

- Remark
- CFL + domain of dependence (numerical + analytical)
- consistency + stability → convergence (exact)
- FEM vs FVM  
(derivation of FVM)
- (conservation form)

## Global Exercise - 12

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### ① A remark about the derivation from coupled to decoupled form of linear hyperbolic systems

1. Case 1:  $\underline{W := R^{-1}U}$  as the scheme shown in exercise

$$\begin{aligned} U_t + AU_x &= 0 \\ U_t + R\Lambda R^{-1}U_x &= 0 \\ R^{-1}U_t + \Lambda R^{-1}U_x &= 0 \\ W_t + \Lambda W_x &= 0 \end{aligned}$$

$$\begin{aligned} U_t + AU_x &= 0 \\ \cancel{R}U_t + \cancel{R}\Lambda \cancel{R}^{-1}U_x &= 0 \\ (\cancel{R}U)_t + \Delta(\cancel{R}U)_x &= 0 \end{aligned}$$

where the matrix  $A$  is diagonalizable with a transformation matrix  $R \in \mathbb{R}^{N \times N}$  in the form

$$\cancel{R} \quad A = R\Lambda R^{-1}. \quad *$$

2. Case 2:  $\underline{W := TU}$  as the scheme shown in lecture note

$$\begin{aligned} U_t + AU_x &= 0 \\ U_t + T^{-1}\Lambda TU_x &= 0 \\ TU_t + \Lambda TU_x &= 0 \\ W_t + \Lambda W_x &= 0 \end{aligned}$$

$$\begin{aligned} U_t + AU_x &= 0 \\ \cancel{T}U_t + \cancel{T}\Lambda \cancel{T}U_x &= 0 \\ (\cancel{T}U)_t + \Delta(\cancel{T}U)_x &= 0 \end{aligned}$$

where the matrix  $A$  is diagonalizable with a transformation matrix  $T \in \mathbb{R}^{N \times N}$  in the form

$$A = T^{-1}\Lambda T. \quad *$$

- Note in passing that both schemes result in the same solution.  
→ We have just to be consistent with which scheme to follow.

## 2 Correlation between Domain of dependence (DoD) and Courant-Friedrichs-Lowy (CFL) condition

Example 1. Examine the numerical domain of dependence and the corresponding CFL condition of the One-sided method, where the stencils point to the left.

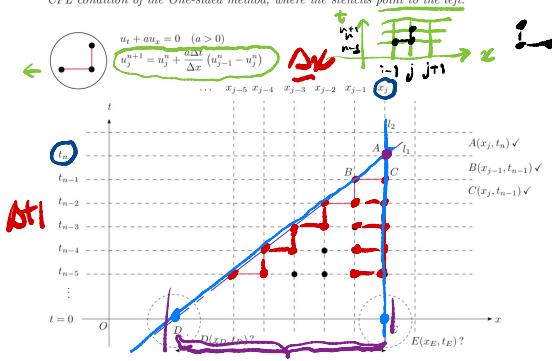


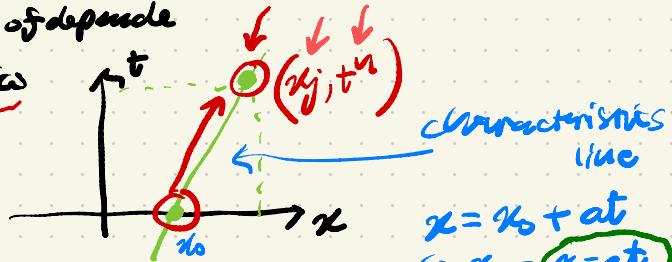
Figure 1: Numerical domain of dependence for One-sided method.

- Numerical domain of dependence:
- Analytical domain of dependence

↪ Characteristics

interval

$$\frac{a \Delta t}{\Delta x} = \text{CFL}$$



$$\text{Ana DoD: } D(x_j, t_n) = \{x \mid x = x_j - at_n\}$$

(1) Num DoD: DE

How can we recognize point D & point E?

i) Perspective of indexed subscripts.

## (2) Num DoD: DE

How can we recognize point D & point E?

i) Perspective of indicial subscription.

### 2 Correlation between Domain of dependence (DoD) and Courant-Friedrichs-Lowy (CFL) condition

Example 1. Examine the numerical domain of dependence and the corresponding CFL condition of the One-sided method, where the stencils point to the left.

