

# The Real Analysis and Combinatorics of Geometry

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**ABSTRACT.** A ruler measures an interval as the nearest number of same-sized subintervals (units), ignoring partial subintervals. The range of possible surjective (many-to-one) mappings from every disjoint domain set of same-sized subintervals of a domain interval to a corresponding image (distance) set containing the same number of same-sized subintervals converges to the triangle inequality with taxicab (Manhattan) distance at the upper boundary and Euclidean distance at the lower boundary, which provides a set-based foundation for the definitions of metric space, longest, and shortest distance measures. A surjective definition of countable size converges to the product of interval sizes used in the Lebesgue measure and Euclidean integrals. A cyclic set of at most 3 dimensions emerges from the same surjective relations generating distance and volume. Implications for higher dimensional geometries are discussed. Proofs are verified in Coq.

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## 1. Introduction

The triangle inequality of a metric space, Euclidean distance metric, and the volume equation (product of interval sizes) of the Lebesgue measure and Euclidean integrals (for example, Riemann and Lebesgue integrals) are imported from Euclidean geometry as definitions [Gol76] rather than derived from set-based axioms. As a consequence, real analysis and calculus have provided no insight into the set-based relationships that motivate and generate those geometric relations.

A ruler measures an interval as the nearest number of same-sized subintervals (units), where the partial subintervals are ignored. The ruler measure allows defining surjective (many-to-one) mappings from one or more of the same-sized subintervals in one interval to a same-sized subinterval in another interval. The discrete, surjective functions converge to continuous, bijective functions as the subinterval size converges to zero.

The range of possible surjective (many-to-one) mappings from every disjoint domain set of same-sized subintervals of a domain interval to a corresponding image (distance) set containing the same number of same-sized subintervals converges to the triangle inequality with taxicab (Manhattan) distance at the upper boundary and Euclidean distance at the lower boundary, which provides a set-based foundation for the definitions of metric space, longest, and shortest distance measures. A surjective definition of countable size converges to the product of interval sizes used in the Lebesgue measure and Euclidean integrals.

A cyclic set of at most 3 dimensions emerges from the same surjective relations generating distance and volume. Implications for higher dimensional geometries are discussed in the summary.

The proofs in this article are verified formally using the Coq Proof Assistant [Coq15] version 8.7.0. The Coq-based definitions, theorems, and proofs are in the files “euclidrelations.v” and “threed.v” located at:

<https://github.com/treeck/CombinatorialGeometry>.

## 2. Ruler measure and convergence

**DEFINITION 2.1.** Ruler measure: A ruler measures the size,  $M$ , of a closed, open, or semi-open interval as the nearest integer number of whole subintervals,  $p$ , times the subinterval size,  $c$ , where  $c$  is the independent variable. Notionally:

$$(2.1) \quad \forall c \, s \in \mathbb{R}, \, [a, b] \subset \mathbb{R}, \, s = |a - b| \wedge c > 0 \wedge \\ (p = \text{floor}(s/c) \vee p = \text{ceiling}(s/c)) \wedge M = \sum_{i=1}^p c = pc.$$

**THEOREM 2.2.** *Ruler convergence:*

$$\forall [a, b] \subset \mathbb{R}, \, s = |a - b| \Rightarrow M = \lim_{c \rightarrow 0} pc = s.$$

The Coq-based theorem and proof in the file euclidrelations.v is “limit\_c\_0.M.eq\_exact\_size.”

**PROOF.** (epsilon-delta proof)

By definition of the floor function,  $\text{floor}(x) = \max(\{y : y \leq x, y \in \mathbb{Z}, x \in \mathbb{R}\})$ :

$$(2.2) \quad \forall c > 0, \, p = \text{floor}(s/c) \Rightarrow 0 \leq |p - s/c| < 1.$$

Multiply all sides of inequality 2.2 by  $|c|$ :

$$(2.3) \quad \forall c > 0, \, 0 \leq |p - s/c| < 1 \Rightarrow 0 \leq |pc - s| < |c|.$$

$$(2.4) \quad \forall \delta : |pc - s| < |c| = |c - 0| < \delta \\ \Rightarrow \forall \epsilon = \delta, \, |c - 0| < \delta \wedge |pc - s| < \epsilon := M = \lim_{c \rightarrow 0} pc = s. \quad \square$$

The proof steps using the ceiling function (the outer measure) are the same as the steps in the previous proof using the floor function (the inner measure).

