# The Real Analysis and Set Relations of Geometry

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ABSTRACT. A range from 1-to-1 to many-to-many mappings between each disjoint domain set and a corresponding range set containing the same number of members, where the range sets in some cases intersect and the set members are the same-sized subintervals of intervals, converges to: the triangle inequality, Manhattan distance at the upper boundary, and Euclidean distance at the lower boundary, which provides countable set-based definitions of: metric space, longest, and shortest distances spanning disjoint sets. A many-to-many relation between sets of same-sized subintervals of intervals converges to the product of interval sizes (Euclidean area/volume). The total ordering and symmetry properties of these set-based relations limit the number of domain dimensions to 3. All ordered and symmetric, higher-dimensional geometries, like the spacetime four-vector, collapse into hierarchical 2 or 3-dimensional geometries. Proofs are verified in Coq.

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### 1. Introduction

The concepts of mathematical analysis are derived from set-based axioms, except for the real-valued relations: triangle inequality, Manhattan distance, Euclidean distance, and Euclidean area/volume, which are used in measures (for example, metric space, Hausdorff, and Lebesgue) and used in integration (Lebesgue and Riemann) [Gol76] as definitions rather than *first* being derived from set-based axioms. This article will use some very simple real analysis to motivate and derive those real-valued distance and volume relations from set-based relations.

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The relationships between countable sets generating distance and volume provides a formal, set-based understanding of geometry, for example, why (without any notions of side, angle, and shapes): 1) Euclidean distance is the smallest distance between two distinct points in Euclidean space. 2) Physical Euclidean space is limited to 3 dimensions.

The proofs in this article are verified formally using the Coq Proof Assistant [Coq15] version 8.7.0. The Coq-based definitions, theorems, and proofs are in the files "euclidrelations.v" and "threed.v" located at:

https://github.com/treeck/RASRGeometry.

## 2. Ruler measure and convergence

Euclidean distance and volume are derived from many-to-many set-based relations. Therefore, deriving distance and volume from set and number theory requires a measure that does not have Euclidean assumptions and also allows the full range of mappings from a one-to-one correspondence to a many-to-many mapping.

A ruler (measuring stick) measures a real-valued interval as the nearest integer number of same-sized subintervals (units), where the partial subintervals are ignored. The ruler measure allows defining relations, for example a many-to-many relation, between the set of same-sized subintervals in one interval and the set of same-sized subintervals in another interval. The countable relations converge to continuous, bijective functions as the subinterval size converges to zero.

DEFINITION 2.1. Ruler measure: A ruler measures the size, M, of a closed, open, or semi-open interval as the sum of the sizes of the nearest integer number of whole subintervals, p, each subinterval having the same size, c. Notionally:

(2.1) 
$$\forall c \ s \in \mathbb{R}, \ [a,b] \subset \mathbb{R}, \ s = |a-b| \land c > 0 \land (p = floor(s/c) \lor p = ceiling(s/c)) \land M = \sum_{i=1}^{p} c = pc.$$

Theorem 2.2. Ruler convergence:

$$\forall [a,b] \subset \mathbb{R}, \ s = |a-b| \Rightarrow M = \lim_{c \to 0} pc = s.$$

The Coq-based theorem and proof in the file euclidrelations.v is "limit\_c\_0\_M\_eq\_exact\_size."

Proof. (epsilon-delta proof)

By definition of the floor function,  $floor(x) = max(\{y: y \le x, y \in \mathbb{Z}, x \in \mathbb{R}\})$ :

$$(2.2) \ \forall \ c > 0, \ p = floor(s/c) \ \land \ 0 \leq |floor(s/c) - s/c| < 1 \ \Rightarrow \ 0 \leq |p - s/c| < 1.$$

