

The Set Properties Generating Geometry and Physics

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ABSTRACT. Volume and the Minkowski distances/Lp norms (e.g., Euclidean distance) are derived from a set and limit-based foundation without referencing the primitives of geometry. Sequencing a linearly ordered set in all n-at-a-time permutations via successor/predecessor relations limits n to at most 3, for example, 3 dimensions of physical space. Therefore, all other interval lengths have different types that can only be related to a 3-dimensional distance interval length via conversion ratios. The ratios and geometry proofs provide simpler derivations of the spacetime, Lorentz, Newton's gravity, Coulomb's charge force, and Einstein-Planck equations and corresponding constants. All proofs are verified in Coq.

CONTENTS

1. Introduction	1
2. Ruler measure and convergence	2
3. Volume	3
4. Distance	4
5. Applications to physics	7
6. Insights and implications	9
References	12

1. Introduction

Mathematical (real) analysis can construct differential calculus from a set and limit-based foundation without the need to reference the primitives and relations of Euclidean (empirical) geometry, like straight line, angle, slope, etc. But the Riemann and Lebesgue integrals and measure theory (for example, Hilbert spaces and the Lebesgue measure) define Euclidean volume as the product of interval lengths. And the vector norm and metric space use Euclidean distance and its properties as definitions [Gol76] [Rud76]. Here, volume and distance are derived from a set and limit-based foundation without the hand-waving references to the primitives and relations of geometry for justification.

An abstract, set-based definition of volume is the cardinal, v_c , of a set of Cartesian product n-tuples, $v_c = \prod_{i=1}^n |x_i|$, where $|x_i|$ is the cardinal of the countable set, x_i . Where $|x_i|$ is the number of partitions of the interval, $[a_i, b_i] \subset \mathbb{R}$, and $s_i = b_i - a_i$, it will be proved that only Euclidean volume, $v = \prod_{i=1}^n s_i$, can be derived from $v_c = \prod_{i=1}^n |x_i|$ without making any assumptions about the function that maps an n-tuple of domain interval sizes to a range interval size. Some generalizations to include non-Euclidean volumes are: $v_c = a_c \prod_{i=1}^n |x_i|$ and $v = a \prod_{i=1}^n s_i$, where a_c and a are functions that return scalar values.

Where the domain set sizes, $|x_i|$ and s_i , are inverse functions of n-volumes: $\exists v_c \in \{0, \mathbb{N}\} : v_c = \sum_{i=1}^m a_{c,i} |x_i|^n$ and $\exists v \in \mathbb{R} : v = \sum_{i=1}^m a_i s_i^n$. $\exists d \in \mathbb{R} : d^n = v \Rightarrow d = (\sum_{i=1}^m a_i s_i^n)^{1/n}$, which are herein defined as “geometric” distances. Proving that Euclidean volume and the L_p norms (Minkowski distances), $d = (\sum_{i=1}^m s_i^n)^{1/n}$, are derived from the same abstract, set-based definition of a volume provides a unifying set and limit-based foundation under real-valued volume and distance.

It is commonly assumed that the dimensions of physical space can be sequenced in any n-at-a-time order. But sequencing of a set, $i = 1, \dots, n$ (for example, a set of n number domain intervals or dimensions), where i indexes to the same element each sequencing, is a strict linear order that set theory defines in terms of successor and predecessor functions. Sequencing a strict linear order in all n-at-a-time orders (permutations) requires the “symmetry” property of every set member being either a successor or predecessor to every other set member. It will be proved that a linearly ordered and “symmetric” set requires $n \leq 3$.

Therefore, an additional element cannot be in a set of 3 linearly ordered and symmetric “distance” elements and has a different type. And relating the size of one set to the size of another set having a different type requires a constant, type (unit) conversion ratio. Constant unit-factoring conversion ratios combined with the geometry proofs provide simpler derivations of the spacetime, Lorentz, Newton’s gravity, Coulomb’s charge force, and Einstein-Planck equations and corresponding constants. Impacts on Einstein’s field (general relativity) equations are also shown.

All the proofs in this article are trivial. But to ensure confidence, all the proofs have been verified using the Coq proof verification system [Coq23]. The formal proofs are in the Coq files, “euclidrelations.v” and “threed.v,” at: <https://github.com/treeck/RASRGGeometry>.

2. Ruler measure and convergence

Derivatives and integrals use a 1-1 correspondence between the infinitesimals of each interval, where the size of the infinitesimals in each interval are proportionate to the size of the interval, which precludes using derivatives and integrals to directly express many-to-one, one-to-many, and many-to-many (Cartesian product) mappings between same-sized, size κ , infinitesimals in different-sized intervals. Further, using tools that define Euclidean volume and distance precludes using those tools to derive Euclidean volume and distance.

