Global exercise - GUE08

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Content covered:

- ✓ Numerics:
 - 1. Review: QR-decomposition by using
 - (a) Givens-Rotation
 - (b) Householder-Reflection
 - 2. QR algorithm to find all eigenvalues of a matrix A.
- ✓ Analysis: Application of Hölder's inequality to approximate integral

1 Numerics: Review of QR-decomposition

There are two main methods used to decompose a matrix into an orthogonal matrix Q and a right upper triangular matrix R

- 1. Givens-Rotation: ideally for **sparse** matrices.
 - \rightarrow Detect non-zero entries standing below the diagonal,
 - \rightarrow Clean them up by applying the corresponding Givens-Rotation matrix.
- 2. Householder-Reflection: ideally for dense matrices

1.1 Step-by-step with Givens-Rotation

Example 1. Examine the following matrix A given as follows

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 0 & 1 & 6 \end{pmatrix}_{3 \times 3}.$$
 (1)

The only entry to be cleaned up is A_{32} . Therefore, the Givens-Rotation matrix is

$$G_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{pmatrix}_{3\times 3} \quad \text{where} \quad \begin{cases} r = \sqrt{a^2 + b^2} = \sqrt{A_{22}^2 + A_{32}^2} = \sqrt{2}, \\ c = a/r = -1/\sqrt{2}, \\ s = -b/r = -1/\sqrt{2}, \end{cases}$$
(2)

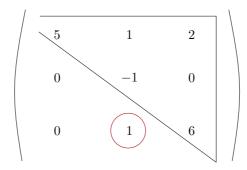


Figure 1: The entry A_{32} of matrix A is the only one that we may clean up so as to obtain a right upper triangular matrix. Givens-Rotation matrix is G_{32} .

Then, applying G_{32} onto A from the left leads to

$$G_{32}A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{pmatrix} \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 0 & 1 & 6 \end{pmatrix} = \begin{pmatrix} 5 & 1 & 2 \\ 0 & \sqrt{2} & 6/\sqrt{2} \\ 0 & 0 & -6/\sqrt{2} \end{pmatrix} =: B, \tag{3}$$

which has already a form of a right upper triangular matrix R. Therefore, we obtain

$$G_{32}A = R, (4)$$

which, equally, leads to

$$G_{32}A = R \Leftrightarrow G_{32}^{-1}G_{32}A = G_{32}^{-1}R \Leftrightarrow A = G_{32}^{-1}R \Leftrightarrow A = G_{32}^{\top}R.$$
 (5)

Note in passing that $G_{32}^{-1} = G_{32}^{\top}$ in the previous step is due to the fact that the matrix G_{32} itself is orthogonal. By assigning $Q := G_{32}^{\top}$ we arrive at QR-decomposition

$$\therefore \quad A = G_{32}^{\top} R = Q R.$$

Example 2. Examine the following matrix A given as follows

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 0 & 0 & 6 \end{pmatrix}_{3 \times 3}.$$
 (6)

The only entry to be cleaned up is A_{21} . Therefore, the Givens-Rotation matrix is

$$G_{21} = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix}_{3\times 3} \quad \text{where} \quad \begin{cases} r = \sqrt{a^2 + b^2} = \sqrt{A_{11}^2 + A_{21}^2} = \sqrt{26}, \\ c = a/r = 5/\sqrt{26}, \\ s = -b/r = -1/\sqrt{26}, \end{cases}$$
(7)

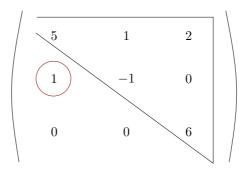


Figure 2: The entry A_{21} of matrix A is the only one that we may clean up so as to obtain a right upper triangular matrix. Givens-Rotation matrix is G_{21} .

Then, applying G_{21} onto A from the left leads to

$$G_{21}A = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 0 & 0 & 6 \end{pmatrix} = \begin{pmatrix} \sqrt{26} & 4/\sqrt{26} & 10/\sqrt{26} \\ 0 & -6/\sqrt{26} & -2/\sqrt{26} \\ 0 & 0 & 6 \end{pmatrix}$$
(8)

which has already a form of a right upper triangular matrix R. Therefore, we obtain

$$G_{21}A = R, (9)$$

which, equally, leads to

$$G_{21}A = R \Leftrightarrow G_{21}^{-1}G_{21}A = G_{21}^{-1}R \Leftrightarrow A = G_{21}^{-1}R \Leftrightarrow A = G_{21}^{\top}R.$$
 (10)

Note in passing that $G_{21}^{-1} = G_{21}^{\top}$ in the previous step is due to the fact that the matrix G_{21} itself is orthogonal. By assigning $Q := G_{21}^{\top}$ we arrive at QR-decomposition

$$\therefore \quad A = G_{21}^{\top} R = Q R.$$

Example 3. Examine the following matrix A given as follows

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 1 & 0 & 6 \end{pmatrix}_{3\times3}.$$
 (11)