The following is an example of ruler convergence, where:  $[0, \pi]$ ,  $s = |\pi - 0|$ ,  $c = 10^{-i}$ , and  $p = \text{floor}(s/c) \Rightarrow p \cdot c = 3.1_{i=1}, 3.14_{i=2}, 3.141_{i=3}, \dots, \pi$ .

### 3. Distance

A simple countable distance measure is that an image (distance) set has the same number of elements as a corresponding domain set. For example, the number of steps walked in a distance set must equal the number pieces of land traversed. Generalizing, for each disjoint domain set,  $x_i$ , containing  $p_i$  number of elements there exists a corresponding distance set,  $y_i$ , with the same  $p_i$  number of elements.

**Notation conventions:** The vertical bars around a set is the standard notation for indicating the cardinal (number of elements in the set). To prevent over use of the vertical bar, the symbol for “such that” is the colon.

If the distance sets intersect ( $\sum_{i=1}^n |y_i| > |\bigcup_{i=1}^n y_i|$ ), then multiple domain set elements can correspond to a single distance element. Therefore, the size of the union of the distance sets,  $d_c$ , is a function of the number of surjective (many-to-one) correspondences to each distance set element. Notionally:

DEFINITION 3.1. Countable distance range,  $d_c$ :

$$\forall i \in \mathbb{N}, \quad x_i \subseteq X, \quad \sum_{i=1}^n |x_i| = |\bigcup_{i=1}^n x_i|, \quad \forall x_i \exists y_i \subseteq Y : \\ |x_i| = |y_i| = p_i \quad \wedge \quad d_c = |Y| = |\bigcup_{i=1}^n y_i| \leq \sum_{i=1}^n |y_i|.$$

The countable distance range principle (3.1),  $|x_i| = |y_i| = p_i$ , constrains the range of surjective correspondences from only one element of  $x_i$  corresponding to an element of  $y_i$  to as many as  $p_i$  number of elements of  $x_i$  corresponding to an element of  $y_i$ . More than  $p_i$  number of surjective correspondences to an element of  $y_i$  would be over-counting correspondences.

Using the rule of product, there is a range from  $|y_i| \cdot 1 = p_i$  to  $|y_i| \cdot p_i = p_i^2$  number of domain-to-distance surjective correspondences per distance set. The case of no intersecting distance sets yields the largest union size of the distance sets,  $d_c$ , which is also the case of the smallest number of surjective correspondences per distance set:  $d_c = f(\sum_{i=1}^n p_i)$ . And  $d_c = f(\sum_{i=1}^n p_i^2)$  is the shortest possible distance because it is the case of the largest number of surjective correspondences per distance set (largest intersection of distance sets).

It will now be proved that using the ruler (2.1) to divide a set of real-valued domain intervals and a distance interval into sets of same-sized subintervals, and applying the ruler convergence theorem (2.2) to the longest and shortest distance cases converge to the real-valued taxicab (Manhattan) and Euclidean distance equations.

**THEOREM 3.2.** *Taxicab (longest) distance,  $d$ , is the size of the distance interval,  $[d_0, d_m]$ , corresponding to a set of disjoint domain intervals,  $\{[a_1, b_1], [a_2, b_2], \dots, [a_n, b_n]\}$ , where:*

$$d = \sum_{i=1}^n s_i, \quad d = |d_0 - d_m|, \quad s_i = |a_i - b_i|.$$

The formal Coq-based theorem and proof in file euclidrelations.v is “taxicab.distance.”

PROOF.

