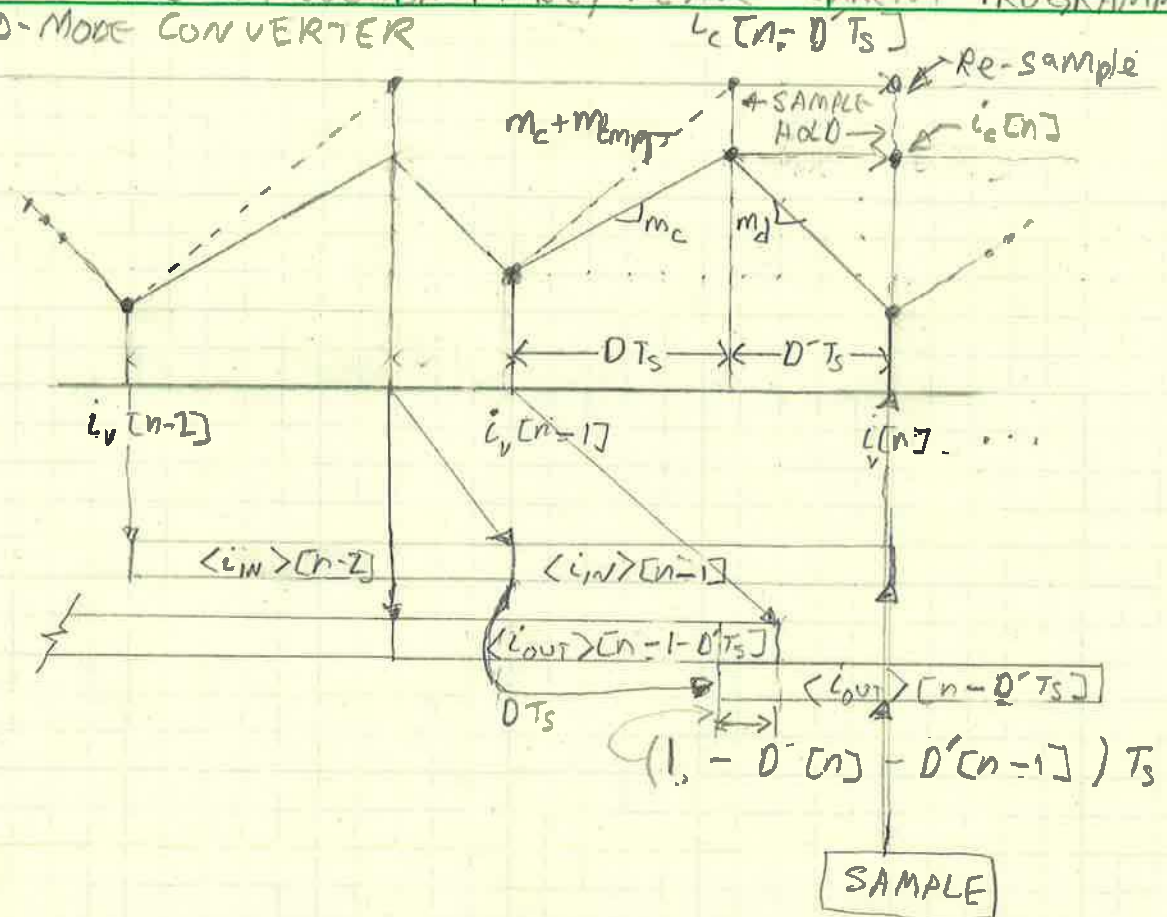


FORCED CONTINUOUS CONDUCTION MODE, PEAK-CURRENT PROGRAMMED MODE SWITCHED-MODE CONVERTER



Observations:

- Valley currents $i_v[n]$ can be expressed exactly in a recurrence relation if the following conditions are met:

A) Charging slope " m_c " and discharging slope " m_d " are constant over the sampling interval.

$$m_c = \frac{V_{IN}}{L_{pri}}$$

$$m_d = \frac{V_{OUT}}{L_{pri}}$$

B) Compensating slope " m_{comp} " is a constant

- Averaged output current is delayed from averaged input current by DT_s .
- Duty cycle " D " is a function of valley currents " i_v ", charging slope " m_c ", compensating slope " m_{comp} " and control current " i_c ".

