



# ML Math Club: Calculus for Optimization

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```
lookup.KeyValue  
f.constant(['em  
=tf.constant([G  
lookup.StaticV  
_buckets=5)
```

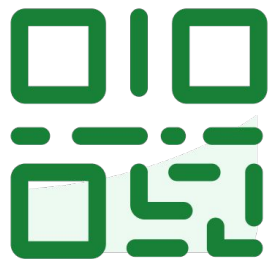
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1. Introduction to Optimization
2. Derivatives and Partial Derivatives
3. Gradient
4. Jacobians
5. Gradient Descent
6. Exercises and Coding Examples



Google Developer Groups

```
/*1*/  
child: Column(  
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  children: [  
    /*2*/  
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      child: const Text(  
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      style: TextStyle(  
        fontWeight: FontWeig  
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    ),  
  ],  
),  
),  
)
```



Join at [slido.com](https://slido.com)  
**#4587614**

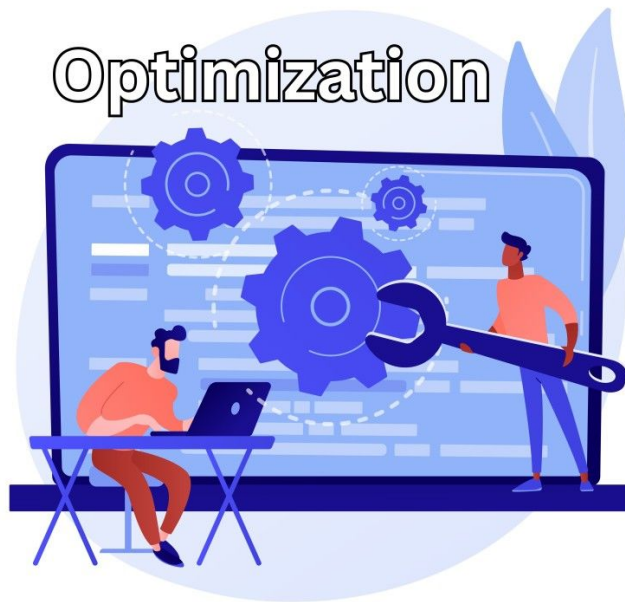


# Introduction to Optimization

```
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```

# What is Mathematical Optimization ?

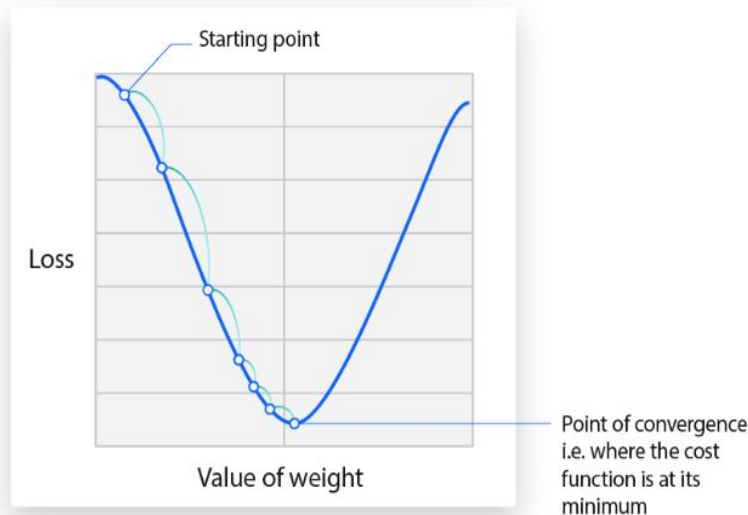
“**Optimization**” comes from the same root as “optimal”, which means best. When you optimize something, you are “making it best”. But “best” can vary. If you’re a runner, you might want to maximize your speed and distance, and also minimize your risk of injury. Both maximizing and minimizing are types of optimization problems...