Therefore, a different tool is used here. A ruler (measuring stick) measures the size of each interval *approximately* as the sum of the nearest integer number, p , of whole subintervals (infinitesimals), where each infinitesimal has the *same* size, κ , across all intervals. The ruler is both an inner and outer measure of an interval.

DEFINITION 2.1. Ruler measure, M : $\forall [a, b] \subset \mathbb{R}, s = b - a \wedge \kappa > 0 \wedge (p = \text{floor}(s/\kappa) \vee p = \text{ceiling}(s/\kappa)) \wedge M = \sum_{i=1}^p \kappa = p\kappa$.

THEOREM 2.2. *Ruler convergence:* $M = \lim_{\kappa \rightarrow 0} p\kappa = s$.

The formal proof, “limit_c_0_M_eq_exact_size,” is in the file, euclidrelations.v.

PROOF. (epsilon-delta proof)

By definition of the floor function, $\text{floor}(x) = \max(\{y : y \leq x, y \in \mathbb{Z}, x \in \mathbb{R}\})$:

$$(2.1) \quad \forall \kappa > 0, p = \text{floor}(s/\kappa) \wedge 0 \leq |\text{floor}(s/\kappa) - s/\kappa| < 1 \Rightarrow |p - s/\kappa| < 1.$$

Multiply both sides of inequality 2.1 by κ :

$$(2.2) \quad \forall \kappa > 0, |p - s/\kappa| < 1 \Rightarrow |p\kappa - s| < |\kappa| = |\kappa - 0|.$$

$$(2.3) \quad \begin{aligned} \forall \epsilon = \delta \quad \wedge \quad |p\kappa - s| < |\kappa - 0| < \delta \\ \Rightarrow \quad |\kappa - 0| < \delta \quad \wedge \quad |p\kappa - s| < \delta = \epsilon \quad := \quad M = \lim_{\kappa \rightarrow 0} p\kappa = s. \quad \square \end{aligned}$$

The following is an example of ruler convergence for the interval, $[0, \pi]$: $s = \pi - 0$, and $p = \text{floor}(s/\kappa) \Rightarrow p \cdot \kappa = 3.1_{\kappa=10^{-1}}, 3.14_{\kappa=10^{-2}}, 3.141_{\kappa=10^{-3}}, \dots, \pi_{\lim_{\kappa \rightarrow 0}}$.

LEMMA 2.3. $\forall n \geq 1, 0 < \kappa < 1 \Rightarrow \lim_{\kappa \rightarrow 0} \kappa^n = \lim_{\kappa \rightarrow 0} \kappa$.

PROOF. The formal proof, “lim_c_to_n_eq_lim_c,” is in the Coq file, euclidrelations.v.

$$(2.4) \quad n \geq 1 \quad \wedge \quad 0 < \kappa < 1 \Rightarrow 0 < \kappa^n < \kappa \Rightarrow |\kappa - \kappa^n| < |\kappa| = |\kappa - 0|.$$

$$(2.5) \quad \begin{aligned} \forall \epsilon = \delta \quad \wedge \quad |\kappa - \kappa^n| < |\kappa - 0| < \delta \\ \Rightarrow \quad |\kappa - 0| < \delta \quad \wedge \quad |\kappa - \kappa^n| < \delta = \epsilon \quad := \quad \lim_{\kappa \rightarrow 0} \kappa^n = 0. \end{aligned}$$

$$(2.6) \quad \lim_{\kappa \rightarrow 0} \kappa^n = 0 \quad \wedge \quad \lim_{\kappa \rightarrow 0} \kappa = 0 \Rightarrow \lim_{\kappa \rightarrow 0} \kappa^n = \lim_{\kappa \rightarrow 0} \kappa. \quad \square$$

3. Volume

DEFINITION 3.1. Volume, v_c , is the number of ordered combinations (n-tuples) of the members of n number of disjoint, countable domain sets, x_i :

$$(3.1) \quad \exists n \in \mathbb{N}, a_c, v_c, \in \{0, \mathbb{N}\}, x_i \in \{x_1, \dots, x_n\}, \bigcap_{i=1}^n x_i = \emptyset : v_c = a_c \prod_{i=1}^n |x_i|.$$

THEOREM 3.2. *Euclidean volume, $v = \prod_{i=1}^n s_i$, is the “flat” volume size case, $v_c = \prod_{i=1}^n |x_i|$, where each countable set, x_i , is the set of partitions of an interval, $[a_i, b_i] \subset \mathbb{R}$.*

$$(3.2) \quad \begin{aligned} \forall [a_i, b_i] \in \{[a_1, b_1], \dots, [a_n, b_n]\}, [v_a, v_b] \subset \mathbb{R}, s_i = b_i - a_i, v = v_a - v_b, \\ v_c = \prod_{i=1}^n |x_i| \Rightarrow v = \prod_{i=1}^n s_i. \end{aligned}$$

The formal proof, “Euclidean_volume,” is in the Coq file, euclidrelations.v.

