



# Algorithms for Wireless Communications II

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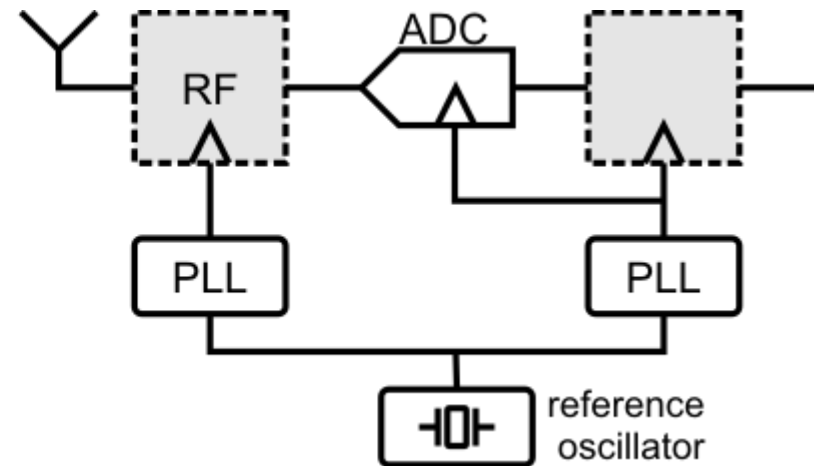
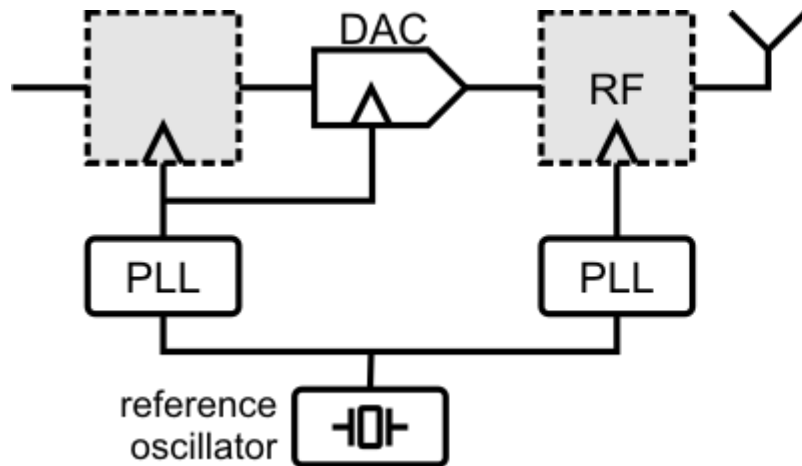
Telecommunications Circuits Laboratory, EPFL

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# OFDM Synchronization

# The Need for Synchronization



- A reference oscillator provides a reference frequency
  - Typical references: 1 MHz, 10 MHz, or 20 MHz (good quartz oscillators available)
- All system frequencies (sampling frequency and carrier frequency) are derived from this reference using Phase Locked Loops

## Each device has its own reference

- References are never 100% accurate
- Signal propagation causes an unknown delay (phase) between devices

# The Need for Synchronization

- Frequency reference oscillators are specified only by ist nominal value
- Individual parts can and do deviate from this nominal value
- Oscillator accuracy is espressed in *Parts per Million [ppm]*
  - Frequency independent metric
  - PPM is typically specified on both directions
- Impact of oscillator accuracy on frequency offset/error

$$\text{Reference: } \Delta f_{\text{ref}} = \varphi \frac{f_{\text{ref}}}{10^6}$$

$$\text{After PLL: } \Delta f_0 = \varphi \frac{f_{\text{ref}}}{10^6} \frac{N}{K} = \varphi \frac{f_0}{10^6}$$

- Typical reference accuracy: 8 – 20ppm

# Synchronization Errors



- Initial Timing Offset
- Carrier Frequency Offset
- Signal to Noise Ratio
- Carrier Phase Noise
- Sampling Frequency Offset



## Example: IEEE 802.11n WLAN

- Carrier frequency: 2.4 GHz
- Bandwidth (sampling frequency): 40 Mhz (128 tones: 312.5 KHz carrier spacing)
- Reference oscillator:  $\pm 10$  ppm

### ▪ Carrier frequency

$$-24 \text{ kHz} < \Delta f_0^{Tx} < +24 \text{ kHz}$$

$$-24 \text{ kHz} < \Delta f_0^{Rx} < +24 \text{ kHz}$$

$$-48 \text{ kHz} < |f_0^{Tx} - f_0^{Rx}| < +48 \text{ kHz}$$

- More than 10% of the carrier spacing
- 70deg per OFDM symbol

### ▪ Sampling frequency

$$-400 \text{ Hz} < \Delta f_s^{Tx} < +400 \text{ Hz}$$

$$-400 \text{ Hz} < \Delta f_s^{Rx} < +400 \text{ Hz}$$

$$-800 \text{ Hz} < |f_s^{Tx} - f_s^{Rx}| < +800 \text{ Hz}$$

- 1 sample per 300 OFDM symbols

# Synchronization (Tx Matched Filter)



**Received signal with frequency offset (no noise) – Dirac channel**

$$y[t] = e^{\frac{2\pi\Delta f t}{N}} p[t - t_0]$$

$\Delta f$ : Frequency offset, normalized to the symbol duration. One period in  $\frac{1}{NT_s} \Rightarrow \Delta f = 1$

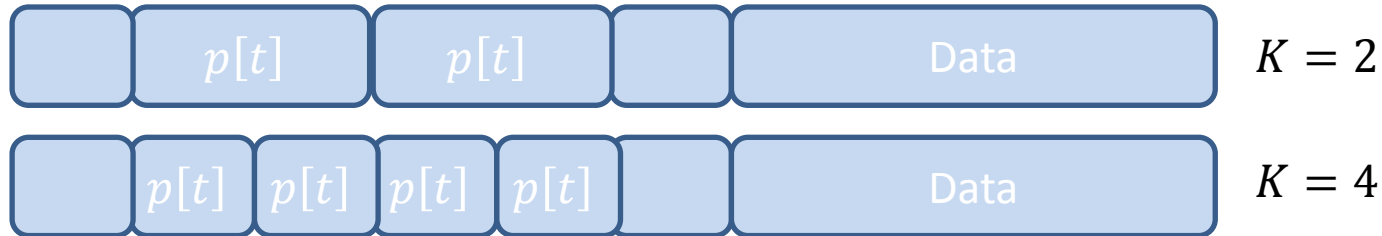
**Correlation with transmitted sequence**

$$c_{\Delta t} = \sum_{t=0}^N y[t] p^*[t - \Delta t] = \sum_{t=0}^N e^{\frac{2\pi\Delta f t}{N}} p[t - t_0] p^*[t - \Delta t]$$