# Why Optimization Matters in ML?

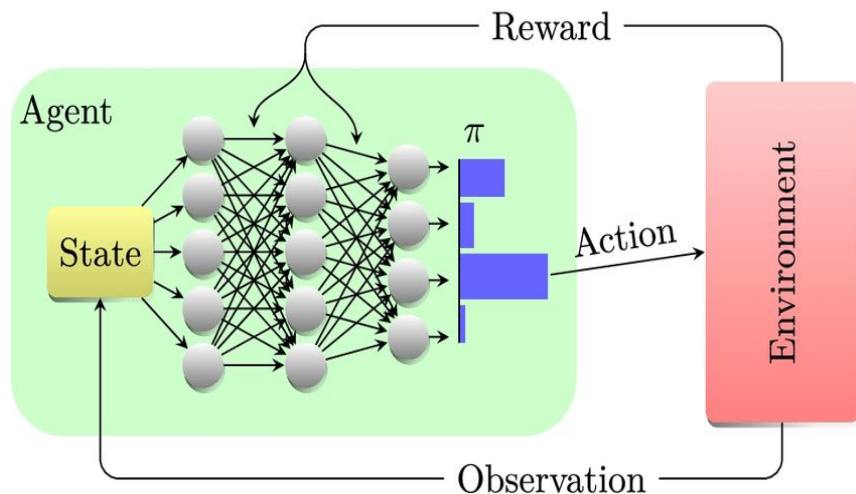
Optimization is at the core of many machine learning tasks. Here are some key areas where optimization techniques are applied:

**Model Training:** Minimize the loss function to improve model accuracy.



# Why Optimization Matters in ML?

Reinforcement Learning: Optimization is used to maximize rewards in reinforcement learning, where an agent learns by interacting with an environment.





# What does "optimization" mean?





# Derivatives and Partial Derivatives

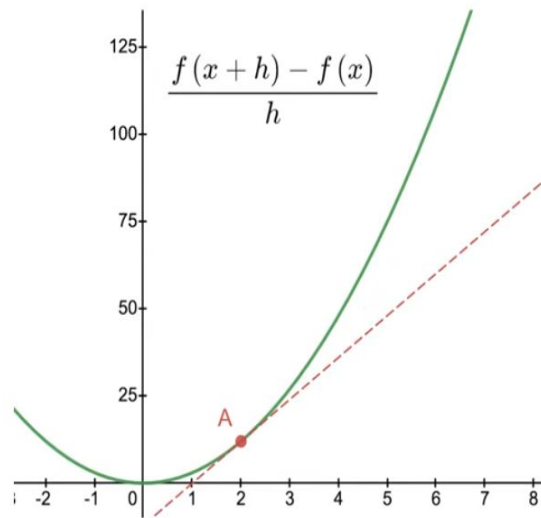
```
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lookup.StaticV  
_buckets=5)
```

# Derivatives

**Rate of Change** of a function with respect to its variable.

The derivative at a point represents the **slope of the tangent line** to the curve at that point.

Notation:  $f'(x)$  or  $\frac{df}{dx}(x)$ .



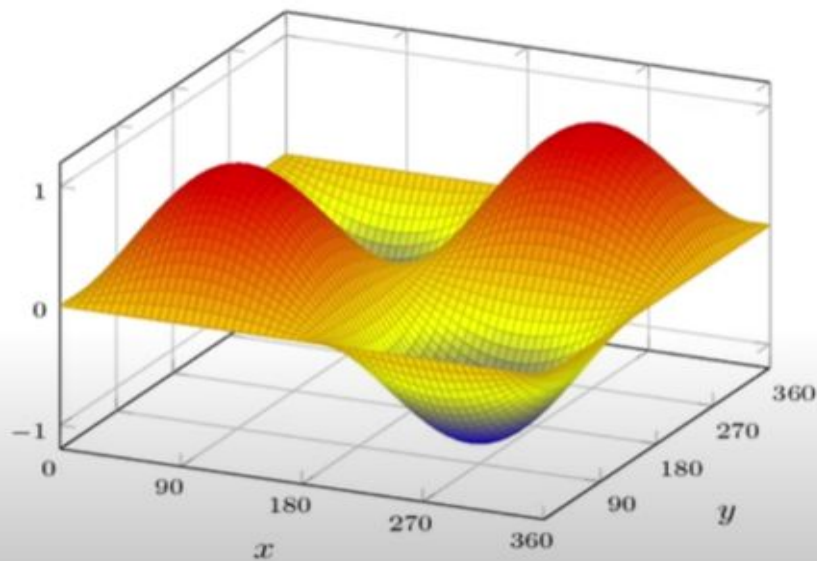
<https://www.desmos.com/calculator/ic9r3mgsxu?>

# Partial Derivatives

A partial derivative measures the rate of change of a function with respect to one of its variables while keeping all other variables constant.

