



THE UNIVERSITY OF ARIZONA
UASouth

CYBV 471 Assembly Programming for Security Professionals Week 12

System Calls and I/O:
Build Your I/O Assembly functions

Agenda



- **Linux kernel structure**
- **Kernel and Operating System**
- **User mode vs kernel mode**
- **What is a system call?**
- **Difference between function and system calls**
- **How do System Calls use Registers?**
- **Use system calls to**
 - Print string
 - Print character
 - Print integer value
 - Provide input to the program

Kernel and Operating System

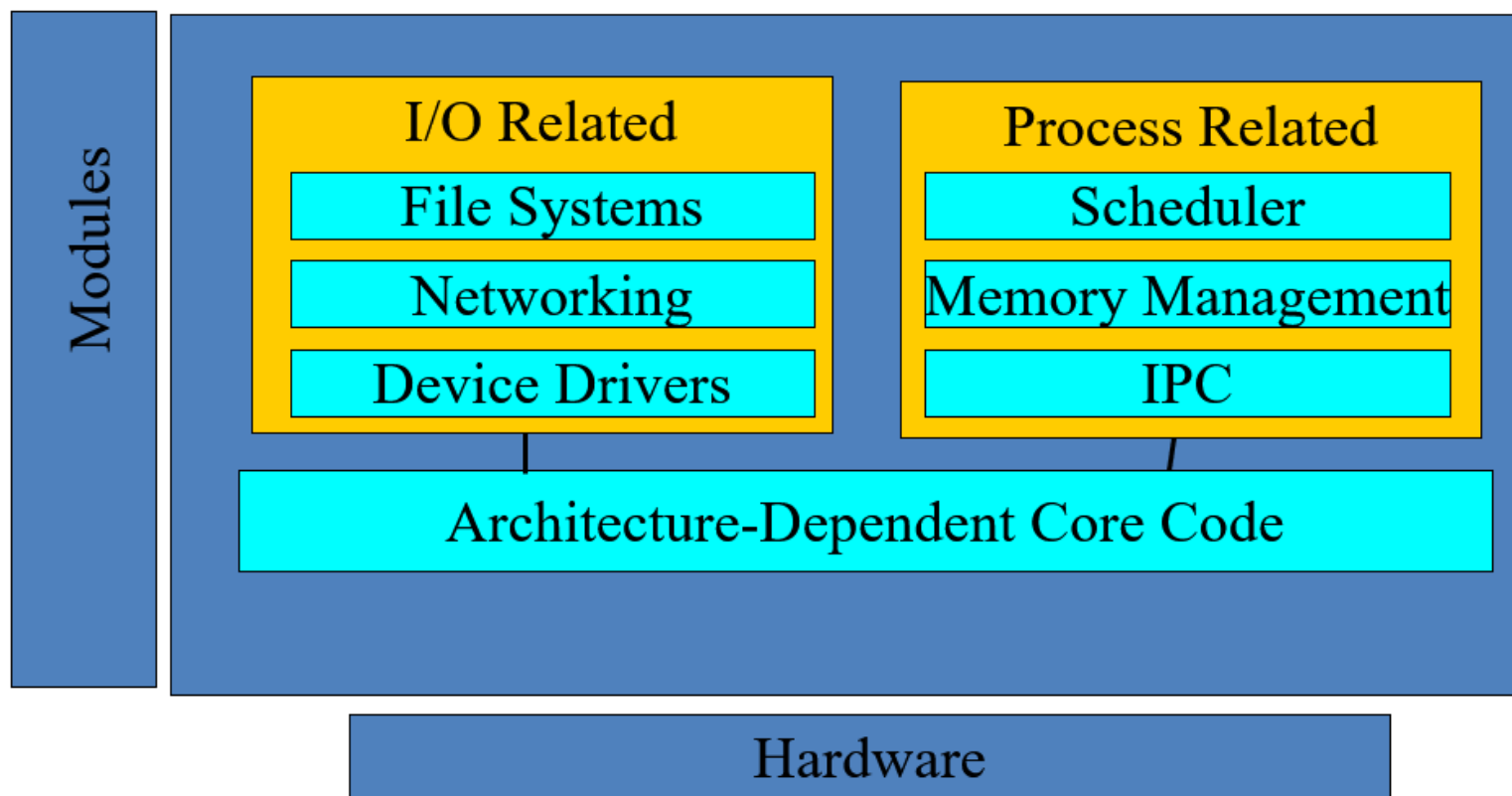


- A *kernel* is the heart of the operating system that control and manage access to system resources.
- It's responsible for enabling multiple applications to effectively share the hardware by controlling access to CPU, memory, disk I/O, and networking
- An *operating system* is the kernel plus applications that enable users to accomplish some tasks (e.g. text editor, file system utilities, etc)