PROOF.

$$(3.3) \quad \begin{aligned} v_c = \prod_{i=1}^n |x_i| \quad \Leftrightarrow \quad v_c \cdot \kappa = (\prod_{i=1}^n |x_i|) \cdot \kappa \\ \Leftrightarrow \quad \lim_{\kappa \rightarrow 0} v_c \cdot \kappa = \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i|) \cdot \kappa. \end{aligned}$$

Apply the ruler (2.1) and ruler convergence (2.2) to v :

$$(3.4) \quad \exists v, \kappa \in \mathbb{R} : v_c = \text{floor}(v/\kappa) \Rightarrow v = \lim_{\kappa \rightarrow 0} v_c \cdot \kappa = \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i|) \cdot \kappa.$$

Apply lemma 2.3 to equation 3.4:

$$(3.5) \quad v = \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i|) \cdot \kappa = \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i|) \cdot \kappa^n = \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i| \cdot \kappa).$$

Apply the ruler (2.1) and ruler convergence (2.2) to s_i :

$$(3.6) \quad \exists s_i, \kappa \in \mathbb{R} : \text{floor}(s_i/\kappa) = |x_i| \Rightarrow \lim_{\kappa \rightarrow 0} (|x_i| \cdot \kappa) = s_i \\ \Rightarrow \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i| \cdot \kappa) = \prod_{i=1}^n s_i.$$

$$(3.7) \quad v = \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i| \cdot \kappa) \quad \wedge \quad \lim_{\kappa \rightarrow 0} (\prod_{i=1}^n |x_i| \cdot \kappa) = \prod_{i=1}^n s_i \\ \Rightarrow v = \prod_{i=1}^n s_i \quad \square$$

4. Distance

4.1. Geometric distance. Where each domain set, x_i and $[a_i, b_i] \subset \mathbb{R}$, are inverse functions of n-volumes:

$$(4.1) \quad v = \sum_{i=1}^m a_i s_i^n. \Rightarrow \exists d \in \mathbb{R} : d^m = v = \sum_{i=1}^m a_i s_i^n. \Rightarrow d = (\sum_{i=1}^m a_i s_i^n)^{1/n}.$$

DEFINITION 4.1. Geometric distance, d : $d = (\sum_{i=1}^m a_i s_i^n)^{1/n}$.

4.2. Minkowski distance (L_p norm).

THEOREM 4.2. *The Minkowski distance (L_p norm) is the “flat” geometric distance (4.1) case, $d_c^n = \sum_{i=1}^m |x_i|^n$.*

The formal proof, “Minkowski_distance,” is in the Coq file, euclidrelations.v.

$$d_c^n = \sum_{i=1}^m |x_i|^n \Rightarrow \exists d, s_1, \dots, s_m \in \mathbb{R} : d = (\sum_{i=1}^m s_i^n)^{1/n}.$$

PROOF. Apply the ruler (2.1):

$$(4.2) \quad \exists d, s_1, \dots, s_m \in \mathbb{R} : d_c = \text{floor}(d/\kappa) \quad \wedge \quad |x_i| = \text{floor}(s_i/\kappa).$$

Apply the ruler convergence (2.2):

$$(4.3) \quad |x_i| = \text{floor}(s_i/\kappa) \Rightarrow s_i = \lim_{\kappa \rightarrow 0} |x_i| \cdot \kappa.$$

$$(4.4) \quad d_c^n = \sum_{i=1}^m |x_i|^n \Rightarrow d^n = \lim_{\kappa \rightarrow 0} d_c^n \cdot \kappa = \lim_{\kappa \rightarrow 0} (\sum_{i=1}^m (|x_i|^n) \cdot \kappa).$$

