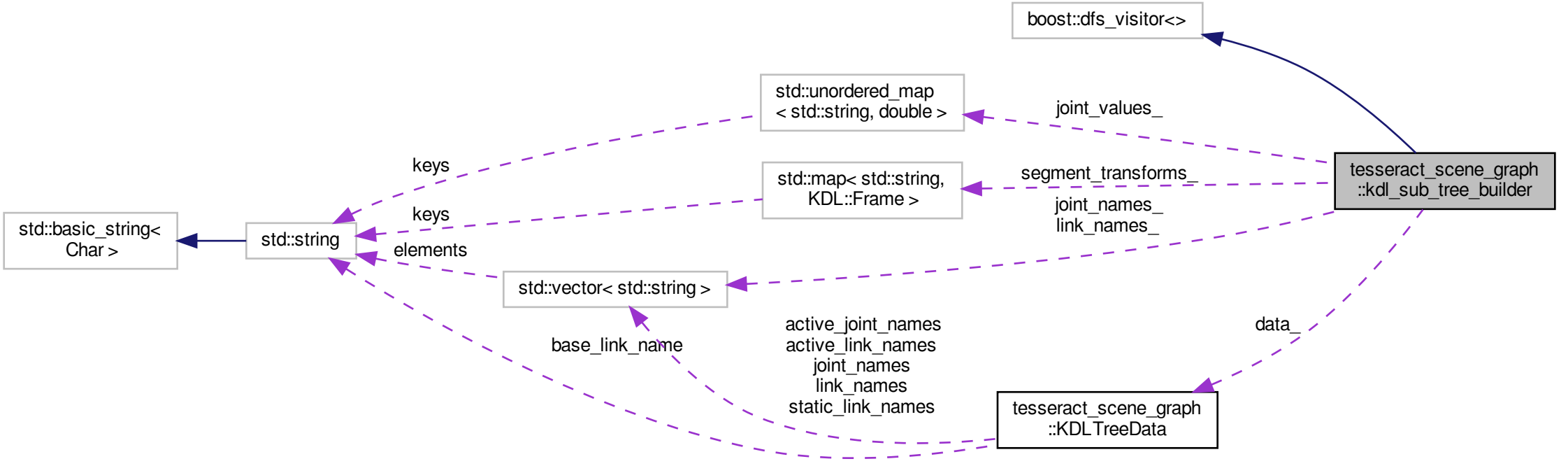
boost::dfs_visitor<>
std::unordered_map
< std::string, double >
joint_values_
keys
std::map< std::string,
KDL::Frame >
segment_transforms_
tesseract_scene_graph
::kdl_sub_tree_builder
keys
joint_names_
link_names_
std::basic_string<
Char >
std::string
elements
std::vector< std::string >
base_link_name
active_joint_names
active_link_names
joint_names
link_names
static_link_names
data_
tesseract_scene_graph
::KDLTreeData