On Zero Forcing and the Inverse Eigenvalue Problem for Graphs

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Abstract

This note is intended to introduce the connection between the inverse eigenvalue problem of a graph and the zero forcing number of a graph.

1 Introduction

Let \mathbb{G} denote the collection of all simple graphs (no loops nor multi-edges) of order n. With each graph $G \in \mathbb{G}$, there is a vertex set $V(G) = \{v_1, v_2, \dots, v_n\}$ and an edge set E(G), where $\{v_i, v_j\} \in E(G)$ if and only if $i \neq j$ and v_i and v_j are adjacent vertices. For example, let G be the star graph of order 7 shown in Figure 1. Then, $V(G) = \{1, 2, 3, 4, 5, 6, 7\}$ and $E(G) = \{\{1, 7\}, \{2, 7\}, \{3, 7\}, \{4, 7\}, \{5, 7\}, \{6, 7\}\}$.

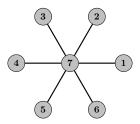


Figure 1: A star graph of order 7.

Every $n \times n$ symmetric matrix $A = [a_{ij}]_{i,j=1}^n$ is associated with a graph $G \in \mathbb{G}$, where $a_{ij} \neq 0$ if and only if $\{v_i, v_j\} \in E(G)$. Given a graph $G \in \mathbb{G}$, the set of all $n \times n$ symmetric matrices associated with G is denoted by

$$S(G) = \{ A = [a_{ij}]_{i,j=1}^n : a_{ij} = a_{ji} \ \forall i \neq j, \ a_{ij} \neq 0 \ \Leftrightarrow \ \{v_i, v_j\} \in E(G) \}.$$

For example, the star graph G shown in Figure 1 is associated with symmetric matrices of the form

$$A = \begin{bmatrix} \alpha_1 & 0 & \cdots & 0 & \beta_1 \\ 0 & \alpha_2 & \cdots & 0 & \beta_2 \\ \vdots & & \ddots & & \vdots \\ 0 & & & \alpha_6 & \beta_6 \\ \beta_1 & \beta_2 & \cdots & \beta_6 & \alpha_7 \end{bmatrix}.$$

The inverse eigenvalue problem of a graph can be stated as follows: Given a graph $G \in \mathbb{G}$, what are all possible length n multi-sets σ such that there is a matrix $A \in \mathcal{S}(G)$ with spectrum σ . This important question is obviously difficult to answer in general; however, there are a few observations we can make.

- The empty graph of order n, denoted E_n , has no edges. Therefore, $\mathcal{S}(E_n)$ is the set of all $n \times n$ diagonal matrices. Since the eigenvalues of a diagonal matrix are equal to its diagonal entries, it follows that every length n multi-set σ corresponds to the eigenvalues of a matrix $A \in \mathcal{S}(E_n)$. It turns out, that the empty graph is the only graph with this property.
- Let K_n denote a complete graph of order n. Then, $\mathcal{S}(K_n)$ is made up of symmetric matrices where all off-diagonal entries are non-zero. Furthermore, for any $\lambda_1 \leq \lambda_2 \leq \cdots \lambda_n$, there is a matrix $A \in \mathcal{S}(K_n)$ with eigenvalues $\lambda_1, \lambda_2, \ldots, \lambda_n$ if and only if $\lambda_1 < \lambda_n$ [1].

• Let P_n denote a path graph of order n. Then, $S(P_n)$ corresponds to tri-diagonal matrices with non-zero entries in the upper and lower diagonals. Furthermore, any length n multi-set σ corresponds to the eigenvalues of a matrix $A \in S(P_n)$ if and only if the entries of σ are distinct [6].

Due to the difficulty of the inverse eigenvalue problem of a graph, there is a focus on solving related but seemingly easier problems. For instance, one may want to find the maximum multiplicity of a graph $G \in \mathbb{G}$, denoted M(G), which is defined as the largest integer k such that there is a matrix $A \in \mathcal{S}(G)$ with an eigenvalue of multiplicity k. Note $M(E_n) = n$, $M(K_n) = (n-1)$, and $M(P_n) = 1$.