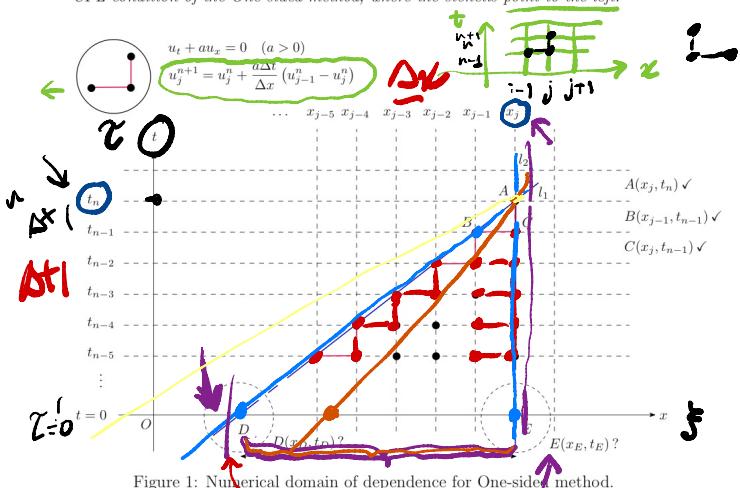


Figure 1: Numerical domain of dependence for One-sided method.

$$\begin{aligned} \text{value } & A(x_j, t_n) \\ \text{value } & B(x_{j-1}, t_{n-1}) \\ \text{index } & A(j, n) \\ \text{index } & B(j-1, n-1) \\ y &= y_A + \frac{y_B - y_A}{\Delta t / \Delta x} (\xi - x_A) \\ \xi &= n + \frac{(n-1)-n}{(n-1)-j} (\xi - j) \\ \xi &= n + \frac{-1}{-1} (\xi - j) \end{aligned}$$

RHS @ Point E  
 $x_\xi = x_j$        $\Delta t / \Delta x$

$$D_{\Delta t}(x_j, t_n) = \{x_\xi \mid -n \Delta x \leq x_\xi - x_j \leq 0\}$$

$$\begin{aligned} -n \Delta x &= -n \Delta t \frac{a \Delta x}{\Delta t} = -n \Delta t \frac{a}{v} = at_n \\ v &:= \frac{a \Delta t}{\Delta x} \quad \text{at } v = n \Delta t \end{aligned}$$

$$D_{\Delta t}(x_j, t_n) = \left\{ x \mid -\frac{at_n}{v} \leq x - x_j \leq 0 \right\}$$

Ans DoD:  $D(x_j, t_n) = \{x \mid x = x_j - at_n\}$



$$D_{\Delta t}(x_j, t_n) = \{x_\xi \mid -n \Delta x \leq x_\xi - x_j \leq 0\}$$

!

→ CFL condition

$$\begin{aligned} x &= (x_j - at_n) \\ -n \Delta x &\leq x - x_j \leq 0 \\ -n \Delta x &\leq x_j - at_n - x_j \leq 0 \rightarrow 0 \leq v \leq 1 \\ -n \Delta x &\leq at_n \leq 0 \quad \frac{at}{\Delta x} \\ 0 &\leq \Delta t \leq \frac{\Delta x}{a} \end{aligned}$$

## 2 Correlation between Domain of dependence (DoD) and Courant-Friedrichs-Lowy (CFL) condition

**Example 1.** Examine the numerical domain of dependence and the corresponding CFL condition of the One-sided method, where the stencils point to the left.

