SOM - Hopfield - RBF

Question 1. Which of the following statements is NOT true for a self-organizing feature map (SOM)?

- A. There are two phases during training: soft competitive learning and fine tuning.
- B. The topological mapping in a well-trained SOM preserves the probability distribution of the training data.
- C. The units are arranged in a regular geometric structure such as a 2-dimensional square or a 1-dimensional ring.
- D. The number of cluster units can be increased by adding new units if the distribution of the input data changes over time.
- E. The learning rate for the neighbors is a decreasing function of the distance from the winning unit in the geometric structures.

Question 2. Consider a self-organizing feature map (SOM), in which an input vector x and two prototype vectors p_1 and p_2 are given by

$$x = [-1.40, 2.30, 0.20]^T$$
 $p_1 = [-1.00, 2.20, 0.10]^T$ $p_2 = [-4.00, 7.00, 0.60]^T$

- a) Which prototype is nearest to x in terms of squared Euclidean distance, p_1 or p_2 ?
- b) Adapt the weight vector of the winning prototype in the above question according to the competitive learning algorithm with a learning rate of 0.5. What is the new weight vector?

A.
$$p_{winner} = [-0.80, 2.15, 0.05]^T$$

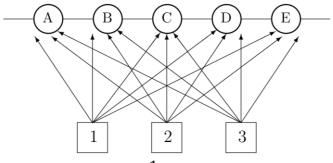
B.
$$p_{winner} = [-1.20, 2.25, 0.15]^T$$

C.
$$p_{winner} = [-2.70, 4.65, 0.40]^T$$

D.
$$p_{winner} = [-5.30, 9.35, 0.80]^T$$

Question 3. A self-organizing feature map (SOM) has 8 input units, and 100 output units arranged in a two-dimensional grid. How many weights w_{ij} does this network have?

Question 4. Below is a diagram of a self-organizing map (SOM)



By looking at the diagram answer the following questions:

- a) How many input nodes does this SOM have?
- b) How many output nodes does this SOM have?
- c) The input to an SOM can be represented by a point in an m-dimensional space (or m-dimensional vector). How many dimensions are in the space that this SOM is analyzing?
- d) How many weights does each of the output nodes have?
- e) How many output nodes can fire simultaneously?
- f) Is it important what value the output node sends when it fires?
- g) Is there any limit on how many data points (input patterns) this SOM can analyze?
- h) How many clusters can this SOM detect in the input data?
- i) If node D is the winner, which output nodes are its immediate neighbors?

Question 5. A Hopfield network has 20 units. How many adjustable parameters (i.e., weights w_{ij}) does this network contain?

Question 6. Which of the following statements is NOT true for a Hopfield network?

- A. The output of the units is often specified by a bipolar step function.
- B. The weight matrix is symmetric that is, $w_{ij} = w_{ji}$ for all units i and j.
- C. A unit can be connected to itself that is, $w_{ii} \neq 0$ for all units i.
- D. The Hopfield network minimizes an energy function during recall

Question 7. Consider a Hopfield network.

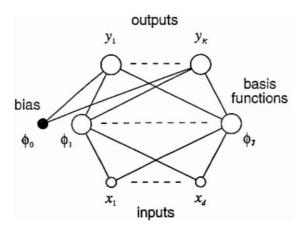
- a) Calculate the weight matrix to store the pattern $\begin{bmatrix} 1 & -1 & 1 & -1 \end{bmatrix}$
- b) Calculate the weight matrix to store two patterns [1 -1 1 -1] and [-1 -1 -1 1]
- c) The trained Hopfield network in b) is used for recall. A pattern [-1 -1 1 -1] is presented to the network, then the nodes of the network are updated until a steady state is reached. What is the final state of the network?

Question 8. A radial basis function (RBF) network has 1 input unit, 10 radial basis function units and 5 output units. How many adjustable parameters does this network have?

Question 9. The below figure shows a two-layer radial basis function (RBF) network with Gaussian radial basis functions in the hidden units defined by

$$\phi_j(x) = \exp\left(-\frac{\left\|x - m_j\right\|^2}{2\sigma_j^2}\right)$$

where m_j is the mean vector and σ_j^2 is the variance for hidden unit j, x is the input vector, and ||a-b|| refers to the Euclidean distance between two vectors a and b.



The following are steps of a training procedure for the given RBF network.

- (i) Decide the number of basis functions.
- (ii) Calculate the variance σ j2 from the training data for each cluster j.
- (iii) Calculate the mean vectors mj using an unsupervised learning algorithm such as the SOFM.
- (iv) Train the weights for the output units using a supervised learning algorithm such as the Delta rule.

What is the correct sequence for training this network?

- A. (i), (ii), (iii), (iv).
- B. (i), (iii), (ii), (iv).
- C. (ii), (i), (iii), (iv).
- D. (ii), (iii), (iv), (i).

Question 10. Which one of the following statements is NOT true in the comparison of RBF networks and multi-layer perceptrons (MLP)?

- A. The decision boundaries formed by the hidden units are hyper-planes for the MLP and hyper-spheres for an RBF network.
- B. The supervised training is highly non-linear with problems of local minima for the MLP, but linear for an RBF network.
- C. All the parameters in an RBF network are determined at the same time using a global training strategy, but a MLP network is often trained in two stages (supervised and unsupervised learning).
- D. The training of an RBF network is usually faster than that of a MLP.
- E. RBF and MLP networks are both able to approximate arbitrary non-linear functions.