The only entry to be cleaned up is A_{31} . Therefore, the Givens-Rotation matrix is

$$G_{31} = \begin{pmatrix} c & 0 & -s \\ 0 & 1 & 0 \\ s & 0 & c \end{pmatrix}_{3\times 3} \quad \text{where} \quad \begin{cases} r = \sqrt{a^2 + b^2} = \sqrt{A_{11}^2 + A_{31}^2} = \sqrt{26}, \\ c = a/r = 5/\sqrt{26}, \\ s = -b/r = -1/\sqrt{26}, \end{cases}$$
(12)

Then, applying G_{31} onto A from the left leads to

$$G_{31}A = \begin{pmatrix} c & 0 & -s \\ 0 & 1 & 0 \\ s & 0 & c \end{pmatrix} \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 1 & 0 & 6 \end{pmatrix} = \begin{pmatrix} \sqrt{26} & 5/\sqrt{26} & 16/\sqrt{26} \\ 0 & -1 & 0 \\ 0 & -1/\sqrt{26} & 28/\sqrt{26} \end{pmatrix} =: B, \quad (13)$$

which is not yet in forms of a right upper triangular matrix R. Herein, we still need to perform one more Givens-Rotation on the later matrix to clean up the entry B_{32} . The second Givens-Rotation takes the form

$$G_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & -s_2 \\ 0 & s_2 & c_2 \end{pmatrix}_{3\times 3} \quad \text{where} \quad \begin{cases} r_2 = \sqrt{a_2^2 + b_2^2} = \sqrt{B_{11}^2 + B_{31}^2} = 9/\sqrt{78}, \\ c_2 = a_2/r_2 = -\sqrt{78}/9, \\ s_2 = -b_2/r_2 = \sqrt{3}/9, \end{cases}$$

$$(14)$$

Next, applying G_{32} onto $B = G_{31}A$ leads to

$$G_{32}B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & -s_2 \\ 0 & s_2 & c_2 \end{pmatrix} \begin{pmatrix} \sqrt{26} & 5/\sqrt{26} & 16/\sqrt{26} \\ 0 & -1 & 0 \\ 0 & -1/\sqrt{26} & 28/\sqrt{26} \end{pmatrix}$$
(15)

which yields

$$G_{32}B = \begin{pmatrix} \sqrt{26} & 5/\sqrt{26} & 16/\sqrt{26} \\ 0 & 3\sqrt{3}/\sqrt{26} & -28\sqrt{3}/(9\sqrt{26}) \\ 0 & 0 & -28\sqrt{3}/9 \end{pmatrix}$$
(16)

which now has a form of a right upper triangular matrix R. Therefore, we obtain

$$G_{32}B = R \Leftrightarrow G_{32}G_{31}A = R \Leftrightarrow A = G_{31}^{-1}G_{32}^{-1}R \Leftrightarrow A = G_{31}^{\top}G_{32}^{\top}R.$$
 (17)

By assigning $Q := G_{31}^{\mathsf{T}} G_{32}^{\mathsf{T}}$ we arrive at QR-decomposition

$$\therefore \quad A = G_{31}^{\mathsf{T}} G_{32}^{\mathsf{T}} R = QR.$$

Example 4. Examine the following matrix A given as follows

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 1 & 1 & 6 \end{pmatrix}_{3 \times 3}.$$
 (18)

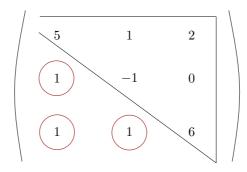


Figure 3: The entry A_{21} , A_{31} , and A_{32} of matrix A are the three entries that we would like clean up so that we may obtain a right upper triangular matrix. Givens-Rotation matrix for A_{21} , A_{31} , and A_{32} is G_{21} , G_{31} , and G_{32} , respectively. The order of applying G_{21} first or G_{31} or G_{32} is no matter, but the coefficients used to build the Givens-Rotation matrix r, a, and b have to be carefully computed, since they become various after every time applying the rotation.

The Givens-Rotation matrix G_{21} takes the form

$$G_{21} = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} \tag{19}$$

The Givens-Rotation matrix G_{31} takes the form

$$G_{31} = \begin{pmatrix} c & 0 & -s \\ 0 & 1 & 0 \\ s & 0 & c \end{pmatrix} \tag{20}$$

The Givens-Rotation matrix G_{32} takes the form

$$G_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{pmatrix} \tag{21}$$

2 Numerics: QR-algorithm

Observation 1 (QR-algorithm vs. QR-decomposition). QR-algorithm (as seen in Maths III) is not QR-decomposition (as seen in Maths III). QR-algorithm (Maths III) is an algorithm used to find all eigenvalues of a matrix A numerically. Meanwhile, QR-decomposition is a technique in linear algebra used to decompose a matrix A into an orthogonal matrix Q and a right upper triangular matrix R. Nevertheless, we will still need QR-decomposition for QR-algorithm.

3 Analysis: Application of Hölder's inequality

Observation 2. Sometimes we would like to estimate whether an integral, from complicated to very complicated, is bounded or not, without actually compute it. The Hölder's inequality is an ideally mathematical tool for such situation.

Example 5. Examine the following integral

$$\int_{\Omega} (x+2)^{-3/5} \exp(-2x/3) \, dx$$

Approach: