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## THEESIS

DESIGNING A VIRTUAL-MEMORY IMPLEMENTATION USING THE  
MOTOROLA MC68010 16-BIT MICROPROCESSOR WITH  
MULTI-PROCESSOR CAPABILITY INTERFACED TO THE VMEbus

by

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The primary purpose of this thesis is to explore and discuss the hardware design of a bus-oriented microprocessor system. A bus-oriented microprocessor system permits it to be expanded to a multi-processor system. Through the use of a bus controller and bus arbiter, as discussed in this thesis, the necessary logic is in place to control bus access by system users. Bus access may be initiated to share another sub-system's resource, such as memory. To accommodate memory sharing between two systems, a dual-port memory controller can be used to resolve memory access between the two systems. This thesis discusses the design of a MC68010 microprocessor system integrated on the VMEbus with dual-ported memory capability. Additional features of the MC68010 microprocessor system include memory-management and interrupt control. The memory-management features permit protected memory and virtual-memory to be implemented on the system, while an interrupt handler is used to assist the MC68010 microprocessor in exception processing.

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MULTI-PROCESSOR CAPABILITY INTERFACED TO THE VMEbus**

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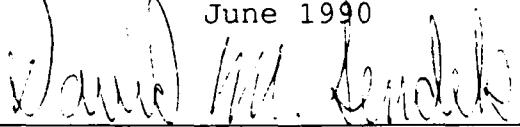
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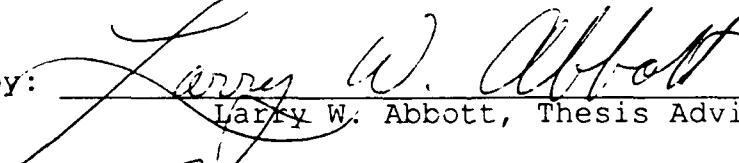
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## **ABSTRACT**

The primary purpose of this thesis is to explore and discuss the hardware design of a bus-oriented microprocessor system. A bus-oriented microprocessor system permits it to be expanded to a multi-processor system. Through the use of a bus controller and bus arbiter, as discussed in this thesis, the necessary logic is in place to control bus access by system users. Bus access may be initiated to share another sub-system's resource, such as memory. To accommodate memory sharing between two systems, a dual-port memory controller can be used to resolve memory access between the two systems. This thesis discusses the design of a MC68010 microprocessor system integrated on the VMEbus with dual-ported memory capability. Additional features of the MC68010 microprocessor system include memory-management and interrupt control. The memory-management features permit protected memory and virtual-memory to be implemented on the system, while an interrupt handler is used to assist the MC68010 microprocessor in exception processing.

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## I. INTRODUCTION

Economic pressure constantly forces computer design and technology to produce more cost-effective system implementations. Computers are made more cost-effective by lowering operating cost through increased speed and power and by lowering design, maintenance and upgrade costs through modular design techniques. Architectural innovations can accelerate this process. Hence, new innovations in system architecture are constantly sought after. Architecture is used here to mean the structuring of the modules which are organized into a computer system [Ref. 1:p. 1]. These modules include processors, memory and input/output (I/O) devices.

A uni-processor system consists of a single processor subsystem and various supporting modules integrated to form a system. In contrast, a multi-processor system is comprised of two or more processor subsystems connected into one interrelated functional system. In a multi-processor system, the interconnection of the processor subsystems must be done in such a way as to maintain control and manage the data flow of the entire system. This may be accomplished through multi-ported memory, a serial link or as in this thesis, by a system bus. A number of computer architectural designs that accommodate growing needs are examined in this thesis. Key architectural features of bus structures, memory-management and interrupt control are described in this chapter.

Bus structures allow for the integration of peripherals, memory and application-specific boards into one coherent system. Bus structures permit the exchange of data and control signals between circuit boards. This allows circuit boards to communicate with each other and to share resources. However, a strict adherence to protocols must be maintained so the integrity of information and control is preserved.

Memory-management features include memory protection and virtual-memory. Special memory schemes have been used to protect a system's integrity, to make more effective use of its physical memory's address range and to permit multi-ported memory so that the memory resource can be shared in a multi-processor system. A memory protection scheme prevents users from inadvertently or maliciously tampering with the operating system, its associated memory-mapped hardware or other users. To accomplish this, a portion of the processor's address range can be reserved for the operating system, while the remaining portion is allocated to system users. The operating system is protected because the user is not permitted to cross into the operating system's memory.

The virtual-memory aspect of memory-management permits a greater dynamic range and flexibility for user memory than actually exists with the system's physical memory. Virtual-memory allows each user to run programs as if he or she has full use of the processor's address range, independent of the memory used by the operating system or the other users. The user is unaware of how the physical memory in the system is allocated. Therefore, memory

resources can be allocated automatically and respond to the dynamic needs of the operating system and the users. In a system without virtual-memory, programs must be executed in a specific memory space and for large programs, the user must provide complex overlay schemes to circumvent the fixed user memory allocation. It is difficult for such a system to support several large programs concurrently. In a virtual-memory system, the operating system breaks up the user's program into segments called pages and moves these pages as needed between physical memory and a secondary storage device such as a hard disk. Thus, a virtual-memory system can easily support several large programs concurrently as long as each program only requires a modest amount of memory at any given time.

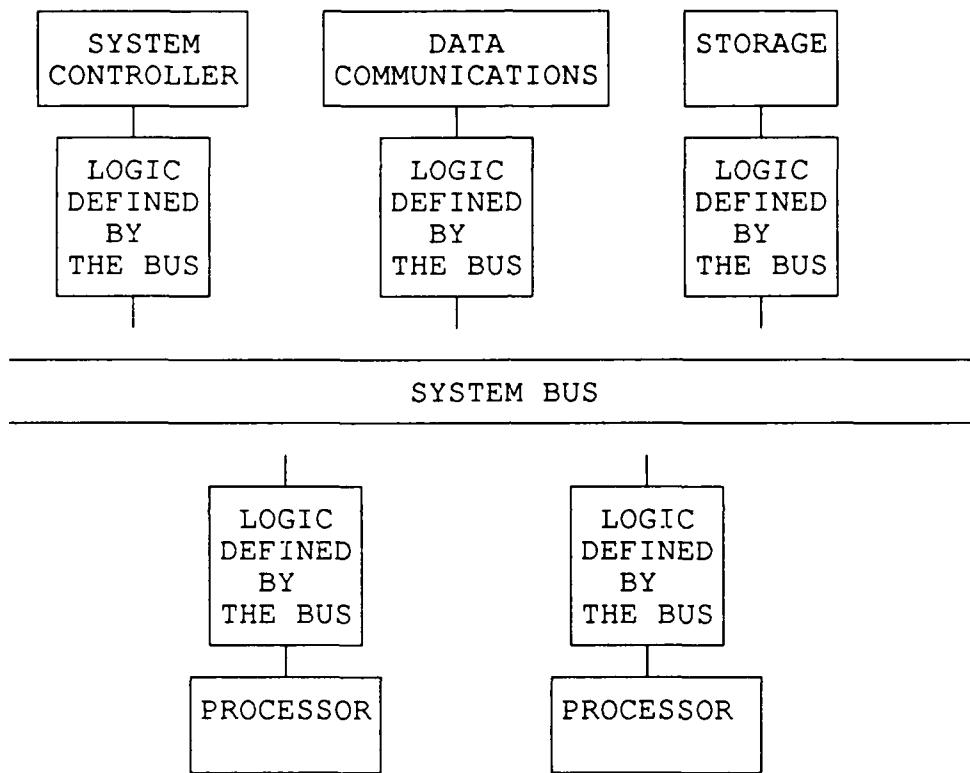
Multi-ported memory, such as dual-ported memory, allows a common memory resource to be shared between two or more processors or peripheral devices. Thus, different processes or different processors can communicate with each other via a multi-ported memory mailbox equipped with an accompanying semaphore to maintain access control and data integrity. Also, multi-porting provides a communication link between tightly coupled systems where there is a high degree of interaction.

Interrupts optimize the performance of a processor. An interrupt is a control signal generated asynchronously by a device, such as a serial port, requesting service from the processor. The processor is free to process other tasks between interrupts from devices requiring service [Ref. 2:pp. 220-223]. When it is ready

to service an interrupting device, the processor saves its current state and then performs the servicing tasks. When the servicing tasks are completed, the saved state of the processor is restored and the operation prior to the interrupt is resumed. Consequently, the processing power of the processor is increased because the overhead from polling peripheral devices for a service request is eliminated.

In a general sense, a generic multi-processor system can be viewed as illustrated in Figure 1.1. Various subsystems such as data processing, storage and data communications are integrated along a system bus to make up a complete system. Each subsystem is comprised of memory, I/O and processor modules configured to accommodate the unique requirements of the users of the multi-processor system. A system controller acts as the arbiter for the entire system. The system controller directs the information flow, much as a traffic policeman directs traffic, between the various subsystems along the system bus to ensure that the system is properly coordinated. In order for each subsystem to have access to the system bus, logic must be incorporated within each subsystem to allow it to interface to the system bus.

The main thrust of this thesis is to explore the concepts of bus structure, memory-management and interrupt control. These concepts are addressed in a greater depth than would be possible in a classroom environment.



**Figure 1.1: Generic Multi-Processor System**

## II. DESIGN CONCEPTS

The concepts addressed in this thesis are limited to bus structure organization, memory-management and interrupt control. These features are commonly used in today's processor systems. However, many options are available within each area. This thesis design is a virtual-memory implementation of a MC68010-based microprocessor system integrated on the VMEbus with dual-ported memory capability.

Borrill [Ref. 3] highlights several advantages of the VMEbus. The VMEbus, through its non-multiplexed address lines and data lines, does not have multiplexing delays as do other buses, nor does it have the transactional protocol overheads as do some other buses. In addition, the non-multiplexed address lines will support address pipelining. For interested readers, Borrill has made a detailed comparison of the features and performance of the VMEbus, Futurebus, Multibus II, Nubus and Fastbus [Ref. 3].

In addition to the advantages that Borrill highlights, the VMEbus structure was selected because of the relative ease of integrating Motorola and Signetics peripheral hardware devices. These hardware devices include a memory management unit, VMEbus controller, bus arbiter, interrupt handler hardware and dual-port dynamic random access memory (DRAM) controller.

The following discussion presents a broad overview of the VMEbus structure and memory-management. This should facilitate

understanding of the concepts that are incorporated into the final system (master circuit board) design.

## A. VMEbus SPECIFICATION

### 1. Background

The VMEbus specification originated with Motorola's 68000 microprocessor products. The 68000 series was introduced to the marketplace in the late 1970s, using the VERSAbus specification. In the early 1980s, Motorola's European Microsystems group in Munich, Germany, introduced the Eurocard version of the VERSAbus, referred to as the VERSAbus-E specification. A joint agreement was reached to adopt the VERSAbus-E as the baseline bus specification for Motorola 68xxx devices with Mostek and Signetics as second-source suppliers of the 68xxx family of devices. The VERSAbus-E was renamed the VMEbus. The VMEbus specification [Ref. 4] delineates the mechanical and electrical characteristics of the bus and the protocols to interface devices on the VMEbus.

### 2. VMEbus Description

The VMEbus offers a versatile combination of timing strategies and support features. It also offers several data transfer sizes, several addressing modes and several arbitration methods. The VMEbus is an asynchronous, non-multiplexed bus that accommodates 8, 16 and 32-bit data transfers. [Ref. 5]

Asynchronous data transfers are flexible and do not impose timing control signals. Completion signals from the asynchronous devices ensure that adequate time is allowed for the data transfer. In contrast, synchronous data transfers impose a timing constraint

on the data transfer which must accommodate the slowest device attached to the bus.

A non-multiplexed bus is one that accommodates data transfers and address transfers as separate signals on separate lines of the bus. This contrasts with the multiplexing strategy where data signals and address signals share the same set of lines. As a simple description, during a write cycle, multiplexing address signals are gated on one clock cycle and data signals are gated on the same lines during a subsequent clock cycle. The non-multiplexing strategy speeds up data transfer by eliminating the second clock cycle.

The VMEbus can be used with 24 or 32 address lines depending on the microprocessor's requirements and it is easily adaptable to the entire family of Motorola 68xxx microprocessors and peripherals.

The VMEbus is composed of four sub-buses that play unique roles within the overall VMEbus functional structure. These include the data transfer bus (DTB), the data transfer arbitration bus, the priority interrupt bus and the utility bus. The VMEbus functional specification describes how each sub-bus interacts and the rules which govern the behavior of each sub-bus [Ref. 4:pp. 15-194]. The DTB provides the pathways for the data signals, the address signals and their associated control signals. The process of resolving bus ownership takes place on the data transfer arbitration bus. The priority interrupt bus is used to accommodate processes which request servicing from another subsystem. An

interrupt stops normal bus activity until the interrupt is serviced. The utilities bus is sometimes referred to as a "miscellaneous functions bus". It includes a system reset line, an alternating current (AC) power failure line, a system failure line and a system clock [Ref. 2:p. 475].

The design in this thesis uses the VMEbus controller and the interrupt handler hardware devices which are designed for use with the VMEbus.

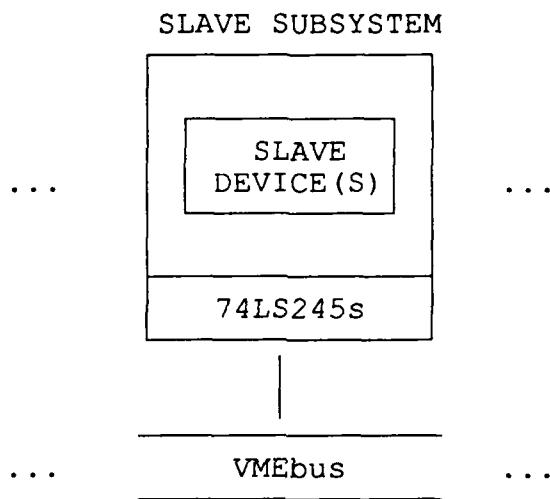
### **3. Configurations**

In a multi-processor VMEbus-based system with a variety of peripheral devices, each subsystem can fulfill one of three primary roles. The subsystem can serve as a slave-only, as a master-only or as a master-slave combination. A subsystem can also have the role of direct memory access (DMA) in a master-slave configuration. (To limit the size and complexity of this thesis, the DMA master-slave configuration is not discussed.) These roles determine the way the subsystem is integrated to the system bus.

#### **a. Slave-Only Application**

In the slave-only configuration, the subsystem is slaved to the VMEbus. In other words, this subsystem is incapable of making a request to obtain access and control of the VMEbus. The slave subsystem is a device which other subsystems utilize. Examples of slave subsystems include communication ports and stand alone memory boards. If intelligence (logic) is added, the subsystem can evolve into an input/output (I/O) channel or a mass storage subsystem. Figure 2.1 shows the simplicity of a slave

subsystem interfaced to the VMEbus. The 74LS245s octal-bus transceivers with 3-state outputs provide the drive capability for transmitting signals onto the VMEbus and the receiver capability for receiving signals from the VMEbus. If desired, the 74LS245s can also be disabled to isolate the slave subsystem from the VMEbus.

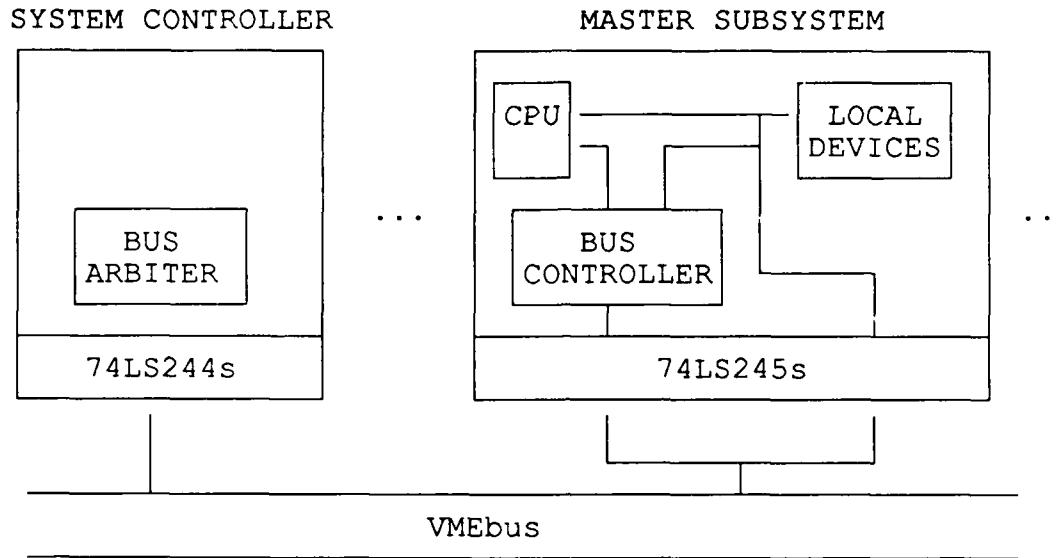


**Figure 2.1: Slave-Only Subsystem**

b. Master-Only Application

In the master-only configuration, the subsystem has the ability to gain control of the VMEbus. A master-only subsystem has an onboard central processor unit (CPU) with or without local slave devices. It is interfaced to the VMEbus with a bus controller. When the subsystem has gained control of the VMEbus, this subsystem is said to be in a master role. Figure 2.2 gives a simplified illustration of a VMEbus system with a master-only subsystem

attached to it. Comparison of Figures 2.1 and 2.2 shows the added complexity required in a subsystem which can gain control of the VMEbus. In addition, a system controller is included in Figure 2.2 to illustrate the added system complexity required to control bus accesses.



**Figure 2.2: Master-Only Subsystem**

Given a request by the CPU, the bus controller generates a bus request signal through an 74LS245 to the system controller's bus arbiter. (The abilities of the 74LS245 were described in the slave-only subsystem.) The bus arbiter receives requests from subsystems on the VMEbus through the 74LS244 octal-buffers and line drivers with 3-state outputs. The function of the bus arbiter is to resolve prioritized requests from the subsystems and to generate a bus grant signal through the 74LS244 to the

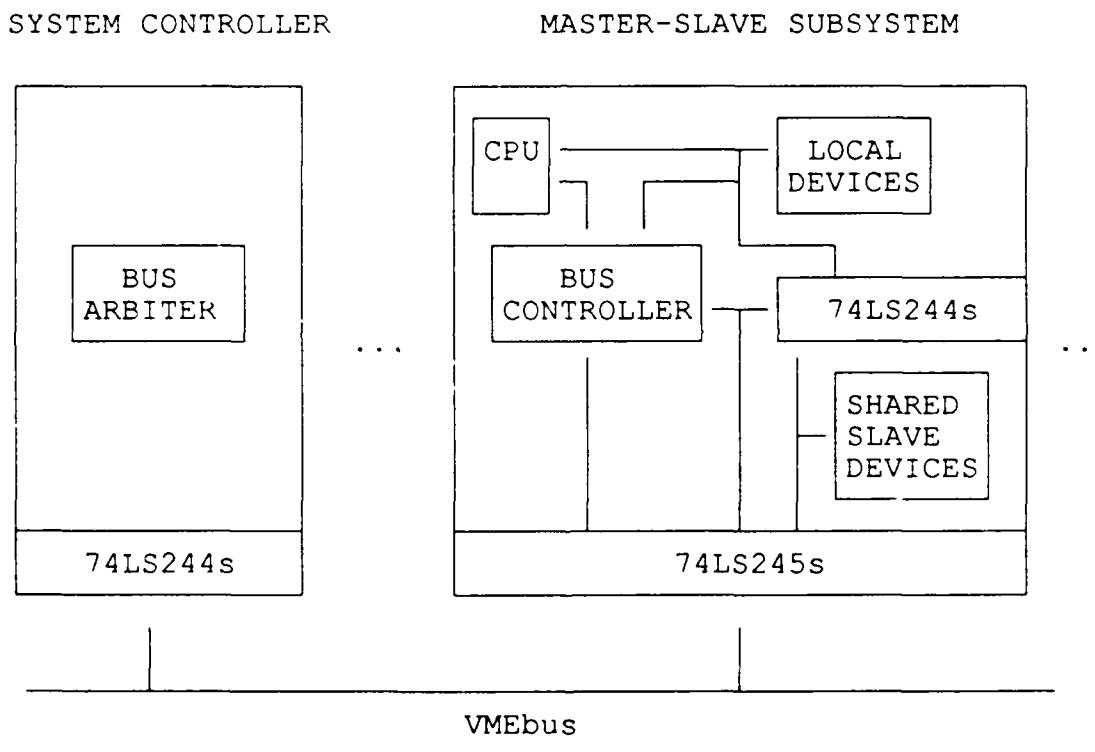
highest priority requesting subsystem. The subsystem's bus controller maintains system integrity by ensuring that a bus grant signal is received prior to permitting a data transfer. The requesting subsystem, after receiving the bus grant signal, negates its bus request and asserts the bus busy signal so that other subsystems cannot gain control of the bus while the data exchange is in process. Also, the bus busy signal informs the bus arbiter that a data exchange is currently in progress and that the bus arbiter can release the bus grant signal. The requesting device is now the bus master. When the data exchange is complete, the requesting device releases the bus busy signal to allow the bus arbiter the opportunity to grant the bus to another subsystem.

If the bus is in use and a higher priority bus request is asserted, the bus arbiter asserts the bus clear line. The bus clear signal informs the current bus master that another subsystem with a higher priority is requesting bus ownership. Each potential bus master should accommodate either a "release when done" or a "release on request" strategy to resolve pending higher priority requests for bus access.

#### c. Master-Slave Application

A master-slave configuration combines the master-only and slave-only capabilities into a single subsystem. As illustrated in Figure 2.3, the CPU residing on the master-slave subsystem has the ability to gain control of the VMEbus. The system controller and bus arbiter perform the same roles as described in the master-only subsystem.

Shared slave devices are onboard the master-slave subsystem. These devices can be accessed by another subsystem when it has control of the VMEbus (Fig. 2.3). The bus controller isolates the shared slave devices from the CPU by putting the 74LS244s outputs into a high impedance state, whenever another subsystem accesses the shared slave devices. When this happens, the shared slave devices become a global asset to the system. The 74LS245s not only act as line drivers and receivers,



**Figure 2.3: Master-Slave Subsystem**

they also prevent access from the VMEbus to shared slave devices when the appropriate control signal is asserted by the bus

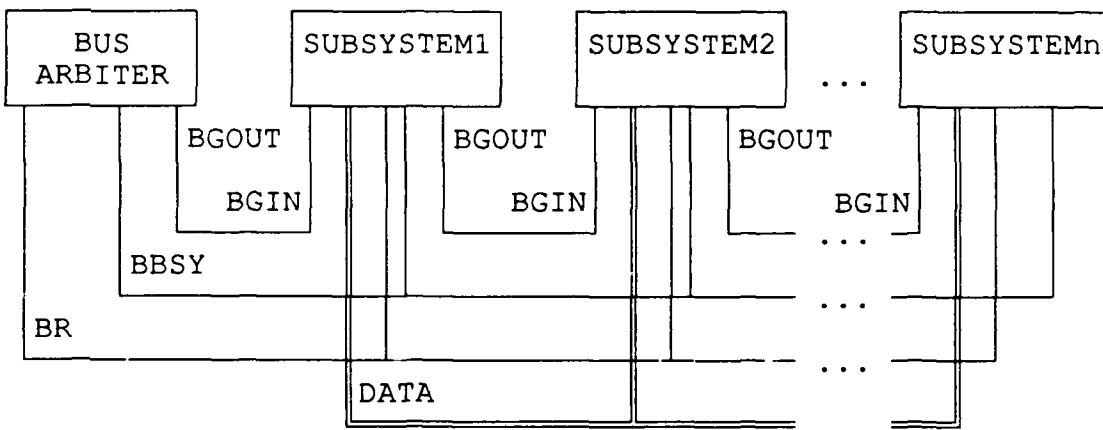
controller. Whenever the local master (in this case the CPU) is accessing the shared slave devices, these devices become a local asset. As discussed in the master-only application, the bus controller preserves the VMEbus protocol.

#### **4. Arbitration Protocols**

Arbitration protocols ensure conflict-free access to the system bus from all subsystems and are crucial in a multi-processor environment [Ref. 6:p. 100]. An arbitration protocol ensures that only one bus master has access to the bus at a time, thus safeguarding the bus from collisions in which information is transferred on the bus by multiple sources. The VMEbus supports both serial and parallel arbitration schemes or a combination of both methods. These two method are described in the following paragraphs.

Daisy chaining is a method of arbitrating a shared communication bus by serial prioritization. Figure 2.4 illustrates daisy chain arbitration. If the bus is in use, any subsystem requesting ownership must wait till the present bus master relinquishes control of the bus. A subsystem requests access to the bus by asserting the bus request (BR) signal. The bus arbiter or other controlling device acknowledges the bus request by asserting a bus grant (BG) signal to the bus grant input (BGIN) of SUBSYSTEM1, the first subsystem in the daisy chain. If SUBSYSTEM1 is requesting the bus, it asserts the bus busy (BBSY) signal and it continues to negate its bus grant output (BGOUT) signal. SUBSYSTEM1 can now begin data transfer. If the bus request was

made by any subsystem other than SUBSYSTEM1, the BG signal is passed by SUBSYSTEM1 to the next subsystem in the chain (SUBSYSTEM2). The BGOUT signal from SUBSYSTEM1 becomes the BGIN signal to the next subsystem in the chain (SUBSYSTEM2). This process is repeated until the highest priority requesting subsystem receives the BGIN signal. SUBSYSTEM1 has a higher priority than SUBSYSTEM2. The last subsystem in the chain (SUBSYSTEMn) has the lowest priority.

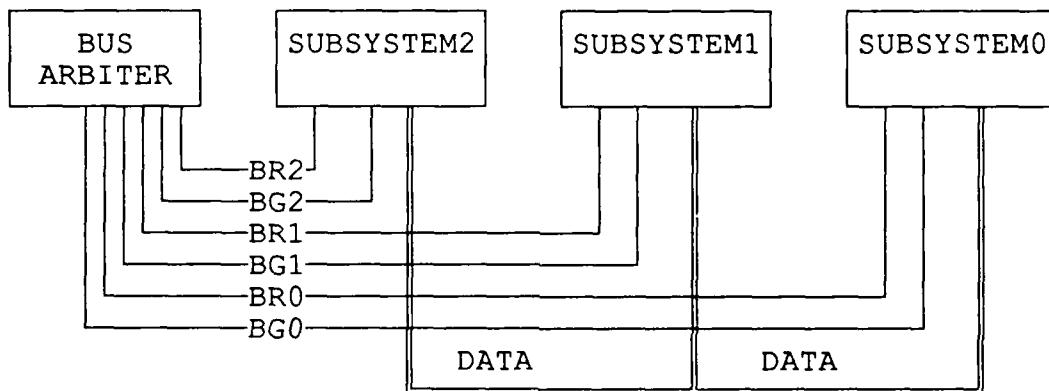


**Figure 2.4: Daisy Chain Arbitration**

The BR and BBSY signals are wire-ORed (open collector-active low), i.e., the logic is tied together at a wire connection. Consequently, the BR signal will cause the BBSY signal to be asserted once the BGIN signal is received through the daisy chain.

Parallel arbitration is a method of arbitrating a shared communication bus by priority levels. An example of a three-level parallel arbitration scheme is shown in Figure 2.5. In Figure 2.5,

bus request zero (BR0) has the lowest priority level, while bus request two (BR2) has the highest priority level. The highest priority subsystem with a pending request is granted access to the bus. In this parallel arbitration scheme, the subsystems desiring use of the bus make bus requests (BRx) through the bus arbiter. The bus arbiter or other controlling device then sends out a bus grant (BGx) onto the bus to the highest priority subsystem with a pending bus request.



**Figure 2.5: Parallel Arbitration**

The main advantage of the daisy chain arbitration scheme over the parallel arbitration scheme is that subsystems can be inserted sequentially, one after the other. Consequently, new subsystems are easily added to the system.

The main advantage of the parallel arbitration scheme over the daisy chain arbitration scheme is that arbitration can be performed faster. Parallel arbitration does not propagate a bus grant signal down a chain, but rather the bus grant signal is sent

directly to the highest priority subsystem requesting service. However, the parallel arbitration scheme limits the number of subsystems that the bus arbiter can accommodate.

Any fixed priority arbitration cannot ensure that the subsystem with the lowest priority level will be serviced if higher priority subsystems make frequent requests. The daisy chain arbitration and parallel arbitration methods may need to be modified or a controller may need to be incorporated to ensure each subsystem can be serviced fairly.

The VMEbus uses a serial-parallel combination for bus arbitration with only one bus arbiter. VMEbus arbitration uses a scheme with four parallel priority levels similar to Figure 2.5. Each priority level, however, can have subsystems daisy-chained as illustrated in Figure 2.4. In other words, the bus arbiter grants bus access to a given level and then the daisy chain at that level determines which subsystem actually gets the bus.

The VMEbus arbitration process includes the BBSY signal (as shown in Figure 2.4) and the bus clear (BCLR) signal. The BBSY and BCLR lines are added to the bus arbiter and all subsystems on the VMEbus. The VMEbus BBSY signal is asserted by the subsystem which is granted bus access. The BCLR output signal informs all subsystems on all priority levels that a subsystem on a higher priority level than the current bus master has requested access to the VMEbus. As mentioned earlier, the requesting subsystem should accommodate a "release when done" or "release on request" strategy to resolve pending higher priority requests for bus access.

## **B. MEMORY-MANAGEMENT**

Memory-management can employ a combination of methods to organize the physical memory associated with a microprocessor or system. These methods effectively free the programmer using the system, from being concerned where the program code and program data will reside in memory. This thesis addresses the memory-management concepts of memory protection, virtual-memory and dual-ported memory.

### **1. Memory Protection**

One method used to organize the address range of a microprocessor is to divide its address space into two or more blocks. Each block of the address space can be designated for a specific purpose, such as supervisor memory or user memory.

The MC68010 microprocessor has two modes of operation. These modes are the user mode and the supervisor mode. The user mode provides an instruction set for the programmer to accommodate a majority of applications. The supervisor mode provides additional instructions and privileges for use by the operating system and other system-related software [Ref. 7:p. 1-1].

The user memory is the area designated for non-privileged individuals to use. Such an individual executes programs in the user mode. The address range for the user is normally limited because it does not include the addresses associated with the operating system and the memory-mapped peripherals. Additionally, the user is restricted from executing privileged supervisor instructions. In contrast, the operating system executes programs

in supervisor mode and can address supervisory memory and memory-mapped peripherals as well as user memory. This segregation of the supervisor and the user precludes the user from reconfiguring the system, but still allows the user access to part of the physical memory and to the computational power of the microprocessor. Typically, the user must request the operating system to perform operations which the user is not allowed to perform.

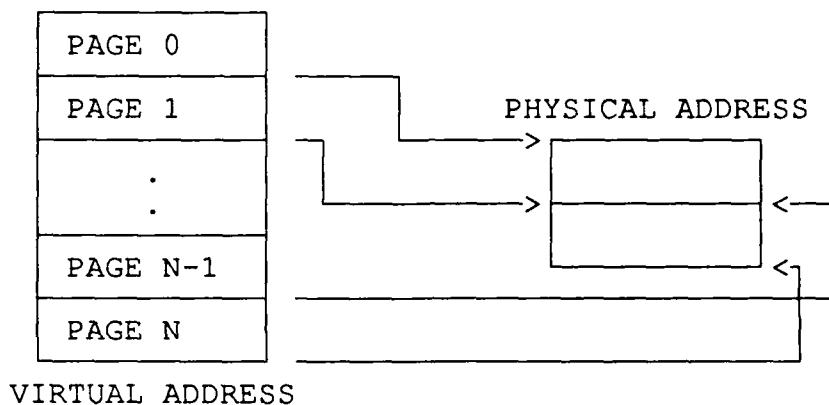
## **2. Virtual-Memory**

Virtual-memory allows programs to be executed which require more memory space than is physically resident. Therefore, the maximum program size is not limited by the size of physical memory. Originally, this method was designed to reduce and more effectively use memory.

A virtual address is an address located within the address space of the microprocessor. Consequently, with the MC68010 microprocessor, there exists 16 megabytes of virtual-memory. A virtual-memory implementation groups the virtual addresses into blocks called pages. Figure 2.6 shows such a grouping with zero through N pages of virtual-memory but with only enough physical memory to accommodate two virtual pages in physical memory. In Figure 2.6, virtual PAGE 1 and virtual PAGE N are mapped into separate physical pages.

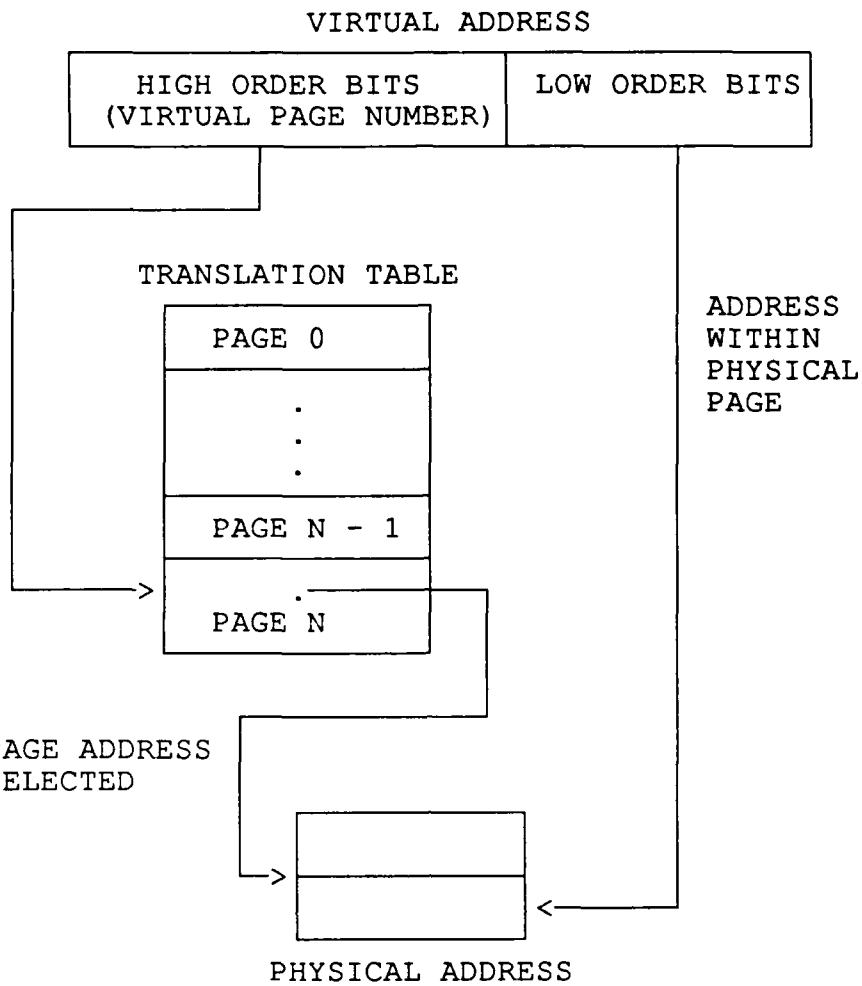
When the CPU generates a virtual address, the virtual address is translated into a physical address. The address translation process includes fairly sophisticated memory protection so that tasks cannot interfere with each other or access resources

not allocated to them. Figure 2.7 illustrates a simplified memory-mapping mechanism. The high order virtual address bits are referred to as a virtual page number. The virtual page number references a location of the translation table. The translation table has as its contents a physical page number which references the starting location of the physical memory's page address. The low order virtual address bits give the relative address offset of the desired address within the physical page selected.



**Figure 2.6: Virtual-Memory-Mapping**

Generally, each processing task has its own translation table similar to Figure 2.7. These tables are switched whenever the active task changes which avoids interference between processing tasks.



**Figure 2.7: Mapping Mechanism**

When the CPU generates a virtual address in a page that is not present in physical memory, for instance PAGE 2 as in Figure 2.7, the memory manager senses that fact and generates a page fault. The page fault triggers a chain of events which ultimately retrieves the desired page of the program from secondary storage and places it in physical memory. The instruction which caused the page fault is then continued or restarted. [Ref. 2:pp. 326-330]

### 3. Dual-ported Memory

Dual-ported memory permits two nearly simultaneous accesses to the memory resource without conflict. Figure 2.8 illustrates a typical configuration of a dual-port memory device. One approach to arbitrating concurrent memory requests in a dual-ported random access memory (RAM) is to sample one request line on the rising clock edge and the other on the falling clock edge. A PORT 1 REQUEST is assumed to be sampled on the rising clock edge.

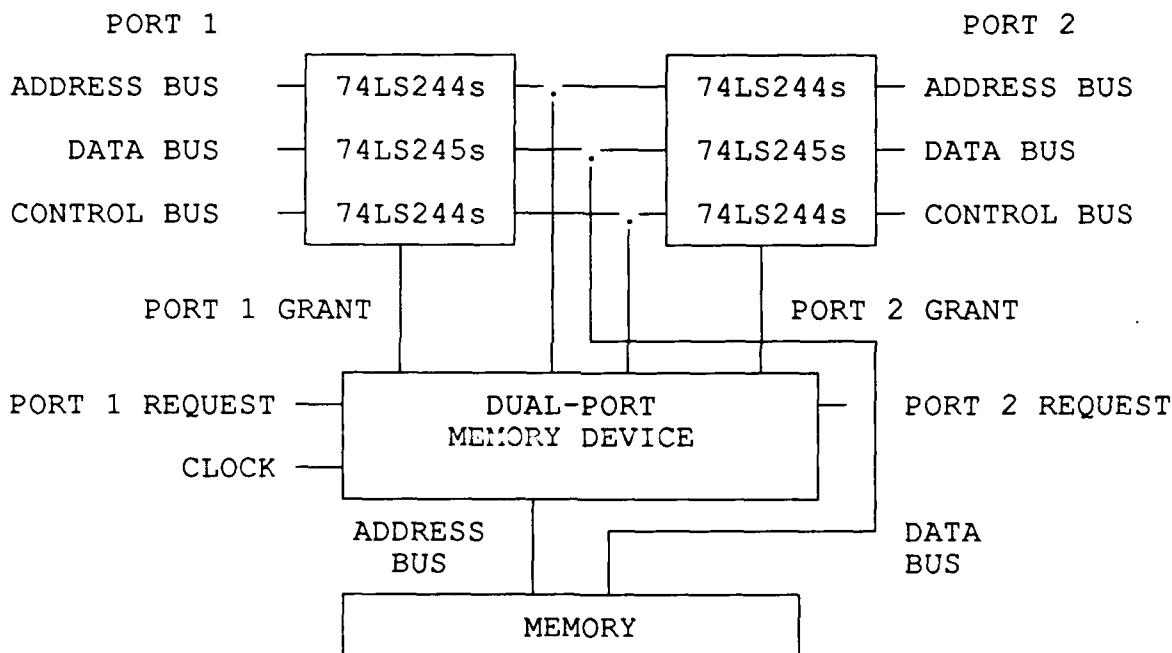


Figure 2.8: Dual-ported Memory

If a PORT 1 REQUEST is asserted, a PORT 1 GRANT is generated which gates the PORT 1 address, data and control lines through the left-hand 74LS244s and 74LS245s in Figure 2.8. The address and control signals are sent to the dual-port memory device and the data

signals are sent directly to memory. The dual-port memory device then gates the address lines to memory. While the PORT 1 GRANT is active, the PORT 2 GRANT cannot be asserted. PORT 2 is thus locked out from gaining access to memory. In contrast, if a PORT 2 REQUEST is asserted and PORT 1 is inactive, a PORT 2 GRANT is generated. This causes PORT 2 to gate the control and address lines through the other 74LS244s to the dual-port memory device and to gate the data lines directly to memory via the 74LS245s.

