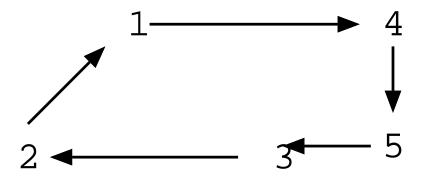
# 21-0: Strongly Connected Graph

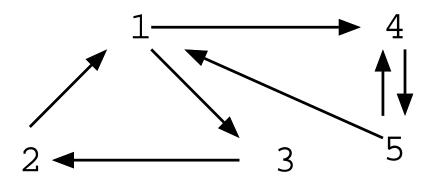
• Directed Path from every node to every other node



• Strongly Connected

## 21-1: Strongly Connected Graph

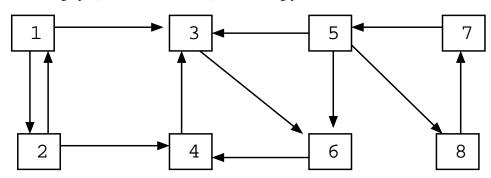
• Directed Path from every node to every other node



• Strongly Connected

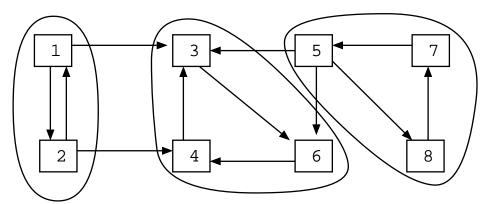
## 21-2: Connected Components

• Subgraph (subset of the vertices) that is strongly connected.



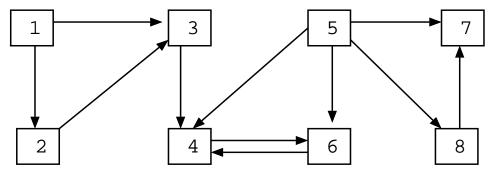
# 21-3: Connected Components

• Subgraph (subset of the vertices) that is strongly connected.



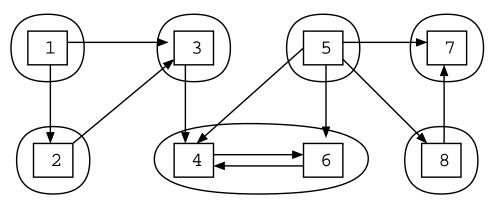
### 21-4: Connected Components

• Subgraph (subset of the vertices) that is strongly connected.



# 21-5: Connected Components

• Subgraph (subset of the vertices) that is strongly connected.



### 21-6: Connected Components

- Connected components of the graph are the *largest possible* strongly connected subgraphs
- If we put each vertex in its own component each component would be (trivially) strongly connected
  - Those would not be the connected components of the graph unless there were no larger connected subgraphs

### 21-7: Connected Components

- Calculating Connected Components
  - Two vertices  $v_1$  and  $v_2$  are in the same connected component if and only if:
    - Directed path from  $v_1$  to  $v_2$
    - Directed path from  $v_2$  to  $v_1$
  - To find connected components find directed paths
    - Use DFS

#### 21-8: DFS Revisited

- We can keep track of the order in which we visit the elements in a Depth-First Search
- For any vertex v in a DFS:
  - d[v] = Discovery time when the vertex is first visited
  - f[v] = Finishing time when we have finished with a vertex (and all of its children)

#### 21-9: DFS Revisited

```
class Edge {
   public int neighbor;
   public int next;
}

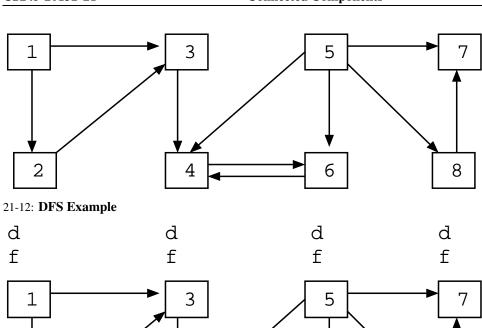
void DPS(Edge G[], int vertex, boolean Visited[], int d[], int f[]) {
   Edge tmp;
   Visited(vertex] = true;
   d[vertex] = time++;
   for (tmp = G[vertex]; tmp != null; tmp = tmp.next) {
      if (!Visited[tmp.neighbor])
            DPS(G, tmp.neighbor, Visited);
   }
   f[vertex] = time++;
}
```

