

Øvingsforelesning 9

TDT 4102

Prosedyre- og objektorientert programmering



15. mars 2017

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Øving 9: Minesweeper

- rather short
- mainly combines knowledge

Initialization:

- Dynamic 2D array of objects
- Mines: random combination

Progression:

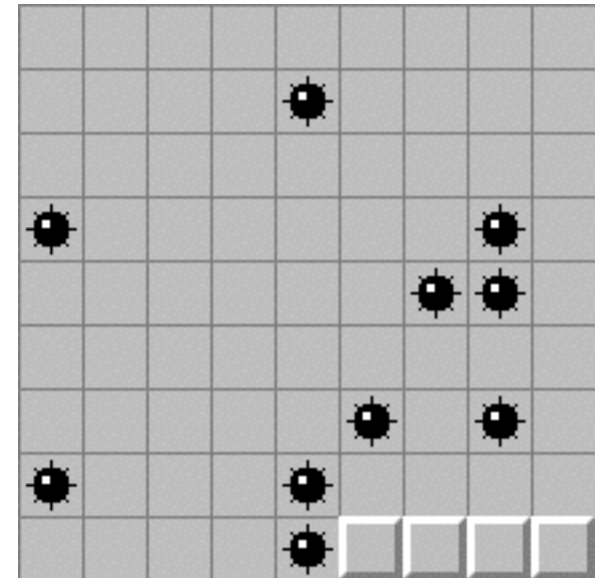
- Checking 8-boundaries
 - Recursive opening
- ★ board boundaries



Minesweeper

Initialization

- Dynamic 2D array of objects
- Mines: random combination



Minesweeper

Progression

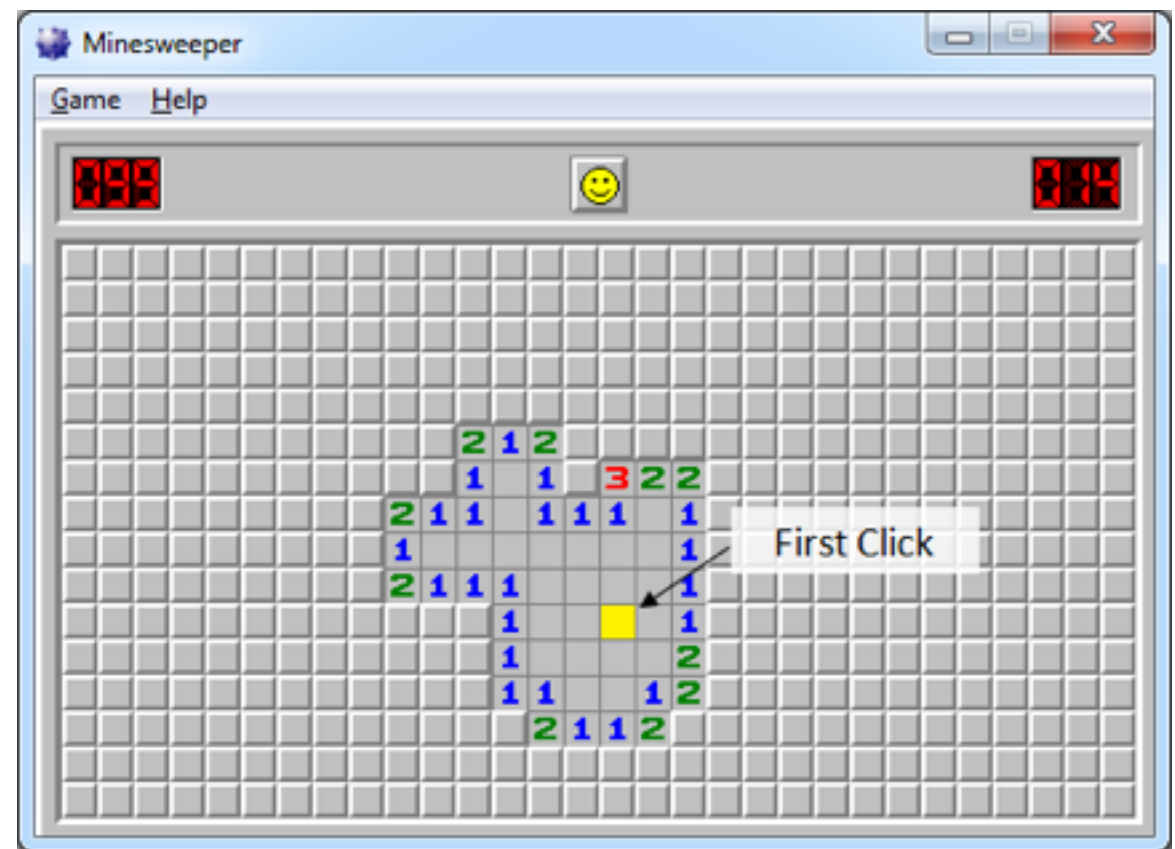
- Recursive opening
- Checking 8-boundaries
 - grid boundaries



Minesweeper

Progression

- Recursive opening



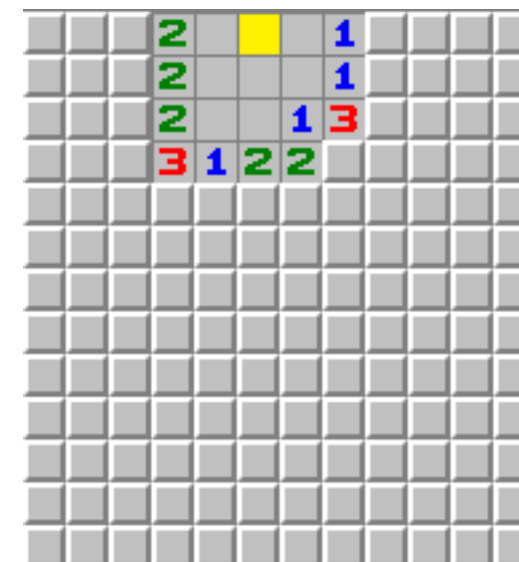
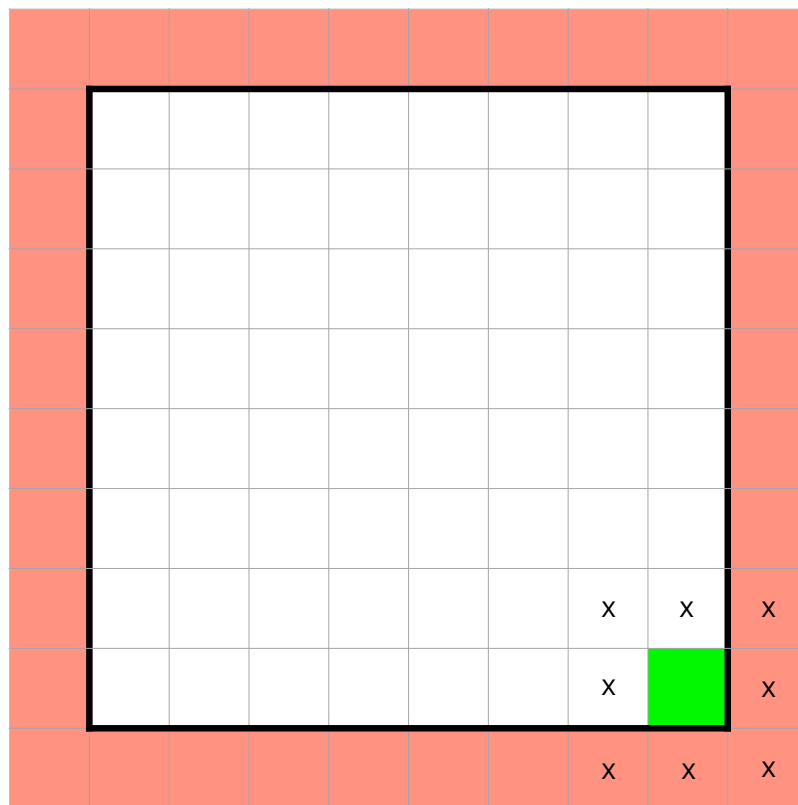
[datagenetics.com]