In the event that both request lines are active, a PORT 1 GRANT will be generated on the rising clock edge or a PORT 2 GRANT will be generated on the falling clock edge. The other request is locked out until the request line of the recognized port is no longer asserted. The other port will then gain access on the appropriate clock edge.

### **III. SYSTEM OVERVIEW**

This thesis seeks to design a system that satisfies the design requirements for a system that can be expanded to a multi-processor system. Additionally, the subsystem design is interrupt-controlled with both virtual-memory and dual-ported memory support. This chapter gives a system perspective on the hardware associated with the system controller circuit board and master circuit board (Fig. 3.1) integrated to the VMEbus.

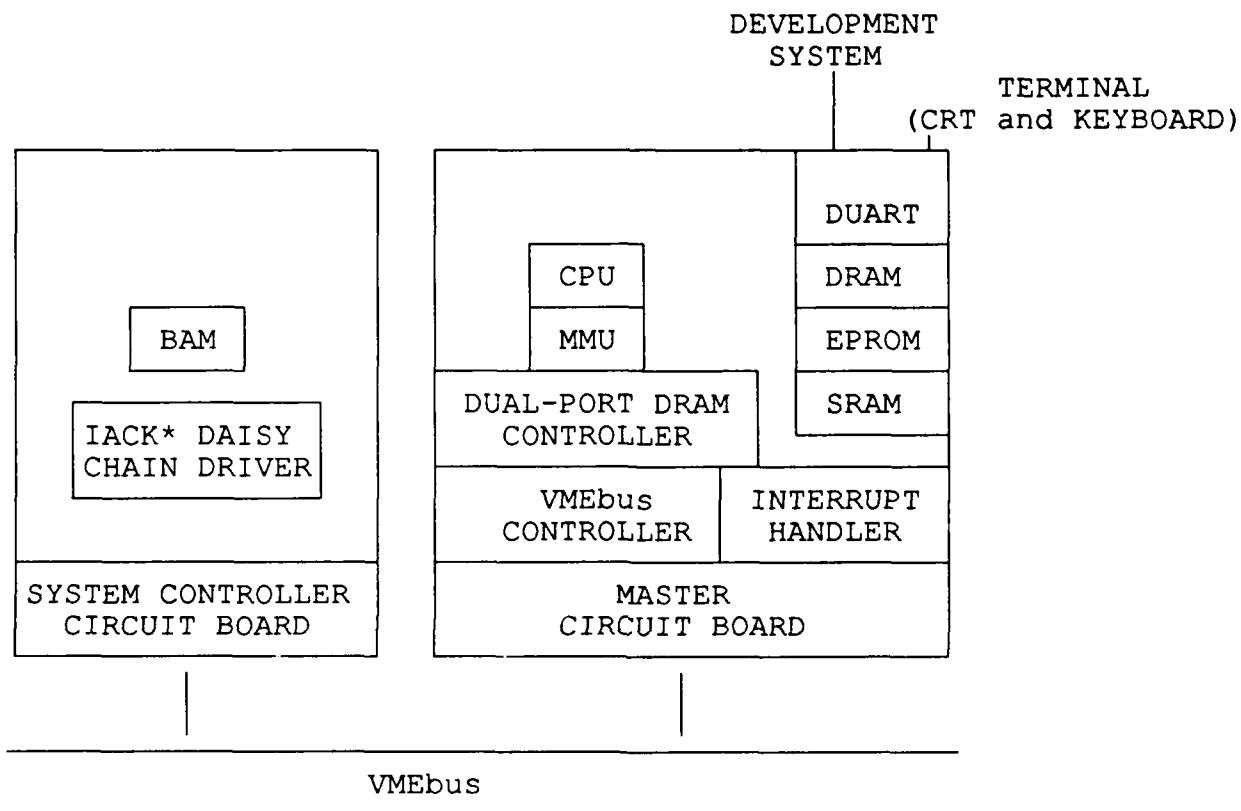
#### **A. SYSTEM CONTROLLER CIRCUIT BOARD**

The VMEbus specification describes the system controller as a board which resides in slot one of the VMEbus back plane [Ref. 4: pp. 5]. The system controller circuit board design provides priority bus access arbitration, a manual system reset and a interrupt acknowledge (IACK\*) daisy chain driver. The system controller subsystem uses line drivers to buffer the arbitration signals and IACK\* signal on the VMEbus.

##### **1. Priority Bus Arbitration**

The Motorola MC68452 bus arbitration module (BAM) peripheral device [Ref. 8] was selected to perform the VMEbus access arbitration. The BAM is configured to accommodate four bus request (BRx\*) inputs and four bus grant (BGx\*) outputs. After parallel arbitration, a bus grant signal is generated by the BAM at the level of the highest priority bus request. The bus grant signal is then daisy chained down on the level of the highest

priority bus request. This VMEbus arbitration method combines the advantages of both the daisy chain arbitration and parallel arbitration methods discussed in Chapter II.



**Figure 3.1: System Block Diagram**

## 2. Manual Reset

The manual system reset provides a system-wide master reset of all devices within all subsystems. Resetting the system re-initializes various devices within it. This is necessary in order to restart the system after system failure.

### **3. Interrupt Driver**

The VMEbus structure provides the IACK\* signal daisy chain. However, a driver is provided on the system controller circuit board to drive the IACK\* signal onto the VMEbus.

## **B. MASTER CIRCUIT BOARD**

The master circuit board is the primary design focus of this thesis. As shown in Figure 3.1, the master circuit board subsystem is composed of nine functional blocks. These functional blocks are the central processor unit (CPU), dual universal asynchronous receiver/transmitter (DUART), dynamic random access memory (DRAM), static random access memory (SRAM), erasable programmable read-only memory (EPROM), memory management unit (MMU), dual-port DRAM controller, VMEbus controller and interrupt handler. The master circuit board is configured in a master-only role as discussed in Chapter II.

### **1. Central Processor Unit**

The Motorola MC68010, 16-bit CPU, was selected to be the processing element because it has the necessary features to support virtual-memory but lacks the added complexity of a 32-bit architecture. It also affords easier wire-wrap assembly than the other Motorola CPUs supporting virtual-memory because wire-wrap is better supported for a dual in-line package (DIP) and there are fewer data and address signals. The signals and programming capabilities of the MC68010 microprocessor are discussed in further detail in Appendix A.

## **2. Dual Universal Asynchronous Receiver/Transmitter**

Two asynchronous serial (RS-232) ports are implemented with the Motorola MC68681 DUART. One serial port is configured to drive a terminal, while the second serial port is used to down-load files from an IBM XT/AT compatible computer. The first serial port is used to permit a human interface to the system. The intent of the second serial port is to provide the ability to develop software on an IBM XT/AT compatible computer with a cross assembler and then to down-load the software through the second serial port to the master circuit board's random access memory (RAM) for testing, debugging and execution.

## **3. Erasable Programmable Read-Only Memory**

The EPROM in this thesis design, contains the exception vector table and the monitor/debugger program. The exception vector table contains the addresses of the routines to be executed as a result of an interrupt or other exception. The monitor program configures the subsystem when it is powered up and handles communications with the terminal for interaction between the microprocessor and the user. It also provides debugging commands and coordinates the previously mentioned down-loading of files. Sixty-four kilobytes of EPROM are provided in the master circuit board.

Once an operating system is developed, it would not be desirable to freeze the interrupt part of the exception vector table into read-only memory (ROM). It should be noted that the

design of an operating system to take advantage of the system's hardware features is beyond the scope of this thesis.

#### **4. Random Access Memory**

Sixteen kilobytes of SRAM and one megabyte of DRAM are provided on the master circuit board.

#### **5. Memory Management Unit**

The use of the Motorola MC68451 MMU affords several advantages to the microprocessor system. The MMU provides the advantages of virtual-memory and a sophisticated memory protection scheme (both previously discussed in Chapters I and II). The MC68451 provides the capability to:

- Translate logical addresses to physical addresses.
- Provide segment descriptors to implement memory protection.
- Detect page faults and other situations requiring operating system intervention.
- Aid the operating system in managing the virtual-memory system efficiently (by use of the segment status registers).

#### **6. Dual-port DRAM Controller**

The Signetics 74F765 dual-port DRAM controller provides access to the DRAM by either a local bus master or a global bus master. If DRAM is accessed by the local bus master, i.e., the CPU on the master circuit board subsystem, it becomes a local asset. It is not desirable for the local CPU to access DRAM via the VMEbus because long access times would be the result. If DRAM is accessed by a global bus master, i.e., another subsystem controlling the VMEbus, it becomes a global asset. The ability to access DRAM locally or globally is desirable for a system that includes

subsystems that interact closely with one another. In addition, the dual-port DRAM controller provides refresh cycles to the dynamic memory integrated circuit chips.

The global memory accesses in this master circuit board subsystem design, use physical addresses to permit the implementation of mailboxes with attached semaphores as discussed in Chapter I. An operating system needs to lock the mailbox page in physical memory at a specified physical address.

## **7. VMEbus Controller**

The Signetics SCB68172 VMEbus controller preserves the VMEbus data transfer and VMEbus access protocols. The VMEbus controller and the MC68010 CPU are configured in a master-only role as illustrated in Figure 2.2 and discussed in Chapter II. The VMEbus controller provides the necessary logic to interface the master circuit board subsystem to the VMEbus.

## **8. Interrupt Handler**

The Signetics SCB68155 interrupt handler is used in the master subsystem design to assist the CPU with interrupt processing. The interrupt handler receives global and local interrupt requests and arbitrates their priority. The arbitration priority is non-maskable interrupts, first, then local interrupts and finally global interrupts.

The interrupt handler acts as a mediator between the CPU and the interrupting device or between the CPU and the interrupting subsystem. Once a local interrupt is generated by the DUART or MMU, control signals are sent between the interrupting device and

the interrupt handler as well as between the interrupt handler and the CPU. The DUART or the MMU responds with a pre-programmed status/ID vector as an interrupt response.

A subsystem can request an interrupt at any time by asserting the appropriate interrupt request line. On detecting an interrupt request, the interrupt handler sends a control signal to the VMEbus controller to request the VMEbus during the interrupt acknowledge cycle. The subsystem making the request then sends the status/ID vector to the master circuit board's CPU.

#### IV. DESIGN IMPLEMENTATION

This chapter discusses the design of the minimal system and of the fully integrated system (master circuit board and system controller circuit board). The minimal system provides the foundation of core resources necessary to construct a computer system. The fully integrated system design can be implemented by integrating additional resources to the minimal system. For comparison, the fully integrated system is illustrated in Figure 3.1, while the minimal system is illustrated in Figure 4.1.

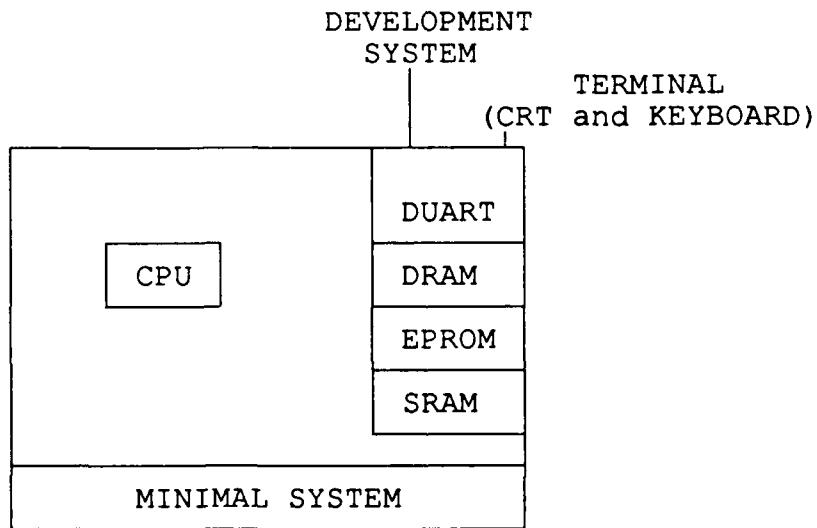


Figure 4.1: Minimal System

## **A. MINIMAL SYSTEM**

Currently at the Naval Postgraduate School (NPS), there exists no computer-aided design (CAD) tools which can simulate the fully integrated system designed in this thesis. This is in part due to the inability of the CAD vendors to keep pace with the profusion of extremely complex very large scale integrated (VLSI) circuit chips. The CAD systems at NPS, Valid Inc.'s SCALD and Futurenet's CAD50, do not support all the peripheral devices incorporated within this thesis. Consequently, a step-by-step progression was made to fully integrate the system. The first stage, referred to as the minimal system, includes the core resources which form the foundation to which more complex devices can be added. When more complexity is added to the minimal system, operational testing can be conducted to insure proper integration of the new devices into the system.

### **1. Memory Map**

Memory-mapping determines how the microprocessor accesses physical memory and peripheral devices. The Motorola MC68010 microprocessor has 23 address lines, A1 through A23. The upper data strobe (UDS\*) and lower data strobe (LDS\*) lines collectively determine address bit A0. Effectively, there are 24 address lines giving an virtual address range of 16 megabytes. Physical memory elements such as static random access memory (SRAM), dynamic random access memory (DRAM) and read-only memory (ROM) are mapped into this 16 megabyte range as are the memory-mapped peripherals.

The memory-mapped peripheral devices have multiple internal registers. The high order physical address bits are used to select a particular peripheral device. The low order physical address bits are decoded inside the peripheral device and subsequently select one of the internal registers. These registers are programmed to configure the device to meet desired performance specifications.

Table I displays the specific locations of the minimal system's memory-mapped devices and the physical memory components within the address space of the MC68010 central processor unit (CPU).

**TABLE I: MINIMAL SYSTEM MEMORY MAP**

PHYSICAL ADDRESS	
\$000000	64K BYTES OF EPROM
\$00FFFF	
\$010000	16K BYTES OF STATIC RAM
\$013FFF	
\$014000	NOT USED
\$7F6FFF	
\$7F7000	MC68681 DUART
\$7F7FFF	
\$7F8000	NOT USED
\$FFFFFF	

The 64k bytes of erasable programmable read-only memory (EPROM) contain the exception vector table and the monitor/debugger program. Appendix B gives the source code listing of the exception

vector table and the monitor/debugger program. The 2500AD MC68010 cross assembler [Ref. 9], running on an IBM XT/AT compatible computer, was used to cross assemble the monitor/debugger source code into a Motorola S-record format [Ref. 10:pp. A-1 - A-4]. In order to program the S-record code into the EPROM, a Data I/O System 29 Universal Programmer was configured to accept Motorola S-records. The S-record file was then sent from the IBM XT/AT to the Data I/O System 29 via an RS-232 interface. Finally, the EPROM programming process was initiated on the Data I/O System 29.

The 16K bytes of SRAM are used to test development software. Files can be down-loaded to the SRAM for debugging. SRAM is used in the minimal system design instead of DRAM to avoid the additional logic necessary to generate refresh cycles for the DRAM.

The MC68681 dual universal asynchronous receiver/transmitter (DUART) is a communications peripheral device that can accommodate two independent full-duplex (receiver/transmitter) ports. The operating mode and data format of each port can be programmed independently. One port of the DUART is configured by the monitor/debugger program to accommodate the down-loading of files from an IBM XT/AT compatible computer. The other port of the DUART is configured to communicate with the terminal. The memory map (Table I) delineates a physical address range of \$7F7000 through \$7F7FFF for the DUART. A chip select signal will be generated for the DUART when a physical address is in the range \$7F7000 through \$7F7FFF. The physical addresses in the range

\$7F7010 through \$7F7FFF are multiple maps for the DUART. Multiple maps provide valid addresses to chip select the DUART. They also permit address decoding logic to be simplified. However, to avoid ambiguity, only the physical addresses \$7F7000 through \$7F700F are used to address the DUART.

## 2. Hardware Interface

Appendix C illustrates the circuitry involved in the minimal system. Figures C.1 through C.8 illustrate the minimum system in its entirety.

Figure C.1 illustrates the MC68010 microprocessor used in the minimal system design.

Figure C.2 illustrates the HALT\* and RESET\* generation circuitry. The NE555 timer provides an automatic system reset when the system is powered up. There is also a manual system reset switch (push button). Resetting the system initializes the internal circuitry of the CPU and DUART. A two-input OR gate in the reset circuitry has one input grounded, so it acts as an unneeded buffer. However, in the fully integrated system (discussed later in this chapter), this input is tied to the VMEbus system reset (SYSRESET\*) line. This permits a system-wide reset to the master circuit board illustrated in Figure 3.1.

Figure C.3 illustrates the clock generation circuitry. The 8 MHz CPU clock signal is produced by using a 74LS161 binary counter to divide a 16 MHz signal from a crystal controlled oscillator. A 4 MHz signal from the 74LS161 provides the clock

input for the shift register which is used to help generate the data transfer acknowledge (DTACK\*) and bus error (BERR\*) signals.

Erasable programmable logic devices (EPLDs), specifically Altera EP310s, were used to reduce the chip count in the minimal system. EPLDs were used for address decoding, generating DTACK and BERR signals, performing interrupt control and generating SRAM write enable and RAM and ROM output enables.

Figure C.4 shows the EPLD implementation for the minimal system address decoder. The minimal system address decoder implements the memory map of Table I. Listing D.1 in Appendix D presents the Abel software program for the address decoder. Abel software will be discussed in the next section.

Figure C.5 shows the logic of the circuitry which generates the DTACK\* and BERR\* signals to the CPU. The circuitry prior to the 74LS05 open collector inverters, is implemented by an EPLD. The DTACK and BERR signals are passed through the 74LS05s to give the open collector outputs and the proper assertion levels (DTACK\* and BERR\*). In the event that the MC68010 microprocessor tries to address a location not supported by the design, a bus error (BERR\*) time-out signal is generated after two microseconds. The BERR\* signal causes the CPU to begin bus error exception processing. This invokes the routine whose address is in the longword at address \$000008. The circuit which generates the delay time for BERR\* is referred as a watchdog timer. Listing D.2 in Appendix D presents the Abel description of the DTACK and BERR signals.

The circuitry for EPROM and SRAM is illustrated in Figure C.6. Since random access memory (RAM) and ROM cannot generate a DTACK\* signal to the CPU, additional circuitry is required. The DTACK\* signal informs the CPU that the data transfer has been completed by the slave device. The 74LS164 shift register generates the data transfer delay times for the RAM and the ROM and the bus time-out delay for a bus error condition (Fig. C.5). A 250 nanosecond delay is provided to ensure an adequate time for data transfer between the CPU and the RAM. A 500 nanosecond delay is provided for data transfer between the CPU and the ROM. These transfer times accommodate the data propagation delay, the system address decoding delay and the internal address decoding delay of the RAM and the ROM. The logic for the output enable and the write enable signals are implemented on an EPLD. Listing D.3 in Appendix D presents the Abel description of the SRAM write enable and RAM and ROM output enable signals.

Figure C.7 shows the logic for the interrupt priority level (IPL0\* through IPL2\*) and the interrupt acknowledge (IACK681\*) signal. A level one interrupt request (HHL) is sent to the MC68010 CPU when the MC68681 DUART asserts its interrupt request output (low). An IACK681\* signal is sent to the DUART when a level one interrupt acknowledge is output by the CPU. The logic for the IACK681\* and the IPL0\* through IPL2\* signals are actually implemented with an EPLD. Listing D.4 in Appendix D presents the Abel description of the IACK681\* and IPL0\* through IPL2\* signals.

Figure C.8 illustrates the circuitry which supports the dual serial ports. As mentioned earlier, one port (Port A) of the DUART is configured to communicate with the terminal. The other port (Port B) is configured by the monitor/debugger program to accommodate the down-loading of files from an IBM XT/AT compatible computer.

### **3. Software Support**

#### **a. Exception Vector Table and Monitor/Debugger Program**

The exception vector table contains the addresses of routines to be executed when an exception (trap or interrupt) is detected. The monitor program sets up communications with the terminal, provides debugging commands as well as a down-load command. The exception vector table and the monitor/debugger program (Appendix B) reside in the EPROM starting at physical address \$000000. The exception vector table occupies physical addresses \$000000 through \$0003FF [Ref. 7:p. 4-5]. Physical addresses \$000400 through \$001FFF are not used and the monitor/debugger program begins at the arbitrarily selected physical address \$002000.

The monitor/debugger program was developed on the Motorola Educational Computer Board (ECB) [Ref. 10]. After a system reset, the microprocessor's program counter is initially loaded with address \$002000 to start the monitor/debugger program.

#### **b. Monitor/Debugger Commands**

The monitor/debugger program provides a user with six commands. These commands are not intended to be comprehensive, but

they do provide assistance in program development and debugging.

The user commands are as follows:

- GO address <,break point address>
- MM start address <,end address>
- MD start address <,end address>
- RCH {Axx, Dxx, PC, US, SP, SR}
- REG
- LOAD
  - where <...> implies optional
  - {...} implies select one entry

The GO command is used to execute a program that resides in the system's memory. The program can be placed in memory by using the memory modify command or by down-loading a program from an IBM XT/AT compatible computer. The address in the GO command gives the location where program execution will begin. An optional break point address can be added within the GO command. The break point will stop program execution at the address specified. This is particularly useful if one desires to know the state of the machine, i.e., memory contents or register contents, at that point.

The memory modify command (MM) is used to modify the contents of an address or, if desired, a range of addresses. This command can modify code or data residing in RAM.

The memory display command (MD) is used to display the contents of an address or a range of addresses, if desired.

The change register command (RCH) is used to modify the contents of an address register (Axx), a data register (Dxx), the program counter (PC), the user stack pointer (US), the system stack

pointer (SP) or the status register (SR). One of these options must be specified with the RCH command.

The display register command (REG) displays the contents of the address registers, data registers, program counter, user stack pointer, system stack pointer and status register. This information gives the state of the MC68010. This command is particularly useful when a breakpoint is reached in the debugging process.

The down-load command (LOAD) permits the minimal system to receive software that was developed on an IBM XT/AT compatible computer. After code has been assembled and linked using software such as the 2500AD MC68010 cross assembler, it can be down-loaded to the absolute address (or addresses) specified during the linking process.

#### c. Programmable Logic Device Programming

As already mentioned, EPLDs are used to reduce the chip count on the printed circuit board. The Data I/O Abel [Ref. 11] program was used to compile a high-level language representation of desired digital logic. The output of Abel is a joint electron device engineering council (JEDEC) standard file for programming the EPLDs. This file is then down-loaded to the Data I/O System 29 Universal Programmer to program the EPLDs. Appendix D shows the Abel source code that generates the logic implementations discussed in this chapter and illustrated in Figures C.4, C.5, C.6 and C.7.

## **B. FULLY INTEGRATED SYSTEM**

The intent of this thesis is to design a hardware system so that at some future date an operating system could be developed to control its hardware facilities. These facilities accommodate virtual-memory, protected memory, serial communications, interrupt control and multi-processor abilities interfaced to the VMEbus. A hard disk controlled by a direct memory access (DMA) controller would be needed to implement the paging function required to support virtual-memory. The operating system would use the memory management unit (MMU) to implement user/supervisor memory allocations (protected memory) and virtual-memory. Considerations for a future operating system will be discussed throughout the following sections.

The fully integrated system is composed of the master circuit board subsystem and the system controller subsystem (Fig. 3.1). Each subsystem is decomposed into functional units. The functional units for the master circuit board subsystem are shown in Figure E.1 and the functional units for the system controller subsystem are shown in Figure E.2. Each of the functional units for the subsystems is discussed in the following sections.

### **1. Memory Map**

The memory map (Table II) of the master circuit board's physical address space contains the memory-mapped peripheral devices and the physical memory. This mapping is an enhanced version of the minimal system's physical memory map (Table I).

**TABLE II: SYSTEM MEMORY MAP**

PHYSICAL ADDRESS	
\$000000	64K BYTES OF EPROM
\$00FFFF	
\$010000	16K BYTES OF SRAM
\$013FFF	
\$014000	OFF-BOARD RESOURCE
\$7F4FFF	
\$7F5000	MC68451 MMU
\$7F5FFF	
\$7F6000	SCB68155 INTERRUPT HANDLER
\$7F6FFF	
\$7F7000	MC68681 DUART
\$7F7FFF	
\$7F8000	OFF-BOARD RESOURCE
\$7FFFFFF	
\$800000	ONE MEGABYTE OF DRAM
\$8FFFFFF	
\$900000	OFF-BOARD RESOURCE
\$FFFFFFF	

The memory map allocates 64K bytes of ROM to include the interrupt vector table, monitor/debugger program and operating system. The interrupt vector table and monitor/debugger program perform the same roles as described in the minimal system. However, an operating system would have to be incorporated to handle the enormous code requirements to manage user/supervisor memory allocations (protected memory), page faults (for virtual-memory) and an operating system kernel. The intent is for the core of the operating system to reside in ROM, since a mass storage

device is not incorporated in this subsystem design. A design of a multi-disk control module for a VMEbus-based system was presented in an earlier thesis [Ref. 12].

The 16k bytes of SRAM retains upward compatibility with the minimal system. The SRAM will be used until the DRAM can be incorporated into the master circuit board subsystem. However, if an operating system requires more than the 64K byte size of ROM, which is a likely possibility, any range spanning the physical addresses \$010000 through \$7F4FFF could be allocated for more ROM or RAM. This would require changing the address decoding logic and adding ROM or RAM chips to the master circuit board subsystem design.

The MC68451 MMU [Ref. 13] is memory-mapped because its internal registers must be programmed for the desired virtual-memory configuration and address translation. By using the MC68010's function codes (see Appendix A) along with the desired address translation scheme, an operating system can separate the supervisor's address space from the user's address space, thus implementing a memory protection scheme.

The SCB68155 interrupt handler hardware [Ref. 14:pp. 2-369 - 2-385] is memory-mapped so that it can be initialized for the desired mode of operation. The interrupt handler can accommodate local interrupts from the DUART and the MMU as well as interrupts from global bus masters.

The MC68681 DUART [Ref. 15] provides the interface to two RS-232 serial links. One link is used for communications with the

terminal, while the other link is used for communications with an IBM XT/AT computer. The DUART is configured to provide the desired serial communications characteristics such as baud rate, parity and stop bits.

One megabyte of DRAM is provided for the master circuit board subsystem. The operating system would manage this resource by assigning virtual pages to physical memory. It is intended that a portion of the DRAM's physical address range map to the same virtual address range. This will permit global memory access to pass semaphores and messages between the master circuit board and other subsystems, as discussed in Chapter I.

It is important to note that if an address falls into the ranges of \$014000 through \$7F4FFF, \$7F8000 through \$7FFFFF or \$900000 through \$FFFFFF, the CPU is accessing an off-board device.

## **2. Master Circuit Board**

### **a. Microprocessor**

The MC68010 CPU (Fig. E.3) is the processing element of the master circuit board subsystem. The signals of the CPU can be organized into functional groups (see Appendix A) which describe the role of the signals within the subsystem.

The CPU has two bi-directional open collector pins, HALT\* and RESET\*, which require pull-up resistors to ensure that the signals are not asserted until the appropriate events occur.

The only bus master on the subsystem is the MC68010. Hence, the bus request (BR\*) and the bus grant acknowledge (BGACK\*)

signals require a pull-up resistor to ensure that the CPU does not perform bus arbitration.

No Motorola M6800 peripherals are used in the master circuit board design. Hence, the valid peripheral address (VPA\*) signal is tied to a logical one.

The circuitry to generate the DTACK\* and BERR\* signals (discussed later) are open collector signals. Hence, pull-up resistors are used to ensure that these signals are not inappropriately asserted.

#### b. Halt and Reset Generation

The HALT\* and RESET\* generation circuitry (Fig. E.4) provides manual and automatic power-on subsystem reset to the CPU and peripheral devices. The NE555 timer provides an automatic power-on reset to the subsystem. The NE555 timer is configured as a one-shot to generate the power-on reset signal. This automatic reset occurs within the first few tenths of a second after the subsystem is powered on. An external system reset can also reset the subsystem. This system reset is generated from the system controller subsystem via the VMEbus. A debounced switch is used to cause a manual reset of the subsystem.

A reset causes the CPU to read into the SP register and PC register the longword (32-bits) contents of physical addresses \$000000 and \$000004, respectively. Recall that ROM begins at physical address \$000000. Consequently, the two longwords beginning at physical address \$000000 are retrieved from non-volatile memory. The initial PC vector at physical address \$000004 contains the

value \$002000, so when this value is read into the PC, execution of the monitor/debugger program is started.

c. Clock Generation

The clock generation circuitry (Fig. E.5) provides clocking signals to the CPU and to the peripheral devices. A 74LS161 binary counter is used to divide the 16 MHz signal from the crystal oscillator into rates that accommodate the CPU, the MMU, the dual-port DRAM controller and the interrupt handler hardware. A 4 MHz signal is sent to additional circuitry to help generate the DTACK\* and BERR\* signals.

d. Local Bus Address Decoding

Once a virtual address is mapped to a physical address, the local bus address decode circuitry (Fig. E.6) is used to generate chip select signals for RAM, ROM or a peripheral device based upon the system memory map (Table II). Two Altera EP310 EPLDs [Ref. 16:pp. 2-57 - 2-62] were used in the design to be programmed via Abel software [Ref. 11]. As mentioned earlier, Abel is software developed by Data I/O Corporation that permits a high-level language description of the logic function to be programmed on a EPLD, programmable array logic (PAL) or similar logic device.

e. Memory Management Unit

The MMU circuitry (Figs. E.7 and E.8) provides the subsystem with virtual-memory support and memory protection. The address translation from a virtual-address-to-physical-address is done by this device. Once the MC68451 MMU has been configured by the operating system, the address translation is performed

internally within the MMU and is thus hidden from the subsystem unless a page fault occurs. The internal details of the MMU are given in its reference manual [Ref. 13].

A page fault (FAULT\*) signal is generated if the MMU detects a write violation or if address translation cannot be performed successfully. The write violation occurs if an attempt is made to write to a write-protected portion of physical memory. If address translation cannot be performed, this denotes to the operating system that a new memory page may need to be brought into memory from a hard disk or that there is a system error. The operating system configures the MMU to write-protect memory segments and to implement virtual-memory-mapping by the MMU.

The circuitry to inhibit virtual-address-to-physical-address translation during an interrupt cycle is illustrated in Figure E.7. The mapped address strobe (MAS\*) and ALL input signals to the MMU are generated during an interrupt acknowledge cycle.

The physical data strobe generation circuitry (Fig. E.8) is used to generate the physical upper data strobe (PUDS\*) and the physical lower data strobe (PLDS\*) signals. The PUDS\* and PLDS\* signals are generated during normal virtual-address-to-physical-address translation. Normal address translation is the mapping of a virtual address to a physical address without a page fault occurring. The physical data strobes will not be generated if there is a write cycle for a write-protected segment. This is accomplished by the write inhibit (WIN\*) signal generated by the MMU.

The physical address strobe circuitry (Fig. E.8) generates a physical address strobe (PAS\*) signal to denote that the address translation has taken place and the physical address is valid and stable.

f. Dual-port DRAM Controller

The dual-port DRAM controller circuitry (Figs. E.9, E.10 and E.11) provides two paths into RAM [Ref. 17]. The local bus master (the CPU) can be ported to the RAM or a global bus master can be ported to the RAM via the VMEbus. Two paths into RAM are especially useful because processor subsystems can pass information-carrying semaphores. Also, The 74F764 dual-port DRAM controller provides DRAM refresh.

The 3-state capability of the 74LS244s (Fig. E.9) octal-buffers and line drivers with 3-state outputs are used to isolate one port access to the dual-port DRAM controller from the other port. The port is selected by the appropriate clock edge and control signal to the request input (REQ1\* or REQ2\*) of the 74F764 dual-port DRAM controller.

The control signal for REQ1\* of the 74F764 (CS764REQ1\*) is generated by the local bus address decoder and the control signal for REQ2\* of the 74F764 (CS764REQ2\*) is generated by the VMEbus address decoder. If CS764REQ1\* is active on a rising clock edge and SEL2\* is not asserted, the local master is granted access to the 74F764. The dual-port DRAM controller then asserts SEL1\* to enable the 74LS244s and 74LS245s on the local bus side.

If CS764REQ2\* is active on a falling clock edge and SEL1\* is not asserted, the global bus master is granted access into the 74F764. The dual-port DRAM controller then asserts SEL2\* to enable the 74LS244s and 74LS245s for the global bus side. In each case, the select line is released after the request signal is no longer asserted.

If both request lines are asserted and neither select line is asserted, on the next (rising or falling) clock edge, the select signal will be generated for the appropriate port access. The request that is locked out cannot gain access to the dual-port DRAM controller until the other port has completed its task and is no longer asserting its request signal.

The 74LS245s octal-bus transceivers with 3-state outputs, illustrated in Figure E.10, are used to buffer the data signals. Data can be sent between the CPU and the VMEbus, between the CPU and the DRAM or between the DRAM and the VMEbus. The data enable signal (DATAEN\*) enables data to flow between the CPU and the VMEbus. The select port one (SEL1\*) signal enables data to flow between the CPU and the DRAM, while the SEL2\* signal enables data to flow between the DRAM and the VMEbus. The data flow direction to the 74LS245s is controlled by the read/write (R/W\*) signal during local DRAM accesses, while the global R/W\* signal (GR/W\*) controls the direction for global DRAM accesses. The data direction enable (DDEN) signal controls the data direction flow between the CPU and the VMEbus.

The 74F764 can only effectively accommodate 18 address lines. Consequently, additional logic illustrated in Figure E.11 must be incorporated to handle address bit A19, which is required to give access to the desired one megabyte of RAM.

When the row address strobe (RAS\*) signal becomes inactive, the data transfer acknowledge output from the 74F764 (DTACK764) is asserted. The DTACK signal of the 74F764 signals that data has been transferred to or from memory.

g. Dynamic Random Access Memory

The dynamic random access memory circuitry (Figs. E.12, E.13, E.14 and E.15) provides one megabyte of DRAM for the master circuit board subsystem. The DRAM is divided into two 512k byte blocks. The odd bytes are stored in one 512k byte block (Figs. E.12 and E.13), while the even bytes are stored in the other 512k byte block (Figs. E.14 and E.15).

The DRAM receives refresh cycles from the dual-port DRAM controller. Although the 74F764 dual-port DRAM controller seizes control of the DRAM during refresh cycles, a bus arbitration process is not needed. An 8 MHz clock pulse (RCP) is divided by 64 to produce a refresh request internal to the 74F764. If no request signal (REQ1\* or REQ2\*) is asserted on the 74F764, a nine-bit counter internal to the 74F764 is incremented. The counter value which represents the row in memory to be refreshed is then placed on output lines MA0 through MA8 of the 74F764. The RAS\* signal is then asserted for four clock cycles to refresh a row in memory.

Finally, the RAS\* signal is released and the refresh cycle is complete.

h. EPROM and SRAM

The EPROM and SRAM circuitry (Fig. E.16) provide 64k bytes of ROM and 16k bytes of SRAM. The EPROM contains the resident exception vector table and the monitor/debugger program. The SRAM is upward compatible from the minimum system. If additional memory is required by a resident operating system, a modification to the local bus address decoding logic would permit the size of ROM or RAM to be increased.

i. Dual Serial Port

The MC68681 dual universal asynchronous receiver/transmitter serial port circuitry (Fig. E.17) is used to provide serial communications with the terminal and the IBM XT/AT computer. Port A is dedicated to the terminal and Port B is dedicated to the IBM XT/AT computer. The 3.6864 MHz crystal is used to generate the baud rates for data transmission for both ports. The terminal provides an interface to the system for the user. The IBM XT/AT is used to down-load files into the master circuit board subsystem's memory.

j. Interrupt Handler

The interrupt handler circuitry (Fig. E.18) provides the necessary logic to accommodate interrupts from devices residing on the master circuit board subsystem and global devices residing on other subsystems. The SCB68155 interrupt handler can

accommodate six local interrupts, seven global interrupts and a non-maskable interrupt (NMI).

Local interrupts (LRQ1\* through LRQ6\*) have a higher precedence than the global interrupts (IRQ1\* through IRQ7\*). The local interrupt signal LRQ6\* has the highest priority, while local interrupt signal LRQ1\* has the lowest priority. The global interrupt signal IRQ7\* has the highest priority, while global interrupt signal IRQ1\* has the lowest priority. The NMI signal has priority over local and global interrupts and it is provided for a catastrophic occurrence such as an alternating current (AC) power failure.

Local interrupts are generated by the DUART and the MMU. The DUART is programmed to provide an interrupt request when a port buffer full condition is met. The buffer full condition of the MC68681 DUART occurs whenever a character is received from the terminal keyboard or from the IBM XT/AT. The local interrupt generated by the MC68451 MMU occurs when the interrupt bit of the page status register is set during normal address translation.

When a local or global interrupt occurs, the interrupt handler hardware generates an interrupt priority level output on lines IPL0\* through IPL2\* to the CPU. The CPU responds by acknowledging the interrupt with the interrupt acknowledge signal (IACK\*) and places the interrupt level on address lines A1 through A3. The interrupt handler hardware reads the interrupt level on address lines A1 through A3 to determine which level is being acknowledged. If the interrupt was from a local device, the

interrupting device provides the vector number on the local data bus. If the interrupt was from another subsystem on the VMEbus, the interrupt handler hardware generates a bus interrupt acknowledge (BIACK\*) signal to the VMEbus controller and the VMEbus. The VMEbus controller obtains control of the data transfer bus (DTB) so that an interrupt vector can be obtained from the interrupting subsystem. The BIACK\* signal is only generated if the bus interrupt level is not masked (within the interrupt handler) and a local interrupt is not pending.

Once the local CPU has acknowledged the (local or global) interrupt request and has obtained an interrupt vector, the local CPU saves the state of the machine and transfers control to the appropriate interrupt handling routine. This prepares the CPU to perform an interrupt handling routine. After completion of the interrupt handling routine, the stored state of the machine is restored and the CPU resumes processing where it left off at the interrupt. [Ref. 7:pp. 4-3 - 4-16; Ref. 18:pp. 5-1 - 5-15]

k. Data Transfer Acknowledge and Bus Error Generation

The data transfer acknowledge and bus error generation circuitry (Fig. E.19) provides control signals to the CPU. This circuitry physically resides within a Altera EP310 EPLD. The DTACK\* signal denotes that a data transfer has been completed by the slave device addressed. The MC68681 DUART, MC68451 MMU, SCB68172 VMEbus controller, SCB68155 interrupt handler and 74F764 dual-port DRAM controller peripheral devices possess the necessary

logic to generate their own DTACK\* signal to acknowledge receipt or availability of data.

The master circuit board's RAM and ROM chips cannot generate their own DTACK\* signals so external circuitry must do it for them. The DTACK\* generation circuitry for the SRAM and ROM must allow adequate time for the data transfer. All these DTACK\* signals are ORed together to produce the MC68010 DTACK\* input.

If the CPU on the master circuit board makes an off-board access using the off-board (OFFBOARD\*) signal to the VMEbus controller, the DTACK\* signal (DTACK172\*) is generated from the VMEbus controller. The off-board device provides a global DTACK\* signal (GDTACK\*) to the VMEbus controller (Fig. E.20) via the VMEbus DTACK\* line. In turn, the VMEbus controller would provide the DTACK172\* signal for the DTACK\* circuitry. This arrangement permits long access times on the VMEbus.