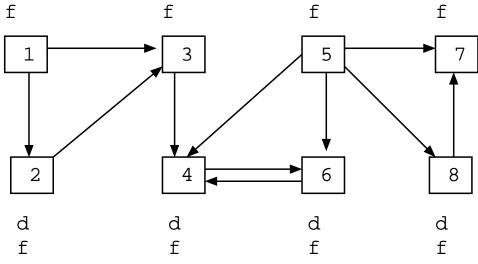
#### 21-10: DFS Revisited

• To visit every node in the graph:

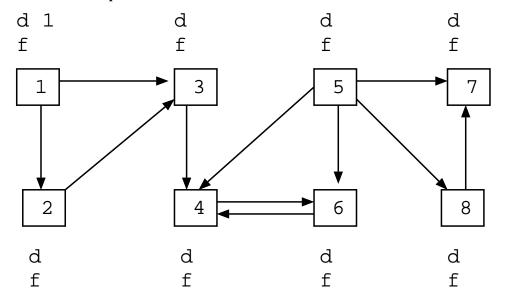
```
TraverseDFS(Edge G[]) {
  int i;
  boolean Visited = new boolean[G.length];
  int d = new int[G.length];
  int v = new int[G.length];
  time = 1;
  for (i=0; i<G.length; i++)
    Visited[i] = false;
  for (i=0; i<G.length; i++)
    if (!Visited[i])
        DFS(G, i, Visited, d, f);
}</pre>
```

