# The Two Set Relations Generating Geometry

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ABSTRACT. A ruler (measuring stick) divides both domain and range intervals approximately into the nearest integer number of same-sized subintervals. As the subinterval size converges to zero: 1) Distance as the union size of range sets converges to: the triangle inequality with Manhattan distance at the upper boundary and Euclidean distance at the lower boundary. 2) The Cartesian product of the number of members in each domain set converges to the product of interval interval sizes (Euclidean area/volume). The ruler measure-based proofs of Euclidean distance and area/volume are used to derive the spacetime, charge force, and Newtonian gravity force equations. Time limits physical geometry to 3 dimensions. All proofs are verified in Coq.

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#### 1. Introduction

Real analysis introduction textbooks start with the step-by-step building of a foundation of continuity, convergence, limit, etc. from set definitions. But, metric space, Euclidean distance (metric/vector norm), and Euclidean area/volume (product of interval sizes) are defined in real analysis [Gol76] [Rud76] rather than built by applying that previously built foundation to yet more set definitions.

A "ruler" measure of intervals applies convergence to two types of set relations to derive the properties of distance and volume, which provides some new insights into geometry and physics, for example: 1) the single set relation generating the triangle inequality, non-negativity, and identity of indiscernibles properties of metric

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space; 2) the mapping between sets that makes Euclidean distance the smallest possible distance between two distinct points in  $\mathbb{R}^n$ ; 3) the mapping between sets that makes distance different from area/volume; 4) the set-based reason the forces of charge and gravity vary inversely with the square of the distance between two infinitesimal objects; 5) how time places an additional constraint on those same two set relations, which limits physical geometry to 3 dimensions.

All the proofs in this article have been formally verified using using the Coq proof verification system [Coq15]. The formal proofs are located in the Coq files, "euclidrelations.v" and "threed.v," at:

https://github.com/treeck/RASRGeometry.

## 2. Ruler measure and convergence

A ruler (measuring stick) partitions both domain and range intervals approximately into the nearest integer number of subintervals, where each subinterval has the same size, c, with the consequence that different-sized intervals have a different number of subintervals. In contrast, the Riemann and Lebesgue integrals partition each domain interval and the range into the same number of subintervals, where different-sized intervals have different-sized subintervals [Gol76] [Rud76].

The ruler measure allows counting the number of mappings, ranging from a one-to-one correspondence to a many-to-many mapping, between the set of subintervals having size c in one interval and the set of subintervals having the same size, c, in another interval. The mapping (combinatorial) relations converge to continuous, bijective relations as the subinterval size, c, converges to zero.

DEFINITION 2.1. Ruler measure: A ruler measures the size, M, of a closed, open, or semi-open interval as the sum of the sizes of the nearest integer number of whole subintervals, p, each subinterval having the same size, c. Notionally:

(2.1) 
$$\forall c \ s \in \mathbb{R}, \ [a,b] \subset \mathbb{R}, \ s = |a-b| \land c > 0 \land (p = floor(s/c) \lor p = ceiling(s/c)) \land M = \sum_{i=1}^{p} c = pc.$$

Theorem 2.2. Ruler convergence:  $\forall [a,b] \subset \mathbb{R}, \ s = |a-b| \Rightarrow M = \lim_{c \to 0} pc = s.$ 

The theorem, "limit\_c\_0\_M\_eq\_exact\_size," and formal proof is in the Coq file, euclidrelations.v.

PROOF. (epsilon-delta proof) By definition of the floor function,  $floor(x) = max(\{y : y \le x, y \in \mathbb{Z}, x \in \mathbb{R}\})$ :

 $(2.2) \ \forall \ c > 0, \ p = floor(s/c) \ \land \ 0 \leq |floor(s/c) - s/c| < 1 \ \Rightarrow \ 0 \leq |p - s/c| < 1.$ 

Multiply all sides of inequality 2.2 by |c|:

$$(2.3) \qquad \forall \ c>0, \quad 0\leq |p-s/c|<1 \quad \Rightarrow \quad 0\leq |pc-s|<|c|.$$

$$(2.4) \quad \forall \ \delta \ : \ |pc - s| < |c| = |c - 0| < \delta$$
 
$$\Rightarrow \quad \forall \ \epsilon = \delta : \ |c - 0| < \delta \ \land \ |pc - s| < \epsilon \ := \ M = \lim_{c \to 0} pc = s. \quad \Box$$

The proof steps using the ceiling function (the outer measure) are the same as the steps in the previous proof using the floor function (the inner measure). The following is an example of ruler convergence, where:  $[0,\pi]$ ,  $s=|0-\pi|$ ,  $c=10^{-i}$ , and  $p=floor(s/c) \Rightarrow p \cdot c = 3.1_{i=1}, 3.14_{i=2}, 3.141_{i=3}, ..., \pi$ .