Use the ruler (2.1) to divide the exact size,  $s_i = |a_i - b_i|$ , of each of the domain intervals,  $[a_i, b_i]$ , into a set,  $x_i$ , containing  $p_i$  number of subintervals and apply the definition of the countable distance range (3.1), where each domain set has a corresponding distance set containing the same  $p_i$  number of elements.

$$(3.1) \quad \forall i \in \mathbb{N}, \quad i \in [1, n], \quad c > 0 \quad \wedge \quad \text{floor}(s_i/c) = p_i = |x_i| = |y_i|.$$

Next, apply the rule of product to the case of one domain set element per distance set element:

$$(3.2) \quad \forall y_i \in Y, \sum_{i=1}^n |y_i| \cdot 1 = \sum_{i=1}^n p_i.$$

Apply the countable distance range definition (3.1) to equation 3.2:

$$(3.3) \quad \forall y_i \in Y, \sum_{i=1}^n |y_i| \cdot 1 = \sum_{i=1}^n p_i \quad \wedge \quad \sum_{i=1}^n |y_i| \geq d_c \\ \Rightarrow \sum_{i=1}^n p_i \geq d_c \quad \Rightarrow \quad \exists p_i, d_c : \sum_{i=1}^n p_i = d_c.$$

Multiply both sides of 3.3 by  $c$  and apply the ruler convergence theorem (2.2):

$$(3.4) \quad s_i = \lim_{c \rightarrow 0} p_i \cdot c \quad \wedge \quad \sum_{i=1}^n (p_i \cdot c) = d_c \cdot c \\ \Rightarrow \sum_{i=1}^n s_i = \sum_{i=1}^n \lim_{c \rightarrow 0} (p_i \cdot c) = \lim_{c \rightarrow 0} d_c \cdot c.$$

Use the ruler to divide the exact size,  $d = |d_0 - d_m|$ , of the image interval,  $[d_0, d_m]$ , into a set,  $Y$ , containing  $d_c$  number of elements:

$$(3.5) \quad \forall d_c \in \mathbb{N}, c > 0 \exists d \in \mathbb{R} : \text{floor}(d/c) = d_c.$$

Multiply both sides of 3.5 by  $c$  and apply the ruler convergence theorem (2.2):

$$(3.6) \quad \text{floor}(d/c) = d_c \Rightarrow d = \lim_{c \rightarrow 0} d_c \cdot c.$$

Combine equations 3.6 and 3.4:

$$(3.7) \quad d = \lim_{c \rightarrow 0} d_c \cdot c \quad \wedge \quad \sum_{i=1}^n s_i = \lim_{c \rightarrow 0} d_c \cdot c \quad \Rightarrow \quad d = \sum_{i=1}^n s_i. \quad \square$$

**THEOREM 3.3.** *Euclidean (shortest) distance,  $d$ , is the size of the distance interval,  $[d_0, d_m]$ , corresponding to a set of disjoint domain intervals,  $\{[a_1, b_1], [a_2, b_2], \dots, [a_n, b_n]\}$ , where:*

$$d^2 = \sum_{i=1}^n s_i^2, \quad d = |d_0 - d_m|, \quad s_i = |a_i - b_i|.$$

The formal Coq-based theorem and proof in the file euclidrelations.v is “Euclidean.distance.”

**PROOF.**

Use the ruler (2.1) to divide the exact size,  $s_i = |a_i - b_i|$ , of each of the domain intervals,  $[a_i, b_i]$ , into a set,  $x_i$ , containing  $p_i$  number of subintervals and apply the definition of the countable distance range (3.1), where each domain set has a corresponding distance set containing the same  $p_i$  number of elements.

$$(3.8) \quad \forall i \in \mathbb{N}, i \in [1, n], c > 0 \quad \wedge \quad \text{floor}(s_i/c) = p_i = |x_i| = |y_i|.$$

Apply the rule of product to largest number of domain-to-distance surjective correspondences, where each of the  $p_i$  number of distance set elements in  $y_i$  corresponds to all  $p_i$  number of elements in the domain set  $x_i$ :

$$(3.9) \quad \sum_{i=1}^n |y_i| \cdot |x_i| = \sum_{i=1}^n p_i^2 = \sum_{i=1}^n |y_i|^2.$$

Choose the equality case of the Cauchy-Schwartz inequality:

$$(3.10) \quad \sum_{i=1}^n p_i^2 \leq (\sum_{i=1}^n p_i)^2 \Rightarrow \exists p_i : \sum_{i=1}^n p_i^2 = (\sum_{i=1}^n p_i)^2$$