### 21-11: **DFS Example**

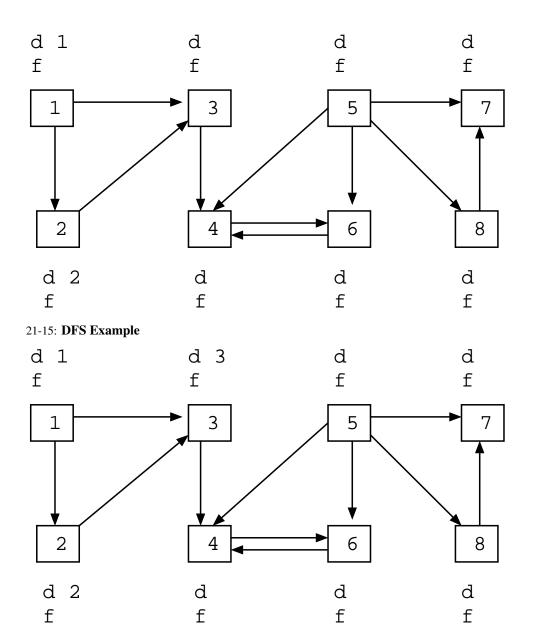




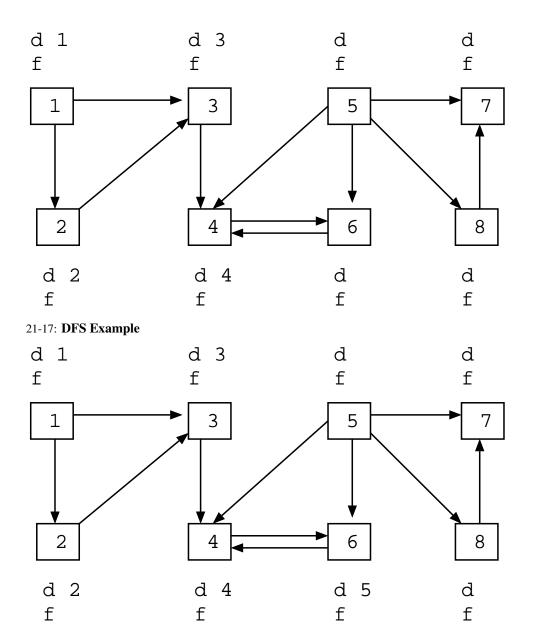
21-13: DFS Example



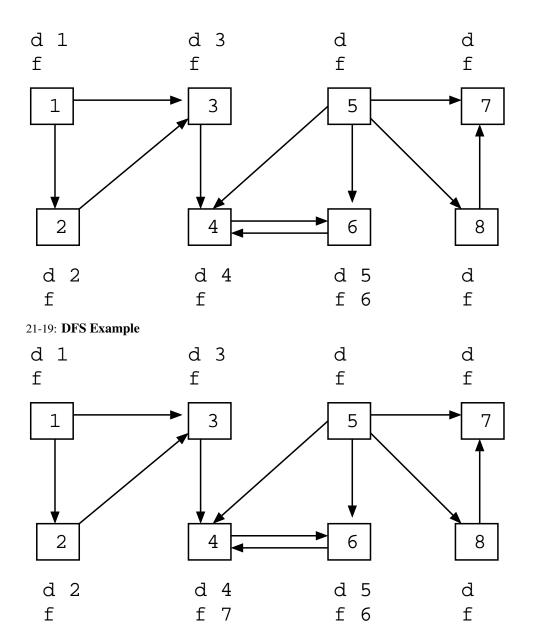
21-14: **DFS Example** 



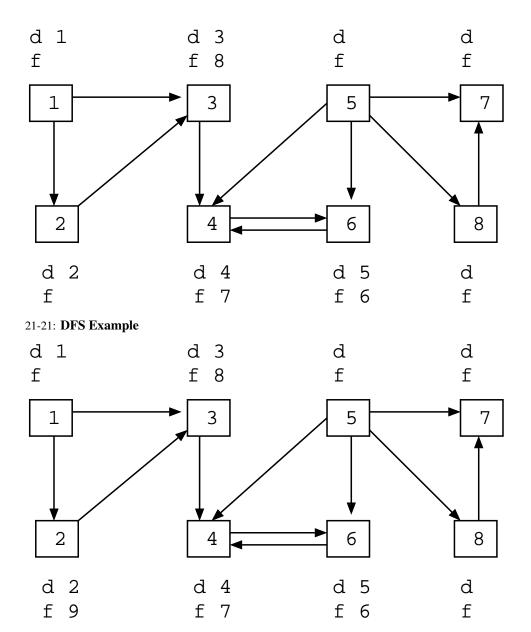
21-16: **DFS Example** 



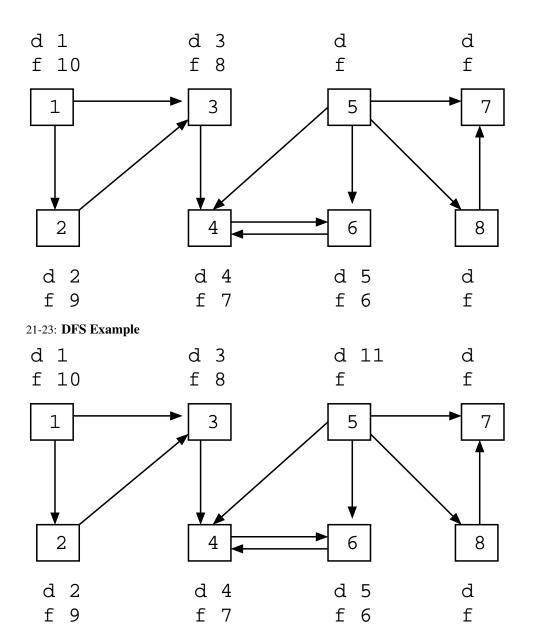
21-18: **DFS Example** 



21-20: DFS Example



21-22: DFS Example



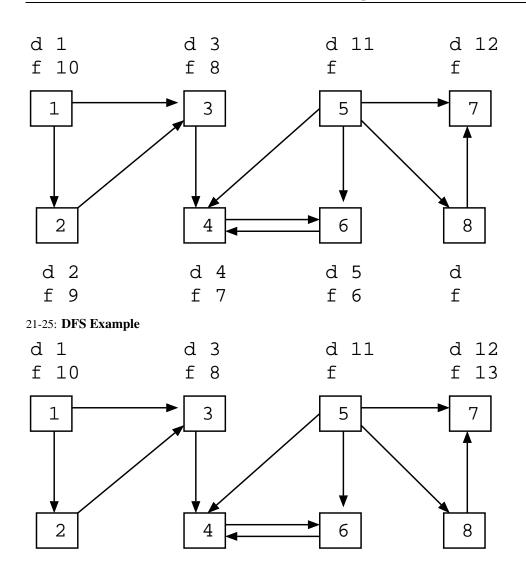
21-24: **DFS Example** 

d 5

f 6

d

f

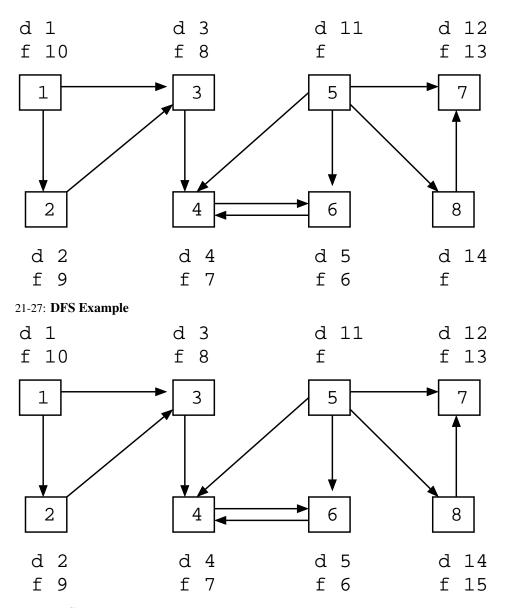


d 4

f 7

21-26: **DFS Example** 

d 2



21-28: **DFS Example** 

6

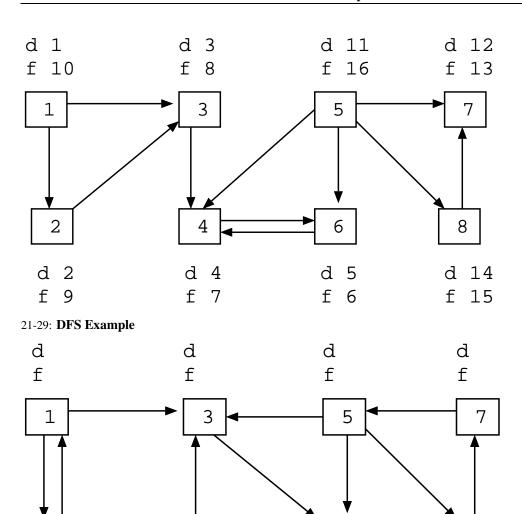
d

f

8

d

f



21-30: **DFS Example** 

d

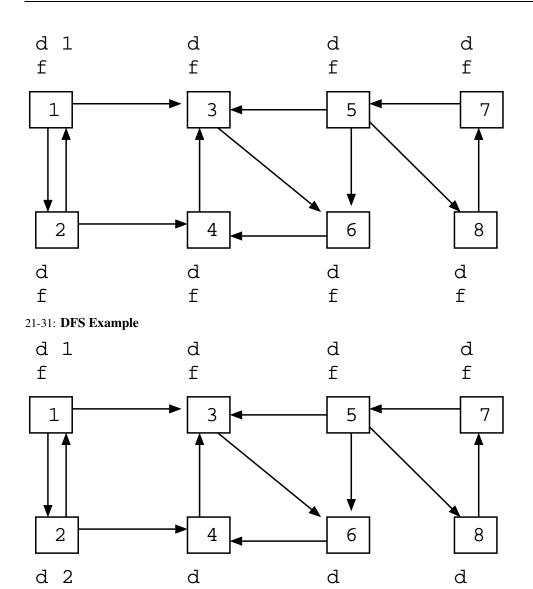
f

2

d