#### 3. Distance

**Notation convention:** Curly brackets,  $\{\cdots\}$ , delimit a set; square brackets,  $[\cdots]$ , delimit a list; and vertical bars around a set or list,  $|\cdots|$ , indicates the cardinal (number of members in the set or list).

**3.1.** Countable distance space. A simple measure of distance is the number of steps walked, which corresponds to an equal number of pieces of land. Abstracting, distance is proportionate to the number of members in a range set,  $y_i$ , which equals the number of members in a corresponding domain set,  $x_i$ :  $|x_i| = |y_i|$ . And the distance spanning multiple, disjoint, domain sets,  $\bigcap_{i=1}^n x_i = \emptyset$ , is proportionate to the number of members,  $d_c$ , in the union range set:  $d_c = |\bigcup_{i=1}^n y_i|$ .

Definition 3.1. Countable distance space,  $d_c$ :

$$\bigcap_{i=1}^{n} x_i = \emptyset \quad \land \quad d_c = |\bigcup_{i=1}^{n} y_i| \quad \land \quad |x_i| = |y_i|.$$

Theorem 3.2. Inclusion-exclusion Inequality:  $|\bigcup_{i=1}^n y_i| \leq \sum_{i=1}^n |y_i|$ .

This well-known inequality follows from the inclusion-exclusion principle [CG15]. But, a more intuitive and simple proof follows from the associative law of addition, which requires the sum of the set sizes to equal the size of all the set members appended into a list. And, by the commutative law of addition, the list can be sorted into a list of unique members (the union set) and a list of duplicate members. For example,  $|\{a,b,c\}| + |\{c,d,e\}| = |[a,b,c,c,d,e]| = |\{a,b,c,d,e\}| + |[c]| \Rightarrow |\{a,b,c,d,e\}| = |\{a,b,c\}| + |\{c,d,e\}| - |[c]|$ . The list of duplicates being  $\geq 0$  implies the union set size is  $\leq$  the sum of the set sizes.

A formal proof, inclusion\_exclusion\_inequality, using sorting into a set of unique members (union set) and a list of duplicate members, is in the file euclidrelations.v.

PROOF. By the associative law of addition, append the sets into a list. Next, by the commutative law of addition, sort the list into uniques and duplicates, and then subtract duplicates from both sides:

$$\begin{array}{ll} (3.1) & \sum_{i=1}^{n}|y_{i}|=|append_{i=1}^{n}y_{i}|=|sort(append_{i=1}^{n}y_{i})|\\ &=|\bigcup_{i=1}^{n}y_{i}|+|duplicates_{i=1}^{n}y_{i}| \quad \Rightarrow \quad \sum_{i=1}^{n}|y_{i}|-|duplicates_{i=1}^{n}y_{i}|=|\bigcup_{i=1}^{n}y_{i}|. \end{array}$$

(3.2) 
$$|\bigcup_{i=1}^{n} y_i| = \sum_{i=1}^{n} |y_i| - |duplicates_{i=1}^{n} y_i| \wedge |duplicates_{i=1}^{n} y_i| \geq 0$$
  
 $\Rightarrow |\bigcup_{i=1}^{n} y_i| \leq \sum_{i=1}^{n} |y_i|. \square$ 

**3.2.** Metric Space. All function range intervals, d(u, w), satisfying the countable distance space definition,  $d_c = |\bigcup_{i=1}^n y_i|$ , where the ruler is applied, generates the three metric space properties: triangle inequality, non-negativity, and identity of indecernables. The fourth property of metric space, symmetry [d(u, v) = d(v, u)], is motivated by Manhattan and Euclidean distance. The formal proofs: triangle\_inequality, non\_negativity, and identity\_of\_indiscernibles are in the Coq file, euclidrelations.v.

Theorem 3.3. Triangle Inequality:  $d_c = |y_1 \cup y_2| \Rightarrow d(u, w) \leq d(u, v) + d(v, w)$ .

PROOF. Apply the ruler measure (2.1), the countable distance space condition (3.1), inclusion-exclusion inequality (3.2), and then ruler convergence (2.2).

$$\begin{aligned} (3.3) \quad \forall \, c > 0, \, d(u,w), \, d(u,v), \, d(v,w) \, : \\ |y_1| &= floor(d(u,v)/c) \quad \wedge \quad |y_2| = floor(d(v,w)/c) \quad \wedge \\ d_c &= floor(d(u,w)/c) \quad \wedge \quad d_c = |y_1 \cup y_2| \leq |y_1| + |y_2| \\ \Rightarrow \quad floor(d(u,w)/c) \leq floor(d(u,v)/c) + floor(d(v,w)/c) \\ \Rightarrow \quad floor(d(u,w)/c) \cdot c \leq floor(d(u,v)/c) \cdot c + floor(d(v,w)/c) \cdot c \\ \Rightarrow \quad \lim_{c \to 0} floor(d(u,w)/c) \cdot c \leq \lim_{c \to 0} floor(d(u,v)/c) \cdot c + \lim_{c \to 0} floor(d(v,w)/c) \cdot c \\ \Rightarrow \quad d(u,w) \leq d(u,v) + d(v,w). \quad \Box \end{aligned}$$

Theorem 3.4. Non-negativity:  $d_c = |y_1 \cup y_2| \Rightarrow d(u, w) \ge 0$ .