Choose the equality case of the countable distance range definition (3.1) and square both sides ( $x = y \Rightarrow f(x) = f(y)$ ):

$$(3.11) \quad \sum_{i=1}^n |y_i| = \sum_{i=1}^n p_i \geq d_c \Rightarrow \exists p_i, d_c : \sum_{i=1}^n p_i = d_c \\ \Rightarrow \exists p_i, d_c : (\sum_{i=1}^n p_i)^2 = d_c^2.$$

Combine equations 3.10 and 3.11:

$$(3.12) \quad \exists p_i : \sum_{i=1}^n p_i^2 = (\sum_{i=1}^n p_i)^2 \quad \wedge \quad \exists p_i, d_c : (\sum_{i=1}^n p_i)^2 = d_c^2 \\ \Rightarrow \quad \exists p_i, d_c : \sum_{i=1}^n p_i^2 = d_c^2.$$

Multiply both sides of equation 3.12 by  $c^2$  and apply the ruler convergence theorem:

$$(3.13) \quad s_i = \lim_{c \rightarrow 0} p_i \cdot c \quad \wedge \quad \sum_{i=1}^n (p_i \cdot c)^2 = (d_c \cdot c)^2 \\ \Rightarrow \quad \sum_{i=1}^n s_i^2 = \sum_{i=1}^n \lim_{c \rightarrow 0} (p_i \cdot c)^2 = \lim_{c \rightarrow 0} (d_c \cdot c)^2.$$

Use the ruler to divide the exact size,  $d = |d_0 - d_m|$ , of the image interval,  $[d_0, d_m]$  into a set,  $Y$ , containing  $d_c$  number of elements:

$$(3.14) \quad \forall d_c \in \mathbb{N}, c > 0 \exists d \in \mathbb{R} : \text{floor}(d/c) = d_c.$$

Apply the ruler convergence theorem (2.2) and then square both sides:

$$(3.15) \quad \text{floor}(d/c) = d_c \quad \Rightarrow \quad d = \lim_{c \rightarrow 0} d_c \cdot c \quad \Rightarrow \quad d^2 = \lim_{c \rightarrow 0} (d_c \cdot c)^2.$$

Combine equations 3.15 and 3.13:

$$(3.16) \quad d^2 = \lim_{c \rightarrow 0} (d_c \cdot c)^2 \quad \wedge \quad \sum_{i=1}^n s_i^2 = \lim_{c \rightarrow 0} (d_c \cdot c)^2 \quad \Rightarrow \quad d^2 = \sum_{i=1}^n s_i^2. \quad \square$$

**3.1. Triangle inequality.** The definition of a metric in real analysis is based on the triangle inequality,  $\mathbf{d}(\mathbf{u}, \mathbf{w}) \leq \mathbf{d}(\mathbf{u}, \mathbf{v}) + \mathbf{d}(\mathbf{v}, \mathbf{w})$ , that has been intuitively motivated by the triangle [Gol76]. Applying the ruler (2.1), and ruler convergence theorem (2.2) to the definition of a countable distance range (3.1) yields the real-valued triangle inequality:

$$(3.17) \quad d_c = |Y| = |\bigcup_{i=1}^2 y_i| \leq \sum_{i=1}^2 |y_i| \quad \wedge \\ d_c = \text{floor}(\mathbf{d}(\mathbf{u}, \mathbf{w})/c) \quad \wedge \quad |y_1| = \text{floor}(\mathbf{d}(\mathbf{u}, \mathbf{v})/c) \quad \wedge \quad |y_2| = \text{floor}(\mathbf{d}(\mathbf{v}, \mathbf{w})/c) \\ \Rightarrow \quad \mathbf{d}(\mathbf{u}, \mathbf{w}) = \lim_{c \rightarrow 0} d_c \cdot c \leq \sum_{i=1}^2 \lim_{c \rightarrow 0} |y_i| \cdot c = \mathbf{d}(\mathbf{u}, \mathbf{v}) + \mathbf{d}(\mathbf{v}, \mathbf{w}).$$

The other metric space properties:  $\mathbf{d}(\mathbf{u}, \mathbf{w}) = 0 \Leftrightarrow u = w$ ,  $\mathbf{d}(\mathbf{u}, \mathbf{w}) = \mathbf{d}(\mathbf{w}, \mathbf{u})$ , and  $\mathbf{d}(\mathbf{u}, \mathbf{w}) \geq 0$  also follow from the countable distance range definition.