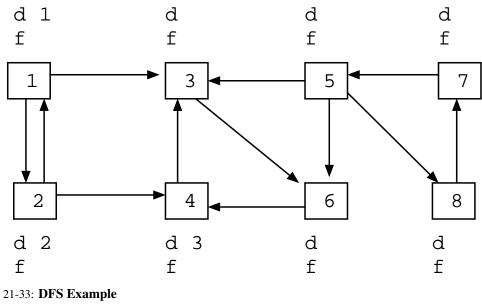
f

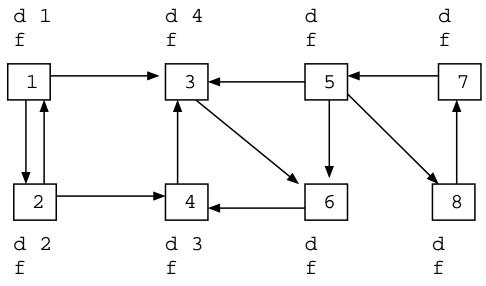
f



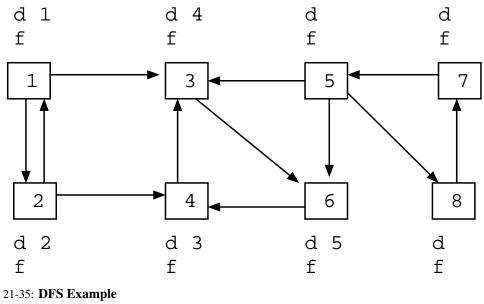
21-32: **DFS Example** 

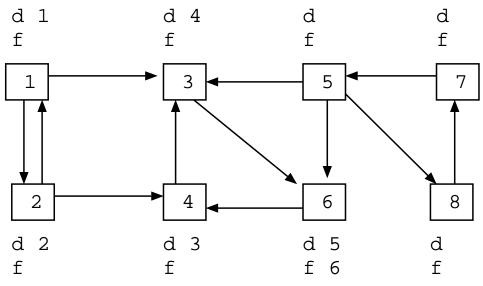
f



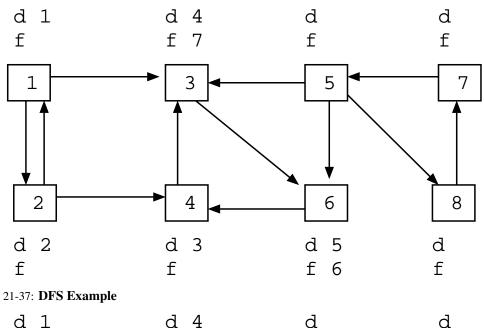


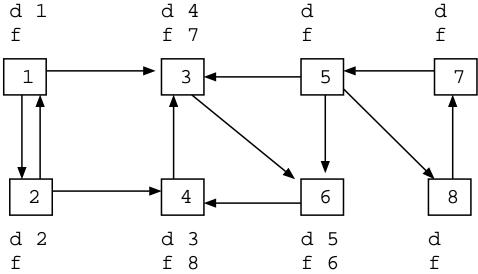
21-34: **DFS Example** 



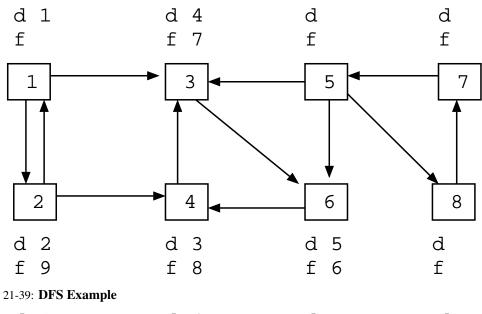


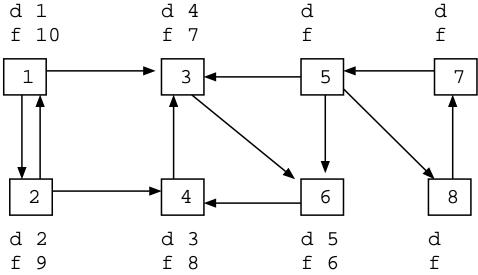
21-36: **DFS Example** 



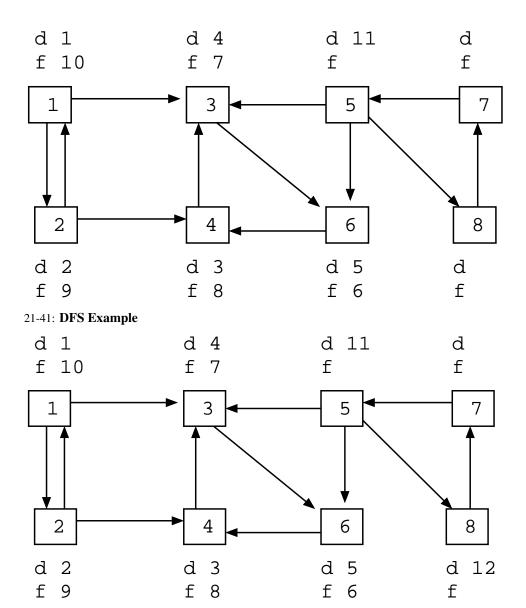


21-38: **DFS Example** 





21-40: **DFS Example** 



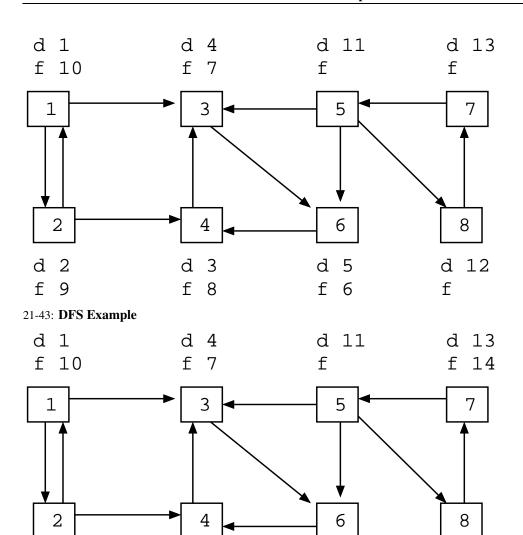
21-42: **DFS Example** 

d 5

f 6

d 12

f

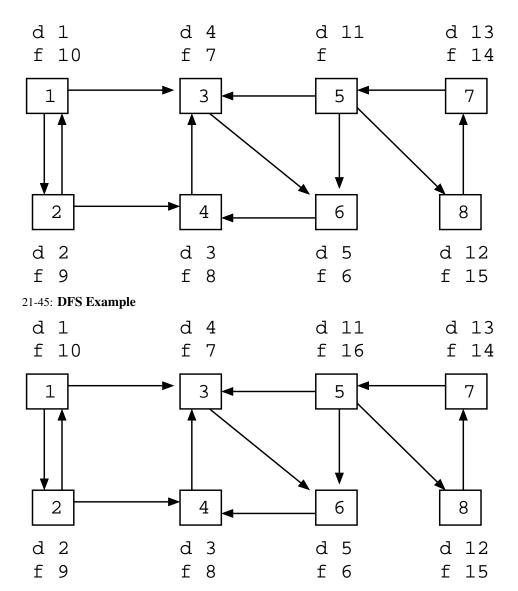


d 3

f 8

21-44: **DFS Example** 

d 2



21-46: **Using d[] & f[]** 