Proof.

$$(3.4) \quad \forall c > 0, \ d(u, w) : \quad floor(d(u, w)/c) = d_c \quad \land \quad d_c = |y_1 \cup y_2| \ge 0$$

$$\Rightarrow \quad floor(d(u, w)/c) = d_c \ge 0 \quad \Rightarrow \quad d(u, w) = \lim_{c \to 0} d_c \cdot c \ge 0. \quad \Box$$

Theorem 3.5. Identity of Indiscernibles: d(w, w) = 0.

PROOF. Apply the triangle inequality property (3.3):

$$(3.5) \quad \forall \ d(u,v) = d(v,w) = 0 \ \land \ d(u,w) \le d(u,v) + d(v,w) \ \Rightarrow \ d(u,w) \le 0.$$

Combine the non-negativity property (3.4) and the previous inequality (3.5):

$$(3.6) \hspace{1cm} d(u,w) \geq 0 \hspace{0.2cm} \wedge \hspace{0.2cm} d(u,w) \leq 0 \hspace{0.2cm} \Leftrightarrow \hspace{0.2cm} 0 \leq d(u,w) \leq 0 \hspace{0.2cm} \Rightarrow \hspace{0.2cm} d(u,w) = 0.$$

(3.7) 
$$d(u, w) = 0 \land d(u, v) = 0 \Rightarrow w = v.$$

$$(3.8) d(v,w) = 0 \wedge w = v \Rightarrow d(w,w) = 0.$$

**3.3. Distance space range.**  $d_c = |\bigcup_{i=1}^n y_i|$  implies that distance varies inversely to the amount of intersection of the range sets. As the amount of intersection increases, a single range set member can map to more domain set members. Therefore,  $d_c$  is a function of range-to-domain set member mappings.

From the countable distance space property (3.1), where  $|x_i| = |y_i| = p_i$ , the total number of range-to-domain set member mappings vary from the sum of one-to-one correspondences (no intersection and largest distance),  $\sum_{i=1}^{n} x_i \cdot 1 = \sum_{i=1}^{n} p_i$ , to the sum of the most many-to-many correspondences (largest intersection and smallest possible distance),  $\sum_{i=1}^{n} |x_i| \cdot |y_i| = \sum_{i=1}^{n} p_i^2$ . Applying the ruler (2.1) and ruler convergence theorem (2.2) to the smallest and largest total number of range-to-domain set mapping cases converges to the real-valued, Manhattan and Euclidean distance relations.

#### 3.4. Manhattan distance.

THEOREM 3.6. Manhattan (largest) distance, d, is the size of the range interval,  $[d_0, d_m]$ , corresponding to a set of disjoint domain intervals,

$$\{[a_1,b_1],[a_2,b_2],\ldots,[a_n,b_n]\},$$
 where:

$$d = \sum_{i=1}^{n} s_i$$
,  $d = |d_0 - d_m|$ ,  $s_i = |a_i - b_i|$ .

The theorem, "taxicab\_distance," and formal proof is in the Coq file, euclidrelations.v.

Proof.

From the countable distance space definition (3.1) and the inclusion-exclusion inequality (3.2), the largest possible countable distance,  $d_c$ , is the equality case:

(3.9) 
$$d_c = |\bigcup_{i=1}^n y_i| \le \sum_{i=1}^n |y_i| \wedge |x_i| = |y_i| = p_i$$
  
 $\Rightarrow d_c \le \sum_{i=1}^n |y_i| = \sum_{i=1}^n p_i \Rightarrow \exists p_i, d_c : d_c = \sum_{i=1}^n p_i.$ 

Multiply both sides of equation 3.11 by c and take the limit:

(3.10) 
$$d_c = \sum_{i=1}^n p_i \Rightarrow d_c \cdot c = \sum_{i=1}^n (p_i \cdot c) \Rightarrow \lim_{c \to 0} d_c \cdot c = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c).$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) to the definition of d:

$$(3.11) d = |d_0 - d_m| \Rightarrow \exists c d: floor(d/c) = d_c \Rightarrow d = \lim_{c \to 0} d_c \cdot c.$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) to the definition of  $s_i$ :

$$(3.12) \ \forall \ i \in [1, n], s_i = |a_i - b_i| \land floor(s_i/c) = |x_i| = |y_i| = p_i \Rightarrow \lim_{c \to 0} p_i \cdot c = s_i.$$

Combine equations 3.11, 3.10, 3.12:

(3.13) 
$$d = \lim_{c \to 0} d_c \cdot c \wedge \lim_{c \to 0} d_c \cdot c = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c) \wedge \lim_{c \to 0} (p_i \cdot c) = s_i \Rightarrow d = \lim_{c \to 0} d_c \cdot c = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c) = \sum_{i=1}^n s_i.$$

### 3.5. Euclidean distance.

THEOREM 3.7. Euclidean (smallest) distance, d, is the size of the range interval,  $[d_0, d_m]$ , corresponding to a set of disjoint domain intervals,

$$\{[a_1,b_1],[a_2,b_2],\ldots,[a_n,b_n]\}, where:$$

$$d^2 = \sum_{i=1}^n s_i^2$$
,  $d = |d_0 - d_m|$ ,  $s_i = |a_i - b_i|$ .

The theorem, "Euclidean\_distance," and formal proof is in the Coq file, euclidrelations.v.

Proof.

Apply the rule of product to the largest number of range-to-domain set mappings, where all  $p_i$  number of range set members,  $y_i$ , map to each of the  $p_i$  number of members in the domain set,  $x_i$ :

(3.14) 
$$\sum_{i=1}^{n} |y_i| \cdot |x_i| = \sum_{i=1}^{n} p_i^2.$$

From the countable distance space definition (3.1) and the inclusion-exclusion inequality (3.2), choose the equality case:

Square both sides of equation 3.15  $(x = y \Leftrightarrow f(x) = f(y))$ :

(3.16) 
$$\exists p_i, d_c : d_c = \sum_{i=1}^n p_i \iff \exists p_i, d_c : d_c^2 = (\sum_{i=1}^n p_i)^2.$$

Apply the Cauchy-Schwartz inequality,  $(\sum_{i=1}^{n} p_i)^2 \ge \sum_{i=1}^{n} p_i^2$ , to equation 3.16 and select the smallest area (the equality) case:

$$(3.17) \quad \forall p_{i}, p_{j} \in \{p_{1}, \cdots, p_{n}\} \quad \land \quad p_{i}, p_{j} \geq 0 \quad \land \quad d_{c} = \sum_{i=1}^{n} p_{i}$$

$$\Rightarrow \quad d_{c}^{2} = (\sum_{i=1}^{n} p_{i})^{2} = (\sum_{j=1}^{n} p_{j}) \cdot (\sum_{i=1}^{n} p_{i}) = \sum_{j=1}^{n} (p_{j} \cdot \sum_{i=1}^{n} p_{i})$$

$$= \sum_{j=1, i=j}^{n} (p_{j} \cdot p_{i}) + \sum_{j=1, i \neq j}^{n} (p_{j} \cdot \sum_{i=1}^{n} p_{i})$$

$$= \sum_{i=1}^{n} p_{i}^{2} + \sum_{j=1, i \neq j}^{n} (p_{j} \cdot \sum_{i=1}^{n} p_{i}) \geq \sum_{i=1}^{n} p_{i}^{2}$$

$$\Rightarrow \quad \exists p_{i} : d_{c}^{2} = \sum_{i=1}^{n} p_{i}^{2}.$$

Multiply both sides of equation 3.17 by  $c^2$ , simplify, and take the limit.

$$(3.18) \quad d_c^2 = \sum_{i=1}^n p_i^2 \implies d_c^2 \cdot c^2 = \sum_{i=1}^n p_i^2 \cdot c^2 \iff (d_c \cdot c)^2 = \sum_{i=1}^n (p_i \cdot c)^2 \\ \implies \lim_{c \to 0} (d_c \cdot c)^2 = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c)^2.$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) and square both sides:

$$(3.19) \quad \exists \ c \ d: \ floor(d/c) = d_c \quad \Rightarrow \quad d = \lim_{c \to 0} d_c \cdot c \quad \Rightarrow \quad d^2 = \lim_{c \to 0} (d_c \cdot c)^2.$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) to each domain interval: (3.20)

$$\forall i \in [1, n], \ s_i = |a_i - b_i| \ \land \ floor(s_i/c) = |x_i| = |y_i| = p_i \ \Rightarrow \ \lim_{c \to 0} (p_i \cdot c) = s_i.$$

Combine equations 3.19, 3.18, 3.20:

(3.21) 
$$d^2 = \lim_{c \to 0} (d_c \cdot c)^2 \wedge \lim_{c \to 0} (d_c \cdot c)^2 = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c)^2 \wedge \lim_{c \to 0} (p_i \cdot c) = s_i \Rightarrow d^2 = \lim_{c \to 0} (d_c \cdot c)^2 = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c)^2 = \sum_{i=1}^n s_i^2.$$

#### 4. Euclidean Volume

The number of all possible combinations (n-tuples) taking one member from each disjoint set is the Cartesian product of the number of members in each set. Notionally:

Definition 4.1. Countable Volume,  $V_c$ :

$$\bigcap_{i=1}^{n} x_i = \emptyset \quad \land \quad V_c = \prod_{i=1}^{n} |x_i|.$$

Theorem 4.2. Euclidean volume, V, is size of the range interval,  $[v_0, v_m]$ , corresponding to all the possible combinations of the members of disjoint domain intervals,  $\{[a_1, b_1], [a_2, b_2], \ldots, [a_n, b_n]\}$ . Notionally:

$$V = \prod_{i=1}^{n} s_i, \ V = |v_0 - v_m|, \ s_i = |a_i - b_i|.$$

The theorem, "Euclidean\_volume," and formal proof is in the Coq file, euclidrelations.v.