Minesweeper

Progression

- Checking 8-boundaries



[datagenetics.com]



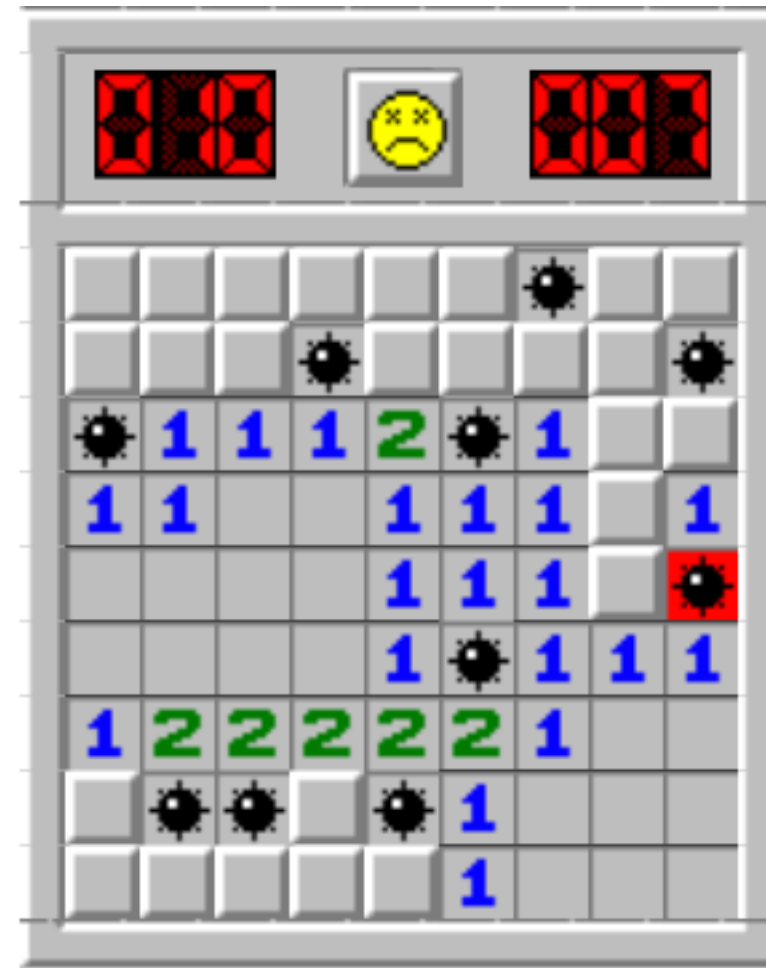
Minesweeper

win & loss

win



loss



But first..

A prelude on **const** type qualifier

- most important uses
- common caveats
- will come handy later



Const keyword

- Automatic error checking
- Potential compiler optimization
- Promises not to change variable

Rule of thumb? 

If you can, use const.



Const keyword

Most notable uses

- Passing by const reference
 - avoids unnecessary copying
 - internally passed as pointer

```
class T;  
class Type{  
    Type( T const& obj );  
};
```

Caveat

Call-by-reference

Reference (T&) .. lvalue

```
void goo(int)    { cout << "goo\n"; }  
void goo(char&) { cout << "hoo\n"; }  
  
int main() {  
    char chr = 'c';  
    goo(chr);  
    goo('c');  
}
```

BUT

Const reference (const T&) .. can be rvalue



Const keyword

Call by reference caveat - advanced

rvalue references (&&)

```
void goo(int)    { cout << "goo\n"; }
void goo(char&) { cout << "hoo\n"; }
void goo(char&&) { cout << "hoho\n"; }

int main() {
    char chr = 'c';
    goo(chr);
    goo('c');
}
```

Example of use

```
class T;
class Type{
    Type( T const& obj );    // expensive
    Type( T && obj );        // cheap
};
```



Const keyword

Most notable uses

Constant methods

```
int get() const {return this->i;}
```

- promise not to change the object
- vital for working with constant objects

```
class Type{
    int i;
public:
    Type(int i): i(i) {}
    int get() {return i;}
};

int main() {
    const Type tmp(0);
    tmp.get();
}
```

❗ Member function 'get' not viable: 'this' argument has type 'const Type', but function is not marked const



Const keyword

pointers and const

```
const int *p1 = nullptr;  
//  p1 = new int;  
//  *p1 = 666;  
  
int * const p2 = nullptr;  
//  p2 = new int;  
//  *p2 = 666;
```

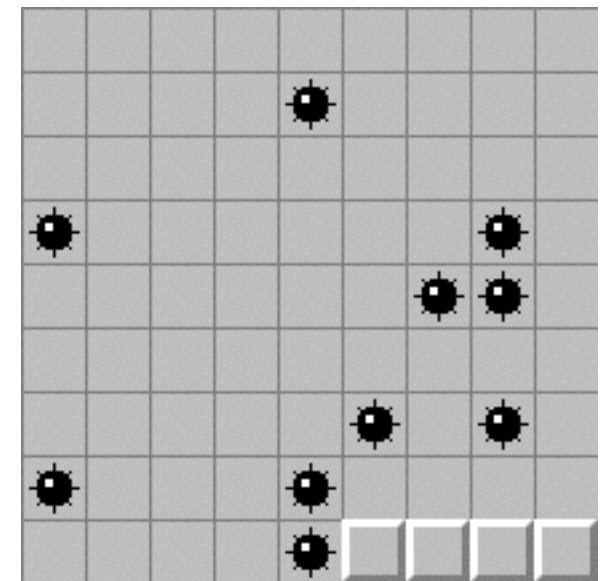
Which of the statements are allowed?