Multiply all sides of inequality 2.2 by |c|:

$$(2.3) \hspace{1cm} \forall \hspace{0.1cm} c>0, \quad 0 \leq |p-s/c| < 1 \quad \Rightarrow \quad 0 \leq |pc-s| < |c|.$$

$$\begin{array}{lll} (2.4) & \forall \; \delta \; : \; |pc-s| < |c| = |c-0| < \delta \\ & \Rightarrow & \forall \; \epsilon = \delta : \; |c-0| < \delta \; \wedge \; |pc-s| < \epsilon \; := \; M = \lim_{c \to 0} pc = s. \end{array} \ \Box$$

The proof steps using the ceiling function (the outer measure) are the same as the steps in the previous proof using the floor function (the inner measure). The following is an example of ruler convergence, where:  $[0,\pi]$ ,  $s=|0-\pi|$ ,  $c=10^{-i}$ , and  $p=floor(s/c) \Rightarrow p \cdot c = 3.1_{i=1}, 3.14_{i=2}, 3.141_{i=3}, ..., \pi$ .

#### 3. Distance

**Notation conventions:** The vertical bars around a set is the standard notation for indicating the cardinal (number of members in the set). To prevent over use of the vertical bar, the symbol for "such that" is the colon.

**3.1. Countable metric space.** A simple countable distance measure is that a range (distance) set has the same number of members as a corresponding domain set. For example, the number of steps walked in a distance set must equal the number pieces of land traversed. Generalizing, for each distance set,  $y_i$ , containing  $p_i$  number of members there exists a corresponding domain set,  $x_i$ , with the same  $p_i$  number of members. Notionally,  $|x_i| = |y_i| = p_i$ .

It is assumed here that the domain sets are disjoint (do not intersect), where:  $|\bigcup_{i=1}^n x_i| = \sum_{i=1}^n |x_i| \Leftrightarrow \bigcap_{i=1}^n x_i = \emptyset$ . And the number of members in the union of the distance sets,  $d_c$ , depends on the amount of intersection of the distance sets, where:  $|\bigcup_{i=1}^n y_i| < \sum_{i=1}^n |y_i| \Leftrightarrow \bigcap_{i=1}^n y_i \neq \emptyset$ .

Definition 3.1. Countable metric space:

$$|\bigcup_{i=1}^{n} x_i| = \sum_{i=1}^{n} |x_i| \quad \land \quad d_c = |\bigcup_{i=1}^{n} y_i| \le \sum_{i=1}^{n} |y_i| \quad \land \quad |x_i| = |y_i| = p_i.$$

**3.2.** Real-valued metric Space. Applying the ruler (2.1), and ruler convergence theorem (2.2) to the definition of a countable metric space (3.1) yields the real-valued triangle inequality and non-negativity properties of metric space:

(3.1) 
$$d_c = |\bigcup_{i=1}^2 y_i| \le \sum_{i=1}^2 |y_i| \land \exists u \ v \ w \ c \in \mathbb{R} :$$
  
 $d_c = floor(d(u, w)/c) \land |y_1| = floor(d(u, v)/c) \land |y_2| = floor(d(v, w)/c)$   
 $\Rightarrow d(u, w) = \lim_{c \to 0} d_c \cdot c \le \sum_{i=1}^2 \lim_{c \to 0} |y_i| \cdot c = d(u, v) + d(v, w).$ 

The number of members in any countable set is always non-negative. And the product of two non-negative numbers,  $d_c \cdot c$ , is always a non-negative number:

$$(3.2) \quad \forall c > 0, \ \exists \ u \ w \ c \in \mathbb{R} : \quad d_c = floor(d(u, w)/c) \quad \wedge \quad d_c = |\bigcup_{i=1}^n y_i| \ge 0$$
$$\Rightarrow \quad floor(d(u, w)/c) = d_c \ge 0 \quad \Rightarrow \quad d(u, w) = \lim_{c \to 0} d_c \cdot c \ge 0.$$

**3.3.** Metric space range. Where the range (distance) sets intersect, multiple domain set members map to a single distance member. Therefore, the union distance,  $d_c$ , is related to the number of domain-to-distance member mappings.