The multiplicity of an eigenvalue λ of the symmetric matrix A is equal to the nullity of $\lambda I - A$, i.e, the dimension of the null space of $\lambda I - A$. Note that for any $A \in \mathcal{S}(G)$, it follows that $\lambda I - A \in \mathcal{S}(G)$. Therefore,

$$M(G) = \max \{ \text{nullity } (A) : A \in \mathcal{S}(G) \}.$$

For this reason, the maximum multiplicity of a graph is often referred to as the max nullity of the graph. In a similar manner, the minimum rank of G, denoted mr(G), is defined by

$$mr(G) = \min \{ \operatorname{rank}(A) : A \in \mathcal{S}(G) \}.$$

Recall that the rank (A) is the dimension of the column space of A. By the rank-nullity theorem, we have

$$mr(G) + M(G) = n.$$

In 2006, at the AIMS Workshop on "Spectra of families of matrices described by graphs, digraphs, and sign pattern", a novel connection between the maximum nullity of a graph and its zero forcing number was presented. Zero forcing was introduced independently by Burgarth and Giovannetti in the control of quantum systems [4], where it was called graph infection. For our purposes, zero forcing is a coloring game on a graph, where an initial set of vertices are colored blue and all other vertices are colored white. Then, the blue vertices force neighboring white vertices blue using a color change rule. There are many color changing rules, but the standard rule is that a blue vertex b can force a white vertex w blue if w is the only white neighbor of b. We will reference this rule as the Z-color change rule to distinguish it from the other variants.

2 Zero-Forcing

Given a graph $G \in \mathbb{G}$, let $B \subseteq V(G)$ denote the initial set of blue vertices; this is called the initial coloring of G. Then, denote by $B^{[t]}$ the blue vertices after t applications of the Z-color change rule, where $B^{[0]} = B$. Because the graph is finite, there exists a $t^* \geq 0$ for which $B^{[t^*]} = B^{[t^*+k]}$, for all $k \in \mathbb{N}$, i.e., no more changes are possible from applying the Z-color change rule. We reference $B^{[t^*]}$ as the final coloring of B. If $B^{[t^*]} = V(G)$, i.e., the final coloring is all of the vertices of G, then we say that B is a zero forcing set of G. The zero forcing number of G is defined as the cardinality of the smallest zero forcing set of G:

$$Z(G) = \min \left\{ |B| : B^{[t^*]} = V(G) \right\}.$$

For example, consider the application of the Z-color change rule to a path graph on 5 vertices shown in Figure 2. It is clear that $B^{[4]}$ is the final coloring of B since $B^{[5]} = B^{[4]}$. Furthermore, since $B^{[4]}$ encompasses all vertices in the graph, it follows that $B = \{1\}$ is a zero forcing set and, hence, the zero forcing number of this path graph is equal to 1.

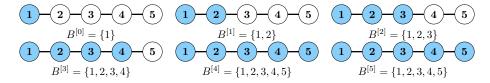


Figure 2: A zero forcing set for a path graph of order 5.

One can easily generalize the above example and conclude that the zero forcing number of all path graphs is equal to 1, i.e., $Z(P_n) = 1$. Note that not every initial coloring of 1 vertex is a zero forcing set of P_n . Indeed, consider the initial coloring of a path graph on 5 vertices shown in Figure 3.

We are now ready to present the connection between the zero forcing number and the maximum nullity of a graph. First we require the following lemma.

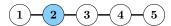


Figure 3: A non zero forcing set for a path graph of order 5.

Lemma 2.1. Suppose that $\alpha \subseteq \{1, 2, ..., n\}$ with $|\alpha| < k$ and U is a subspace of \mathbb{R}^n of dimension k. Then, U contains a non-zero vector of \mathbf{v} with $\mathbf{v}[\alpha] = 0$.

Proof. Note that if U and V are subspaces of \mathbb{R}^n whose dimensions satisfy

$$\dim V > n - \dim U$$
,

then U and V must have a non-trivial intersection, i.e., there is a non-zero vector in $U \cap V$. Now, define

$$V = \{ \mathbf{v} \in \mathbb{R}^n \colon \mathbf{v}[\alpha] = 0 \},\,$$

and note that dim $V = n - |\alpha| > n - k = \dim U$. Hence, there exists a non-zero vector $\mathbf{v} \in U \cap V$, and the result follows.

Theorem 2.2. Let $G \in \mathbb{G}$. Then, $M(G) \leq Z(G)$.