Minesweeper

Initialization

- **Dynamic 2D array of objects**
 - principles
 - pros & cons
 - a trick
- Mines: random combination

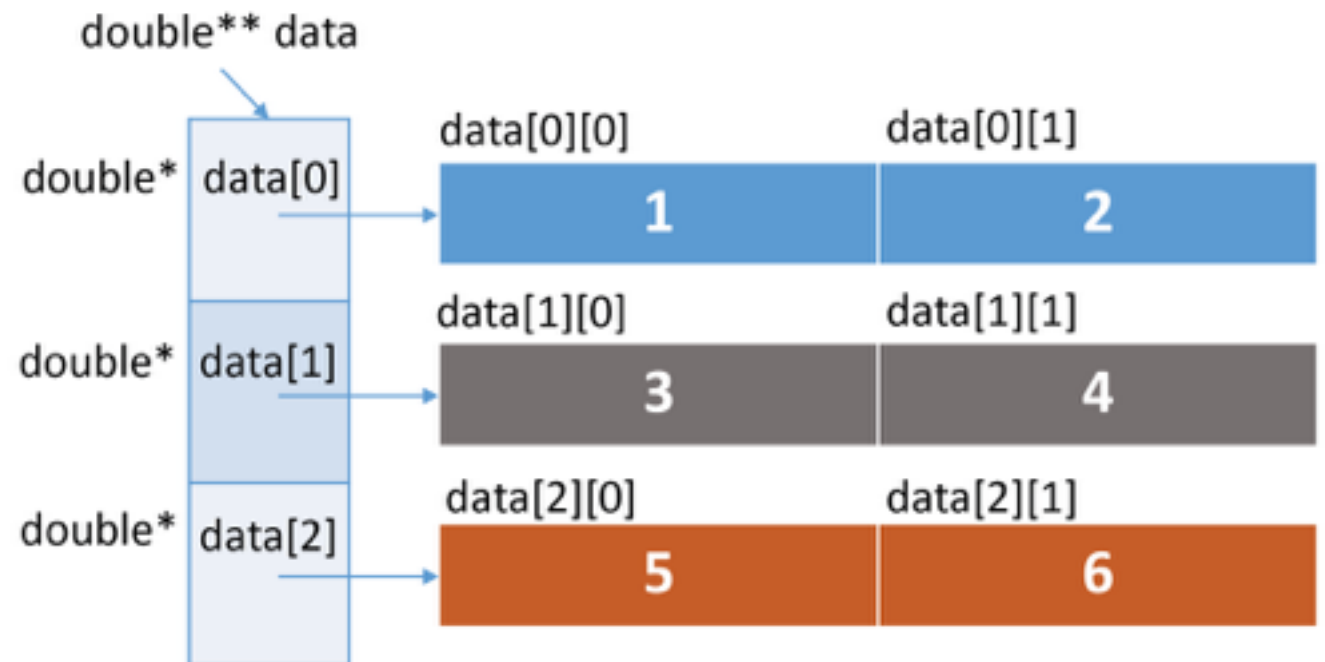


Saving 2D arrays

Pointers to pointers

Pros

- Intuitive
- Indexing `[i][j]` ready



Cons

- more complicated (de)allocation
- less efficient (time & space)

1 3 5
2 4 6



Saving 2D arrays

Single array

Pros

- Efficient (time & space)
 - Better caching
 - Less dereferencing
- Easy (de)allocation

Cons

- More code to write
- Δ performance: (usually) negligible

kolonne 1		kolonne 2		kolonne 3	
1	2	3	4	5	6

1	3	5
2	4	6



Saving 2D arrays

Static 2D array?

```
int array1[3][2] = {{0, 1}, {2, 3}, {4, 5}};
```

How is it stored in memory?

In memory looks like this:

```
0 1 2 3 4 5
```

exactly the same as:

```
int array2[6] = { 0, 1, 2, 3, 4, 5 };
```

[stackoverflow]

caveat

```
int q[2][3];  
cout<<q[0][4]<<endl; // legal, same as q[1][1] !
```



Saving 2D arrays

Single array

kolonne 1		kolonne 2		kolonne 3	
1	2	3	4	5	6

1 3 5
2 4 6

Can we get back intuitive indexing?



Saving 2D arrays

Yes! The following code does what we expect:

```
class Grid{
    unsigned height, width;
    int* values;
public:
    int* operator[] (int i)
    {
        return values + i*width;
    }

    Grid(unsigned height, unsigned width): width(width), height(height),
        values(nullptr)
    {
        values = new int[width*height];
        for (int i=0; i<height*width; i++) values[i]=i;
    }
};

int main() {
    Grid test(3,4);

    cout<<test[1][2];
    test[1][2] = 0;
    cout<<test[1][2];

    return 0;
}
```

Or does it?



Saving 2D arrays

Now it's better. :)

```
class Grid{
    unsigned height, width;
    int* values;
public:
    const int* operator[] (int i)
    {
        return values + i*width;
    }

    Grid(unsigned height, unsigned width): width(width), height(height),
        values(nullptr)
    {
        values = new int[width*height];
        for (int i=0; i<height*width; i++) values[i]=i;
    }
};

int main() {
    Grid test(3,4);

    cout<<test[1][2];
    test[1][2] = 0;
    cout<<test[1][2];

    return 0;
}
```

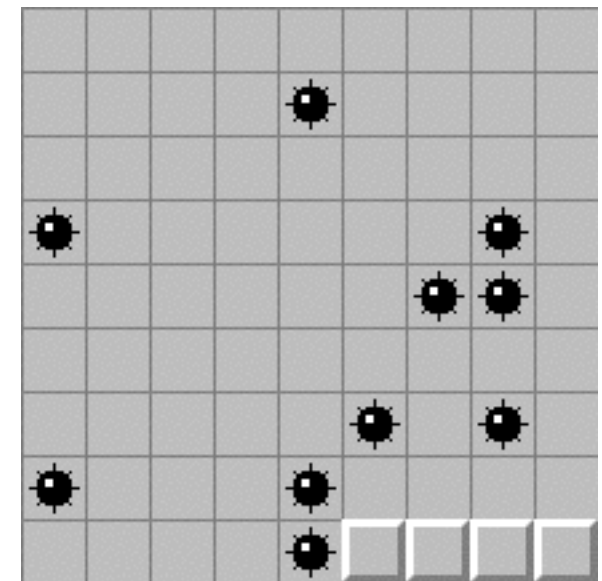
! Read-only variable is not assignable



Minesweeper

Initialization

- Dynamic 2D array of objects
- Mines: random combination
 - Naive vs effective solution
 - `<algorithm> std::random_shuffle`



