

# Global exercise - GUE08

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Content covered:

✓ Numerics:

1. Review: QR-decomposition by using
  - (a) Givens-Rotation
  - (b) Householder-Reflection
2. QR algorithm to find all eigenvalues of a matrix  $A$ .

✓ Analysis: Application of Hölder's inequality to approximate integral

## 1 Numerics: Review of QR-decomposition

There are two main methods used to decompose a matrix into an orthogonal matrix  $Q$  and a right upper triangular matrix  $R$

1. Givens-Rotation: ideally for **sparse** matrices.
  - Detect non-zero entries standing below the diagonal,
  - Clean them up by applying the corresponding Givens-Rotation matrix.
2. Householder-Reflection: ideally for **dense** matrices

## 1.1 Step-by-step with Givens-Rotation

**Example 1.** *Examine the following matrix  $A$  given as follows*

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 0 & 1 & 6 \end{pmatrix}_{3 \times 3}. \quad (1)$$

The only entry to be cleaned up is  $A_{32}$ . Therefore, the Givens-Rotation matrix is

$$G_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{pmatrix}_{3 \times 3} \quad \text{where} \quad \begin{cases} r = \sqrt{a^2 + b^2} = \sqrt{A_{22}^2 + A_{32}^2} = \sqrt{2}, \\ c = a/r = -1/\sqrt{2}, \\ s = -b/r = -1/\sqrt{2}, \end{cases} \quad (2)$$

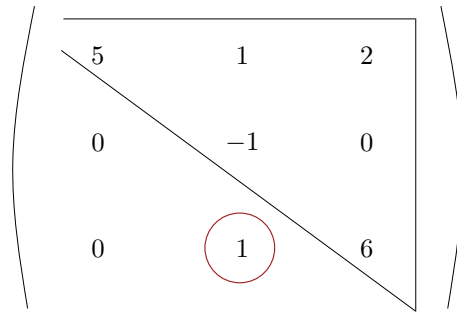


Figure 1: The entry  $A_{32}$  of matrix  $A$  is the only one that we may clean up so as to obtain a right upper triangular matrix. Givens-Rotation matrix is  $G_{32}$ .

Then, applying  $G_{32}$  onto  $A$  from the left leads to

$$G_{32}A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{pmatrix} \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 0 & 1 & 6 \end{pmatrix} = \begin{pmatrix} 5 & 1 & 2 \\ 0 & \sqrt{2} & 6/\sqrt{2} \\ 0 & 0 & -6/\sqrt{2} \end{pmatrix} =: B, \quad (3)$$

which has already a form of a right upper triangular matrix  $R$ . Therefore, we obtain

$$G_{32}A = R, \quad (4)$$

which, equally, leads to

$$G_{32}A = R \Leftrightarrow G_{32}^{-1}G_{32}A = G_{32}^{-1}R \Leftrightarrow A = G_{32}^{-1}R \Leftrightarrow A = G_{32}^{\top}R. \quad (5)$$

Note in passing that  $G_{32}^{-1} = G_{32}^{\top}$  in the previous step is due to the fact that the matrix  $G_{32}$  itself is orthogonal. By assigning  $Q := G_{32}^{\top}$  we arrive at QR-decomposition

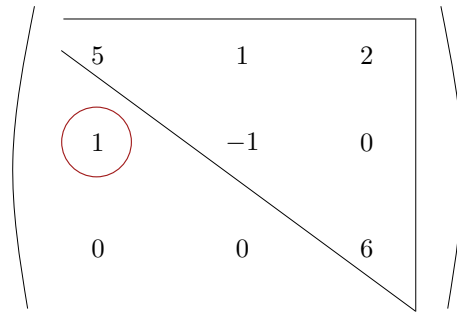
$$\therefore \quad \boxed{A = G_{32}^{\top}R = QR.}$$

**Example 2.** *Examine the following matrix  $A$  given as follows*

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 0 & 0 & 6 \end{pmatrix}_{3 \times 3}. \quad (6)$$

The only entry to be cleaned up is  $A_{21}$ . Therefore, the Givens-Rotation matrix is

$$G_{21} = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix}_{3 \times 3} \quad \text{where} \quad \begin{cases} r = \sqrt{a^2 + b^2} = \sqrt{A_{11}^2 + A_{21}^2} = \sqrt{26}, \\ c = a/r = 5/\sqrt{26}, \\ s = -b/r = -1/\sqrt{26}, \end{cases} \quad (7)$$



$$\begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

Figure 2: The entry  $A_{21}$  of matrix  $A$  is the only one that we may clean up so as to obtain a right upper triangular matrix. Givens-Rotation matrix is  $G_{21}$ .