Proof.

Use the ruler (2.1) to divide the exact size,  $s_i = |a_i - b_i|$ , of each of the domain intervals,  $[a_i, b_i]$ , into a set,  $x_i$  of  $p_i$  number of subintervals.

$$(4.1) \forall i \ n \in \mathbb{N}, \quad i \in [1, n], \quad c > 0 \quad \land \quad floor(s_i/c) = p_i = |x_i|.$$

Apply the ruler convergence theorem (2.2) to equation 4.1:

$$(4.2) floor(s_i/c) = p_i \Rightarrow \lim_{c \to 0} (p_i \cdot c) = s_i.$$

Use the ruler (2.1) to divide the exact size,  $V = |v_0 - v_m|$ , of the range interval,  $[v_0, v_m]$ , into  $p^n$  subintervals. Use those cases, where  $V_c$  has an integer  $n^{th}$  root.

(4.3) 
$$\forall p^n = V_c \in \mathbb{N}, \exists V \in \mathbb{R}, x_i : floor(V/c^n) = V_c = p^n = \prod_{i=1}^n |x_i| = \prod_{i=1}^n p_i.$$

Apply the ruler convergence theorem (2.2) to equation 4.3 and simplify:

$$(4.4) floor(V/c^n) = p^n \Rightarrow V = \lim_{c \to 0} p^n \cdot c^n = \lim_{c \to 0} (p \cdot c)^n.$$

Multiply both sides of equation 4.3 by  $c^n$  and simplify:

$$(4.5) \quad p^n = \prod_{i=1}^n p_i \quad \Rightarrow \quad p^n \cdot c^n = (\prod_{i=1}^n p_i) \cdot c^n \quad \Leftrightarrow \quad (p \cdot c)^n = \prod_{i=1}^n (p_i \cdot c)$$
$$\Rightarrow \quad \lim_{c \to 0} (p \cdot c)^n = \prod_{i=1}^n \lim_{c \to 0} (p_i \cdot c)$$

Combine equations 4.4, 4.5, and 4.2:

$$(4.6) \quad V = \lim_{c \to 0} (p \cdot c)^n \quad \wedge \quad \lim_{c \to 0} (p \cdot c)^n = \prod_{i=1}^n \lim_{c \to 0} (p_i \cdot c) \quad \wedge$$
  
$$\lim_{c \to 0} (p_i \cdot c) = s_i \quad \Rightarrow \quad V = \lim_{c \to 0} (p \cdot c)^n = \prod_{i=1}^n \lim_{c \to 0} (p_i \cdot c) = \prod_{i=1}^n s_i. \quad \Box$$

### 5. Applications to physics

**5.1. Spacetime equations.** From the Euclidean distance proof (3.7), the Euclidean range interval, [0, D], is the smallest distance interval spanning two independent domain intervals,  $[0, d_1]$  and  $[0, d_2]$ . Therefore, any interval, [0, t], proportionate to the smallest range interval, [0, D], is measured in terms of a proportionality constant, c, that is the ratio of some value,  $d_c$  to some value,  $t_c$ , such that  $D = (d_c/t_c)t = ct$ .

(5.1) 
$$D^2 = d_1^2 + d_2^2 \quad \land \quad D = (d_c/t_c)t = ct$$
  
 $\Rightarrow \quad (ct)^2 = d_1^2 + d_2^2 \quad \Rightarrow \quad d_2 = \sqrt{(ct)^2 - d_1^2}.$ 

(5.2) 
$$d_2 = \sqrt{(ct)^2 - d_1^2} \quad \land \quad d = d_2 \quad \land \quad d_1 = vt$$
  

$$\Rightarrow \quad d = \sqrt{(ct)^2 - (vt)^2} = ct\sqrt{1 - (v^2/c^2)},$$

which is the spacetime dilation equation. [Bru17].

(5.3) 
$$d_2 = \sqrt{(ct)^2 - d_1^2} \quad \land \quad d = d_2 \quad \land \quad d_1^2 = x^2 + y^2 + z^2$$
  

$$\Rightarrow \quad d = \sqrt{(ct)^2 - (x^2 + y^2 + z^2)},$$

which is the four-vector length of the spacetime interval (relativistic change in 3-dimensional Euclidean distance) [Bru17].