Consider the trivial case of the countable metric space (3.1), where a domain set has only one member:  $|x_i| = |y_i| = p_i = 1$ : 1) Each member of  $x_i$  maps to only one member of  $y_i$ , yielding  $|x_i| \cdot |y_i| = |x_i| \cdot 1 = p_i = 1$  number of domain-to-distance member mappings. 2) All  $p_i$  number of members of  $x_i$  map to each member in  $y_i$ , yielding  $|x_i| \cdot |y_i| = p_i^2 = 1$  number of domain-to-distance member mappings.

The range of domain-to-distance mappings,  $p_i$  to  $p_i^2$ , that is true for one nonempty set size is true for all non-empty set sizes. Therefore,  $d_c = \sum_{i=1}^n p_i$  is the largest possible distance because it is the case of the smallest number of domain-todistance mappings (no intersection of the distance sets). And  $\exists \mathbf{f} : d_c = \mathbf{f}(\sum_{i=1}^n p_i^2)$ is the smallest possible distance because it is the case of the largest number of domain-to-distance mappings (largest allowed intersection of distance sets). Applying the ruler (2.1) and ruler convergence theorem (2.2) to the longest and shortest distance cases yields the real-valued, Manhattan and Euclidean distance functions.

#### 3.4. Manhattan distance.

THEOREM 3.2. Manhattan (longest) distance, d, is the size of the distance interval,  $[d_0, d_m]$ , mapping to a set of disjoint domain intervals,  $\{[a_1, b_1], [a_2, b_2], \ldots, [a_n, b_n]\}$ , where:

$$d = \sum_{i=1}^{n} s_i$$
,  $d = |d_0 - d_m|$ ,  $s_i = |a_i - b_i|$ .

The formal Coq-based theorem and proof in file euclidrelations.v is "taxicab\_distance."

PROOF.

From the countable metric space definition (3.1), the largest possible countable distance,  $d_c$ , is the equality case:

(3.3) 
$$d_c \leq \sum_{i=1}^n |y_i| \wedge |y_i| = p_i$$
  
 $\Rightarrow d_c \leq \sum_{i=1}^n |y_i| = \sum_{i=1}^n p_i \Rightarrow \exists p_i, d_c : d_c = \sum_{i=1}^n p_i.$ 

Multiply both sides of equation 3.5 by c and take the limit:

$$(3.4) \ d_c = \sum_{i=1}^n p_i \ \Rightarrow \ d_c \cdot c = \sum_{i=1}^n (p_i \cdot c) \ \Rightarrow \ \lim_{c \to 0} d_c \cdot c = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c).$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) to the definition of d:

$$(3.5) d = |d_0 - d_m| \Rightarrow \exists c d: floor(d/c) = d_c \Rightarrow d = \lim_{c \to 0} d_c \cdot c.$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) to the definition of  $s_i$ :

$$(3.6) \quad \forall i \in [1, n], \ s_i = |a_i - b_i| \quad \Rightarrow \quad floor(s_i/c) = p_i \quad \Rightarrow \quad \lim_{c \to 0} p_i \cdot c = s_i.$$

Combine equations 3.5, 3.4, 3.6:

(3.7) 
$$d = \lim_{c \to 0} d_c \cdot c \quad \wedge \quad \lim_{c \to 0} d_c \cdot c = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c) \quad \wedge \quad \lim_{c \to 0} (p_i \cdot c) = s_i \quad \Rightarrow \quad d = \lim_{c \to 0} d_c \cdot c = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c) = \sum_{i=1}^n s_i. \quad \Box$$

### 3.5. Euclidean distance.

THEOREM 3.3. Euclidean (shortest) distance, d, is the size of the distance interval,  $[d_0, d_m]$ , mapping to a set of disjoint domain intervals,  $\{[a_1, b_1], [a_2, b_2], \ldots, [a_n, b_n]\}$ , where:

$$d^2 = \sum_{i=1}^{n} s_i^2$$
,  $d = |d_0 - d_m|$ ,  $s_i = |a_i - b_i|$ .

The formal Coq-based theorem and proof in the file euclidrelations.v is "Euclidean\_distance."

Proof.