Then, applying  $G_{21}$  onto  $A$  from the left leads to

$$G_{21}A = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 0 & 0 & 6 \end{pmatrix} = \begin{pmatrix} \sqrt{26} & 4/\sqrt{26} & 10/\sqrt{26} \\ 0 & -6/\sqrt{26} & -2/\sqrt{26} \\ 0 & 0 & 6 \end{pmatrix} \quad (8)$$

which has already a form of a right upper triangular matrix  $R$ . Therefore, we obtain

$$G_{21}A = R, \quad (9)$$

which, equally, leads to

$$G_{21}A = R \Leftrightarrow G_{21}^{-1}G_{21}A = G_{21}^{-1}R \Leftrightarrow A = G_{21}^{-1}R \Leftrightarrow A = G_{21}^{\top}R. \quad (10)$$

Note in passing that  $G_{21}^{-1} = G_{21}^{\top}$  in the previous step is due to the fact that the matrix  $G_{21}$  itself is orthogonal. By assigning  $Q := G_{21}^{\top}$  we arrive at QR-decomposition

$$\therefore \quad \boxed{A = G_{21}^{\top}R = QR.}$$

**Example 3.** Examine the following matrix  $A$  given as follows

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 1 & 0 & 6 \end{pmatrix}_{3 \times 3}. \quad (11)$$

The only entry to be cleaned up is  $A_{31}$ . Therefore, the Givens-Rotation matrix is

$$G_{31} = \begin{pmatrix} c & 0 & -s \\ 0 & 1 & 0 \\ s & 0 & c \end{pmatrix}_{3 \times 3} \quad \text{where} \quad \begin{cases} r = \sqrt{a^2 + b^2} = \sqrt{A_{11}^2 + A_{31}^2} = \sqrt{26}, \\ c = a/r = 5/\sqrt{26}, \\ s = -b/r = -1/\sqrt{26}, \end{cases} \quad (12)$$

Then, applying  $G_{31}$  onto  $A$  from the left leads to

$$G_{31}A = \begin{pmatrix} c & 0 & -s \\ 0 & 1 & 0 \\ s & 0 & c \end{pmatrix} \begin{pmatrix} 5 & 1 & 2 \\ 0 & -1 & 0 \\ 1 & 0 & 6 \end{pmatrix} = \begin{pmatrix} \sqrt{26} & 5/\sqrt{26} & 16/\sqrt{26} \\ 0 & -1 & 0 \\ 0 & -1/\sqrt{26} & 28/\sqrt{26} \end{pmatrix} =: B, \quad (13)$$

which is not yet in forms of a right upper triangular matrix  $R$ . Herein, we still need to perform one more Givens-Rotation on the later matrix to clean up the entry  $B_{32}$ . The second Givens-Rotation takes the form

$$G_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & -s_2 \\ 0 & s_2 & c_2 \end{pmatrix}_{3 \times 3} \quad \text{where} \quad \begin{cases} r_2 = \sqrt{a_2^2 + b_2^2} = \sqrt{B_{11}^2 + B_{31}^2} = 9/\sqrt{78}, \\ c_2 = a_2/r_2 = -\sqrt{78}/9, \\ s_2 = -b_2/r_2 = \sqrt{3}/9, \end{cases} \quad (14)$$

Next, applying  $G_{32}$  onto  $B = G_{31}A$  leads to

$$G_{32}B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_2 & -s_2 \\ 0 & s_2 & c_2 \end{pmatrix} \begin{pmatrix} \sqrt{26} & 5/\sqrt{26} & 16/\sqrt{26} \\ 0 & -1 & 0 \\ 0 & -1/\sqrt{26} & 28/\sqrt{26} \end{pmatrix} \quad (15)$$

which yields

$$G_{32}B = \begin{pmatrix} \sqrt{26} & 5/\sqrt{26} & 16/\sqrt{26} \\ 0 & 3\sqrt{3}/\sqrt{26} & -28\sqrt{3}/(9\sqrt{26}) \\ 0 & 0 & -28\sqrt{3}/9 \end{pmatrix} \quad (16)$$

which now has a form of a right upper triangular matrix  $R$ . Therefore, we obtain

$$G_{32}B = R \Leftrightarrow G_{32}G_{31}A = R \Leftrightarrow A = G_{31}^{-1}G_{32}^{-1}R \Leftrightarrow A = G_{31}^{\top}G_{32}^{\top}R. \quad (17)$$

By assigning  $Q := G_{31}^{\top}G_{32}^{\top}$  we arrive at QR-decomposition

$$\therefore \quad \boxed{A = G_{31}^{\top}G_{32}^{\top}R = QR.}$$

**Example 4.** *Examine the following matrix  $A$  given as follows*

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 1 & -1 & 0 \\ 1 & 1 & 6 \end{pmatrix}_{3 \times 3}. \quad (18)$$

Figure 3: The entry  $A_{21}$ ,  $A_{31}$ , and  $A_{32}$  of matrix  $A$  are the three entries that we would like clean up so that we may obtain a right upper triangular matrix. Givens-Rotation matrix for  $A_{21}$ ,  $A_{31}$ , and  $A_{32}$  is  $G_{21}$ ,  $G_{31}$ , and  $G_{32}$ , respectively. The order of applying  $G_{21}$  first or  $G_{31}$  or  $G_{32}$  is no matter, but the coefficients used to build the Givens-Rotation matrix  $r$ ,  $a$ , and  $b$  have to be carefully computed, since they become various after every time applying the rotation.

