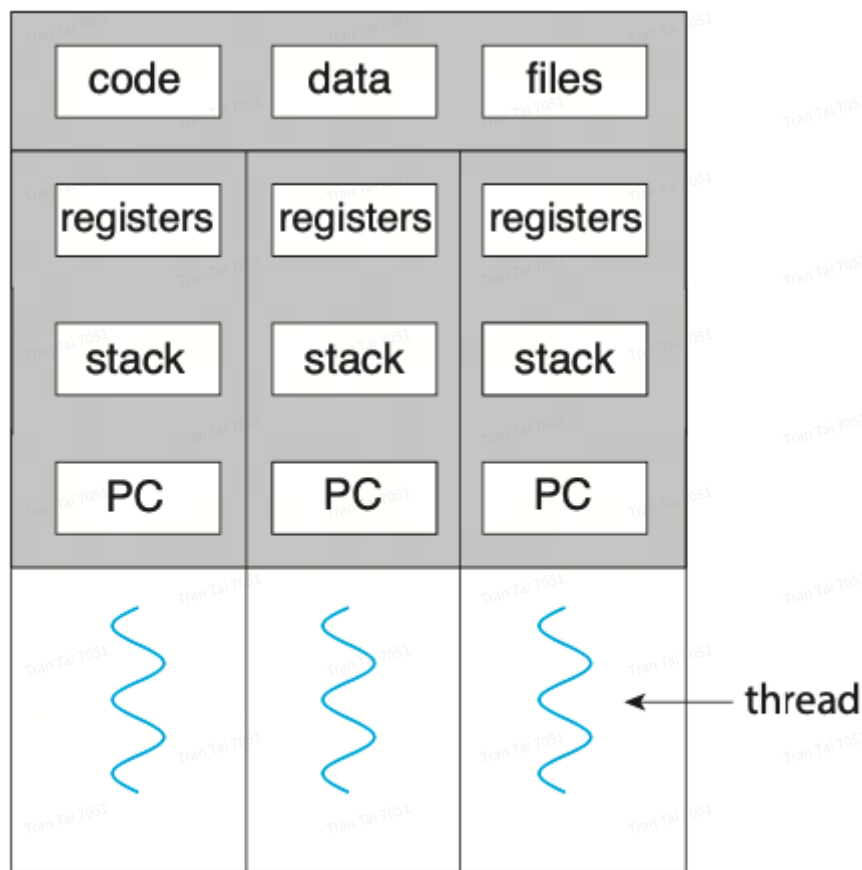


Threads and Concurrency

Revised about threads

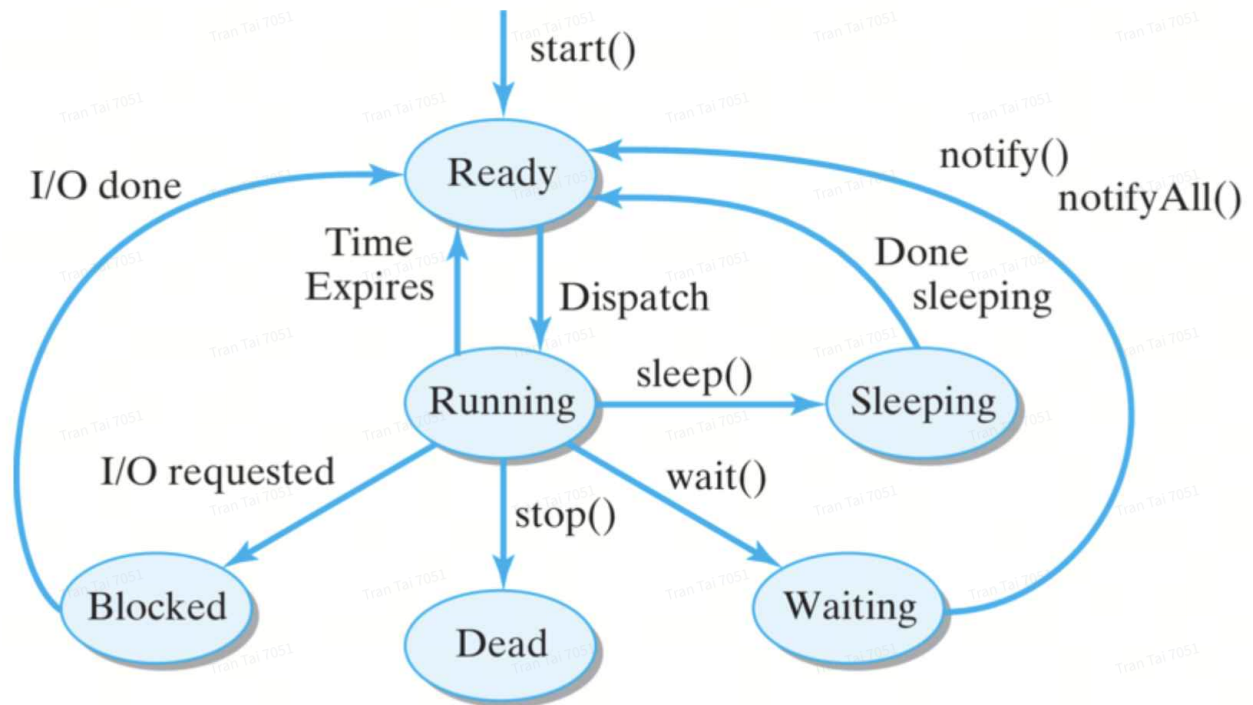
- Thread is a basic unit of CPU utilization. Thread creation is more efficient compared to process creation in terms of **time** and **resource intensive**.
- Each thread contains a **threadID**, **program counter**, **register set** and **stack**. Within the same process, they share **code section**, **data section** and **some OS resources** like files and signals.



multithreaded process

- Each user created thread will be assigned to a kernel thread in OS by 3 types of relationship: 1-to-1, many-to-1, many-to-many.
- Thread life cycle:
 - **Ready:** thread is ready to be executed and wait for CPU.
 - **Running:** thread is executed on CPU.
 - **Sleeping:** thread is being suspended.
 - **Waiting:** thread is waited for some events to trigger.