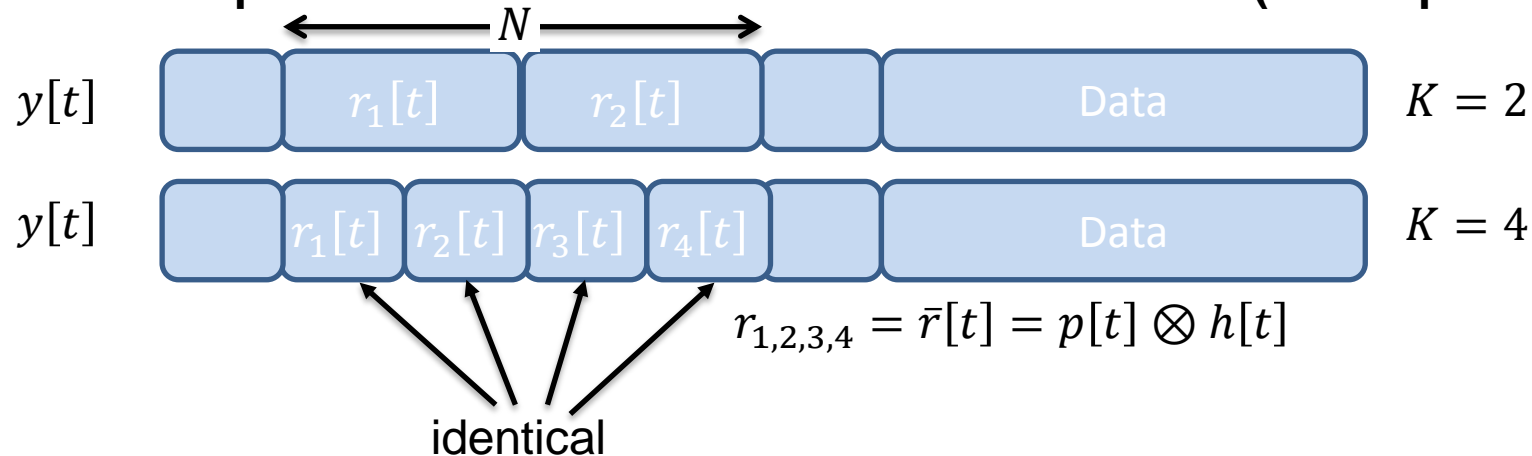
**Assume  $\Delta t = t_0$  : what happens when the normalized frequency offset  $\Delta f = 1$  ?**

# Synchronization with a Periodic Preamble

**New preamble design: OFDM symbol is periodic in itself**



**Received preamble after convolution with the channel (no freq. offset)**



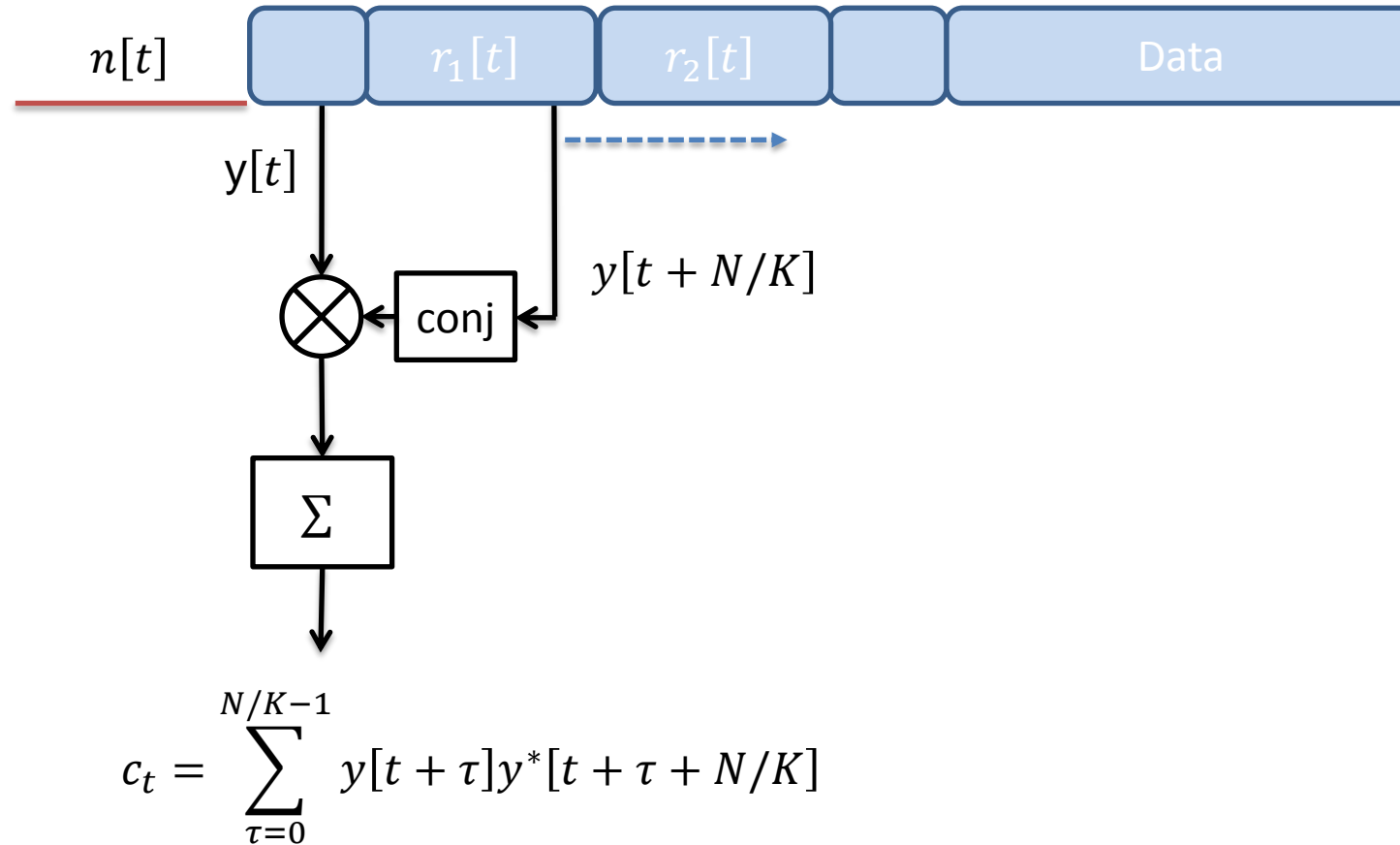
**With frequency offset:**

$$r_k[t] = e^{\frac{2\pi\Delta f t}{N} + \frac{2\pi\Delta f (k-1)}{K}} \bar{r}[t]$$



