

tesseract_collision
/include/tesseract_collision
/bullet/tesseract_collision
_configuration.h

```
graph TD; A["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_collision  
_configuration.h"] --> B["tesseract_common/macros.h"]; A --> C["BulletCollision/Collision  
Dispatch/btDefaultCollisionConfiguration.h"];
```

The diagram illustrates the include structure for the tesseract_collision configuration file. The top box, which has a gray background, represents the main configuration file. Two blue arrows point from its bottom edge to two separate boxes below. The left box contains the path to tesseract_common/macros.h, and the right box contains the paths to BulletCollision/CollisionDispatch/btDefaultCollisionConfiguration.h.

tesseract_common/macros.h

BulletCollision/Collision
Dispatch/btDefaultCollisionConfiguration.h