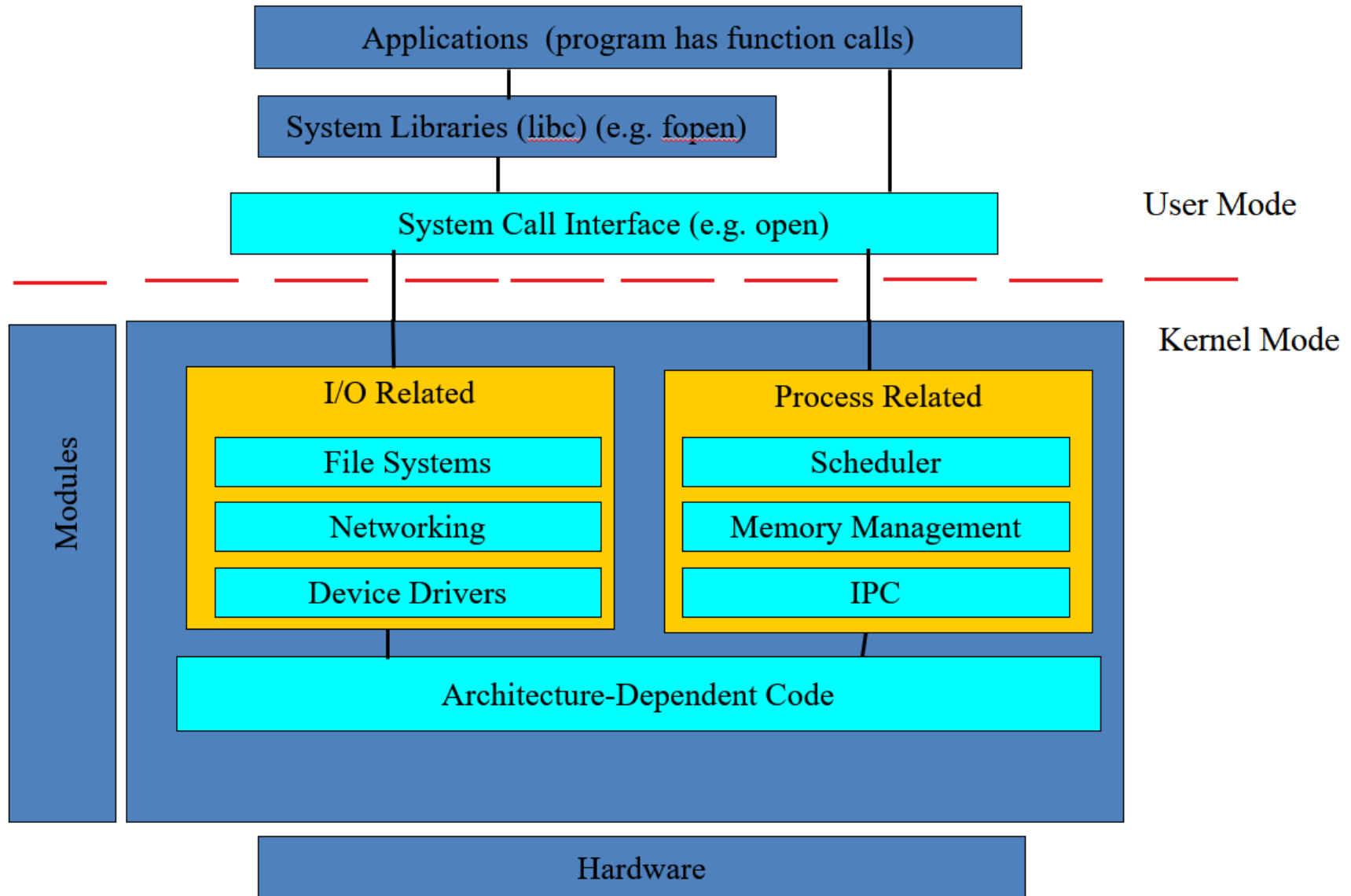
Linux kernel structure



- Include core and dynamically loadable modules
- Modules include: device drivers, file systems, network protocols, etc
- Modules were originally developed to support the **device drivers**
- Modules can be **dynamically** loaded and unloaded



User Mode vs kernel Mode





What is a System Call?

- A System Call
 - A request to the operating system to perform some task
 - Allow a user to control the operating system
- Example:
 - `getuid()` //get the user ID
 - `fork()` //create a child process
 - `exec()` //execute a program

Function and Standard Library calls vs System Calls



- Function and standard library calls perform in user mode
- Function and standard library calls use system calls to perform some OS activities
- A System Call
 - A request to the operating system to perform some activity
 - Allow a user to control the operating system

Library calls	System calls
fopen	open
fclose	close
fread, getchar, scanf, fscanf, getc, fgetc, gets, fgets	read
fwrite, putchar, printf, fprintf putc, fputc, puts, fputs	write
fseek	lseek

Function and Standard Library calls vs System Calls



- Examples

- `fopen (char* filename, char* mode);` // Standard Library call
- `open (char* filename, int flags [char* mode]);` // General System call

- `fread (int fd, , char *buf, int size);` // Standard Library call
- `read (int fd, char *buf, int size);` // General System call

- `fwrite (int fd, , char *buf, int size);` // Standard Library call