Apply lemma 2.3 to equation 4.4 and substitute equation 4.3:

$$(4.5) \quad d^n = \lim_{\kappa \rightarrow 0} (\sum_{i=1}^m (|x_i|^n) \cdot \kappa) \quad \wedge \quad \lim_{\kappa \rightarrow 0} \kappa^n = \lim_{\kappa \rightarrow 0} \kappa \\ \Rightarrow d^n = \lim_{\kappa \rightarrow 0} \sum_{i=1}^m (|x_i|^n) \cdot \kappa^n = \lim_{\kappa \rightarrow 0} \sum_{i=1}^m (|x_i| \cdot \kappa)^n.$$

Apply equation 4.3 to equation 4.5:

$$(4.6) \quad d^n = \lim_{\kappa \rightarrow 0} \sum_{i=1}^m (|x_i| \cdot \kappa)^n \quad \wedge \quad s_i = \lim_{\kappa \rightarrow 0} |x_i| \cdot \kappa \Rightarrow d^n = \sum_{i=1}^m s_i^n.$$

$$(4.7) \quad d^n = \sum_{i=1}^m s_i^n \Leftrightarrow d = (\sum_{i=1}^m s_i^n)^{1/n}. \quad \square$$

4.3. Distance inequality. Proving that all Minkowski distances (L_p norms) satisfy the metric space triangle inequality requires another inequality. The formal proof, distance_inequality, is in the Coq file, euclidrelations.v.

THEOREM 4.3. *Distance inequality*

$$\forall n \in \mathbb{N}, v_a, v_b \geq 0 : (v_a + v_b)^{1/n} \leq v_a^{1/n} + v_b^{1/n}.$$

PROOF. Expand the n-volume, $(v_a^{1/n} + v_b^{1/n})^n$, using the binomial expansion:

$$(4.8) \quad \forall v_a, v_b \geq 0 : \quad v_a + v_b \leq v_a + v_b + \\ \sum_{i=1}^n \binom{n}{i} (v_a^{1/n})^{n-i} (v_b^{1/n})^i + \sum_{i=1}^n \binom{n}{i} (v_a^{1/n})^i (v_b^{1/n})^{n-i} = (v_a^{1/n} + v_b^{1/n})^n.$$

Take the n^{th} root of both sides of the inequality:

$$(4.9) \quad \forall v_a, v_b \geq 0, n \in \mathbb{N} : v_a + v_b \leq (v_a^{1/n} + v_b^{1/n})^n \Rightarrow (v_a + v_b)^{1/n} \leq v_a^{1/n} + v_b^{1/n}. \quad \square$$

4.4. Distance sum inequality. The formal proof, `distance_sum_inequality`, is in the `Coq` file, `euclidrelations.v`.

THEOREM 4.4. *Distance sum inequality*

$$\forall m, n \in \mathbb{N}, a_i, b_i \geq 0 : (\sum_{i=1}^m (a_i^n + b_i^n))^{1/n} \leq (\sum_{i=1}^m a_i^n)^{1/n} + (\sum_{i=1}^m b_i^n)^{1/n}.$$

PROOF. Apply the distance inequality (4.3):

$$(4.10) \quad \forall m, n \in \mathbb{N}, v_a, v_b \geq 0 : \quad v_a = \sum_{i=1}^m a_i^n \quad \wedge \quad v_b = \sum_{i=1}^m b_i^n \quad \wedge \\ (v_a + v_b)^{1/n} \leq v_a^{1/n} + v_b^{1/n} \quad \Rightarrow \quad ((\sum_{i=1}^m a_i^n) + (\sum_{i=1}^m b_i^n))^{1/n} = \\ (\sum_{i=1}^m (a_i^n + b_i^n))^{1/n} \leq (\sum_{i=1}^m a_i^n)^{1/n} + (\sum_{i=1}^m b_i^n)^{1/n}. \quad \square$$

4.5. Metric Space. All Minkowski distances (L_p norms) have the properties of metric space.

The formal proofs: `triangle_inequality`, `symmetry`, `non_negativity`, and `identity_of_indiscernibles` are in the `Coq` file, `euclidrelations.v`.

THEOREM 4.5. *Triangle Inequality:*

$$d(s_1, s_2) = (\sum_{i=1}^2 s_i^p)^{1/p} \quad \Rightarrow \quad d(u, w) \leq d(u, v) + d(v, w).$$

PROOF. $\forall p \geq 1, \quad k > 1, \quad u = s_1, \quad w = s_2, \quad v = w/k:$

$$(4.11) \quad (u^p + w^p)^{1/p} \leq ((u^p + w^p) + 2v^p)^{1/p} = ((u^p + v^p) + (v^p + w^p))^{1/p}.$$