Apply the rule of product to the largest number of domain-to-distance set mappings, where all  $p_i$  number of domain set members,  $x_i$ , map to each of the  $p_i$  number of members in the distance set,  $y_i$ :

(3.8) 
$$\sum_{i=1}^{n} |y_i| \cdot |x_i| = \sum_{i=1}^{n} p_i^2.$$

From the countable metric space definition (3.1), choose the equality case:

(3.9) 
$$d_c \leq \sum_{i=1}^n |y_i| \wedge |y_i| = p_i$$
  
 $\Rightarrow d_c \leq \sum_{i=1}^n |y_i| = \sum_{i=1}^n p_i \Rightarrow \exists p_i, d_c : d_c = \sum_{i=1}^n p_i.$ 

Square both sides of equation 3.9  $(x = y \Leftrightarrow f(x) = f(y))$ :

(3.10) 
$$\exists p_i, d_c : d_c = \sum_{i=1}^n p_i \iff \exists p_i, d_c : d_c^2 = (\sum_{i=1}^n p_i)^2.$$

Applying the distributive law of multiplication to equation 3.10:

$$(3.11) \forall p_i p_j \in \{ p_1 \cdots p_n \} : d_c^2 = (\sum_{i=1}^n p_i)^2 = \sum_{i=1}^n (p_i \cdot (\sum_{j=1}^n p_j)).$$

Applying the commutative law of addition to equation 3.11:

(3.12) 
$$d_c^2 = \sum_{i=1}^n (p_i \cdot (\sum_{j=1}^n p_j))$$

$$= \sum_{i=1}^n p_i^2 + \sum_{i=1}^n (p_i \cdot (\sum_{j=1, j \neq i}^n p_j))$$

$$\geq \sum_{i=1}^n p_i^2$$

$$\Rightarrow \exists p_i : d_c^2 = \sum_{i=1}^n p_i^2.$$

Multiply both sides of equation 3.12 by  $c^2$ , simplify, and take the limit.

$$(3.13) d_c^2 = \sum_{i=1}^n p_i^2 \Rightarrow d_c^2 \cdot c^2 = \sum_{i=1}^n p_i^2 \cdot c^2 \Leftrightarrow (d_c \cdot c)^2 = \sum_{i=1}^n (p_i \cdot c)^2$$
$$\Rightarrow \lim_{c \to 0} (d_c \cdot c)^2 = \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c)^2.$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) and square both sides:

$$(3.14) \qquad \exists \ c \ d: \ floor(d/c) = d_c \quad \Rightarrow \quad d = \lim_{c \to 0} d_c \cdot c \quad \Rightarrow \quad d^2 = \lim_{c \to 0} (d_c \cdot c)^2.$$

Apply the ruler (2.1) and ruler convergence theorem (2.2) and square both sides: (3.15)  $\forall i \in [1, n], floor(s_i/c) = p_i \Rightarrow \lim_{c \to 0} p_i \cdot c = s_i$ 

$$\Rightarrow \lim_{c \to 0} (p_i \cdot c)^2 = s_i^2 \quad \Rightarrow \quad \sum_{i=1}^n \lim_{c \to 0} (p_i \cdot c)^2 = \sum_{i=1}^n s_i^2.$$

Combine equations 3.14, 3.13, 3.15:

(3.16) 
$$d^{2} = \lim_{c \to 0} (d_{c} \cdot c)^{2} \wedge \lim_{c \to 0} (d_{c} \cdot c)^{2} = \sum_{i=1}^{n} \lim_{c \to 0} (p_{i} \cdot c)^{2} \wedge \sum_{i=1}^{n} \lim_{c \to 0} (p_{i} \cdot c)^{2} = \sum_{i=1}^{n} s_{i}^{2}$$

$$\Rightarrow d^{2} = \lim_{c \to 0} (d_{c} \cdot c)^{2} = \sum_{i=1}^{n} \lim_{c \to 0} (p_{i} \cdot c)^{2} = \sum_{i=1}^{n} s_{i}^{2}. \quad \Box$$

### 4. Euclidean Volume

The number of all possible combinations (all many-to-many mappings) between members in a countable set  $x_1$  and a countable set  $x_2$  is the Cartesian product,  $|x_1| \cdot |x_2|$ . This section will use the ruler (2.1) and ruler convergence theorem (2.2) to prove that the Cartesian product of the same-sized subintervals of intervals converges to the product of interval sizes as the subinterval size converges to zero. The first step is to define a countable set-based measure of area/volume as the Cartesian product (many-to-many mappings) of disjoint domain set members.