**5.2.** Charge and gravity force equations. Apply the ruler to the two independent domain intervals,  $[0, q_1]$  and  $[0, q_2]$ . Each subinterval of  $[0, q_1]$  is a force that interacts (corresponds to) all the subintervals in  $[0, q_2]$ . The number of possible correspondences (interactions) is the Cartesian product of the number of subintervals in each interval. And applying the volume proof (3.3), the Cartesian product of the subinterval sizes converges to the area size,  $q_1q_2$ , as the subinterval size converges to zero.

For any interval, [0, q], there is a proportionately sized interval, [0, r]:

(5.4) 
$$\forall q_1 q_2 \in \mathbb{R} \exists q \in \mathbb{R} : q^2 = q_1 q_2 \land r(q_C/r_C) = q$$
  
 $\Rightarrow (r(q_C/r_C))^2 = q_1 q_2 \Rightarrow 1 = (r_C^2/q_C^2)q_1 q_2/r^2.$ 

Use force (F = ma) ratios equal to the scalar (unit-less) value one:

$$(5.5) \exists m_0, m_C, a, a_C \in \mathbb{R} : (m_0 a / m_C a_C) = 1 = (r_C^2 / q_C^2) q_1 q_2 / r^2.$$

Multiplying both sides of equation 5.5 by  $m_C a_C$  yields the charge force equation:

(5.6) 
$$(m_0 a/m_C a_C)(m_C a_C) = (r_C^2/q_C^2)(q_1 q_2/r^2)(m_C a_C)$$
  
 $\Rightarrow \exists F, k_C \in \mathbb{R} : F = m_0 a = (m_C a_C r_C^2/q_C^2)q_1 q_2/r^2 = k_C q_1 q_2/r^2,$ 

where  $k_C = m_C a_C r_C^2/q_C^2$  agrees with the accepted standard units:  $Nm^2C^{-2}$ .

As with charge, applying the ruler to two independent force intervals,  $[0, m_1]$  and  $[0, m_1]$ , converges to the area size,  $m_1m_2$ . And using intervals of type, [0, m], that are proportionate in size to [0, r]:

(5.7) 
$$\forall m_1 m_2 \in \mathbb{R} \exists m \in \mathbb{R} : m^2 = m_1 m_2 \land r(m_g/r_g) = m$$
  
 $\Rightarrow (r(m_g/r_g))^2 = m_1 m_2 \Rightarrow 1 = (r_g^2/m_g^2)m_1 m_2/r^2.$ 

Use force (F = ma) ratios equal to the scalar (unit-less) value one:

(5.8) 
$$\exists m_0, m_G, a, a_G \in \mathbb{R} : (m_0 a / m_G a_G) = 1 = (r_g^2 / m_g^2) m_1 m_2 / r^2.$$

Multiplying both sides of equation 5.8 by  $m_G a_G$  yields the charge force equation:

(5.9) 
$$(m_0 a/m_G a_G)(m_G a_G) = (r_g^2/m_g^2)(m_1 m_2/r^2)(m_G a_G)$$
  
 $\Rightarrow \exists F, k_C \in \mathbb{R} : F = m_0 a = (m_G a_G r_g^2/m_g^2)m_1 m_2/r^2 = Gm_1 m_2/r^2,$ 

where  $G = m_G a_G r_g^2 / m_g^2$  agrees with the accepted standard units:  $m^3 k g^{-1} s^{-2}$ .

**5.3.** 3 dimensions of physical geometry. The set and arithmetic operations used to calculate distance and volume requires sequencing through a totally ordered set of dimensions, for example, the countable distance space:  $d_c = |\bigcup_{i=1}^n y_i|$ , Euclidean distance:  $d^2 = \sum_{i=1}^n s_i^2$ , countable volume:  $V_c = \prod_{i=1}^n |x_i|$ , and Euclidean volume:  $V = \prod_{i=1}^n s_i$ . The commutative property of the set and arithmetic operations also allows sequencing through a set of n number of dimensions in all n! number of possible orders.

But, a physical, deterministic sequencer requires a physical set to have a single total order, at most one successor and at most one predecessor per set member, during the time of sequencing. A total order is the only way to "determine" that a sequencer traversed in the order,  $[2, 1, \cdots]$ , and next sequenced in the order,  $[1, 2, \cdots]$ , during some time period. Deterministic sequencing in every possible order via the same successor/predecessor relations (same total order) requires each set member to be either a successor or predecessor to every other set member (sequentially adjacent), herein referred to as a symmetric geometry.

It will now be proved that a set satisfying the constraints of a single total order and also symmetric defines a cyclic set containing at most 3 members, in this case, 3 dimensions of physical space.