- `write (int fd, char *buf, int size);` // General System call

- `fseek (int fd, int offset, int whence);` // Standard Library call
- `lseek (int fd, int offset, int whence);` // General System call

- `fclose (FILE *fp);` // Standard Library call
- `close (int fd);` // General System call

Standard Input, Output and Error



- Standard file descriptors:
 - File descriptor 0 is standard input (keyboard)
 - File descriptor 1 is standard output (screen)
 - File descriptor 2 is standard error.
- You can read from standard input, using **read(0, ...)**.
 - **eax= 03**
- You can write to standard output using **write(1, ...)**
 - **eax= 04**

How do System Calls use Registers?



- Every system call uses some fields
- These fields must be saved in certain registers before calling the system call
- **Therefore**, to use a system call in assembly language, you **must prepare** the registers used by that system call
- Examples: To use

```
read (int fd, char *buf, int size);    // System call
    - save 0x03 in eax
    - save fd in ebx register          // 3 is file descriptor for standard input
    - save *buf in ecx register
    - save size in edx register
    - call INT 80                     // to execute the read system call
```

```
write (int fd, char *buf, int size);   // System call
    - save 0x04 in eax                // 4 is file descriptor for standard output
    - save fd in ebx register
    - save *buf in ecx register
    - save size in edx register
    - call INT 80                     // to execute the write system call
```