Proof. Let $B \subseteq V(G)$ be a zero forcing set of G, and let $A \in \mathcal{S}(G)$. If |B| < nullity (A), then Lemma 2.1 implies that there exists a non-zero vector $\mathbf{x} \in \text{null } (A)$ such that $\mathbf{x}_i = 0$ for all $i \in B$. However, if a vector $\mathbf{x} \in \text{null } (A)$ satisfies $\mathbf{x}_i = 0$ for all $i \in B$, then it follows that $\mathbf{x} = \mathbf{0}$.

Indeed, let $j \in V(G) \setminus B$ be any vertex that is forced by some $i \in B$; at least one such vertex must exist since B is a zero forcing set. Then, the equation $A\mathbf{x} = \mathbf{0}$ implies that $a_{ij}\mathbf{x}_j = 0$, which gives $\mathbf{x}_j = 0$ since $a_{ij} \neq 0$. If necessary, we can repeat the above argument on the zero forcing set $B \cup \{j\}$, and perhaps again, until all vertices in V(G) are accounted for at which point it follows that $\mathbf{x} = \mathbf{0}$.

This contradiction with Lemma 2.1 implies that $|B| \ge \text{nullity}(A)$. Since B and A are arbitrary, it follows that $Z(G) \ge M(G)$.

Theorem 2.2 can be used to determine the maximum nullity of a graph via its zero forcing number. For instance, we know that the path graph satisfies $Z(P_n) = 1$. Therefore, Theorem 2.2 implies that $M(P_n) \leq 1$. Since there is always a singular matrix in S(G), for any graph G, it follows that $M(P_n) = 1$.

As a more interesting example, consider the star graph in Figure 1. Note that $B = \{1, 2, 3, 4, 5\}$ is a zero-forcing set of minimal size. This observation can easily be generalized and we conclude that the zero forcing number of the star graph $K_{1,n-1}$ of order n satisfies $Z(K_{1,n-1}) = n-2$. Therefore, the maximum nullity and minimum rank satisfy

$$M(K_{1,n-1}) \le n-2$$
 and $mr(K_{1,n-1}) \ge 2$,

respectively. Furthermore, the adjacency matrix of the star graph $K_{1,n-1}$:

$$A = \begin{bmatrix} 0 & 0 & \cdots & 0 & 1 \\ 0 & 0 & \cdots & 0 & 1 \\ \vdots & & \ddots & & \vdots \\ 0 & & & 0 & 1 \\ 1 & 1 & \cdots & 1 & 0 \end{bmatrix}.$$

is a $n \times n$ matrix in $S(K_{1,n-1})$ that satisfies rank A = 2. Therefore, $M(K_{1,n-1}) = n-2$ and $mr(K_{1,n-2}) = 2$.

2.1 Known Values and Bounds

It is worth pointing out that there are some classes of graphs for which the zero-forcing number is well known. In many of these cases, the bound in Theorem 2.2 is sharp, see the list below.

i. For any tree T,

$$Z(T) = M(T) = P(T),$$

where P(T) denotes the path cover number, i.e., the minimum number of paths in a path cover of T.

ii. For n > 2,

$$Z(K_n) = M(K_n) = n - 1.$$

iii. For $n \geq 1$,

$$Z(E_n) = M(E_n) = n.$$

iv. For n > 3,

$$Z(C_n) = M(C_n) = 2,$$

where C_n is a cycle graph of order n.

v. For $n \geq 3$,

$$Z(\overline{C}_n) = M(\overline{C}_n) = n - 3,$$

where - denotes the graph conjugate.

vi. For n > 4,

$$Z(W_n) = M(W_n) = 3,$$

where W_n is a wheel graph of order n. Note that wheel graphs are formed by connecting a single vertex to all vertices in a cycle.

vii. For $p, q \ge 1$ and $p + q \ge 3$,

$$Z(K_{p,q}) = M(K_{p,q}) = p + q - 2,$$

where $K_{p,q}$ is a bipartite graph, i.e., the join of two empty graphs of order p and q, respectively.

- viii. The Cartesian product of two graphs G = (V, E) and G' = (V', E'), denoted $G \square G'$, is a graph on $V \times V'$ such that (v, v') and (u, u') are adjacent if and only if v = u and $\{v', u'\} \in E'$, or v' = u' and $\{v, u\} \in E$. Note that we have the following known values for Cartesian products:
 - a. $Z(K_n \square P_m) = M(K_n \square P_m) = n$,
 - b. $Z(P_n \square P_m) = M(P_n \square P_m) = \min\{n, m\},\$
 - c. $Z(C_n \square P_m) = M(C_n \square P_m) = \min\{n, 2m\},\$
 - d. $Z(C_n \square K_m) = M(C_n \square K_m) = 2m$, for $n \ge 4$,
 - e. $Z(K_n \square K_m) = M(K_n \square K_m) = m n + 2$.