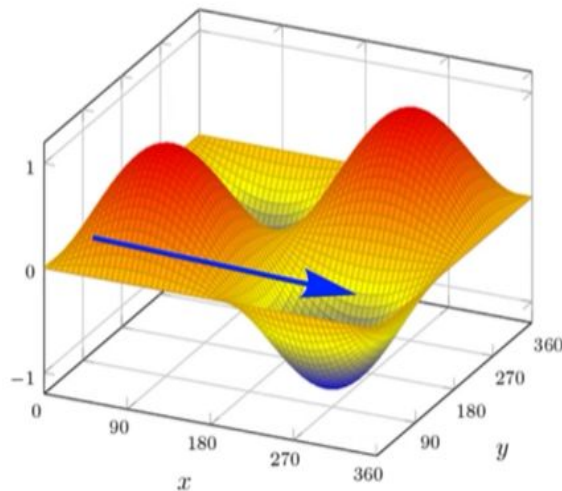
$$\frac{\partial f}{\partial x}(x, y) = \lim_{h \rightarrow 0} \frac{f(x + h, y) - f(x, y)}{h},$$
$$\frac{\partial f}{\partial y}(x, y) = \lim_{h \rightarrow 0} \frac{f(x, y + h) - f(x, y)}{h}$$

$f(x, y)$



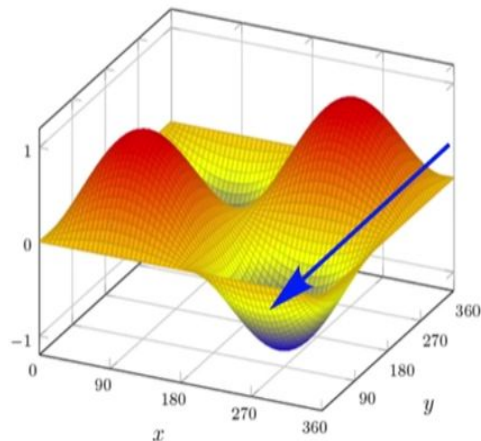
$f(x, y)$

$$\frac{\partial}{\partial x}$$



**partial derivative with respect to x**

$f(x, y)$



$$\frac{\partial}{\partial y}$$



**partial derivative with respect to  $y$**

$$f(x, y) = xy^2 + x^3$$

$$\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} (x)y^2 + \frac{\partial}{\partial x} (x^3) = y^2 + 3x^2$$

$$\frac{\partial f}{\partial y} = \frac{\partial}{\partial y} x(y^2) + \frac{\partial}{\partial y} x^3 = 2xy$$

these are the **rates of change** for the function

<https://www.desmos.com/3d/out3uua3js>



Given the function  $f(x,y) = 3x^2y + 2xy^2 + x$ ,  
what is the partial derivative of  $f$  with  
respect to  $x$  and  $y$





# Gradient & Jacobian

```
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```

# Gradient

The gradient of a function is a vector of its partial derivatives.

Explanation: Points in the direction of the greatest increase of the function and its magnitude represents the rate of increase.

notation :

$$\nabla f(p) = \left( \frac{\partial f}{\partial x_1}(p), \dots, \frac{\partial f}{\partial x_n}(p) \right)$$

# Jacobian

The Jacobian matrix of a vector-valued function  $\mathbf{f}(x_1, x_2, \dots, x_n)$  is a matrix of its first-order partial derivatives.

Notation:

$$\mathbf{J}_f = \begin{bmatrix} \frac{\partial \mathbf{f}}{\partial x_1} & \cdots & \frac{\partial \mathbf{f}}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \nabla^\top f_1 \\ \vdots \\ \nabla^\top f_m \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

Example:

Consider a function  $\mathbf{f} : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ , with  $(x, y) \mapsto (f_1(x, y), f_2(x, y))$ , given by

$$\mathbf{f} \left( \begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} f_1(x, y) \\ f_2(x, y) \end{bmatrix} = \begin{bmatrix} x^2 y \\ 5x + \sin y \end{bmatrix}.$$

The Jacobian matrix of  $\mathbf{f}$  is:

$$\mathbf{J}_{\mathbf{f}}(x, y) = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} = \begin{bmatrix} 2xy & x^2 \\ 5 & \cos y \end{bmatrix}$$

# Gradient Descent