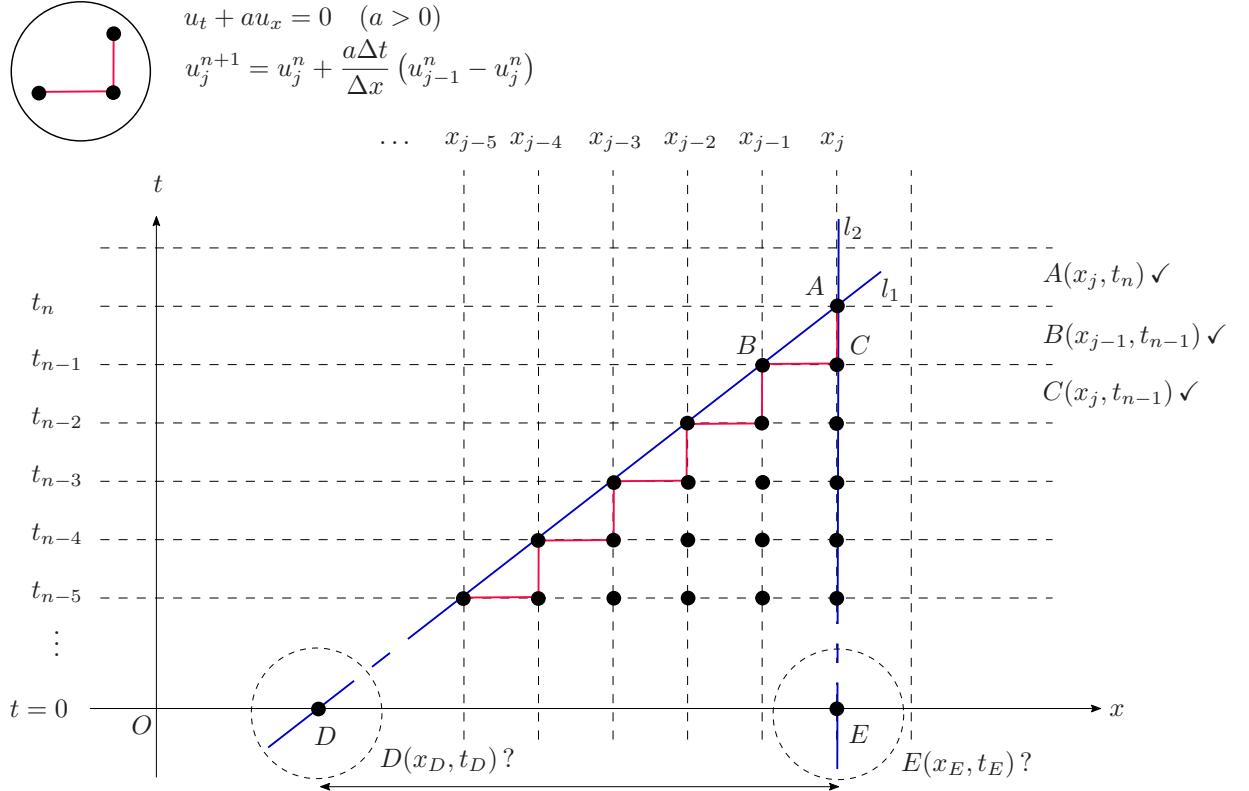


Figure 1: Numerical domain of dependence for One-sided method.

As it can be seen from Figure 1, the numerical value computed at point  $A$  depends essentially on computed initial conditions laying between point  $D$  and  $E$ .

- Perspective of indicial subscription:

Line  $(l_1)$  passing point  $A(j, n)$  and  $B(j-1, n-1)$  has the following form

$$\begin{aligned}
 (l_1) : \quad \tau &= \tau_A + \frac{\tau_B - \tau_A}{\xi_B - \xi_A} (\xi - \xi_A) \\
 \Leftrightarrow \tau &= n + \frac{(n-1) - n}{(j-1) - j} (\xi - j) \\
 \Leftrightarrow \tau &= n + \frac{-1}{-1} (\xi - j),
 \end{aligned} \tag{1}$$

where  $\tau$  is the indicial variable corresponding to  $t$ , and  $x$  the indicial variable to  $x$ . Hence, line  $(l_1)$  passing line  $x$  with index  $\tau = 0$  at point  $D$  leads to the following relation

$$\xi = j - n \Leftrightarrow x_\xi = x_{j-n} \Leftrightarrow x_\xi = x_j - n\Delta x \Leftrightarrow x_\xi - x_j = -n\Delta x. \tag{2}$$

Likewise, line  $(l_2)$  passing line  $x$  with index  $\tau = 0$  at point  $E$  leads to the following relation

$$x_\xi - x_j = 0. \quad (3)$$

Therefore, by combining (2) and (3) we arrive at the numerical domain of dependence for the One-sided method in terms of indicial perspective

$$\mathcal{D}_{\Delta t}(x_j, t_n) = \left\{ x_\xi \mid -n\Delta x \leq x_\xi - x_j \leq 0 \right\}. \quad (4)$$

Next, by using the *CFL* number  $\nu := a\Delta t/\Delta x$  we obtain the following equality

$$-n\Delta x = -n\Delta t \frac{a\Delta x}{a\Delta t} \stackrel{(CFL)}{=} -n\Delta t \frac{a}{\nu} = -\frac{at_n}{\nu}. \quad (5)$$

Then, by substituting (5) into (4) with limit consideration we obtain the entire set of the numerical domain of dependence, as follows

$$\boxed{\mathcal{D}_{\Delta t}(x_j, t_n) = \left\{ x \mid -\frac{at_n}{\nu} \leq x - x_j \leq 0 \right\}}. \quad (6)$$

Besides, the analytical domain of dependence for the linear advection PDE reads

$$\mathcal{D}(x_j, t_n) = \left\{ x \mid x = x_j - at_n \right\}. \quad (7)$$

Furthermore, the *CFL* condition enforces that

$$\mathcal{D}(x_j, t_n) \subset \mathcal{D}_{\Delta t}(x_j, t_n), \quad (8)$$

which implies that characteristics should lie within the triangular zone under the line  $(l_1)$  and  $(l_2)$ , as shown in Figure 1. Therefore, substitution of (7) into (6) yields the *CFL* condition applied on the linear advection equation, as follows

$$-\frac{at_n}{\nu} \leq (x_j - at_n) - x_j \leq 0 \Leftrightarrow -\frac{at_n}{\nu} \leq -at_n \leq 0, \quad (9)$$

which, equally, leads to the *CFL* condition

$$\therefore \boxed{0 \leq \nu \leq 1 \Leftrightarrow 0 \leq \Delta t \leq \frac{\Delta x}{a}}. \quad (10)$$

Herein, the *CFL* condition (10) leads to constraint on the time step  $\Delta t$  for the case when  $a > 0$ . Note in passing that  $\nu$  is non-negative.