#### 4. Size (length/area/volume)

The surjective (many-to-one) relationship between all elements in domain set  $x_1$  to each element of domain set  $x_2$  results in the Cartesian product of  $|x_1| \cdot |x_2|$  number of correspondences. This section will use the ruler (2.1) and ruler convergence theorem (2.2) to prove that the Cartesian product of the number of same-sized subintervals of intervals converges to the product of interval sizes. The first step is to define a set-based, countable size measure as the Cartesian product of disjoint domain set members.

**DEFINITION 4.1.** Countable size (length/area/volume) measure,  $S_c$ :

$$\forall i \ n \in \mathbb{N}, \quad i \in [1, n], \quad x_i \subseteq X, \quad \sum_{i=1}^n |x_i| = |\bigcup_{i=1}^n x_i|, \quad \wedge \quad S_c = \prod_{i=1}^n |x_i|.$$

**THEOREM 4.2.** *Euclidean size (length/area/volume),  $S$ , is the size of an image interval,  $[v_0, v_m]$ , corresponding to a set of disjoint intervals:*

*$\{[a_1, b_1], [a_2, b_2], \dots, [a_n, b_n]\}$ , where:*

$$S = \prod_{i=1}^n s_i, \quad S = |v_0 - v_m|, \quad s_i = |a_i - b_i|, \quad i \in [1, n], \quad i, n \in \mathbb{N}.$$

The Coq-based theorem and proof in the file euclidrelations.v is “Euclidean\_size.”

PROOF.

Use the ruler (2.1) to divide the exact size,  $s_i = |a_i - b_i|$ , of each of the domain intervals,  $[a_i, b_i]$ , into a set,  $x_i$  of  $p_i$  number of subintervals.

$$(4.1) \quad \forall i \ n \in \mathbb{N}, \quad i \in [1, n], \quad c > 0 \quad \wedge \quad \text{floor}(s_i/c) = p_i = |x_i|.$$

Use the ruler (2.1) to divide the exact size,  $S = |v_0 - v_m|$ , of the image interval,  $[v_0, v_m]$ , into  $p_S^n$  subintervals. Every integer number,  $S_c$ , does **not** have an integer  $n^{th}$  root. However, for those cases where  $S_c$  does have an integer  $n^{th}$  root, there is a  $p_S^n$  that satisfies the definition a countable size measure,  $S_c$  (4.1). Notionally:

$$(4.2) \quad \forall p_S^n = S_c \in \mathbb{N}, \exists S \in \mathbb{R}, x_i : \text{floor}(S/c) = p_S^n = S_c = \prod_{i=1}^n |x_i| = \prod_{i=1}^n p_i.$$

Multiply both sides of equation 4.2 by  $c^n$  to get the ruler measures:

$$(4.3) \quad p_S^n = \prod_{i=1}^n p_i \quad \Rightarrow \quad (p_S \cdot c)^n = \prod_{i=1}^n (p_i \cdot c).$$

Apply the ruler convergence theorem (2.2) to equation 4.3:

$$(4.4) \quad S = \lim_{c \rightarrow 0} (p_S \cdot c)^n \quad \wedge \quad (p_S \cdot c)^n = \prod_{i=1}^n (p_i \cdot c) \quad \wedge \quad \lim_{c \rightarrow 0} (p_i \cdot c) = s_i$$

$$\Rightarrow \quad S = \lim_{c \rightarrow 0} (p_S \cdot c)^n = \prod_{i=1}^n \lim_{c \rightarrow 0} (p_i \cdot c) = \prod_{i=1}^n s_i. \quad \square$$

## 5. Ordered and symmetric geometries

Neither classical nor modern analytic geometry has provided any insight into why physical Euclidean geometry appears to be limited to at most three dimensions. It will be proved that the same combinatorial relationships that converge to the triangle inequality, taxicab distance, Euclidean distance, and volume also limit distance and volume to a cyclic set of at most three dimensions.