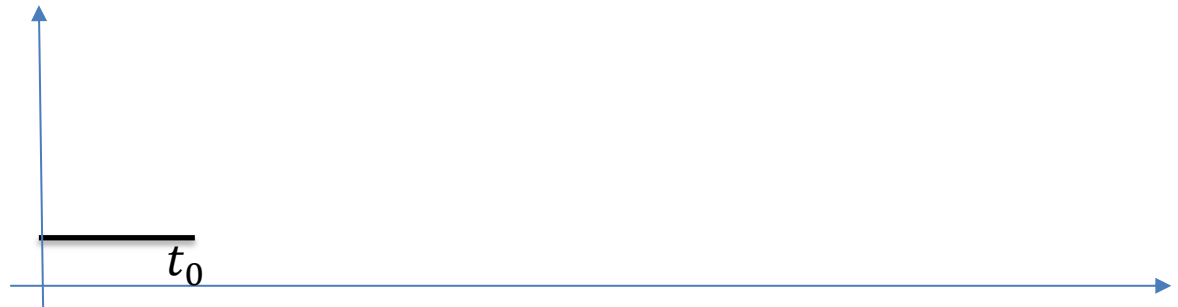
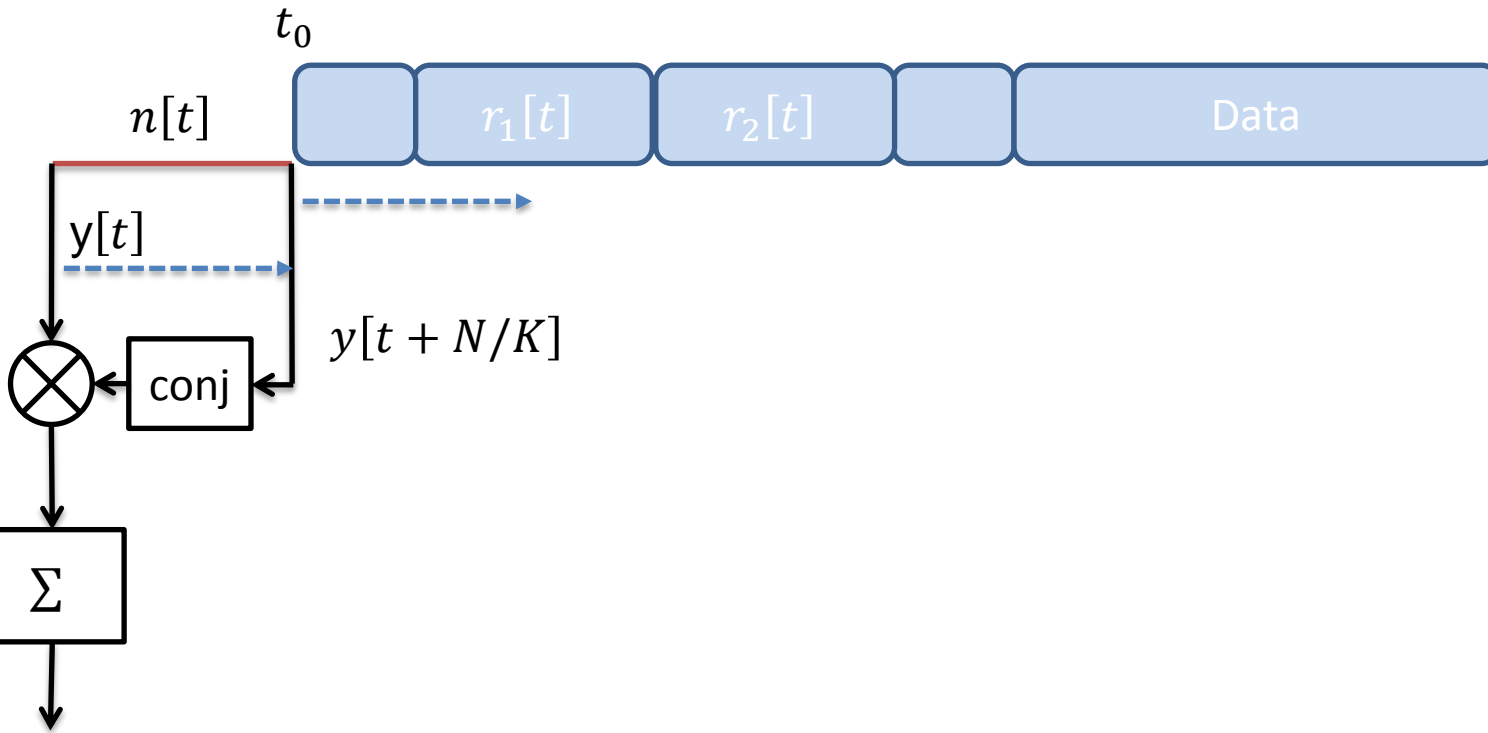
# Synchronization with a Periodic Preamble

