Mathematical modelling for all-solid-state battery: (se|sse)-Interface

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Mathematical modelling for the next-generation All-solid-state batteries: Nucleation (SE|SSE)^(*)-interface

Rechargeable Lithium-ion battery (LIB) is at the heart of every electric vehicle (EV), portable electronic device, and energy storage system [5]. Nowadays, LIBs enable human life more efficient and help to solve global environment issues thanks to EVs' zero However, conventional LIB (c-LIB) is emission. sensible to temperature and pressure, hence, flammable and explosive, which is undesirable. This bottleneck is mainly due to liquid-based electrolyte found in c-LIBs.

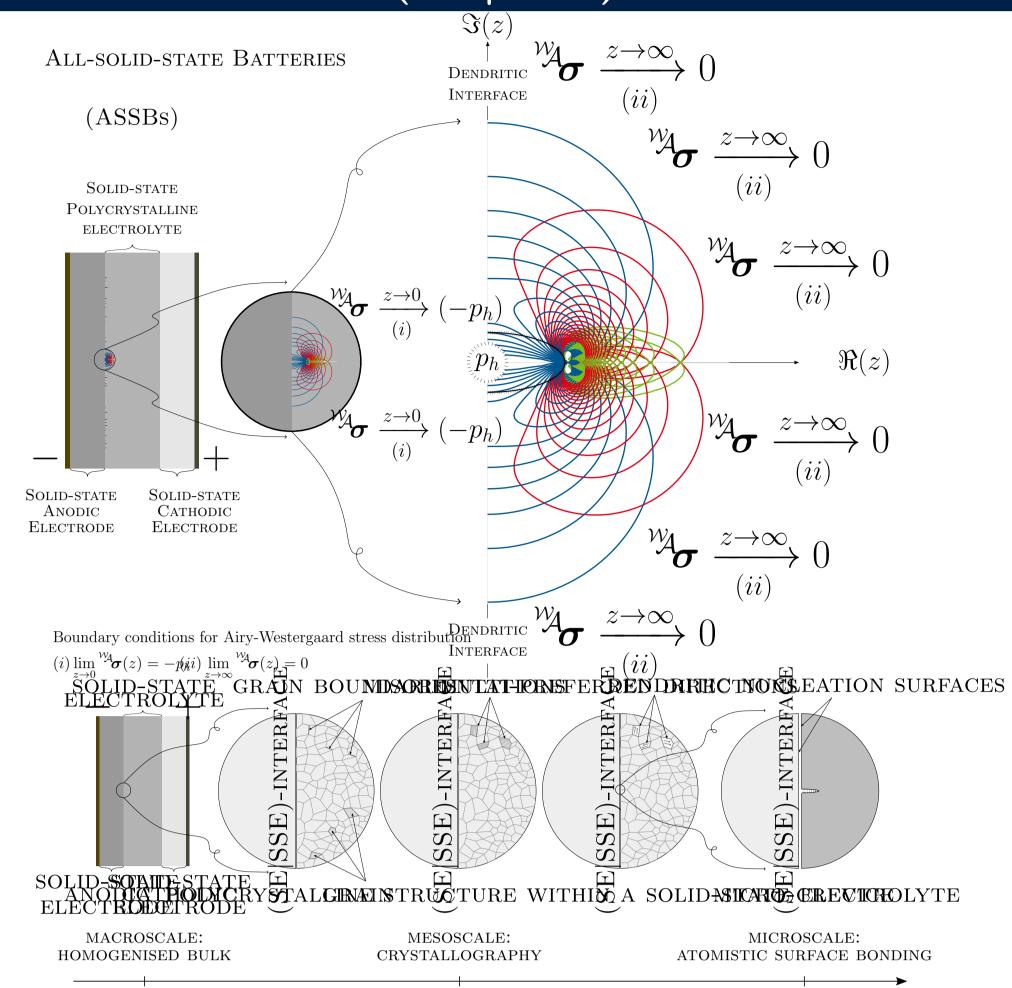
All-solid-state battery (ASSB) is one of promising candidates to overcome bottlenecks of c-LIBs. Thanks to solid-state electrolyte (SSE), ASSB is highly stable towards temperature and pressure. Nevertheless, Limetal dendrite triggered at (SE|SSE)-interface [?] is the main drawback of ASSB since these dendritic threads extrapolate into SSE grain boundary network, causing crevice, degradation of ionic conductivity, and the probability of short-circuit, which is unfavorable.