Both taxicab (Manhattan) and Euclidean distance exists at the same time between every two distinct points because both types of distance are allowed by the countable distance range (3.1). Likewise, the commutative properties of union and addition in the defintion of countable distance range and multiplication in countable size allow all orderings (permutations) of the domain sets to exist at the same time.

Mathematics defines the order in a set in terms of a successor function and a predecessor (inverse) function. Half of the permutations of an ordered set are traversed via the successor function and the other half via the predecessor function.

Consider a set of four elements labeled and asserted to have the successor order,  $\{1, 2, 3, 4\}$ . A successor function or predecessor function listing the order,  $(\dots, 2, 4, \dots)$ , would contradict the previously asserted order because element 4 is neither the successor nor predecessor of 2 in the previous order.

Every possible order exists at the same time without contradicting each other only where each element of a set is sequentially adjacent (a successor or predecessor) to every other element (herein refered to as a "symmetric geometry"). It will now be proved that an "ordered" and "symmetric" geometry is a cyclic set containing at most three elements (three dimensions of intervals).

DEFINITION 5.1. Ordered geometry:

$$\forall i \ n \in \mathbb{N}, \ i \in [1, n-1], \ \forall x_i \in \{x_1, \dots, x_n\}, \\ \text{successor } x_i = x_{i+1} \ \wedge \ \text{predecessor } x_{i+1} = x_i.$$

where  $\{x_1, \dots, x_n\}$  are a set of real-valued intervals (dimensions).

DEFINITION 5.2. Symmetric geometry (all permutations):

$$\forall i \ j \ n \in \mathbb{N}, \ \forall x_i \ x_j \in \{x_1, \dots, x_n\}, \ \text{successor } x_i = x_j \ \wedge \ \text{predecessor } x_j = x_i.$$

THEOREM 5.3. *An ordered and symmetric geometry is a cyclic set.*

$$\text{successor } x_n = x_1 \ \wedge \ \text{predecessor } x_1 = x_n.$$

The theorem and formal Coq-based proof is “ordered\_symmetric\_is\_cyclic,” which is located in the file `threed.v`.

PROOF. The property of order (5.1) defines unique successors and predecessors for all elements except for the successor of  $x_n$  and the predecessor of  $x_1$ . From the properties of a symmetric geometry (5.2):

$$(5.1) \quad i = n \ \wedge \ j = 1 \ \wedge \ \text{successor } x_i = x_j \Rightarrow \text{successor } x_n = x_1.$$

$$(5.2) \quad i = n \ \wedge \ j = 1 \ \wedge \ \text{predecessor } x_j = x_i \Rightarrow \text{predecessor } x_1 = x_n. \quad \square$$

In a cyclic set, every element is the first element and every element the last element. For example, using the cyclic set with elements labeled,  $\{1, 2, 3\}$ , starting with each element and counting through 3 cyclic successors and counting through 3 cyclic predecessors yields the permutations:  $(1, 2, 3)$ ,  $(2, 3, 1)$ ,  $(3, 1, 2)$ ,  $(1, 3, 2)$ ,  $(3, 2, 1)$ , and  $(2, 1, 3)$ . That is, a cyclically ordered set preserves sequential order while allowing some n-at-a-time permutations. If all possible n-at-a-time permutations are generated, then the cyclic set is also a symmetric geometry.

THEOREM 5.4. *An ordered and symmetric geometry is limited to at most 3 elements.*

The Coq-based lemmas and proofs in the file `threed.v` are:

**Lemmas:** `adj111`, `adj122`, `adj212`, `adj123`, `adj133`, `adj233`, `adj213`, `adj313`, `adj323`, and `not_all_mutually_adjacent_gt_3`.

The following proof uses Horn clauses (a subset of first-order logic) that uses unification and resolution. Horn clauses make it clear which facts satisfy a proof goal.

