

# 有限元方法 2025 秋冬作业六

曾申昊 3220100701 \*

电子科学与技术 2202, 浙江大学

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## 1. Morley 有限元的分析与编程

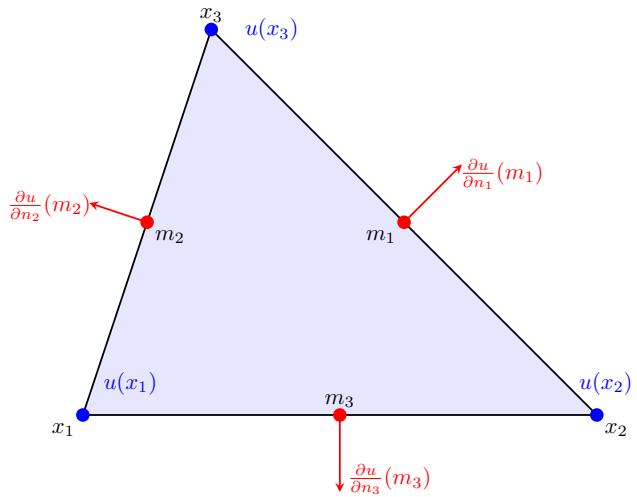


图 1: Morley 单元示意图

- (a) Morley 元  $(\mathcal{T}, \mathcal{P}_2, \mathcal{N}_M)$  的自由度为 6 个, 包括三角形单元的三个顶点处的函数值  $u(\mathbf{x}_i)$  以及三个边中点处的法向导数  $\frac{\partial u}{\partial n_i}(\mathbf{m}_i)$ , 如图 ?? 所示。定义 Morley 元的基函数  $\{\phi_i\}_{i=1}^6$  满足

$$\begin{cases} \phi_i(\mathbf{x}_j) = \delta_{ij} & j = 1, 2, 3 \\ \frac{\partial \phi_i}{\partial n_j}(\mathbf{m}_j) = 0 & j = 1, 2, 3 \end{cases} \quad i = 1, 2, 3 \quad (1)$$

$$\begin{cases} \phi_{i+3}(\mathbf{x}_j) = 0 & j = 1, 2, 3 \\ \frac{\partial \phi_{i+3}}{\partial n_j}(\mathbf{m}_j) = \delta_{ij} & j = 1, 2, 3 \end{cases} \quad i = 1, 2, 3 \quad (2)$$

于是 Morley 元插值  $I_T$  可以表示为

$$I_T(u) = \sum_{i=1}^3 u(\mathbf{x}_i) \phi_i + \sum_{i=1}^3 \frac{\partial u}{\partial n_i}(\mathbf{m}_i) \phi_{i+3} \quad (3)$$

\* 邮箱: 3097714673@qq.com 或 3220100701@zju.edu.cn

(b) 下面的证明中我们先观察单位元上的  $u(x)$

$$\begin{cases} u(\mathbf{x}_i) = u(\mathbf{x}) + (\mathbf{x}_i - \mathbf{x})^T \nabla u(\mathbf{x}) + \frac{1}{2} (\mathbf{x}_i - \mathbf{x})^T \nabla^2 u(\mathbf{x}) (\mathbf{x}_i - \mathbf{x}) + R(\mathbf{x}_i) \\ R(\mathbf{x}_i) = \frac{1}{2} \int_0^1 g'''(t; \mathbf{x}_i) (1-t)^2 dt \\ g'''(t; \mathbf{x}_i) = \sum_{|\alpha|=3} \frac{\partial^3 u}{\partial x^\alpha} (\mathbf{x} + t(\mathbf{x}_i - \mathbf{x})) (\mathbf{x}_i - \mathbf{x})^\alpha \end{cases} \quad (4)$$

$$\begin{cases} \nabla u(\mathbf{m}_i) = \nabla u(\mathbf{x}) + \nabla^2 u(\mathbf{x}) (\mathbf{m}_i - \mathbf{x}) + \nabla R(\mathbf{m}_i) \\ \frac{\partial u}{\partial n_i}(\mathbf{m}_i) = \mathbf{n}_i^T \nabla u(\mathbf{x}) + \mathbf{n}_i^T \nabla^2 u(\mathbf{x}) (\mathbf{m}_i - \mathbf{x}) + \mathbf{n}_i^T \nabla R(\mathbf{m}_i) \end{cases} \quad (5)$$

