

tesseract\_collision  
/include/tesseract\_collision  
/bullet/tesseract\_convex  
\_convex\_algorithm.h

```
graph BT; A["tesseract_collision  
/src/bullet/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_convex  
_convex_algorithm.h"]; B["tesseract_collision  
/src/bullet/tesseract  
_convex_convex_algorithm.cpp"] --> C;
```

This diagram illustrates the relationship between three files in the tesseract\_collision library. At the top is a header file, tesseract\_collision/include/tesseract\_collision/bullet/tesseract\_convex\_convex\_algorithm.h, which is shaded gray. Below it are two source files: tesseract\_collision/src/bullet/tesseract\_collision\_configuration.cpp on the left and tesseract\_collision/src/bullet/tesseract\_convex\_convex\_algorithm.cpp on the right. Both source files have blue arrows pointing up to the header file, indicating that they include it.

tesseract\_collision  
/src/bullet/tesseract  
\_collision\_configuration.cpp

tesseract\_collision  
/src/bullet/tesseract  
\_convex\_convex\_algorithm.cpp