If the master circuit board's DRAM is being accessed as a global asset, the GDTACK\* signal is generated by the SEL2\* and DTACK764 signals as illustrated in Figure E.11.

The BERR\* signal is generated under one of three conditions. First, the BERR\* signal is generated when the maximum allowable SRAM and ROM data transfer time has been reached and a DTACK\* signal has not been received by the CPU. Secondly, a global bus error (BERR172\*) signal can be received from a VMEbus watchdog timer if the master circuit board subsystem has control of the VMEbus. Finally, if a page fault signal (FAULT\*) is generated by the MMU, this also causes a bus error condition.

The bus error condition causes exception processing to occur. The current state of the machine is saved. Information from the saved state of the machine can be used to determine the cause of the bus error. This is handled by the bus error exception routine as part of an operating system.

If the first port of the dual-port DRAM controller is not active and a refresh cycle is not taking place, a global bus master can have access to the DRAM. The master circuit board's CPU is unaware of the access to the DRAM through the second port. Consequently, the burden is placed upon a global master or a VMEbus watchdog timer to provide a global BERR\* signal (GBERR\*) on the VMEbus BERR\* line, when appropriate, to the VMEbus controller. The GBERR\* signal is sent to the BERR\* circuitry (Fig. E.19) via the BERR172\* signal.

#### 1. VMEbus Controller

The VMEbus controller circuitry (Fig. E.20) provides the necessary logic for the master circuit board subsystem to gain access to the VMEbus. The SCB68172 VMEbus controller provides control signals (VMEEN\*, DATAEN\* and DDEN) to the master circuit board subsystem's drivers and transceivers. The purpose of the VMEbus enable (VMEEN\*) signal is to enable the bus drivers only when there is an off-board (OFFBOARD\*) access. In addition, the data flow (DATAEN\*) and its direction (DDEN) are controlled. Parallel jacks are provided which permit jumper selection of the master circuit board subsystem's priority on the VMEbus.

m. VMEbus Address Decoding

The VMEbus address decode circuitry (Fig. E.21) permits access of a global bus master to the second port of the dual-port DRAM controller and ultimately into DRAM. Any subsystem, which has gained control of the VMEbus, has the ability to access the designated (by the operating system) area of DRAM for semaphore passing. The VMEbus address decoder provides the chip select signal CS764REQ2\* to the dual-port DRAM controller (Fig. E.9). If the CS764REQ2\* is asserted when clock edge falls and SEL1\* signal of the 74F764 is not asserted, the isolation drivers are enabled to permit the flow of data and addresses from the global resource to the DRAM.

n. VMEbus Drivers

The circuitry for the master circuit board's VMEbus drivers (Figs. E.22, E.23 and E.24) provides control of signals from the local bus to the VMEbus and from the VMEbus to the local bus. The VMEbus controller controls the direction of the signal flow as requested by the CPU. Whenever the local bus master, the CPU, is not in control of the VMEbus, all signals from the local bus are isolated at the drivers by the VMEbus controller. Thus, in this case, no signals are gated onto the VMEbus from the local bus. However, another subsystem, if in control of the VMEbus, has direct access to the DRAM through the dual-port DRAM controller. The global addresses on the VMEbus fall into the range of the one megabyte of user DRAM in the master circuit board subsystem's memory map (Table II).

### **3. System Controller Circuit Board**

#### **a. Bus Arbiter**

The VMEbus arbitration circuitry (Fig. E.25) provides the logic to arbitrate prioritized bus requests in parallel. Each bus request is then daisy chained down to the requesting device. Each subsystem capable of VMEbus access must have the ability to provide a bus request at one of four priority levels. The highest priority signal used is  $\text{DBG7}^*$ , while the lowest priority level signal used is  $\text{DBG4}^*$ . The process of resolving the VMEbus requests was described in Chapter II. Since the MC68452 bus arbitration module (BAM) [Ref. 8] is an asynchronous device, the bus grant signals ( $\text{DBGx}^*$ ) are not guaranteed to be spike-free. Consequently, a 50 nanosecond delay circuit is used to disable the  $\text{DBGx}^*$  signals during the parallel arbitration process.

#### **b. System Reset**

The system reset circuitry (Fig. E.26) provides a system-wide master reset. This signal is sent on the VMEbus to all circuit boards and it is used to reset the entire system much like the local reset discussed earlier in this chapter.

#### **c. VMEbus Drivers**

The circuitry for the system controller drivers (Fig. E.27) provides the drive capability for signals to/from the VMEbus. Since circuitry was not designed to detect an AC power failure, the  $\text{ACFAIL}^*$  signal is never asserted. This signal is input to the non-maskable interrupt of the interrupt handler (Fig. E.17). The bus clear ( $\text{BCLR}^*$ ) signal informs the current bus master that there is

a higher pending bus request. Burden is placed upon the current bus master to either relinquish control of the bus or to continue control until its task is completed. For the sake of simplicity, the master circuit board subsystem was designed to relinquish control upon the completion of its task. Finally, an IACK\* daisy chain driver is provided for VMEbus interrupts.

## V. RESULTS

Once the minimal system and fully integrated system hardware was designed, the schematic drawings drafted and the pin-out list implemented, software support was required to implement the minimal system. The monitor/debugger program required a thorough check of all its software features. These software features include the capability to set and remove a breakpoint, to display and modify memory, to display and change registers, to start program execution and to down-load software from a development system.

It was discovered while debugging the down-load portion of the monitor/debugger program that the 2500AD 68010 cross assembler's linking process incorrectly resolved external references. The linking process generates a file in the Motorola S-record format. The problem was isolated only after comparing the Motorola S-record to Motorola's instruction format. It was identified that the 2500AD cross assembler was improperly resolving external references. A corrected version of the 2500AD cross assembler was obtained from the vendor that resolved this problem. With the monitor/debugger software developed, the minimal system design was complete.

The monitor/debugger and vector table were programmed in the erasable programmable read-only memory (EPROM) with the Data I/O System 29 Universal Programmer. The Data I/O System 29 segregated

the even bytes and odd bytes into separate EPROMs as required by the Motorola MC68010 central processor unit (CPU).

Erasable programmable logic devices (EPLDs) were used to reduce the chip count in the minimal system design. The minimal system used an EPLD to perform the interrupt request (IRQ681\*) and the interrupt acknowledge (IACK681\*) logic. Also, EPLDs were used to implement the circuit logic required for the generation of the data transfer acknowledge (DTACK) and the bus error (BERR) signals and for address decoding. In order to program the EPLDs, Abel software was used to compile the source code representation of the logic to be implemented with the EPLD. Once all of the source code for the EPLDs had been written, compiled and software tested, the EPLDs were programmed.

On the Data I/O System 29, once the EPLD is programmed, the test vectors are again tested against the programmed EPLD. During this test run, the System 29 failed for every EPLD that was programmed, even though they passed the software tests. On the advice of an applications engineer at Data I/O Corporation, the test vectors were removed from the source code. This code was compiled, then the EPLDs were programmed. The EPLDs were bread-boarded, while determining with reasonable certainty that the devices were actually implementing the desired logic.

The ultimate goal in this thesis was to implement the master circuit board subsystem design. One of the steps to achieve this goal requires the memory management unit (MMU) to translate a virtual address to a physical address. To avoid significant wiring

modifications to the minimal system to build up to the master subsystem, the MMU was wire-wrapped into the minimal system design. However, the MMU was not programmed at the minimal system stage. The MMU translates a virtual address to the same physical address when the MMU is not programmed after being reset. The MMU was configured to accommodate an automatic, manual and programmed (CPU reset instruction) reset.

## VI. SUMMARY AND CONCLUSIONS

### A. SUMMARY

The goal of this thesis was two-fold: first, to explore hardware ramifications of designing a microprocessor system for a multi-processor environment; and secondly, to implement the minimal system design.

#### 1. Design Concepts

In exploring hardware ramifications, the scope was limited to features of the VMEbus structure, in memory-management and interrupt control. The memory-management features included memory protection, dual-ported memory and virtual-memory.

##### a. VMEbus Structure

The VMEbus permits an exchange of data and control beyond the boundaries of a single circuit board. Other subsystems or circuit boards which may include processing elements, memory and/or input/output (I/O) devices can be integrated to the VMEbus. A strict adherence to data transfer protocols over the VMEbus ensures the reliability and integrity of the system. The ability to integrate various subsystems along the VMEbus supports a multi-processor environment.

##### b. Memory-Management

The Motorola MC68010 central processor unit (CPU) generates function codes which can be used by the memory management unit (MMU) to partition memory into supervisor and user portions.

An operating system would manage memory partitioning. Normally, systems are designed so that the supervisor memory portion contains the memory-mapped I/O devices and the read-only memory (ROM) and some random access memory (RAM). The ROM is mapped to the supervisor portion of memory since it provides the exception vector table and start-up program.

The function codes reflect the CPU's two modes of operation, the supervisor and user. The supervisor mode is a privileged mode which permits access to all instructions and the full range of memory (supervisor and user memory). The user mode permits access to only user instructions and the user memory. Typically, in the user mode, permission must be granted through the operating system to use system resources. The separation of supervisor memory from user memory prevents the user from tampering with the system assets or gaining supervisor privileges.

Dual-ported memory permits two separate sources to access the same memory block and provides the refresh signals for the dynamic random access memory (DRAM). Dual-ported memory permits RAM to be used as a shared asset. It is especially useful when a portion of the physical RAM is dedicated to passing parameters between microprocessor subsystems. Dedicating a portion of RAM for parameters is analogous to a mailbox delivery system. The mail courier (subsystem 1) delivers mail (parameters) to the mailbox (RAM). The addressee (subsystem 2) picks up the mail (parameters) and responds as required. If appropriate, the occupant (subsystem 2) places mail (parameters) in the mailbox

(RAM) to be delivered (to subsystem 1). These parameters can be used in managing a multi-processor operating system.

A MC68010-based system typically has memory-mapped I/O devices, RAM and ROM. DRAM is added the master circuit board subsystem to supplement the minimal system's static random access memory (SRAM). The MC68010 CPU has a virtual address range of 16 megabytes. However, the physical RAM's size is usually considerably less than the size of the virtual address space. Virtual-memory is used to extend the range of programming beyond the range of physical RAM. An MMU is used to map virtual addresses into RAM physical addresses. Also, the MMU detects an attempt by the CPU to access a virtual-memory address which is not currently present in physical memory. When such an attempt is detected, the MMU generates a page fault. This page fault causes the page fault exception routine to be invoked. The exception routine reads a page of information from secondary storage into RAM. The MMU maps the virtual addresses associated with the page into addresses in the physical RAM. After completion of the exception routine, program execution resumes with the completion of the instruction that caused the page fault.

#### c. Interrupt Control

Using interrupts results in more effective use of the microprocessor because the microprocessor is not kept waiting for a device to respond. The devices requesting interrupts in this thesis are programmed to provide an interrupt vector number during an interrupt acknowledge cycle for local interrupts. The interrupt

vector number causes the address of the exception routine to be obtained from the exception vector table by the CPU so that it can be executed.

## **2. Design Implementation**

### **a. Hardware Configurations**

The recommended wiring configurations that accompanied the product specifications for the MMU, VMEbus controller, dual universal asynchronous receiver/transmitter (DUART), dual-port DRAM controller, interrupt handler hardware and bus arbitration module (BAM) greatly assisted in the designs of the minimal system, system controller subsystem and master circuit board subsystem. However, in order to integrate these components into a system, care was taken to ensure that the control signals were interfaced properly. Since no computer-aided design (CAD) tools existed at the Naval Postgraduate School (NPS) to fully simulate even the minimal system design, prototyping the minimal system was necessary. The minimal system has a foundation of core resources. The intent was to prove the system design by building up a master circuit board subsystem from the minimal system.

The system controller subsystem provides a bus arbiter, interrupt acknowledge (IACK\*) daisy chain driver and system-wide reset. The bus arbiter determines bus ownership between subsystems that make bus requests and it grants bus ownership to the subsystem with the highest priority. An IACK\* daisy chain driver sends the IACK\* signal on to the bus during an interrupt acknowledge cycle.

The system reset is used to reset all devices on all subsystems after a system failure.

The master circuit board subsystem accommodates the VMEbus structure, virtual-memory-mapping facilities, a protected memory scheme, dual-ported memory and interrupt handling hardware. The master circuit board subsystem design is an extension of the minimal system and should not be implemented until the minimal system is operational. In the master circuit board subsystem, the VMEbus controller provides the necessary logic to meet the VMEbus specification for setting up the baseline bus structure. Drivers and transceivers are incorporated to meet the specified signal drive capability and isolation requirements.

b. Erasable Programmable Logic Devices

The erasable programmable logic device (EPLD) used in the minimal system's address decoding must be modified to include the additional memory-mapped devices of the master circuit board subsystem. The EPLD used for interrupt handling in the minimal system is replaced by the interrupt handler hardware in the master circuit board subsystem design.

The master circuit board subsystem design is an upgraded version of the minimal system. A pin-out list for all wiring connections was developed in order to reduce wire-wrap errors, but it is not included as part of this thesis. The small scale integrated circuit (SSI) logic shown for the generation of the data transfer acknowledge (DTACK), bus error (BERR), physical upper data strobe (PUDS\*), physical lower data strobe (PLDS\*) and

physical address strobe (PAS\*) signals was actually implemented with EPLDs to reduce the chip count.

## B. CONCLUSIONS

Meeting all the goals set in this thesis made this thesis an ambitious undertaking. The major integrated circuit (IC) chips included the CPU, DUART, interrupt handler hardware, dual-port DRAM controller, MMU, VMEbus controller and BAM. These IC chips required an extensive study of product specification and application notes to understand the wiring configurations and programming of the devices. Study of the specification notes invoked support ideas in the design that required further investigation. These support ideas included DRAM memory refresh accommodations, driver characteristics, noise reduction and virtual-memory. Once each device was reasonably understood, the problem of integrating the devices into a single system remained. Care was exercised to ensure that control signals were properly integrated to the devices. Consequently, a major portion of this thesis was spent in the research and design process without the assistance of CAD tools.

The design and implementation work of this thesis spanned almost two years. A major problem encountered was the inability to simulate the system designs. Hence, the system's validity could only be verified by actual design implementation.

The design phase took a considerable length of time because the inter-relationships between the devices to support a multi-processor environment, dual-port memory, virtual-memory, memory

protection, dual serial ports and interrupt control features were not trivial. Some of these features should have been eliminated so that a simpler design could have been implemented. However, using the approach of building a complex subsystem from a minimal system is an important technique. For a growing number of new application IC chips, facilities to simulate designs using these chips do not yet exist. Thus, there is a strong need for advanced design tools and engineering practices to support complex designs.

An important restriction of the master circuit board subsystem design is the lack of an operating system. The capability provided in this thesis could not be fully utilized without an operating system and a mass storage device, such as a hard disk. Managing the virtual-memory and protected memory requirements would require a tremendous amount of code which is beyond the scope of this thesis. However, while designing the master circuit board subsystem, foresight was exercised to consider the requirements of an operating system. This confirms the need for a dialogue between system designers and operating system designers to communicate the system requirements.

## **APPENDIX A: MC68010 16-BIT MICROPROCESSOR**

Since the entire hardware system design revolves about the MC68010 microprocessor, a description of the microprocessor, its external signals and its programming is appropriate.

### **A. MC68010 DESCRIPTION**

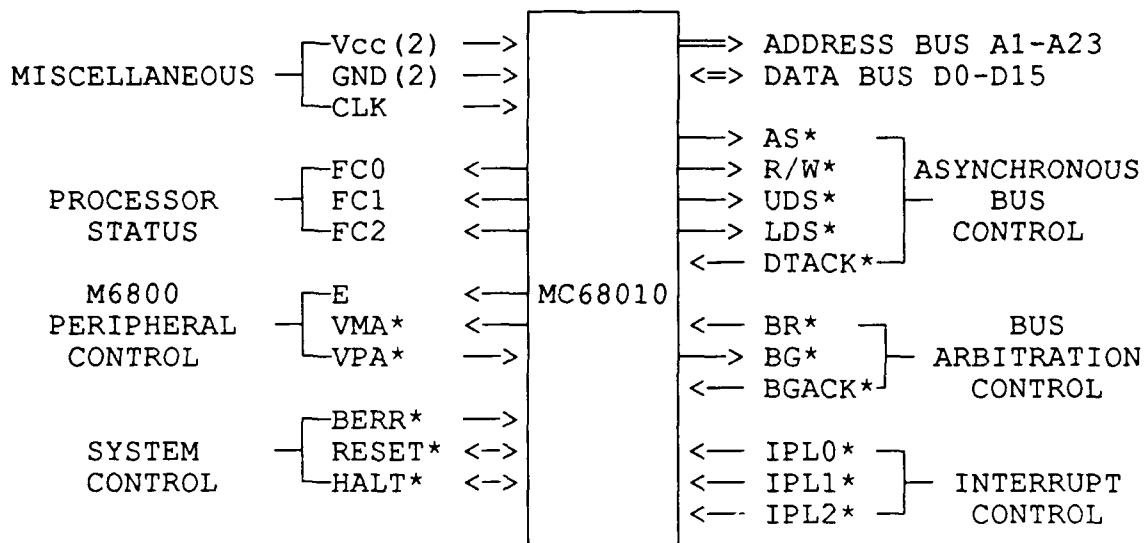
The MC68010 has seventeen 32-bit general purpose registers, a 16 megabyte address space, virtual-memory/machine support, 57 instructions with 14 addressing modes using five main data types and memory-mapped input/output (I/O) [Ref. 7:p. 1-1]. Motorola provides a complete signal description and timing analysis of the MC68010 microprocessor [Ref. 18].

### **B. MC68010 SIGNALS**

The MC68010 central processing unit (CPU) comes in a 64-pin package. As shown in Figure A.1, the signals are organized into groups and the direction of the signal flow is denoted by the arrows. To avoid any confusion over logic assertion levels, the asterisk ( \* ) at the end of a signal name is used to denote an active low assertion level.

#### **1. Address Bus**

The address bus consists of 23 address lines giving an eight megaword address range for the CPU.



**Figure A.1: MC68010 Signal Groups**

## 2. Data Bus

The data bus is a 16-bit bi-directional bus used for transferring byte or word length data.

## 3. Asynchronous Bus Control

The asynchronous bus control group provides information about the data that is being transferred. The address strobe (AS\*) signal signifies that valid address signals are being gated from the CPU. The read/write (R/W\*) line denotes that the CPU is reading from a device (active high) or that the CPU is writing to the device (active low). The upper data strobe (UDS\*) indicates that the data being transferred is on an even byte boundary. The lower data strobe (LDS\*) indicates that the data being transferred is on an odd byte boundary. When UDS\* and LDS\* are both asserted, a word (16-bits) of data is being transferred. The UDS\* and LDS\*

signals together determine address bit A0, thus giving an address range of 16 megabytes for the CPU. The UDS\*, LDS\* and R/W\* signals control the flow of the data on the data bus as illustrated in Table III [Ref. 18:p. 4-2]. Finally, the data transfer acknowledge (DTACK\*) signal informs the CPU that the current data transfer has been completed by the peripheral device or memory location addressed.

**TABLE III: DATA STROBE CONTROL OF THE DATA BUS**

UDS*	LDS*	R/W*	D8 - D15	D0 - D7
1	1	1 or 0	NO VALID DATA BITS	NO VALID DATA BITS
0	0	1	VALID DATA BITS	VALID DATA BITS
1	0	1	NO VALID DATA BITS	VALID DATA BITS
0	1	1	VALID DATA BITS	NO VALID DATA BITS
0	0	0	VALID DATA BITS	VALID DATA BITS
1	0	0	#VALID DATA BITS 0-7	VALID DATA BITS
0	1	0	VALID DATA BITS	#VALID DATA BITS 8-15

# These conditions are a result of current implementation and may not appear on future devices.

#### **4. Bus Arbitration Control**

As a group, the bus arbitration control signals provide a mechanism for the CPU to give up control of the bus. However, these signals do not determine (directly) which alternate bus master gets control. The bus request (BR\*) signal is a signal generated by a device or devices requesting access to the bus. The bus grant (BG\*) is a signal from the CPU indicating that it will release the bus at the end of the current bus cycle. The bus

grant acknowledge (BGACK\*) is a signal asserted by an alternate bus master while it has control of the bus.

### **5. Interrupt Control**

The interrupt priority levels (IPL0\* through IPL2\*) are signals which represent the encoded priority level for the highest priority device desiring interrupt service. The signal IPL0\* is the least significant bit and the signal IPL2\* is the most significant bit of the group. A level zero interrupt (all signals are asserted high) indicates there is no interrupt request pending. A level seven interrupt (all IPLx\* signals are asserted low) has the highest priority and is non-maskable. This implies that level seven is not an ordinary interrupt level for requesting routine interrupt service. Rather, a level seven interrupt should be reserved for catastrophic events such as alternating current (AC) power failure where the non-maskable property is essential.

### **6. System Control**

The system control group is used to reset the CPU and to indicate to the CPU that a bus error has occurred. It is also used to reset peripheral devices and to generate a bus error exception. The halt signal (HALT\*), active low, is a bi-directional signal. As an input, it is used to stop the CPU at the completion of the current bus cycle. As an output, HALT\* is asserted only when a double bus error or address error exception has caused the MC68010 to enter a halt state.

The reset signal (RESET\*), active low, is also a bi-directional signal. It can be used as an input to reset the

internal microcircuitry within the CPU. When a reset instruction is executed by the CPU, it can be used to reset system devices.

Typically, a maximum time is allotted for data transfer. If the data transfer is not completed within the allotted time, bus error (BERR\*) is asserted by a time out circuit called a watchdog timer. Often, the BERR\* signal is used to inform the CPU that the current address on the address bus is invalid because no physical memory or peripheral device is mapped at that address. The BERR\* signal can also be used to flag the condition that the CPU is making an attempt to write to read-only memory (ROM). In a virtual-memory system, BERR\* is asserted by the memory management unit (MMU) when a page fault occurs.

## **7. M6800 Peripheral Control**

The M6800 peripheral control group is a group of signals which are used to interface the MC68010's 16-bit asynchronous data bus to synchronous peripheral devices in the Motorola M6800 eight-bit family.

The enable (E) signal which acts as the 6800 phase two clock is used to synchronize data transfer between the MC68010 CPU and M6800 peripheral device. The E signal's period is ten clock periods of the MC68010's clock input. The valid peripheral address (VPA\*) signal denotes to the CPU that the device selected is a M6800 peripheral device. The VPA\* signal indicates to the CPU that it should initiate a data transfer synchronized with the E signal. The valid memory address (VMA\*) signal from the CPU indicates to a

M6800 device that there is a valid address on the address bus and that the MC68010 is synchronized with the E signal.

## 8. Processor Status

The MC68010 has three function code lines (FC0 through FC2) which delineate the current processor state (user or supervisor) and the address space (program or data) being accessed as defined by Table IV [Ref. 18:p. 5-3]. The address strobe (AS\*) signal from the CPU indicates that a valid address and function code are available from the CPU.

TABLE IV: STATE AND ADDRESS SPACE

FUNCTION CODE OUTPUT			ADDRESS SPACE
FC2	FC1	FC0	
0	0	0	UNDEFINED, RESERVED FOR FUTURE USE
0	0	1	USER DATA SPACE
0	1	0	USER PROGRAM SPACE
0	1	1	UNDEFINED, RESERVED FOR FUTURE USE
1	0	0	UNDEFINED, RESERVED FOR FUTURE USE
1	0	1	SUPERVISOR DATA SPACE
1	1	0	SUPERVISOR PROGRAM SPACE
1	1	1	CPU SPACE (INTERRUPT ACKNOWLEDGE)

## 9. Miscellaneous

Both Vcc pins and both GND pins must be connected in order to power the CPU. The clock (CLK) input signal is used to develop all the synchronizing signals required within the CPU.

## C. PROGRAMMING

Motorola provides programming information in its reference manual [Ref. 7]. The MC68010's instruction set includes the following operations:

- |                      |   |
|----------------------|---|
| - Data Movement      | - Bit Manipulation                      |
| - Integer Arithmetic | - Binary Coded Decimal (BCD) Arithmetic |
| - Logical            | - Program Control                       |
| - Shift and Rotate   | - System Control                        |
| - Bit Manipulation   | - Multi-processor Communications        |

supporting the following data types:

- Bit
- BCD (Four-bits)
- Byte (Eight-bits)
- Word (16-bits)
- Long Word (32-bits)

Fourteen addressing modes that are available to the assembly language programmer. The addressing modes available include:

- Data Register Direct
- Address Register Direct
- Address Register Indirect
- Address Register Indirect with Postincrement
- Address Register Indirect with Predecrement
- Address Register Indirect with Offset
- Address Register Indirect with Index and Offset
- Absolute Short
- Absolute Long
- Program Counter with Offset
- Program Counter with Index and Offset
- Immediate Data
- Quick Immediate
- Implied Register

The following assets are available:

- Eight Data Registers
  - Seven Address Registers
  - User Stack Pointer (User Mode)
  - Supervisor Stack Pointer (Supervisor Mode)
  - Program Counter
  - \*Status Register (Supervisor mode)
  - Vector Base Register (Supervisor Mode)
  - Alternate Function Code Registers (Supervisor Mode)
- \* The condition code register is the lower byte of the status register and it is accessible in the user mode.

To support virtual-memory, the MC68010 microprocessor allows an interrupted bus cycle to be re-run after a bus error exception. The return from exception (RTE) instruction uses the format field of the exception stack to determine whether the exception was caused by bus or address error. After a bus or address error caused the exception, the CPU continues the interrupted instruction after completion of the exception routine. [Ref. 19]

## **APPENDIX B: MINIMAL SYSTEM EXCEPTION VECTOR TABLE AND MONITOR/DEBUGGER PROGRAM**

This appendix contains the source listings of the exception vector table and monitor/debugger program. The separate file names are as follows:

- VECTABLE.ASM
- MAIN.ASM
- MESSAGE.ASM
- CONSOLE.ASM
- GETSTRIN.ASM
- GET\_ADDR.ASM
- IO\_UTIL.ASM
- DECODER.ASM
- BYTEOUT.ASM
- MEM\_LIST.ASM
- HEXCONV.ASM
- GO.ASM
- STUB.ASM
- REG.ASM
- REGCHANG.ASM
- DOWNLOAD.ASM
- UNUSED.ASM

Using the 2500AD 68010 cross assembler and linker, a Motorola S-record format file was generated as a load module. The load module was loaded as a ASCII file into a Data I/O System 29 Universal Programmer. Once resident in the programmer, the load module was programmed to erasable programmable read-only memory (EPROM). It should be noted that the data section as contained in MAIN.ASM was not programmed on EPROM, but rather it resides in random access memory (RAM).

The first two entries in the exception vector table are used during the system boot up to provide the initial contents for the stack pointer and the program counter. The exception vector table contains the addresses of exception routines. The monitor/debugger

program initializes the MC68681 peripheral device and provides facilities for performing software debugging and the down-loading of files from an IBM XT/AT compatible computer.

```
*****
*          EXCEPTION VECTOR TABLE
*****
* WRITTEN BY LARRY ABBOTT JUNE 5, 1987
*****
* FILENAME: VECTABLE.ASM
*****
* VERSION 1.3
* REV DATE      NAME           DESCRIPTION
* A 29 SEPT 87  DAVID M. SENDEK ADDITIONAL DOCUMENTATION
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES:
*   BKPT      - GO.ASM
*   INIT      - MAIN.ASM
*   INIT_SP    - MAIN.ASM
*   MESSAGE    - MESSAGE.ASM
*   MONITOR    - MAIN.ASM
*   UNUSED     - UNUSED.ASM
*****
```

EXTERNAL BKPT, INIT, INIT\_SP, MESSAGE, MONITOR  
 EXTERNAL UNUSED

ORG 0	VECTOR TABLE STARTS AT ABSOLUTE ADDRESS \$000000	
LONG	INIT_SP	INITIAL STACK POINTER VECTOR
LONG	INIT	INITIAL PROGRAM COUNTER (PC)
		;
		VECTOR
LONG	UNUSED	BUS ERROR VECTOR
LONG	UNUSED	ADDRESS ERROR VECTOR
LONG	UNUSED	ILLEGAL INSTRUCTION VECTOR
LONG	UNUSED	ZERO DIVIDE VECTOR
LONG	UNUSED	CHK INSTRUCTION VECTOR
LONG	UNUSED	TRAPV INSTRUCTION VECTOR
LONG	UNUSED	PRIVILEGE VIOLATION VECTOR
LONG	UNUSED	TRACE VECTOR
LONG	UNUSED	LINE 1010 EMULATION VECTOR
LONG	UNUSED	LINE 1111 EMULATION VECTOR
ORG \$38		NOTE: VECTOR NUMBERS 12 AND 13
		;
		ARE UNASSIGNED, RESERVED
LONG	UNUSED	FORMAT ERROR VECTOR
LONG	UNUSED	UNINITIALIZED INTERRUPT VECTOR
ORG \$60		NOTE: VECTOR NUMBERS 16-23 ARE
		;
		UNASSIGNED, RESERVED
LONG	UNUSED	SPURIOUS INTERRUPT VECTOR
LONG	UNUSED	LEVEL 1 AUTOVECTOR VECTOR
LONG	UNUSED	LEVEL 2 AUTOVECTOR VECTOR
LONG	UNUSED	LEVEL 3 AUTOVECTOR VECTOR
LONG	UNUSED	LEVEL 4 AUTOVECTOR VECTOR
LONG	UNUSED	LEVEL 5 AUTOVECTOR VECTOR
LONG	UNUSED	LEVEL 6 AUTOVECTOR VECTOR
LONG	UNUSED	LEVEL 7 AUTOVECTOR VECTOR

LONG	BKPT	TRAP 0 VECTOR USED AS ; MONITOR BRKPT
LONG	UNUSED	TRAP 1 VECTOR
LONG	UNUSED	TRAP 2 VECTOR
LONG	UNUSED	TRAP 3 VECTOR
LONG	UNUSED	TRAP 4 VECTOR
LONG	UNUSED	TRAP 5 VECTOR
LONG	UNUSED	TRAP 6 VECTOR
LONG	UNUSED	TRAP 7 VECTOR
ORG \$100		NOTE: VECTOR NUMBERS 48-63 ARE ; UNASSIGNED, RESERVED
LONG	MONITOR	USER INTERRUPT 0 VECTOR ; DEFINED FOR MONITOR
LONG	UNUSED	USER INTERRUPT 1 VECTOR
LONG	UNUSED	USER INTERRUPT 2 VECTOR
LONG	UNUSED	USER INTERRUPT 3 VECTOR
LONG	UNUSED	USER INTERRUPT 4 VECTOR
LONG	UNUSED	USER INTERRUPT 5 VECTOR
LONG	UNUSED	USER INTERRUPT 6 VECTOR
LONG	UNUSED	USER INTERRUPT 7 VECTOR
LONG	UNUSED	USER INTERRUPT 8 VECTOR
LONG	UNUSED	USER INTERRUPT 9 VECTOR
LONG	UNUSED	USER INTERRUPT 10 VECTOR
LONG	UNUSED	USER INTERRUPT 11 VECTOR
LONG	UNUSED	USER INTERRUPT 12 VECTOR
LONG	UNUSED	USER INTERRUPT 13 VECTOR
LONG	UNUSED	USER INTERRUPT 14 VECTOR
LONG	UNUSED	USER INTERRUPT 15 VECTOR
LONG	UNUSED	USER INTERRUPT 16 VECTOR
LONG	UNUSED	USER INTERRUPT 17 VECTOR
LONG	UNUSED	USER INTERRUPT 18 VECTOR
LONG	UNUSED	USER INTERRUPT 19 VECTOR
LONG	UNUSED	USER INTERRUPT 20 VECTOR
LONG	UNUSED	USER INTERRUPT 21 VECTOR
LONG	UNUSED	USER INTERRUPT 22 VECTOR
LONG	UNUSED	USER INTERRUPT 23 VECTOR
LONG	UNUSED	USER INTERRUPT 24 VECTOR
LONG	UNUSED	USER INTERRUPT 25 VECTOR
LONG	UNUSED	USER INTERRUPT 26 VECTOR
LONG	UNUSED	USER INTERRUPT 27 VECTOR
LONG	UNUSED	USER INTERRUPT 28 VECTOR
LONG	UNUSED	USER INTERRUPT 29 VECTOR
LONG	UNUSED	USER INTERRUPT 30 VECTOR
LONG	UNUSED	USER INTERRUPT 31 VECTOR
LONG	UNUSED	USER INTERRUPT 32 VECTOR
LONG	UNUSED	USER INTERRUPT 33 VECTOR
LONG	UNUSED	USER INTERRUPT 34 VECTOR
LONG	UNUSED	USER INTERRUPT 35 VECTOR
LONG	UNUSED	USER INTERRUPT 36 VECTOR
LONG	UNUSED	USER INTERRUPT 37 VECTOR
LONG	UNUSED	USER INTERRUPT 38 VECTOR
LONG	UNUSED	USER INTERRUPT 39 VECTOR



LONG	UNUSED	USER	INTERRUPT	92	VECTOR
LONG	UNUSED	USER	INTERRUPT	93	VECTOR
LONG	UNUSED	USER	INTERRUPT	94	VECTOR
LONG	UNUSED	USER	INTERRUPT	95	VECTOR
LONG	UNUSED	USER	INTERRUPT	96	VECTOR
LONG	UNUSED	USER	INTERRUPT	97	VECTOR
LONG	UNUSED	USER	INTERRUPT	98	VECTOR
LONG	UNUSED	USER	INTERRUPT	99	VECTOR
LONG	UNUSED	USER	INTERRUPT	100	VECTOR
LONG	UNUSED	USER	INTERRUPT	101	VECTOR
LONG	UNUSED	USER	INTERRUPT	102	VECTOR
LONG	UNUSED	USER	INTERRUPT	103	VECTOR
LONG	UNUSED	USER	INTERRUPT	104	VECTOR
LONG	UNUSED	USER	INTERRUPT	105	VECTOR
LONG	UNUSED	USER	INTERRUPT	106	VECTOR
LONG	UNUSED	USER	INTERRUPT	107	VECTOR
LONG	UNUSED	USER	INTERRUPT	108	VECTOR
LONG	UNUSED	USER	INTERRUPT	109	VECTOR
LONG	UNUSED	USER	INTERRUPT	110	VECTOR
LONG	UNUSED	USER	INTERRUPT	111	VECTOR
LONG	UNUSED	USER	INTERRUPT	112	VECTOR
LONG	UNUSED	USER	INTERRUPT	113	VECTOR
LONG	UNUSED	USER	INTERRUPT	114	VECTOR
LONG	UNUSED	USER	INTERRUPT	115	VECTOR
LONG	UNUSED	USER	INTERRUPT	116	VECTOR
LONG	UNUSED	USER	INTERRUPT	117	VECTOR
LONG	UNUSED	USER	INTERRUPT	118	VECTOR
LONG	UNUSED	USER	INTERRUPT	119	VECTOR
LONG	UNUSED	USER	INTERRUPT	120	VECTOR
LONG	UNUSED	USER	INTERRUPT	121	VECTOR
LONG	UNUSED	USER	INTERRUPT	122	VECTOR
LONG	UNUSED	USER	INTERRUPT	123	VECTOR
LONG	UNUSED	USER	INTERRUPT	124	VECTOR
LONG	UNUSED	USER	INTERRUPT	125	VECTOR
LONG	UNUSED	USER	INTERRUPT	126	VECTOR
LONG	UNUSED	USER	INTERRUPT	127	VECTOR
LONG	UNUSED	USER	INTERRUPT	128	VECTOR
LONG	UNUSED	USER	INTERRUPT	129	VECTOR
LONG	UNUSED	USER	INTERRUPT	130	VECTOR
LONG	UNUSED	USER	INTERRUPT	131	VECTOR
LONG	UNUSED	USER	INTERRUPT	132	VECTOR
LONG	UNUSED	USER	INTERRUPT	133	VECTOR
LONG	UNUSED	USER	INTERRUPT	134	VECTOR
LONG	UNUSED	USER	INTERRUPT	135	VECTOR
LONG	UNUSED	USER	INTERRUPT	136	VECTOR
LONG	UNUSED	USER	INTERRUPT	137	VECTOR
LONG	UNUSED	USER	INTERRUPT	138	VECTOR
LONG	UNUSED	USER	INTERRUPT	139	VECTOR
LONG	UNUSED	USER	INTERRUPT	140	VECTOR
LONG	UNUSED	USER	INTERRUPT	141	VECTOR
LONG	UNUSED	USER	INTERRUPT	142	VECTOR
LONG	UNUSED	USER	INTERRUPT	143	VECTOR

LONG	UNUSED	USER	INTERRUPT	144	VECTOR
LONG	UNUSED	USER	INTERRUPT	145	VECTOR
LONG	UNUSED	USER	INTERRUPT	146	VECTOR
LONG	UNUSED	USER	INTERRUPT	147	VECTOR
LONG	UNUSED	USER	INTERRUPT	148	VECTOR
LONG	UNUSED	USER	INTERRUPT	149	VECTOR
LONG	UNUSED	USER	INTERRUPT	150	VECTOR
LONG	UNUSED	USER	INTERRUPT	151	VECTOR
LONG	UNUSED	USER	INTERRUPT	152	VECTOR
LONG	UNUSED	USER	INTERRUPT	153	VECTOR
LONG	UNUSED	USER	INTERRUPT	154	VECTOR
LONG	UNUSED	USER	INTERRUPT	155	VECTOR
LONG	UNUSED	USER	INTERRUPT	156	VECTOR
LONG	UNUSED	USER	INTERRUPT	157	VECTOR
LONG	UNUSED	USER	INTERRUPT	158	VECTOR
LONG	UNUSED	USER	INTERRUPT	159	VECTOR
LONG	UNUSED	USER	INTERRUPT	160	VECTOR
LONG	UNUSED	USER	INTERRUPT	161	VECTOR
LONG	UNUSED	USER	INTERRUPT	162	VECTOR
LONG	UNUSED	USER	INTERRUPT	163	VECTOR
LONG	UNUSED	USER	INTERRUPT	164	VECTOR
LONG	UNUSED	USER	INTERRUPT	165	VECTOR
LONG	UNUSED	USER	INTERRUPT	166	VECTOR
LONG	UNUSED	USER	INTERRUPT	167	VECTOR
LONG	UNUSED	USER	INTERRUPT	168	VECTOR
LONG	UNUSED	USER	INTERRUPT	169	VECTOR
LONG	UNUSED	USER	INTERRUPT	170	VECTOR
LONG	UNUSED	USER	INTERRUPT	171	VECTOR
LONG	UNUSED	USER	INTERRUPT	172	VECTOR
LONG	UNUSED	USER	INTERRUPT	173	VECTOR
LONG	UNUSED	USER	INTERRUPT	174	VECTOR
LONG	UNUSED	USER	INTERRUPT	175	VECTOR
LONG	UNUSED	USER	INTERRUPT	176	VECTOR
LONG	UNUSED	USER	INTERRUPT	177	VECTOR
LONG	UNUSED	USER	INTERRUPT	178	VECTOR
LONG	UNUSED	USER	INTERRUPT	179	VECTOR
LONG	UNUSED	USER	INTERRUPT	180	VECTOR
LONG	UNUSED	USER	INTERRUPT	181	VECTOR
LONG	UNUSED	USER	INTERRUPT	182	VECTOR
LONG	UNUSED	USER	INTERRUPT	183	VECTOR
LONG	UNUSED	USER	INTERRUPT	184	VECTOR
LONG	UNUSED	USER	INTERRUPT	185	VECTOR
LONG	UNUSED	USER	INTERRUPT	186	VECTOR
LONG	UNUSED	USER	INTERRUPT	187	VECTOR
LONG	UNUSED	USER	INTERRUPT	188	VECTOR
LONG	UNUSED	USER	INTERRUPT	189	VECTOR
LONG	UNUSED	USER	INTERRUPT	190	VECTOR
LONG	UNUSED	USER	INTERRUPT	191	VECTOR
END					

```
*****
*      MAIN IS THE ENTRY POINT INTO THE MONITOR. MAIN          *
*      INITIALIZES THE RS-232 PORT BEFORE ENTERING THE        *
*      MONITOR. ALSO, MAIN CONTAINS THE MEMORY MAPS,          *
*      EQUATES AND MEMORY ALLOCATIONS.                      *
*****
*      68K MONITOR VERSION V1.3 - AN ACCUMULATION OF ALL      *
*      PRIOR VERSIONS                                         *
*      COPYRIGHT @ AUG. 1986 BY DR. LARRY ABBOTT             *
*****
*      FILENAME: MAIN.ASM                                     *
*****
*      VERSION 1.3                                           *
*      REV. MODIFIED BY          DATE      DESCRIPTION       *
*      A      LARRY ABBOTT    11/7/86   *
*      B      LARRY ABBOTT    12/14/86  MONSTAT-ESCAPE     *
*      C      LARRY ABBOTT    6/6/87    ADAPT TO MC68681    *
*      D      DAVID M. SENDEK 29 SEPT 87  -INCLUDE VECTOR TABLE *
*                                         -INCLUDE MONITOR PROMPT   *
*                                         -CORRECT FOR 68681        *
*****
*      DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES:   *
*      CMD_DECODE - DECODER.ASM                            *
*      GETSTRING - GETSTRIN.ASM                           *
*      MESSAGE   - MESSAGE.ASM                            *
*      MONMSG    - MESSAGE.ASM                            *
*      SCRLF     - IO_UTIL.ASM                           *
*****
```

```
GLOBAL      BKPTAB, BS, BTLEN, BUFFIN, CHECKSUM, CK_SUM
GLOBAL      CONTINUE, CR
GLOBAL      END_ADDRESS, EPROMRNG, EPROMWR, ESC, ESCAPE
GLOBAL      FOUND, FWDARW, HEX_ERR, LF, MODIFY, MONSTAT,
GLOBAL      NULL, PORT1, PORT2, RBA, RECFULL
GLOBAL      SPACE, SRA, SRAM, SRAMSIZE, STRING, STRINGEND
GLOBAL      SYSTAX, SRB, TBA, TBB, RBB
GLOBAL      TBA, XEMPTY
GLOBAL      INIT_SP, INIT_MONITOR
EXTERNAL    CMD_DECODE, GETSTRING, MESSAGE, MONMSG, SCRLF
EXTERNAL    PROMPT
*
```

```
*      DATA      ALL R/W DATA IS STORED IN SRAM AT ADDRESS
*                  $010000
*
```

```
*      EQUATES
*
```

