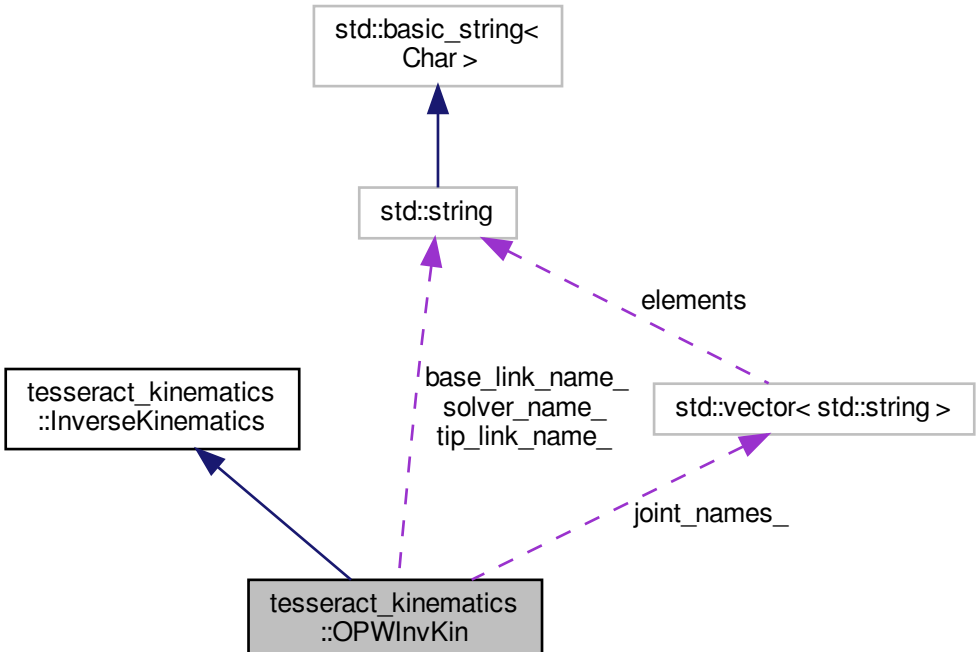
std::basic_string<
Char >
std::string
elements
tesseract_kinematics
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base_link_name_
solver_name_
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joint_names_
tesseract_kinematics
::OPWInvKin