Idea: delayed autocorrelation finds periodic sequence



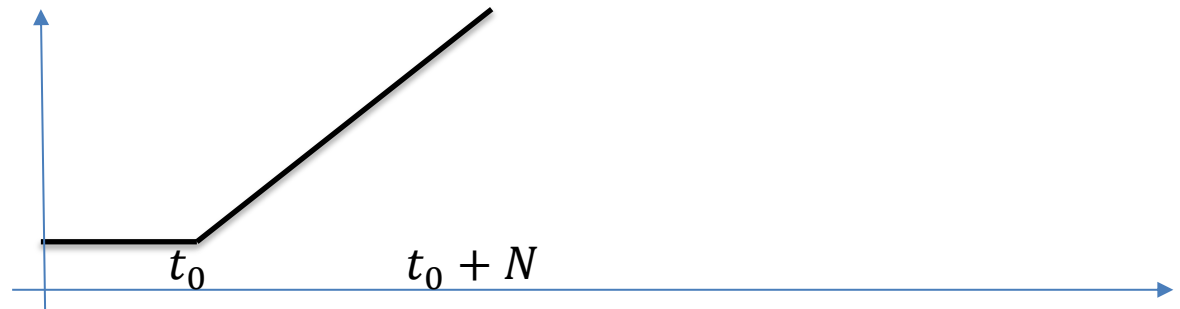
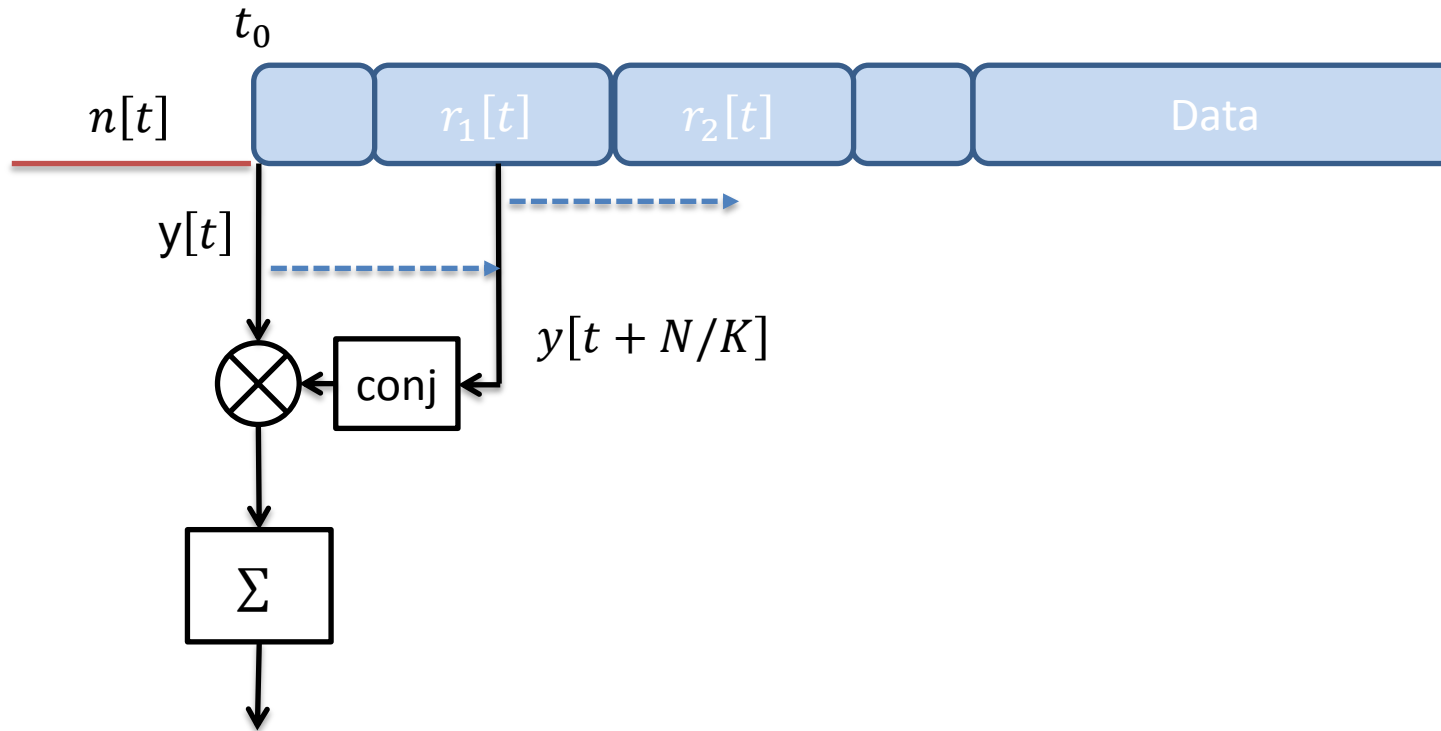
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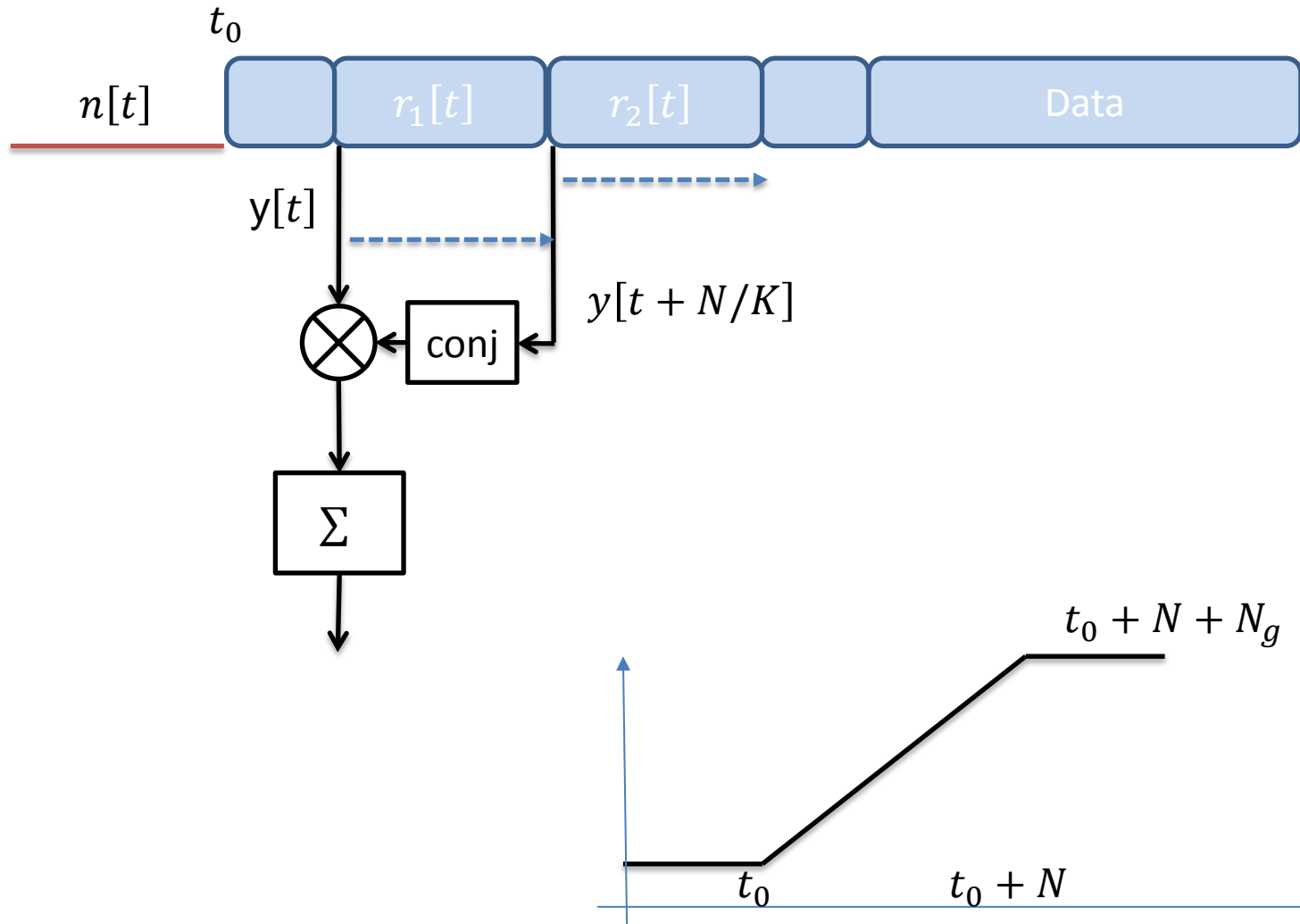
