

Anurag Pandey

Robotics student looking for abroad experience

Experience

Address Nantes, France

07/19 - 09/19 Robotics Developer (Intern)

Ingeniarius (Coimbra, Portugal)

- Co-designed a mobile ground robot able to solve a maze while mapping. and then able to reproduce the optimized path with the A* algorithm.
- Participated to the SEMFIRE project by starting to implement the link between the Neural Network predicting inflammable materials and ROS.
- Won the robotic competition organized by the company and earned top 10 intern honors.

Contact

+33 699205825 erwin.lejeune15@ gmail.com

02/19 - 07/19 Embedded Systems Developer (Trainee)

Hiventive (Bordeaux, France)

- Simulated hardware components models and developed an open-source virtual fablab to optimize the development of embedded systems.
- Focused on developing a virtual prototype of the STM32F4xx.

Web & Git

erwinlejeune-lkn github.com/guilyx

06/18 - 08/18 Robotics Engineer (Intern)

LS2N (Nantes, France)

Research and Development of a collaborative robotic mesh network with Turtlebots using ROS.

Programming

03/15 - 10/17 Student Tutor

Université de Nantes

Tutored freshmen in English communication, Mathematics and basic programming.

VHD

Bash

Education

2019 - 2021 MSc - Control and Robotics

Ecole Centrale de Nantes

Specialized in Embedded Real Time Systems.

Courses: Al, Mobile Robots, Object-Oriented Programming, Digital Design, Microcontrollers, Signal Processing, Control Theory, Computer Vision, Scheduling...

Technologies



MEng - Embedded Systems 2018 - 2019

Bordeaux Ynov Campus

Specialized in Computer Engineering.

Courses: Embedded C, Real Time Systems, Human-Machine Interaction (Qt), Python, Linux, Digital Design (VHDL), Embedded Linux (U-boot, Yocto), Open-Source, Signal Processing...

2015 - 2018 **BSc - Electrical Engineering**

Université de Nantes

Courses: Analog Electronics, Hardware testing, Mechanics, Linear Algebra, Automatic control, Signal processing...

Projects:

- Programming a 99.99 chronometer with different options (store up to eight different times, reverse the clock, reset the clock) with logic latches on a FPGA in VHDL.
- Full study of sensors used in today's autonomous vehicules.
- Study and conception of a metal sensor on an electronic card.
- Programming a complex model of resolution for the Bateman's equation system (C++)

Personal Skills