Definition 4.1. Countable volume measure,  $V_c$ :

$$\sum_{i=1}^{n} |x_i| = |\bigcup_{i=1}^{n} x_i|, \quad V_c = \prod_{i=1}^{n} |x_i|.$$

THEOREM 4.2. Euclidean volume, V, is the size of a range interval,  $[v_0, v_m]$ , corresponding to a set of disjoint intervals:  $\{[a_1, b_1], [a_2, b_2], \ldots, [a_n, b_n]\}$ , where:

$$V = \prod_{i=1}^{n} s_i$$
,  $V = |v_0 - v_m|$ ,  $s_i = |a_i - b_i|$ ,  $i \in [1, n]$ ,  $i, n \in \mathbb{N}$ .

The Coq-based theorem and proof in the file euclidrelations.v is "Euclidean\_volume."

Proof.

Use the ruler (2.1) to divide the exact size,  $s_i = |a_i - b_i|$ , of each of the domain intervals,  $[a_i, b_i]$ , into a set,  $x_i$  of  $p_i$  number of subintervals.

$$(4.1) \forall i \ n \in \mathbb{N}, \quad i \in [1, n], \quad c > 0 \quad \land \quad floor(s_i/c) = p_i = |x_i|.$$

Apply the ruler convergence theorem (2.2) to equation 4.1:

$$(4.2) floor(s_i/c) = p_i \Rightarrow \lim_{c \to 0} (p_i \cdot c) = s_i.$$

Use the ruler (2.1) to divide the exact size,  $V = |v_0 - v_m|$ , of the range interval,  $[v_0, v_m]$ , into  $p^n$  subintervals. Every integer number,  $V_c$ , does **not** have an integer  $n^{th}$  root. However, for those cases where  $V_c$  does have an integer  $n^{th}$  root, there is a  $p^n$  that satisfies the definition a countable volume measure,  $V_c$  (4.1). Notionally:

$$(4.3) \quad \forall \ p^n = V_c \in \mathbb{N}, \ \exists \ V \in \mathbb{R}, \ x_i : floor(V/c^n) = V_c = p^n = \prod_{i=1}^n |x_i| = \prod_{i=1}^n p_i.$$

Apply the ruler convergence theorem (2.2) to equation 4.3 and simplify:

$$(4.4) floor(V/c^n) = p^n \Rightarrow V = \lim_{c \to 0} p^n \cdot c^n = \lim_{c \to 0} (p \cdot c)^n.$$

Multiply both sides of equation 4.3 by  $c^n$  and simplify:

$$(4.5) p^n = \prod_{i=1}^n p_i \Rightarrow p^n \cdot c^n = (\prod_{i=1}^n p_i) \cdot c^n \Leftrightarrow (p \cdot c)^n = \prod_{i=1}^n (p_i \cdot c).$$

Combine equations 4.4, 4.5, and 4.2:

$$(4.6) \quad V = \lim_{c \to 0} (p \cdot c)^n \quad \wedge \quad (p \cdot c)^n = \prod_{i=1}^n (p_i \cdot c) \quad \wedge \quad \lim_{c \to 0} (p_i \cdot c) = s_i$$

$$\Rightarrow \quad V = \lim_{c \to 0} (p \cdot c)^n = \prod_{i=1}^n \lim_{c \to 0} (p_i \cdot c) = \prod_{i=1}^n s_i. \quad \Box$$

# 5. Ordered and symmetric geometries

The union operations of the set-based relations generating the properties of metric space, Euclidean distance, and volume requires being able to iterate sequentially through each set (dimension of sets), which implies a total order of the sets exist. The commutative property of the union operation also allows each set to be sequentially adjacent to any other set, herein referred to as a symmetric geometry.