Random combinations

Naive

Idea

- Choose random index
- Repeat if already chosen

Algorithm 1 Naive random combinations

```
1: function RANDOMCOMBINATION( $k, n$ )
2:    $combination = \{\}$ 
3:   for  $i$  in  $\{1, 2, \dots, k\}$  do
4:      $element = randomFromTo(1, n)$ 
5:     while  $element \in combination$  do
6:        $element = randomFromTo(1, n)$ 
7:     end while
8:      $combination = combination \cup \{element\}$ 
9:   end for return  $combination$ 
10: end function
```

Complexity?

$$n \log n - n \log(n - k) \approx n \log n$$

for $k \in O(n)$

→ not optimal



Random combinations

Naive - derivation

$$\# \text{attempts} = \# \text{step}_0 + \# \text{step}_1 + \dots$$

$$\mathbf{E}[\# \text{attempts}] = \mathbf{E}[\# \text{step}_0] + \mathbf{E}[\# \text{step}_1] + \dots$$

$$\begin{aligned} \text{step}_i: \quad & P(\text{valid}_i) = \frac{n-i}{n} \\ & \mathbf{E}(\text{step}_i) = \frac{n}{n-i} \end{aligned}$$

Expected running time

$$\mathbf{E}(\# \text{attempts}) = \sum_{i=0}^{k-1} \frac{n}{n-i} \sim \int_{i=0}^{k-1} \frac{n}{n-i}$$



Random combinations

Fisher-Yates shuffle

Idea

- Choose random index from those not already chosen

Pros

- Unbiased
- Linear - $O(k)$



Random combinations

Fisher-Yates shuffle

Pseudocode - shuffle full array in $O(n)$

```
-- To shuffle an array a of n elements (indices 0..n-1):  
for i from n-1 downto 1 do  
    j  $\leftarrow$  random integer such that  $0 \leq j \leq i$   
    exchange a[j] and a[i]
```

[wiki]

<algorithm> std::random_shuffle

How do we get the combination?

Conclusion:

Don't reinvent the wheel.



Minesweeper

Progression

- **Recursive opening**
 - principles
 - pros & cons
 - Fibonacci (øv 7)
- Checking 8-neighbourhood
 - grid boundaries



Recursion

Algorithm 2 Generate n-th fibonacci number

```
1: function FIBONACCI( $n$ )
2:   if  $n \leq 2$  then
3:     return 1 base case
4:   end if
5:   return FIBONACCI( $n - 1$ ) + FIBONACCI( $n - 2$ ) recursive call
6: end function
```

Algorithm 3 Compute factorial recursively

```
1: function FACT( $n$ )
2:   if  $n == 0$  then
3:     return 1 base case
4:   end if
5:   return  $n * \text{FACT}(n-1)$  recursive call
6: end function
```

- function calls itself
 - requires base case
-
- new model of thinking
 - alternative to iteration
 - replaces it in *functional programming* :)



Recursion

Algorithm 2 Generate n-th fibonacci number

```
1: function FIBONACCI( $n$ )
2:   if  $n \leq 2$  then
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Algorithm 3 Compute factorial recursively

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6: end function
```

Pros

- conceptually elegant
- often reasonably efficient
 - when not, often leads to dynamic programming algorithm
- *divide & conquer*
- easier to prove correctness



Recursion

Algorithm 2 Generate n-th fibonacci number

```
1: function FIBONACCI( $n$ )
2:   if  $n \leq 2$  then
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6: end function
```

Cons

- generally greater overhead (space, time)
- function calls accumulate on *stack*
 - rather limited 1-2 MB
 - scalability issues - stack overflow :)
- possible redundant computations
- trickier to determine complexity



Recursion

Algorithm 2 Generate n-th fibonacci number

```
1: function FIBONACCI( $n$ )
2:   if  $n \leq 2$  then
3:     return 1 base case
4:   end if
5:   return FIBONACCI( $n - 1$ ) + FIBONACCI( $n - 2$ ) recursive call
6: end function
```

Algorithm 3 Compute factorial recursively

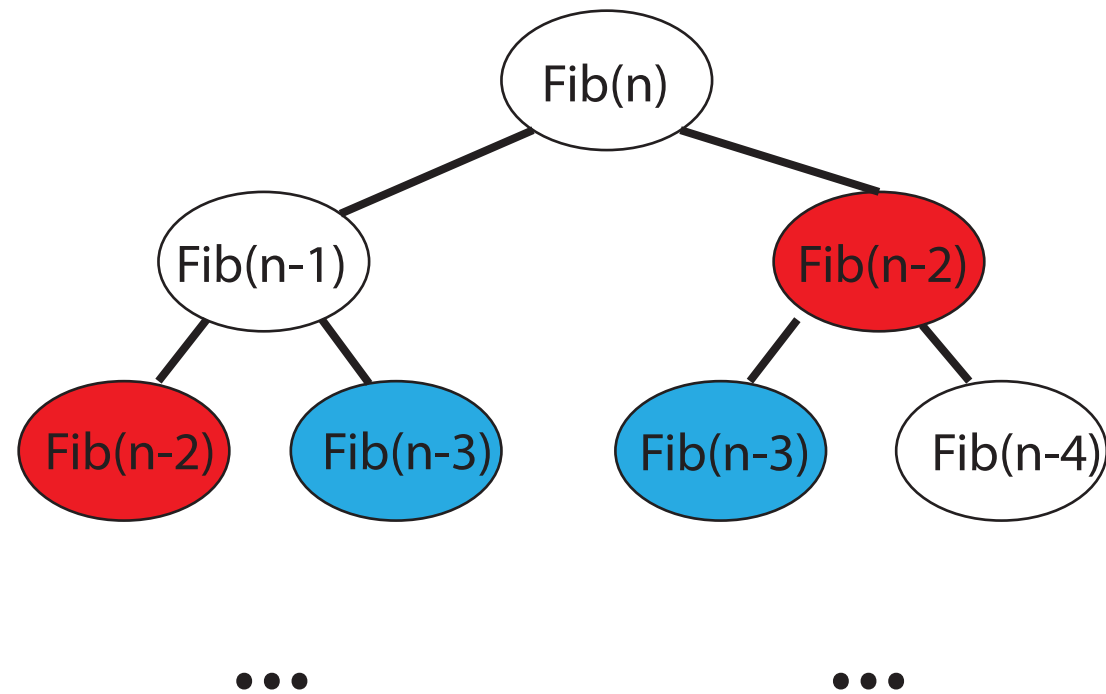
```
1: function FACT( $n$ )
2:   if  $n == 0$  then
3:     return 1 base case
4:   end if
5:   return  $n * \text{FACT}(n-1)$  recursive call
6: end function
```

Control question

Which of the algorithms above is inefficient? Why? How inefficient?



