

You are given an image of robot's observation. Additionally, you are given the movement information of 5 points in the image. Over the last 6 frames, the 5 points moved as follows:

Point 2 moved through positions: [218,96], [200,122], [185,10], ... Point 3 moved through positions: [237,118], [208,42], [161,79], ... Point 4 moved through positions: [225,49], [200,127], [171,72], ... Point 5 moved through positions: [251,93], [200,103], [181,91], ...

Now what the robot should do to pick up the coke can?