PROOF.

Because a symmetric and ordered set is a cyclic set (5.3), the successors and predecessors are cyclic:

DEFINITION 5.5. Successor of  $m$  is  $n$ :

$$(5.3) \quad \text{Successor}(m, n, \text{setsize}) \leftarrow (m = \text{setsize} \wedge n = 1) \vee (m + 1 \leq \text{setsize}).$$

DEFINITION 5.6. Predecessor of  $m$  is  $n$ :

$$(5.4) \quad \text{Predecessor}(m, n, \text{setsize}) \leftarrow (m = 1 \wedge n = \text{setsize}) \vee (m - 1 \geq 1).$$

DEFINITION 5.7. Adjacent: element  $m$  is adjacent to element  $n$  (an allowed permutation), if the cyclic successor of  $m$  is  $n$  or the cyclic predecessor of  $m$  is  $n$ . Notionally:

$$(5.5) \quad \text{Adjacent}(m, n, \text{setsize}) \leftarrow \text{Successor}(m, n, \text{setsize}) \vee \text{Predecessor}(m, n, \text{setsize}).$$

Every element is adjacent to every other element, where  $\text{setsize} \in \{1, 2, 3\}$ :

$$(5.6) \quad \text{Adjacent}(1, 1, 1) \leftarrow \text{Successor}(1, 1, 1) \leftarrow (1 = 1 \wedge 1 = 1).$$

$$(5.7) \quad \text{Adjacent}(1, 2, 2) \leftarrow \text{Successor}(1, 2, 2) \leftarrow (1 + 1 \leq 2).$$

$$(5.8) \quad \text{Adjacent}(2, 1, 2) \leftarrow \text{Successor}(2, 1, 2) \leftarrow (2 = 2 \wedge 1 = 1).$$

$$(5.9) \quad \text{Adjacent}(1, 2, 3) \leftarrow \text{Successor}(1, 2, 3) \leftarrow (1 + 1 \leq 2).$$

$$(5.10) \quad \text{Adjacent}(2, 1, 3) \leftarrow \text{Predecessor}(2, 1, 3) \leftarrow (2 - 1 \geq 1).$$

$$(5.11) \quad \text{Adjacent}(3, 1, 3) \leftarrow \text{Successor}(3, 1, 3) \leftarrow (3 = 3 \wedge 1 = 1).$$

$$(5.12) \quad \text{Adjacent}(1, 3, 3) \leftarrow \text{Predecessor}(1, 3, 3) \leftarrow (1 = 1 \wedge 3 = 3).$$

$$(5.13) \quad \text{Adjacent}(2, 3, 3) \leftarrow \text{Successor}(2, 3, 3) \leftarrow (2 + 1 \leq 3).$$

$$(5.14) \quad \text{Adjacent}(3, 2, 3) \leftarrow \text{Predecessor}(3, 2, 3) \leftarrow (3 - 1 \geq 1).$$

Must prove that for all  $\text{setsize} > 3$ , there exist non-adjacent elements (not every permutation allowed). For example, the first and third elements are not adjacent:

$$(5.15) \quad \forall \text{setsize} > 3: \quad \neg \text{Successor}(1, 3, \text{setsize}) \\ \leftarrow \text{Successor}(1, 2, \text{setsize}) \leftarrow (1 + 1 \leq \text{setsize}).$$

That is, 2 is the only successor of 1 for all  $\text{setsize} > 3$ , which implies 3 is not a successor of 1 for all  $\text{setsize} > 3$ .

$$(5.16) \quad \forall \text{setsize} > 3: \quad \neg \text{Predecessor}(1, 3, \text{setsize}) \\ \leftarrow \text{Predecessor}(1, n, \text{setsize}) \leftarrow (1 = 1 \wedge n = \text{setsize}).$$

That is,  $n = \text{setsize}$  is the only predecessor of 1 for all  $\text{setsize} > 3$ , which implies 3 is not a predecessor of 1 for all  $\text{setsize} > 3$ .

$$(5.17) \quad \forall \text{setsize} > 3: \quad \neg \text{Adjacent}(1, 3, \text{setsize}) \\ \leftarrow \neg \text{Successor}(1, 3, \text{setsize}) \wedge \neg \text{Predecessor}(1, 3, \text{setsize}). \quad \square$$

## 6. Summary

Applying the ruler measure (2.1) and ruler convergence proof (2.2) to a set of real-valued domain intervals and an image interval yields some new insights into geometry and physics.