Next-generation All-solid-state battery (ng-ASSB) with a consideration of nucleation criterion defined by

$$\partial_t \boldsymbol{u} + \nabla \cdot \left(\overset{4}{\mathbb{C}} f_{\text{alocation}}(\lambda, \mu, \boldsymbol{d}_{G_i, i=1, \dots, N}^R, \boldsymbol{d}^E; \boldsymbol{x}) : \nabla \boldsymbol{u}^{(s)} \right) + \rho \boldsymbol{b} = -\rho \nabla V_e, \tag{1}$$

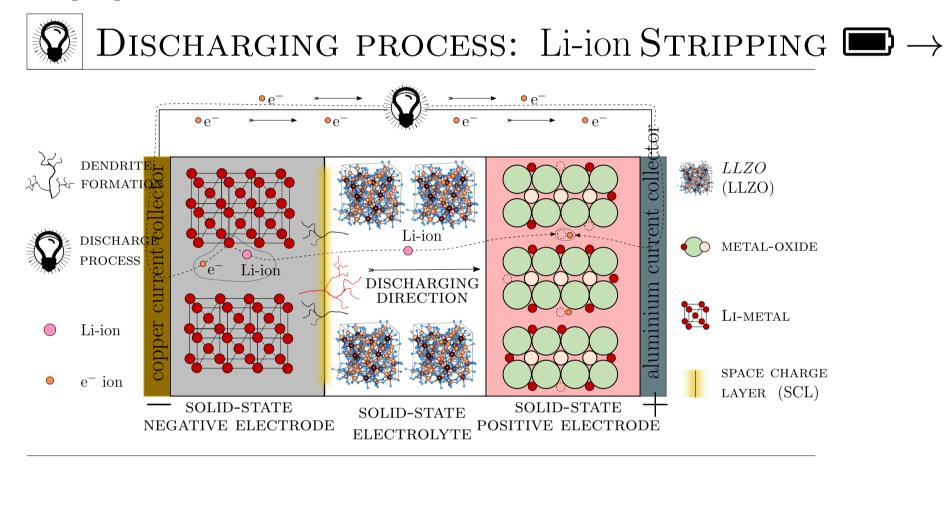
s.t.
$$a_{\text{Griffith}} := a^* = \arg\min_{a \in \mathbb{R}} \iiint_{\Omega} f(a, \boldsymbol{u}, \theta; \lambda, \mu, \boldsymbol{d}^{(\star)} \otimes \boldsymbol{d}^{(\star)}) d\Omega - \iint_{\Gamma} f(a; \gamma) d\Gamma \Big|_{\bar{\boldsymbol{u}}}$$
 (2)

where $V_e: \mathbb{R}^3 \to \mathbb{R}$ is the electric potential applied globally on ASSB. Due to nature setting of ASSB taking the form (SE|SSE|SE) the electric potential becomes uniform. Additionally, \boldsymbol{u} is the displacement field, θ temperature field, a crevice length, λ , μ Lamé constants, $\mathbf{d}^{(\star)} \otimes \mathbf{d}^{(\star)}$ embedded misorientation structural tensor, and γ cracking-surface energy density, can help to improve ASSB performance.

