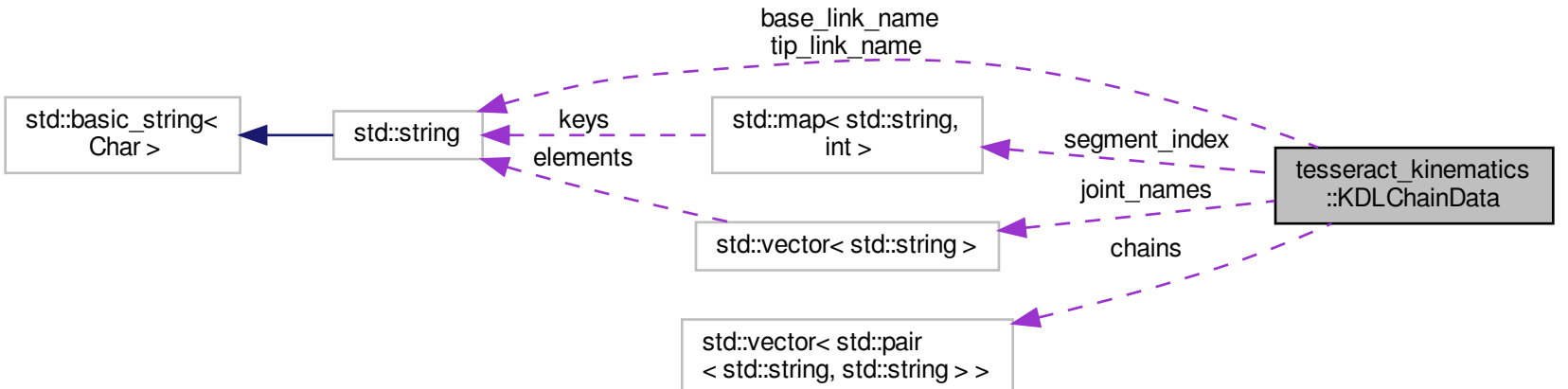
base_link_name
tip_link_name
std::basic_string< Char >
std::string
keys
elements
std::map< std::string, int >
segment_index
tesseract_kinematics ::KDLChainData
joint_names
std::vector< std::string >
chains
std::vector< std::pair < std::string, std::string > >