```
lookup.KeyValue  
f.constant(['em  
=tf.constant([G  
.lookup.StaticV  
_buckets=5)
```

## Understanding Gradient Descent

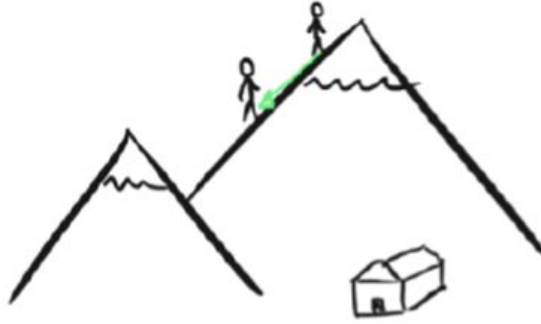
Imagine being lost in the mountains. Your goal is to reach the shelter at the lowest point in the valley. Without a map, you don't know the shelter's exact location—you must find it on your own.



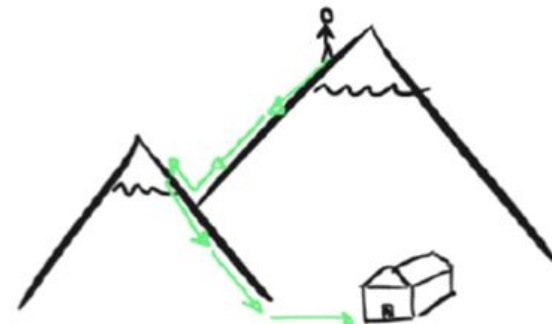
## solution



Step 1: Find the steepest slope

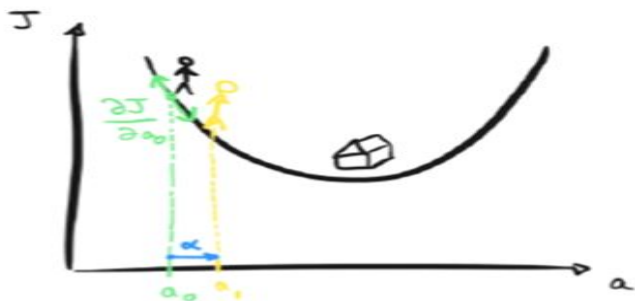
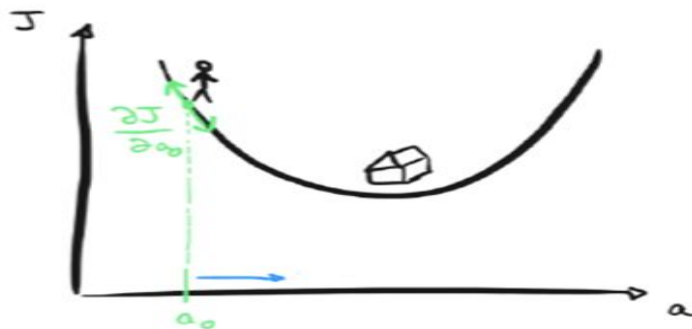
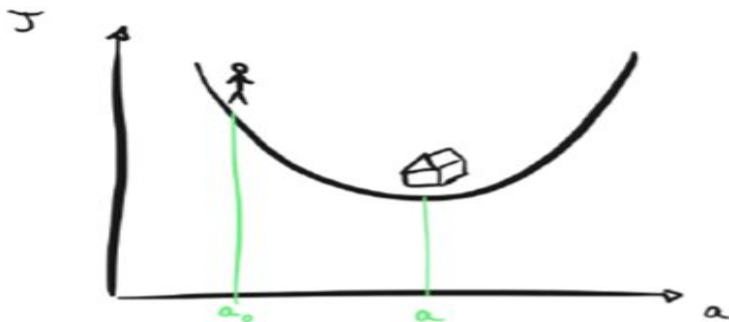


Step 2: Walk some distance in that direction



Step 3: Repeat steps 1 and 2 in a loop

Step 1: Calculate the gradient





**Our ultimate goal:** Find the parameters  $a$  and  $b$  that minimize  $J(a, b)$ .

