

# Hopf bifurcation

week 7

# 3. Hopf bifurcation

### 3. Hopf bifurcation

#### Lotka-Volterra models: example

$$T' = bT - \beta ST \longrightarrow N' = r_1 N - a N P$$

N = prey

$$S' = m \beta ST - d S \longrightarrow P' = b N P - d P$$

P = predator

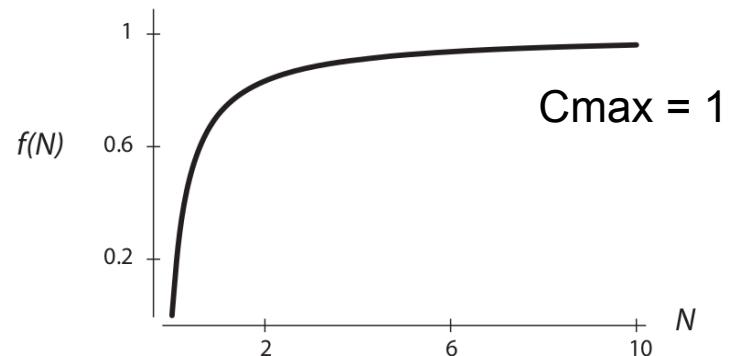
**problem 1:** in absence of predator: prey can grow exponentially

**solution 1:** we should add  $rN(1 - \frac{N}{K})$

**problem 2:** term  $aNP$ : at every value of P, the amount of prey (N) eaten by predators (P)  $\sim N \rightarrow$  No matter what, the predators never get full

**solution 2:** change term  $a NP \rightarrow f(N)*P$

$$f(N) = \frac{C_{max} \cdot N}{N + h}$$



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$$N' = r_1 N \left(1 - \frac{N}{k}\right) - \frac{wN}{d + N} P$$

w = maximal consumption rate

d = the prey density at which consumption is half the max rate

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$$T' = bT - \beta ST \longrightarrow N' = r_1 N - a N P$$

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Predator equation:

$$P' = r_2 P \left(1 - \frac{jP}{N}\right)$$

Logistic growth:

- Carrying capacity is set by the prey population!
- $j$  = number of prey needed to support one predator  $\rightarrow jP$  = number of prey necessary to support  $P$  predators
- $jP < N$ :  $P$  can grow
- $jP > N$ ,  $P$  exceeded its carrying capacity and must decline

### 3. Hopf bifurcation

The destruction of a stable equilibrium point and its replacement by an unstable equilibrium point and a stable limit cycle attractor is called Hopf bifurcation.

You can see this in the eigenvalues:

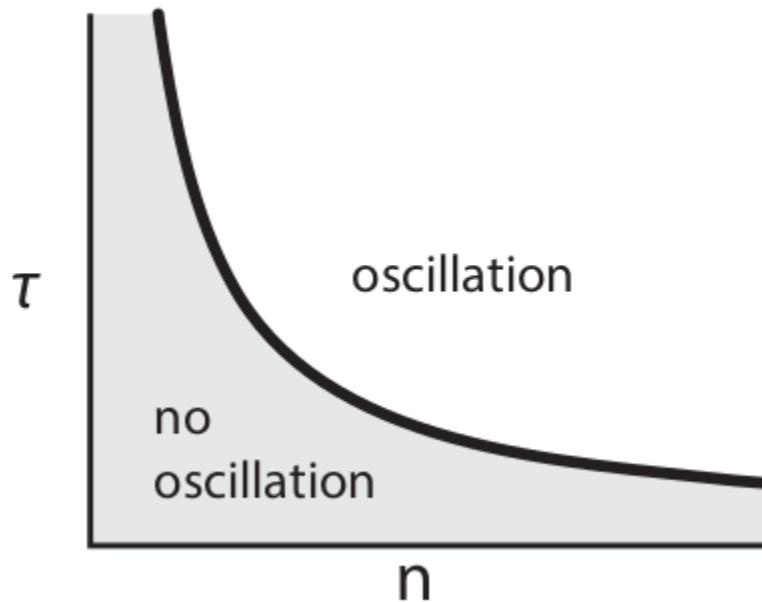
For a complex eigenvalue, the real part of the eigenvalue passes through zero from negative (stable) to positive (unstable)

# Exercise 5.3

### 3. Hopf bifurcation

Oscillations depend on:

- $n$ , which controls the steepness of the feedback,
- $\tau$ , which controls the time delay



The chief causes of oscillation in feedback systems are steep negative feedback and time delays