• Given two vertices  $v_1$  and  $v_2$ , what do we know if  $f[v_2] < f[v_1]$ ?

## 21-47: **Using d[] & f[]**

- Given two vertices  $v_1$  and  $v_2$ , what do we know if  $f[v_2] < f[v_1]$ ?
  - Either:
    - ullet Path from  $v_1$  to  $v_2$ 
      - Start from  $v_1$
      - ullet Eventually visit  $v_2$
      - $\bullet$  Finish  $v_2$
      - Finish  $v_1$

## 21-48: **Using d[] & f[]**

- Given two vertices  $v_1$  and  $v_2$ , what do we know if  $f[v_2] < f[v_1]$ ?
  - Either:
    - Path from  $v_1$  to  $v_2$
    - No path from  $v_2$  to  $v_1$ 
      - Start from  $v_2$
      - Eventually finish  $v_2$
      - Start from  $v_1$
      - Eventually finish  $v_1$

## 21-49: **Using d[] & f[]**

- If  $f[v_2] < f[v_1]$ :
  - Either a path from  $v_1$  to  $v_2$ , or no path from  $v_2$  to  $v_1$
  - If there is a path from  $v_2$  to  $v_1$ , then there must be a path from  $v_1$  to  $v_2$
- $f[v_2] < f[v_1]$  and a path from  $v_2$  to  $v_1 \Rightarrow v_1$  and  $v_2$  are in the same connected component

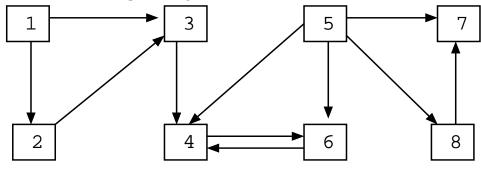
## 21-50: Calculating paths

- Path from  $v_2$  to  $v_1$  in G if and only if there is a path from  $v_1$  to  $v_2$  in  $G^T$ 
  - $G^T$  is the transpose of G G with all edges reversed
- If after DFS,  $f[v_2] < f[v_1]$
- Run second DFS on  $G^T$ , starting from  $v_1$ , and  $v_1$  and  $v_2$  are in the same DFS spanning tree
- ullet  $v_1$  and  $v_2$  must be in the same connected component