Fibonacci

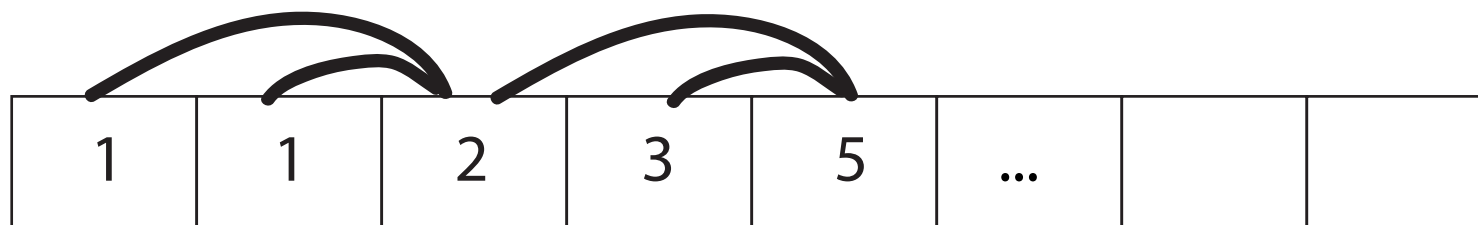


Recursion

$O(2^n)$
repeated subproblems
 $O(1)$ per leaf

Iteration

dynamic programming



$O(n)$
 $O(1)$ per value



Master theorem

$$T(n) = a T\left(\frac{n}{b}\right) + f(n) \text{ where } a \geq 1, b > 1$$

In the application to the analysis of a recursive algorithm, the constants and function take on the following significance:

- n is the size of the problem.
- a is the number of subproblems in the recursion.
- n/b is the size of each subproblem. (Here it is assumed that all subproblems are essentially the same size.)
- $f(n)$ is the cost of the work done outside the recursive calls, which includes the cost of dividing the problem and the cost of merging the solutions to the subproblems.

- determines time complexity
- can be applied to most feasible recursive algorithms

a	increases width
b	decreases height
f(n)	determines work done at nodes



Recursion Summary

Algorithm 2 Generate n-th fibonacci number

```
1: function FIBONACCI( $n$ )
2:   if  $n \leq 2$  then
3:     return 1 base case
4:   end if
5:   return FIBONACCI( $n - 1$ ) + FIBONACCI( $n - 2$ ) recursive call
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```

Algorithm 3 Compute factorial recursively

```
1: function FACT( $n$ )
2:   if  $n == 0$  then
3:     return 1 base case
4:   end if
5:   return  $n * \text{FACT}(n-1)$  recursive call
6: end function
```

- function calls itself
- requires base case
- elegant
 - but beware



Minesweeper

Progression

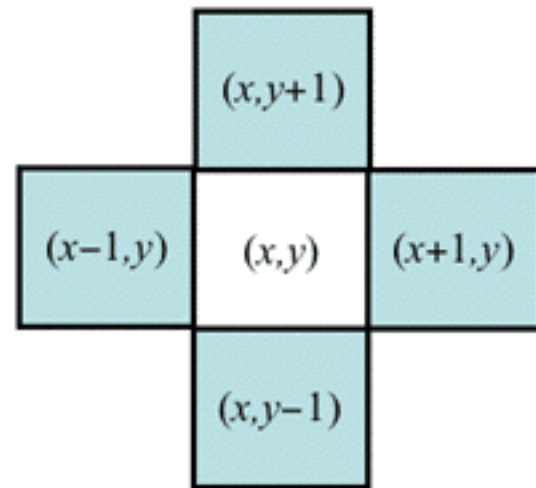
- Recursive opening
- Checking 8-neighbourhood
 - naive vs offsets-based



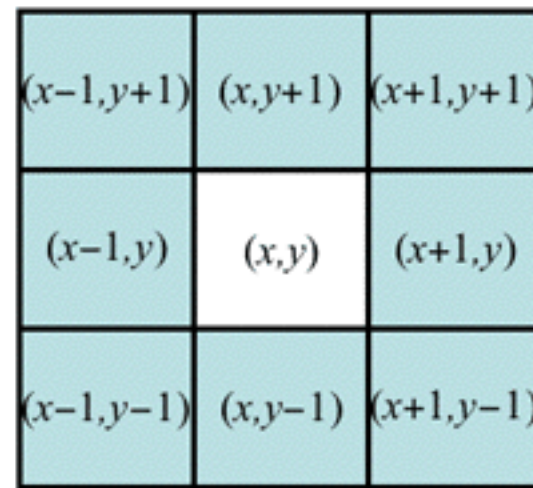
Neighbourhoods in grids

- esp. important in *image processing*

2D



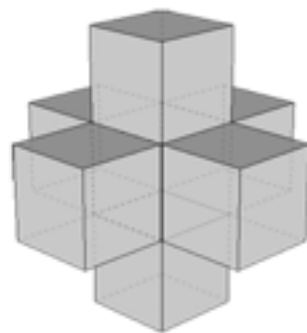
4-neighbourhood



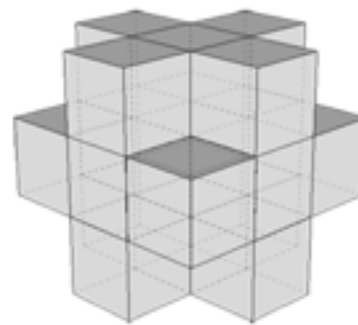
8-neighbourhood

[www.cs.auckland.ac.nz]

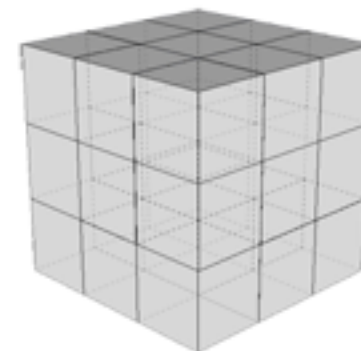
3D



Faces
(7 voxels)



Faces + Edges
(19 voxels)



Faces + Edges + Corners
(27 voxels)

[CPAC documentation]



8-neighbourhood in grids

How to go through it?

Naive

- 8 different statements
- error-prone
- bloated code
- scaling



Alternative?

```
int Minesweeper::numAdjacentMines(int row, int col) const {
    int adjacentMines = 0;

    if (row != 0){
        adjacentMines += isTileMine(row-1,col);
    }
    if (col != 0){
        adjacentMines += isTileMine(row,col-1);
    }
    if (col != width-1){
        adjacentMines += isTileMine(row,col+1);
    }
    if (row != height-1){
        adjacentMines += isTileMine(row+1,col);
    }
    if ((row!=0) && (col!=0)){
        adjacentMines += isTileMine(row-1,col-1);
    }
    if ((row!=0) && (col!=width-1)){
        adjacentMines += isTileMine(row-1,col+1);
    }
    if ((row!=height-1) && (col!=0)){
        adjacentMines += isTileMine(row+1,col-1);
    }
    if ((row!=height-1) && (col!=width-1)){
        adjacentMines += isTileMine(row+1,col+1);
    }

    return adjacentMines;
}
```

[Piazza] (sorry!)



8-neighbourhood in grids

Offsets

- readability
- scalability
- clean code



```
// Naboene til en rute
const int row_offsets[8] = { -1, -1, -1, 0, 0, 1, 1, 1 };
const int col_offsets[8] = { -1, 0, 1, -1, 1, -1, 0, 1 };

...

