

## Even More Connected Systems Practice

#1)

$$m_1 = 2.25 \text{ kg}$$

$$m_2 = 0.600 \text{ kg}$$

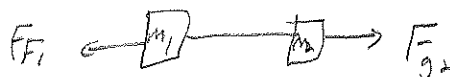
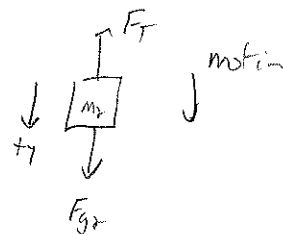
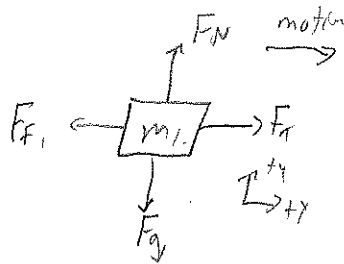
$$\vec{F}_1 = 2.25 \text{ N [W]}$$

$$a_{\text{sys}} = ?$$

$$\vec{g} = 9.81 \text{ m/s}^2 \text{ [down]}$$

$$\vec{a}_{1y} = 0 \text{ m/s}^2$$

$$m_{\text{sys}} = m_1 + m_2 = 2.85 \text{ kg}$$



$$F_{\text{net, sys}} = F_{g2} - F_{f1} = m_{\text{sys}} a_{\text{sys}}$$

$$a_{\text{sys}} = \frac{m_2 g - F_{f1}}{m_{\text{sys}}} = \frac{(0.600 \text{ kg})(9.81 \text{ m/s}^2) - 2.25 \text{ N}}{2.85 \text{ kg}}$$

$$= 1.2758 \text{ m/s}^2 = 1.28 \text{ m/s}^2$$

$$\boxed{\vec{a}_1 = 1.28 \text{ m/s}^2 \text{ [E]}}$$

#2)

$$\mu_k = 0.211$$

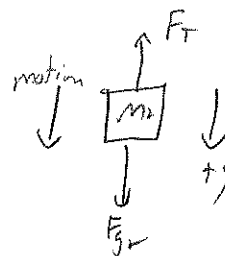
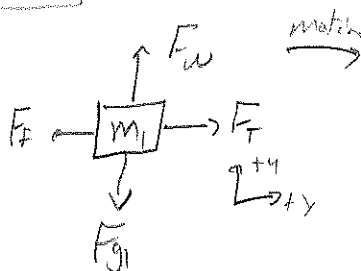
$$m_2 = 346 \text{ g}$$

$$a_{\text{sys}} = 0.109 \text{ m/s}^2$$

$$\vec{g} = 9.81 \text{ m/s}^2$$

$$\vec{a}_{1y} = 0 \text{ m/s}^2$$

$$m_1 = ?$$



$$F_{\text{net, sys}} = F_{g2} - F_f = m_{\text{sys}} a_{\text{sys}}$$

$$F_{\text{net, 1y}} = F_N - F_{g1} = m a_{y1} = 0 \text{ N} \rightarrow F_N = F_{g1} = m_1 g$$

$$F_f = \mu_k F_N = \mu_k m_1 g$$

$$m_{\text{sys}} a_{\text{sys}} = m_2 g - \mu_k m_1 g$$

$$m_1 a_{\text{sys}} + m_2 a_{\text{sys}} = m_2 g - \mu_k m_1 g$$

$$m_2 g - m_2 a_{sys} = m_1 a_{sys} + \mu_k m_1 g$$

$$m_2 (g - a_{sys}) = m_1 (a_{sys} + \mu_k g)$$

$$m_1 = \frac{m_2 (g - a_{sys})}{(a_{sys} + \mu_k g)} = \frac{(0.346 \text{ kg}) (9.81 \text{ m/s}^2 - 0.109 \text{ m/s}^2)}{(0.109 \text{ m/s}^2 + (0.211)(9.81 \text{ m/s}^2)}$$

$$m_1 = 1.54047 \text{ kg} = \boxed{1.54 \text{ kg}}$$

#3)

$$m_1 = 750 \text{ g}$$

$$\vec{F}_A = 0.7616 \text{ N [down]}$$

$$a_{sys} = 0.296 \text{ m/s}^2$$

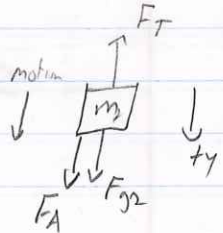
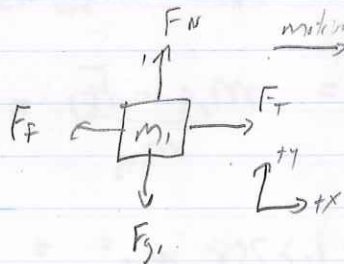
$$\mu_k = 0.138$$