But, once you assert that a particular set has a particular total order, then that particular set can have only that one order. Asserting that the same set also has a different order results in contradictions because each member of a sequentially ordered set can have at most one successor and at most one predecessor. Therefore, the question becomes how a set can only one sequential order where each member can be sequentially adjacent to any other member?

A single set-based distance relation (3.1) allows both a Manhattan and Euclidean distance between every two distinct points to exist *simultaneously* without contradictions. Likewise, it will now be proved that a set satisfying the *simultaneous* constraints of a total order and symmetry limits the number of set members (dimensions of distance and volume) to at most 3 members.

Definition 5.1. Ordered geometry:

$$\forall i \ n \in \mathbb{N}, \ i \in [1, n-1], \ \forall x_i \in \{x_1, \dots, x_n\},\$$

$$successor x_i = x_{i+1} \land predecessor x_{i+1} = x_i,$$

where each  $x_i \in \{x_1, \ldots, x_n\}$  is a set of subintervals of a real-valued domain interval (from a dimension of intervals).

DEFINITION 5.2. Symmetric geometry (every member of a set is sequentially adjacent to every other member):

$$\forall i \ j \ n \in \mathbb{N}, \ \forall \ x_i \ x_j \in \{x_1, \dots, x_n\}, \ successor \ x_i = x_j \ \land \ predecessor \ x_j = x_i.$$

Theorem 5.3. An ordered and symmetric set is a cyclic set.

successor 
$$x_n = x_1 \land predecessor x_1 = x_n$$
.

The theorem and formal Coq-based proof is "ordered\_symmetric\_is\_cyclic," which is located in the file threed.v.

PROOF. The property of order (5.1) defines unique successors and predecessors for all set members except for the successor of  $x_n$  and the predecessor of  $x_1$ . Therefore, the only member that can be a successor of  $x_n$ , without creating a contradiction, is  $x_1$ . And the only member that can be a predecssor of  $x_1$ , without creating a contradiction, is  $x_n$ . From the properties of a symmetric geometry (5.2):

$$(5.1) i = n \land j = 1 \land successor x_i = x_j \Rightarrow successor x_n = x_1.$$

$$(5.2) i = n \land j = 1 \land predecessor x_j = x_i \Rightarrow predecessor x_1 = x_n. \Box$$

Theorem 5.4. An ordered and symmetric set is limited to at most 3 members.

The Coq-based lemmas and proofs in the file threed.v are:

Lemmas: adj111, adj122, adj212, adj123, adj133, adj233, adj213, adj313, adj323, and not\_all\_mutually\_adjacent\_gt\_3.

The following proof uses Horn clauses (a subset of first-order logic) that uses unification and resolution. Horn clauses make it clear which facts satisfy a proof goal.

Proof.

It was proved that an ordered and symmetric set is a cyclic set of sets (5.3). In other words, the successors and predecessors of ordered and symmetric set are cyclic:

Definition 5.5. Cyclic successor of m is n:

$$(5.3) \quad Successor(m,n,setsize) \leftarrow (m = setsize \land n = 1) \lor (m+1 \leq setsize).$$

Definition 5.6. Cyclic predecessor of m is n:

$$(5.4) \qquad Predecessor(m,n,setsize) \leftarrow (m=1 \land n=setsize) \lor (m-1 \ge 1).$$

DEFINITION 5.7. Adjacent: member m is sequentially adjacent to member n (required for a "symmetric" set (5.2)), if the cyclic successor of m is n or the cyclic predecessor of m is n. Notionally: (5.5)

 $Adjacent(m, n, setsize) \leftarrow Successor(m, n, setsize) \lor Predecessor(m, n, setsize).$ 