Linux System Call Reference



- Linux system call reference shows the necessary registers for each system call

#	Name	Registers						Definition
		eax	ebx	ecx	edx	esi	edi	
0	sys_restart_syscall	0x00	-	-	-	-	-	kernel/signal.c:2058
1	sys_exit	0x01	int error_code	-	-	-	-	kernel/exit.c:1046
2	sys_fork	0x02	struct pt_regs *	-	-	-	-	arch/alpha/kernel/entry.S:716
3	sys_read	0x03	unsigned int fd	char __user *buf	size_t count	-	-	fs/read_write.c:391
4	sys_write	0x04	unsigned int fd	const char __user *buf	size_t count	-	-	fs/read_write.c:408
5	sys_open	0x05	const char __user *filename	int flags	int mode	-	-	fs/open.c:900
6	sys_close	0x06	unsigned int fd	-	-	-	-	fs/open.c:969
7	sys_waitpid	0x07	pid_t pid	int __user *stat_addr	int options	-	-	kernel/exit.c:1771
8	sys_creat	0x08	const char __user *pathname	int mode	-	-	-	fs/open.c:933
9	sys_link	0x09	const char __user *oldname	const char __user *newname	-	-	-	fs/namei.c:2520
10	sys_unlink	0x0a	const char __user *pathname	-	-	-	-	fs/namei.c:2352
11	sys_execve	0x0b	char __user *	char __user * __user *	char __user * __user *	struct pt_regs *	-	arch/alpha/kernel/entry.S:925
12	sys_chdir	0x0c	const char __user *filename	-	-	-	-	fs/open.c:361
13	sys_time	0x0d	time_t __user *tloc	-	-	-	-	kernel/posix-timers.c:855

Recall Hello World Program from Lecture-1



- We used system calls to print message “Hello world” in the first program in Lecture #1

SECTION .DATA

```
msg:    db 'Hello world!',10    ; message to be displayed
msgLen: equ $-msg              ; Length of the message to be displayed
```

; Code goes in the text section

SECTION .TEXT

```
GLOBAL _start
```

_start:

```
mov eax,4          ; use 'write' system call = 4;
mov ebx,1          ; file descriptor 1 = STDOUT
mov ecx,msg        ; string to write
mov edx,msgLen     ; length of string to write
int 80h            ; call the kernel
```

; Terminate program

```
mov eax,1          ; 'exit' system call
mov ebx,0          ; exit with error code 0
int 80h            ; call the kernel
```

```
write (int fd, char *buf, int size);
- save 0x04 in eax
- save fd in ebx register
- save *buf in ecx register
- save size in edx register
- call INT 80
```

Recall Hello World Program from Lecture-10



- We used “printf” to print message “Hello world” in Lecture #10

```
section .data (segment .data)
```

```
msg:  db 'Display Hello world with printf !',10, 0
```

```
section .text
```

```
extern printf
```

```
global main
```

```
main:
```

```
    push ebp
```

```
    mov ebp, esp
```

```
    ; Code goes in the text section
```

```
    push msg      ; push the memory address of the message to the stack
```

```
    call printf   ; printf will display the contents of that memory address
```

```
    mov esp, ebp
```

```
    pop ebp
```

```
    ret
```

Use system calls to print string



- In lecture#10, we used “printf” to print a message (string)
- In Lecture#1, we used system calls (registers) to print a message (string)
- In lecture#11, we need to use system calls (registers) to build our **PString** function
- Before using “**PString**” function, we have to prepare the required registers with proper values related to the message to be displayed
 - mov ecx, msg ; move the memory address of the first byte of the message in eax
 - mov edx, msgL ; move the message length in edx
 - call Pstring ; call Pstring from main function
- Then we need to define Pstring using system calls (e.g. registers)

PString:

; save register values of the called function
pusha

mov eax,4 ; use 'write' system call = 4
mov ebx,1 ; file descriptor 1 = STDOUT
int 80h ; call the kernel

; restore the old register values of the called function
popa
ret

Use system calls to print string



; PMUSC1.am Print message using system calls

SECTION .data ; Data section

msg: db "Display Hello world with our PString function!",10,0 ; message to be displayed

msgL: equ \$-msg ; Length of the message to be displayed

SECTION .text

global main

main:

 push ebp

 mov ebp, esp

 ; Before calling PString function

 ; Assign the required registers with the proper values to display the message

 mov ecx,msg ; string to write (address of the first byte)

 mov edx,msgL ; length of the message to be displayed

 call PString

 ; exit the program and cleaning

 mov esp, ebp

 pop ebp

 ret

PString:

 ; save register values of the called function

 pusha

 mov eax,4 ; use 'write' system call = 4

 mov ebx,1 ; file descriptor 1 = STDOUT

 int 80h ; call the kernel

 ; restore the old register values of the called function

 popa

 ret

```
File Edit View Search Terminal Help
root@kali-Test:~/Desktop/Week-10# cd /root/Desktop/Week-11
root@kali-Test:~/Desktop/Week-11# nasm -g -f elf PMUSC1.asm -o PMUSC1.o
PMUSC1.asm:4: error: expression syntax error
root@kali-Test:~/Desktop/Week-11# nasm -g -f elf PMUSC1.asm -o PMUSC1.o
root@kali-Test:~/Desktop/Week-11# gcc -m32 -lc PMUSC1.o -o PMUSC1
root@kali-Test:~/Desktop/Week-11# ./PMUSC1
Display Hello world with our PString function!
```

Use the stack and system calls to print string



```
; PMUSC2.asm    using satck and system calls to print message
```

```
SECTION .data                ; Data section
msg:    db "Display Hello world using syste calls and stack",10,0
```

```
msgL:   equ $-msg
```

```
SECTION .text
```

```
global main
```

```
main:
```

```
    push ebp
    mov ebp, esp
```

```
; Before calling PString function
```

```
; Assign the required registers with the proper values to display the message
```

```
    push DWORD msgL
    push msg
    call PString2
```

```
; exit the program and cleaning
```

```
    mov esp, ebp
    pop ebp
    ret
```

```
PString2:
```

```
    push ebp
    mov ebp, esp
```

```
    mov eax,4
    mov ebx,1
    mov ecx,[ebp+8]
    mov edx,[ebp+12]
    int 80h
```

```
    mov esp, ebp
    pop ebp
    ret
```

```
File Edit View Search Terminal Help
root@kali-Test:~/Desktop/Week-11# nasm -g -f elf PMUSC2.asm -o PMUSC2.o
root@kali-Test:~/Desktop/Week-11# gcc -m32 -lc PMUSC2.o -o PMUSC2
root@kali-Test:~/Desktop/Week-11# ./PMUSC2
Display Hello world using syste calls and stack
root@kali-Test:~/Desktop/Week-11# gcc -m32 -lc PMUSC2.o -o PMUSC2
```


Use system calls to print character



```
; PCUSC1.am    Print character using system calls
```

```
SECTION .data          ; Data section  
ch1 db "A" ; character to be displayed
```

```
SECTION .text  
global main  
main:
```

```
    push ebp  
    mov ebp, esp
```

```
    ; Before calling PString function  
    ; Assign the required registers with the proper values to display the message
```

```
    mov ecx, ch1      ; chracter to write (address of the first byte)  
    mov edx, 1         ; length of the character  
    call PChar
```

```
    ; exit the program and cleaning  
    mov esp, ebp  
    pop ebp  
    ret
```

```
PChar:
```

```
    ; save register values of the called fuction  
    pusha
```

```
    mov eax, 4          ; use 'write' system call = 4  
    mov ebx, 1          ; file descriptor 1 = STDOUT  
    int 80h            ; call the kernel
```

```
    ; restore the old register values of the called function  
    popa  
    ret
```

Use system calls to Print New Line (local variable)



```

; PLUSC1.asm   Print character using system calls
SECTION .data           ; Data section
ch1    db "A"    ; character to be displayed
ch2    db "B"    ; character to be displayed

SECTION .text
global main
main:
    push ebp
    mov ebp, esp

    PLine          ; print new Line
    mov ecx, ch1   ; print A
    mov edx, 1     ; length of the character
    call PChar

    PLine          ; print new Line
    mov ecx, ch2   ; print B
    mov edx, 1     ; length of the character
    call PChar

    ; exit the program and cleaning
    mov esp, ebp
    pop ebp
    ret

; save register values of the called fuction
pusha

mov eax, 4          ; use 'write' system call = 4
mov ebx, 1          ; file descriptor 1 = STDOUT
int 80h            ; call the kernel

; restore the old register values of the called function
popa
ret

PChar:
section .data
nl db "", 10        ; local variable
section .text

; save register values of the called fuction
pusha
mov ecx, nl
mov edx, 1
mov eax, 4          ; use 'write' system call = 4
mov ebx, 1          ; file descriptor 1 = STDOUT
int 80h            ; call the kernel

; restore the old register values of the called function
popa
ret
    
```

```

root@kali-Test:~/Desktop/Week-11# nasm -g -f elf PLUSC1.asm -o PLUSC1.o
root@kali-Test:~/Desktop/Week-11# gcc -m32 -lc PLUSC1.o -o PLUSC1
root@kali-Test:~/Desktop/Week-11# ./PLUSC1
A
B
    
```