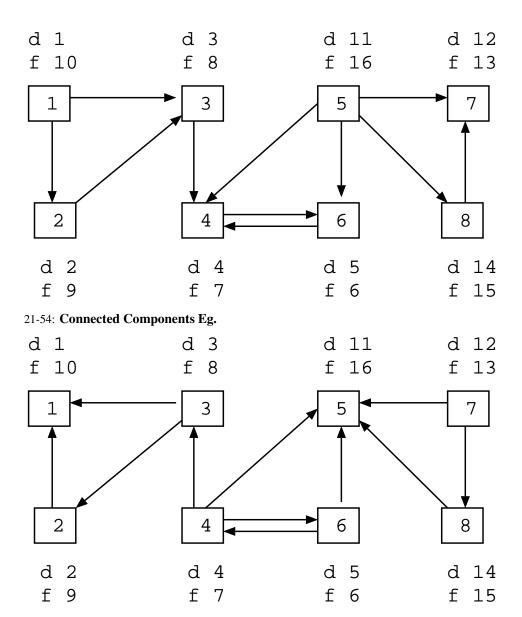
## 21-51: Connected Components

- Run DFS on G, calculating f[] times
- Compute  $G^T$
- Run DFS on  $G^T$  examining nodes in inverse order of finishing times from first DFS
- ullet Any nodes that are in the same DFS search tree in  $G^T$  must be in the same connected component

## 21-52: Connected Components Eg.

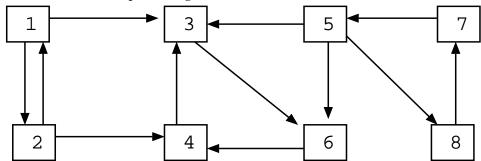


## 21-53: Connected Components Eg.

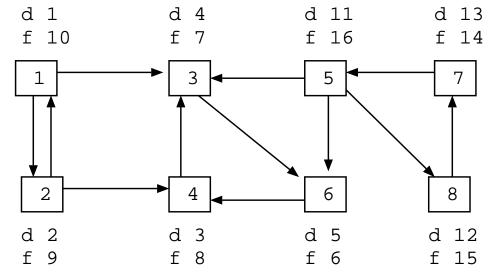


21-55: Connected Components Eg.

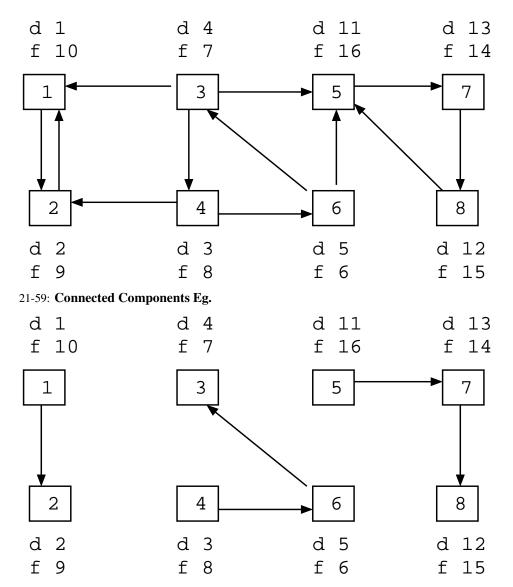
CS245-2013S-21	<b>Connected Components</b>		
d 1 f 10	d 3 f 8	d 11 f 16	d 12 f 13
2	4	6	8
d 2 f 9	d 4 f 7	d 5 f 6	d 14 f 15
21-56: Connected Cor	nponents Eg.	5	7



21-57: Connected Components Eg.



21-58: Connected Components Eg.



## 21-60: **Topological Sort**

- How could we use DFS to do a Topological Sort?
  - (Hint Use discover and/or finish times)

## 21-61: Topological Sort

- How could we use DFS to do a Topological Sort?
  - (Hint Use discover and/or finish times)
  - (What does it mean if node x finished before node y?)

# 21-62: **Topological Sort**

• How could we use DFS to do a Topological Sort?

- Do DFS, computing finishing times for each vertex
- As each vertex is finished, add to front of a linked list
- This list is a valid topological sort