This quantity can be computed exactly from the outputs of the difference equation for $i_v[n]$.

④ The system is perturbed by changes in control current threshold, not duty cycle, i.e., duty is an output, not an input.

⑤ Averaged currents can be computed from either energy transfer, or geometrically from duty cycle

A) Energy Transfer

$$\langle i_x \rangle = \frac{1}{2} L_{pri} (i_{pk}^2 - i_v^2) \cdot \frac{f_{sw}}{V_x}$$

f_{sw} = Switching frequency

V_x = Either input or output voltage, depending which current is being averaged.

B) Geometry:



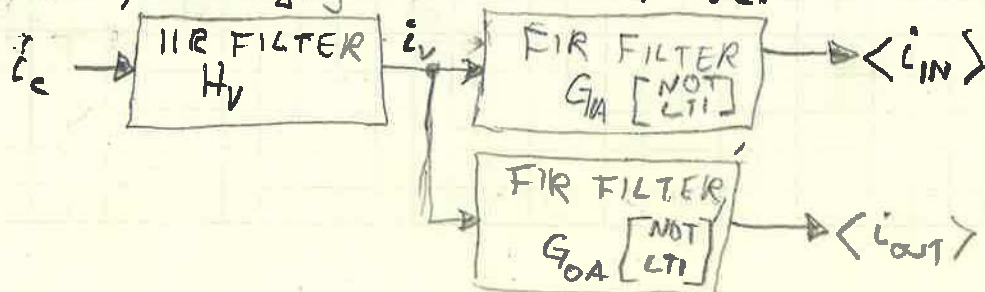
$$\langle i \rangle = (i_v DT + \frac{1}{2} DT \Delta i) \cdot \frac{1}{T}$$

⑥ Quasi-periodic sampling changes averaging interval. Sampling of average output current is periodic as long as Duty does not change.

The spill-over or deficit due to changing duty cycle can be added into the current averaging interval.

⑦ The recurrence relation for valley currents $i_v[n]$ is an IIR filter convolved with the control current, $i_c[n]$.

⑧ Since averaging can be computed entirely from $i_v[n]$ and values assumed constant during the averaging interval, it can be expressed as an FIR filter, that is, averaging is non-recursive.



FCCM CONVERTER: DIFFERENCE EQUATION

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$i_v[n]$ = Valley Current, Sampled at termination of cycle

$i_c[n - 0^- T_s]$ = Peak control current at time of sampling

m_c = Slope of charging interval = $\frac{V_{IN}}{L_{PRI}}$

m_{comp} = Slope compensation = Constant

m_d = Slope of discharging interval = $\frac{V_{OUT}}{L_{PRI}}$

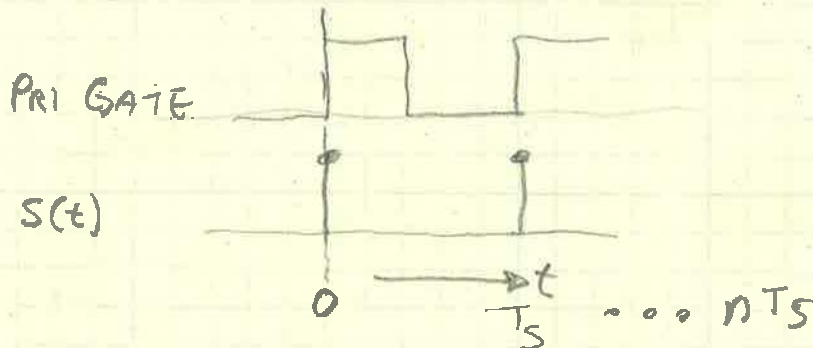
T_s = Sampling period

To use $i_c[n]$ directly in the recurrence relation, the following block diagram is assumed.



$$S(t) = \sum_{n=0}^{\infty} \delta(t - nT_s) \leftarrow \begin{matrix} \text{Single-sided} \\ \text{(causal)} \\ \text{Sampling function} \end{matrix}$$

The rising edge of the primary gate is synchronized to $t=0$, or $S(t)$.