BS	EQU	\$08	ASCII CODE FOR <-- (BACKSPACE)
CR	EQU	\$0D	ASCII CODE FOR RET'RN
EPROMRNG	EQU	\$3FF	EPROM RNG 0 -> \$3FF (EXCEPTION TBL)
ESC	EQU	\$1B	ASCII CODE FOR ESCAPE
FWDARW	EQU	\$3E	ASCII CODE FOR '>' (FORWARD ARROW)
LF	EQU	\$0A	ASCII CODE FOR LINEFEED

```

NULL      EQU      $00      ASCII CODE FOR NUL
SPACE     EQU      $20      ASCII CODE FOR SPACE
BTLEN     EQU      $10      BREAKPOINT TABLE LENGTH IN WORDS
*
*      MEMORY ALLOCATIONS
*
BKPTAB    BLKW 3/2*BTLEN RESERVE BTLEN/2 32-BIT BKPT's
BUFFIN    BLKB $3F      RESERVE 63 BYTE INPUT BUFFER
END_ADDRESS BLKW 2      RESERVE WORD FOR END ADDRESS
MONSTAT   BLKW 1      RESERVE A WORD FOR MONITOR STATUS
STAX      BLKW 36     SAVE AREA FOR APPLICATION REG'S
SYSTAX    BLKW 2      RESERVE MEMORY FOR STACK POINTER
CK_SUM    BLKW 1      CHECK SUM STORAGE
SRAM      EQU      BKPTAB DATA BEGINS AT LOW ADDR OF SRAM
SRAMSIZE  EQU      $3FFF 16K BYTES OF STATIC RAM
INIT_SP   EQU      $013FFE INITIAL STACK POINTER
*
*      DEFINITION OF MONSTAT (MONITOR STATUS WORD)
*
EPROMWR   EQU      0      WRITE TO EPROM FLAG
ESCAPE     EQU      1      ESCAPE FLAG
CONTINUE   EQU      2      CONTINUATION FLAG
FOUND      EQU      3      CMD FOUND FLAG
HEX_ERR    EQU      4      HEX CONVERSION ERROR
MODIFY    EQU      5      MEMORY MODIFY FLAG
STRING     EQU      6      STRING BUILDING IN PROGRESS
STRINGEND EQU      7      END OF STRING BUILDING
CHECKSUM   EQU      8      CHECKSUM ERROR FLAG
*
*      68681 EQUATES
*
RECFULL   EQU      $00    SRA(0)=1=>RECEIVE FIFO HAS A CHAR
XEMPTY    EQU      $02    SRA(2)=1=>XMIT HOLDING REG EMPTY
MR1RFSET  EQU      $1A    RESET MODE REG PTR & DISABLE XMIT/RECV
CLK_SRC   EQU      $30    XTAL/16 CLOCK
CONF_1AB  EQU      $13    8-BIT DATA, NO PARITY
CONF_2A   EQU      $07    1 STOP BIT
CONF_2B   EQU      $0F    2 STOP BITS
BAUD2400 EQU      $88    2400 BAUD
BAUD9600 EQU      $BB    9600 BAUD
EN_PORT   EQU      $45    RESET ERROR, ENABLE XMIT & RECV
RUPTMASK EQU      $02    ENABLE RECV READY RUPT
RUPTVECT EQU      $40    USER INTERRUPT 0 VECTOR
*
*      68681 REGISTERS
*
* CRT      <- PORT A:9600 BAUD, 8 DATA BITS,
*           NO PARITY, 1 STOP BIT
* DOWNLOAD <- PORT B:2400 BAUD, 8 DATA BITS,
*           NO PARITY, 2 STOP BITS
*

```

DUART	EQU	\$7F7000	BASE ADDRESS FOR MC68681
PORT1	EQU	DUART	PORT A
PORT2	EQU	DUART+\$10	PORT B
MR1A	EQU	1	R/W:MODE REG 1 FOR PORT A
MR2A	EQU	1	R/W:MODE REG 2 FOR PORT A
SRA	EQU	3	R :STATUS REGISTER FOR PORT A
CSRA	EQU	3	W:CLOCK SELECT REGISTER A
CRA	EQU	5	W:COMMAND REGISTER FOR PORT A
RBA	EQU	7	R :RECEIVER BUFFER FOR PORT A
TBA	EQU	7	W:TRANSMITTER BUFFER FOR PORT A
IPCR	EQU	9	R :INPUT PORT CHANGE REGISTER
ACR	EQU	9	W:AUXILIARY CONTROL REGISTER
ISR	EQU	\$B	R :INTERRUPT STATUS REG
IMR	EQU	\$B	W:INTERRUPT MASK REGISTER
CUR	EQU	\$D	R :COUNTER MODE: CURRENT CNTR MSB
CTUR	EQU	\$D	W:COUNTER/TIMER UPPER REGISTER
CLR	EQU	\$F	R :COUNTER MODE: CURRENT CNTR LSB
CTLR	EQU	\$F	W:COUNTER/TIMER LOWER REGISTER
MR1B	EQU	\$11	R/W:MODE REG 1 FOR PORT B
MR2B	EQU	\$11	R/W:MODE REG 2 FOR PORT B
SRB	EQU	\$13	R :STATUS REGISTER FOR PORT B
CSRB	EQU	\$13	W:CLOCK SELECT REGISTER B
CRB	EQU	\$15	W:COMMAND REGISTER FOR PORT B
RB	EQU	\$17	R :RECEIVER BUFFER FOR PORT B
TBB	EQU	\$17	W:TRANSMITTER BUFFER FOR PORT B
IVR	EQU	\$19	R/W:INTERRUPT VECTOR REGISTER
OPCR	EQU	\$1B	W:OUTPUT PORT CONFIGURATION REG

\*

## CODE

\*

INIT:	LEA	DUART,A4	A4 <-- PTR TO DUART
	CLR.W	MONSTAT	CLR MONITOR STATUS WORD
*	MOVE.B	#MR1RESET,CRA(A4)	RESET PORT A MR1 PTR, DISABLE XMIT & RCV
*	MOVE.B	#MR1RESET,CRB(A4)	RESET PORT B MR1 PTR, DISABLE XMIT & RCV
*	MOVE.B	#CLK_SRC,ACR(A4)	CNTR/TMR CLK FROM CRYSTAL/16
*	MOVE.B	#CONF_1AB,MR1A(A4)	PORT A:8 DATA BITS & NO PARITY
*	MOVE.B	#CONF_2A,MR2A(A4)	PORT A: 1 STOP BIT
*	MOVE.B	#BAUD9600,CSRA(A4)	PORT A: 9600 BAUD
*	MOVE.B	#CONF_1AB,MR1B(A4)	PORT B:8 DATA BITS & NO PARITY
*	MOVE.B	#CONF_2B,MR2B(A4)	PORT B: 2 STOP BITS
*	MOVE.B	#BAUD2400,CSRB(A4)	PORT B: 2400 BAUD
*	MOVE.B	#RUPTVECT,IVR(A4)	SET DUART INTERRUPT SERVICE AT USER INTERRUPT 0
*	MOVE.B	#EN_PORT,CRA(A4)	RESET ERRS & ENABLE XMIT/RCV
*	MOVE.B	#EN_PORT,CRB(A4)	RESET ERRS & ENABLE XMIT/RCV
*	MOVE.B	#RUPTMASK,IMR(A4)	RUPT WHEN PORT A RCVS CHAR

BANNER:	BSR SCRLF	MOVE CURSOR TO NEXT LINE
	LEA MONMSG,A5	SET MESSAGE POINTER TO MONMSG
	BSR MESSAGE	CRT<--68010 MONITOR V1.3
	BSR SCRLF	MOVE CURSOR TO NEXT LINE
	LEA PROMPT,A5	SET UP FOR A PROMPT TO THE CRT
	BSR MESSAGE	SEND PROMPT TO CRT
LOOP:	BRA.S LOOP	WAIT FOR AN INTERRUPT
*		
MONITOR:	MOVE.L SP,SYSTAX	SAVE PTR TO APPL REGs
	MOVEM.L A0-A7/D0-D7,-(SP)	SAVE ALL REGISTERS
	LEA STAX,A6	SET MONITOR STATE PTR
	MOVEM.L (A6)+,A0-A5/D0-D7	GET LAST MONITOR STATE
	BSR GETSTRING	ENTER MONITOR
	BCLR.B #STRINGEND,MONSTAT	CHECK FOR END OF STRING
	BEQ RESTORE	NOT THE END, SO EXIT
	BCLR.B #STRING,MONSTAT	CLEAR NEW STRING FLAG
	BSR CMD_DECODE	IF END THEN DECODE
	LEA PROMPT,A5	SET MSG PNTR TO PROMPT
	BSR MESSAGE	CRT <- '>' (CRT PROMPT)
RESTORE:	MOVEM.L A0-A5/D0-D7,-(A6)	SAVE MONITOR STATE
	MOVEM.L (SP)+,A0-A7/D0-D7	RESTORE ALL REGISTERS
	RTE	
	END	

```

*****
* THIS PROGRAM OUTPUTS MESSAGES TO THE CRT SCREEN. *
*****
* WRITTEN BY DR. LARRY ABBOTT *
*****
* FILENAME: MESSAGE.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 29 SEPT 87 -INCLUDE A MONITOR PROMPT*
* -INCLUDE BUFFER FULL *
* CONDITION *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* ECHO1 - CONSOLE.ASM *
*****
```

GLOBAL	BKPTMSG, EPROMSG, ERRMSG, HEXMSG, ILLMSG
GLOBAL	MONMSG, REGERR, REGMSG, SREC_ERR, USEMSG
GLOBAL	MESSAGE, PROMPT, BUFFULLMSG, SPCE
EXTERNAL	ECHO1

\*

CR	EQU	\$0D	ASCII CODE FOR RETURN
LF	EQU	\$0A	ASCII CODE FOR LINEFEED
NULL	EQU	\$00	ASCII CODE FOR NUL

\*

```

MESSAGE: MOVE.B (A5)+,D0 ;GET MESSAGE CHAR,
*                         INCREMENT POINTER
    BEQ.S  MSGRET      IF CHAR = NULL THEN EXIT
    BSR     ECHO1       ;OUTPUT CHAR TO CONSOLE
    BRA.S  MESSAGE      ;GET ANOTHER CHARACTER
MSGRET: RTS
;

BKPTMSG: BYTE   'BREAKPOINT TRAP AT '
            BYTE   NULL
ERRMSG:  BYTE   'ERROR RE-ENTER',CR,LF
            BYTE   NULL
EPROMSG: BYTE   'ATTEMPTED WRITE TO EPROM',CR,LF
            BYTE   NULL
HEXMSG:  BYTE   'HEX CONVERSION ERROR...RE-ENTER',CR,LF
            BYTE   NULL
ILLMSG:  BYTE   'ILLEGAL INSTRUCTION TRAP',CR,LF
            BYTE   NULL
MONMSG:  BYTE   '68010 MONITOR V1.3',CR,LF
            BYTE   'WRITTEN BY DR. LARRY ABBOTT',CR,LF
            BYTE   '@ COPYRIGHT 1986',CR,LF
            BYTE   NULL
REGERR:  BYTE   'REGISTER CONTENTS ERROR RE-ENTER',CR,LF
            BYTE   NULL
```

```
REGMSG:  BYTE      'D0='',NULL,' D1='',NULL,' D2='',NULL,' D3='',
                NULL,CR,LF
                BYTE      'D4='',NULL,' D5='',NULL,' D6='',NULL,' D7='',
                NULL,CR,LF
                BYTE      'A0='',NULL,' A1='',NULL,' A2='',NULL,' A3='',
                NULL,CR,LF
                BYTE      'A4='',NULL,' A5='',NULL,' A6='',NULL,' A7='',
                CR,LF
                BYTE      'SR='',NULL,' PC='',NULL,' (PC)='',NULL,CR,LF
                BYTE      'US='',NULL,' SS='',NULL,CR,LF
                BYTE      NULL
SREC_ERR:  BYTE      'S RECORD ERROR MESSAGE',LF,CR
                BYTE      NULL
USEMSG:   BYTE      'UNUSED EXCEPTION ENCOUNTERED',LF,CR
                BYTE      'WITH FORMAT WORD = '
                BYTE      NULL
PROMPT:   BYTE      '>'
                BYTE      NULL
SPCE:     BYTE      ' '
                BYTE      NULL
BUFFULLMSG: BYTE      LF,CR,' INPUT BUFFER IS FULL, TRY AGAIN.',LF,CR
                BYTE      NULL
                END
```

```
*****
* THIS MODULE INPUTS FROM THE KEYBOARD AND DOWNLOAD PORT,      *
* AND IT OUTPUTS CHARACTERS TO THE CRT.                      *
*****
* NEW CONSOLE WRITTEN DEC. 19, 1986 BY DR. LARRY ABBOTT      *
*****
* FILENAME: CONSOLE.ASM                                     *
*****
* VERSION 1.3                                              *
* REV. MODIFIED BY           DATE      DESCRIPTION          *
* A    LARRY ABBOTT       6/6/87    ADAPT TO 68681        *
* B    DAVID M. SENDEK 30 SEPT 87 DOCUMENTATION UPGRADE   *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES:      *
* ESCAPE    - MAIN.ASM                                     *
* MONSTAT   - MAIN.ASM                                     *
* PORT1     - MAIN.ASM                                     *
* PORT2     - MAIN.ASM                                     *
* RECFULL   - MAIN.ASM                                     *
* RBA, RBB   - MAIN.ASM                                     *
* SRA, SRB   - MAIN.ASM                                     *
* TBA, TBB   - MAIN.ASM                                     *
*****
```

```

GLOBAL      ECHO1,ECHO2
GLOBAL      GETCHAR1,GETCHR2
GLOBAL      SCANCHR2
EXTERNAL    ESCAPE,MONSTAT,PORT1,PORT2
EXTERNAL    RECFULL,RBA,SRA,TBA,TBB,SRB
EXTERNAL    XEMPTY,RBB
*
ESC        EQU      $1B          ASCII CODE FOR ESCAPE
*
GETCHAR1: LEA      PORT1,A4          POINT TO RS_232 PORT 1
          BTST.B #RECFULL,SRA(A4)  CONSOLE CHAR READY ?
          BEQ     GETCHAR1         - NO, CHECK AGAIN
          MOVE.B RBA(A4),D0        - YES, GET CHAR
          RTS
GETCHAR2: LEA      PORT2,A4          POINT TO RS-232 PORT 2
          BTST.B #RECFULL,SRB(A4)  CONSOLE CHAR READY ?
          BEQ     GETCHAR2         - NO, CHECK AGAIN
          MOVE.B RBB(A4),D0        - YES, GET CHAR
          RTS
*
*      SCANCHAR GETS A CHARACTER FROM A PORT IF IT IS THERE
*      OTHERWISE, SCANCHAR RETURNS TO THE CALLING ROUTINE
*
SCANCHR1  LEA      PORT1,A4          POINTS TO RS-232 PORT 1
          BTST.B #RECFULL,SRA(A4)  DOES PORT 1 HAVE A CHAR?
          BEQ.S  SCAN1_EX          - NO, EXIT
          MOVE.B RBA(A4),D0        - YES, GET CHAR
SCAN1_EX  RTS
```

```

SCANCHR2 LEA PORT2,A4           POINTS TO RS-232 PORT 2
          BTST.B #RECFULL,SRB(A4) DOES PORT 2 HAVE A CHAR?
          BEQ.S SCAN2_EX           - NO, EXIT
          MOVE.B RBB(A4),D0         - YES, GET CHAR
SCAN2_EX  RTS
*
* WHILE DOWNLOADING CHARACTERS FROM PORT 2, THIS PROCESS CAN BE
* HALTED BY SENDING AN ESC CHARACTER FROM THE KEYBOARD TO PORT 1
*
GETCHR2  BSR SCANCHR1           GET CHAR FROM PORT 1, IF PRESENT
          CMP.B #ESC,D0            IS THE CHAR AN ESCAPE ?
          BEQ GC2_EXIT             - YES, SO EXIT
          BSR GETCHAR2              - NO, GET DOWNLOAD CHAR
          BRA.S EXIT_GC2
GC2_EXIT BSET.B #ESCAPE,MONSTAT IF ESC CHAR, SET MONSTAT BIT
EXIT_GC2 RTS
*
ECHO2    LEA PORT2,A4           POINTS TO RS-232 PORT 2
          BTST.B #XEMPTY,SRB(A4) IS CONSOLE XMIT RDY ?
          BEQ ECHO2                - NO, CHECK AGAIN
          MOVE.B D0,TBA(A4)         - YES, OUTPUT CHAR TO PORT 1
          RTS
ECHO1    LEA PORT1,A4           POINTS TO RS-232 PORT 1
          BTST.B #XEMPTY,SRA(A4) IS CONSOLE XMIT RDY ?
          BEQ ECHO1                - NO, CHECK AGAIN
          MOVE.B D0,TBA(A4)         - YES, OUTPUT CHAR TO PORT 1
          RTS
*
END

```

```
*****
*THIS PROGRAM BUILDS THE CMD STRING INPUT FROM THE KEYBOARD.*  

*****  

* WRITTEN BY DR. LARRY ABBOTT *  

*****  

* FILENAME: GETSTRIN.ASM *  

*****  

* VERSION 1.3 *  

* REV. MODIFIED BY DATE DESCRIPTION *  

* A DAVID M. SENDEK 2 OCT 87 DOCUMENTATION UPGRADE *  

*****  

* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *  

* BS - MAIN.ASM MESSAGE - MESSAGE.ASM *  

* BUFFIN - MAIN.ASM SPCE - MESSAGE.ASM *  

* CR - MAIN.ASM *  

* CMD_DECODE - DECODER.ASM *  

* ECHO1 - CONSOLE.ASM *  

* GETCHAR1 - CONSOLE.ASM *  

* MONSTAT - MAIN.ASM *  

* STRING - MAIN.ASM *  

* STRINGEND - MAIN.ASM *  

* BUFFULLMSG - MESSAGE.ASM *  

*****
```

```
GLOBAL GETSTRING  

EXTERNAL BS,BUFFIN,CR,CMD_DECODE,ECHO1,GETCHAR1  

EXTERNAL MONSTAT,STRING,STRINGEND  

EXTERNAL BUFFULLMSG,SPCE  

EXTERNAL MESSAGE  

*  

GETSTRING:BSET.B #STRING,MONSTAT IS THIS A NEW STRING ?  

    BNE BUILD - NO, SKIP PTR INIT  

    BCLR.B #STRINGEND,MONSTAT - YES, CLR STRG END BIT  

    LEA BUFFIN+1,A0 - YES, INIT STRING PTR  

BUILD: BSR GETCHAR1 D0 <- CHR FROM CRT  

    CMP.B #CR,D0 IS CHAR A CR ?  

    BNE ADD_STRING - NO, ADD CHAR TO STRG  

    BSET.B #STRINGEND,MONSTAT - YES, SET STRG END BIT  

    MOVE.W A0,D0 - YES, D0 <- CURRENT  

                                BUFFIN PTR  

    SUB.W #BUFFIN+1,D0 - YES, CALC BUFFIN LEN  

    MOVE.B D0,BUFFIN - YES, BUFFIN(0)<-  

                                BUFFIN LENGTH  

*  

    BRA STRING_EXIT - YES, EXIT  

ADD_STRING: BSR ECHO1_ECHO CHAR TO CRT  

    BSR CONCAT ADD CHAR TO END OF STRG  

STRING_EXIT:RTS
```

```

*      CONCAT CONCATENATES THE CHAR ONTO THE END OF THE STRING
*
CONCAT:    CMP.B  #BS,D0      IS INPUT CHAR A BACKSPACE?
            BEQ    BKSPACE      - YES, GOT BACKSPACE
            CMPA.L BUFFIN+63,A0  IS BUFFIN FULL ?
            BNE    ADD_TO_STRING - NO, ADD BYTE TO STRING
            LEA    BUFFULLMSG,A5   - YES, SET UP POINTER
                           FOR MESSAGE
            BSR    MESSAGE        - YES, SEND MSG TO CRT
            BRA    CONCAT_EXIT    - YES, NOW EXIT
ADD_TO_STRING: MOVE.B D0,(A0)+  ADD BYTE TO STRING

            BRA    CONCAT_EXIT
BKSPACE:    CMPA.L BUFFIN,A0  IS BUFFIN PTR POINTING TO
*              1st BYTE ?
            BEQ    CONCAT_EXIT    - YES, EXIT
            SUBQ.W #1,A0          - NO, BACKUP BUFFIN PNTR
            LEA    SPCE,A5
            BSR    MESSAGE

CONCAT_EXIT: RTS
             END

```

```

*****
* GET_ADDRESS CONVERTS THE START AND END ADDRESS TO HEX. *
*****
* WRITTEN BY DR. LARRY ABBOTT *
*****
* FILENAME: GET_ADDR.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 30 SEPT 87 DOCUMENTATION UPGRADE *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* BUFFIN - MAIN.ASM *
* END_ADDRESS - MAIN.ASM *
* HEX_CONV - HEXCONV.ASM *
* HEX_ERR - MAIN.ASM *
* MONSTAT - MAIN.ASM *
* HEXMSG - MESSAGE.ASM *
* MESSAGE - MESSAGE.ASM *
*****
GLOBAL      GET_ADDR
EXTERNAL    BUFFIN,END_ADDRESS,HEX_CONV,HEX_ERR
EXTERNAL    MONSTAT,HEXMSG,MESSAGE
*
GET_ADDR: CLR.L D2           CLEAR HEX BUFFER
          LEA 0,A2           CLEAR START ADDRESS
          LEA 0,A3           CLEAR END ADDRESS
          CLR D3
          MOVE.B BUFFIN,D3    D3 <-- BUFFIN LENGTH
          BLE EXIT            EXIT IF NULL CMD STRING
          SUBQ.W #1,D3         ADJUST FOR DBCC INST
START_ADDR:MOVE.B (A0)+,D0    D0 <-- BUFFIN(I) &
                           I <- I + 1
                           IS CHAR IN D0 A COMMA ?
                           BEQ STORE_START   - YES, INDICATE END OF
                           START ADDRESS
                           BSR HEX_CONV        CONVERT 1 CHAR OF START
                           ADDR TO HEX
                           BTST.B #HEX_ERR,MONSTAT WAS THERE AN HEX
                           CONVERSION ERROR ?
                           BNE ADDR_ERR       - YES, EXIT ROUTINE
                           DBF D3,START_ADDR  IF MORE CHARACTERS CONT
                           STORE_START:SUBQ.W #1,D3 ADJUST LENGTH FOR COMMA
                           MOVE.L D2,A2        STORE START ADDRESS IN A2
                           CLR.L D2           CLEAR HEX BUFFER
                           *
                           * D3 CONTAINS THE LENGTH OF THE REMAINING COMMAND LINE
                           *
                           TST.W D3           IS BUFFIN LENGTH < 0 ?
                           BMI ADDREXIT      - YES, EXIT WITH END.ADDR=0

```

```
END_ADDR:MOVE.B (A0)+,D0          D0 <-- BUFFIN(I, & I <- I+1
                                BSR    HEX_CONV      CONVERT 1 CHAR OF END
*                                BTST.B #HEX_ERR,MONSTAT WAS THERE AN HEX
*                                BNE    ADDR_ERR      ADDR TO HEX
                                DBF    D3,END_ADDR   CONVERSION ERROR ?
                                MOVE.L D2,A3        - YES, EXIT ROUTINE
ADDRExit MOVE.L A3,END_ADDRESS   IF MORE CHARS CONTINUE
                                BRA    EXIT          ELSE STR END ADDR IN A3
ADDR_ERR LEA    HEXMSG,A5      SAV END ADR IN MEM
                                BSR    MESSAGE
EXIT     RTS
END
```

```
*****
* THIS PROGRAM CONTAINS A GROUP OF CONSOLE UTILITIES. *
*****
* WRITTEN BY LARRY ABBOTT JAN. 1986 *
*****
* FILENAME: IO_UTIL.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 30 SEPT 87 -DOCUMENTATION UPGRADE *
* -CORRECT FOR 68681 *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* BS - MAIN.ASM PORT1 - MAIN.ASM *
* CR - MAIN.ASM *
* ECHO1 - CONSOLE.ASM *
* ESC - CONSOLE.ASM *
* FWDARW - MAIN.ASM *
* GETCHAR1 - CONSOLE.ASM *
* LF - MAIN.ASM *
* RECFULL - MAIN.ASM *
* SRA - MAIN.ASM *
* SPACE - MAIN.ASM *
*****
```

```
GLOBAL BACKSPACES, SCROLL, SCRLF, SPACES
EXTERNAL BS, CR, ECHO1, ESC, FWDARW, GETCHAR1, LF
EXTERNAL RECFULL, SPACE
EXTERNAL SRA, PORT1
```

```
* BACKSPACES MOVES THE CURSOR ON THE CRT TO THE LEFT
* N TIMES
BACKSPACES: SUBQ.W #1,D2      ADJ INDEX FOR THE # OF BK_SP
BK_SPACE:  MOVE.B #BS,D0      D0 <- ASCII CODE FOR BACKSPACE
          BSR    ECHO1      OUTPUT BACKSPACE TO CONSOLE
          DEF    D2,BK_SPACE IF MORE BCKSP LOOP TO BK_SPACE
          RTS
*
* SCRLF SEND A CARRIAGE RETURN AND A LINEFEED
* TO THE CONSOLE
*
SCRLF:  MOVE.B #CR,D0      D0 <- ASCII CODE FOR CR
          BSR    ECHO1      OUTPUT CR TO CONSOLE
          MOVE.B #LF,D0      D0 <- ASCII CODE FOR LF
          BSR    ECHO1      OUTPUT LF TO CONSOLE
          RTS
```

```

*      SPACES MOVE THE CURSOR ON THE CRT TO THE RIGHT N TIMES
*
SPACES:   SUBQ.W #1,D2          ADJUST INDEX FOR THE # OF SP
SPACE_LOOP: MOVE.B #SPACE,D0    ASCII CODE FOR ' '
           BSR    ECHO1        OUTPUT SPACE TO CONSOLE
           DBF    D2,SPACE_LOOP IF MORE SPACES LOOP TO SPACE
           RTS
*
*      SCROLL ALLOWS THE SCREEN SCROLL TO BE ABORTED BY AN ESC
*      OR STOPPED AND STARTED BY ANY OTHER KEY
*
SCROLL:   LEA    PORT1,A4
           BTST.B #RECFULL,SRA(A4) GET CONSOLE STATUS
           BEQ.S  SCROLL_EXIT     IF NO CHAR FROM
                           CONSOLE, EXIT
*
           BSR    GETCHAR1       ELSE GET CHAR
           CMP.B #ESC,D0        IS THE CHAR AN ESC?
           BEQ.S  SCROLL_EXI    - YES, ABORT

PAUSE_CHK: LEA    PORT1,A4
           BTST.B #RECFULL,SRA(A4) GET CONSOLE STATUS
           BEQ.S  PAUSE_CHK      IF NO NEW KEY STROKE, WAIT
           BSR    GETCHAR1       ELSE GET CHAR

SCROLL_EXIT: RTS
             END

```

```

*****
* THIS PROGRAM DECODES COMMANDS FROM THE COMMAND LINE. *
*****
* 68K MONITOR VERSION 1.3 *
* WRITTEN BY DR. LARRY ABBOTT NOV. 7, 1986 *
*****
* FILENAME: DECODER.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* BUFFIN - MAIN.ASM BKPT_LIST - STUB.ASM *
* ERRMSG - MESSAGE.ASM DOWNLOAD - DOWNLOAD.ASM *
* FOUND - MAIN.ASM GO - GO.ASM *
* MESSAGE - MESSAGE.ASM MEM_DISPLAY - MEM_LIST.ASM *
* MONSTAT - MAIN.ASM MEM MODIFY - MEM_LIST.ASM *
* NULL - MAIN.ASM NO_BKPT - STUB.ASM *
* SPACE - MAIN.ASM REG - REG.ASM *
* SCRLF - IO_UTIL.ASM REGCHANG - REGCHANG.ASM *
* BKPT - GO.ASM *
*****
* COMMAND FORMATS: *
* LEGEND : < .. > - OPTIONAL *
* { .. } - SELECT ONE ITEM *
* XX - NUMBER 0 -> 15 *
* NOTE : ALL ADDRESSES AND VALUES IN HEX *
*
* BREAK POINT - BR (NOT IMPLEMENTED) *
* NO BREAKPOINT - NOBR (NOT IMPLEMENTED) *
* DOWNLOAD - LOAD *
* GO - GO address <,break point address> *
* MEMORY MODIFY - MM start address <,end address> *
* MEMORY DISPLAY - MD start address <,end address> *
* REGISTER CHANGE - RCH { Axx,Dxx,PC,US,SP,SR} value *
* DISPLAY REGISTERS- REG *
*****

```

```

GLOBAL      CMD_DECODE
EXTERNAL    BUFFIN,ERRMSG,FOUND,MESSAGE,MONSTAT,NULL
EXTERNAL    SPACE,SCRLF
EXTERNAL    BKPT,BKPT_LIST,DOWNLOAD,GO
EXTERNAL    MEM_DISPLAY,MEM MODIFY,NO_BKPT,REG,REGCHANG
*
*
CMD_DECODE: LEA      COMMANDS,A1      INITIALIZE COMMAND POINTER
            BCLR    #FOUND,MONSTAT
DECODE_INIT:LEA      BUFFIN+1,A0      INITIALIZE BUFFIN POINTER
            MOVE.L #3,D1          INIT INDEX FOR 4 CHARS

```

SCAN:	MOVE.B (A1)+,D0	GET COMMAND.TABLE(I) & I<--I+1
*	CMP.B #SPACE,D0	IS CHARACTER A SPACE ? - YES, FOUND COMMAND
	BEQ FOUND_CMD	IS CHARACTER A NULL ? - YES, EXHAUSTED COM TABLE
	CMP.B #NULL,D0	IS BUFFIN = COMMAND.TABLE ? - YES & MORE CHAR, CONT
	BEQ NO_CMD	- NO, ADJUST ADDR FOR NEXT COMMAND
	CMP.B (A0)+,D0	
	DBNE D1,SCAN	
	BNE ADDR_FIELD	
*		
FOUND_CMD:	BSET #FOUND,MONSTAT	SET COMMAND FND STATUS BIT
	CMPI.W #0,D1	IS COMMAND A 4 CHAR COM?
	BMI CMD_FOUND	- YES, SKIP "JUMP ADDRESS" ADJUST
*		
ADDR_FIELD:	ADDQ.L #2,D1	ADJUST INDEX FOR NEXT COM
	ADD.L D1,A1	ADD INDEX TO COMMAND PNTR
	BCLR #FOUND,MONSTAT	CLEAR COM FOUND STATUS BIT
	BEQ DECODE_INIT	CHECK NEXT CMD
	SUB.L #5,D1	
	ADD.B D1,BUFFIN	ADJUST BUFFIN LENGTH
	SUBQ.L #2,A1	ADJUST ADDRESS FOR JUMP
CMD_FOUND:	MOVE.W (A1),A1	GET JUMP ADDRESS
	JSR (A1)	JUMP TO COMMAND
	BRA DECODEXT	EXIT DECODER
NO_CMD:	BSR SCRLF	
	MOVE.W #ERRMSG,A5	SET MESSAGE POINTER
	BSR MESSAGE	PRINT ERROR MESSAGE TO CRT
DECODEXT:	RTS	
*		
EVEN ON		
COMMANDS:	BYTE 'BR '	
	WORD BKPT_LIST	
	BYTE 'LOAD'	
	WORD DOWNLOAD	
	BYTE 'GO '	
	WORD GO	
	BYTE 'MD '	
	WORD MEM_DISPLAY	
	BYTE 'MM '	
	WORD MEM MODIFY	
	BYTE 'NOBR'	
	WORD NO_BKPT	
	BYTE 'RCH '	
	WORD REGCHANG	
	BYTE 'REG '	
	WORD REG	
	BYTE NULL,NULL,NULL,NULL	
EVEN OFF		
END		

```
*****
* THIS PROGRAM CONVERTS A BYTE INTO 2 ASCII CHARACTERS AND      *
* IT SENDS THE CHARACTERS TO THE CRT DISPLAY.                      *
*****  

* WRITTEN BY DR. LARRY ABBOTT                                     *
*****  

* FILENAME: BYTEOUT.ASM                                         *
*****  

* VERSION 1.3                                                 *
* REV. MODIFIED BY      DATE      DESCRIPTION                  *
* A    DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE       *
*****  

* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES           *
*   ECHO1 - CONSOLE.ASM                                       *
*****
```

```
GLOBAL      OUTPUT_BYTE
EXTERNAL    ECHO1
*
OUTPUT_BYTE:MOVE.B D0,D2      MAKE A TEMPORARY COPY OF BYTE
             LSR.B #4,D0      SHIFT M.S. NIBBLE TO L.S. NIBBLE
             BSR    ASCONV     CONVERT M.S. NIBBLE TO ASCII
             MOVE.B D2,D0      D0 <-- TEMPORARY COPY OF BYTE
             ANDI.B #$0F,D0    MASK OFF M.S. NIBBLE
             BSR    ASCONV     CONVERT L.S. NIBBLE TO ASCII
             RTS
ASCONV:    ADDI.B #$30,D0    ADD ASCII BASE
             CMP.B #$3A,D0    IS NUMBER 0-9 ?
             BLT    ASCOUT     - YES, OUTPUT TO CONSOLE
             ADDQ.B #7,D0      ADJUST FOR A - F (HEX)
ASCOUT:   BSR    ECHO1      OUTPUT TO CONSOLE
             RTS
             END
```

```
*****
* THIS PROGRAM MODIFIES OR LISTS THE CONTENTS OF THE *
* SPECIFIED MEMORY LOCATIONS. *
*****
* WRITTEN BY DR. LARRY ABBOTT *
*****
* FILENAME: MEM_LIST.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* BUFFIN - MAIN.ASM MONSTAT - MAIN.ASM *
* BACKSPACES - IO_UTIL.ASM OUTPUT_BYTE - BYTEOUT.ASM *
* END_ADDRESS - MAIN.ASM SCRLF - IO_UTIL.ASM *
* ESC - MAIN.ASM SCROLL - IO_UTIL/ASM *
* GET_ADDR - GET_ADDR.ASM SPACE - MAIN.ASM *
* GETSTRING - GETSTRIN.ASM SPACES - IO_UTIL.ASM *
* HEX_CONV - HEXCONV.ASM STRINGEND - MAIN.ASM *
* HEX_ERR - MAIN.ASM STRING - MAIN.ASM *
* MODIFY - MAIN.ASM *
*****
```

```
GLOBAL MEM_DISPLAY, MEM MODIFY
EXTERNAL BUFFIN, BACKSPACES, END_ADDRESS, ESC
EXTERNAL GET_ADDR, GETSTRING, HEX_CONV, HEX_ERR, MODIFY
EXTERNAL MONSTAT, OUTPUT_BYTE, SCRLF, SCROLL, SPACE, SPACES
EXTERNAL STRINGEND, STRING
```

```
*
MEM MODIFY:BSET.B #MODIFY,MONSTAT      SET MODIFY FLAG
          BSR    MEM DISPLAY        DISPLAY MEMORY
          BCLR.B #MODIFY,MONSTAT    CLEAR MODIFY FLAG
          RTS

*
*      THIS PROGRAM LIST THE CONTENTS OF THE SPECIFIED
*
MEM DISPLAY:CMPI.B #SPACE, (A0)      DOES BUFFIN(I)
          *                               CHAR = SPACE?
          BNE    START_ADDR        - NO, GET START & END
          *                               ADDRESS
          ADDQ.W #1,A0             - YES, SO I <-- I+1
          SUBQ.B #1,BUFFIN         DECREMENT BUFFIN LENGTH
          BRA    MEM DISPLAY        CONT SCANNING BUFFIN
START_ADDR: BSR    GET_ADDR         CONVERT ADDRS TO HEX
          BCLR.B #HEX_ERR,MONSTAT WAS THERE AN HEX ERROR ?
          BNE    MD_EXIT           - YES, SO EXIT
NEWLINE:   BSR    SCRLF            MOVE CURSOR TO NEXT LINE
          BSR    LINE_NUMBER        DISPLAY LINE ADDRESS
```