Apply the distance inequality (4.3) to the inequality 4.11:

$$(4.12) \quad (u^p + w^p)^{1/p} \leq ((u^p + v^p) + (v^p + w^p))^{1/p} \quad \wedge \quad (v_a + v_b)^{1/n} \leq v_a^{1/n} + v_b^{1/n} \\ \wedge \quad v_a = u^p + v^p \quad \wedge \quad v_b = v^p + w^p \\ \Rightarrow \quad (u^p + w^p)^{1/p} \leq ((u^p + v^p) + (v^p + w^p))^{1/p} \leq (u^p + v^p)^{1/p} + (v^p + w^p)^{1/p} \\ \Rightarrow \quad d(u, w) = (u^p + w^p)^{1/p} \leq \\ (u^p + v^p)^{1/p} + (v^p + w^p)^{1/p} = d(u, v) + d(v, w). \quad \square$$

THEOREM 4.6. *Symmetry:* $d(s_1, s_2) = (\sum_{i=1}^2 s_i^p)^{1/p} \quad \Rightarrow \quad d(u, v) = d(v, u).$

PROOF. By the commutative law of addition:

$$(4.13) \quad \forall p : p \geq 1, \quad d(s_1, s_2) = (\sum_{i=1}^2 s_i^p)^{1/p} = (s_1^p + s_2^p)^{1/p} \\ \Rightarrow \quad d(u, v) = (u^p + v^p)^{1/p} = (v^p + u^p)^{1/p} = d(v, u). \quad \square$$

THEOREM 4.7. *Non-negativity:* $d(s_1, s_2) = (\sum_{i=1}^2 s_i^p)^{1/p} \quad \Rightarrow \quad d(u, w) \geq 0.$

PROOF. By definition, the length of an interval is always ≥ 0 :

$$(4.14) \quad \forall [a_1, b_1], [a_2, b_2], \quad u = b_1 - a_1, v = b_2 - a_2, \quad \Rightarrow \quad u \geq 0, v \geq 0.$$

$$(4.15) \quad p \geq 1, \quad u, v \geq 0 \quad \Rightarrow \quad d(u, v) = (u^p + v^p)^{1/p} \geq 0. \quad \square$$

THEOREM 4.8. *Identity of Indiscernibles: $d(u, u) = 0$.*

PROOF. From the non-negativity property (4.7):

$$(4.16) \quad d(u, w) \geq 0 \quad \wedge \quad d(u, v) \geq 0 \quad \wedge \quad d(v, w) \geq 0 \\ \Rightarrow \quad \exists d(u, w) = d(u, v) = d(v, w) = 0.$$

$$(4.17) \quad d(u, w) = d(v, w) = 0 \quad \Rightarrow \quad u = v.$$

$$(4.18) \quad d(u, v) = 0 \quad \wedge \quad u = v \quad \Rightarrow \quad d(u, u) = 0. \quad \square$$

4.6. The properties limiting a set to at most 3 members.

DEFINITION 4.9. Totally ordered set:

$$\forall i \, n \in \mathbb{N}, \, i \in [1, n-1], \, \forall x_i \in \{x_1, \dots, x_n\}, \\ \text{successor } x_i = x_{i+1} \quad \wedge \quad \text{predecessor } x_{i+1} = x_i.$$

DEFINITION 4.10. Symmetry (every set member is sequentially adjacent to every other member):

$$\forall i \, j \, n \in \mathbb{N}, \, \forall x_i \, x_j \in \{x_1, \dots, x_n\}, \quad \text{successor } x_i = x_j \Leftrightarrow \text{predecessor } x_j = x_i.$$

THEOREM 4.11. *A strict linearly ordered and symmetric set is a cyclic set.*

$$i = n \quad \wedge \quad j = 1 \quad \Rightarrow \quad \text{successor } x_n = x_1 \quad \wedge \quad \text{predecessor } x_1 = x_n.$$

The formal proof, “ordered_symmetric_is_cyclic,” is in the Coq file, `threed.v`.

PROOF. A total order (4.9) assigns a unique label to each set member and assigns unique successors and predecessors for all set members except for the successor of x_n and the predecessor of x_1 . Therefore, the only member that can be a successor of x_n , without creating a contradiction, is x_1 . And the only member that can be a predecessor of x_1 , without creating a contradiction, is x_n . Applying the symmetry property (4.10):

$$(4.19) \quad i = n \quad \wedge \quad j = 1 \quad \wedge \quad \text{successor } x_i = x_j \quad \Rightarrow \quad \text{successor } x_n = x_1.$$

Applying the definition of the symmetry property (4.10) to conclusion 4.19:

$$(4.20) \quad \text{successor } x_i = x_j \quad \Rightarrow \quad \text{predecessor } x_j = x_i \quad \Rightarrow \quad \text{predecessor } x_1 = x_n. \quad \square$$

THEOREM 4.12. *An ordered and symmetric set is limited to at most 3 members.*

The formal proofs in the Coq file `threed.v` are:

Lemmas: `adj111`, `adj122`, `adj212`, `adj123`, `adj133`, `adj233`, `adj213`, `adj313`, `adj323`, and `not_all_mutually_adjacent_gt_3`.