## 2. Perspective of fixed-point value:

Line  $(l_1)$  passing point  $A(x_j, t_n)$  and  $B(x_{j-1}, t_{n-1})$  has the following form

$$(l_1) : \quad t = t_A + \frac{t_B - t_A}{x_B - x_A} (x - x_A) \Leftrightarrow t = t_n + \frac{t_{n-1} - t_n}{x_{j-1} - x_j} (x - x_j) \\ \Leftrightarrow t = t_n + \frac{-\Delta t}{-\Delta x} (x - x_j). \quad (11)$$

Hence, line  $(l_1)$  passing line  $t = 0$  at point  $D$  leads to the relation

$$x = x_j - \frac{t_n \Delta x}{\Delta t} \Leftrightarrow x - x_j = -\frac{t_n \Delta x}{\Delta t}. \quad (12)$$

Likewise, line  $(l_2)$  passing line  $t = 0$  at point  $E$  leads to the relation

$$x - x_j = 0. \quad (13)$$

Therefore, combination of (12) and (13) leads to the numerical domain of dependence for the One-sided method in terms of fixed-point value

$$\boxed{\mathcal{D}_{\Delta t}(x_j, t_n) = \left\{ x \mid -\frac{t_n \Delta x}{\Delta t} \leq x - x_j \leq 0 \right\}}. \quad (14)$$

Besides, the analytical domain of dependence for the linear advection PDE, as given by (7), reads

$$\mathcal{D}(x_j, t_n) = \left\{ x \mid x = x_j - at_n \right\}. \quad (15)$$

Then, by taking into consideration of requirement of the CFL condition, we obtain the following relation

$$-\frac{t_n \Delta x}{\Delta t} \leq (x_j - at_n) - x_j \leq 0, \quad (16)$$

which we have substituted (15) into (14). Herein, the relation (16) enforcing CFL condition on the time step  $\Delta t$

$$\therefore \boxed{0 \leq \Delta t \leq \frac{\Delta x}{a}}, \quad (17)$$

which is similar to (10).

**Example 2.** Examine the numerical domain of dependence and the corresponding CFL condition of the One-sided method, where the stencils point to the right.

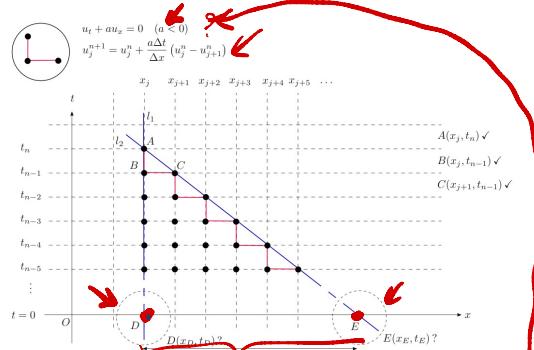


Figure 2: Numerical domain of dependence for One-sided method, where the stencils point to the right.

DE

$$D_{Dt}(x_j, m) = \left\{ x \mid 0 \leq \frac{x - x_j}{v} \leq -\frac{atm}{v} \right\}$$

$$D(v_j, t_n) = \{x \mid x = v_j - c t_n\}$$

$$\text{CFL: } \Delta t \geq \frac{\Delta x}{a} \quad \begin{cases} a = -2 \\ a < 0 \end{cases}$$

e.g.  $\Delta t \leq \frac{\Delta x}{|a|}$

**Example 2.** Examine the numerical domain of dependence and the corresponding CFL condition of the One-sided method, where the stencils point to the right.