GETABYTE:	MOVE.B (A2)+,D0	D0 <-- (START ADDRESS)
	BSR OUTPUT_BYTE	OUTPUT BYTE TO CRT
	BTST #MODIFY,MONSTAT	JS MEMORY MODIFY STATUS BIT SET ? - NO, SKIP CHANGE - YES, MODIFY MEMORY
*		
	BEQ WORD_SPACE	
	BSR CHANGE	
	BCLR.B #HEX_ERR,MONSTAT	CLR HEX STATUS BIT ERROR
	BNE MD_EXIT	IF ERROR EXIT
WORD_SPACE:	MOVE.W #2,D2	SETUP FOR 2 SPACES
	BSR SPACES	OUTPUT 2 SPACES TO CRT
	MOVE.L END_ADDRESS,D1	GET END ADDRESS
	MOVE.L A2,D0	D0 <- START ADDRESS
	SUB.L D0,D1	D1<--END ADDR-START ADDR
	BLT MD_EXIT	IF START > END THEN EXIT
	ANDI.B #\$0F,D0	DOES L.S. NIBBLE = 0 ?
	BNE GETABYTE	- NO, GET ANOTHER BYTE
	BSR SCROLL	SCROLL PAUSE CHECK
	CMP.B #ESC,D0	ABORT SCROLL ?
	BEQ MD_EXIT	- YES, SO EXIT
	BRA NEWLINE	- NO, START A NEW LINE
MD_EXIT:	BSR SCRLF	MOVE CURSOR TO NEXT LINE
*		
LINE_NUMBER:	MOVE.L A2,D0	GET CURRENT ADDRESS
	ROR.L #8,D0	MOVE M.S. BYTE TO L.S. BYTE
	BSR OUTPUT_BYTE	DISPLAY BYTE ON CRT
	ROR.L #8,D0	MOVE M.S. BYTE TO L.S. BYTE
	BSR OUTPUT_BYTE	DISPLAY BYTE ON CRT
	ROR.L #8,D0	MOVE M.S. BYTE TO L.S. BYTE
	BSR OUTPUT_BYTE	DISPLAY BYTE ON CRT
	ROR.L #8,D0	MOVE M.S. BYTE TO L.S. BYTE
	BSR OUTPUT_BYTE	DISPLAY BYTE ON CRT
	MOVE.W #4,D2	SETUP FOR 4 SPACES
	BSR SPACES	OUTPUT 4 SPACES TO CRT
	RTS	
*		
CHANGE:	MOVE.W #2,D2	SETUP FOR 2 BCKSPCES
	BCLR.B #STRING,MONSTAT	SET FOR NEW STRING
CHGAGIN:	BSR BACKSPACES	MOVE 2 SP TO THE LEFT
MORE_CHAR:	BSR GETSTRING	GET ANY NEW CHARACTERS
	BCLR.B #STRINGEND,MONSTAT	CHECK FOR END OF STR
	BEQ MORE_CHAR	IF MORE STRING, BRANCH
	MOVE.B BUFFIN,D3	GET STRING LENGTH
	BEQ NO_ENTRY	IF STR LEN=0 THEN NO ENTRY
*		
	CMPI.B #2,D3	DOES STRING LEN = 2 ?
	BNE CHGAGIN	- NO, THEN RE-ENTER
	BSR GET_DATA	CONVERT BYTE TO HEX
	BTST.B #HEX_ERR,MONSTAT	IS THERE A HEX ERROR ?
	BNE CHG_EXIT	- YES, EXIT
	MOVE.B D2,-(A2)	BUFFIN(I) <-- HEX
	ADDQ.W #1,A2	

NO_ENTRY:	CLR.W D2	GET STRING LENGTH
	MOVE.B D3,D2	D1 <- -(STRING_LENGTH)
	NEG.W D2	ADJUST SPACE COUNT
	ADDQ.W #4,D2	SPACE TO END OF BYTE
BSR SPACES		
CHG_EXIT	RTS	
*		
GET_DATA	CLR.L D2	CLEAR HEXBUF
	CLR D4	CLR WORD FOR DBCC INDEX
	MOVE.B BUFFIN,D4	GET BUFFIN LENGTH
	SUBQ #1,D4	ADJUST FOR DBCC INST
	LEA BUFFIN+1,A0	INITIALIZE BUFFING PNTR
DATALOOP	MOVE.B (A0)+,D0	GET CHAR FROM BUFFIN
	BSR HEX CONV	CONV ASCII CHAR TO HEX
	BTST.B #HEX_ERR,MONSTAT	IS THERE A HEX ERR ?
	DBNE D4,DATALOOP	IF MORE CHARS, THEN LOOP AGAIN
*		
DATAEXIT	RTS	
	END	

```
*****
* THIS PROGRAM CONVERTS THE CONTENTS OF D0<7..0> FROM *
* ASCII TO HEX AND STORES THE RESULT IN REG D2. *
*****
* WRITTEN BY DR. LARRY ABBOTT *
*****
* FILENAME: HEXCONV.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* HEX_ERR - MAIN.ASM *
* MONSTAT - MAIN.ASM *
*****
```

GLOBAL       HEX\_CONV  
 EXTERNAL     HEX\_ERR,MONSTAT

\*  
 HEX\_CONV: SUB.B #\\$30,D0                          ADJUST ASCII TO  
   HEX BASE  
 \*  
     CMPI.B #9,D0                                  IS CHARACTER <= 9 ?  
     BLS.S ZERO\_CHECK                                - YES, CHECK >= 0  
     SUB.B #7,D0                                    ADJUST FOR A-F  
     CMPI.B #\\$A,D0                                  IS CHARACTER >= A ?  
     BCS.S HEXERR                                    - NO, HEX ERROR  
     CMPI.B #\\$F,D0                                  IS CHARACTER <= F ?  
     BHI.S HEXERR                                    - NO, HEX ERROR  
 ZERO\_CHECK: CMPI.B #0,D0                            IS CHARACTER >= 0 ?  
   - NO, HEX ERROR  
     BMI.S HEXERR                                    HEX # INTO  
     BSR    HEX\_SHIFT                                HEX BUFFER  
 \*  
     BCLR.B #HEX\_ERR,MONSTAT CLR HEX CONVERSION  
 \*    ERROR STATUS BIT  
     BRA.S HEX\_EXIT                                  EXIT HEX CONVERSION  
 HEXERR:    BSET.B #HEX\_ERR,MONSTAT SET HEX CONVERSION ERROR  
 \*    STATUS BIT  
 HEX\_EXIT: RTS  
 \*  
 HEX\_SHIFT: LSL.B #4,D0                          SHIFT L.S. NIBBLE TO M.S. NIBBLE  
   MOVE.W #3,D1                            SET FOR INDEX TO 4 SHIFTS  
 NIBBLE\_SHF: LSL.B #1,D0                          SHIFT HEX CHARACTER OUT  
   ROXL.L #1,D2                            SHIFT INTO HEX BUFFER  
   DBF    D1,NIBBLE\_SHF BRANCH IF MORE BITS  
   RTS  
   END

```
*****
* THE GO ROUTINE EXECUTES A PROGRAM FROM THE MONITOR. *
* THE FORMAT IS: *
*   GO <start address>, [optional breakpoint] *
*****  

* WRITTEN BY DR. LARRY ABBOTT *
*****  

* FILENAME: GO.ASM *
*****  

* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE *
* B DAVID M. SENDEK 5 OCT 87 BSET, BCLR ASSEMBLY *
*                                     LANGUAGE CORRECTION *
*****  

* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* BKPTAB - MAIN.ASM ILLMSG - MESSAGE.ASM *
* BKPTMSG - MESSAGE.ASM MESSAGE - MESSAGE.ASM *
* BTLEN - MAIN.ASM MONSTAT - MAIN.ASM *
* BUFFIN - MAIN.ASM OUTPUT_BYTE - BYTEOUT.ASM *
* CONTINUE - MAIN.ASM SCRLF - IO_UTIL.ASM *
* CMD_DECODE - DECODER.ASM SPACE - MAIN.ASM *
* GET_ADDR - GET_ADDR.ASM STRING - MAIN.ASM *
* GETSTRING - GETSTRIN.ASM STRINGEND - MAIN.ASM *
* HEX_ERR - MAIN.ASM SYSTAX - MAIN.ASM *
*****
```

```
GLOBAL BKPT,GO
EXTERNAL BKPTAB, BKPTMSG, BTLEN, BUFFIN, CONTINUE
EXTERNAL GET_ADDR, GETSTRING, HEX_ERR, ILLMSG, MESSAGE
EXTERNAL OUTPUT_BYTE, SCRLF, SPACE, STRING, STRINGEND
EXTERNAL MONSTAT, SYSTAX, CMD_DECODE
*
TRAP0 EQU $4E40          OP CODE FOR TRAP #0
*
GO    CMPI.B #SPACE, (A0) + IS BUFFIN(X) A SPACE ?
      BNE GO_ADDR           - NO, GET GO ADDRESS
      SUBQ.B #1,BUFFIN       - YES, ADJUST BUFFIN LENGTH
      BRA GO                - YES, SCAN FOR NEXT SPACE
GO_ADDR SUBQ #1,A0         ADJUST FOR POST INCREMENT
      BSR GET_ADDR          A2<-GO ADDR, A3<-BREAKPOINT
      CMPA #0,A2             IS THERE A START ADDRESS ?
      BEQ CONTINU            - NO, THIS IS A CONTINUATION
      BCLR.B #4,MONSTAT      CHECK FOR HEXCONV ERROR
      BNE GO_EXIT            IF HEX ERROR THEN EXIT
      MOVEA.L SYSTAX,A0        ELSE GET SYSTAX POINTER
      MOVE.L A2,(A0)           SYSTAX(PC) <-- GO ADDRESS
      CMPA #0,A3             IS THERE A BREAKPOINT ?
      BEQ GO_EXIT            - NO, SO EXIT
      LEA BKPTAB,A0           SET BREAK TAB POINTER
      MOVEA.L A3,(A0)           STORE BREAKPOINT IN TABLE
      MOVE.W (A3),BTLEN(A0)     STORE INSTRUCTION AT BKPT
```

```

MOVE.W #TRAP0, (A3)      STORE ILL INSTRUCT AT BKPT
CONTINU:BSET.B #CONTINUE,MONSTAT   SET CONTINUE FLAG
GO_EXIT RTS
*
*      THE BREAKPOINT (BKPT) ROUTINE RESTORES THE INSTRUCTION
*      AT THE BREAKPOINT
*
BKPT:   BCLR.B #CONTINUE,MONSTAT INIT CONTINUATION FLAG
        LEA     BKPTAB,A0      SET BREAK TABLE POINTER
        MOVE.L (A0),A3      GET BKPT ADDRESS
        MOVE.W 16(A0), (A3)  RESTORE INSTRUCTION
        LEA     BKPTMSG,A5      SET BREAKPOINT MESSAGE
BADINST BSR    MESSAGE      PRINT MESSAGE
        MOVE.L A3,D0      GET BKPT ADDRESS
        MOVE.W #3,D3      SET BYTE INDEX
ADDRROUT ROL.L #8,D0      ROTATE D0 BY 1 BYTE
        BSR    OUTPUT_BYTE  CRT <-- D0<0..7>
        DBF    D3,ADDRROUT MORE ADDRESS THE LOOP
        BSR    SCRLF      MOV CURSOR TO STRT OF LINE
        SUBQ.L #2,2(SP)  ADJUST RETURN ADDRESS
        MOVE.L SP,SYSTAX  SAVE POINTER TO RETURN ADDR
EXAMINE  BSR    GETSTRING  ALLOWS EXAM AT BKPT
        BCLR.B #STRINGEND,MONSTAT END OF STRING ?
        BEQ    EXAMINE   - NO, SO LOOP
        BCLR.B #STRING,MONSTAT CLEAR NEW STRING FLAG
        BSR    CMD_DECODE IF END THEN DECODE
        BCLR.B #CONTINUE,MONSTAT IS THIS A CONTINUATION ?
        BEQ    EXAMINE   - YES, LOOP AGAIN
        RTE
        END

```

```
*****
* THIS FILE CONTAINS PROGRAMMING STUBS TO COMPLETE THE      *
* LINKING PROCESS WHILE BUILDING AND TESTING HIGHER      *
* LEVEL MODULES.                                         *
*****  
* WRITTEN BY DR. LARRY ABBOTT                         *
*****  
* FILENAME: STUB.ASM                                  *
*****  
* VERSION 1.3                                         *
* REV. MODIFIED BY        DATE      DESCRIPTION      *
*   A    DAVID M. SENDEK  1 OCT 87 -DOCUMENTATION UPGRADE  *
*                                         -INCORPORATE PROMPT MSG  *
*****  
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES:  *
*   PROMPT - MESSAGE.ASM                            *
*   MESSAGE - MESSAGE.ASM                           *
*****
```

```
GLOBAL     BKPT_LIST, NO_BKPT
EXTERNAL   PROMPT, MESSAGE
```

```
BKPT_LIST:LEA      PROMPT, A5
                BSR      MESSAGE
                RTS
NO_BKPT:    LEA      PROMPT, A5
                BSR      MESSAGE
                RTS
                END
```

```
*****
* THIS ROUTINE PRINTS OUT THE CONTENTS OF THE REGISTERS. *
*****  

* WRITTEN BY DR. LARRY ABBOTT *
*****  

* FILENAME: REG.ASM *
*****  

* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE *
*****  

* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* MESSAGE - MESSAGE.ASM SCRLF - IO_UTIL.ASM*
* OUTPUT_BYTE - BYTEOUT.ASM SPACES - IO_UTIL.ASM*
* REGMSG - MESSAGE.ASM SYSTAX - MAIN.ASM *
*****
```

```
GLOBAL REG
EXTERNAL MESSAGE,OUTPUT_BYTE,REGMSG
EXTERNAL SCRLF,SPACES,SYSTAX
```

REG	BSR	SCRLF	
	LEA	REGMSG,A5	GET POINTER TO MESSAGE
	MOVEA.L	SYSTAX,A2	GET STACK POINTER AT MONITOR ENTRY
*	SUB.L	#\$40,A2	OFFSET OF THE STACK
	MOVE.W	#15,D3	SET REGS CNTR FOR 16 REGS
REGLIST	BSR	MESSAGE	PRINT PART OF REGISTER MESSAGE
	MOVE.W	#3,D4	SET FOR 32-BIT REGISTER
	BSR	REG_DUMP	PRINT CONTENTS OF A REGISTER
*	DBF	D3,REGLIST	IF MORE REGS, THEN GO TO REGLIST
	BSR	MESSAGE	PRINT "SR ="
	MOVE.W	#1,D4	SET FOR 16-BIT REGISTER
	BSR	REG_DUMP	PR CONTENTS OF STAT REG (SR)
	MOVE.W	#4,D2	SET FOR 4 SPACES
	BSR	SPACES	PRINT 4 SPACES
	BSR	MESSAGE	PRINT "PC ="
	MOVE.W	#3,D4	SET FOR 32-BIT PC REGISTER
	BSR	REG_DUMP	PRINT CONTENTS OF PC REGISTER
	MOVE.W	#1,D2	SET FOR 1 SPACES
	BSR	SPACES	PRINT 1 SPACES
	BSR	MESSAGE	PRINT "(PC) ="
	SUBQ.L	#4,A2	
	MOVE.L	(A2),A2	
	MOVE.W	#1,D4	SET FOR WORD POINTED TO BY PC
	BSR	REG_DUMP	PRINT CONTENTS OF WD PNTD BY PC
	BSR	SCRLF	FORMAT DISPLAY
	RTS		

```
*  
REG_DUMP MOVE.B (A2)+,D0      GET A BYTE OF THE REG  
*                                FROM APPLICATION PSW  
BSR     OUTPUT_BYTE  OUTPUT BYTE TO CONSOLE  
DBF     D4,REG_DUMP  IF MORE BYTES THEN REG_DUMP  
RTS  
END
```

```
*****
* THIS ROUTINE CHANGES THE CONTENTS OF DESIRED REGISTERS. *
*****
* WRITTEN BY DR. LARRY ABBOTT *
*****
* FILENAME: REGCHANG.ASM *
*****
* VERSION 1.3 *
* REV. MODIFIED BY DATE DESCRIPTION *
* A DAVID M. SENDEK 1 OCT 87 DOCUMENTATION UPGRADE *
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES: *
* BUFFIN - MAIN.ASM MONSTAT - MAIN.ASM *
* GET_ADDR - GET_ADDR.ASM REG - REG.ASM *
* * REGERR - MESSAGE.ASM *
* HEX_CONV - HEXCONV.ASM SPACE - MAIN.ASM *
* HEX_ERR - MAIN.ASM SYSTAX - MAIN.ASM *
* MESSAGE - MESSAGE.ASM SCRLF - IO_UTIL.ASM *
*****
```

```
GLOBAL REGCHANG
EXTERNAL BUFFIN,GET_ADDR,HEX_CONV,HEX_ERR
EXTERNAL MESSAGE,MONSTAT,REG,REGERR,SPACE,SYSTAX,SCRLF
```

```
*
ESC EQU $1B
*
*
REGCHANG: BSR REG DISPLAY REGISTERS ON CRT
BLANKSCAN: MOVE.B (A0)+,D0 DECREMENT BUFFIN LENGTH
           SUBQ.B #1,BUFFIN DOES BUFFIN(I) CHAR = SPACE ?
           CMPI.B #SPACE,D0 - NO, GET START AND END ADDR
           BNE START_REG CONTINUE SCANNING BUFFIN
           BRA BLANKSCAN DOES D0 = ESC (ASCII) ?
START_REG: CMPI.B #ESC,D0 - YES, RTS
           BEQ REG_DONE DOES D0 = 'A' ?
           CMPI.B #'A',D0 - YES, ADJUST POINTER
           BEQ REGA DOES D0 = 'D' ?
           CMPI.B #'D',D0 - YES, ADJUST POINTER
           BEQ REGD DOES D0 = 'P' ?
           CMPI.B #'P',D0 - YES, CK FOR 'C' & ADJUST PNTR
           BEQ REGP DOES D0 = 'U' ?
           CMPI.B #'U',D0 - YES, CHECK FOR 'S'
           BEQ REGU DOES D0 = 'S' ?
           CMPI.B #'S',D0 - NO, PRINT ERR D0 <> A,D,P,U,S
           BNE PRINTERR GET SECOND CHAR OF COMMAND LINE
           MOVE.B (A0)+,D0 SUBTRACT 1 FROM BUFFIN
           SUBQ.B #1,BUFFIN
           CMPI.B #'P',D0
           BEQ REGSP
           CMPI.B #'R',D0
           BEQ REGREP
           CMPI.B #'S',D0
```

```

        BNE      PRINTERR
        MOVE.L  #-4,D3
        BRA     REGREP
REGA:   MOVE.L  #-32,D3
        BRA     REGFIN
REGD:   MOVE.L  #-64,D3
        BRA     REGFIN
REGP:   MOVE.B  (A0)+,D0
        SUBQ.B #1,BUFFIN
        CMPI.B #'C',D0
        BNE      PRINTERR
        MOVE.L  #2,D3
        BRA     REGREP
REGU:   MOVE.B  (A0)+,D0
        SUBQ.B #1,BUFFIN
        CMPI.B #'S',D0
        BNE      PRINTERR
        MOVE.L  #-4,D3
        BRA     REGREP
REGSP:  MOVE.L  #-4,D0
        BRA     REGREP
PRINTERR: LEA     REGERR,A5
        BSR     MESSAGE
        BRA     REG_DONE
REGFIN: MOVE.B  (A0)+,D0
        SUBQ.B #1,BUFFIN
        CLR.L  D2
        BSR     HEX_CONV
        BTST.B #HEX_ERR,MONSTAT
        BNE      PRINTERR
        LSL.L  #2,D2
        ADD.L  D2,D3
REGREP: LEA     SYSTAX,A1
        MOVE.L  (A1),A1
        ADD.L  D3,A1
RCA:    CMPI.B #SPACE,(A0)
        BNE      FFF
        ADDQ.W #1,A0
        SUBQ.B #1,BUFFIN
        BRA     RCA
FFF:    BSR     GET_ADDR
        MOVE.L  A2,(A1)
        BSR     REG
REG_DONE: RTS

```

```
*****
* DOWNLOAD ALLOWS THE MONITOR TO DOWNLOAD Sxx RECORDS TO ITS*
* RESIDENT 680XX MICROCOMPUTER OVER A SECOND RS-232 PORT.   *
*****  

* WRITTEN BY DR. LARRY ABBOTT      APRIL 24, 1986      *
*****  

* FILENAME: DOWNLOAD.ASM          *
*****  

* VERSION 1.3                   *
* REV. MODIFIED BY      DATE      DESCRIPTION      *
* A    LARRY ABBOTT    12/18/86  INIT DEBUG PROCESS      *
* B    DAVID M. SENDEK  1 OCT 87 -DOCUMENTATION UPGRADE      *
*                                -CORRECT FOR MC68681      *
* C    DAVID M. SENDEK  5 OCT 87 BCLR,BSET ASSEMBLY      *
*                                LANGUAGE CORRECTION      *
* D    DAVID M. SENDEK  4 JAN 88 -CORRECT DOWNLOADING OF      *
*                                S1,S9 FORMAT RECORDS.      *
*                                NOTE:FINAL S9 RECORD WILL      *
*                                HAVE A '**' AFTER LAST      *
*                                CHARACTER IN THE RECORD      *
*****  

* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES:      *
* CHECKSUM - MAIN.ASM      CK_SUM - MAIN.ASM      *
* ECHO1   - CONSOLE.ASM     ECHO2  - CONSOLE.ASM      *
* EPROMRNG - MAIN.ASM      EPROMSG - MESSAGE.ASM      *
* EPROMWR - MAIN.ASM      *
* HEX_CONV - HEXCONV.ASM    SCRLF  - IO_UTIL.ASM      *
* HEX_ERR  - MAIN.ASM      SREC_ERR - MESSAGE.ASM      *
* HEXMSG   - MESSAGE.ASM    SCANCHR2 - CONSOLE.ASM      *
* MESSAGE  - MESSAGE.ASM    SPACES  - IO_UTIL.ASM      *
* MONSTAT - MAIN.ASM      SRB    - MAIN.ASM      *
* RECFULL - MAIN.ASM      GETCHR2 - CONSOLE.ASM      *
*****
```

```
GLOBAL DOWNLOAD
EXTERNAL CHECKSUM,CK_SUM,ECHO1,ECHO2,EPROMRNG,EPROMSG
EXTERNAL EPROMWR,ESCAPE
EXTERNAL HEX_CONV,HEX_ERR,HEXMSG,MESSAGE,MONSTAT
EXTERNAL RECFULL,SCRLF,SREC_ERR
EXTERNAL SCANCHR2,SPACES
EXTERNAL SRB,GETCHR2
```

```
*
*
*
DOWNLOAD:BSR    SCANCHR2      DO DUMMY RD TO CLR CHAN B
            BTST.B #REFULL,SRB      ANY THING ELSE IN CHAN B ?
            BNE.S DOWNLOAD       - YES,SCAN CHANNEL B AGAIN
            BSR    SCRLF         ECHO CR & LF TO CRT
DOWNLOOP:BCLR.B #HEX_ERR,MONSTAT CLEAR HEX ERROR FLAG
S_LOOP    BSR    GETCHR2      GET A CHAR FROM DWNLNK PORT
            BTST.B #ESCAPE,MONSTAT ESC THE DOWNLOAD PROCESS ?
            BNE    DOWNEXIT      - YES, EXIT
```

CMPI.B #'S',D0	IS CHARACTER = 'S' ?
BNE S_LOOP	- NO, SEARCH FOR A 'S'
BSR ECHO2	ECHO 'S' TO CONSOLE
MOVE.W #1,D3	SET FOR 16-BIT ADDR
BSR GETCHR2	GET A CHAR FROM DWNLNK PORT
BSR ECHO2	ECHO DWNLNK CHAR TO CONSOLE
CMPI.B #'0',D0	IS THIS A S0 RECORD ?
BEQ S_RECORD	- YES, GO TO S RECORD
CMPI.B #'1',D0	IS THIS A S1 RECORD ?
BEQ S_RECORD	- YES, GO TO S RECORD
CMPI.B #'9',D0	IS THIS A S9 RECORD ?
BEQ S9_RECORD	- YES, GO TO S9 RECORD
ADDQ.W #1,D3	SET FOR 24-BIT ADDR
CMPI.B #'2',D0	IS THIS A S2 RECORD ?
BEQ S_RECORD	- YES, GO TO S RECORD
ADDQ.W #1,D3	SET FOR A 32-BIT ADDRESS
CMPI.B #'3',D0	IS THIS A S3 RECORD ?
BEQ S_RECORD	- YES, GO TO S RECORD
LOADERR: LEA SREC_ERR,A5	IF NO Sxx RECORD ;THEN 'S RECORD ERROR' MSG
BSR ERREMSG	
DOWNEXIT: BSR SCRLF	ECHO CR & LF
LEA EPROMSG,A5	SET UP
*	"ATTEMPTED WRITE TO EPROM"
BCLR.B #EPROMWR,MONSTAT	WAS THERE A WRITE TO EPROM?
BEQ.S ERREMSG	- YES, PRINT ERROR MESSAGE
RTS	
ERREMSG: BSR MESSAGE	PRINT ERROR MESSAGE
RTS	
S_RECORD: BSR SN_RECORD	PROCESS S RECORD
BCLR.B #HEX_ERR,MONSTAT	IF NOT HEX CONVERSION ERR
BEQ DOWNLOOP	THEN GET NEXT RECORD
LEA HEXMSG,A5	ELSE HEX CONV ERROR MSG
BRA ERREMSG	PRINT ERROR MSG
*	
S9_RECORD: BSR SN_RECORD	PROCESS S RECORD
BTST.B #HEX_ERR,MONSTAT	IF HEX CONVERSION ERROR
BEQ DOWNEXIT	THEN TERMINATE XMISSION
RTS	
*	
SN_RECORD: CLR.W D6	SET FOR 1 BYTE
CLR.B CK_SUM	CLEAR CHECK SUM
BSR GETFIELD	GET DOWNLOAD FIELD
BTST.B #HEX_ERR,MONSTAT	IF HEX CONVERSION ERROR
BNE.S SN_EXIT	THEN EXIT SN RECORD
MOVE.W D2,D4	D4<-HEXBUFFER (S REC LEN)
SUB.W D3,D4	LEN = (S REC LEN) - ADDR
SUBQ.W #2,D4	ADJST FOR DBF INST & ADDR
MOVE.W D3,D6	SET ADDRESS SIZE

	BSR	GETFIELD	GET ADDRESS FIELD
	BTST.B	#HEX_ERR,MONSTAT	IF HEX CONVERSION ERROR
	BNE.S	SN_EXIT	THEN EXIT SN_RECORD
	MOVE.L	D2,A0	A0 <-- LOAD ADDRESS
	BSR	DOWN_DATA	GET DOWN LOAD DATA
SN_EXIT	RTS		
*			
DOWN_DATA	BSR	GETCHR2	GET FIRST CHARACTER
*	BSR	ECHO2	ECHO DWNLD CHARACTER TO CONSOLE
	CLR.L	D2	
	BSR	HEX_CONV	CONVERT CHAR TO HEX
	BTST.B	#HEX_ERR,MONSTAT	IF HEX CONVERSION ERROR
	BNE.S	DD_EXIT	THEN EXIT DOWN_DATA
	BSR	GETCHR2	GET SECOND CHARACTER
	BSR	ECHO2	ECHO DWNLD CHAR TO CONSOLE
	CMPA.L	#EPROMRNG,A0	IS THIS A WRITE TO EPROM?
	BLS.S	EPROMERR	- YES, GO TO EPROMERR
	BSR	HEX_CONV	CONVERT CHARACTER TO HEX
	MOVE.B	D2,(A0)	LOAD BYTE INTO MEMORY
	BRA.S	CHK_SUM	
EPROMERR	BSET.B	#EPROMWR,MONSTAT	FLAG EPROM WRITE
CHK_SUM	ADDQ.L	#1,A0	INCREMENT MEM LOAD ADDR
	TST.W	D4	ARE NXT CHARS CHECK SUM ?
	BEQ.S	LOOP_END	- YES, DONT ADD TO CHK SUM
	ADD.B	D2,CK_SUM	ADD THIS BYTE TO CHK SUM
LOOP_END	DBF	D4,DOWN_DATA	IF MORE DATA THEN LOOP
	NOT.B	CK_SUM	COMPLEMENT CHECK SUM
	MOVE.B	- (A0),D2	GET COMPUTED CHECK SUM
*	CMP.B	CK_SUM,D2	COMP CALC'S AND
*	BEQ.S	ERRCHECK	XMIT CHK SUMS
*			IF CHECK SUMS AGREE
			THEN EXIT DOWNLOAD
	MOVE.L	MONSTAT,D3	
	BSET.L	#CHECKSUM,D3	SET FLAG IF CHECK SUM ERR
	MOVE.L	D3,MONSTAT	
	BRA.S	ERR_MARK	
ERRCHECK	BTST.B	#EPROMWR,MONSTAT	A WRITE TO EPROM ?
	BEQ.S	DD_EXIT	- NO, EXIT
ERR_MARK	MOVE.W	'*',D0	- YES, MARK ERROR WITH *
	BSR	ECHC1	
DD_EXIT	BSR	SCRLF	ECHO CR & LF
*			
GETFIELD	CLR.L	D2	CLEAR HEX BUFFER
LOOPINIT	MOVE.W	#1,D5	SET COUNT TO
*			PACK 2 NIBBLES
GF_LOOP	BSR	GETCHR2	GET DOWNLOAD CHARACTER
*	BSR	ECHO2	ECHO DOWNLOAD CHARACTER TO CONSOLE
	BSR	HEX_CONV	CONVERT ASCII CHAR TO HEX
	BTST.B	#HEX_ERR,MONSTAT	IF HEX CONVERSION ERROR

BN.E.S GF\_EXIT                    THEN EXIT GET FIELD  
DBF D5,GF\_LOOP                GET SECOND NIBBLE  
ADD.B D2,CK\_SUM                COMPUTE CHECK SUM  
DBF D6,LOOPINIT              IF MORE CHARS THEN LOOP  
GF\_EXIT RTS                    ELSE EXIT  
END

```
*****
* THIS ROUTINE IS VECTORED TO BY ALL EXCEPTIONS THAT
* LACK A DEFINITE EXCEPTION SERVICE ROUTINE.
*****
* WRITTEN BY DR. LARRY ABBOTT
*****
* FILENAME: UNUSED.ASM
*****
* VERSION 1.3
* REV. MODIFIED BY      DATE      DESCRIPTION
* A      DAVID M. SENDEK  1 OCT 87  -DOCUMENTATION UPGRADE
*                                -INCORPORATE A PROMPT
*****
* DEFINING MODULES OF EXTERNALLY DECLARED VARIABLES:
*   OUTPUT_BYTE - BYTEOUT.ASM      MESSAGE - MESSAGE.ASM
*   REG         - REG.ASM          SCRLF  - IO_UTIL.ASM
*   SYSTAX     - MAIN.ASM         USEMSG - MESSAGE.ASM
*   PROMPT     - MESSAGE.ASM
*****
```

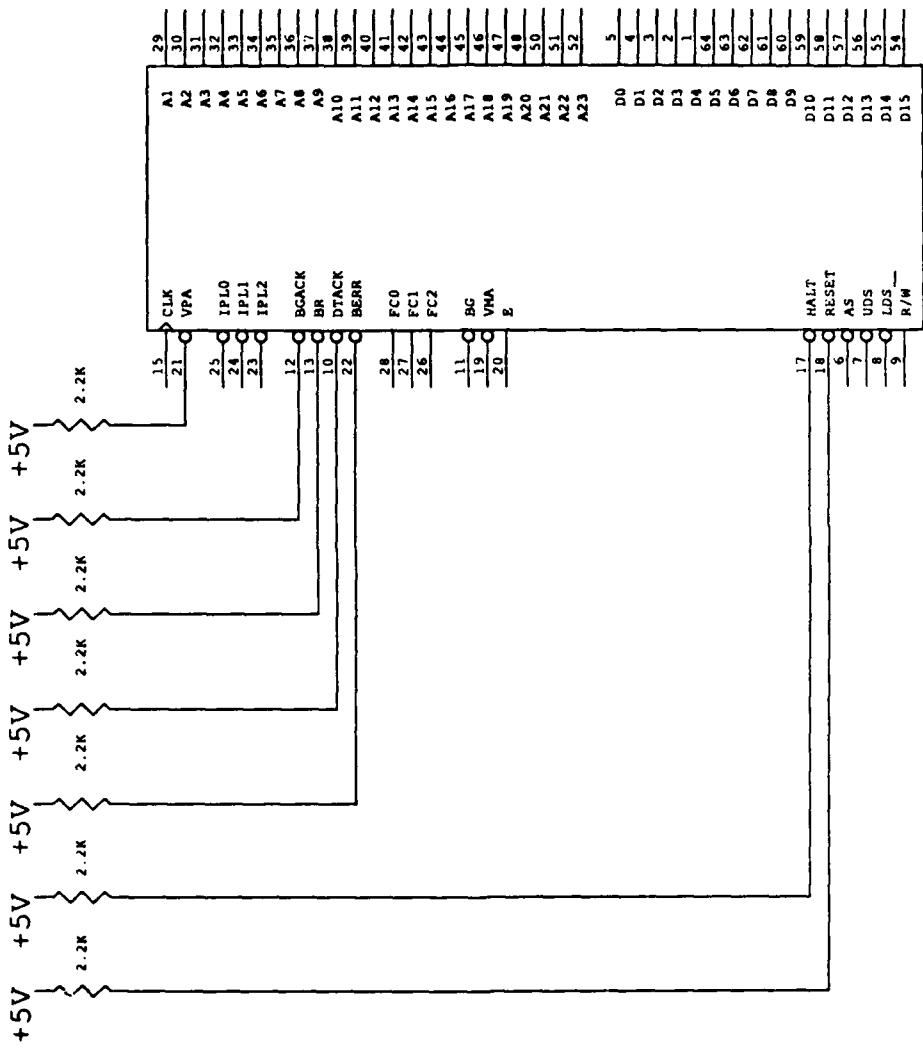
```
GLOBAL    UNUSED
EXTERNAL  OUTPUT_BYTE,MESSAGE,REG,SCRLF,SYSTAX,USEMSG
EXTERNAL  PROMPT
```

UNUSED:MOVEM.L SP,SYSTAX	SAVE POINTER TO APPLICATION REGISTERS
*	
MOVEM.L A0-A7/D0-D7,-(SP)	SAVE ALL REGISTERS
BSR      SCRLF	MOVE CURSOR TO NEXT LINE
LEA      USEMSG,A5	SET MSG POINTER TO MONMSG
BSR      MESSAGE	CRT<-UNUSED EXCEPTION MSG
MOVE.L   SYSTAX,A5	GET TOP OF STACK AT ENTRY
ADDQ.L  #6,A5	POINT TO STACK FORMAT WORD
MOVE.B   (A5)+,D0	GET FORMAT.HIGH
BSR      OUTPUT_BYTE	OUTPUT FORMAT.HIGH
MOVE.B   (A5),D0	GET FORMAT.LOW
BSR      OUTPUT_BYTE	OUTPUT FORMAT.LOW
BSR      SCRLF	MOVE CURSOR TO NEXT LINE
BSR      REG	DISPLAY REGISTERS
MOVEM.L (SP)+,A0-A7/D0-D7	RESTORE ALL REGISTERS
RTE	
END	

#### **APPENDIX C: MINIMAL SYSTEM DIAGRAMS**

The figures (Figs. C.1 through C.8) contained in this appendix are discussed in Chapter IV. These figures were created using the OrCAD/SDT III computer-aided design (CAD) tool. Each signal's source(s) and/or destination(s) are noted on the diagrams. It is, however, the integration of these various components into a minimal system that comprises the work that is original to this thesis.