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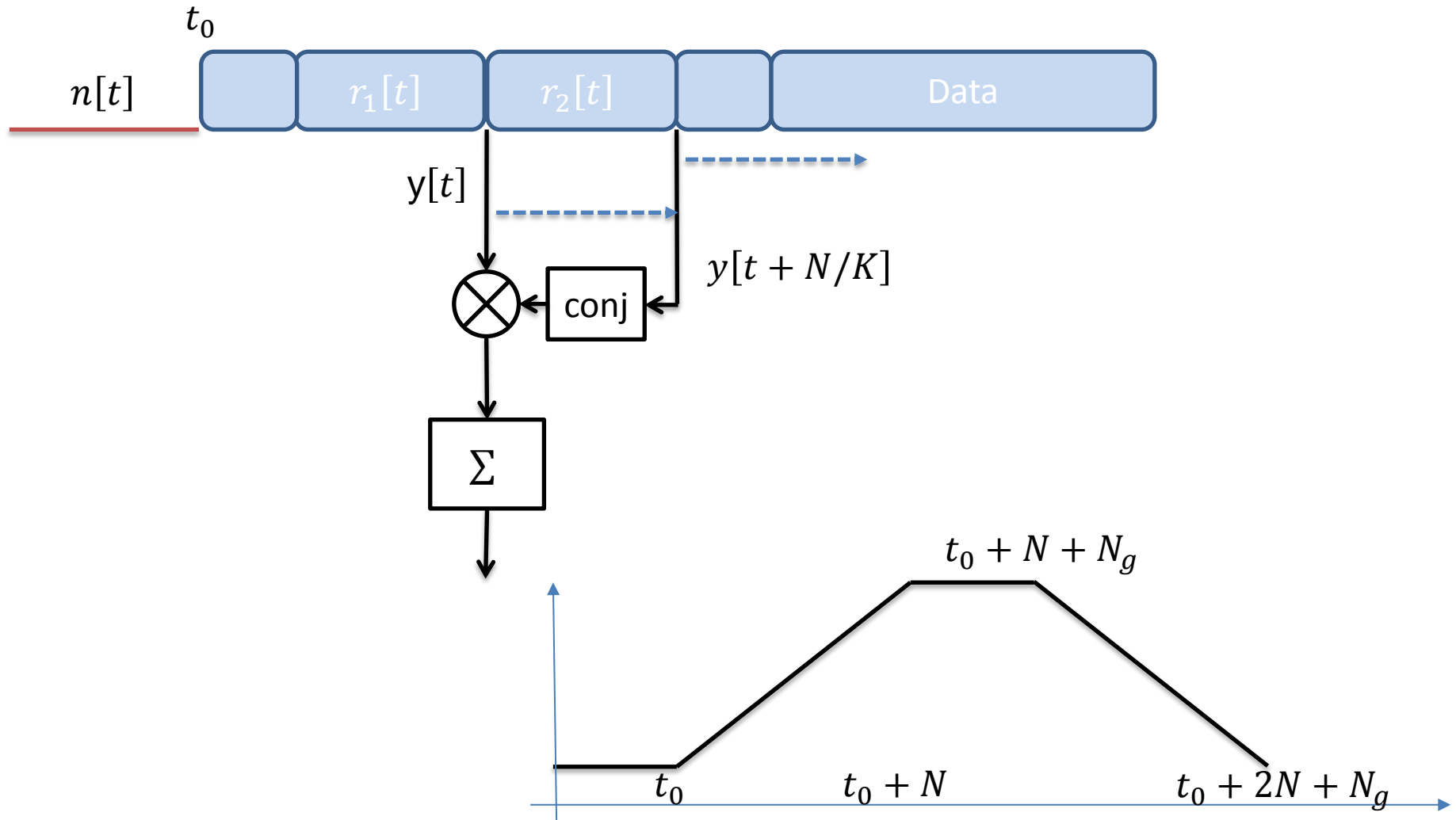
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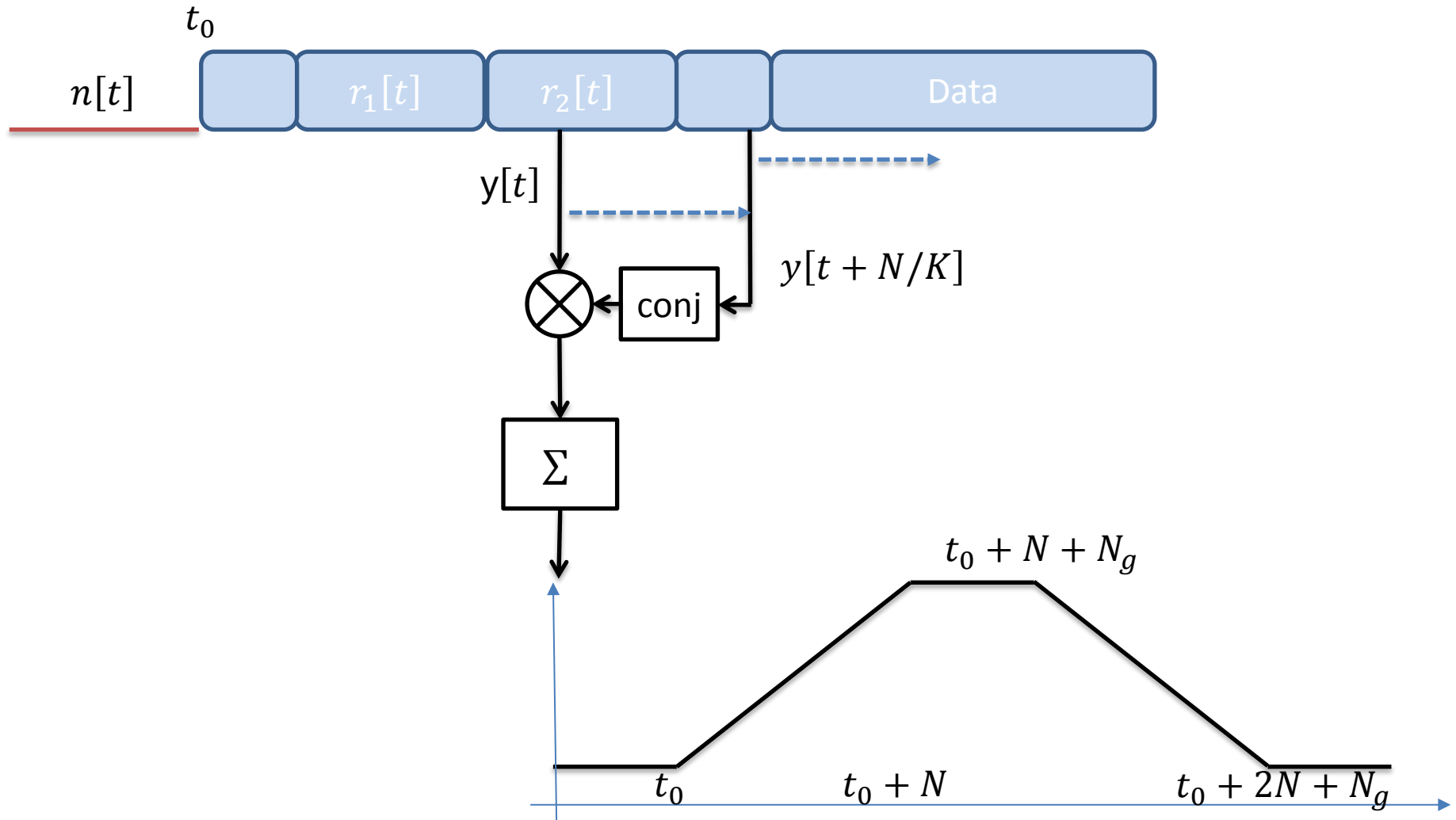
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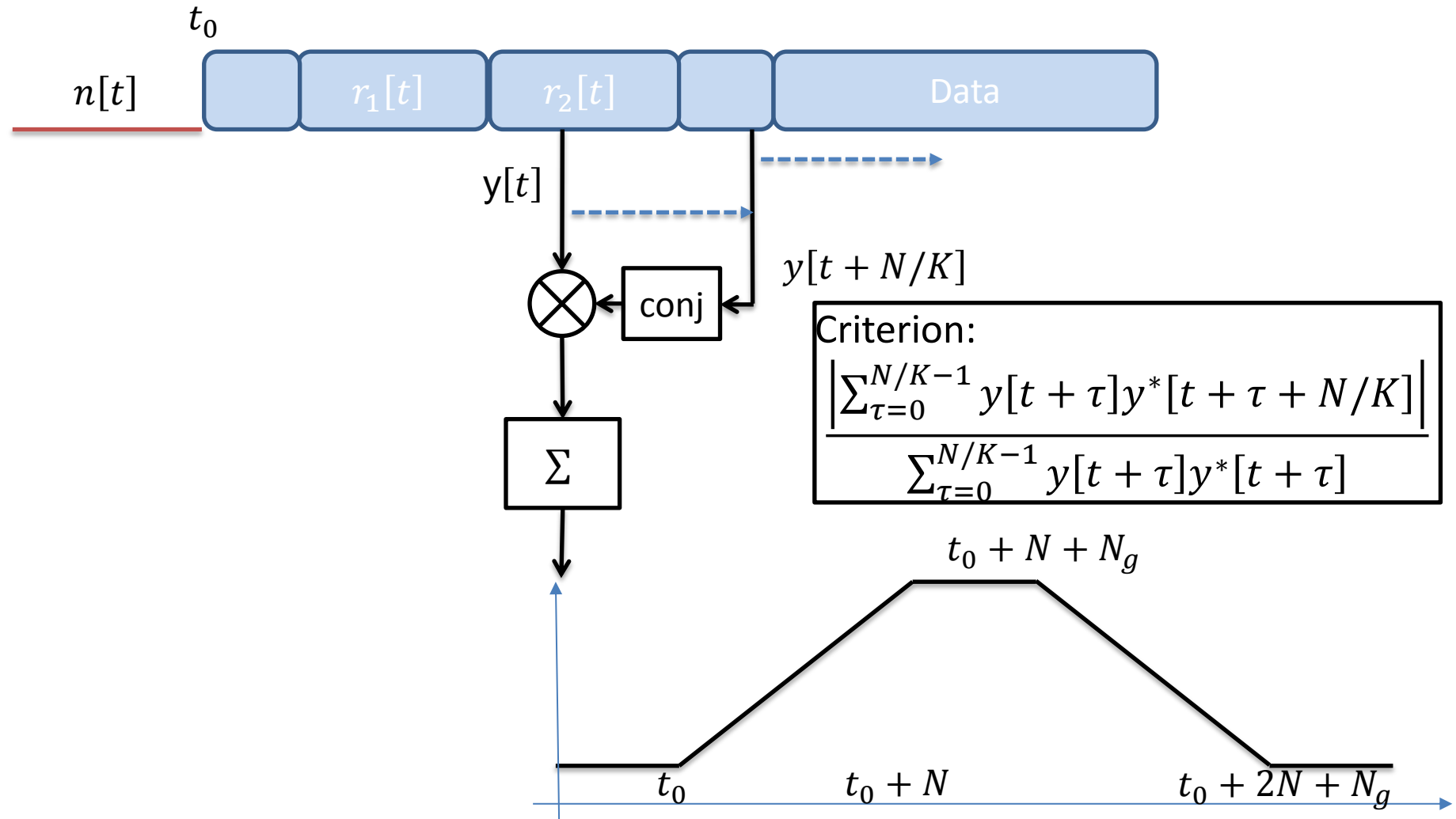