The following proof uses Horn clauses (a subset of first order logic), which makes it clear which facts satisfy a proof goal.

PROOF.

It was proved that an ordered and symmetric set is a cyclic set (4.11).

DEFINITION 4.13. (Cyclic) Successor of m is n :

$$(4.21) \quad \text{Successor}(m, n, \text{setsize}) \leftarrow (m = \text{setsize} \wedge n = 1) \vee (n = m + 1 \leq \text{setsize}).$$

DEFINITION 4.14. (Cyclic) Predecessor of m is n :

$$(4.22) \quad \text{Predecessor}(m, n, \text{setsize}) \leftarrow (m = 1 \wedge n = \text{setsize}) \vee (n = m - 1 \geq 1).$$

DEFINITION 4.15. Adjacent: member m is sequentially adjacent to member n if the successor of m is n or the predecessor of m is n . Notionally:

$$(4.23) \quad \text{Adjacent}(m, n, \text{setsize}) \leftarrow \text{Successor}(m, n, \text{setsize}) \vee \text{Predecessor}(m, n, \text{setsize}).$$

Prove that every member is adjacent to every other member, where $\text{setsize} \in \{1, 2, 3\}$:

$$(4.24) \quad \text{Adjacent}(1, 1, 1) \leftarrow \text{Successor}(1, 1, 1) \leftarrow (m = \text{setsize} \wedge n = 1).$$

$$(4.25) \quad \text{Adjacent}(1, 2, 2) \leftarrow \text{Successor}(1, 2, 2) \leftarrow (n = m + 1 \leq \text{setsize}).$$

$$(4.26) \quad \text{Adjacent}(2, 1, 2) \leftarrow \text{Successor}(2, 1, 2) \leftarrow (n = \text{setsize} \wedge m = 1).$$

$$(4.27) \quad \text{Adjacent}(1, 2, 3) \leftarrow \text{Successor}(1, 2, 3) \leftarrow (n = m + 1 \leq \text{setsize}).$$

$$(4.28) \quad \text{Adjacent}(2, 1, 3) \leftarrow \text{Predecessor}(2, 1, 3) \leftarrow (n = m - 1 \geq 1).$$

$$(4.29) \quad \text{Adjacent}(3, 1, 3) \leftarrow \text{Successor}(3, 1, 3) \leftarrow (n = \text{setsize} \wedge m = 1).$$

$$(4.30) \quad \text{Adjacent}(1, 3, 3) \leftarrow \text{Predecessor}(1, 3, 3) \leftarrow (m = 1 \wedge n = \text{setsize}).$$

$$(4.31) \quad \text{Adjacent}(2, 3, 3) \leftarrow \text{Successor}(2, 3, 3) \leftarrow (n = m + 1 \leq \text{setsize}).$$

$$(4.32) \quad \text{Adjacent}(3, 2, 3) \leftarrow \text{Predecessor}(3, 2, 3) \leftarrow (n = m - 1 \geq 1).$$

Member 2 is the only successor of member 1 for all $\text{setsize} > 3$, which implies member 3 is not (\neg) a successor of member 1 for all $\text{setsize} > 3$:

$$(4.33) \quad \neg \text{Successor}(1, 3, \text{setsize} > 3) \\ \leftarrow \text{Successor}(1, 2, \text{setsize} > 3) \leftarrow (n = m + 1 \leq \text{setsize}).$$

Member $n = \text{setsize} > 3$ is the only predecessor of member 1, which implies member 3 is not (\neg) a predecessor of member 1 for all $\text{setsize} > 3$:

$$(4.34) \quad \neg \text{Predecessor}(1, 3, \text{setsize} > 3) \\ \leftarrow \text{Predecessor}(1, \text{setsize}, \text{setsize} > 3) \leftarrow (m = 1 \wedge n = \text{setsize} > 3).$$

For all $\text{setsize} > 3$, some elements are not (\neg) sequentially adjacent to every other element (not symmetric):

$$(4.35) \quad \neg \text{Adjacent}(1, 3, \text{setsize} > 3) \\ \leftarrow \neg \text{Successor}(1, 3, \text{setsize} > 3) \wedge \neg \text{Predecessor}(1, 3, \text{setsize} > 3). \quad \square$$