### Pull-up Resistors

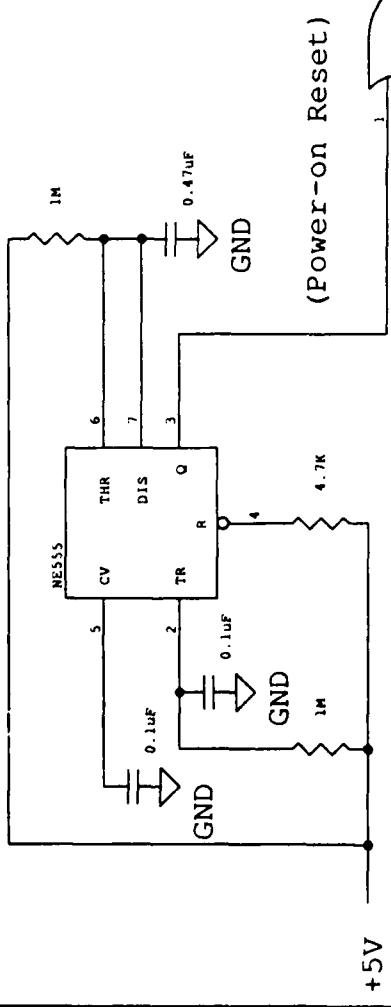


MC68010

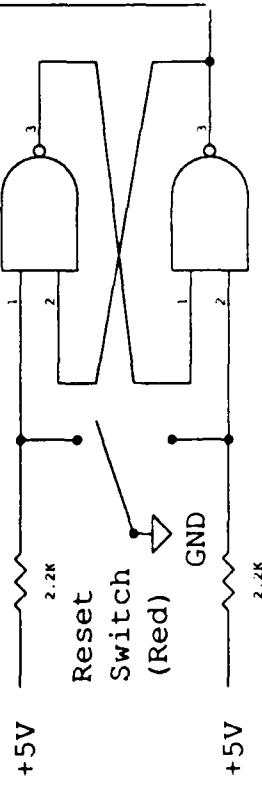
TITLE: Minimal System MC68010  
Microprocessor Circuitry

Figure: C.1

### One-shot Connection



### Debouncing Circuitry



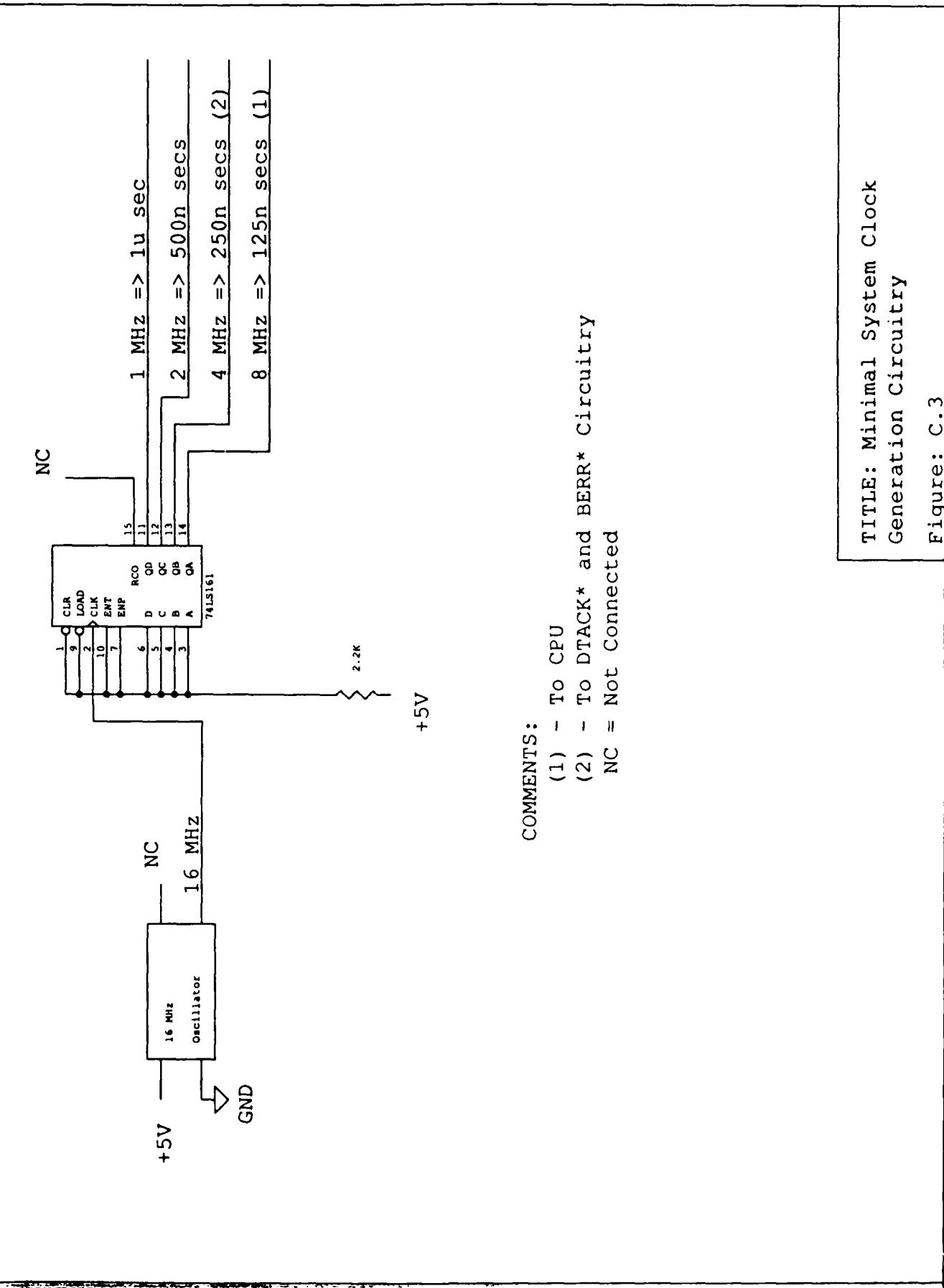
119

### COMMENT:

- (1) - To CPU
- (2) - To CPU and DUART Circuitry

**TITLE: Minimal System HALT\* and RESET\***  
**Generation Circuitry**

**Figure: C.2**

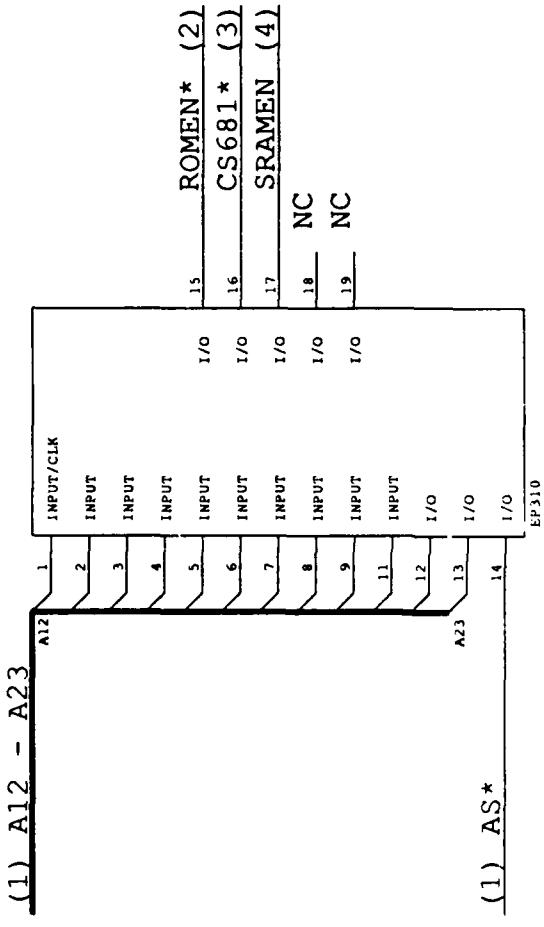


**COMMENTS:**

- (1) - TO CPU
  - (2) - TO DTACK\* and BERR\* Circuitry
- NC = Not Connected

**TITLE: Minimal System Clock Generation Circuitry**

**Figure: C.3**

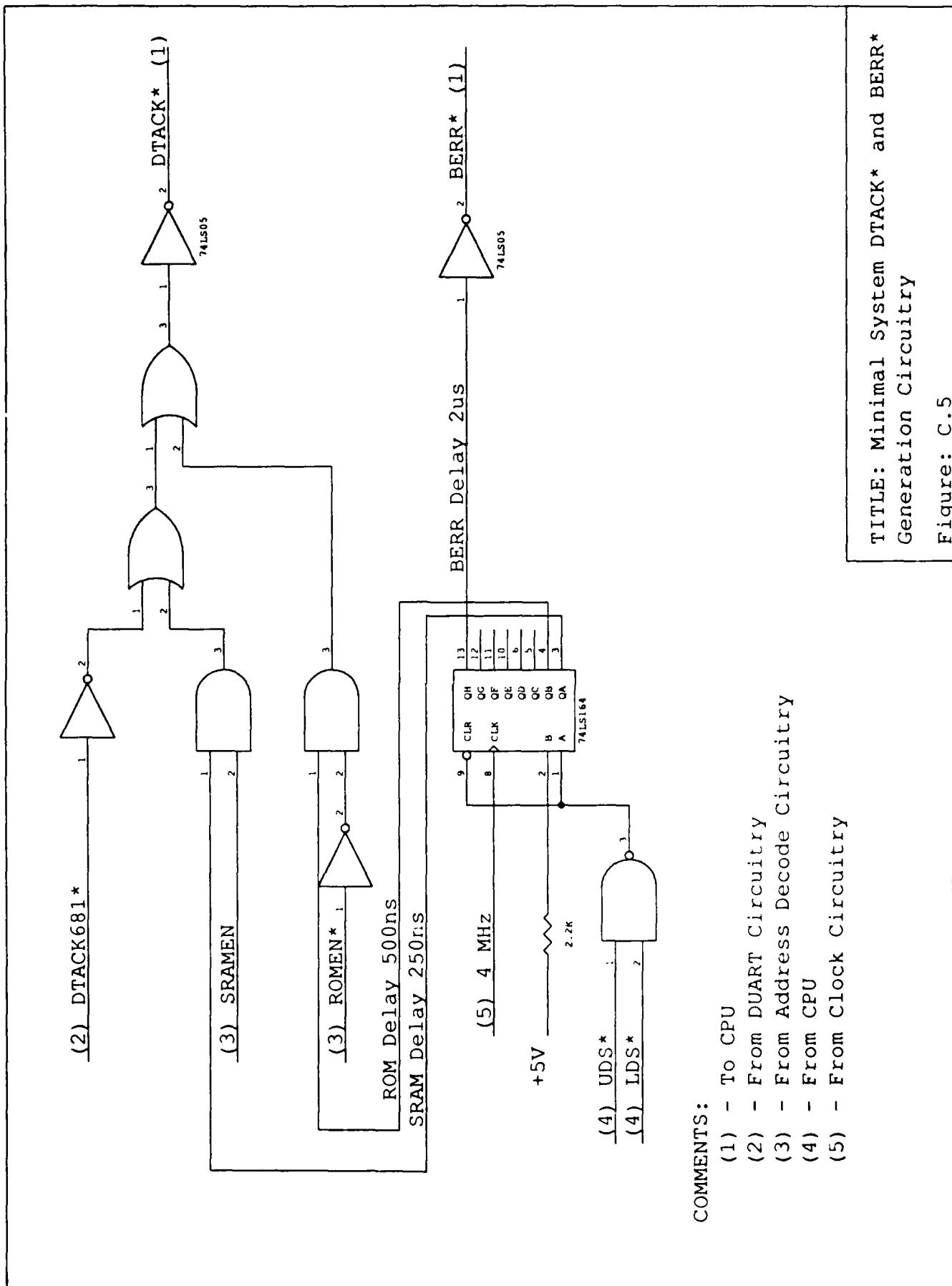


#### COMMENTS:

- (1) - From CPU
  - (2) - ROM Enable; To ROM Circuity and DTACK\* Circuity
  - (3) - Chip Select MC68681 DUART; To DUART Circuity
  - (4) - SRAM Enable; To SRAM Circuity and DTACK\* Circuity
- NC = Not Connected

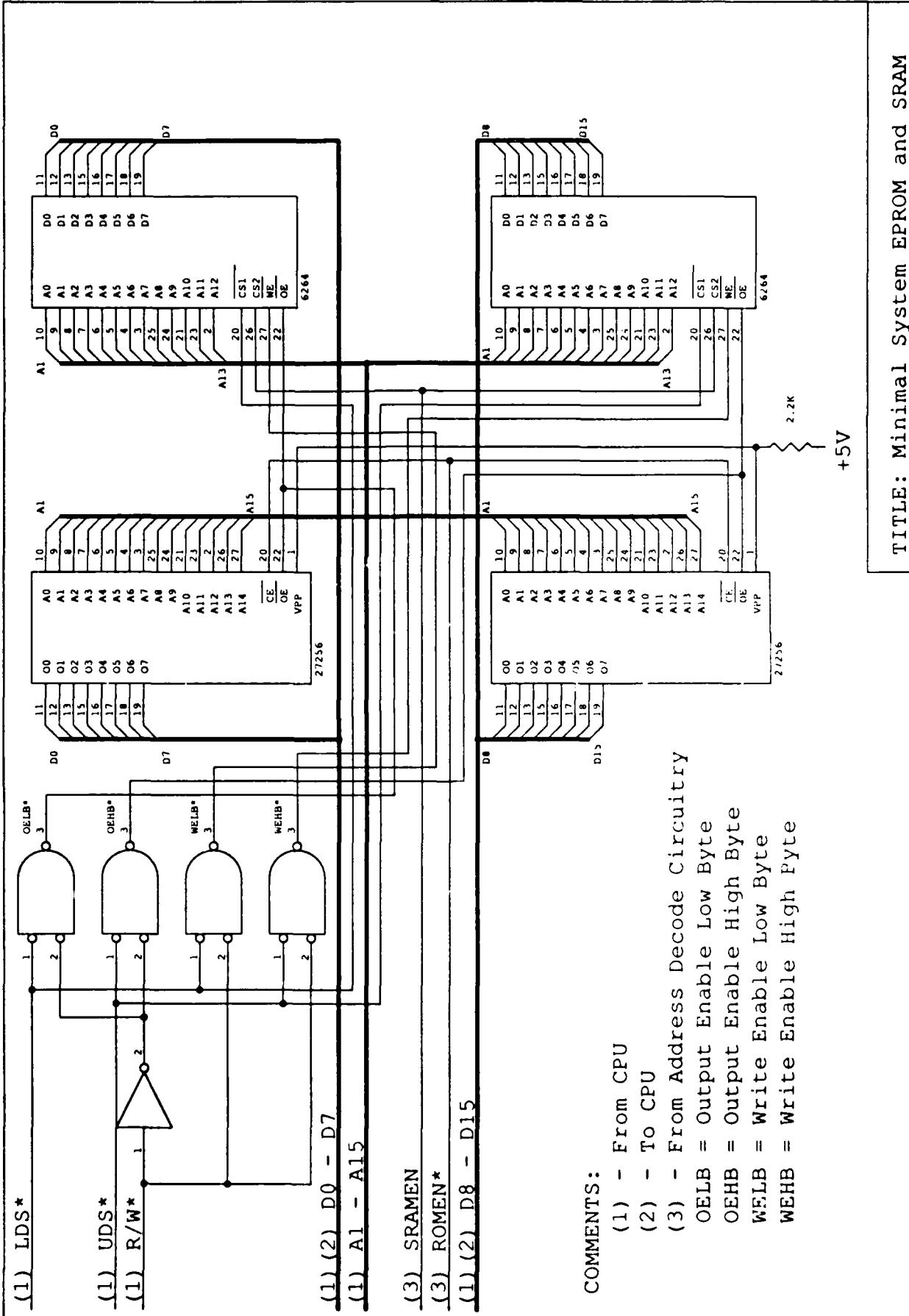
TITLE: Minimal System Address Decode  
Circuity

Figure: C.4



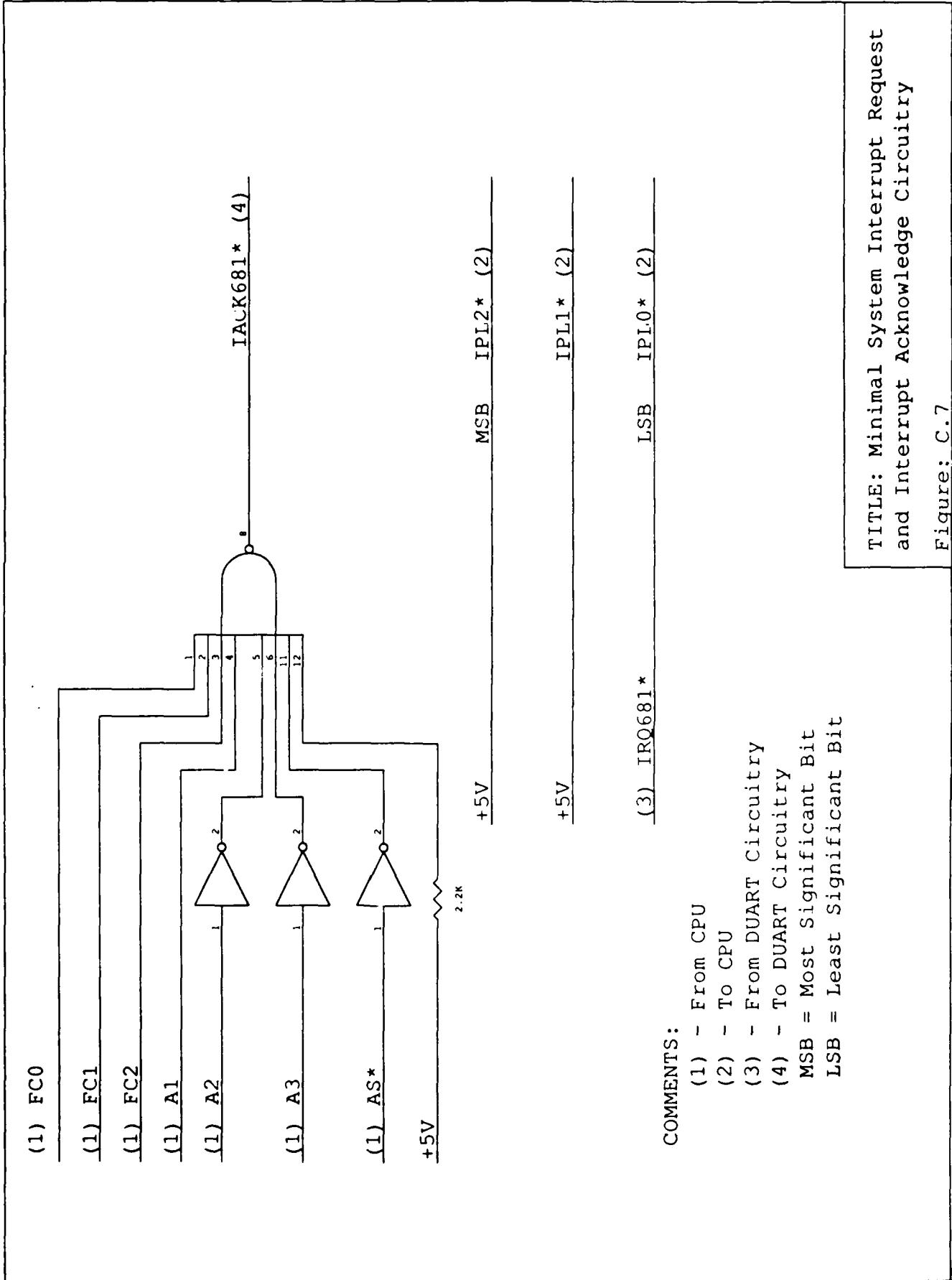
## COMMENTS:

- (1) - To CPU
  - (2) - From DUART Circuitry
  - (3) - From Address Decode Circuitry
  - (4) - From CPU
  - (5) - From Clock Circuitry



**TITLE: Minimal System EPROM and SRAM Circuity**

**Figure: C.6**

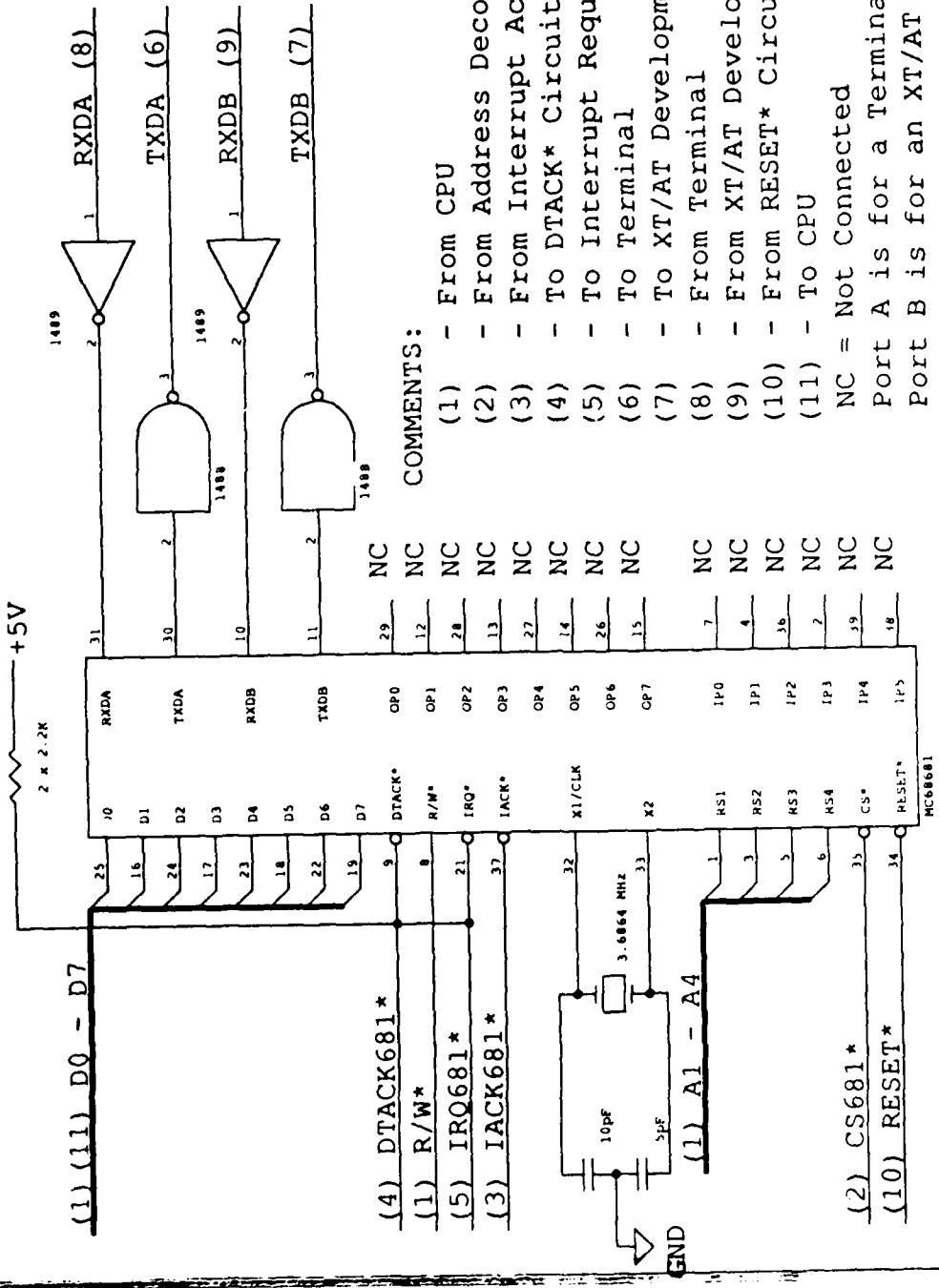


**COMMENTS:**

- (1) - From CPU
  - (2) - To CPU
  - (3) - From DUART Circuitry
  - (4) - To DUART Circuitry
- MSB = Most Significant Bit  
LSB = Least Significant Bit

**TITLE:** Minimal System Interrupt Request and Interrupt Acknowledge Circuitry

**Figure:** C.7



TITLE: Minimal System Dual-port Receiver  
Transmitter Serial Port Circuitry

Figure: C.8

#### **APPENDIX D: MINIMAL SYSTEM'S PROGRAMMABLE LOGIC DEVICE SOURCE CODE**

In order to reduce the chip count, Altera EP310 erasable programmable logic devices (EPLDs) were used within the minimal system. Abel, a logic software design tool by Data I/O Corporation, was used to program Altera EP310 EPLDs [Ref. 16:pp. 2-57 - 2-62]. Abel files provides a high-level representation of the logic to be implemented on the EP310s. The EP310 comes in a 20-pin package. Nine pins are used strictly for input logic; one pin can be used for input logic or as a clocked input; eight pins can be used for input logic or output logic; the remaining two pins are used for Vcc input and ground input.

The following Abel modules were implemented:

- `minimal_system_address_decoder`
- `dtack_and_bus_error_generation`
- `output_enable_write_enable`
- `interrupt_controller`

```

"
" THIS FILE USES DATA I/O'S ABEL DESIGN LANGUAGE
" TO GENERATE A JEDEC FILE TO PROGRAM AN ALTERA
" EP310 ERASABLE PROGRAMMABLE LOGIC DEVICE (EPLD) .
"

MODULE minimal_system_address_decoder FLAG '-X0'
TITLE '68010 ADDRESS DECODER FOR THE MINIMAL SYSTEM'

u61 DEVICE 'E0310'; "Abel V2 must be used for this device.

"DEFINE LABELS ASSOCIATED WITH INPUT AND OUTPUT PINS
"      FOR THE EP310
"- INPUT PINS
    a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,
      as PIN 1,2,3,4,5,6,7,8,9,11,12,13,15;

"- OUTPUT PINS
    cs681,romen,sramen PIN 16,18,19;

"ASSIGNMENT STATEMENTS
    h = 1;      "HIGH
    l = 0;      "LOW
    x = .X.;    "DONT CARE

    ramaddr = [a23,a22,a21,a20,a19,a18,a17,a16,a15,a14,
               x,x,x,x,x,x,x,x,x,x,x];
    romaddr = [a23,a22,a21,a20,a19,a18,a17,a16,x,x,x,x,
               x,x,x,x,x,x,x,x,x];
    duartaddr = [a23,a22,a21,a20,a19,a18,a17,a16,a15,a14,
                 a13,a12,x,x,x,x,x,x,x,x,x,x];

"DEFINE EQUATIONS AS PER MEMORY MAP
"      ! = INVERSION
"      & = AND
"      # = OR
EQUATIONS
    sramen= (ramaddr >= ^h010000)&(ramaddr <= ^h013FFF)&!as;
    !cs681= (duartaddr >= ^h7F7000)&(duartaddr <= ^h7F7FFF)&!as;
    !romen = (romaddr <= ^h00FFFF)&!as;

END minimal_system_address_decoder

```

```

"
" THIS FILE USES DATA I/O'S ABEL DESIGN LANGUAGE
" TO GENERATE A JEDEC FILE TO PROGRAM AN ALTERA
" EP310 ERASABLE PROGRAMMABLE LOGIC DEVICE (EPLD) .
"

MODULE dtack_and_bus_error_generation FLAG '-X0'
TITLE 'DTACK AND BUS ERROR GENERATION FOR THE MINIMAL SYSTEM'

u64 DEVICE 'E0310'; "Abel V2 must be used for this device.

"DEFINE LABELS ASSOCIATED WITH INPUT AND OUTPUT PINS
"    FOR THE EP310
"    - INPUT PINS
        berr_delay,rom_delay,sram_delay,romen,
        dtack681,sramen PIN 1,8,9,11,13,16;

"    - OUTPUT PINS
        dtack,berr PIN 18,19;

"ASSIGNMENT STATEMENTS
    h = 1;      "HIGH
    l = 0;      "LOW
    x = .X.;    "DONT CARE

"DEFINE EQUATIONS
"  NOTE: ! = INVERSION
"        & = AND
"        # = OR
EQUATIONS
dtack=(!dtack681) #(sramen&sram_delay) # (!romen&rom_delay);
berr = berr_delay;

END dtack_and_bus_error_generation

```

```

"
" THIS FILE USES DATA I/O'S ABEL DESIGN LANGUAGE
" TO GENERATE A JEDEC FILE TO PROGRAM AN ALTERA
" EP310 ERASABLE PROGRAMMABLE LOGIC DEVICE (EPLD) .
"

MODULE output_enable_write_enable FLAG '-X1'
TITLE 'SRAM WRITE ENABLE AND SRAM AND ROM OUTPUT ENABLES FOR
      THE MINIMAL SYSTEM'

u63 DEVICE 'E0310';"Abel V2 must be used for this device.

"DEFINE LABELS ASSOCIATED WITH INPUT AND OUTPUT PINS
"      FOR THE EP310
"- INPUT PINS
rw,win,uds,lds,mas,as,pudsi,pldsi PIN 1,2,3,4,5,6,8,9;
"- OUTPUT PINS
oelb,weu34,weu35,oehb,pudso,pldso,pas
      PIN 13,14,15,16,17,18,19;

"ASSIGNMENT STATEMENTS
h = 1;      "HIGH
l = 0;      "LOW
x = .X.;    "DONT CARE

"DEFINE EQUATIONS
" NOTE:   ! = INVERSION
"       & = AND
"       # = OR
"       rw = read
"       !rw = write
EQUATIONS
!weu34 = !rw & !pldsi;
!weu35 = !rw & !pudsi;
!oehb = rw & !pudsi;
!oelb = rw & !pldsi;

END output_enable_write_enable

```

```

"
" THIS FILE USES DATA I/O'S ABEL DESIGN LANGUAGE
" TO GENERATE A JEDEC FILE TO PROGRAM AN ALTERA
" EP310 ERASABLE PROGRAMMABLE LOGIC DEVICE (EPLD).
"

MODULE interrupt_controller FLAG '-X1'
TITLE 'INTERRUPT CONTROLLER FOR THE MINIMAL SYSTEM'

"THIS IS NOT UPWARDS COMPATIBLE FOR THE FULLY INTEGRATED SYSTEM

u00 DEVICE 'E0310'; "Abel V2 must be used for this device.

"DEFINE LABELS ASSOCIATED WITH INPUT AND OUTPUT PINS
"    FOR THE EP310
"    - INPUT PINS
        a1,a2,a3,as,irq681,fc1,fc2,fc3 PIN 1,2,3,4,5,6,7,8;
"    - OUTPUT PINS
        ip10,ip11,ip12,irack681 PIN 16,17,18,19;

"ASSIGNMENT STATEMENTS
    h = 1;      "HIGH
    l = 0;      "LOW
    x = .X.;    "DONT CARE

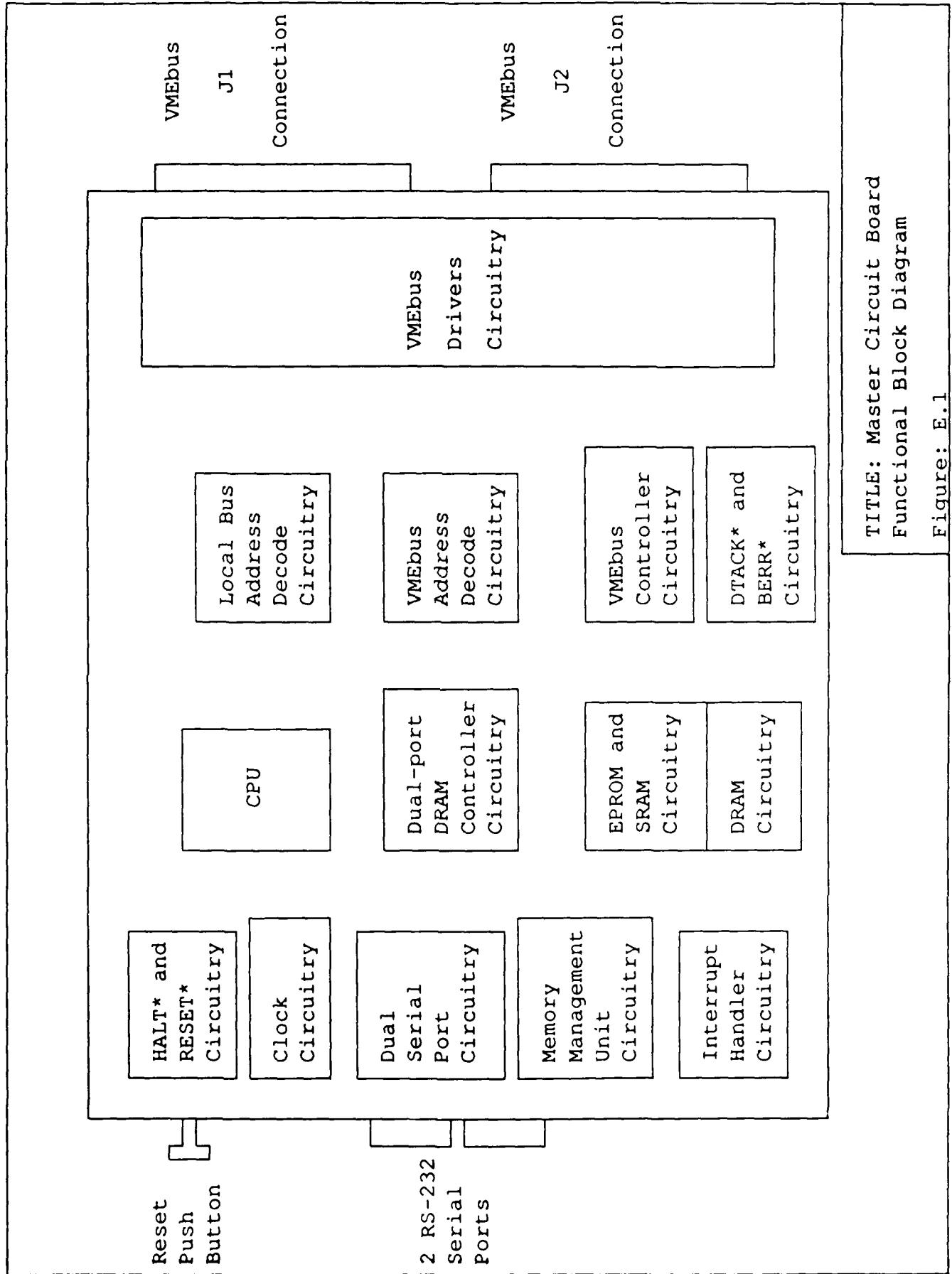
"DEFINE EQUATIONS
" NOTE: ! = INVERSION
"       & = AND
"       # = OR
EQUATIONS
!irack681 = a1 & !a2 & !a3 & !as & fc1 & fc2 & fc3;
ip10     = h;
ip11     = h;
ip12     = irq681;

END interrupt_controller

```

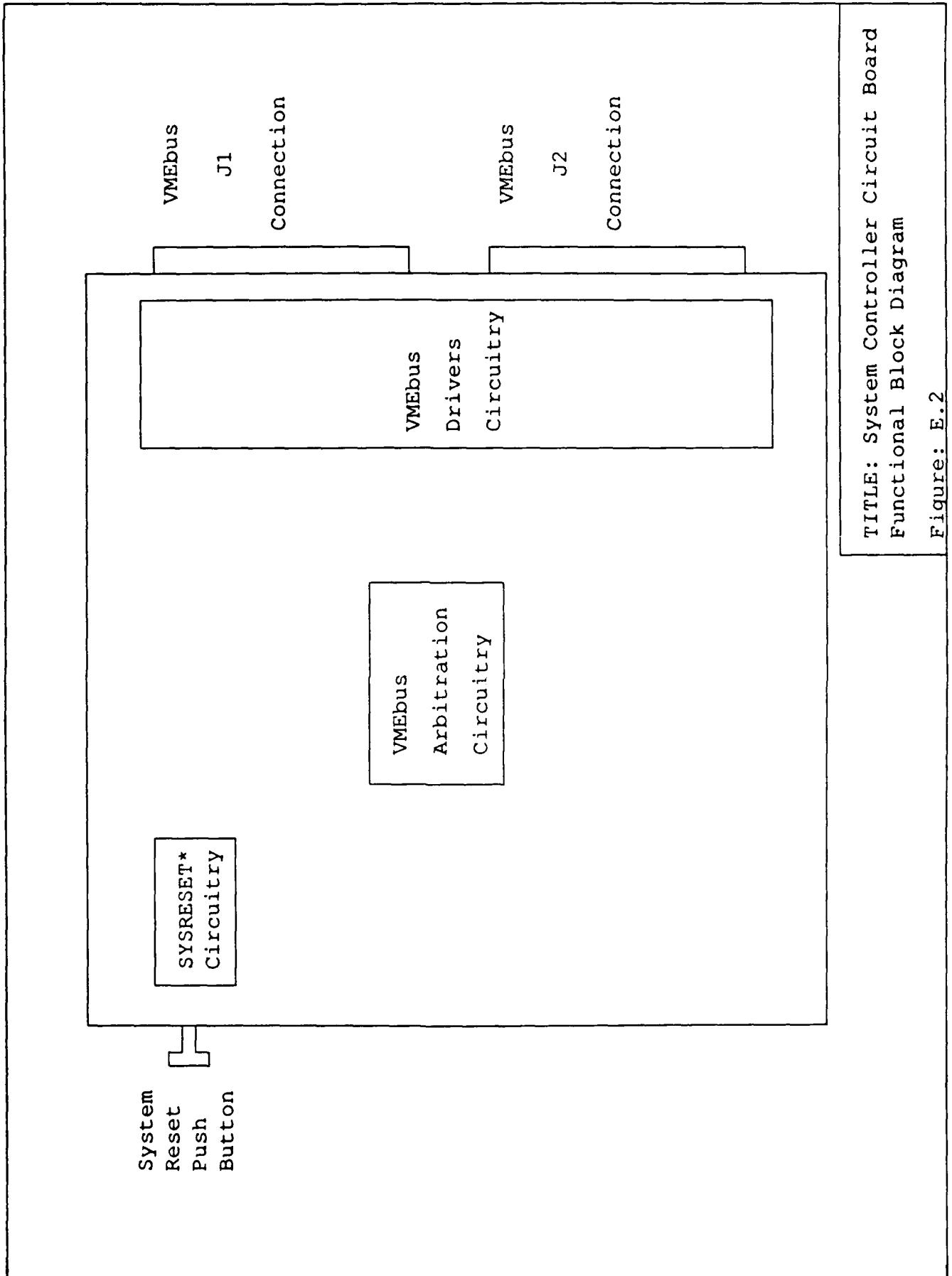
#### **APPENDIX E: SYSTEM DIAGRAMS**

In this appendix are the wiring diagrams which implement the master circuit board subsystem and system controller subsystem which are discussed in Chapter IV. These diagrams were produced by the OrCAD/SDT III computer-aided design (CAD) tool. It is, however, the integration of these various components into a multi-processor system that comprises the work that is original to this thesis.