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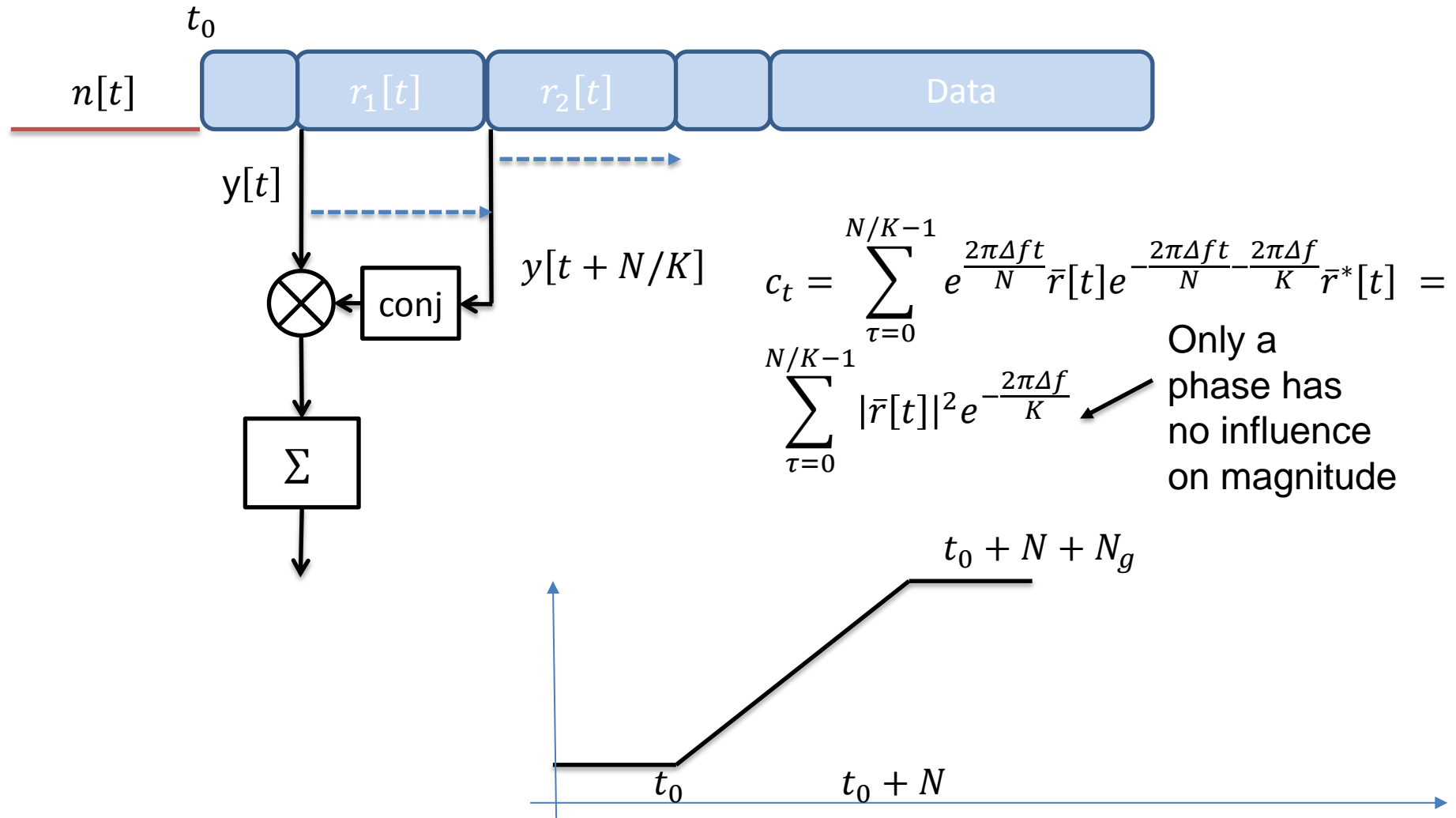
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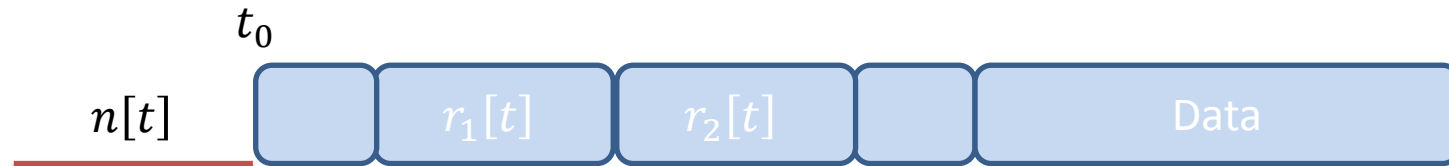
## Robustness against frequency offset