5. Applications to physics

From the 3D proof (4.12), the interval lengths: t (time), m (mass), and q (charge) have different types (are from different sets) from a 3-dimensional interval length, r , that can be related via constant, unit-factoring, conversion ratios:

$$(5.1) \quad r = (r_c/t_c)t = ct = (r_c/m_G)m = (r_c/q_C)q,$$

5.1. Spacetime and Lorentz equations. From the Euclidean volume proof (3.2), two disjoint intervals, $[0, r]$ and $[0, r']$, defines an Euclidean 2-space. From the Minkowski distance proof (4.2), the interval lengths, r and r' , are inverse functions of 2 cuboid 2-volumes.

$$(5.2) \quad \forall r \geq r' \exists r_v \in \mathbb{R} : r^2 = r'^2 + r_v^2 \quad \wedge \quad \exists r_c, t_c, c, v \in \mathbb{R} : r/t = r_c/t_c = c \\ \wedge \quad r_v/t = v \quad \Rightarrow \quad r' = \sqrt{(ct)^2 - (vt)^2} = ct\sqrt{1 - (v/c)^2}.$$

Local (proper) distance, r' , contracts relative to coordinate distance, r , as $v \rightarrow c$:

$$(5.3) \quad r' = ct\sqrt{1 - (v/c)^2} \quad \wedge \quad ct = r \quad \Rightarrow \quad r' = r\sqrt{1 - (v/c)^2}.$$

From equation 5.2, coordinate time, t , dilates relative to local time, t' , as $v \rightarrow c$:

$$(5.4) \quad ct = r'/\sqrt{1 - (v/c)^2} \quad \wedge \quad r' = ct' \quad \Rightarrow \quad t = t'/\sqrt{1 - (v/c)^2}.$$

Using $r^2 = r'^2 + r_v^2$ from equation 5.2, where r_v is a 3-dimensional distance, one form of the flat Minkowski's spacetime event interval is:

$$(5.5) \quad dr^2 = dr'^2 + dr_v^2 \quad \wedge \quad dr_v^2 = dx_1^2 + dx_2^2 + dx_3^2 \quad \wedge \quad d(ct) = dr \\ \Rightarrow \quad dr'^2 = d(ct)^2 - dx_1^2 - dx_2^2 - dx_3^2.$$

The Lorentz transformations follow from equation 5.3 and Galilean transformation:

$$(5.6) \quad r' = r/\sqrt{1 - (v/c)^2} \quad \wedge \quad r = r' + vt \quad \Rightarrow \quad r' = (r - vt)/\sqrt{1 - (v/c)^2}.$$

$$(5.7) \quad r' = (r - vt)/\sqrt{1 - (v/c)^2} \quad \wedge \quad r = ct \quad \wedge \quad r' = ct' \\ \Rightarrow \quad t' = (t - (vt/c))/\sqrt{1 - (v/c)^2} = (t - (vr/c^2))/\sqrt{1 - (v/c)^2}.$$

5.2. Einstein's field (general relativity) equations. The spacetime interval equation (5.5) is the “flat” case of a geometric distance (4.1), where the general case is: $ds^2 = \sum_{i=0}^3 g_{i,i} dx_i^2$, where the metric tensor in Einstein's field equations is: $g_{\mu,\nu} = \text{diag}(g_{0,0}, g_{1,1}, g_{2,2}, g_{3,3})$ [Ein15] [Wey52].

The Gaussian curvature of a surface is limited to, at most, 3-space. Einstein created a Gaussian-like curvature, $G_{\mu,\nu}$, induced by $g_{\mu,\nu}$, in 4-space via the Ricci tensor, $\mathbf{R}_{\mu,\nu}$, and it's scalar curvature, R , where $G_{\mu,\nu} = \mathbf{R}_{\mu,\nu} - (1/2)Rg_{\mu,\nu}$. And the sum of two tensors is a tensor, $T_{\mu,\nu} : G_{\mu,\nu} + g_{\mu,\nu} = kT_{\mu,\nu}$, where Einstein defined the conversion factor as $k = 8\pi G/c^4$ [Wey52]. Newton's gravitational constant, G , was defined rather than derived from more basic constants.