$$\vec{g} = 9.81 \text{ m/s}^2 \text{ [down]}$$

$$\vec{a}_{1y} = 0 \text{ m/s}^2$$

$$m_2 = ?$$

$$F_T = ?$$



$$a) F_{\text{net}, sys} = F_A + F_{g2} - F_T = m_{sys} a_{sys}$$

$$F_{\text{net}, y, 1} = F_N - F_{g1} = m_1 a_{1y} = 0 \text{ N} \rightarrow F_N = F_{g1} \rightarrow F_T = \mu_k F_N = \mu_k m_1 g$$

$$m_1 a_{sys} + m_2 a_{sys} = F_A + m_2 g - \mu_k m_1 g$$

$$m_2 g - m_2 a_{sys} = m_1 a_{sys} + \mu_k m_1 g - F_A$$

$$m_2 (g - a_{sys}) = m_1 (a_{sys} + \mu_k g) - F_A$$

$$m_2 = \frac{m_1 (a_{sys} + \mu_k g) - F_A}{g - a_{sys}}$$

$$= \frac{(0.750 \text{ kg}) (0.296 \text{ m/s}^2 + (0.138)(9.81 \text{ m/s}^2) - 0.7616 \text{ N}}{(9.81 \text{ m/s}^2 - 0.296 \text{ m/s}^2)}$$

### Even More Connected Systems Practice

#3)  
Cont

$$m_1 = 0.050004 \text{ kg} = \boxed{0.050 \text{ kg}}$$

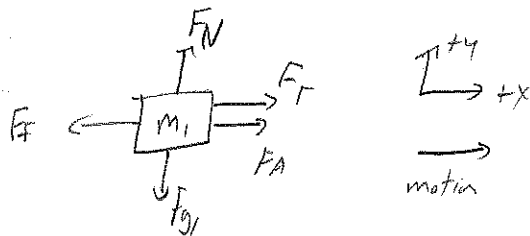
$$b) F_{\text{net},2} = F_A + F_{g2} - F_T = m_2 a_2$$

$$F_T = F_A + F_{g2} - m_2 a_2 = F_A + m_2 (g - a_{\text{sys}})$$

$$= 0.7616 \text{ N} + (0.050004 \text{ kg}) (9.81 \text{ m/s}^2 - 0.296 \text{ m/s}^2)$$

$$= 1.237335 \text{ N} = \boxed{1.24 \text{ N}}$$

c) If same  $F_A$  on pencil case instead,  $a_{\text{sys}}$  still the same



$$F_{\text{net},1,x} = F_T + F_A - F_F = m_1 a_1$$

$$F_T = m_1 a_1 + F_F - F_A$$

$$= m_1 a_1 + M_K m_1 g - F_A$$

$$= m_1 (a_{\text{sys}} + M_K g) - F_A$$

$$= (0.750 \text{ kg}) (0.296 \text{ m/s}^2 + (0.138)(9.81 \text{ m/s}^2)) - 0.7616 \text{ N}$$

$$= 0.475735 \text{ N} = \boxed{0.48 \text{ N}}$$

#3d)  $F_{\text{net, sys}} = F_{g2} - F_F = m_{\text{sys}} a_{\text{sys}}$

$$a_{\text{sys}} = \frac{m_2 g - \mu_k m_1 g}{m_1 + m_2}$$

$$= \frac{(0.050004 \text{ kg})(9.81 \text{ m/s}^2) - (0.138)(0.750 \text{ kg})(9.81 \text{ m/s}^2)}{(0.750 \text{ kg} + 0.050004 \text{ kg})}$$

$$= -0.655996 \text{ m/s}^2 = \boxed{-0.66 \text{ m/s}^2} \quad \text{"-"} \text{ means slowing down}$$

#4)  $m_2 = 120 \text{ g}$

$m_1 = 150 \text{ g}$

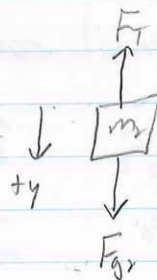
$\theta = 25^\circ$

$a_{\text{11y}} = 0 \text{ m/s}^2$

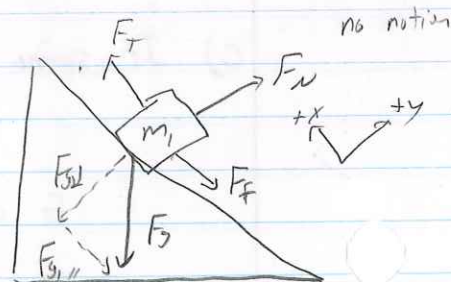
$a_{\text{sys}} = 0 \text{ m/s}^2$

$\vec{g} = 9.81 \text{ m/s}^2 \text{ [down]}$

$\mu_s = ?$



no motion



Assume if could move, hanging mass would descend. \*

$$F_{\text{net, sys}} = F_{g2} - F_{g1||} - F_F = m_{\text{sys}} a_{\text{sys}} = 0 \text{ N}$$