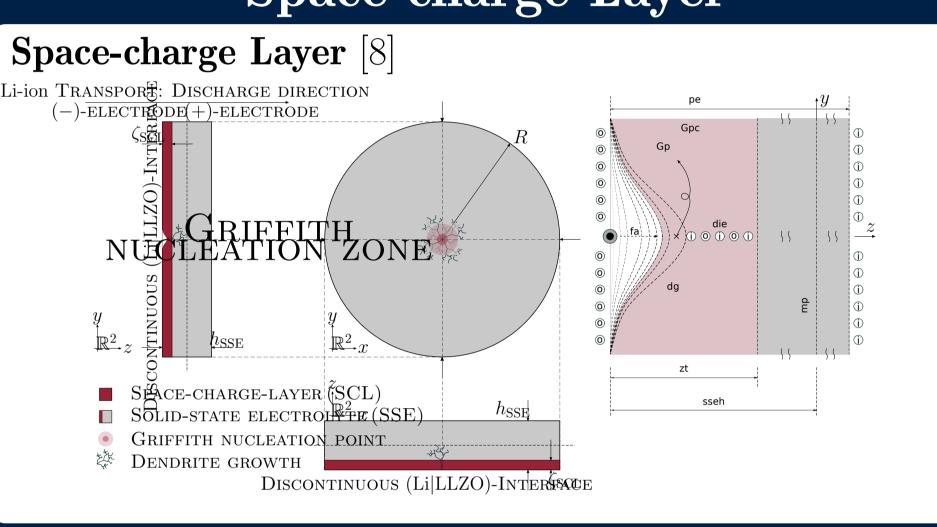


Next-generation All-solid-state battery

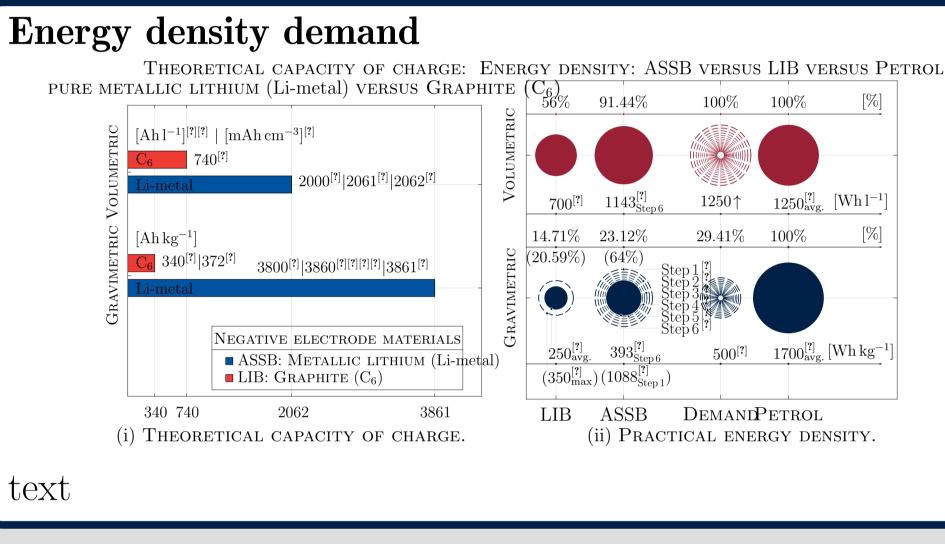
Griffith nucleation criterion governs the unstable (SE|SSE)interface [10]



Space-charge Layer



Energy density demand landscape



Artificial Neural Networks

Application: Steel property prediction [9]

Semiconductor

Application: Start/Stop Starter [7]

Nucleation interface: Taking place at the critically dendritic (SE|SSE)-interface

