Understanding Problems In Concurrency Using Directed

Topology and Homotopy Theory

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Recall deadlock from class...

Necessary conditions:

- Hold and wait or resource holding
- Circular wait
- Mutual exclusion
- No preemption



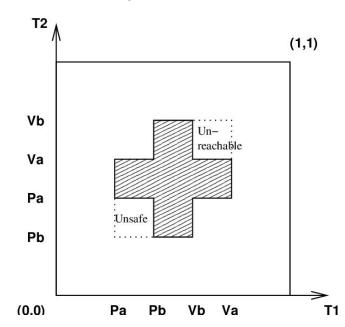
deadlock is a state in which each member of a group is waiting for another member, including itself, to take action

Deadlock

Dining philosophers!

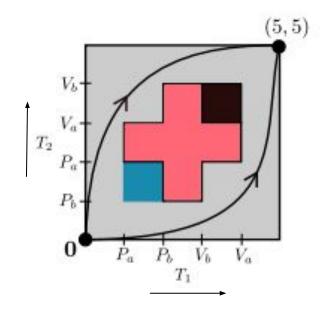


State space and fatal region as a geometric object:



In Geometric Terms...

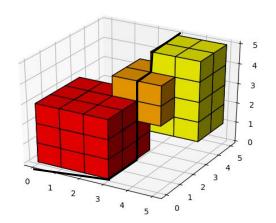
- The complement of the shaded region produces a Euclidean cubical complex (union of cubes) aka a po-space (partially ordered)
- Two possible paths through grey region
- These two paths are dihomotopic (same output given same input)



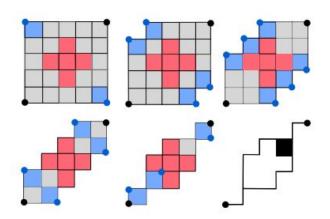
More complexity...

3 dimensions, 3 philosophers

Generating paths gets a lot more complicated!



The goal is to produce classes of paths that result in successful concurrent execution (verification)



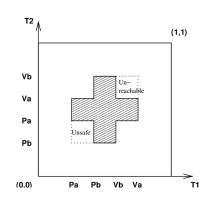
Verification

For any set of processes, does a sequence of acquiring and releasing resources result in deadlock?

Infinite number of sets of inputs

P acquires a resource:

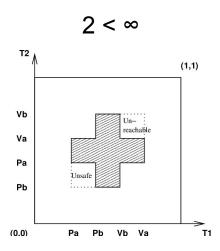
- one second later
- .5 seconds later
- .25 seconds later
- ...



Impossible to give a description of the executions that result in deadlock

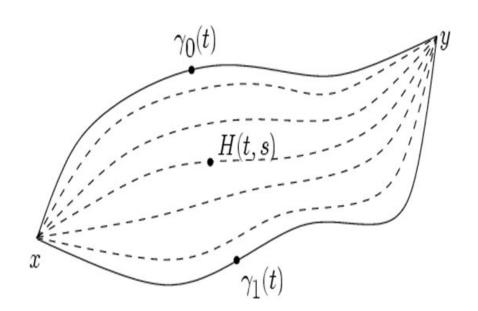
Solution: Equivalence classes on executions

The payoff: Need to check fewer executions in order to verify that deadlock does not occur.



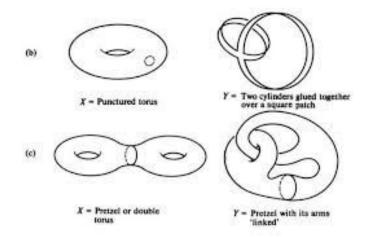
Equivalence on paths is a homotopy

Homotopy - a movie, one path continuously turns into another.

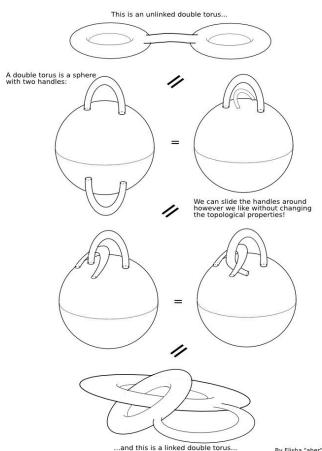


Application of a tool that was developed to answer theoretical questions in mathematics.

Are two topological spaces the same?



Linked and unlinked double torus



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To conclude:

Homotopy is useful in giving a description of executions that will result in deadlock.

Bibliography

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