代入插值算子表达式，整理得到

$$\begin{aligned} I_T(u) &= \sum_{i=1}^3 u(\mathbf{x}_i) \phi_i + \sum_{i=1}^3 \frac{\partial u}{\partial n_i}(\mathbf{m}_i) \phi_{i+3} \\ &= u(x) \left( \sum_{i=1}^3 \phi_i \right) + \nabla u(\mathbf{x}) \cdot \left( \sum_{i=1}^3 (\mathbf{x}_i - \mathbf{x}) \phi_i + \sum_{i=1}^3 \mathbf{n}_i \phi_{i+3} \right) \\ &\quad + \frac{1}{2} \nabla^2 u(\mathbf{x}) : \left( \sum_{i=1}^3 (\mathbf{x}_i - \mathbf{x}) (\mathbf{x}_i - \mathbf{x})^T \phi_i + \sum_{i=1}^3 \mathbf{n}_i (\mathbf{m}_i - \mathbf{x})^T \phi_{i+3} \right) \\ &\quad + \sum_{i=1}^3 R(\mathbf{x}_i) \phi_i + \sum_{i=1}^3 \mathbf{n}_i^T \nabla R(\mathbf{m}_i) \phi_{i+3} \\ &= u(x) + \sum_{i=1}^3 R(\mathbf{x}_i) \phi_i + \sum_{i=1}^3 \mathbf{n}_i^T \nabla R(\mathbf{m}_i) \phi_{i+3} \end{aligned} \quad (6)$$

下面可以计算  $|u - I_T u|_{H^2(T)}$  我们可以验证等式

$$\begin{aligned} |\nabla^2 u - \nabla^2(I_T u)| &= \left| \nabla^2 \left( \sum_{i=1}^3 R(\mathbf{x}_i) \phi_i + \sum_{i=1}^3 \mathbf{n}_i^T \nabla R(\mathbf{m}_i) \phi_{i+3} \right) \right| \\ &= \left| \sum_{i=1}^3 R(\mathbf{x}_i) \nabla^2 \phi_i + \sum_{i=1}^3 \mathbf{n}_i^T \nabla R(\mathbf{m}_i) \nabla^2 \phi_{i+3} \right| \end{aligned} \quad (7)$$

然后我们可以对误差进行估计

$$\begin{aligned} |\nabla^2 u - \nabla^2(I_T u)| &\leq \sum_{i=1}^3 |R(\mathbf{x}_i) \nabla^2 \phi_i| + \sum_{i=1}^3 |\mathbf{n}_i^T \nabla R(\mathbf{m}_i) \nabla^2 \phi_{i+3}| \\ &\leq \tilde{C}_1 \sum_{i=1}^3 \left| h_T^3 \nabla^3 u \cdot \frac{1}{h_T^2} \right| + \tilde{C}_2 \sum_{i=1}^3 \left| h_T \cdot h_T^2 \nabla^3 u \cdot \frac{1}{h_T^2} \right| \\ &\leq \tilde{C} h_T |\nabla^3 u| \end{aligned} \quad (8)$$

两边平方并积分可得结论。

(c) 令  $\phi_i = a\lambda_1^2 + b\lambda_2^2 + c\lambda_3^2 + d\lambda_1\lambda_2 + e\lambda_1\lambda_3 + f\lambda_2\lambda_3$ 。以  $\phi_1$  为例进行计算， $\phi_2$  和  $\phi_3$  类似。

$$\begin{cases} \phi_1(\mathbf{x}_j) = \delta_{1j} & j = 1, 2, 3 \\ \frac{\partial \phi_1}{\partial n_j}(\mathbf{m}_j) = 0 & j = 1, 2, 3 \end{cases} \quad (9)$$