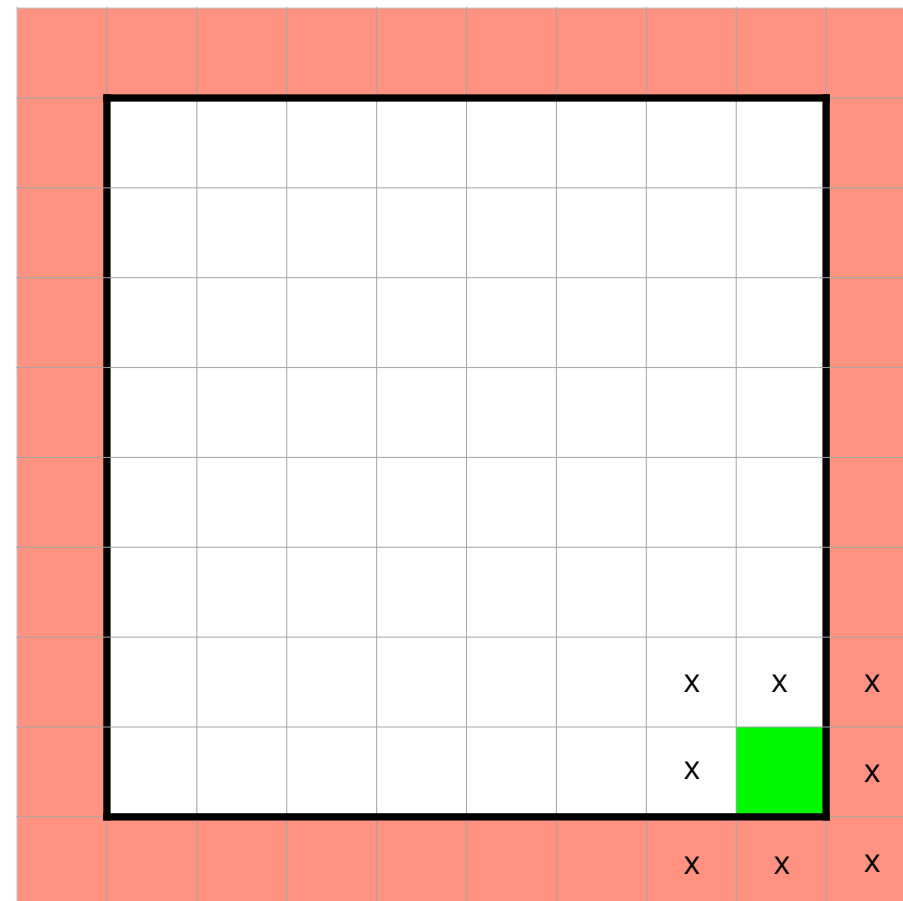
for(int i = 0; i < 8; ++i) {
    const int neighbour_row = row + row_offsets[i];
    const int neighbour_col = col + col_offsets[i];
    ...
}
```



Grid boundaries

Tips

- minimize lines of code
 - often most robust
- consider a dedicated function
 - private/public?



Good to know

Deleting default copying and =

An extra tip

shallow copy inappropriate + no need for these
⇒ delete the defaults

- avoids hard-to-see bugs