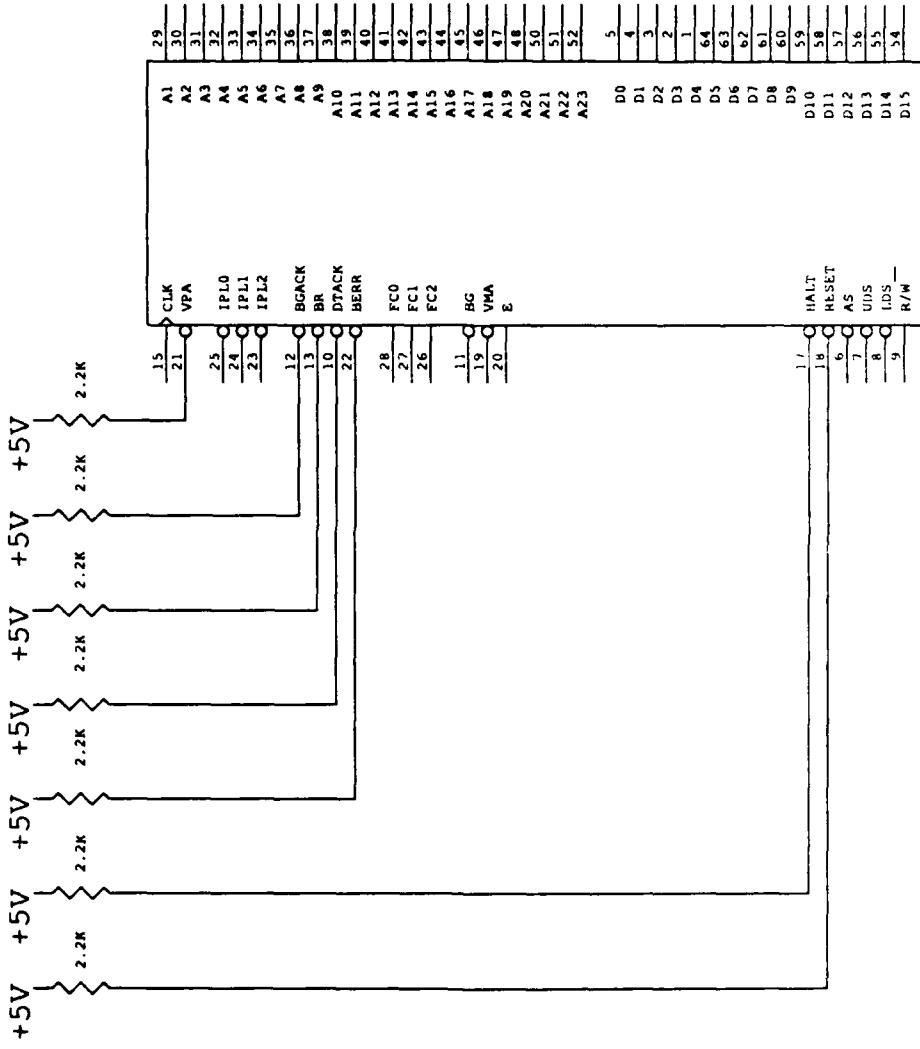


TITLE: Master Circuit Board  
Functional Block Diagram

Figure: E.1



### Pull-up Resistors

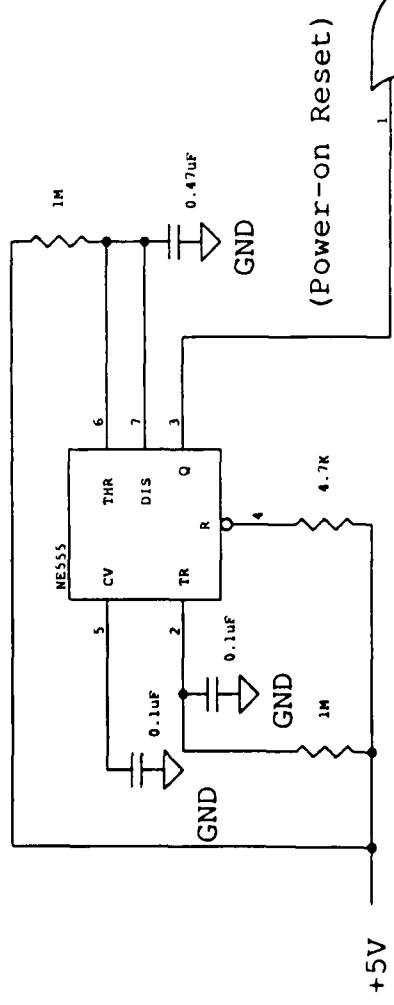


MC68010

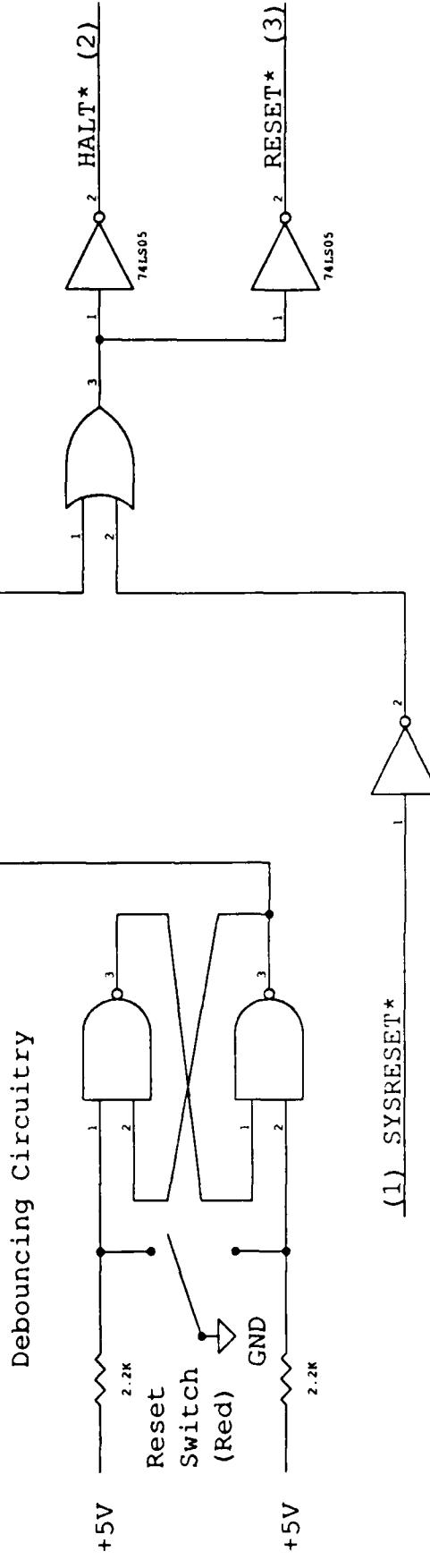
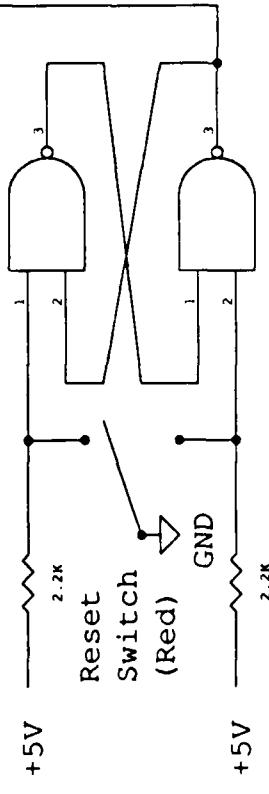
TITLE: MC68010 Microprocessor Circuitry

Figure: E.3

### One-shot Connection



### Debouncing Circuitry

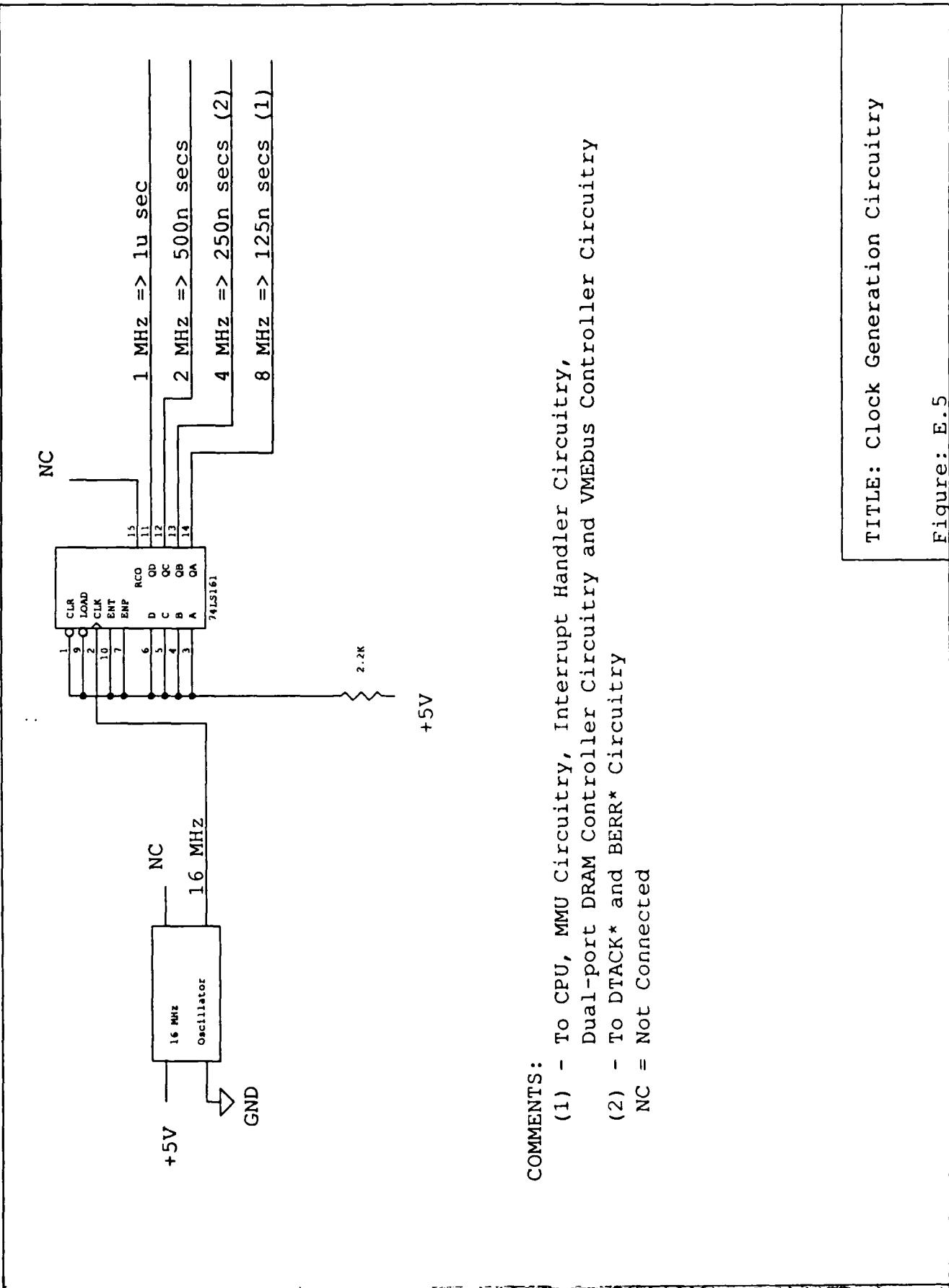


### COMMENTS:

- (1) - From VMEbus
- (2) - To CPU
- (3) - To CPU, MMU Circuitry, DUART Circuitry, Interrupt Handler Circuitry and VMEbus Controller Circuitry

TITLE: HALT\* and RESET\* Generation  
Circuitry

Figure: E.4

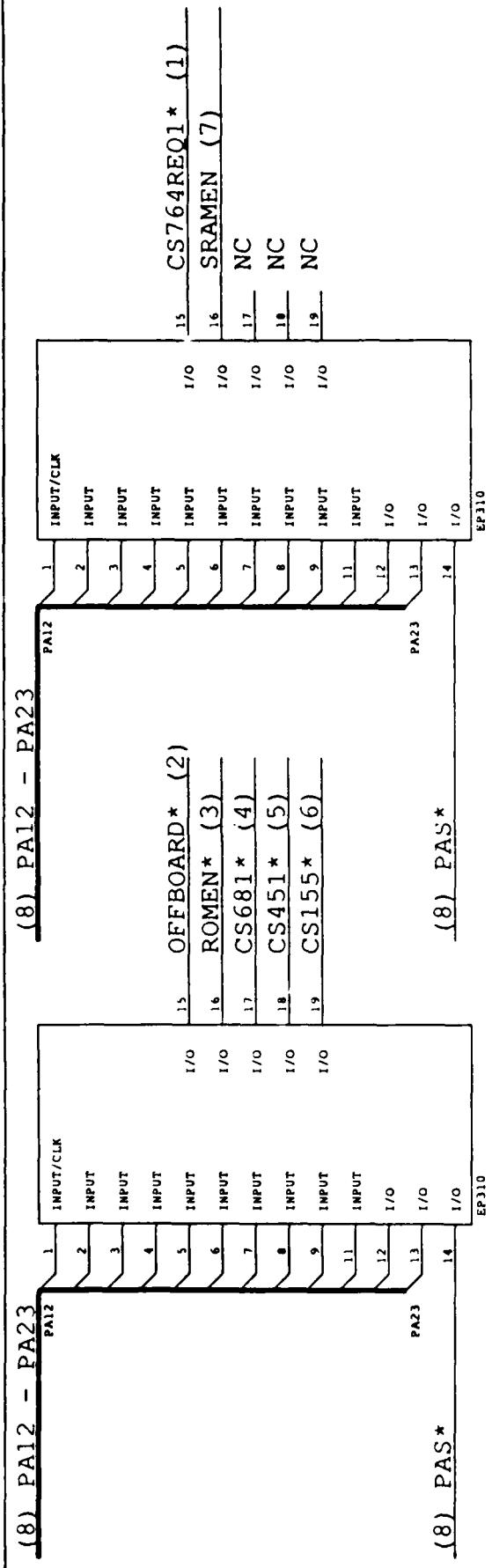


**COMMENTS:**

- (1) - To CPU, MMU Circuitry, Interrupt Handler Circuitry,  
Dual-port DRAM Controller Circuitry and VMEbus Controller Circuitry
  - (2) - To DTACK\* and BERR\* Circuitry
- NC = Not Connected

TITLE: Clock Generation Circuitry

Figure: E.5



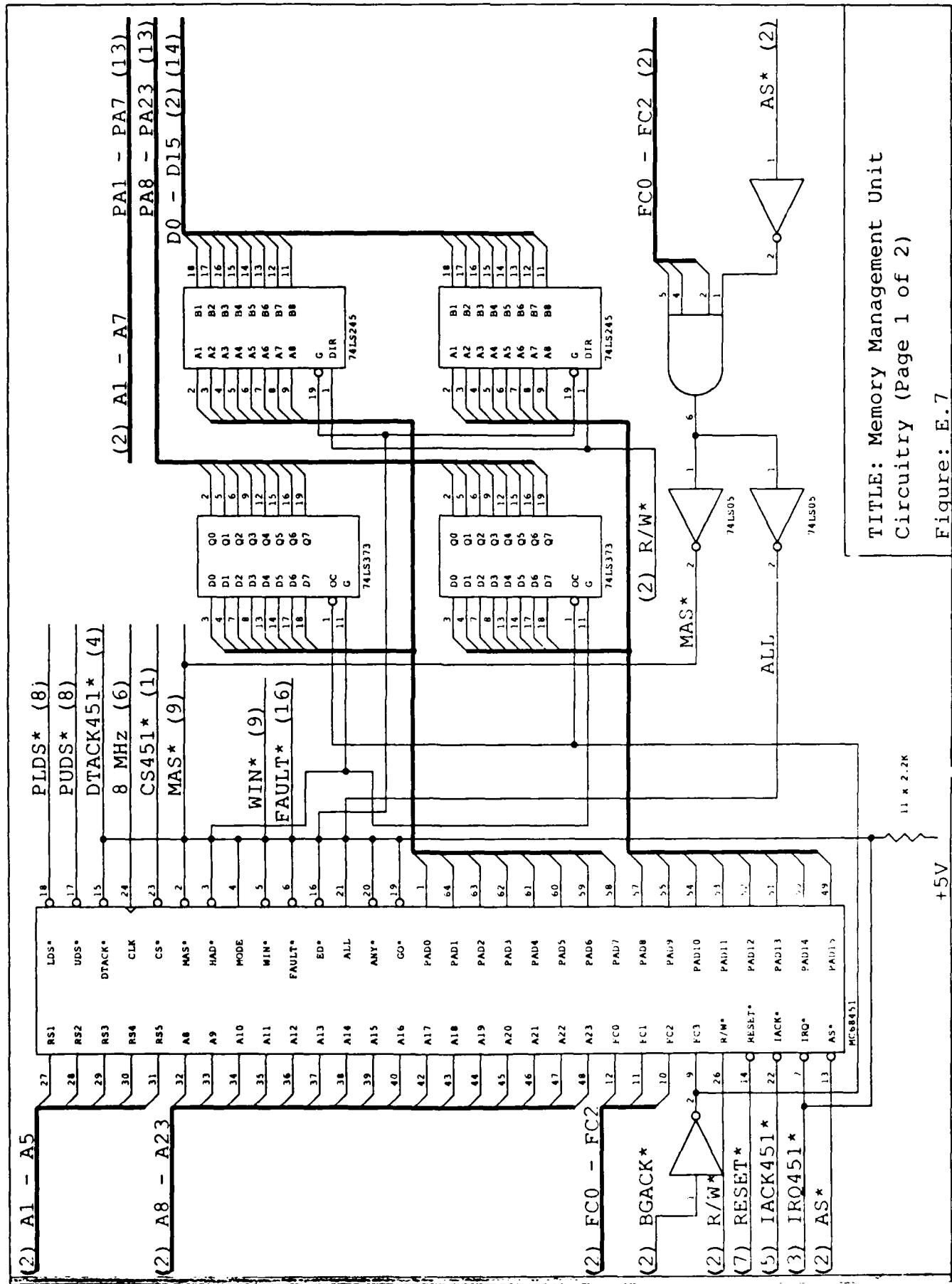
### COMMENTS:

- (1) - Chip Select Request Line 1 of 74F764; To Dual-port DRAM Controller Circuity
  - (2) - Off Board Resource; To VMEbus Controller Circuity and BERR\* Circuity
  - (3) - ROM Enable; To EPROM Circuity and DTACK\* Circuity
  - (4) - Chip Select MC68681 DUART; To DUART Circuity
  - (5) - Chip Select MC68451 MMU; To MMU Circuity
  - (6) - Chip Select SCN6815; Interrupt Handler Hardware; To Interrupt Handler Circuity
  - (7) - SRAM Enable; To SRAM Circuity and DTACK\* Circuity
  - (8) - From MMU Circuity

NC = Not Connected

TITLE: Local Bus Address Decode  
Circuitry

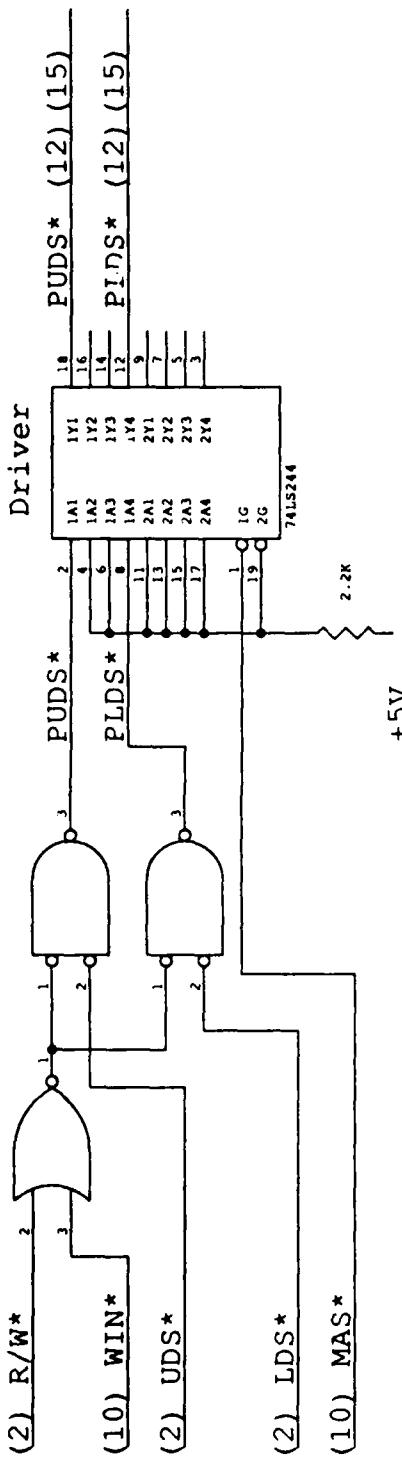
Figure: E.6



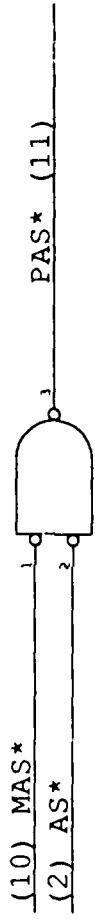
TITLE: Memory Management Unit  
Circuitry (Page 1 of 2)

Figure: E.7

### Physical Data Strobe Generator Circuitry



### Physical Address Strobe Generator Circuitry



#### COMMENTS:

- (1) - From Local Bus Address Decode Circuitry
- (2) - From CPU
- (3) - To Interrupt Handler Circuitry
- (4) - To DTACK\* Circuitry
- (5) - From Interrupt Handler Circuitry
- (6) - From Clock Circuitry
- (7) - From RESET\* Circuitry
- (8) - From Physical Data Strobe Circuitry, Page 2 of 2
- (9) - To Page 2 of 2
- (10) - From Page 1 of 2
- (11) - To Devices Requiring an Address Strobe
- (12) - To Devices Requiring Data Strobes
- (13) - To Devices Requiring Address Lines
- (14) - To CPU
- (15) - To Page 1 of 2
- (16) - To BERR\* Circuitry

TITLE: Memory Management Unit  
Circuitry (Page 2 of 2)

Figure: E.8

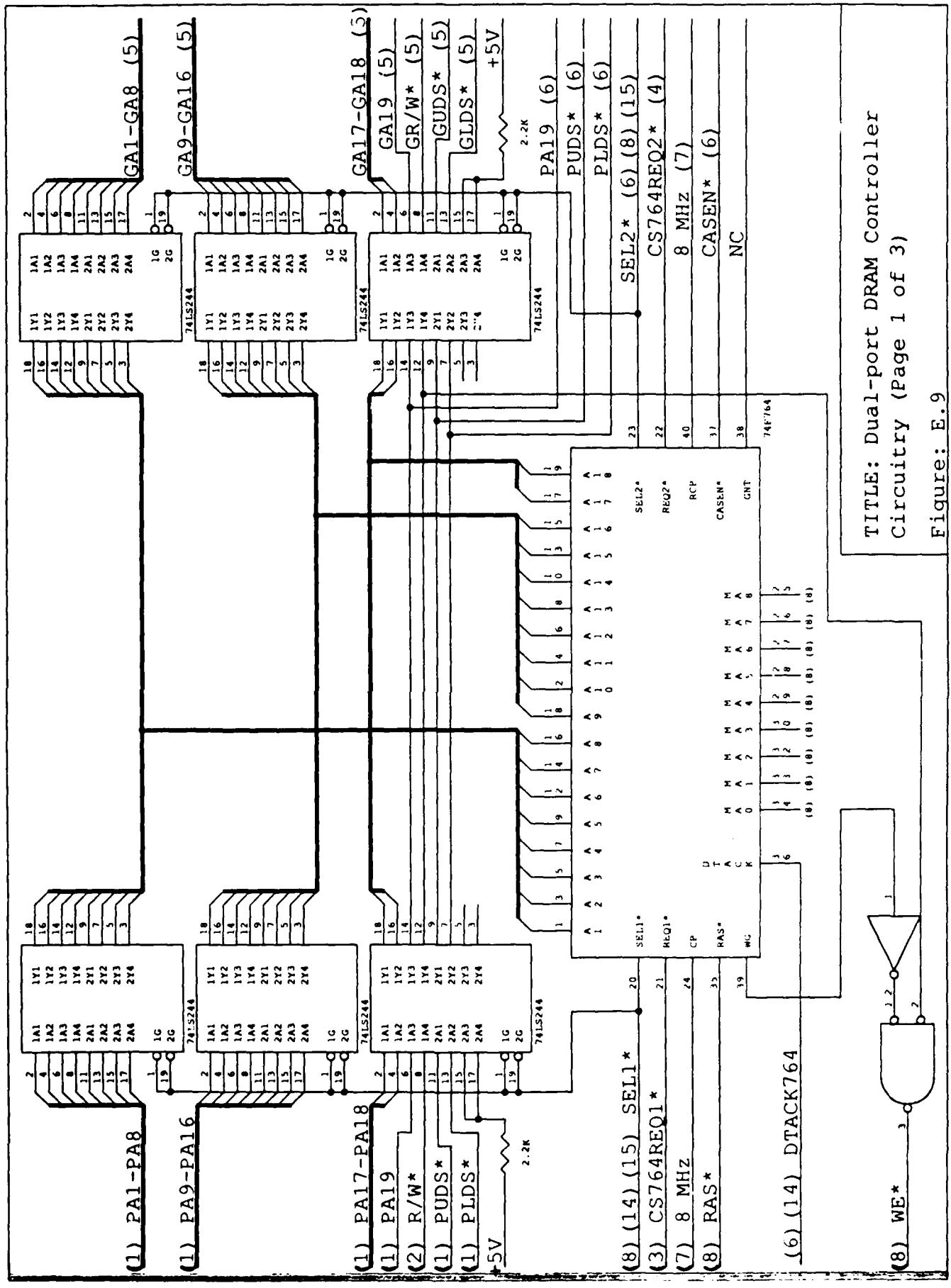
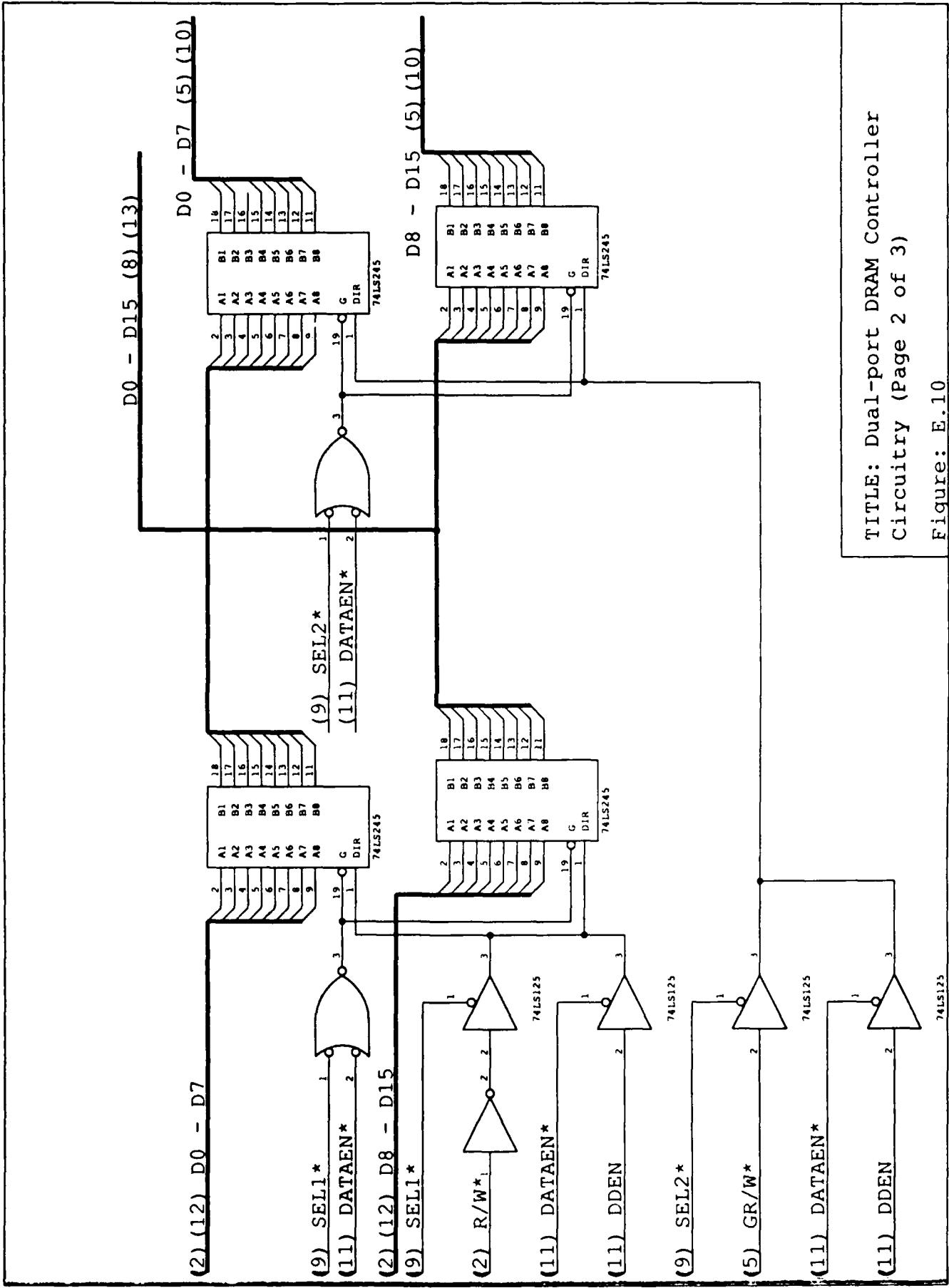
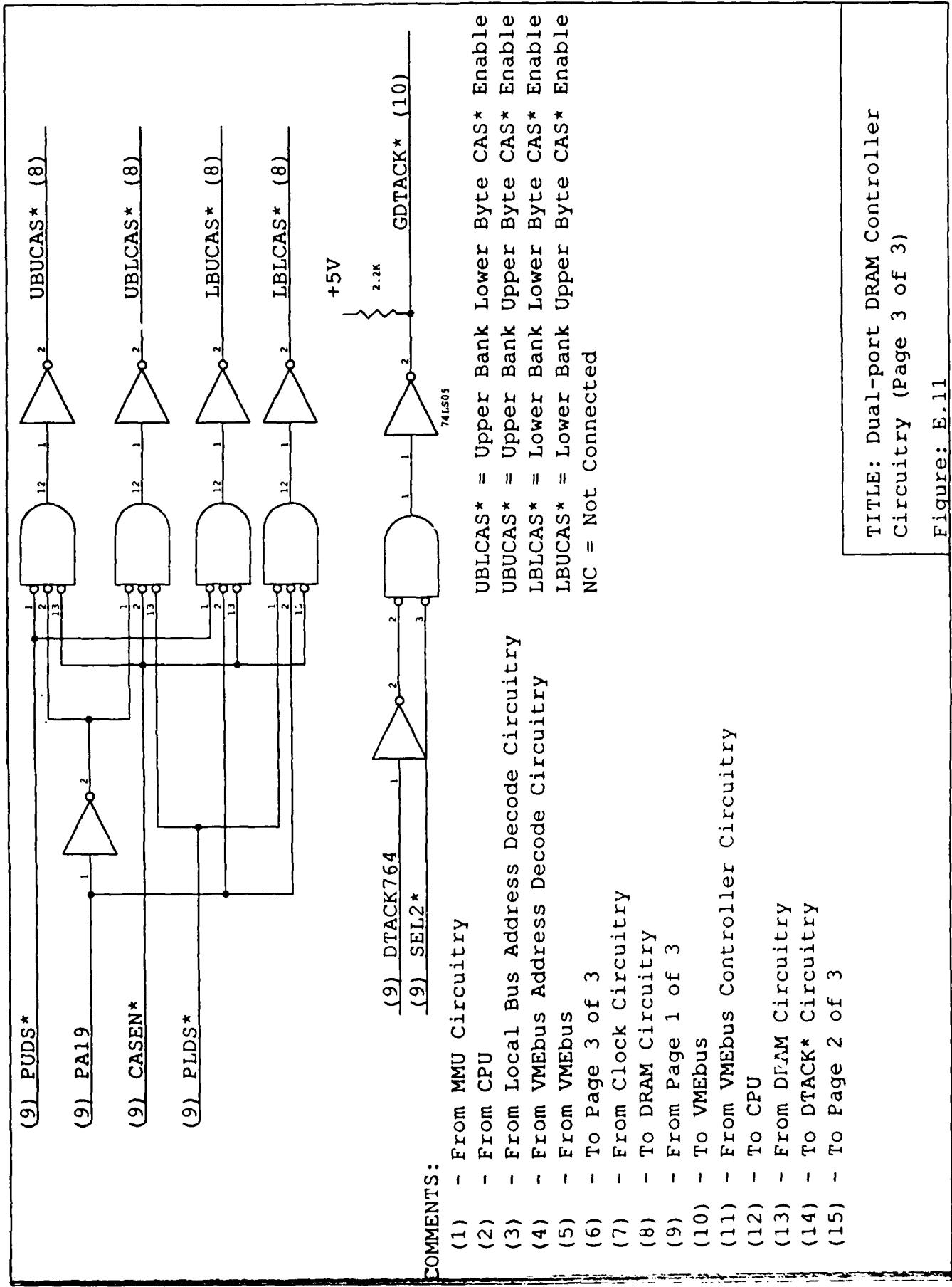


Figure: E.9

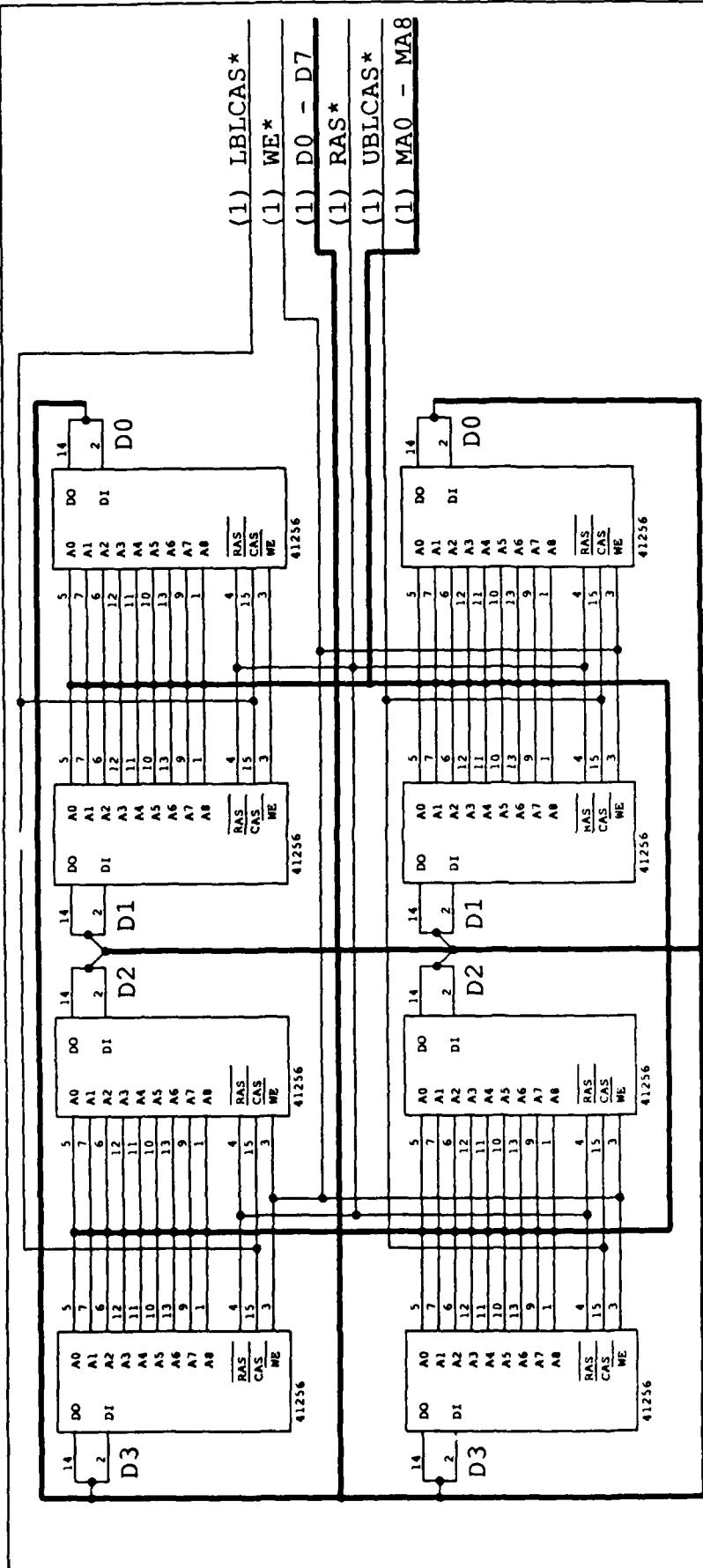


TITLE: Dual-port DRAM Controller  
Circuitry (Page 2 of 3)