We conclude with readily verifiable bounds on the zero-forcing number of a graph. Throughout, let $\delta(G)$ denote the minimum degree of a vertex in G and let $\Delta(G)$ denote the maximum degree of a vertex in G.

Proposition 2.3. If G has at least one edge, then

$$\delta(G) \le Z(G) \le n - 1.$$

Proposition 2.4. If $\delta(G) \geq 1$, then

$$Z(G) \le \frac{\Delta(G)}{\Delta(G) + 1}n$$

and if $\delta(G) \geq 2$, then

$$Z(G) \le \frac{(\Delta(G) - 2) n + 2}{\Delta(G) - 1}.$$

Proposition 2.5. If G is a graph of order n, then

$$Z(G) \ge \frac{|E(G)|}{n}.$$

3 Positive Semidefinite Zero Forcing

As mentioned in Section 1, there are many color change rules that can be used in the coloring game of zero forcing. The so-called standard zero forcing rule provides an upper bound on the maximum nullity of a graph via Theorem 2.2. The positive semidefinite zero forcing rule provides an upper bound on the maximum positive semidefinite nullity:

$$M_{+}(G) = \max \{ \text{nullity } (A) : A \in \mathcal{S}(G), \ \forall \lambda \in \sigma(A), \ \lambda \geq 0 \}.$$

Note that the additional condition on the eigenvalues of A, i.e., $\lambda \geq 0$ for all $\lambda \in \sigma(A)$, implies that A must be positive semidefinite.

Given a graph $G \in \mathbb{G}$, let $B \subseteq V(G)$ denote the initial coloring of G. Let G - B denote the resulting graph after the blue vertices (and adjacent edges) have been removed, and let W_1, \ldots, W_k denote the vertex sets of the connected components of G - B. If $b \in B$ and $w \in W_i$ is the only white neighbor of b in $G[W_i \cup B]$, for some $i \in \{1, \ldots, k\}$, then the positive semidefinite zero forcing rule says that b can force w blue.

As with the standard zero forcing rule, there exists a $t^* \geq 0$ such that $B^{[t^*]} = B^{[t^*+k]}$ for all $k \in \mathbb{N}$, and we say that B is a positive semidefinite zero forcing set if the final coloring satisfies $B^{[t^*]} = V(G)$. The positive semidefinite zero forcing number of G is defined as the cardinality of the smallest positive semidefinite zero forcing set of G:

$$Z_{+}(G) = \min \{ |B| : B^{[t^*]} = V(G) \}.$$

Theorem 3.1. Let $G \in \mathbb{G}$. Then, $M_+(G) \leq Z_+(G)$.

Proof. Let $A \in \mathcal{S}(G)$ be positive semidefinite with nullity $(A) = M_+(G)$ and consider a non-zero vector $\mathbf{x} \in A$, which is guaranteed to exist since the max nullity is at least 1. Let $B \subset V(G)$ denote the set of vertices such that $\mathbf{x}_i = 0$, and let W_1, \ldots, W_k denote the vertex sets of the connected components of $G \setminus B$. For every $i \in \{1, \ldots, k\}$, we claim that no $w \in W_i$ can be the only neighbor of a $b \in B$ in $G[W_i \cup B]$.

Indeed, note that we can write A, possibly after re-ordering the vertices of G, as follows

$$A = \begin{bmatrix} A_1 & 0 & \cdots & 0 & C_1 \\ 0 & A_2 & \cdots & 0 & C_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & A_k & C_k \\ C_1 & C_2 & \cdots & C_k & D \end{bmatrix},$$

where A_1, \ldots, A_k corresponds to the vertex sets W_1, \ldots, W_k , respectively, D corresponds to the vertex set B, and C_i corresponds to the edges between W_i and B, for all $i \in \{1, \ldots, k\}$.

Now, consider the partition $\mathbf{x} = [\mathbf{x}_1^T, \dots, \mathbf{x}_k^T, \mathbf{0}^T]$, where \mathbf{x}_i has size equal to $|W_i|$, for all $i \in \{1, \dots, k\}$, and the zero vector $\mathbf{0}$ has size equal to |B|. Note that all entries of $\mathbf{x}_1, \dots, \mathbf{x}_k$ must be non-zero. Moreover, the equation $A\mathbf{x} = \mathbf{0}$ implies that $A_i\mathbf{x}_i = \mathbf{0}$ for all $i \in \{1, \dots, k\}$.