$$\therefore F_F = F_{g2} - F_{g1||} = m_2 g - m_1 g \sin \theta$$

$$F_{\text{net, 1y}} = F_N - F_{g1\perp} = m a_{1y} = 0 \text{ N} \rightarrow F_N = F_{g1\perp} \rightarrow F_F = \mu_s F_N = \mu_s F_{g1\perp}$$

$$\therefore \mu_s m_1 g \cos \theta = m_2 g - m_1 g \sin \theta$$

$$\mu_s = \frac{m_2 - m_1 \sin \theta}{m_1 \cos \theta} = \frac{(120 \text{ g}) - (150 \text{ g}) \sin(25^\circ)}{(150 \text{ g}) \cos(25^\circ)}$$

$$= 0.41639 = 0.4$$

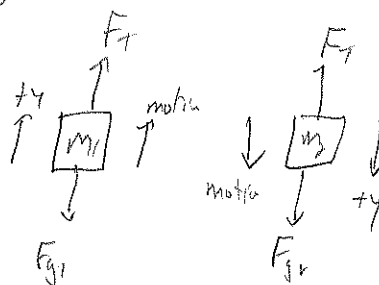
\* If you assumed other direction for  $F_F$ , would get  $-0.4$  which means choice of direction was wrong.

## Even More Connected Systems Practice

45)  $m_1 = 0.25 m_2 \leftarrow m_2$  is heavier mass

$\vec{g} = 9.81 \text{ m/s}^2 \text{ [down]}$

$m_{\text{sys}} = m_1 + m_2 = 1.25 m_2$

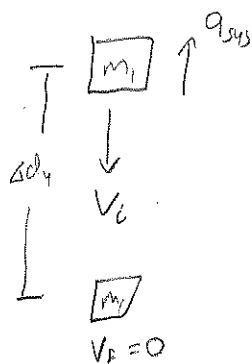


a)  $F_{\text{net, sys}} = F_{g2} - F_{g1} = m_{\text{sys}} a_{\text{sys}}$

$$a_{\text{sys}} = \frac{m_2 g - m_1 g}{m_{\text{sys}}} = \frac{m_2 g - 0.25 m_2 g}{1.25 m_2} = \frac{0.75 g}{1.25}$$

$$a_{\text{sys}} = \frac{3}{5} g = 5.886 \text{ m/s}^2 = \boxed{5.89 \text{ m/s}^2}$$

b)



$\vec{V}_i = 4.6 \text{ m/s [down]}$

$\vec{a}_1 = 5.89 \text{ m/s}^2 \text{ [up]}$

$\Delta d_y = ? \text{ [down]}$

$\vec{V}_f = 0 \text{ m/s [down]}$

$$V_f^2 = V_i^2 + 2 a_{\text{sys}} \Delta d_y$$

$$V_i^2 = -2 g \Delta d_y$$

$$\Delta d_y = \frac{V_i^2}{-2a} = \frac{(4.6 \text{ m/s})^2}{-2(-5.886 \text{ m/s}^2)} = 1.79749 \text{ m} = \boxed{1.8 \text{ m}}$$

c)  $\Delta \vec{V} = \vec{a} \Delta t \rightarrow \vec{V}_f - \vec{V}_i = \vec{a}_1 \Delta t \rightarrow \Delta t = \frac{V_f - V_i}{a_1} = \frac{0 \text{ m/s} - 4.6 \text{ m/s}}{-5.886 \text{ m/s}^2}$

$$\Delta t = 0.7815 \text{ s} = \boxed{0.78 \text{ s}}$$

$$d) \vec{F}_A = -1.00 \text{ N [sys dir]} \quad a_{\text{sys}} = 0 \text{ m/s}^2$$

$$m_2 = ?$$

$$F_{\text{Net, sys}} = F_{g2} - F_{g1} - F_A = m_{\text{sys}} a_{\text{sys}} = 0 \text{ N}$$

$$m_2 g - m_1 g = F_A$$

$$m_2 g - 0.25 m_2 g = F_A$$

$$0.75 m_2 g = F_A$$

$$\therefore m_2 = \frac{F_A}{0.75g} = \frac{1.00 \text{ N}}{0.75(9.8 \text{ m/s}^2)} = 0.13592 \text{ kg}$$

$$= \boxed{136 \text{ g}}$$