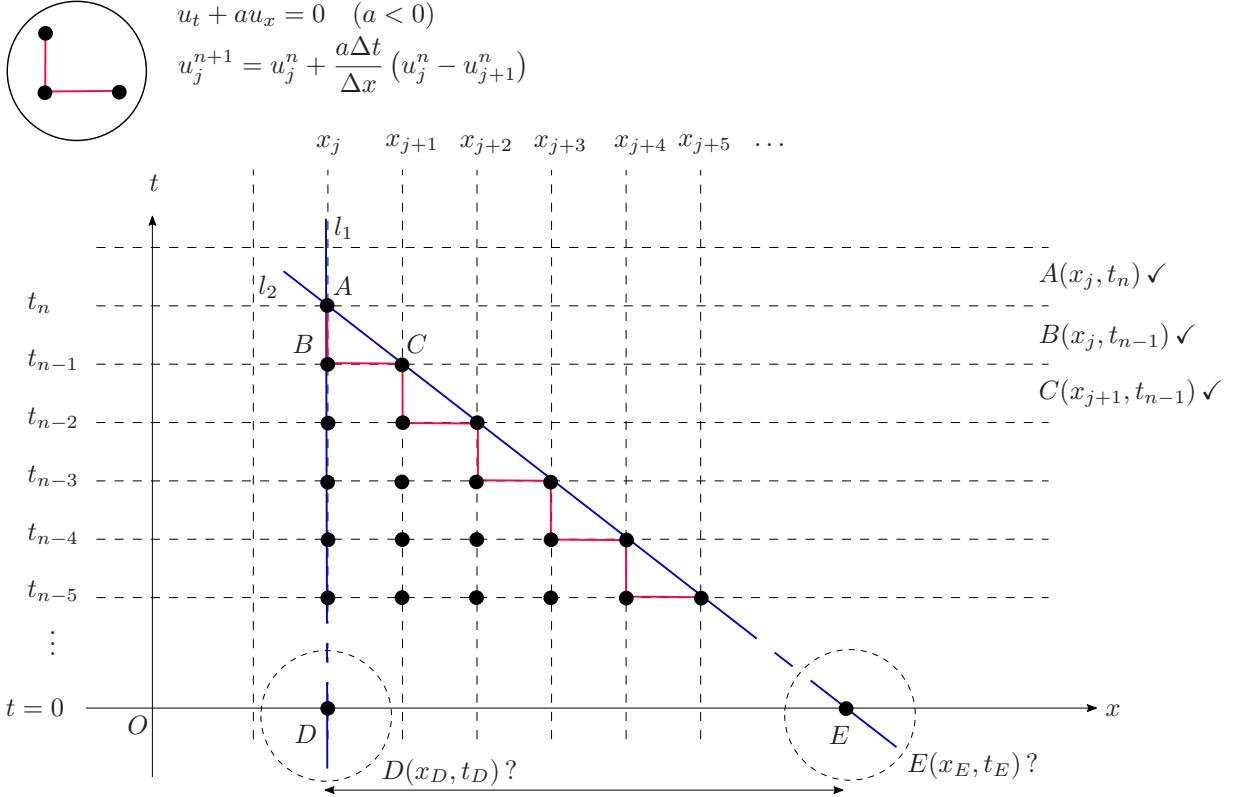


Figure 2: Numerical domain of dependence for One-sided method, where the stencils point to the right.

Similarly, by following steps done in Example 1 we obtain the following summary:

1. Point  $E$  in terms of fixed-point value satisfying

$$(l_2) : \quad t = t_n + \frac{t_{n-1} - t_n}{x_{j+1} - x_j} (x - x_j) \quad (18)$$

2. Numerical domain of dependence reads

$$\mathcal{D}_{\Delta t}(x_j, t_n) = \left\{ x \mid 0 \leq x - x_j \leq -\frac{at_n}{\nu} \right\}. \quad (19)$$

3. Analytical domain of dependence reads

$$\mathcal{D}(x_j, t_n) = \left\{ x \mid x = x_j - at_n \right\}. \quad (20)$$

4. CFL condition reads

$$\therefore \boxed{\Delta t \geq \frac{\Delta x}{a}}. \quad (21)$$

Note in passing that the advection velocity  $a$  in this Example 2 is  $a < 0$ .

**Example 3.** Examine the numerical domain of dependence and the corresponding CFL condition for a three-point scheme.

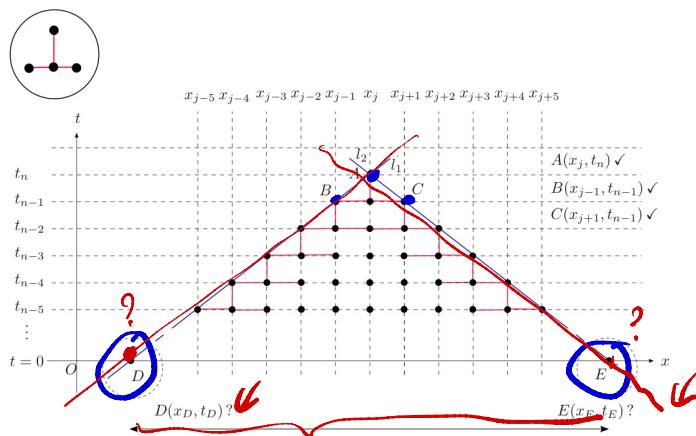


Figure 3: General numerical domain of dependence for a three-point scheme.