Definition 5.1. Ordered geometry:

$$\forall i \ n \in \mathbb{N}, \ i \in [1, n-1], \ \forall x_i \in \{x_1, \dots, x_n\},$$
$$successor \ x_i = x_{i+1} \ \land \ predecessor \ x_{i+1} = x_i.$$

DEFINITION 5.2. Symmetric geometry (every set member is sequentially adjacent to any other member):

 $\forall i \ j \ n \in \mathbb{N}, \ \forall x_i \ x_j \in \{x_1, \dots, x_n\}, \ successor \ x_i = x_j \ \Leftrightarrow \ predecessor \ x_j = x_i.$ 

Theorem 5.3. An ordered and symmetric set is a cyclic set.

successor 
$$x_n = x_1 \land predecessor x_1 = x_n$$
.

The theorem, "ordered\_symmetric\_is\_cyclic," and formal proof is in the Coq file, threed.v.

PROOF. A total order (5.1) defines unique successors and predecessors for all set members except for the successor of  $x_n$  and the predecessor of  $x_1$ . Therefore, the only member that can be a successor of  $x_n$ , without creating a contradiction, is  $x_1$ . And the only member that can be a predecessor of  $x_1$ , without creating a contradiction, is  $x_n$ . From the properties of a symmetric geometry (5.2):

$$(5.10) i = n \land j = 1 \land successor x_i = x_j \Rightarrow successor x_n = x_1.$$

(5.11) 
$$i = n \land j = 1 \land predecessor x_j = x_i \Rightarrow predecessor x_1 = x_n.$$

Theorem 5.4. An ordered and symmetric set is limited to at most 3 members.

The lemmas and formal proofs in the Coq file threed.v are:

Lemmas: adj111, adj122, adj212, adj123, adj133, adj233, adj213, adj313, adj323, and not\_all\_mutually\_adjacent\_gt\_3.

The following proof uses Horn clauses (a subset of first-order logic) that uses unification and resolution. Horn clauses make it clear which facts satisfy a proof goal.

Proof.

It was proved that an ordered and symmetric set is a cyclic set (5.3). In other words, the successors and predecessors of an ordered and symmetric set are cyclic:

Definition 5.5. Cyclic successor of m is n:

$$(5.12) \ \ Successor(m,n,setsize) \leftarrow (m=setsize \land n=1) \lor (n=m+1 \leq setsize).$$

Definition 5.6. Cyclic predecessor of m is n:

$$(5.13) \quad Predecessor(m, n, setsize) \leftarrow (m = 1 \land n = setsize) \lor (n = m - 1 \ge 1).$$

DEFINITION 5.7. Adjacent: member m is sequentially adjacent to member n if the cyclic successor of m is n or the cyclic predecessor of m is n. Notionally: (5.14)

 $Adjacent(m, n, setsize) \leftarrow Successor(m, n, setsize) \vee Predecessor(m, n, setsize).$ 

Every member is adjacent to every other member, where  $setsize \in \{1, 2, 3\}$ :

$$(5.15) \qquad Adjacent(1,1,1) \leftarrow Successor(1,1,1) \leftarrow (m = setsize \land n = 1).$$

$$(5.16) Adjacent(1,2,2) \leftarrow Successor(1,2,2) \leftarrow (n=m+1 \leq setsize).$$

$$(5.17) \hspace{1cm} \textit{Adjacent}(2,1,2) \leftarrow Successor(2,1,2) \leftarrow (n = setsize \land m = 1).$$

- $(5.18) Adjacent(1,2,3) \leftarrow Successor(1,2,3) \leftarrow (n=m+1 \leq setsize).$
- $(5.19) Adjacent(2,1,3) \leftarrow Predecessor(2,1,3) \leftarrow (n=m-1 \ge 1).$
- $(5.20) \qquad Adjacent(3,1,3) \leftarrow Successor(3,1,3) \leftarrow (n = setsize \land m = 1).$
- $(5.21) Adjacent(1,3,3) \leftarrow Predecessor(1,3,3) \leftarrow (m=1 \land n=setsize).$
- $(5.22) Adjacent(2,3,3) \leftarrow Successor(2,3,3) \leftarrow (n=m+1 \leq setsize).$
- $(5.23) \qquad Adjacent(3,2,3) \leftarrow Predecessor(3,2,3) \leftarrow (n=m-1 > 1).$

Must prove that for all setsize > 3, there exist non-adjacent members. For example, the first and third members are not  $(\neg)$  adjacent:

$$\begin{array}{ll} (5.24) & \forall \ set size > 3: & \neg Successor(1,3,set size > 3) \\ & \leftarrow Successor(1,2,set size > 3) \leftarrow (n=m+1 \leq set size). \end{array}$$

That is, member 2 is the only successor of member 1 for all setsize > 3, which implies member 3 is not a successor of member 1 for all setsize > 3.

$$(5.25) \quad \forall \ setsize > 3: \quad \neg Predecessor(1, 3, setsize > 3) \\ \leftarrow Predecessor(1, setsize, setsize > 3) \leftarrow (m = 1 \land n = setsize > 3).$$

That is, member n = set size > 3 is the only predecessor of member 1, which implies member 3 is not a predecessor of member 1 for all set size > 3.