Use system calls to Print New Line (global variable)



; PMUSC2.asm Print message using system calls

```
SECTION .data                ; Data section
ch1    db "A"                ; character to be displayed
ch2    db "C"                ; character to be displayed
nl     db "", 10
```

SECTION .text

global main

main:

```
    push ebp
    mov ebp, esp
```

```
    PLine                ; print new Line
    mov ecx, ch1          ; print A
    mov edx, 1            ; length of the character
    call PChar
```

```
    PLine                ; print new Line
    mov ecx, ch1          ; print B
    mov edx, 1            ; length of the character
    call PChar
```

```
; exit the program and cleaning
    mov esp, ebp
    pop ebp
    ret
```

PChar:

```
; save register values of the called fuction
    pusha
```

```
    mov eax, 4            ; use 'write' system call = 4
    mov ebx, 1            ; file descriptor 1 = STDOUT
    int 80h              ; call the kernel
```

```
; restore the old register values of the called function
    popa
    ret
```

PLine:

```
; save register values of the called fuction
    pusha
```

```
    mov ecx, nl
    mov edx, 1
    mov eax, 4            ; use 'write' system call = 4
    mov ebx, 1            ; file descriptor 1 = STDOUT
    int 80h              ; call the kernel
```

```
; restore the old register values of the called function
    popa
    ret
```

```
root@kali-Test:~/Desktop/Week-11# nasm -g -f elf PLUSC2.asm -o PLUSC2.o
root@kali-Test:~/Desktop/Week-11# gcc -m32 -lc PLUSC2.o -o PLUSC2
root@kali-Test:~/Desktop/Week-11# ./PLUSC2
A
C
```

Get Input From a User using System Calls



SECTION .data ; Data section

msg1: db "What is your name!",10,0 ; message to be displayed

msgL1: equ \$-msg1 ; Length of the message to be displayed

To print (**write**) the previous message using system call, we can use the following code

```
; print msg1
mov eax,4 ; use 'write' system call = 4
mov ebx,1 ; file descriptor 1 = STDOUT
mov ecx,msg1 ; string to write (address of the first byte)
mov edx,msgL1 ; length of the message to be displayed
int 80h ; call the kernel
```

To get input (**read**) from a user using system call, we can use the following code

SECTION .bss

msg2 resb 16 ; reserve 16 bytes to hold the input message

```
; Get msg2
mov eax,3 ; use 'read' system call = 3
mov ebx,0 ; file descriptor 0 = STDINPUT (Keyboard)
mov ecx,msg2 ; string to write (address of the first byte)
mov edx,16 ; assume length of the input message = 16 bytes
int 80h ; call the kernel
```

Example: Get and print user name using System Calls



; GPMUSC1.am Get input from from a user and print message using system calls

```
SECTION .data                ; Data section
msg1:  db "What is your name!",10,0  ; message to be displayed
msgL1: equ $-msg1                ; Length of the message to be displayed

msg2:  db "Hello!",10,0  ; message to be displayed
msgL2: equ $-msg2        ; Length of the message to be displayed
```

```
SECTION .bss
name resb 16  ; reserve 16 bytes to hold the input (user's name)
```

```
SECTION .text
global main
main:
    push ebp
    mov ebp, esp

    ; print msg1
    mov eax,4                ; use 'write' system call = 4
    mov ebx,1                ; file descriptor 1 = STDOUT
    mov ecx,msg1             ; string to write (address of the first byte)
    mov edx,msgL1            ; length of the message to be displayed
    int 80h                  ; call the kernel
```

```
; Get name from user
mov eax,3                    ; use 'read' system call = 3
mov ebx,0                    ; file descriptor 0 = STDINPUT
mov ecx,name                 ; string to read. saved in memory (name)
mov edx,16                   ; we reserve 16 bytes for the name
int 80h                      ; call the kernel
```

```
; print msg2
mov eax,4
mov ebx,1
mov ecx,msg2
mov edx,msgL2
int 80h
```

```
; print name
mov eax,4
mov ebx,1
mov ecx,name
mov edx,16
int 80h
```

```
; exit the program and cleaning
mov esp, ebp
pop ebp
ret
```