```
class Array {  
    ...  
    Array(const Array& other) = delete;  
    Array& operator= (Array rhs) = delete;  
    ...  
};
```

Sometimes deeper meaning:

- Every student unique

Óvín 9?

every game is unique?

“save game”?



What's more?

A quick peek to øving 10..



LF-oving10
12 items

No; not so easy. :)

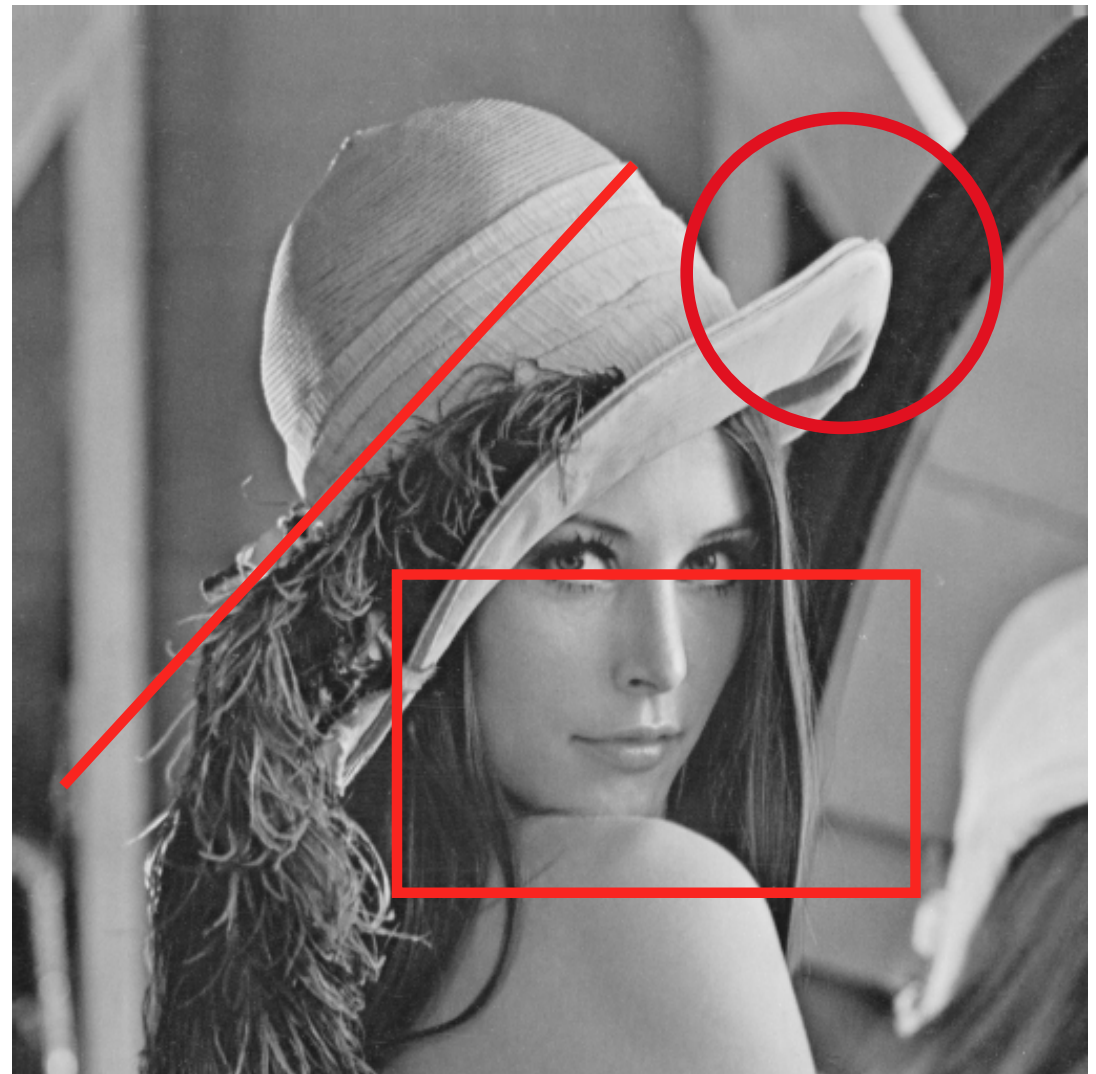


Øving 10: Drawing shapes

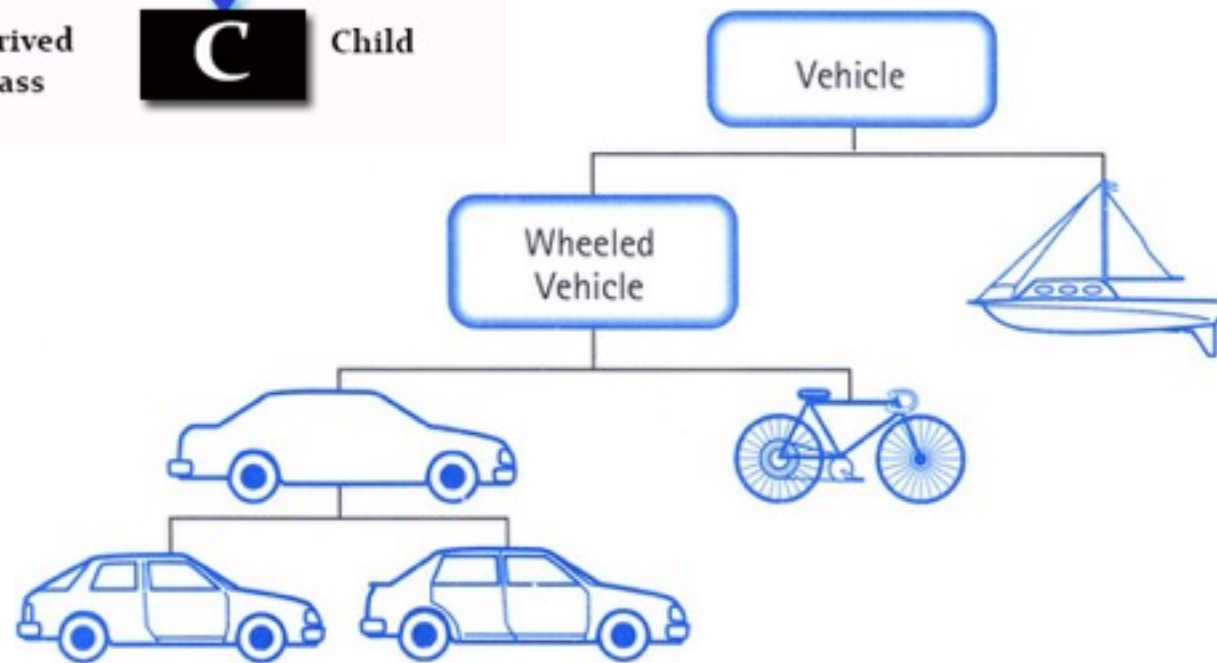
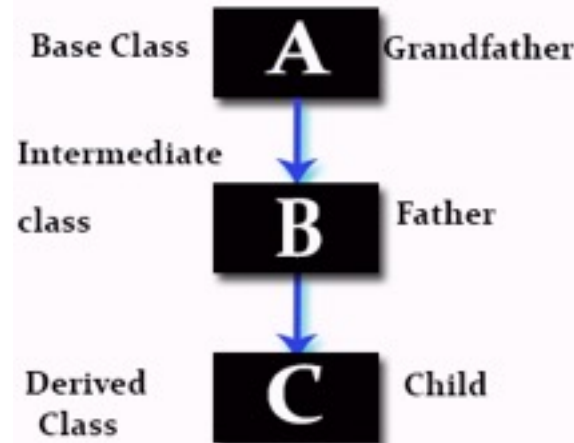
Sneak peek

Topics

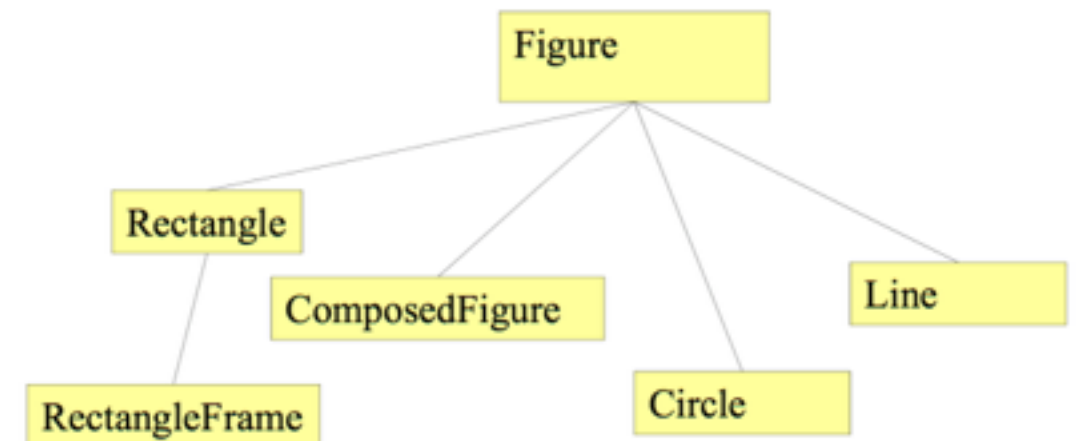
- Inheritance
 - Polymorphism
 - Virtual functions



Inheritance