The column inclusion property for Hermitian positive semidefinite matrices [8], guarantees that each column in C_i is the span of the columns in A_i , for all $i \in \{1, ..., k\}$. Therefore, for each $i \in \{1, ..., k\}$, there exists a matrix Y_i such that $C_i = A_i Y_i$. Since A is symmetric, it follows that $C_i = Y_i^T A_i$; hence, $C_i \mathbf{x}_i = \mathbf{0}$ for all $i \in \{1, ..., k\}$. But if $w \in W_i$ were the only white neighbor of $b \in B$ in $G[W_i \cup B]$, then $C_i \mathbf{x}_i \neq \mathbf{0}$, which is a contradiction.

This contradiction implies that B is not a positive semidefinite zero forcing set of G. Furthermore, it follows that there is no non-trivial $\mathbf{x} \in \text{null}(A)$ with $\mathbf{x}_i = 0$ for all i in a positive semidefinite zero forcing set of G. Therefore, by Lemma 2.1, we have $M_+(G) \leq Z_+(G)$.

As an example of how Theorem 3.1 could be applied, consider the star graph $K_{1,n-1}$. Note that the "center" vertex constitutes a positive semidefinite zero forcing set of $K_{1,n-1}$. Therefore,

$$Z_+(K_{1,n-1}) = 1$$

and it follows that $M_{+}(K_{1,n-1}) = 1$.

Finally, note that every standard zero forcing set of a graph $G \in \mathbb{G}$ constitutes a positive semidefinite zero forcing set; hence, $Z_{+}(G) \leq Z(G)$. Furthermore, it is also clear that $M_{+}(G) \leq M(G)$.

Question 3.2. Is there a relationship between $Z_{+}(G)$ and M(G), i.e., does the following hold

$$Z_+(G) \leq M(G)$$

for all (or some) graphs $G \in \mathbb{G}$.

4 Historical Background of the Minimum Rank

Parter appears to be the first to study the spectral properties of matrices with a given graph; in 1960, he published his investigation of sign symmetric matrices with multiple eigenvalues whose underlying graph is a tree [10].

Recall that a forest is an acyclic graph, i.e., a graph with no cycles, and a tree is a connected forest. Moreover, given a tree T and a vertex $v \in V(T)$, a branch of T at v is a connected component of T - v. If $A \in S(T)$, then each branch of T at v determines a principal submatrix of A, namely A[W], where W is the vertex set of the branch. The following result is due to Parter [10].

Theorem 4.1. Let T be a tree and let $A \in \mathcal{S}(T)$. Then, nullity $(A) \geq 2$ if and only if there exists a vertex $v \in V(T)$ and at least three branches $T[W_i]$ of T at v such that the principal submatrix $A[W_i]$ is singular.

The following result is due to Fiedler [5]

Theorem 4.2. Let T be a tree and let $A \in \mathcal{S}(T)$ with nullity $(A) \geq 2$. Then, there exists an $i \in \{1, 2, ..., n\}$ such that every null vector $\mathbf{x} = [x_i]$ has $x_i = 0$.

An index $i \in \{1, 2, ..., n\}$ with the property that every eigenvector of A corresponding to an eigenvalue λ has its ith coordinate zero is known as a $Fiedler\ index$ of A corresponding to λ .

In [5], Fiedler also showed that one can often determine the location of an eigenvalue λ of $A \in \mathcal{S}(T)$ among the ordering of its eigenvalues from an eigenvector of A corresponding to λ .

Theorem 4.3. Let T be a tree, $A \in \mathcal{S}(A)$, and $\mathbf{y} = [y_i]$ be an eigenvector corresponding to an eigenvalue λ . Let p be the number of edges $ij \in E(T)$ such that $a_{ij}y_iy_j < 0$, q the number of edges $ij \in E(T)$ such that $a_{ij}y_iy_j > 0$, and r the number of coordinates of \mathbf{y} that are zero. If there does not exist an index i such that $y_i = 0$ and $y_j = 0$ for all j adjacent to i in T, then there are p + r eigenvalues of A greater than λ and q + r eigenvalues of A less than λ (counting multiplicity).