Every member is adjacent to every other member, where  $setsize \in \{1, 2, 3\}$ :

$$(5.6) Adjacent(1,1,1) \leftarrow Successor(1,1,1) \leftarrow (1=1 \land 1=1).$$

$$(5.7) Adjacent(1,2,2) \leftarrow Successor(1,2,2) \leftarrow (1+1 \leq 2).$$

$$(5.8) \qquad \qquad Adjacent(2,1,2) \leftarrow Successor(2,1,2) \leftarrow (2=2 \land 1=1).$$

$$(5.9) Adjacent(1,2,3) \leftarrow Successor(1,2,3) \leftarrow (1+1 \leq 2).$$

$$(5.10) Adjacent(2,1,3) \leftarrow Predecessor(2,1,3) \leftarrow (2-1 \ge 1).$$

$$(5.11) Adjacent(3,1,3) \leftarrow Successor(3,1,3) \leftarrow (3=3 \land 1=1).$$

$$(5.12) Adjacent(1,3,3) \leftarrow Predecessor(1,3,3) \leftarrow (1=1 \land 3=3).$$

$$(5.13) Adjacent(2,3,3) \leftarrow Successor(2,3,3) \leftarrow (2+1 \le 3).$$

$$(5.14) \qquad \qquad Adjacent(3,2,3) \leftarrow Predecessor(3,2,3) \leftarrow (3-1 \geq 1).$$

Must prove that for all setsize > 3, there exist non-adjacent members. For example, the first and third members are not adjacent:

(5.15) 
$$\forall setsize > 3: \neg Successor(1, 3, setsize) \\ \leftarrow Successor(1, 2, setsize) \leftarrow (1 + 1 < setsize).$$

That is, 2 is the only successor of 1 for all setsize > 3, which implies 3 is not a successor of 1 for all setsize > 3.

(5.16) 
$$\forall \ set size > 3: \neg Predecessor(1, 3, set size) \\ \leftarrow Predecessor(1, n, set size) \leftarrow (1 = 1 \land n = set size).$$

That is, n = set size is the only predecessor of 1 for all set size > 3, which implies 3 is not a predecessor of 1 for all set size > 3.

$$(5.17) \quad \forall \ setsize > 3: \quad \neg Adjacent(1,3,setsize) \\ \leftarrow \neg Successor(1,3,setsize) \land \neg Predecessor(1,3,setsize). \quad \Box$$

That is, for all setsize > 3, some elements are not sequentially adjacent to every other element (violates the symmetry property).

## 6. Summary

Applying some very simple real analysis, in the form of the ruler measure (2.1) and ruler convergence proof (2.2), to a set of real-valued domain intervals and a range interval yields some new insights into geometry and physics.

- (1) Ruler measure-based proofs expose the difference between distance and volume measures: Distance is a function of the number of domain-to-range set member mappings. Area/volume is a function of the number of domain-to-domain set member mappings. Other types of measures, like Borel, Hausdorff, and Lebesgue, do not provide that insight. The definition of metric space is too broad to be valid because it allows area/volume, which the ruler measure-based proofs show are not distance relations.
- (2) Applying the ruler measure to the countable metric space (3.1) provides the insight that all notions of distance are based on the principle that for

each disjoint domain set there exists a corresponding range set containing the same number of members, where the range sets in some cases intersect:

- (a) Applying the ruler and ruler convergence to the countable metric space principle (3.1) generates the real-valued triangle inequality and non-negativity properties of metric space (3.2), which provides the insight that a "flat" geometry is one where for each disjoint, countable domain set of same-sized members there exists a corresponding range (distance) set with same number of same-sized members.
- (b) The upper bound of the countable metric space is the size,  $d_c$ , of the union of disjoint range (distance) sets, where there is a 1-1 correspondence between the domain and range set members. Therefore, the total number of domain-to-range set mappings is  $d_c = \sum_{i=1}^{n} p_i$ , which is the Manhattan distance.
- (c) The lower bound case is the size,  $d_c$ , of the union of intersecting range (distance) sets, where all domain members map to each range member (a many-to-many relation) yielding  $\sum_{i=1}^{n} p_i^2$  number of domain-to-range set member mappings. Combining the previous equation,  $d_c = \sum_{i=1}^{n} p_i \Rightarrow d_c^2 = (\sum_{i=1}^{n} p_i)^2 \geq \sum_{i=1}^{n} p_i^2$ . The smallest (shortest) distance is the equality case:  $d_c^2 = \sum_{i=1}^{n} p_i^2$ , which explains from a set-based perspective (without any notions of side, angle, or shape) why Euclidean distance is the smallest possible distance spanning countable, disjoint domain sets. And applying the ruler measure and convergence theorem yields the real-valued smallest possible distance relation:  $d^2 = \sum_{i=1}^{n} s_i^2$  (3.3).
- (d) All  $L^p$  norms  $(||\mathbf{x}||_p = (\sum_{i=1}^n x_i^p)^{1/p})$ , where p > 2, over-count the number of possible domain-to-range mappings and therefore do not satisfy the countable metric space properties. But,  $L^p$  norms, where p > 2, do satisfy the triangle inequality. Accepting area/volume and  $L^p$  norms, where p > 2, as distance measures, the common definition of metric space is too broad to be valid.
- (e) Euclidean distance (3.3) was derived from a set-based, many-to-many relation without any notions of side, angle, or shape. A parametric variable relating the sizes of two domain intervals can be easily derived using using calculus (Taylor series) and the Euclidean distance equation to generate the arc sine and arc cosine functions of the parametric variable (arc angle). In other words, the notions of side and angle are derived from Euclidean distance, which is the reverse perspective of classical geometry [Joy98] [Loo68] [Ber88] and axiomatic foundations for geometry [Bir32] [Hil80] [TG99].
- (3) Applying the ruler measure and ruler convergence proof to the countable volume definition (4.1) allows a proof that the Cartesian product of same-sized subintervals of real-valued intervals converges to the product of the interval sizes (Euclidean length/area/volume):
  - (a) Euclidean volume was derived from a many-to-many (combinatorial) relation without notions of sides, angles, and shape.
  - (b) The Lebesgue measure, Riemann and Lebesgue integration, and vector analysis assume Euclidean volume/space ( $\mathbb{R}^n$ ) rather than deriving Euclidean volume from more fundamental set-based relations.

- (4) The set-based relations generating metric space (3.2), Manhattan distance (3.2), Euclidean distance (3.3), and volume (4.2) have the properties of total ordering (5.1) and symmetry (5.2). A geometry that is *simultaneously* ordered and symmetric limits distance and volume to a cyclic set (5.3) of three dimensions (5.4), which explains why there are only three dimensions of physical space (length, width, and height).
- (5) Higher dimensions of "space" must have types that are different from the three geometric/physical dimensions of space. The *simultaneously* ordered and symmetric properties that generate the three dimensions of geometric space constrain all *valid* higher dimensional theories of physics to hierarchical 2 or 3-dimensional geometries to prevent logic contradictions. For example, the four-vectors common in physics [Bru17] are hierarchical, 2-dimensional geometries that have been "flattened."

The spacetime four-vector length,  $d = \sqrt{(ct)^2 - (x^2 + y^2 + z^2)}$ , where c is the speed of light and t is time, can be expressed in a form like,  $(ct)^2 = d_1^2 + d_2^2$ , where  $d_1^2 = x^2 + y^2 + z^2$  and  $d_2 = d$ . Likewise, the energy-momentum four-vector has the 2-dimensional length:  $E^2 = (mv^2)^2 + (pc)^2$ , where E is energy, m is the resting mass, v is the 3-dimensional velocity, c is the speed of light, and p is the relativistic momentum  $(p = \gamma mv)$ , where  $\gamma = (1/(1 - (v/c)^2))^{1/2}$  is the Lorentz factor).

Applying the Euclidean distance proof (3.3) to the 2-dimensional spacetime and energy-momentum equations provides the perspective that for each set of subintervals (units of physical measure) of a domain interval there is a corresponding range interval containing the same number of same-sized subintervals. The Euclidean distance proof is a set and real analysis-based explanation of Albert Einstein's second law of relativity stating that all units of measure are the same in every frame of reference [Bru16].

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