(5.26) 
$$\forall setsize > 3: \neg Adjacent(1, 3, setsize > 3)$$
  
 $\leftarrow \neg Successor(1, 3, setsize > 3) \land \neg Predecessor(1, 3, setsize > 3). \square$ 

That is, for all setsize > 3, some elements are not sequentially adjacent to every other element (not symmetric).

## 6. Insights and implications

Applying the ruler measure (2.1) and ruler convergence (2.2) to the set relations, countable distance space (3.1) and countable volume (4.1) yields the following insights and implications:

- (1) The properties of metric space, Euclidean distance and area/volume can be derived from two very simple set relations without using the notions of Euclidean geometry [Joy98] like plane, side, angle, perpendicular, congruence, intersection, etc.
- (2) The ruler measure-based proofs provide the insight that distance is a function of the combinatorial *range*-to-domain set member mappings. Whereas, area/volume is a function of the combinatorial *domain*-to-domain set member mappings.
- (3) The distance spanning multiple, disjoint, domain sets being proportionate to the number of members,  $d_c$ , in the union range set:  $d_c = |\bigcup_{i=1}^n y_i|$  (3.1) generates the triangle inequality, non-negativity, and identity of indiscernibles properties of metric space (3.2). And combined with the constraint,  $|x_i| = |y_i|$ , also generates Manhattan and Euclidean distance, which motivates the fourth property of metric space, symmetry [d(u, v) = d(v, u)]. The reason Manhattan and Euclidean distance have the property of symmetry is that the type of combinatorial range-to-domain set mapping is the same for every set of mappings being summed.

- (4) As the amount of intersection of the range sets increases, a single range set member can map to more domain set members, where the constraint,  $|x_i| = |y_i| = p_i$ , limits the largest total number of range-to-domain set mappings (largest intersection and smallest distance) to  $\sum_{i=1}^{n} |x_i| \cdot |y_i| = \sum_{i=1}^{n} p_i^2$ , which is the set-based reason Euclidean distance (3.7) is the smallest possible distance between two distinct points in  $\mathbb{R}^n$ .
- (5) Time, charge, and mass intervals can be defined that are directly proportionate in size to any distance interval. Applying the ruler to those intervals allows application of the Euclidean distance and area/volume proofs to derive the spacetime, charge force, and Newtonian gravity force equations.
  - (a) The derivations of the four-vector spacetime interval provides some new insights:
    - (i) The derivation of the spacetime equations do not require the notion of light.
    - (ii) There is a hierarchical Euclidean distance, where the Euclidean distances in two independent (inertial) frames of reference are themselves the sizes of two domain intervals corresponding to a yet higher-level Euclidean range interval.
    - (iii) Time, t, being proportionate to that higher-level Euclidean distance, D, such that  $D = (d_c/t_c)t = ct$ , is the reason there is a maximum velocity constant, c.
    - (iv) Changes of other, non-distance variables with respect to time, could be observed at multiple locations at the same time independent of the distance between the locations (e.g., quantum coupling).
  - (b) The charge and gravity force equations were derived from the more fundamental relations that the size, r, of a distance interval is proportionate to the size, q, of a charge interval:  $r(q_C/r_C) = q$ , and proportionate to the size, m, of a mass interval:  $r(m_q/r_q) = m$ .
    - (i) Distance, r, proportionate to charge and mass combined with the ruler-based derivations of charge area,  $q_1q_2$ , and mass area,  $m_1m_2$  implies there are proportionate geometric areas,  $r^2$ , which explains why the forces vary inversely with the square of the distance between two infinitesimal objects.
    - (ii) If there are quantum values of charge,  $q_C$ , and mass,  $m_g$ , then there are quantum distances,  $r_C$  and  $r_g$ , where the forces do not exist at smaller distances. Quantum charge and mass would eliminate the need to invent stronger forces to override the charge and gravity forces at distances smaller than  $r_C$  and  $r_g$ .
  - (c) Applying the ruler to sets of ordered intervals is critical to deriving geometric relations. But, applying the ruler to an unordered collection of intervals (a "bag" of intervals) might be a way to model some statistical mechanics and subatomic behavior, where the behavior would be described by probability equations.
- (6) Relativity theory assumes only 3 dimensions of space [Bru17]. Time constraining a physical set having a total order to at most 3 members (5.4) explains why there are only 3 dimensions of physical space.

- (7) Note that Euclidean distance (3.7) and volume (4.2) are range sets. All compressions, expansions, ripples, bends, bubbles, tunnels, etc. are in the range set space, where the range set is also a function of other variables.
  - (a) Particles, waves, energy, force, etc. are range set phenomena that are projected onto (viewed from) our local, domain, Euclidean frame of reference.
  - (b) An expanding universe is an expansion of the range set space.

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