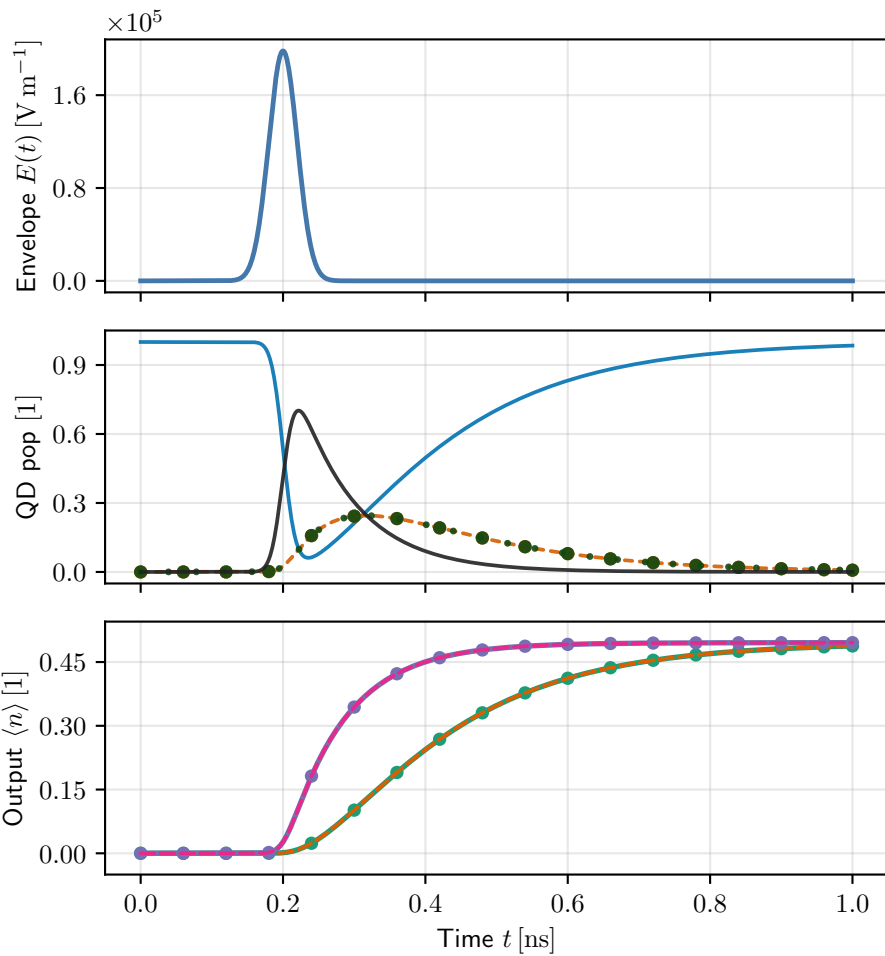


# QD scheme: tpe



**Drives**

qd\_tpe

**QD populations**

$|G\rangle$

$|X_1\rangle$

$|X_2\rangle$

$|XX\rangle$

**Output expectations**

$X \leftrightarrow G, (H)$

$X \leftrightarrow G, (V)$

$XX \leftrightarrow X_1, (H)$

$XX \leftrightarrow X_1, (V)$