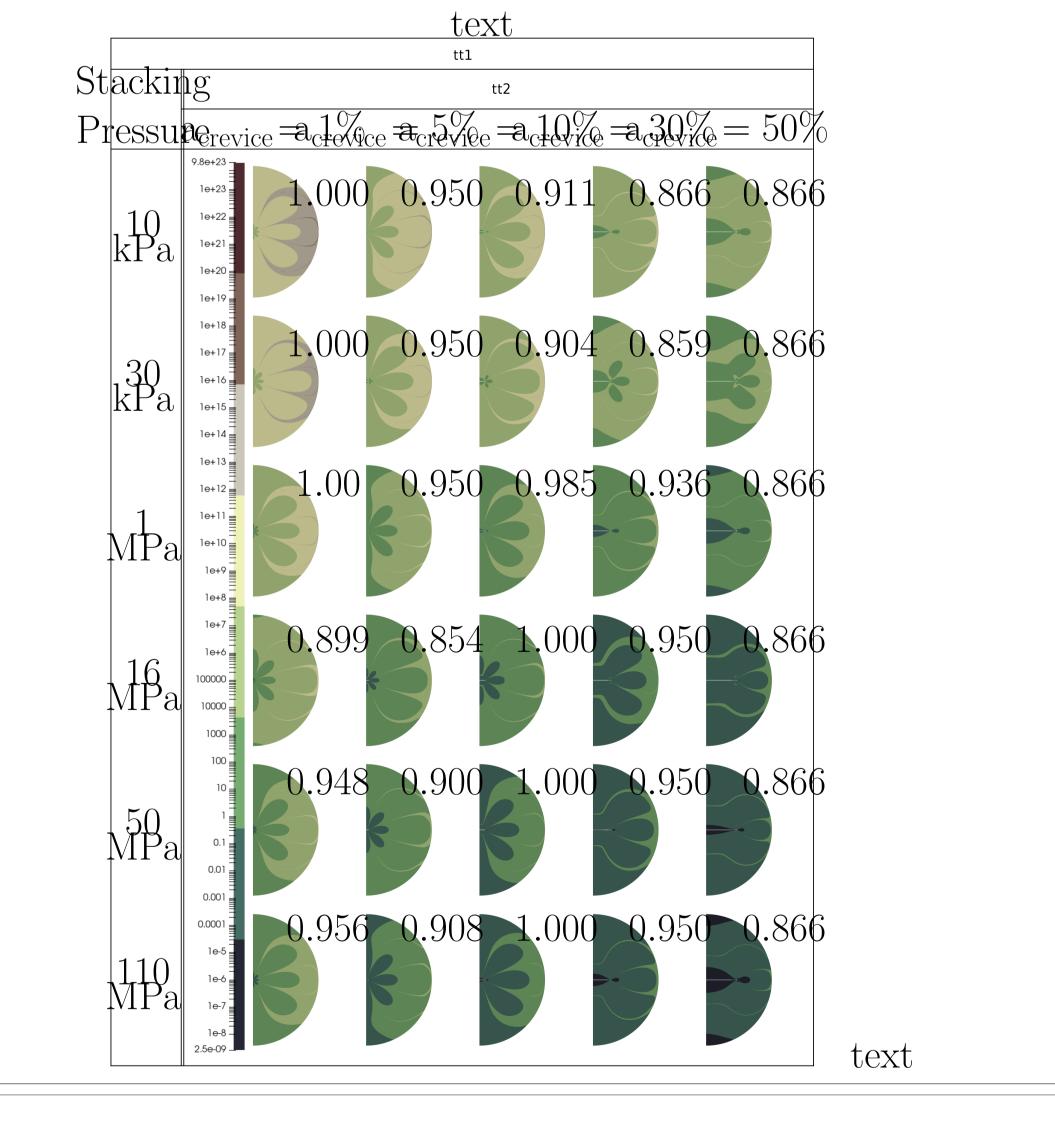
Coupled fields are Displacement field u and temperature field θ ;

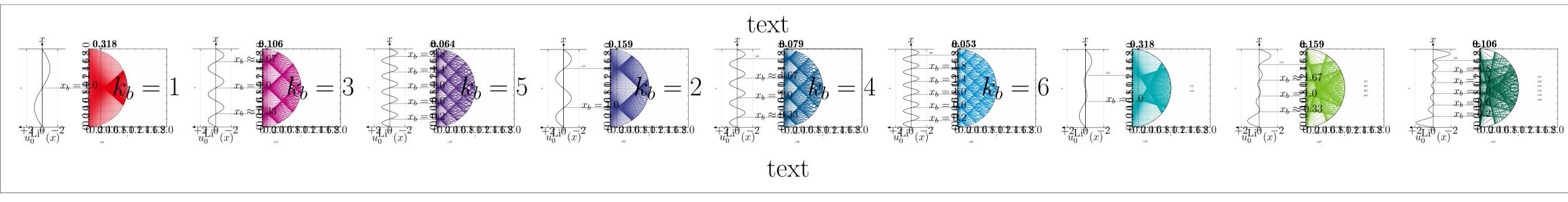
$$m{u}: egin{cases} \Omega imes \mathbb{R}_+ & \to \mathbb{R}^3, \\ (m{x},t) \mapsto m{u}(m{x},t), \end{cases} \quad heta: egin{cases} \Omega imes \mathbb{R}_+ & \to \mathbb{R}, \\ (m{x},t) \mapsto m{\theta}(m{x},t), \end{cases}$$

Governing conservation equations used to describe balance of mass, conservation of linear momentum, conservation of angular momentum, and conservation of energy with $\rho(\boldsymbol{x},t)$ is mass density per unit volume (puv); $\boldsymbol{b}(\boldsymbol{x},t)$ body force puv; $\boldsymbol{v}(\boldsymbol{x},t)$ velocity; $e(\boldsymbol{x},t)$ internal energy puv; $\boldsymbol{q}(\boldsymbol{x},t)$ heat flux; $r(\boldsymbol{x},t)$ heat source puv; σ Cauchy stress and ε infinitesimal strain.

the deformation of SSE due to dendrite formation at (SE|SSE)interface

Strain energy is based on | Surface energy is analysised based on the open crevice cracking at (SE|SSE)-interface affected by prescribed pressure





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