12/1/2016 Udacity Reviews



PROJECT SPECIFICATION

Train a Smartcab to Drive

[OPTIONAL] Getting Started

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
[OPTIONAL] Understand the World	Student provides a thorough discussion of the driving agent as it interacts with the environment.	
[OPTIONAL] Understand the Code	Student correctly addresses the questions posed about the Train a Smartcab to Drive code.	

Implement a Basic Driving Agent

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
Agent accepts inputs Produces a valid output Runs in simulator	Driving agent produces a valid action when an action is required. Rewards and penalties are received in the simulation by the driving agent in accordance with the action taken.	
[OPTIONAL] Basic Agent Simulation Results	A visualization is included that correctly captures the results of the basic driving agent.	
Basic Agent Simulation Analysis	Student summarizes observations about the basic driving agent and its behavior. Optionally, if a visualization is included, analysis is conducted on the results provided.	

Inform the Driving Agent

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
Identify States	Student justifies a set of features that best model each state of the driving agent in the environment. Unnecessary features not included in the state (if applicable) are similarly justified.	

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
[OPTIONAL] State Space	The total number of possible states is correctly reported. The student discusses whether the driving agent could learn a feasible policy within a reasonable number of trials for the given state space.	
Update Driving Agent State	The driving agent successfully updates its state based on the state definition and input provided.	

Implement a Q-Learning Driving Agent

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
Q-Learning AgentAgent updates Q-valuesPicks the best action	The driving agent chooses the best available action from the set of Q-values for a given state. Additionally, the driving agent updates a mapping of Q-values for a given state correctly when considering the learning rate and the reward or penalty received.	
[OPTIONAL] Q-Learning Agent Simulation Results	A visualization is included that correctly captures the results of the initial/default Q-Learning driving agent.	
Q-Learning Agent Simulation Analysis	Student summarizes observations about the initial/default Q-Learning driving agent and its behavior, and compares them to the observations made about the basic agent. If a visualization is included, analysis is conducted on the results provided.	

Improve the Q-Learning Driving Agent

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
Improved Q-Learning Agent • Improvements reported	The driving agent performs Q-Learning with alternative parameters or schemes beyond the initial/default implementation.	
[OPTIONAL] Improved Q-Learning Agent Simulation Results	A visualization is included that correctly captures the results of the improved Q-Learning driving agent.	

CRITERIA	MEETS SPECIFICATIONS	REVIEWER TIPS
Improved Q-Learning Agent Simulation Analysis • Improvements reported	Student summarizes observations about the optimized Q- Learning driving agent and its behavior, and further compares them to the observations made about the initial/default Q-Learning driving agent. If a visualization is included, analysis is conducted on the results provided.	
Safety and Reliability	The driving agent is able to safely and reliably guide the Smartcab to the destination before the deadline.	
Define an Optimal Policy	Student describes what an optimal policy for the driving agent would be for the given environment. The policy of the improved Q-Learning driving agent is compared to the stated optimal policy, and discussion is made as to whether the final driving agent commits to unusual or unexpected behavior based on the defined states.	
[OPTIONAL] Future Rewards	Student correctly identifies the two characteristics about the project that invalidate the use of future rewards in the Q-Learning implementation.	

Reviewer FAQ Student FAQ