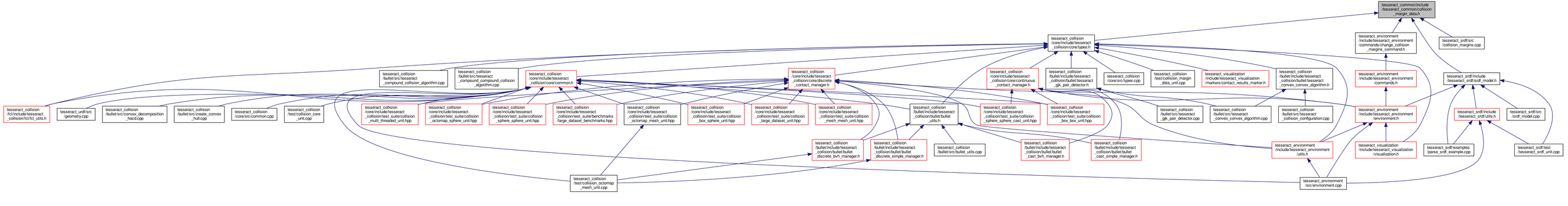
tesseract_common/include/tesseract_common/collision_margin_data.h
tesseract_collision/core/include/tesseract_collision/core/types.h
tesseract_environment/include/tesseract_environment/commands/change_collision_margins_command.h
tesseract_srdf/src/collision_margins.cpp
tesseract_collision/bullet/src/tesseract_compound_collision_algorithm.cpp
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tesseract_collision/core/include/tesseract_collision/core/common.h
tesseract_collision/core/include/tesseract_collision/core/discrete_contact_manager.h
tesseract_collision/core/include/tesseract_collision/core/continuous_contact_manager.h
tesseract_collision/bullet/include/tesseract_collision/bullet/tesseract_gjk_pair_detector.h
tesseract_collision/core/src/types.cpp
tesseract_collision/test/collision_margin_data_unit.cpp
tesseract_visualization/include/tesseract_visualization/markers/contact_results_marker.h
tesseract_collision/bullet/include/tesseract_collision/bullet/tesseract_convex_convex_algorithm.h
tesseract_environment/include/tesseract_environment/commands.h
tesseract_srdf/include/tesseract_srdf/srdf_model.h
tesseract_collision/fcl/include/tesseract_collision/fcl/fcl_utils.h
tesseract_urdf/src/geometry.cpp
tesseract_collision/bullet/src/convex_decomposition_hacd.cpp
tesseract_collision/bullet/src/create_convex_hull.cpp
tesseract_collision/core/src/common.cpp
tesseract_collision/test/collision_common_unit.cpp
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tesseract_collision/core/include/tesseract_collision/test_suite/collision_octomap_sphere_unit.hpp
tesseract_collision/core/include/tesseract_collision/test_suite/collision_sphere_sphere_unit.hpp
tesseract_collision/core/include/tesseract_collision/test_suite/benchmarks/large_dataset_benchmarks.hpp
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tesseract_collision/bullet/src/tesseract_collision_configuration.cpp
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tesseract_environment/include/tesseract_environment/utils.h
tesseract_visualization/include/tesseract_visualization/visualization.h
tesseract_srdf/examples/parse_srdf_example.cpp
tesseract_srdf/test/tesseract_srdf_unit.cpp
tesseract_collision/test/collision_octomap_mesh_unit.cpp
tesseract_environment/src/environment.cpp