# Freq. Offset Estimation with Periodic Preamble (OFDM)

Idea: use phase of the autocorrelation at  $t_0 + N + N_g$  for freq. offset estimation



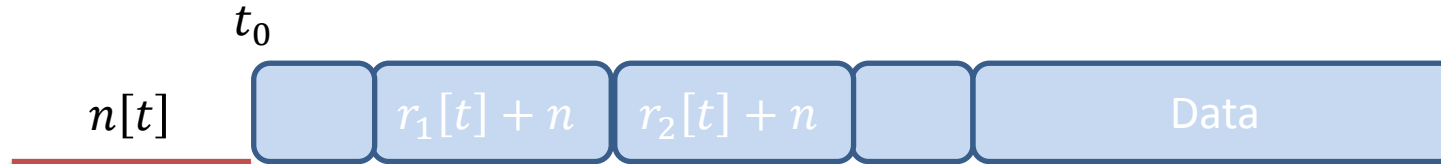
$$c_{t_0+N+N_g} = \sum_{\tau=0}^{N/K-1} |\bar{r}[t]|^2 e^{-\frac{2\pi\Delta f}{K}}$$

$$-2\pi\Delta f_0 K = \angle c_t$$

$$\Delta f_0 = -\frac{\angle c_t}{2\pi K}$$

# SNR Estimation with Periodic Preamble (OFDM)

Introduce a preamble consisting of two identical OFDM training symbols



$$y[t + kN/K] = \bar{r}[t] + n[t + kN/K]$$

$$A = \frac{1}{N} \sum_{\tau=0}^{N-1} y[t] y^*[t + kN/K] = \frac{1}{N} \sum_{\tau=0}^{N-1} \bar{r}[t] \bar{r}^*[t] + n[t] n^*[t + kN/K] \approx$$
$$E\{|\bar{r}[t]|^2\} + \underbrace{E\{n[t] n^*[t + kN/K]\}}_{\rightarrow 0}$$

$$B = \frac{1}{N} \sum_{\tau=0}^{N-1} |y[t]|^2 \approx E\{|\bar{r}[t]|^2\} + E\{|n[t]|^2\}$$
$$SNR = \frac{E\{|\bar{r}[t]|^2\}}{E\{|n[t]|^2\}} = \frac{A}{B - A}$$

# Residual carrier offset and phase noise

## Signal after CFO compensation in time domain

- Assume phase  $\Theta(t)$  changes only very slowly  $\Rightarrow$  constant within an OFDM symbol
- Does not cause inter carrier interference, but

$$y[t] = e^{j\Theta(t)} \sum_{k=0}^{\infty} s[t - k(N + N_g)] \approx \sum_{k=0}^{\infty} e^{j\Theta(k(N+N_g))} s_k[t - k(N + N_g)]$$

## Signal still rotates over time

## Consider the freq. domain representation of the $k$ th OFDM symbol

$$DFT \left\{ e^{j\Theta(k(N+N_g))} s_k[t] \right\} = e^{j\Theta(k(N+N_g))} s[f] h[f]$$