For example, consider the tree graph shown in Figure 4. The adjacency matrix of this graph is

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

and has spectrum $\sigma(A) = \{-2, 2, -1, 1, 0, 0\}$. To illustrate Theorem 4.1, note that there are three branches of the vertex 2, namely $\{1\}$, $\{3\}$, and $\{4, 5, 6\}$, with corresponding principal submatrix of A that is singular. A similar argument can be made for the branches of the vertex 5. Moreover, the null (A) is spanned by the following basis vectors

$$\begin{bmatrix} 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}^T \\ \begin{bmatrix} -1 & 0 & 1 & 0 & 0 & 0 \end{bmatrix}^T$$

Hence, every null vector of A has a zero in the index 2 and 5, which illustrates Theorem 4.2. Finally, note the following eigenvalue-eigenvector pairs for the matrix A:

$$\lambda = -2, \quad \mathbf{v} = \begin{bmatrix} -1 & 2 & -1 & 1 & -2 & 1 \end{bmatrix}^T,$$

$$\lambda = 2, \quad \mathbf{v} = \begin{bmatrix} 1 & 2 & 1 & 1 & 2 & 1 \end{bmatrix}^T,$$

$$\lambda = -1, \quad \mathbf{v} = \begin{bmatrix} 1 & -1 & 1 & 1 & -1 & 1 \end{bmatrix}^T,$$

$$\lambda = 1, \quad \mathbf{v} = \begin{bmatrix} -1 & -1 & -1 & 1 & 1 & 1 \end{bmatrix}^T.$$

Note that Theorem 4.3 holds for each of the eigenvalue-eigenvector pairs since none of the eigenvectors do not have any zero elements. For instance, every entry of the eigenvector associated with $\lambda=2$ is positive. Hence, there are 5 (total number of edges) eigenvalues of A less than 2 (counting multiplicity). For the eigenvector associated with $\lambda=-1$, we have p=4 (corresponding to edges $\{1,2\}$, $\{2,3\}$, $\{4,5\}$, $\{5,6\}$) and q=1 (corresponding to the edge $\{2,5\}$). Hence, there are 4 eigenvalues of A greater than -1 and 1 eigenvalue less than -1. A similar statement can be made for the eigenvectors associated with all other eigenvalues of A.

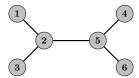


Figure 4: A tree graph of order 6.

In 1984, Wiener strengthened the result in Theorem 4.1 [11]. This stronger result, stated in Theorem 4.4, is now referred to as the Parter-Wiener theorem.

Theorem 4.4. Let T be a tree and $A \in \mathcal{S}(T)$ with nullity $(A) \geq 2$. Then, there is a vertex $i \in V(T)$ such that nullity (A(i)) = nullity(A) + 1, and the principal submatrices of A corresponding to at least three branches of T at i are singular.

Note that A(i) is the principal submatrix of A obtained by deleting row and column i from the matrix A. Moreover, the vertex i for which nullity $((A - \lambda I)(i)) = \text{nullity}(A - \lambda I) + 1$ is known as a Parter-Wiener vertex for A corresponding to the eigenvalue λ . For example, the adjacency matrix of the tree graph in Figure 4 has Parter-Wiener vertices 2 and 5 corresponding to the eigenvalue 0. Over the subsequent years, the Parter-Wiener theorem has been further developed and produced many beautiful results, e.g., see Chapter 2 of [7].

Nylen appears to be the first to study the minimum rank of a graph, which appeared in his 1996 paper [9]. In that paper, Nylen made the following observations.

Proposition 4.5. Let $G \in \mathbb{G}$ have order $n \geq 1$. Then,

- a. If $A \in \mathcal{S}(G)$ and $v \in V(G)$, then the principal submatrix A(v) corresponds to the induced subgraph G v.
- b. If G is disconnected with connected components G_1, G_2, \ldots, G_k , then

$$mr(G) = \sum_{i=1}^{k} mr(G_i).$$

c. If G has k connected components, then

$$mr(G) \le n - k$$
.

d. For each vertex $v \in V(G)$, we have

$$mr(G) - 2 \le mr(G - v) \le mr(G).$$

e. For each edge $e \in E(G)$, we have

$$mr(G) - 1 \le mr(G - e) \le mr(G) + 1.$$

In addition, Nylen proved the following more substantial result.