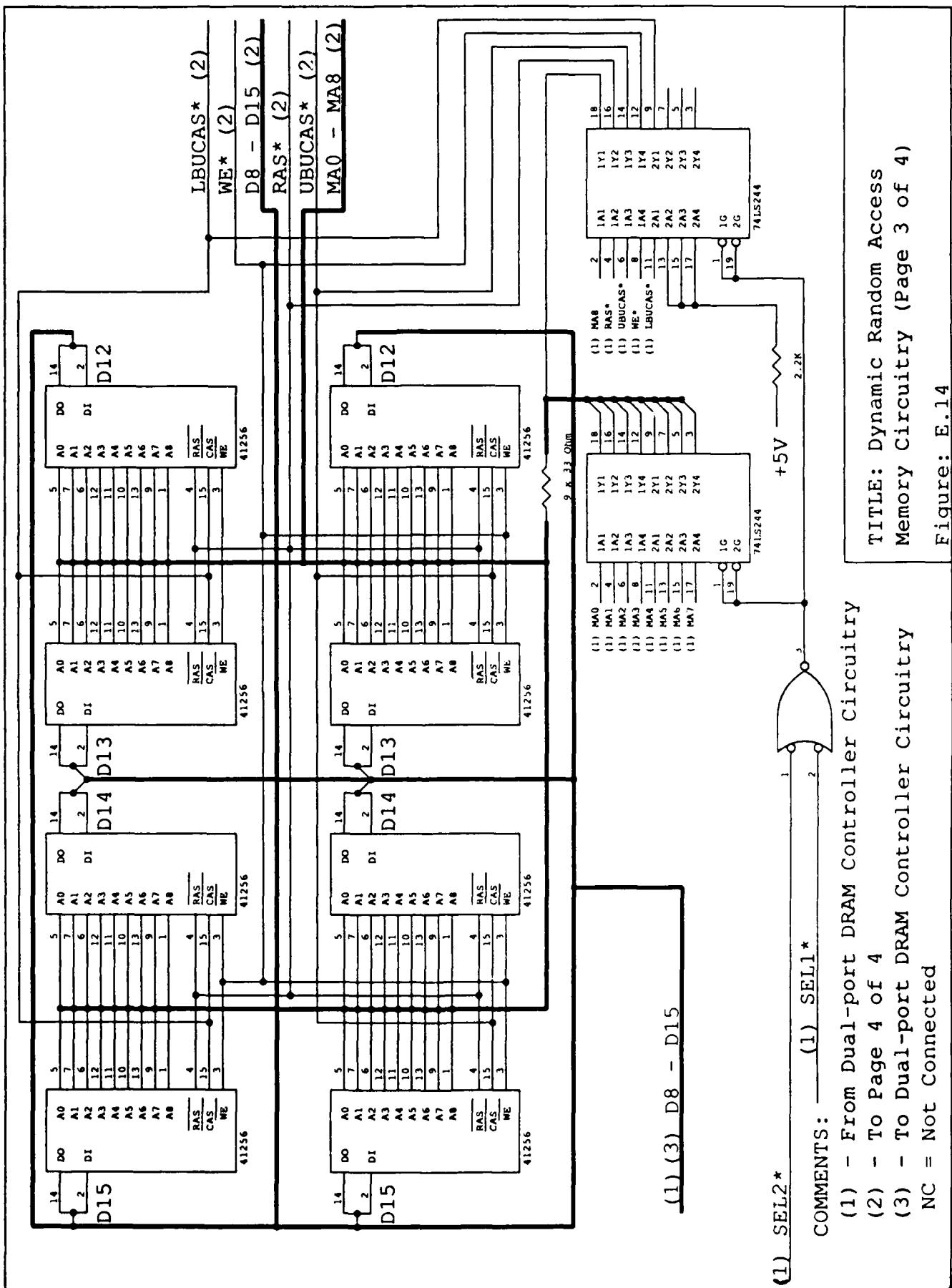
Figure: E.10

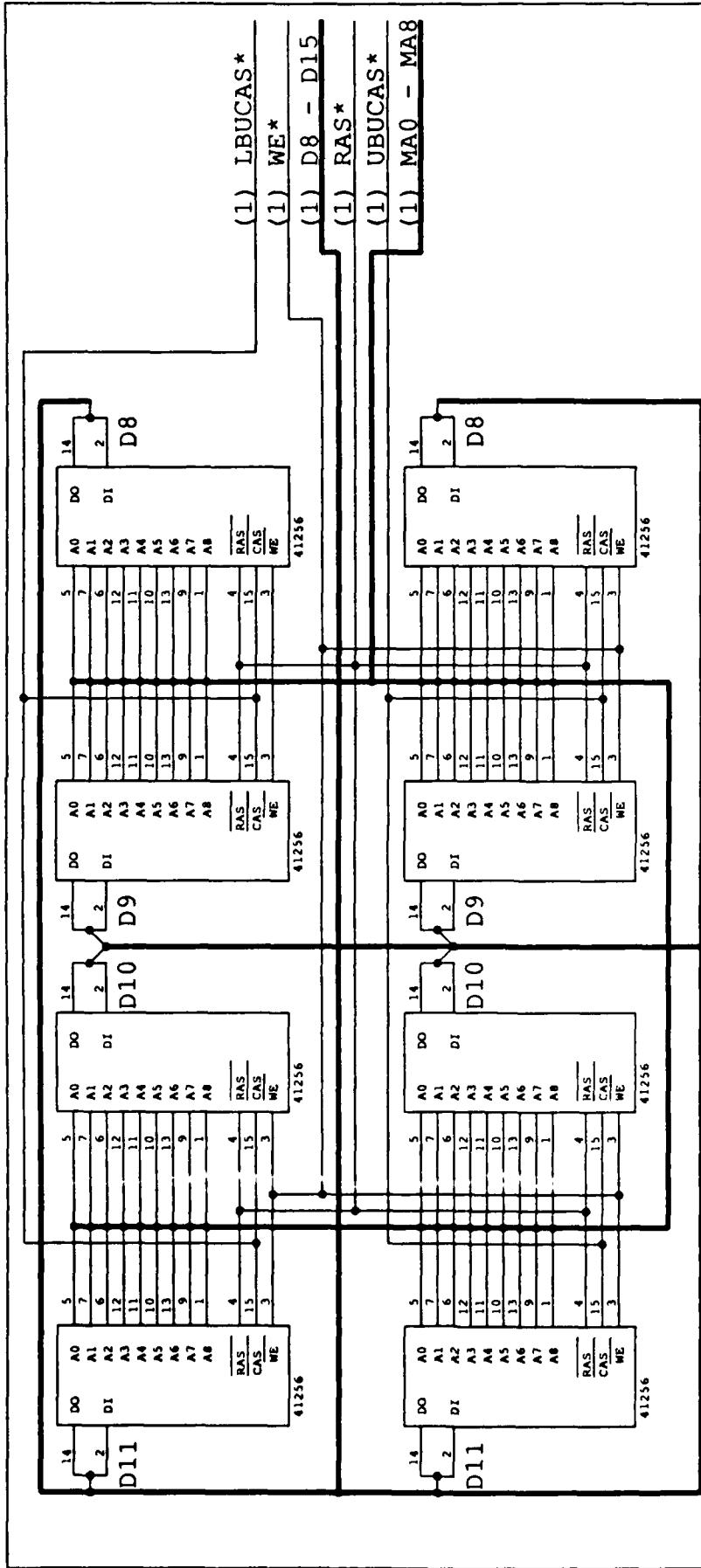






COMMENT:  
 (1) - From Page 1 of 4



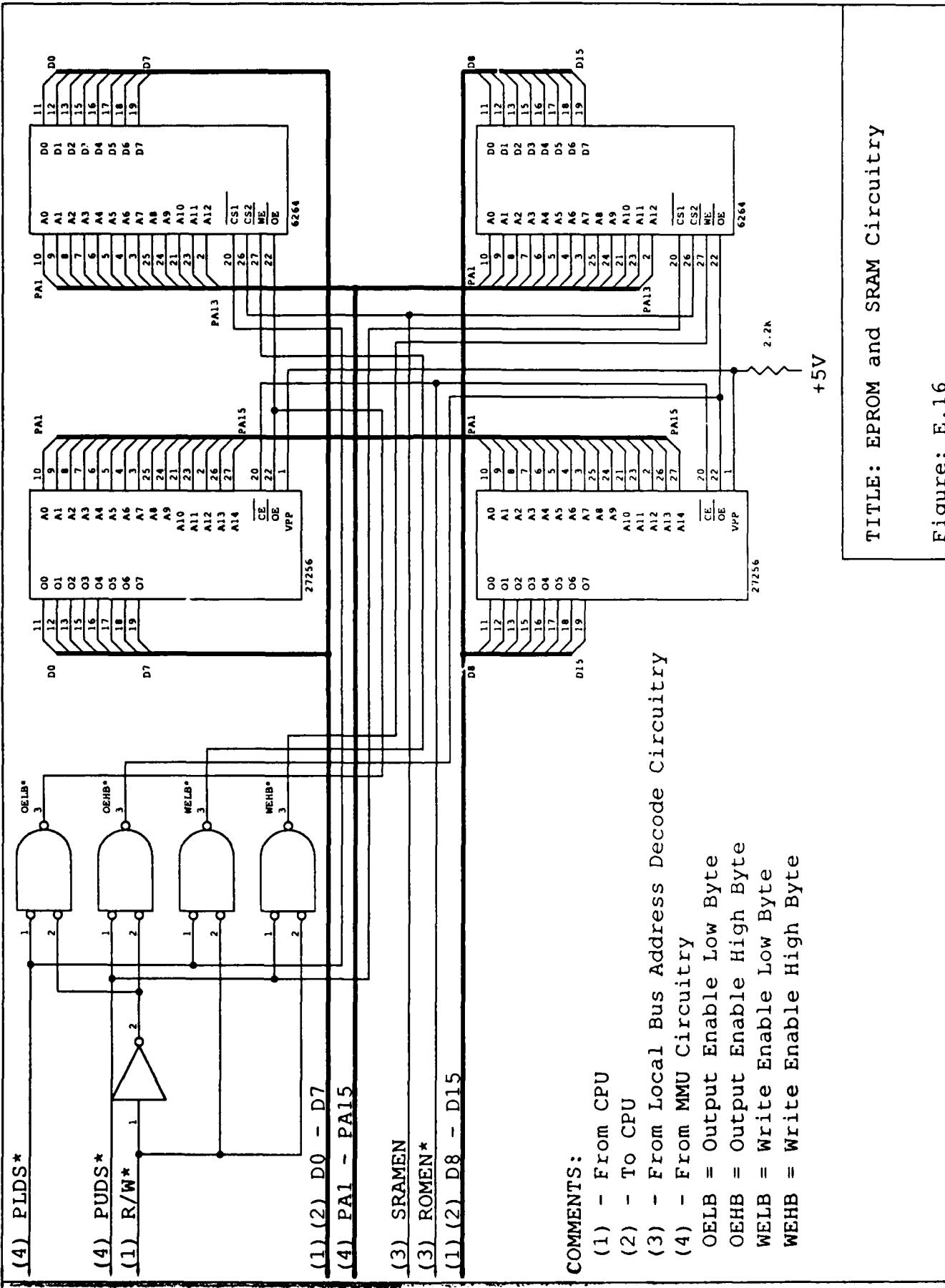


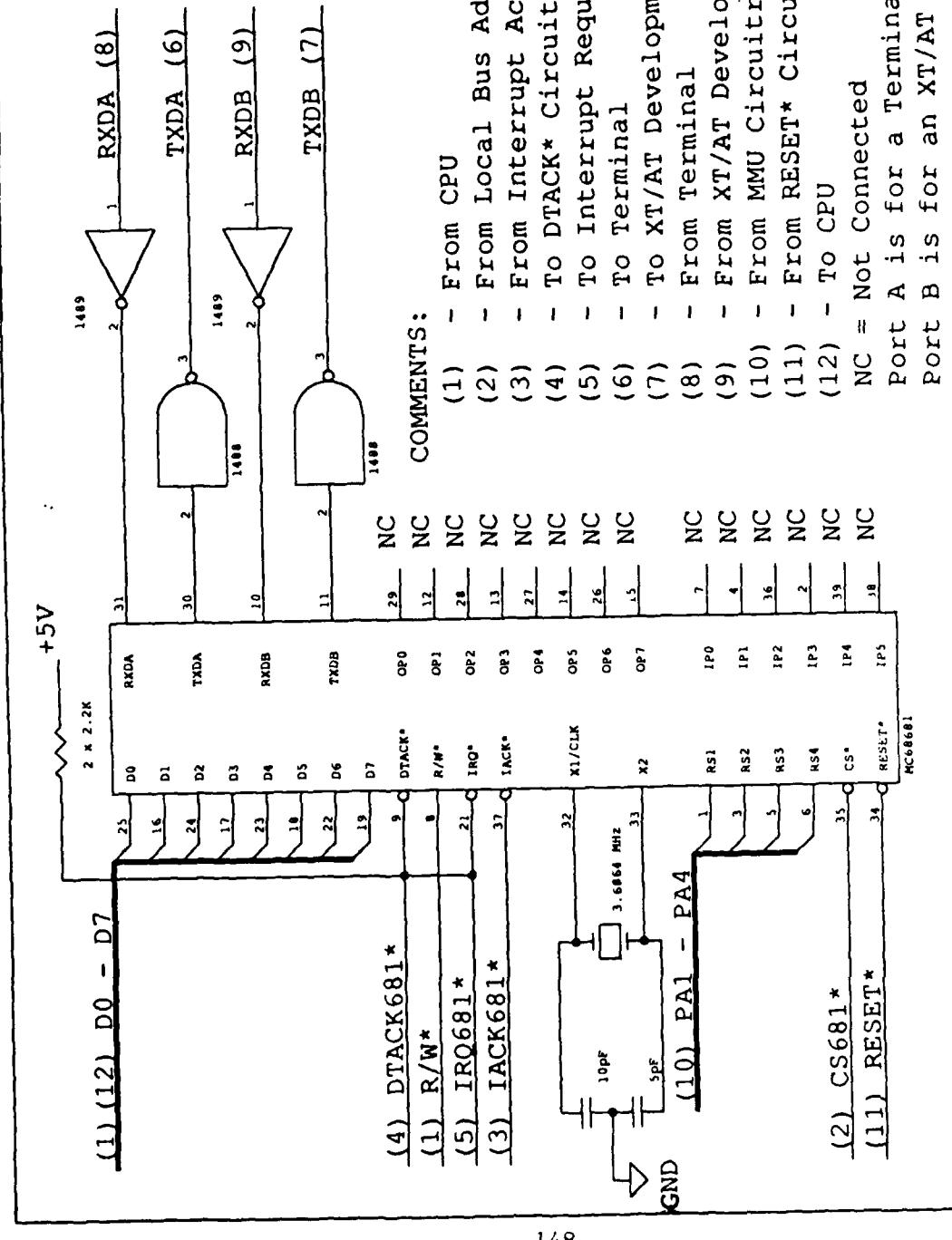
COMMENT:

(1) - From Page 3 of 4

TITLE: Dynamic Random Access  
Memory Circuitry (Page 4 of 4)

Figure: E.15





**TITLE:** Dual-port Asynchronous Receiver/  
Transmitter Serial Port Circuitry

Figure: E.17

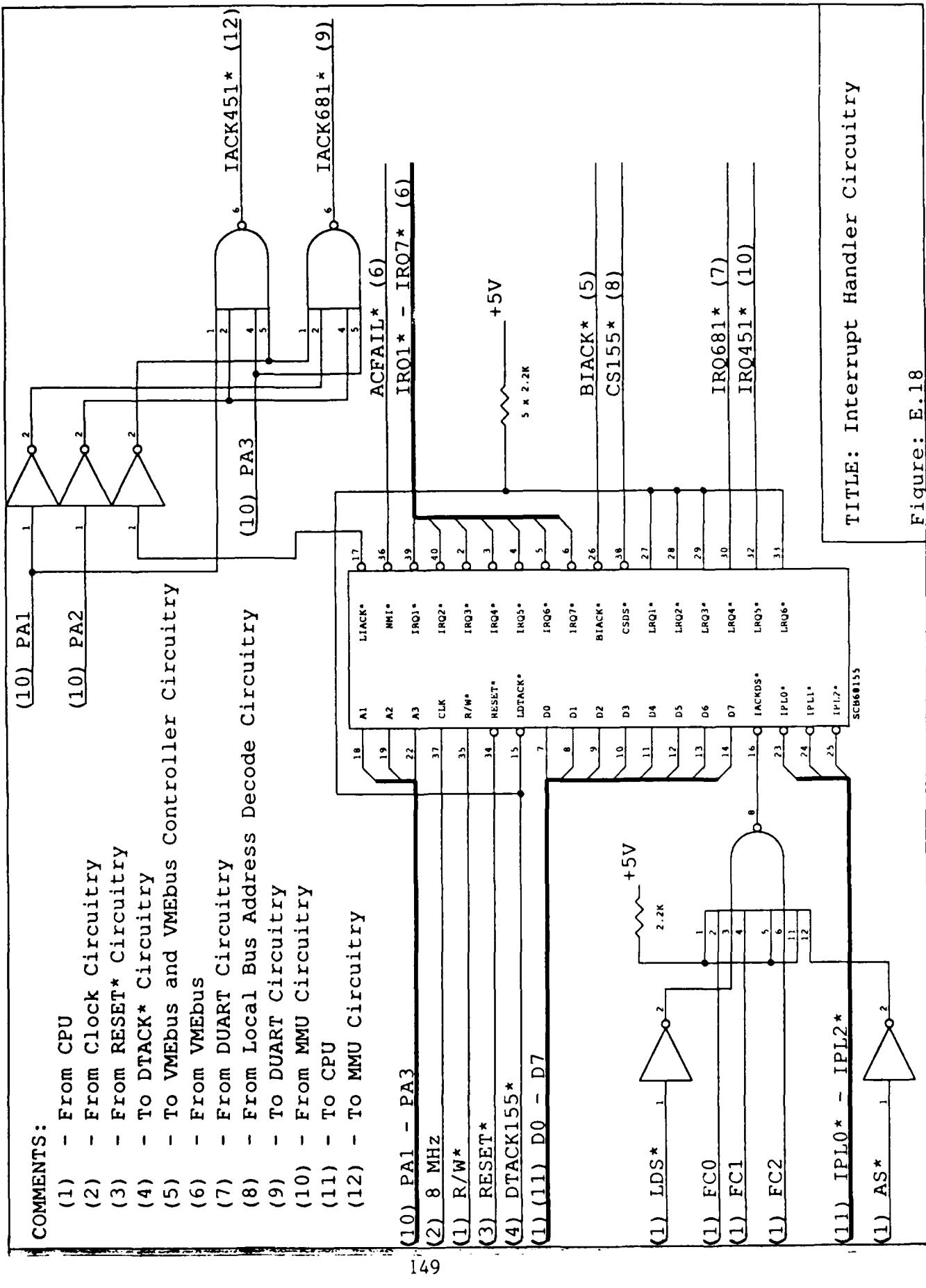
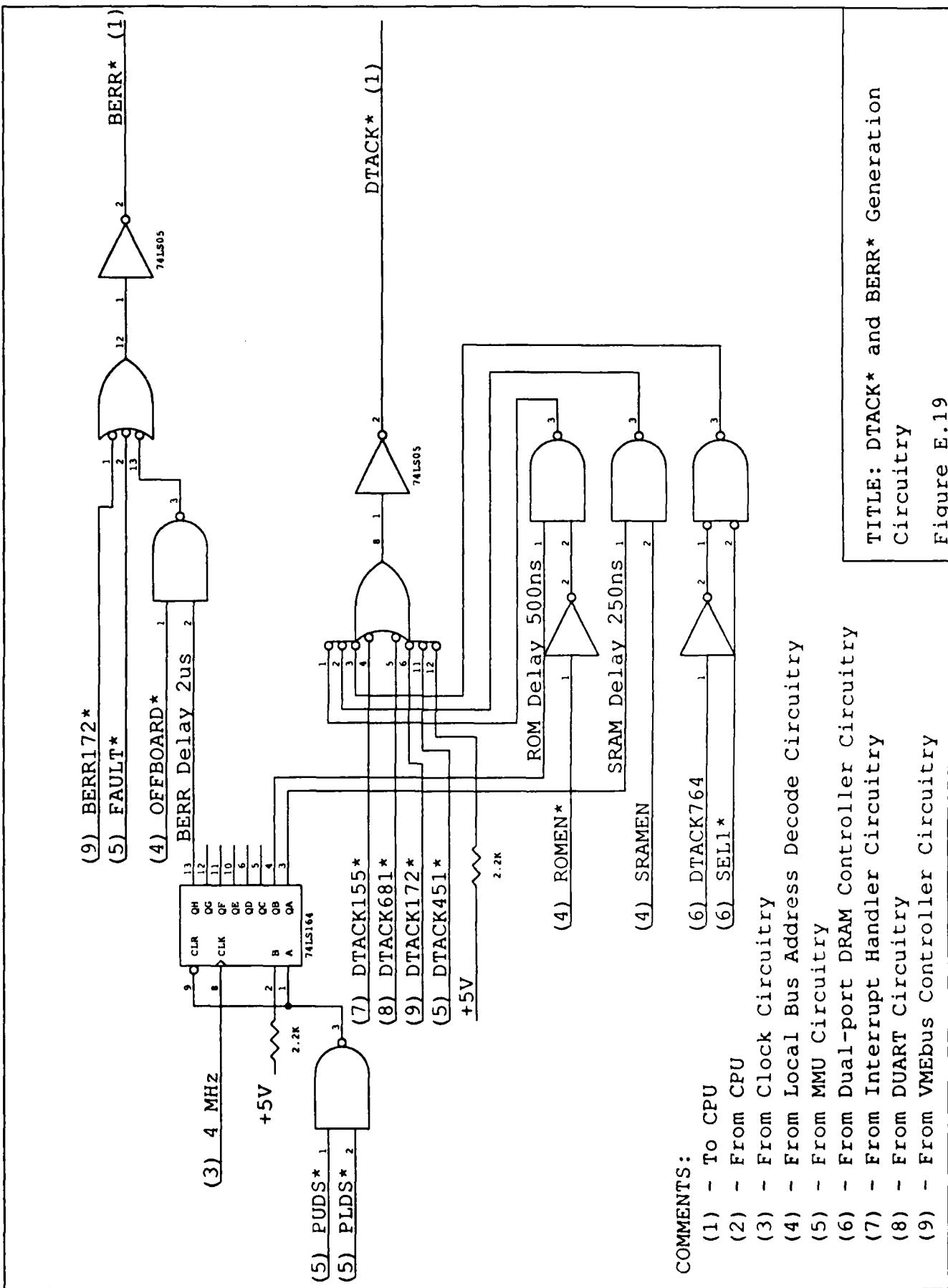
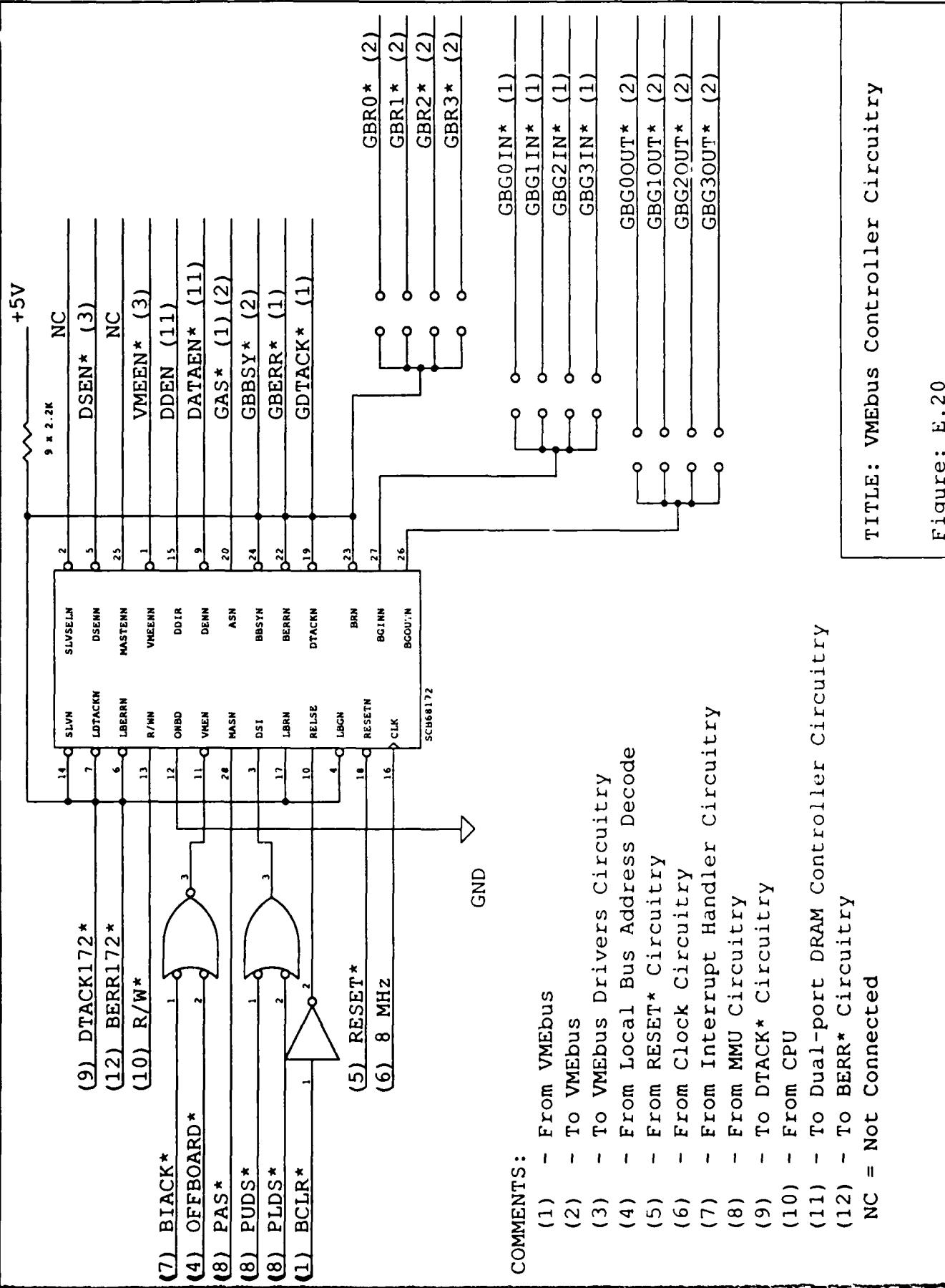
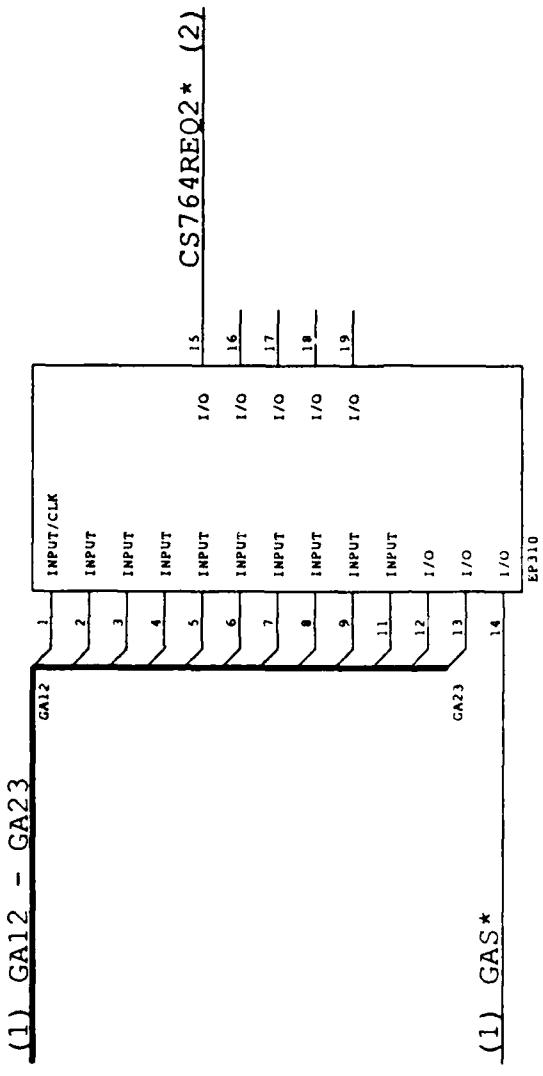


Figure: E.18





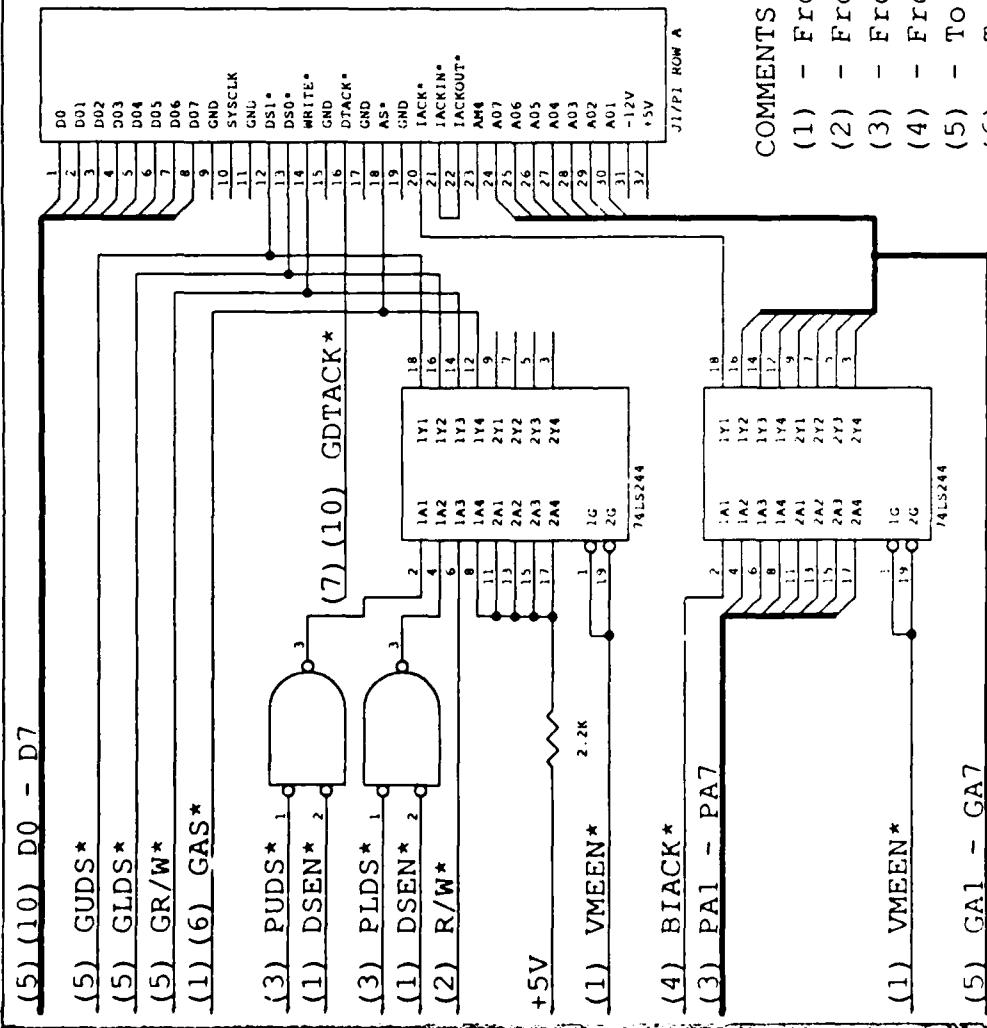


COMMENTS:

- (1) - From VMEbus
- (2) - Chip Select Request Line 2 of 74F764; To Dual-port DRAM Controller Circuitry

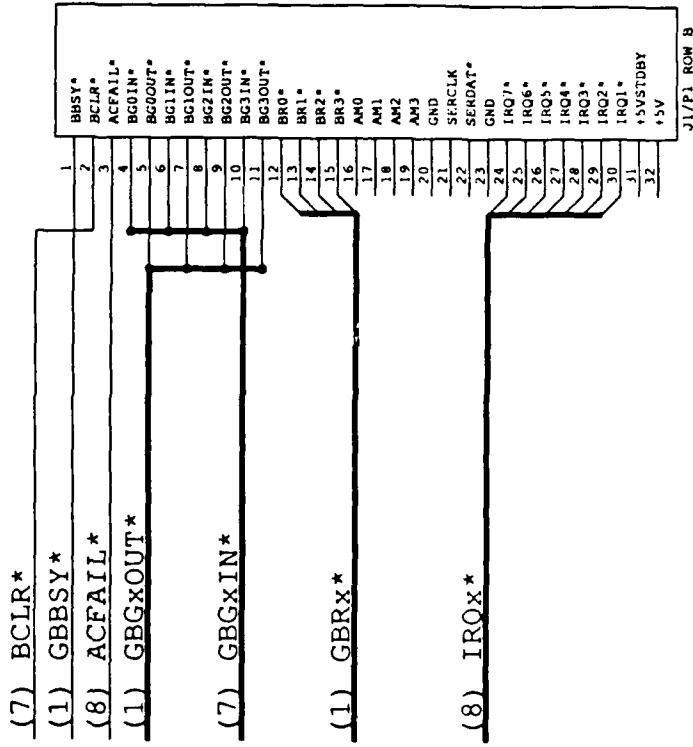
TITLE: VMEbus Address Decode  
Circuitry

Figure: E.21



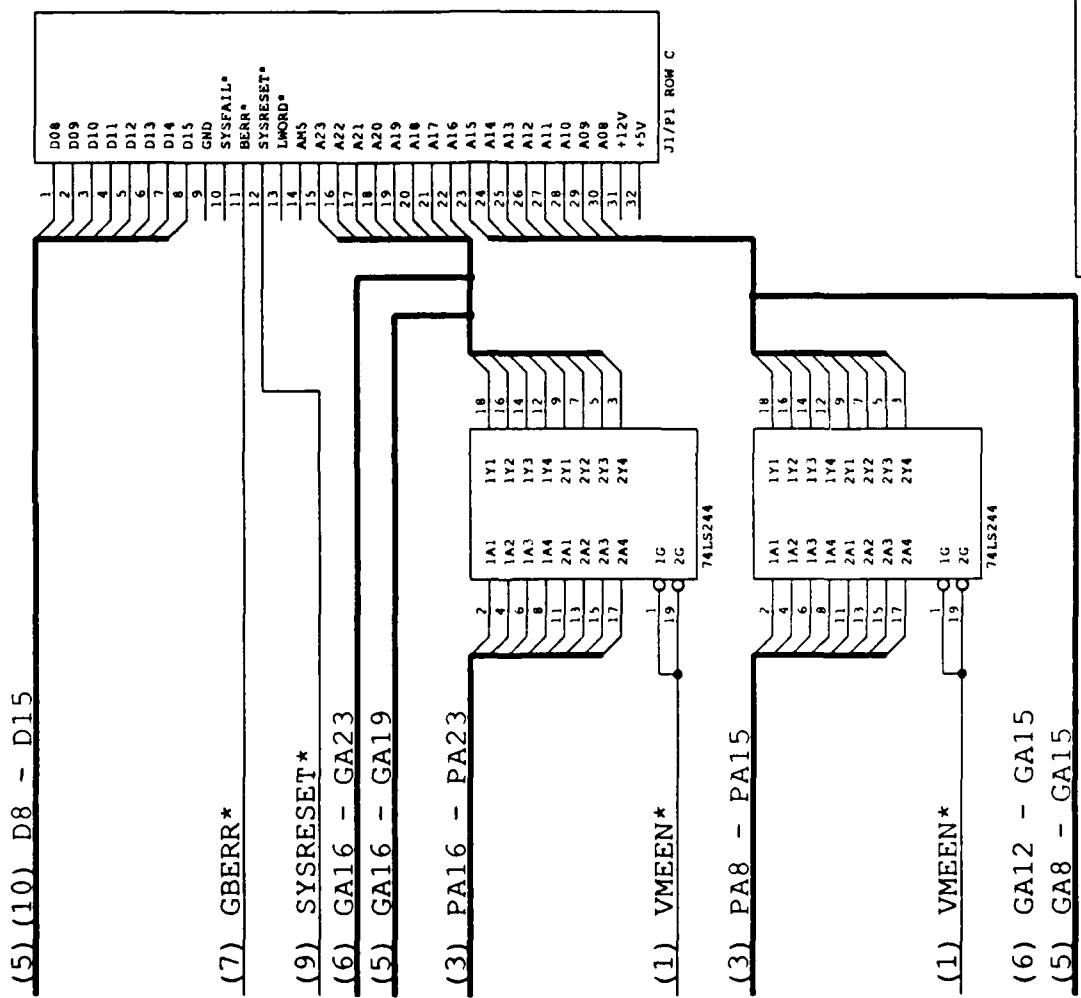
TITLE: Master Circuit Board VMEbus  
Drivers Circuitry (Page 1 of 3)

Figure: E.22



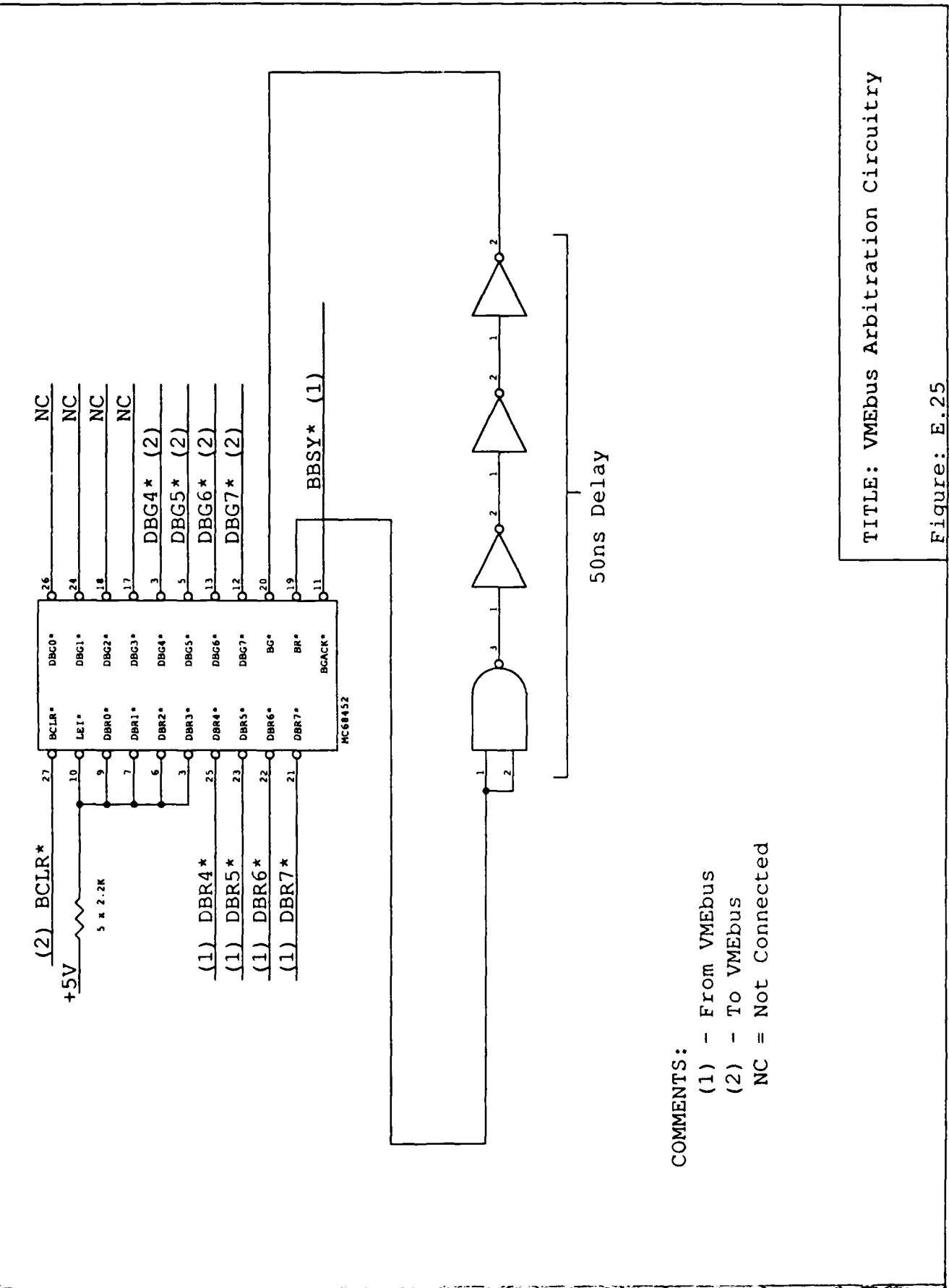
TITLE: Master Circuit Board VMEbus  
Drivers Circuitry (Page 2 of 3)

Figure: E.23



**TITLE:** Master Circuit Board VMEbus  
**Drivers Circuitry** (Page 3 of 3)

Figure: E.24



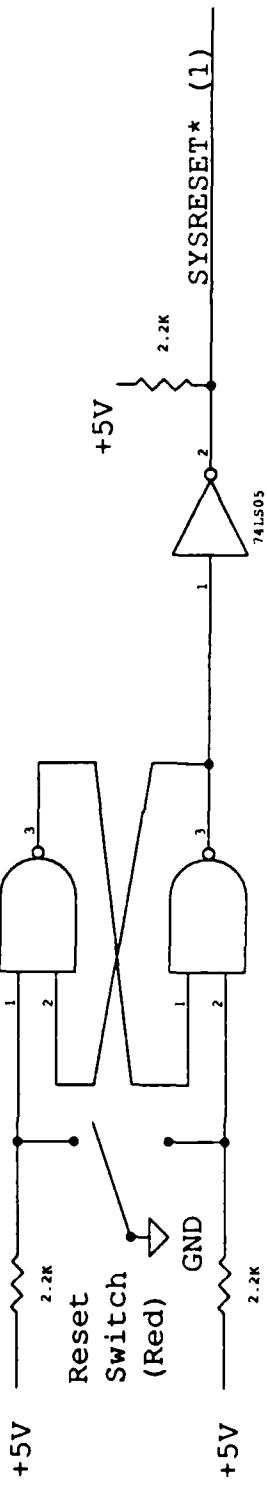
**COMMENTS:**

- (1) - From VMEbus
- (2) - To VMEbus
- NC = Not Connected

TITLE: VMEbus Arbitration Circuitry

Figure: E.25

### Debouncing Circuitry



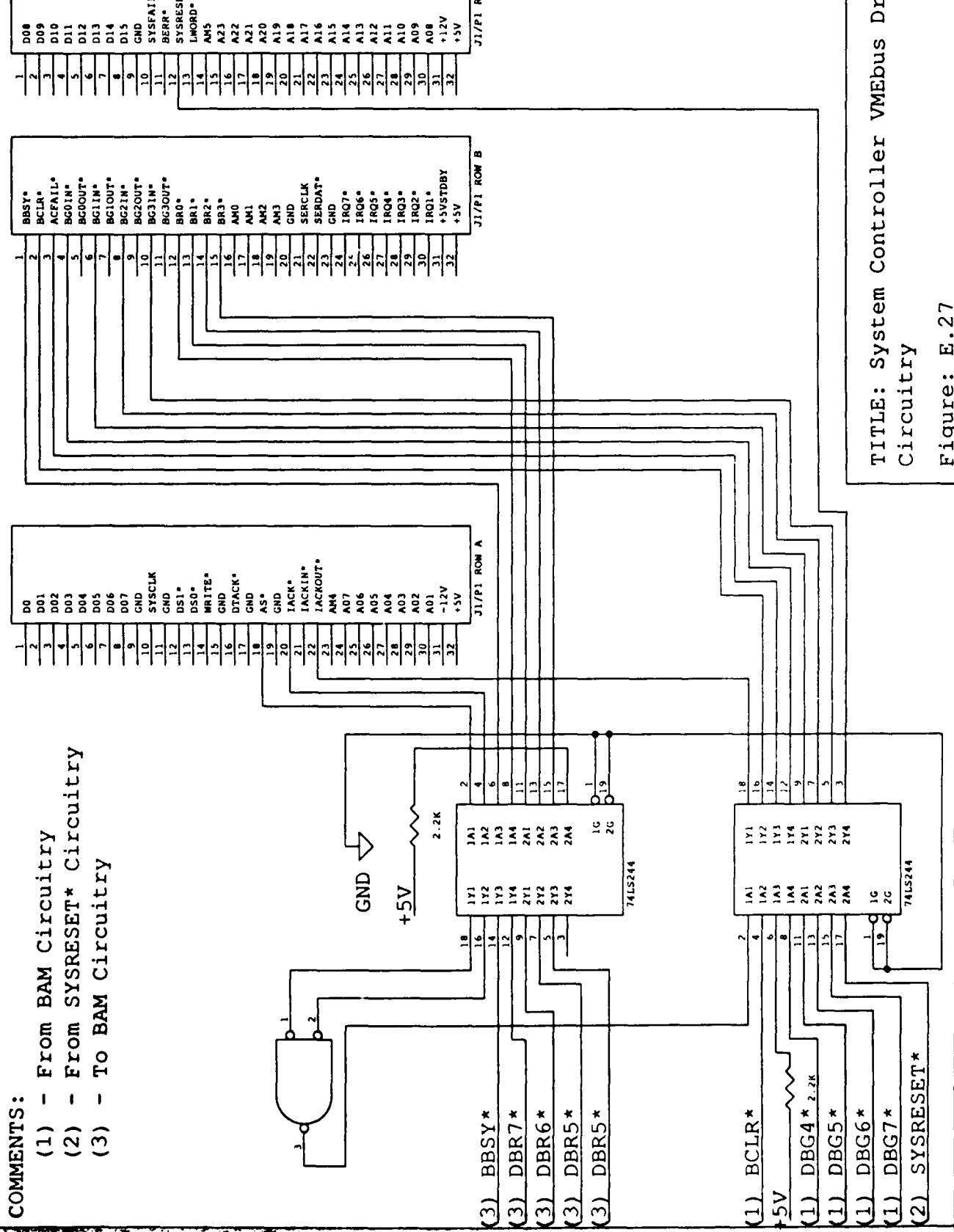
COMMENT:  
(1) - To VMEbus

TITLE: SYSRESET\* Generation Circuitry

Figure: E.26

**COMMENTS:**

- (1) - From BAM Circuitry
- (2) - From SYSRESET\* Circuitry
- (3) - To BAM Circuitry



**TITLE: System Controller VMEbus Drivers Circuitry**

**Figure: E.27**

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