```
class Circle : public Shape {  
...  
};
```



Derived class

- “is a” baseclass 🙌
- extra functionality
- different functionality

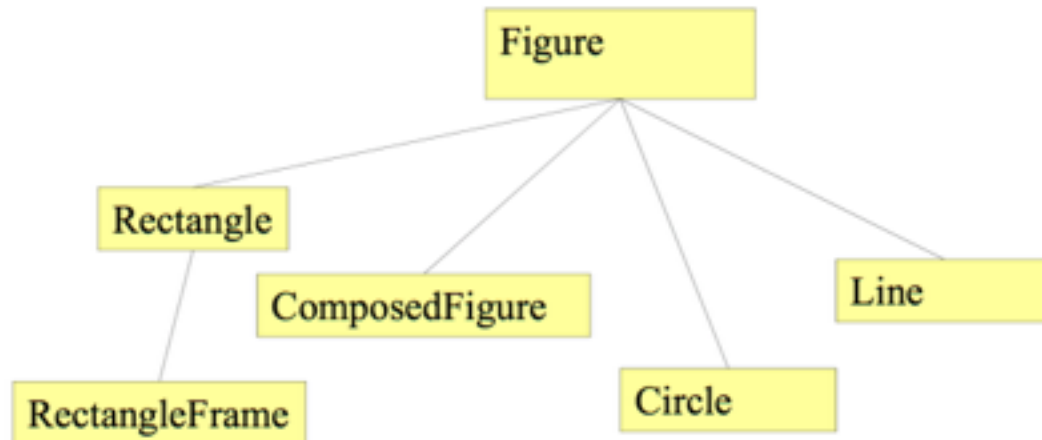
Purposes

- reusing existing code
- using *by* existing code
 - **shared interface**
- often elegant
 - often tricky / abused
 - better know what you're doing



Inheritance

virtual



```
std::vector<const Figure*> figures;  
figures.push_back(new Rectangle() )  
figures.push_back(new Circle() )  
  
for ( int i = 0; i < figures.size(); i++ ) {  
    figures[i]->draw( img );  
}
```

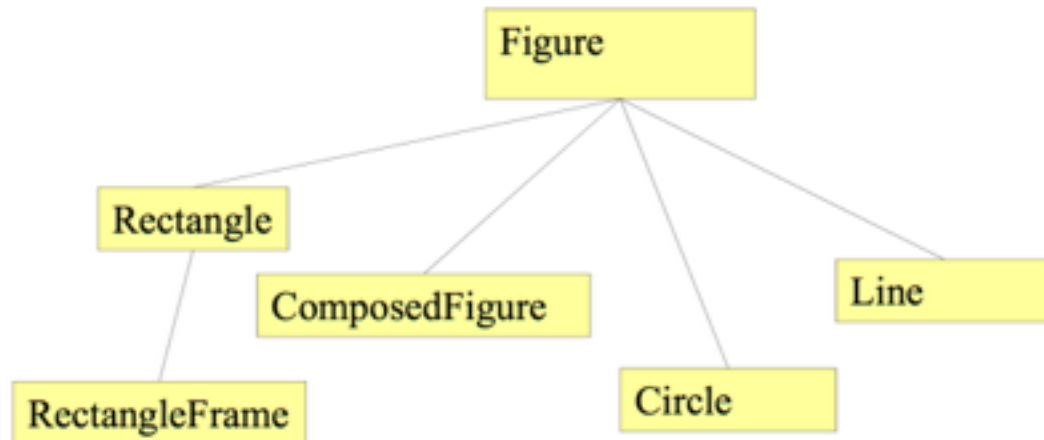
- key concept
 - main argument for inheritance
- allows late binding
 - Code above draws implementations of **draw** by **Circle** and **Rectangle**, rather than that by **Figure**.

Why not all virtual?




Inheritance

virtual



```
std::vector<const Figure*> figures;
figures.push_back(new Rectangle() )
figures.push_back(new Circle() )

for ( int i = 0; i < figures.size(); i++ ) {
    figures[i]->draw( img );
}
```

- Requires pointer or reference!!!  Why?
- The following code won't work as intended:

```
std::vector<const Figure> figures;
figures.push_back(Rectangle() )
figures.push_back(Circle() )

for ( int i = 0; i < figures.size(); i++ ) {
    figures[i].draw( img );
}
```



Inheritance

pure virtual

```
class Base {  
    // ...  
    virtual void f() = 0;  
    // ...  
};
```

virtual method with no body and special syntax

- class becomes *abstract*
→ no object can be made

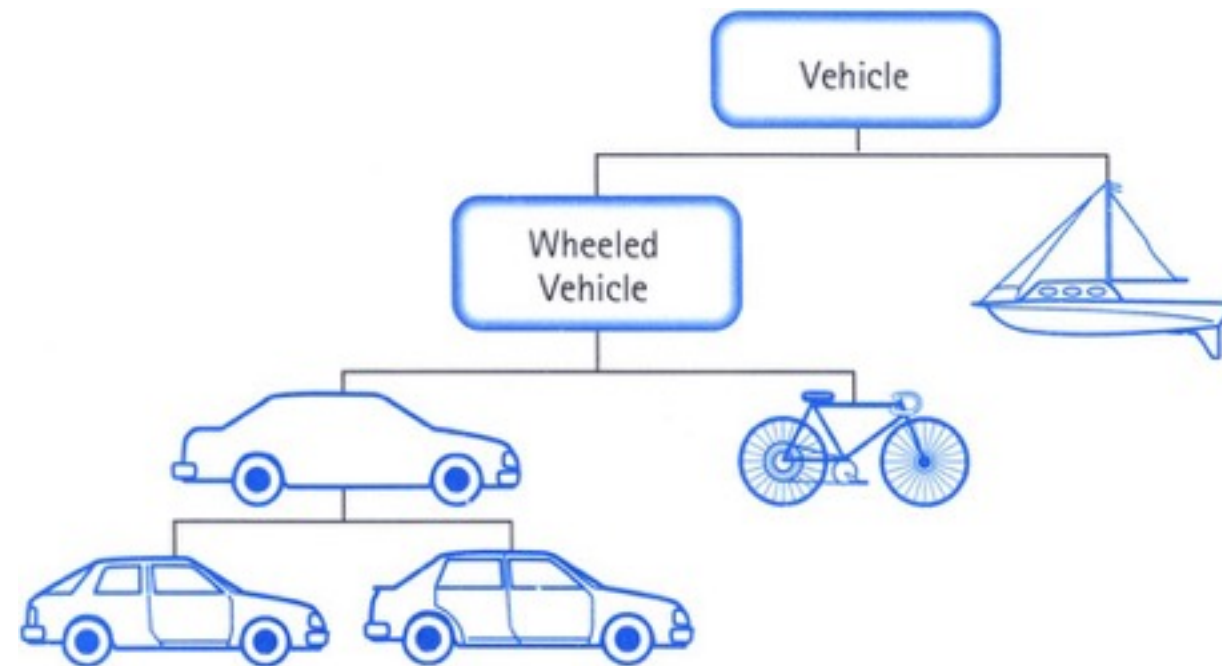
In essence, defines **interface** that derived classes
need to provide, so as not to be abstract.



Good to know

Inheritance

last note



Not inherited:

- constructors
- copy and operator=
- *private functions*



Summary

Øving 9

- short
- focus on good coding practices

Øving 10

- focus on inheritance & polymorphism
 - often vital for large projects