- (1) Countable, surjective functions (many-to-one/combinatorial relationships) converge to the continuous, bijective functions: triangle inequality, taxicab (Manhattan) distance, Euclidean distance and volume.
- (2) Ruler-based proofs expose the difference between distance and size (length/area/volume) measures: The number of elements in a distance set is a function of the surjective correspondences from the elements of each disjoint domain set to the elements of an image (distance) set. In contrast,



the number of elements in a size (length/area/volume) set is a function solely of the surjective correspondences between the elements of disjoint domain set elements.

- (3) Applying the ruler measure to the surjective, countable distance range (3.1) provides the insight that all notions of distance are based on the principle that for each disjoint domain set there exists a corresponding distance set containing the same number of elements:
  - (a) The countable distance range principle converges to the real-valued triangle inequality, which is the basis for the definition of metric space. The other properties of metric space also come from the countable distance range principle. Therefore, a function is not a distance metric unless it satisfies the more fundamental countable distance range principle (3.1).
  - (b) The upper bound of the countable distance range converging to taxicab (Manhattan) distance shows that the longest possible path starting at point A and going to point B where each step decreases the distance to point B, is due to the union of disjoint distance sets, where there is a one-to-one correspondence (bijective mapping) of each domain set element to each distance set element.
  - (c) The lower bound of the countable distance range converging to Euclidean distance provides the insight that the shortest possible distance path is due to the maximum intersection of distance sets within the constraint of the maximum number of surjective correspondences, where all of the  $p_i$  number of elements in the  $i^{th}$  domain set correspond to each of the  $p_i$  number of elements in the  $i^{th}$  distance set.
  - (d) All  $L^{p>2}$  norms generated from the countable distance range principle would require more than all the  $p_i$  number of elements in the  $i^{th}$  domain set corresponding to an element of the  $i^{th}$  distance set, which would be over-counting the number of possible surjective (many-to-one) correspondences. The definition of metric space and number theory have not provided this over-counting insight into  $L^{p>2}$  norms.
  - (e) Euclidean distance (3.3) was derived without any notions of side, angle, or shape. A parametric variable relating the sizes of two domain intervals can be easily derived using calculus (Taylor series) and the Euclidean distance equation to generate the arc sine and arc cosine functions of the parametric variable (arc angle). In other words, the notions of side and angle are derived from Euclidean distance, which is the reverse perspective of classical geometry [Joy98] [Loo68] [Ber88] and axiomatic foundations for geometry [Bir32] [Hil80] [TG99].
- (4) Applying the ruler measure and ruler convergence proof to the countable size definition (4.1) allows a proof that the Cartesian product of same-sized subintervals of real-valued intervals converges to the product of the interval sizes (Euclidean volume):
  - (a) Euclidean size (length/area/volume) was derived from a countable set-based notion of size without notions of sides, angles, and shape.

- (b) The countable set-based definition of size converging to Euclidean volume provides a more self-contained foundation under real analysis and calculus by not having to import volume from Euclidean geometry as a definition.
- (5) The surjective relations of countable distance range (3.1) and countable size (4.1) that generate the real-valued triangle inequality, taxicab (Manhattan) distance, Euclidean distance, and volume equations also have a symmetry property (5.2) that limits distance and volume to a cyclic set (5.3) of three dimensions (5.4). This symmetry property explains why only three dimensions of physical space can be observed.
- (6) There are two ways to extend a geometry beyond three dimensions:
  - (a) The properties of any higher number of dimensions of distance-like and volume-like equations can be studied. But, those higher dimensional equations are not applicable to physics because they ignore the dimensions-limiting property of symmetry (5.2).
  - (b) A higher dimensional geometry that can be applied to physics is where distance and volume in three dimensions is a function of other (non-distance, non-volume) variables, like time.

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