Theorem 4.6. Let $G \in \mathbb{G}$ and $A \in \mathcal{S}(G)$ with rank (A) = mr(G). Then, for any vertex $i \in V(G)$, either rank (A(i)) = mr(G) - 2 or rank (A(i)) = mr(G).

The rest of Nylen's paper focuses on trees; in particular, he proved the following result, which provides an algorithm for computing the minimum rank of a tree. Note that a high-degree vertex of a graph is a vertex with degree at least 3; a $Nylen\ path$ in a forest F is a path with at most one high-degree vertex, and whose initial and terminal vertices each have degree 1.

Theorem 4.7. Let P be a Nylen path of the forest F. Then,

- a. If P has a high-degree vertex v, then mr(F) = mr(F-i) + 2.
- b. If P does not have a high-degree vertex, then mr(F) = |V(P)| 1 + mr(F V(P)).

5 Colin de Verdiére Type Parameters

6 Computational Approaches to Zero Forcing Number

6.1 Integer Program

In this section, we review the integer program model introduced by Brimkov et al. [2] to compute the zero forcing number of a graph $G \in \mathbb{G}$. This integer program is shown in (1a)–(1e), and we reference this program by ZIP (G). Note that every edge in E(G) is replaced by two directed edges with opposite direction. A binary variable s_v indicates whether vertex v is in the zero forcing set; an integer variable x_v ranging in $\{0,\ldots,T\}$ indicates at which timestep vertex v is forced, where T is the maximum difference between the forcing times of two vertices; finally, a binary variable y_e for each directed edge e = (u,v) indicates whether u forces v. The notation $\delta^-(v)$ refers to the set of edges pointing towards the node v, N(u) denotes the open neighborhood of u, i.e., all vertices $v \in V(G)$ that are adjacent to u, and N[u] denotes the closed neighborhood of u, i.e., $N[u] = N(u) \cup \{u\}$.

$$\min_{v \in V} s_v \tag{1a}$$

subject to
$$s_v + \sum_{e \in \delta^-(v)} y_e = 1, \quad \forall v \in V,$$
 (1b)

$$x_u - x_v + (T+1)y_e \le T, \quad \forall e = (u,v) \in E, \tag{1c}$$

$$x_w - x_v + (T+1)y_e \le T, \quad \forall e = (u,v) \in E, \ \forall w \in N(u) \setminus \{v\},$$
 (1d)

$$s \in \{0,1\}^n, \ x \in \{0,\dots,T\}^n, \ y \in \{0,1\}^m$$
 (1e)

The triple (s, x, y), where $s \in \{0, 1\}^n$, $x \in \{0, ..., T\}^n$, $y \in \{0, 1\}^m$, is a feasible solution of ZIP (G) provided that s, x, y satisfy (1b)–(1e). If, in addition, s is minimal with respect to the objective function 1a, then we say that (s, x, y) is an optimal solution of ZIP (G). The corresponding minimal value of the objective function 1a is the optimal value of ZIP (G).

Theorem 6.1. Let $G \in \mathbb{G}$. The optimal value of ZIP (G) is equal to the zero-forcing number of G.

Proof. Let $B \subseteq V$ denote a zero-forcing set of G. Also, fix some chronological list of forces that results in a total coloring of G, and let \mathcal{F} be the associated set of forcing chains. Since B is a zero forcing set, every vertex $v \in V(G)$ is either in B, i.e., $s_v = 1$, or is forced by some other vertex $u \in V(G)$, i.e., $y_e = 1$ where e = (u, v). Thus, constraint (1b) must hold. Now, let x_v be the time step in which $v \in V(G)$ is forced. Since a vertex cannot force until all but one of its neighbors are forced, it follows that for every edge e = (u, v) for which $y_e = 1$, u must be forced before v, i.e., $x_u < x_v$. Similarly, $x_w < x_v$ for all neighbors w of u. Thus, constraints (1c) and (1d) are satisfied. If $y_e = 0$, then constraints (1c) and (1d) hold since T is the maximum difference between the forcing times of two vertices. Therefore, constraints (1b)–(1e) are valid for any zero-forcing set B and associated set of forcing chains \mathcal{F} .