$$D_{\Delta t} \quad |x - x_j| \leq \frac{c \Delta t}{v}$$

$$\text{CFL} \quad \left| \frac{c \Delta t}{\Delta x} \right| \leq 1$$

**Example 3.** Examine the numerical domain of dependence and the corresponding CFL condition for a three-point scheme.

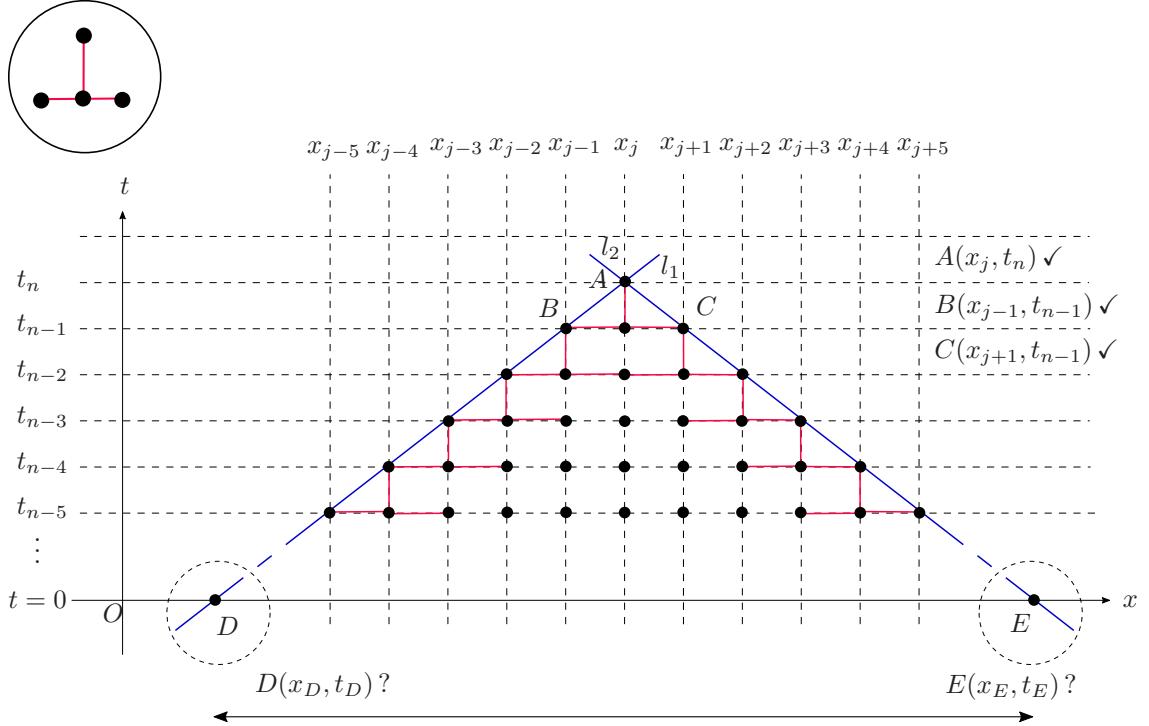


Figure 3: General numerical domain of dependence for a three-point scheme.

Similarly, by following steps done in Example 1 we obtain the following summary:

1. Point  $D$  and  $E$  in terms of fixed-point value satisfying

$$(l_1) : \quad t = t_n + \frac{t_{n-1} - t_n}{x_{j-1} - x_j} (x - x_j) \quad (22)$$

$$(l_2) : \quad t = t_n + \frac{t_{n-1} - t_n}{x_{j+1} - x_j} (x - x_j) \quad (23)$$

2. Numerical domain of dependence reads

$$\mathcal{D}_{\Delta t}(x_j, t_n) = \left\{ x \mid |x - x_j| \leq \frac{a\Delta t_n}{\nu} \right\}. \quad (24)$$

3. Analytical domain of dependence reads

$$\mathcal{D}(x_j, t_n) = \left\{ x \mid x = x_j - at_n \right\}. \quad (25)$$

4. CFL condition reads

$$\therefore \boxed{\left| \frac{a\Delta t}{\Delta x} \right| \leq 1.} \quad (26)$$

**Example 4.** Examine the numerical domain of dependence of Lax-Friedrichs method.

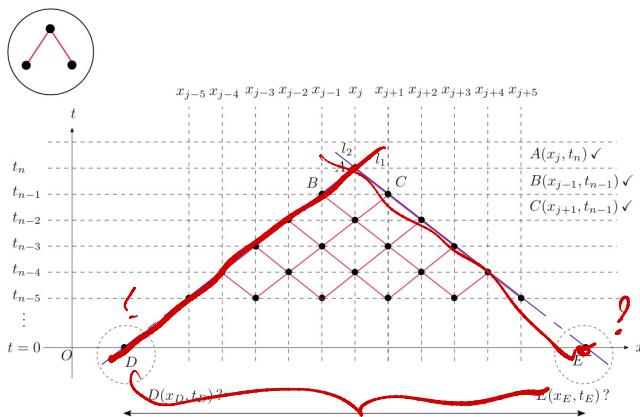
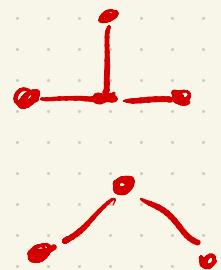


Figure 4: General numerical domain of dependence for a three-point scheme.



