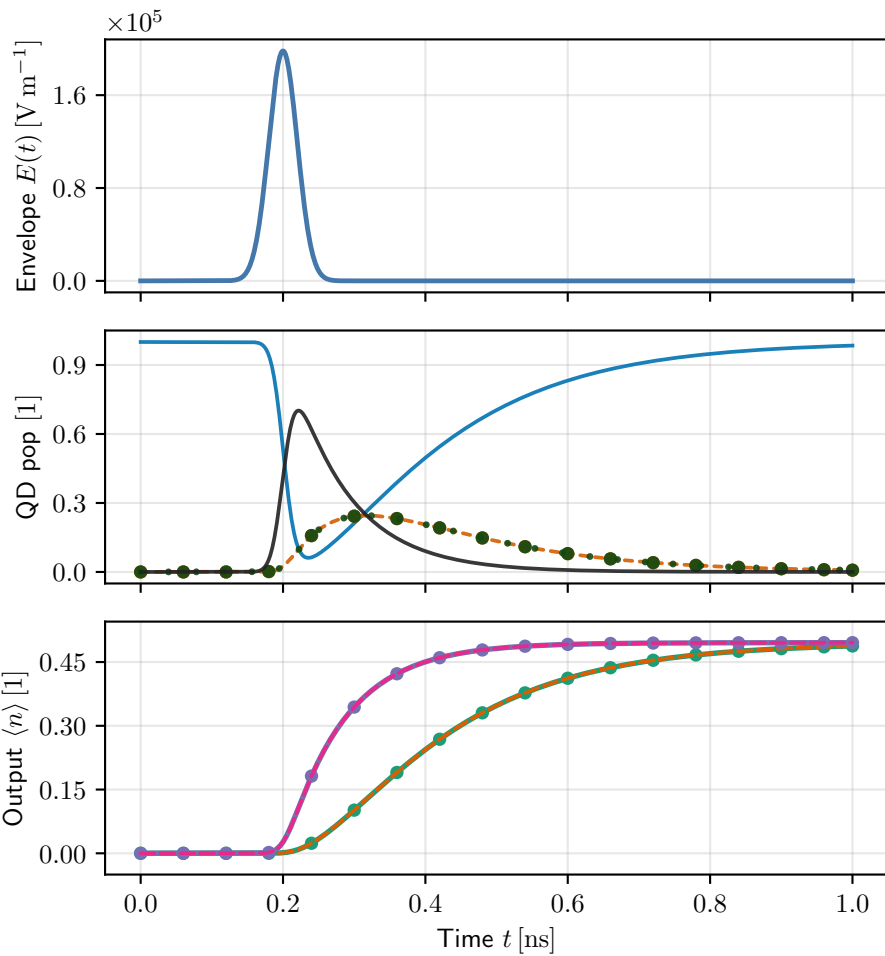


QD scheme: tpe



Drives

qd_tpe

QD populations

$|G\rangle$

$|X_1\rangle$

$|X_2\rangle$

$|XX\rangle$

Output expectations

$X \leftrightarrow G, (H)$

$X \leftrightarrow G, (V)$

$XX \leftrightarrow X_1, (H)$

$XX \leftrightarrow X_1, (V)$