512, P256, P128, P64, P32, P16, P8, P4, P2, P1, where Px are the line and column parity.

In case of an 8-bit memory, P4, P2, P1 define the error bit position. And P1024, P512, P256, P128, P64, P32, P16, P8 define the error byte position.

5 STM32F10xxx FSMC configuration in 100-pin packages

The FSMC is present in devices delivered in both 144-pin and 100-pin packages. For devices in 100-pin packages, however, only some FSMC banks can be used because not all pins are available.

5.1 Interfacing the FSMC with a NAND Flash memory

In devices that come in 100-pin packages, only Bank2 can be used to interface the FSMC with an 8-/16-bit NAND Flash memory. This is because the NCE3 pin is not available in these packages.

Likewise, no interrupt can be used because the two interrupt pins INT2 and INT3 are not available in 100-pin packages.

Table 8 shows how to connect an 8-/16-bit NAND Flash memory to the FSMC peripheral of devices delivered in 100-pin packages.

Table 8. NAND Flash memory connection to the FSMC

| 8-/16-bit NAND memory pins | FSMC pins | 100-pin package |
|----------------------------|-----------------|-----------------|
| \bar{E} | NCE2/NCE3 | NCE2 |
| \bar{R} | NOE | NOE |
| \bar{W} | NWE | NWE |
| AL | A17 | A17 |
| CL | A16 | A16 |
| R/\bar{B} | NWAIT/INT2/INT3 | NWAIT |
| I/O0-I/O7 | D0-D7 | D0-D7 |
| I/O8-I/O15 | D8-D15 | D8-D15 |

5.2 Interfacing the FSMC with a NOR Flash memory

In devices that come in 100-pin packages, only Bank 1 (NOR/PSRAM 1) can be used to interface with a NOR Flash memory. This is because the NE2, NE3 and NE4 pins are not available in these packages.

Likewise, the A0-A15 pins are not available, so the NOR Flash controller should be used in multiplexed mode to use the databus for both address and data.

Table 9 shows how to connect a NOR Flash memory to the FSMC peripheral of devices delivered in 100-pin packages.

Table 9. NOR Flash memory connection to the FSMC

| 8-/16-bit NOR pins | FSMC pins | 100-pin package |
|--------------------|-----------------|-----------------|
| A0-A15 | A0-A15 | DA0-DA15 |
| A16-A23 | A16-A23 | A16-A23 |
| \overline{W} | NWE | NWE |
| \overline{E} | NE1/NE2/NE3/NE4 | NE1 |
| \overline{G} | NOE | NOE |
| DQ0-DQ14 | D0-D14 | D0-D14 |
| DQ15A-1 | D15 | D15 |

6 Revision history

Table 10. Document revision history

| Date | Revision | Changes |
|-------------|----------|---|
| 22-Jul-2008 | 1 | Initial release. |
| 19-Sep-2008 | 2 | <p>Cellular RAM, OneNAND and COSMORAM references removed. NWAIT signal removed from Figure 3: Asynchronous NOR Flash read access timing, Figure 4: Asynchronous NOR Flash write access timing, Figure 5: 16-bit NOR Flash: M29W128FL/GL connection to STM32F10xxx, Figure 6: SRAM asynchronous read access timing and Figure 7: SRAM asynchronous write access timing.</p> <p>Note modified in Section 2.3: Hardware connection. Table 9: NOR Flash memory connection to the FSMC modified.</p> <p>Note added to Section 2.2: Timing computation.</p> <p>Small text changes.</p> |
| 07-Apr-2009 | 3 | <p>Figure 1: FSMC block diagram corrected. $t_{su}(\text{Data_NE})$ and $t_{v(A_NE)}$ rows removed and $t_{su}(\text{Data_NE}) + t_{v(A_NE)}$ value modified in Table 2: STM32F10xxx parameters.</p> <p>Note: on page 11 modified. Data setup time modified in Section 2.2: Timing computation and Section 3.2: Timing computation. Small text change in Section 4.1.1: Typical use of the FSMC to interface with a NAND memory.</p> <p>Small text changes.</p> |

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