The Givens-Rotation matrix  $G_{21}$  takes the form

$$G_{21} = \begin{pmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (19)$$

The Givens-Rotation matrix  $G_{31}$  takes the form

$$G_{31} = \begin{pmatrix} c & 0 & -s \\ 0 & 1 & 0 \\ s & 0 & c \end{pmatrix} \quad (20)$$

The Givens-Rotation matrix  $G_{32}$  takes the form

$$G_{32} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{pmatrix} \quad (21)$$

## 2 Numerics: QR-algorithm

**Observation 1 (QR-algorithm vs. QR-decomposition).** *QR-algorithm (as seen in Maths III) is not QR-decomposition (as seen in Maths II). QR-algorithm (Maths III) is an algorithm used to find **all** eigenvalues of a matrix  $A$  **numerically**. Meanwhile, QR-decomposition is a technique in linear algebra used to decompose a matrix  $A$  into an orthogonal matrix  $Q$  and a right upper triangular matrix  $R$ . Nevertheless, we will still need QR-decomposition for QR-algorithm.*

### 3 Analysis: Application of Hölder's inequality

**Observation 2.** *Sometimes we would like to estimate whether an integral, from complicated to very complicated, is bounded at a certain value or not, without actually compute it. The Hölder's inequality is a useful mathematical tool for such situation.*

**Example 5.** *Examine the following integral*

$$\int_{\Omega} (x+2)^{-3/5} \exp(-2x/3) dx$$

**Observation 3.** *The given integral is complicated to compute, but it would be easier if we may split the exponential term away from the polynomial term.*

Approach: Setting

$$f(x) := (x+2)^{-3/5} \quad (22)$$

$$g(x) := \exp(-2x/3) \quad (23)$$

Given  $f(x) \in L^6(\Omega)$ , then we can compute

$$\begin{aligned} \|f(x)\|_{L^6(\Omega)}^6 &= \int_0^\infty |f(x)|^6 dx \\ &= \int_0^\infty (x+2)^{-3 \cdot 6/5} dx \\ &= -\frac{5}{13} (x+2)^{-13/5} \Big|_{x=0}^{x=\infty} = \frac{5}{13} \cdot 2^{-13/5} < \infty. \end{aligned} \quad (24)$$

Therefore, we obtain

$$\therefore \left\| f(x) \right\|_{L^6(\Omega)}^6 = \frac{5}{13} \cdot 2^{-13/5} < \infty. \quad (25)$$

Besides, the following relation hold for Hölder's inequality

$$\frac{1}{6} + \frac{1}{q} = 1 \Leftrightarrow q = \frac{6}{5} \quad (26)$$

which leads to  $g(x) \in L^q(\Omega)$ :

$$\begin{aligned}
\|g(x)\|_{L^{6/5}(\Omega)}^{6/5} &= \int_0^\infty |g(x)|^{6/5} dx \\
&= \int_0^\infty \exp\left(-\frac{2}{3} \cdot \frac{6}{5} \cdot x\right) dx \\
&= -\frac{5}{4} \exp\left(-\frac{4}{5}x\right) \Big|_{x=0}^{x=\infty} = \frac{5}{4} < \infty.
\end{aligned} \tag{27}$$

Therefore, we obtain

$$\therefore \quad \boxed{\|g(x)\|_{L^{6/5}(\Omega)}^{6/5} = \frac{5}{4} < \infty.} \tag{28}$$

Finally, we can estimate the integral by using the Hölder's inequality

$$\begin{aligned}
\int_{\Omega} \frac{\exp(-2x/3)}{\sqrt[5]{(x+2)^3}} dx &= \|f(x) g(x)\|_{L^1(\Omega)} \leq \|f(x)\|_{L^p(\Omega)} \|g(x)\|_{L^q(\Omega)} \\
&= \|f(x)\|_{L^6(\Omega)} \|g(x)\|_{L^{6/5}(\Omega)} \\
&= \left(\frac{5 \cdot 2^{-13/5}}{13}\right)^{1/6} \left(\frac{5}{4}\right)^{5/6} \\
&< \infty.
\end{aligned} \tag{29}$$