$$\text{CFL } \left| \frac{\alpha \Delta t}{\Delta x} \right| \leq 1$$

**Example 4.** Examine the numerical domain of dependence of Lax-Friedrichs method.

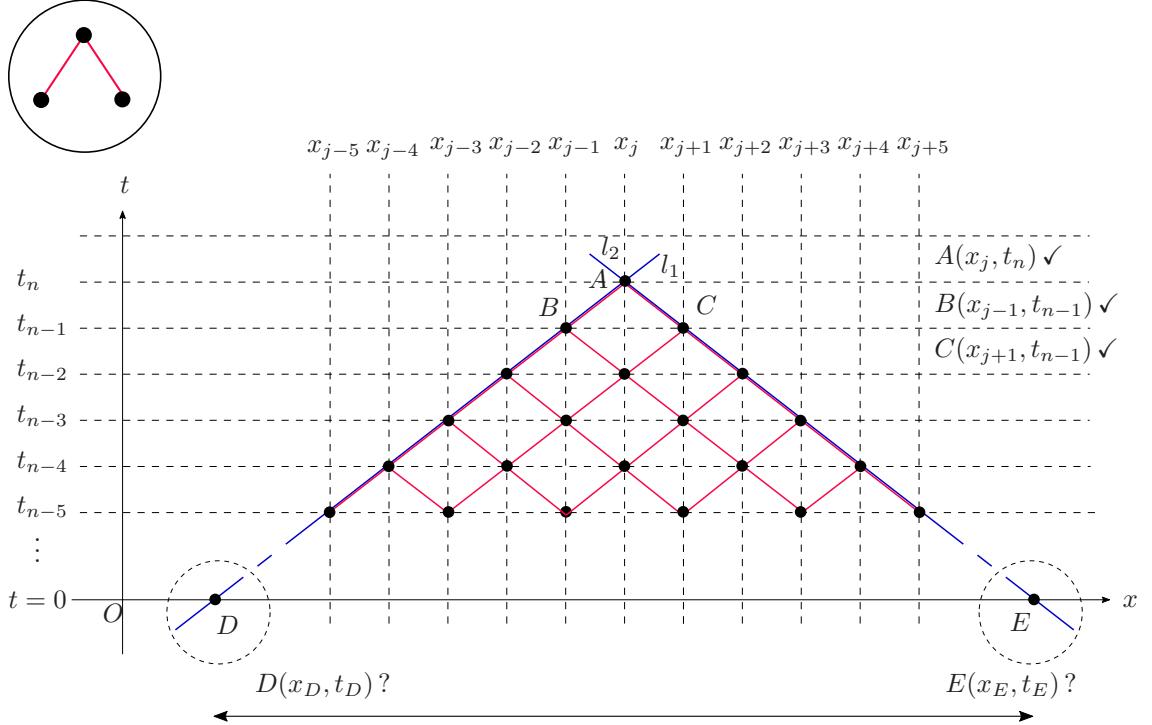


Figure 4: General numerical domain of dependence for a three-point scheme.

Similarly, by following steps done in Example 1, or the same as 3 we obtain the following summary:

1. Point  $D$  and  $E$  in terms of fixed-point value satisfying

$$(l_1) : \quad t = t_n + \frac{t_{n-1} - t_n}{x_{j-1} - x_j} (x - x_j) \quad (27)$$

$$(l_2) : \quad t = t_n + \frac{t_{n-1} - t_n}{x_{j+1} - x_j} (x - x_j) \quad (28)$$

2. Numerical domain of dependence reads

$$\mathcal{D}_{\Delta t}(x_j, t_n) = \left\{ x \mid |x - x_j| \leq \frac{at_n}{\nu} \right\}. \quad (29)$$

3. Analytical domain of dependence reads

$$\mathcal{D}(x_j, t_n) = \left\{ x \mid x = x_j - at_n \right\}. \quad (30)$$

4. CFL condition reads

$$\therefore \boxed{\left| \frac{a\Delta t}{\Delta x} \right| \leq 1.} \quad (31)$$

### 3 von Neumann stability analysis

Example 5. von Neumann stability analysis for Upwind method.