Conversely, let (s, x, y) be a feasible solution of ZIP (G). Define $B \subseteq V(G)$ to be the set of vertices for which $s_v = 1$. By constraint (1b), each vertex $v \in V(G)$ is either in B or is the head of exactly one edge e = (u, v) such that $y_e = 1$. Consider any such edge; then, by constraints (1c) and (1d), there must be an integer $x_v \in \{0, \ldots, T\}$ such that $x_w + 1 \le x_v$ for all $w \in N[u] \setminus \{v\}$. Therefore, the edges e = (u, v) for which $y_e = 1$ define a chronological list of forces. Since every vertex $v \in V(G)$ is either in B or is the head of exactly one edge e = (u, v) such that $y_e = 1$, it follows that B is a zero-forcing set. If, in addition, s is minimal with respect to the objective function (1a), i.e., (s, x, y) is an optimal solution of ZIP (G), then B is a minimal zero-forcing set and it follows that the objective value of ZIP (G) is the zero-forcing number of G.

6.2 Heuristics

In this section, we review a heuristic method for the zero-forcing number of a graph from [3]. This heuristic is based on adding vertices to a set in order to maximize its closure. Let G = (V, E) be a simple graph and let $S \subseteq V$ be an initial set of blue vertices. The closure of S, denoted cl(S), is the set of blue vertices obtained after applying the color change rule until no other white vertices can be forced blue. Note that S is a zero-forcing set of S if S if S is a zero-forcing set of S if S is a zero-forcing set of S if S is a zero-forcing set of S is a zer

In Algorithm 1, $S \subseteq V$ denotes a set of blue vertices and let C denotes the closure of S. Note that S is initialized as the empty set and grows on each iteration of the while loop until its closure, C, is equal to V.

Algorithm 1 Heuristic method for the zero-forcing number.

```
Given a graph G = (V, E), this algorithm returns a zero-forcing of G.
\mathcal{S} \leftarrow \emptyset
\mathcal{C} \leftarrow \emptyset
while C \neq V do
    \mathcal{C}^* \leftarrow \emptyset
    \mathcal{A}^* \leftarrow \emptyset
    for v \in V \setminus \mathcal{C} do
         \mathcal{S} \leftarrow \mathcal{C} \cup A(v, \mathcal{C})
         if f(cl(S), v, C) > f(C^*, v, C) then
              A^* \leftarrow A(v, \mathcal{C})
              C^* \leftarrow cl(\mathcal{S})
         end if
    end for
    \mathcal{C} \leftarrow \mathcal{C}^*
    \mathcal{S} \leftarrow \mathcal{S} \cup \mathcal{A}^*
    for v \in \mathcal{S} do
         if cl(S \setminus \{v\} = V then
             \mathcal{S} \leftarrow \mathcal{S} \setminus \{v\}
         end if
    end for
end while
```

7 Propagation Time and Throttling Number

Given a color change rule and a graph G, the propagation time of $B \subseteq V(G)$, denoted pt(G,B), is the smallest t such that $B^{[t]} = V(G)$ or ∞ if B is not a zero-forcing set. The propagation time of G is defined by

$$pt(G) = \min \{ pt(G, B) : B \text{ is a minimal zero-forcing set} \}.$$

In Figure 5, we illustrate the standard propagation process and blue sets $B^{[i]}$ for a tree T and initial set $B = B^{[0]}$ such that pt(T) = pt(G, B).

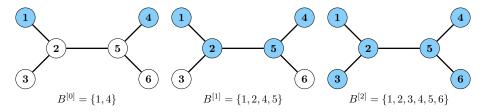


Figure 5: A zero forcing set for a tree graph of order 6.

Given a color change rule and a graph G, the throttling number of $B \subseteq V(G)$ is defined by

$$th(G,B) = |B| + pt(G,B).$$

Furthermore, the throttling number of G is defined by

$$th(G) = \min_{B \subseteq V(G)} th(G, B).$$

Note that throttling number is not necessarily attained for minimal zero-forcing sets. Indeed, consider the path graph of order n, denoted by P_n . Note that $Z(P_n) = 1$, and any of the two leafs in P_n will serve as a zero forcing set, e.g., see Figure 2. Since every other node will be forced, one at a time, it follows that $pt(P_n, B) = n - 1$, for any minimal zero-forcing set. Therefore,

$$th(P_n, B) = n$$

for any minimal zero-forcing set B. However, if we let the initial coloring B be made up of both leafs in P_n , then $pt(P_n, B) = \lceil (n-2)/2 \rceil$, and it follows that

$$th(P_n, B) = 2 + \lceil (n-2)/2 \rceil.$$

Therefore, $th(P_n) < n \text{ for all } n > 3.$

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