To achieve this, we will start by choosing  $a$  and  $b$  randomly (starting from an arbitrary point on the mountain) and then iteratively use gradient descent to update our parameters in the direction that lowers the Cost Function the most.

**Repeat in a loop:**

$$a = a - \alpha \frac{\partial J(a, b)}{\partial a}$$

$$b = b - \alpha \frac{\partial J(a, b)}{\partial b}$$

$J$  : Loss Function

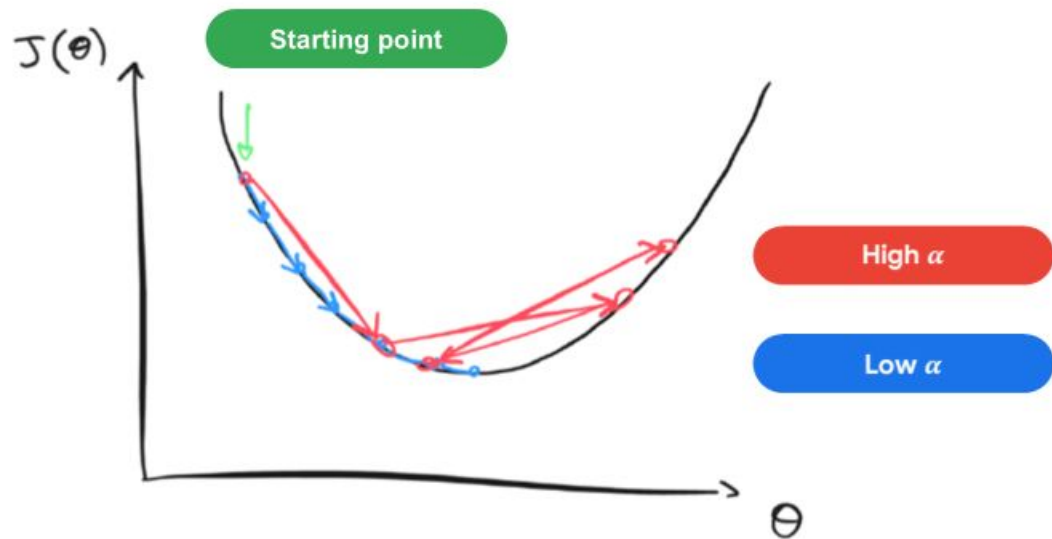
$\alpha$  : Learning rate

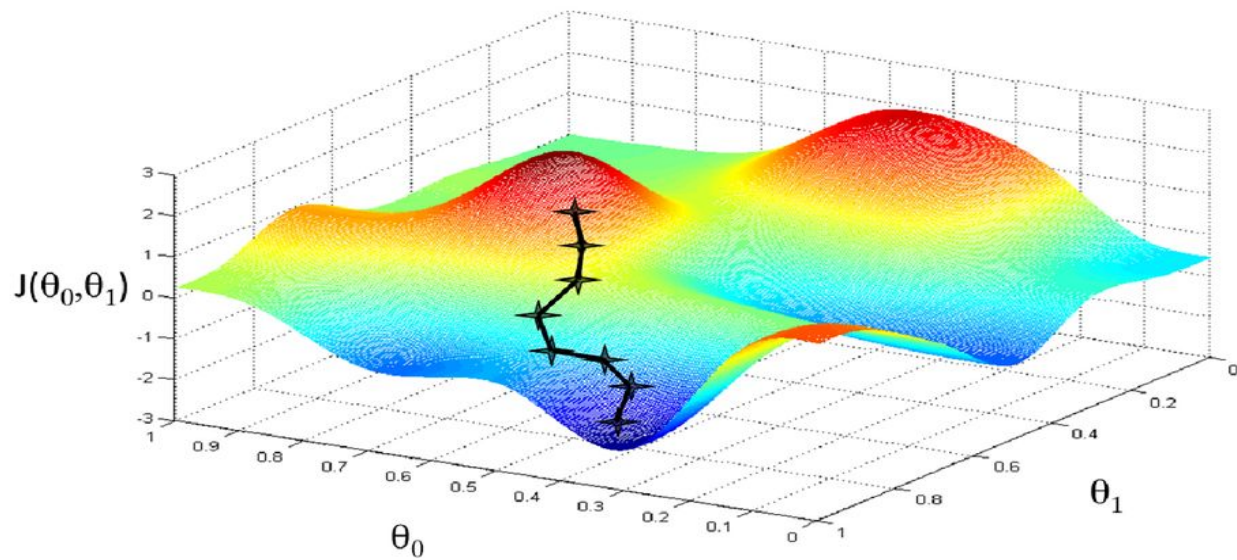
$a$  : Slope

$b$  : Intercept



## Effect of Learning Rate ( $\alpha$ ) on Gradient Descent





**Gradient Descent**

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child: Column(  
  crossAxisAlignment: CrossAxisAlignment.  
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```

# QUIZ!



**If the learning rate is too small, gradient descent will converge very slowly?**





# What happens if the learning rate is too high?