由前三个方程可设  $\phi_1 = \lambda_1^2 + d\lambda_1\lambda_2 + e\lambda_1\lambda_3 + f\lambda_2\lambda_3$ ，并且要记得

$$\begin{cases} \nabla \phi_1 = 2\lambda_1 \nabla \lambda_1 + d(\lambda_1 \nabla \lambda_2 + \lambda_2 \nabla \lambda_1) + e(\lambda_1 \nabla \lambda_3 + \lambda_3 \nabla \lambda_1) + f(\lambda_2 \nabla \lambda_3 + \lambda_3 \nabla \lambda_2) \\ \frac{\partial \phi_1}{\partial n_j}(\mathbf{m}_j) = \mathbf{n}_j \cdot \nabla \phi_1(\mathbf{m}_j) & j = 1, 2, 3 \end{cases} \quad (10)$$

$$\begin{cases} \nabla \lambda_i = -\frac{\mathbf{n}_i}{d_i} & i = 1, 2, 3 \\ \nabla \lambda_1 + \nabla \lambda_2 + \nabla \lambda_3 = 0 \end{cases} \quad (11)$$

代入后三个方程进行计算

$$\begin{cases} \mathbf{n}_1 \cdot [d(0.5\nabla \lambda_1) + e(0.5\nabla \lambda_1) + f(0.5\nabla \lambda_3 + 0.5\nabla \lambda_2)] = 0 \\ \mathbf{n}_2 \cdot [\nabla \lambda_1 + d(0.5\nabla \lambda_2) + e(0.5\nabla \lambda_3 + 0.5\nabla \lambda_1) + f(0.5\nabla \lambda_2)] = 0 \\ \mathbf{n}_3 \cdot [\nabla \lambda_1 + d(0.5\nabla \lambda_2 + 0.5\nabla \lambda_1) + e(0.5\nabla \lambda_3) + f(0.5\nabla \lambda_3)] = 0 \end{cases} \quad (12)$$

解得

$$\begin{cases} d = -\frac{d_2}{d_1} \mathbf{n}_2 \cdot \mathbf{n}_1 = -d_2^2 \nabla \lambda_2 \cdot \nabla \lambda_1 \\ e = -\frac{d_3}{d_1} \mathbf{n}_3 \cdot \mathbf{n}_1 = -d_3^2 \nabla \lambda_3 \cdot \nabla \lambda_1 \\ f = -\left(\frac{d_2}{d_1} \mathbf{n}_2 + \frac{d_3}{d_1} \mathbf{n}_3\right) \cdot \mathbf{n}_1 = -(d_2^2 \nabla \lambda_2 + d_3^2 \nabla \lambda_3) \cdot \nabla \lambda_1 \end{cases} \quad (13)$$

以  $\phi_4$  为例进行计算,  $\phi_5$  和  $\phi_6$  类似。

$$\begin{cases} \phi_4(\mathbf{x}_j) = 0 & j = 1, 2, 3 \\ \frac{\partial \phi_4}{\partial n_j}(\mathbf{m}_j) = \delta_{1j} & j = 1, 2, 3 \end{cases} \quad (14)$$

由前三个方程可设  $\phi_4 = d\lambda_1\lambda_2 + e\lambda_1\lambda_3 + f\lambda_2\lambda_3$  代入后三个方程进行计算

$$\begin{cases} \mathbf{n}_1 \cdot [d(0.5\nabla \lambda_1) + e(0.5\nabla \lambda_1) + f(0.5\nabla \lambda_3 + 0.5\nabla \lambda_2)] = 1 \\ \mathbf{n}_2 \cdot [d(0.5\nabla \lambda_2) + e(0.5\nabla \lambda_3 + 0.5\nabla \lambda_1) + f(0.5\nabla \lambda_2)] = 0 \\ \mathbf{n}_3 \cdot [d(0.5\nabla \lambda_2 + 0.5\nabla \lambda_1) + e(0.5\nabla \lambda_3) + f(0.5\nabla \lambda_3)] = 0 \end{cases} \quad (15)$$