$$\begin{aligned} i_v[n] &= i_v[n-1] + DT_s m_c - ((1-D)T_s m_d) \\ &= i_v[n-1] + DT_s m_c - (T_s m_d - DT_s m_d) \\ &= i_v[n-1] + DT_s m_c - T_s m_d + D T_s m_d \\ &= i_v[n-1] + DT_s (m_c + m_d) - T_s m_d \end{aligned}$$

DUTY

$$D(i_v[n]) = \frac{i_c[n] - i_v[n-1]}{(m_c + m_{comp}) T_s}$$

$D(i_v[n])$

FCCM CONVERTER: DIFFERENCE EQUATION

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$$\dot{i}_v[n] = \dot{i}_v[n-1] + \left(\frac{\dot{i}_c[n] - \dot{i}_v[n-1]}{(m_c + m_{cmp})T_s} \right) (m_c + m_d) T_s - T_s m_d$$

Substitute $\alpha = \frac{m_c + m_d}{m_c + m_{cmp}}$

$$\dot{i}_v[n] = \dot{i}_v[n-1] - \dot{i}_v[n-1]\alpha + \alpha \dot{i}_c[n] - T_s m_d$$

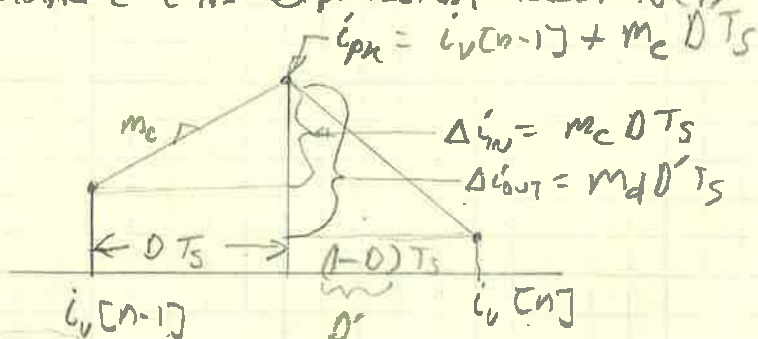
$$\dot{i}_v[n] = (1-\alpha)\dot{i}_v[n-1] + \alpha \dot{i}_c[n] - T_s m_d$$

$\dot{i}_v[n]$

FCCM CONVERTER: AVERAGE CURRENTS

(5)

- This is an FIR FILTER — BUT NON-LTI
- SPICE can handle this expression accurately



INPUT CURRENT

$$\langle i_{IN} \rangle = \left(\frac{1}{2} DT_s (m_c DT_s) + i_v[n-1] \cdot DT_s \right) \frac{1}{T_s}$$

$$\langle i_{IN} \rangle = \frac{1}{2} D^2 T_s m_c + D i_v[n-1]$$

$\langle i_{IN} \rangle$

OUTPUT CURRENT

$$\langle i_{OUT} \rangle = \left(\frac{1}{2} D' T_s m_d D' T_s + i_o[n] \cdot D' T_s \right) \frac{1}{T_s}$$

$$\langle i_{OUT} \rangle = \frac{1}{2} D'^2 T_s m_d + D' i_o[n]$$

$\langle i_{OUT} \rangle$

DUTY CLAMPING

If the converter averaged model is implemented in SPICE, DUTY must be clamped. The recurrence relation does not constrain $D_{MIN} < D < D_{MAX}$ naturally.

$$D = \frac{i_c[n] - i_v[n-1]}{(m_c + m_{comp}) T_s}$$

$$D_{MIN} < \frac{i_c[n] - i_v[n-1]}{(m_c + m_{comp}) T_s}$$

$$- (m_c + m_{comp}) T_s D_{MIN} < -i_c[n] + i_v[n-1]$$

$$i_v[n-1] > i_c[n] - (m_c + m_{comp}) T_s D_{MIN}$$

$$D_{MAX} > \frac{i_c[n] - i_v[n-1]}{(m_c + m_{comp}) T_s}$$

$$(m_c + m_{comp}) T_s D_{MAX} > i_c[n] - i_v[n-1]$$

$$i_v[n-1] < i_c[n] - (m_c + m_{comp}) T_s D_{MAX}$$

D_{MAX}

$$i_v[n-1] > i_c[n] - (m_c + m_{comp}) T_s D_{MIN}$$

D_{MIN}