Print Integer value using system calls



```
; PInt1.asm  Print integer value
section .data
```

```
z    dd    12345789
msgZ db    "z = "
```

```
section .text
    global main
```

```
main:
    push ebp
    mov ebp, esp
    call println ; print new line
```

```
;display z mesg and z value
```

```
    mov ecx, msgZ
    mov edx, 4
    call printString
    mov eax, [z]
    call printDec
    call println
```

```
; exit the program and cleaning
    mov esp, ebp
    pop ebp
    ret
```

```
printString:
```

```
; save register values of the called function
    pusha
```

```
; string is pointed by ecx, edx has its length
    mov eax, 4
    mov ebx, 1
    int 80h
```

```
; return the old register values of the called function
    popa
    ret
```

```
println:
```

```
; we will call _printString function
; that will change the content of ecx and edx
; we need to save registers used by the main program
```

```
    section .data
nl    db    10
```

```
    section .text
    pusha
```

```
    mov     ecx, nl
    mov     edx, 1
    call    printString
```

```
; return the original register values
    popa
    ret
```

Print Integer value using system calls



printDec:

;;; saves all the registers so that they are not changed by the function
;;; We build the function to handle the dword size (4 bytes)

```
section .bss
decstr    resb    10    ; 10 digits number for 32 bits
ct1       resd    1     ; to keep track of the size of the dec-string

section .text
pusha                    ; save all registers

mov     dword[ct1],0    ; assume initially 0
mov     edi,decstr      ; edi points to dec-string in memory
add     edi,9           ; moved to the last element of string
xor     edx,edx         ; clear edx for 64-bit division

whileNotZero:
mov     ebx,10          ; get ready to divide by 10
div     ebx             ; divide by 10
add     edx,'0'         ; converts to ascii char
mov     byte[edi],dl    ; put it in string
dec     edi             ; mov to next char in string
inc     dword[ct1]      ; increment char counter
xor     edx,edx         ; clear edx
cmp     eax,0           ; is remainder of division 0?
jne     whileNotZero    ; no, keep on looping

inc     edi             ; conversion, finish, bring edi
mov     ecx,edi         ; back to beg of string. make ecx
mov     edx,[ct1]       ; point to it, and edx gets # chars
mov     eax,4           ; and print! to the studardout
mov     ebx,1
int     0x80

popa                    ; restore all registers
ret
```

```
root@kali-Test:~/Desktop/Week-11# nasm -g -f elf PInt1.asm -o PInt1.o
root@kali-Test:~/Desktop/Week-11# gcc -m32 -lc PInt1.o -o PInt1
root@kali-Test:~/Desktop/Week-11# ./PInt1
z = 12345789
root@kali-Test:~/Desktop/Week-11#
```



HW-Q1: Draw the flow chart and explain how “printDec” work?

Assume

z1 dd 232

z2 dd 434

z3 dd 0

Pstring (z1)

Pstring (z2)

mov eax, z1

add eax, z2

mov z3, eax

PrintDEC (z3)

Pstring (z3)

???

???



Putting It All Together

You should know:

- **Linux kernel structure**
- **User mode vs kernel mode**
- **What is a system call?**
- **Difference between function and system calls**
- **How do System Calls use Registers?**
- **Use system calls to**
 - Print string
 - Print character
 - Print integer value
 - Provide input to the program



Questions?

Coming Next Week
Arras

Week 11 Assignments



- **Learning Materials**

- 1- Week 11 Presentation

- 2- Read Pages 452-462 & 487-493 (Ch.12: Duntermann, Jeff. Assembly Language Step by Step, Programming with Linux, PP: 201-211)

- **Assignment**

- 1- Complete “Lab 12” by coming Sunday 11:59 PM.