解得  $d = e = -d_1$  和  $f = 0$ 。

(d) 这里选取如下的  $f$  和对应的解析解

$$\begin{cases} f(x, y) = 24(x^2(1-x)^2 + y^2(1-y)^2) + 8(1-6x+6x^2)(1-6y+6y^2) \\ u(x, y) = x^2(1-x)^2y^2(1-y)^2 \end{cases} \quad (16)$$

数值解图像如图所示 (不正确, 误差估计没有做)

## 2. Nabla 算子的相关结论

(a) 用 Einstein 求和约定容易得到

$$\begin{aligned} \nabla \cdot (\nabla \times \vec{u}) &= \partial_i(\epsilon_{ijk}\partial_j u_k) \\ &= \partial_j(\epsilon_{ijk}\partial_i u_k) \\ &= -\partial_i(\epsilon_{ijk}\partial_j u_k) = -\nabla \cdot (\nabla \times \vec{u}) \end{aligned} \quad (17)$$

$$\begin{aligned} \nabla \times (\nabla v) &= \epsilon_{ijk}\partial_j(\partial_k v)e_i \\ &= \epsilon_{ijk}\partial_k(\partial_j v)e_i \\ &= -\epsilon_{ijk}\partial_j(\partial_k v)e_i = -\nabla \times (\nabla v) \end{aligned} \quad (18)$$

