

tesseract\_collision  
/include/tesseract\_collision  
/bullet/tesseract\_compound  
\_compound\_collision\_algorithm.h

```
graph BT; A["tesseract_collision  
/src/bullet/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_compound  
_compound_collision_algorithm.h"]; B["tesseract_collision  
/src/bullet/tesseract  
_compound_compound_collision  
_algorithm.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `_collision_configuration.cpp` and `_compound_compound_collision_algorithm.cpp`, both include the header file `_compound_collision_algorithm.h`. The header file is located in the `/include/tesseract_collision/bullet/` directory, while the source files are in the `/src/bullet/tesseract/` directory.

tesseract\_collision  
/src/bullet/tesseract  
\_collision\_configuration.cpp

tesseract\_collision  
/src/bullet/tesseract  
\_compound\_compound\_collision  
\_algorithm.cpp