- All tones are affected equally by the frequency offset
- **Solution:** insert known Pilot tones at carrier  $f_p$  to estimate  $\Theta(k(N + N_g))$  as

$$\Theta(k(N + N_g)) = \angle \psi_k[f_p] p^*[f] h^*[f]$$

# Timing offset in frequency domain

Sampling offset leads to a drift in the start of OFDM symbols over time

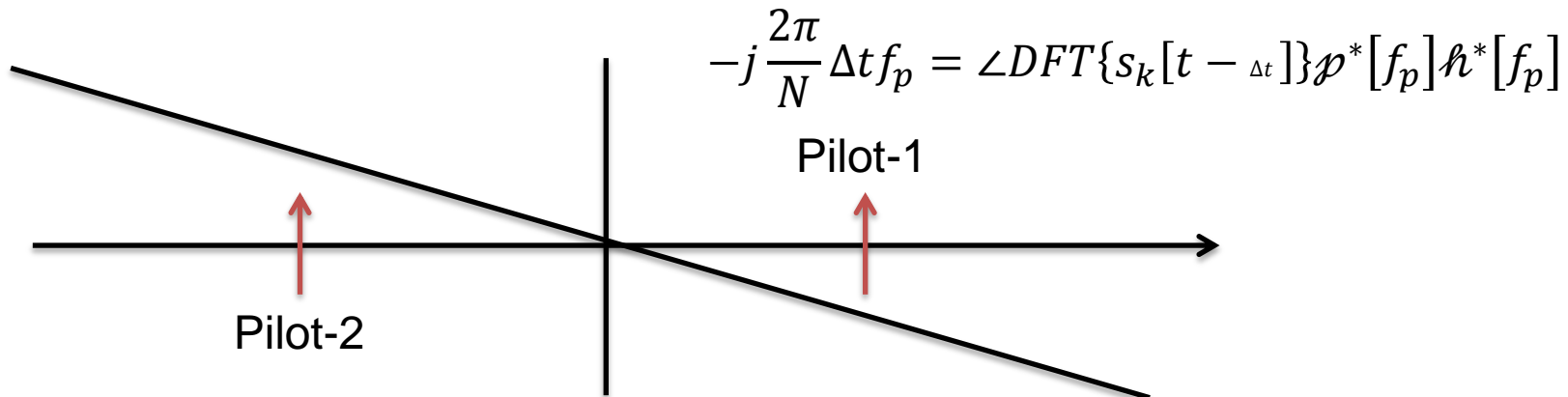


$$DFT\{y_1[t]\} = p[f]h[f]$$

$$DFT\{y_k[t]\} = DFT\{s_k[t - \Delta t]\} = s[f]h[f]e^{-j\frac{2\pi}{N}\Delta t f}$$

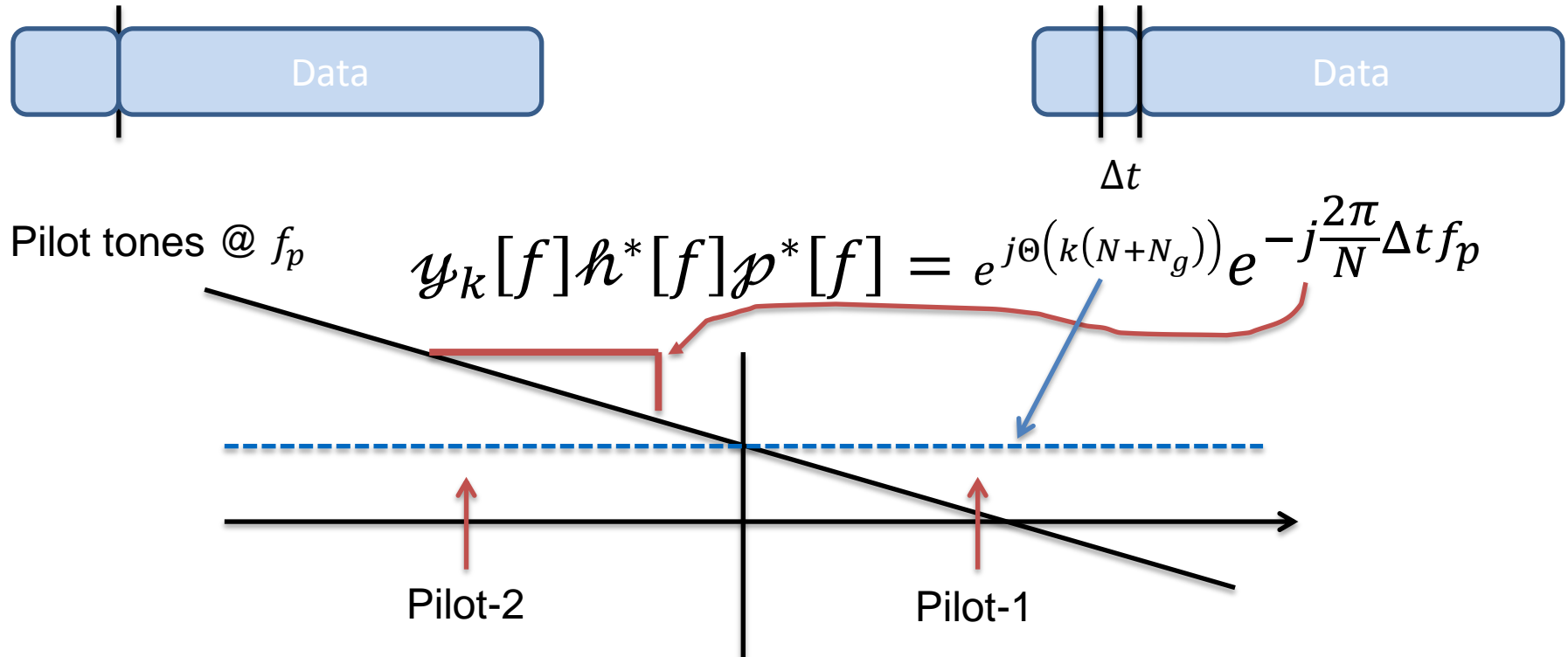
Timing offset leads to a linear phase change over tones

Pilot tones @  $f_p$        $y_k[f]h^*[f]p^*[f] = e^{-j\frac{2\pi}{N}\Delta t f_p}$



# Timing offset and phase noise in frequency domain

Sampling offset leads to a drift in the start of OFDM symbols over time



$$-j\frac{2\pi}{N}\Delta t f_p + \Theta(k(N+N_g)) = \angle DFT\{s_k[t - \Delta t]\}p^*[f_p]h^*[f_p]$$

- Slope (across tones): timing offset; mean (across tones): phase noise