可得恒等式成立。

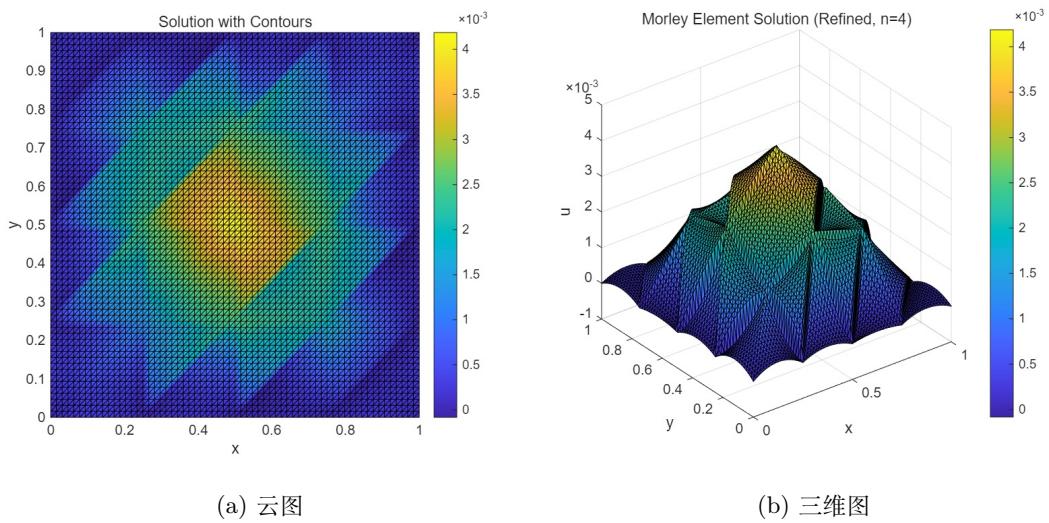


图 2:  $h = 0.25$  时有限元解的图像

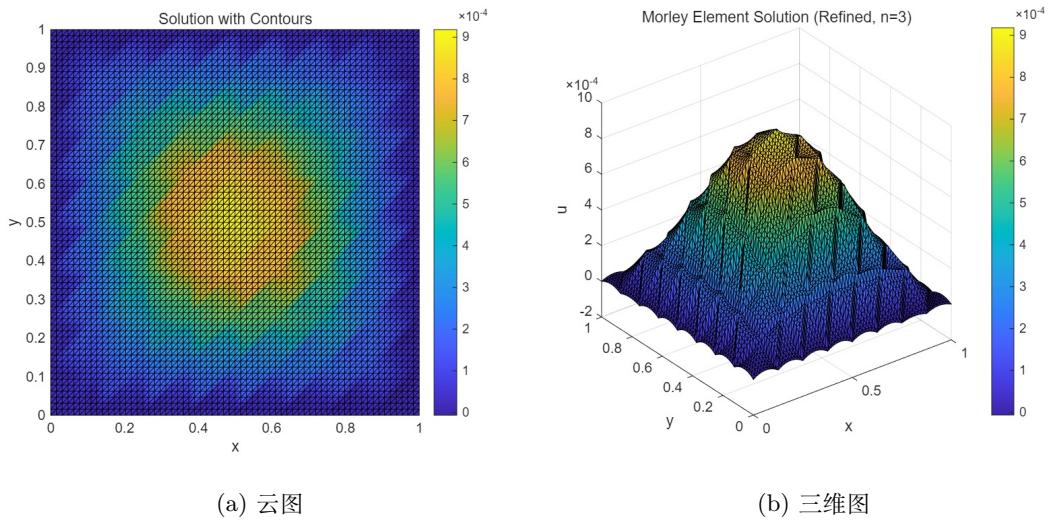


图 3:  $h = 0.125$  时有限元解的图像

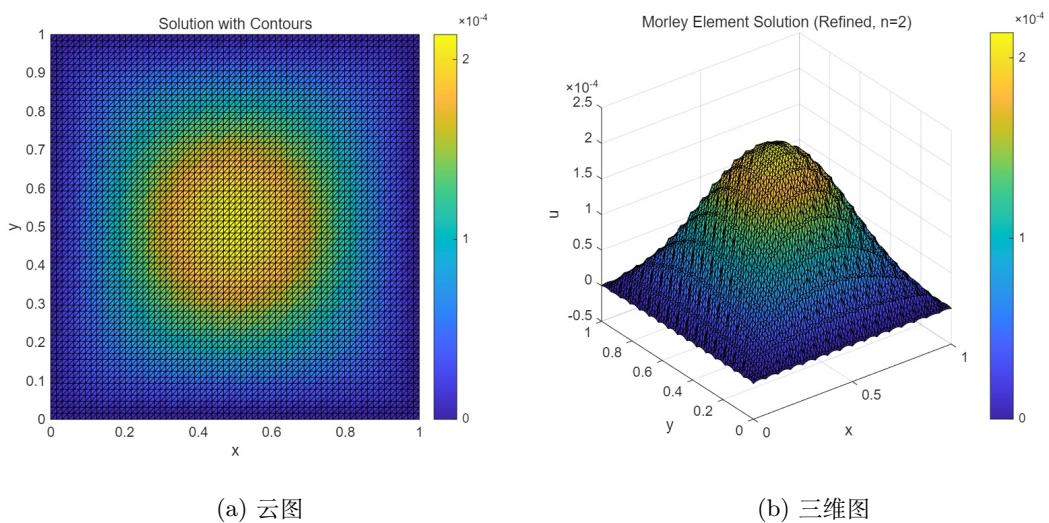


图 4:  $h = 0.0625$  时有限元解的图像

(b) 由 Stokes 定理可得

$$\int_{\partial\Omega} \vec{u} \cdot d\mathbf{l} = \int_{\Omega} \nabla \times \vec{u} dS = 0 \quad (19)$$

因此我们可以定义

$$\phi(\vec{r}) = \int_{\vec{r}_0}^{\vec{r}} \vec{u} \cdot d\mathbf{l} \quad (20)$$

积分路径可以取从  $\vec{r}_0$  到  $\vec{r}$  的任意路径。则有  $\nabla\phi = \vec{u}$ 。

另一方面，根据 Helmholtz 分解定理，任何向量场  $\vec{u}$  都可以分解为

$$\vec{u} = \nabla\phi + \nabla \times \vec{\varphi} \quad (21)$$

两边取散度可以得到

$$\begin{aligned} \nabla \cdot \vec{u} &= \nabla \cdot (\nabla\phi) + \nabla \cdot (\nabla \times \vec{\varphi}) \\ 0 &= \nabla \cdot \nabla\phi \end{aligned} \quad (22)$$

显然  $\phi$  满足一个调和方程，因此在要求有界的条件下， $\phi$  是一个确定的常数。于是就有  $\vec{u} = \nabla \times \vec{\varphi}$ 。