- **Blocked:** thread is waiting for I/O to finish.
- **Dead:** thread is finished executing.



Synchronizations

- Concurrent access to shared data might lead to data inconsistency.
- Those primitives below provide some mechanism to resolve that issue.

Lock

- When a thread wants to | enter the critical section, it should **acquire()** the lock.
| exit the critical section, it should **release()** the lock.
- This pseudocode is called **spinlock**:

```

1 acquire() {
2   while (!available) {
3     // waiting
4   }
5   available = false
6 }
7
8 release(){
9   available = true
10 }

```

- Lock can be implemented using CAS (Compare-And-Swap) operation. // TODO: implement
- **Lock contention**
 - If a lock is available when a thread attempts to acquire it, the lock is considered **uncontended**. Else, it is **contended**.
 - If high contention occurs (many threads try to acquire the lock at the same time), the performance of the application will be degraded.
- SpinLock?

Semaphore

- An integer that is accessed via 2 atomic operations: **signal()** and **wait()**

```

1 wait() {
2     while (S <= 0){
3         // busy waiting
4     }
5
6     S--
7 }
8
9 signal() {
10    S++
11 }

```

- From the pseudo-code, binary semaphore ($S = 2$) behaves exactly like mutex lock.
- Counting semaphores can be used to control the **access to a given resource with fixed number of instances**.
- Semaphore implementations pseudocode
 - **sleep()** and **awake()** here are system calls.

```

1 type Semaphore struct {
2     value int
3     Thread*[] waitingThread
4 }
5
6 func (sem *Semaphore) wait(thread *Thread) {
7     while (sem.S <= 0) {

```

```

8         // busy waiting;
9     }
10
11     sem.S--
12
13     sleep(thread)
14     waitingThreads = append(waitingThreads, thread) // insert to thread
    list;
15 }
16
17 func (sem *Semaphore) signal(thread *Thread) {
18     sem.value++
19
20     wakeup(thread)
21     erase(waitingThreads, thread) // remove from the thread list;
22 }
23
24

```

Monitor?

- The misuse of semaphores and locks can lead to some errors like the critical section is accessed by 2 threads at the same time or the threads will be blocked.
- Monitor incorporates simple synchronization tool as high-level language constructs.
- Pseudocode syntax of a monitor

```

1 monitor monitor name
2 { /* shared variable declarations */
3     function P1 ( . . . ) { ...
4     }
5     function P2 ( . . . ) { ...
6     }
7     function Pn ( . . . ) { ...
8     }
9     initialization code ( . . . ) {
10    ...
11    }
12 }

```

- A function declared on the monitor can only access those variables declared inside monitor or the function params.

- Monitor ensures that at one time only one process is active in the monitor.

// TODO implement it;

Side questions

1. Difference between thread and goroutines (in Golang)

- Thread managed by OS while goroutines managed by go-runtime.
- Goroutine will be scheduled and execute in a thread.
- Will be answered in detail in next sharing.

2. Difference between binary semaphore and lock.

3. Different between multi-core, multi-threaded

Multiple-core -> system characteristic

Multi-threaded -> program characteristic

4. When sleep() operation occurs, how is that thread awake?

- When the thread sleeps, it will be

5. How differences between OS (kernel) memory, heap mem, stack mem.

6. Condition variables? [OK]

7. When using Read/Write Mutex and Wait/Notify Conditional Variables.

8. Compare and Swap - strong mode and weak mode. For strong mode -> has a for loop and reassigned expected value to the actual value. For weak mode just return false. [TODO]

9. How to avoid spinlock behaviour.

- **BackOff strategy:** increase delay between each delay.
- Fine-Grained Locking: smaller sections each with locks. And reduce contention.
- Some kind of blocking mechanism.

10. What is Reentrant Lock

- Allow threads to reenter into a lock on a resource (multiple times) without deadlock.
- Is there anything similar in Golang

11. How to guarantee lock will be unlock() finally.

<https://en.cppreference.com/w/cpp/language/raii>

- Basically is to attach the lock to an object life cycle so that when the object is terminated (destructor func is call, the lock also unlocked)

12. std::lock for n locks to prevent deadlocks. Make sure the order of locks acquired consistent between different threads.

- Will dive deep into later.

13. Difference between the lock, semaphore and conditional variable.

- Lock: 1 thread to enter. Locking mechanism.
- Semaphore: allows x threads to enter, limit no of resource used.
- Cond: allow thread suspension and has a mechanism to wake it up later. Have option to notify most longest waiting thread or all threads.

// TO add-on

Reference

- Operating System Dinosaur book
- <https://codedost.com/java/multithreading-in-java/life-cycle-of-a-thread-in-java/>

Next sharing

- Deep dive into goroutine.