one-sided method

Ex 1 ✓

Ex 2

$$0 \leq \text{CFL} \leq 1$$

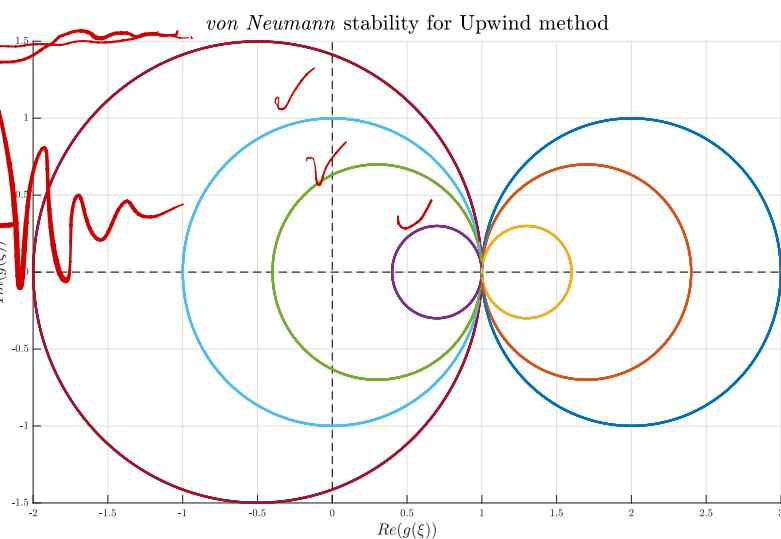
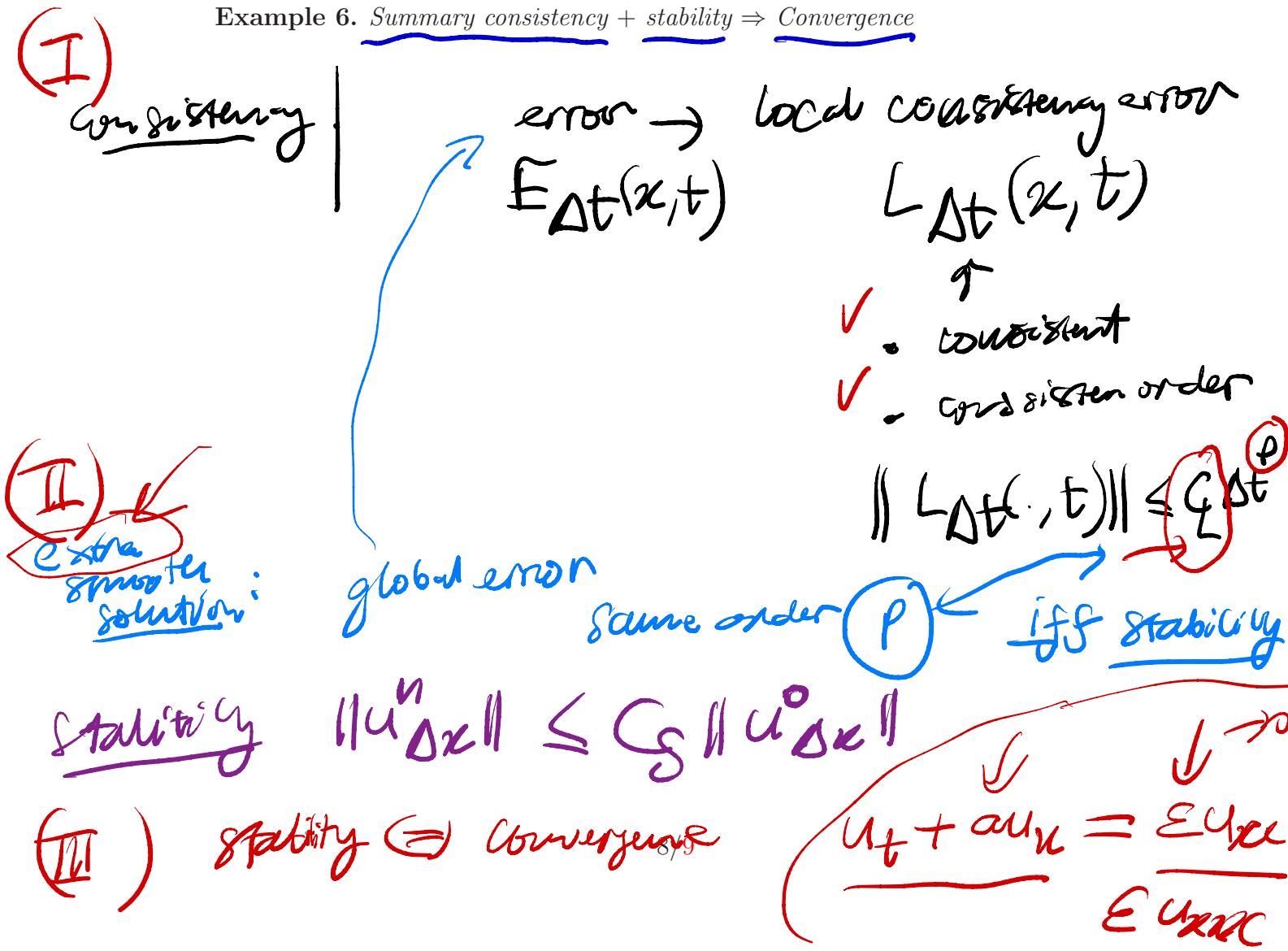


Figure 5: von Neumann stability analysis for Upwind method.

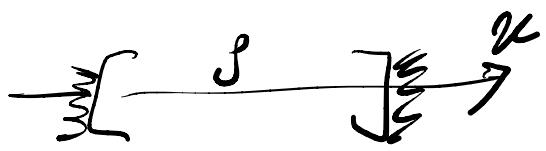
Example 6. Summary consistency + stability  $\Rightarrow$  Convergence



$$\frac{d}{dt} \int L dx = \text{Surface} + \text{Volume} + \cancel{\text{uncontrolled}}$$

#### 4 Conservation form - Finite Volume Method

Example 7. Derivation of conservation form.



$$\frac{d}{dt} \int_{x_1}^{x_2} g(x, t) dx = f(u(x_1, t)) - f(u(x_2, t))$$

Integration over time t

$$\int_{x_1}^{x_2} g(x, t_2) dx - \int_{x_1}^{x_2} g(x, t_1) dx = \int_{t_1}^{t_2} f(g(x_1, t)) dt$$

(1)V

(2)V

$$-\int_{t_1}^{t_2} f(g(x_2, t)) dt$$

Cell average:  $\bar{u}_j^n = \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t_n) dx$

$$\bar{u}_j^{n+1} = \bar{u}_j^n - \frac{1}{\Delta x} (\text{RHS})$$

$$\bar{u}_j^{n+1} = \bar{u}_j^n - \frac{\Delta t}{\Delta x} (\tilde{F}_{x_{j+1/2}} - \tilde{F}_{x_{j-1/2}})$$

$$\tilde{F}(u(x_{j+1/2}, t))$$

$$= \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} f(u(x_{j+1/2}, t)) dt$$