5.3. Newton's gravity force equation and constant. From equation 5.1:

$$(5.8) \quad \forall m_1 m_2 = m^2 = (m_G/r_c)^2 r^2 \quad \Rightarrow \quad (r_c/m_G)^2 m_1 m_2 / r^2 = 1.$$

From equation 5.4, if r is the proper distance, then $r = ct\sqrt{1 - (v/c)^2}$, and where $v = 0$:

$$(5.9) \quad mr = ((m_G/r_c)r)(ct) = (m_G/r_c)(ct)^2 \quad \Rightarrow \quad ((r_c/m_G)/c^2)mr/t^2 = 1.$$

$$(5.10) \quad ((r_c/m_G)/c^2)mr/t^2 = 1 \quad \wedge \quad (r_c/m_G)^2 m_1 m_2 / r^2 = 1 \\ \Rightarrow \quad F := mr/t^2 = ((r_c/m_G)c^2) m_1 m_2 / r^2 = Gm_1 m_2 / r^2,$$

where the constant, $G = (r_c/m_G)c^2$, has the SI units: $m^3 \cdot kg^{-1} \cdot s^{-2}$. And where $|v| > 0$, $F = (r_c/m_G)(c^2 - v^2)m_1 m_2 / r^2$.

5.4. Coulomb's charge force and constant. From equation 5.1:

$$(5.11) \quad r = (r_c/m_G)m = (r_c/q_C)q_1 \Rightarrow m = (m_G/q_C)q_1.$$

Substituting equations 5.11 and 5.1 into equation 5.10:

$$(5.12) \quad m = (m_G/q_C)q_1 \quad \wedge \quad r_c/t_c = c \quad \wedge \quad F = ((r_c/m_G)c^2)m_1m_2/r^2 \\ \Rightarrow \quad F = (m_G/q_C)(r_c/q_C)(r_c/t_c)^2q_1q_2/r^2.$$

$$(5.13) \quad a_G = r_c/t_c^2 \quad \wedge \quad F = (m_G/q_C)(r_c/q_C)(r_c/t_c)^2q_1q_2/r^2 \\ \Rightarrow \quad F = (m_Ga_G)(r_c/q_C)^2q_1q_2/r^2 = k_eq_1q_2/r^2,$$

where the charge constant, $k_e = (m_Ga_G)(r_c/q_C)^2$, has the SI units: $N \cdot m^2 \cdot C^{-2}$. And where $|v| > 0$, $F = (m_G/q_C)(r_c/q_C)(c^2 - v^2)q_1q_2/r^2$.

5.5. Work and Einstein-Planck equations: From the ratios 5.1:

$$(5.14) \quad r = (r_c/m_G)m \quad \wedge \quad r = (r_c/t_c)t = ct \quad \wedge \quad m_p = (t/t_c)^2m_G \\ \Rightarrow mr = (m_G/r_c)r^2 = (m_G/r_c)(r_c/t_c)^2t^2 = (t/t_c)^2m_Gr_c = m_pr_c = k_W \\ \approx 2.2102190943 \cdot 10^{-42} \text{ kg } m,$$

where r is the displacement (Compton wavelength) of the mass, m .

$$(5.15) \quad m(ct)^2 = mr^2 \quad \wedge \quad mr = k_W \quad \Rightarrow \quad m(ct)^2 = k_Wr.$$

$$(5.16) \quad m(ct)^2 = k_Wr \Rightarrow E = mc^2 = k_Wr/t^2 = k_W(r/t)(1/t) = (k_Wc)(1/t) = hf,$$

where the Planck constant $h = k_Wc$ and the frequency $f = 1/t$. The relativistic Einstein-Planck equation is: $m(c^2 - v^2) = hf$.

6. Insights and implications

- (1) Euclid's proof that Euclidean distance is the smallest distance between two distinct points equate Euclidean distance to a straight line, where it is assumed that the straight line length is the smallest distance [Joy98]. And proofs that a straight line is the smallest distance equate the straight line to the Euclidean distance.

The calculus of variations cannot be used to prove that the smallest distance is the Euclidean distance in Euclidean space because the integrals make Euclidean assumptions, which would result in circular logic.

In Euclidean 2-space, if m represents the number of dimensions, then $m = 2 \Rightarrow 1 \leq n \leq 2$, which constrains the Minkowski distances (4.2) to a range from Manhattan distance (the largest distance, $d = (\sum_{i=1}^2 s_i^1)^{1/1}$, to Euclidean distance (the smallest distance, $d = (\sum_{i=1}^2 s_i^2)^{1/2}$).

- (2) The case of intersecting distance sets and requires generalizing the countable geometric distance definition (4.1) from: $d_c = (\sum_{i=1}^m |x_i|^n)^{1/n}$ to:

$$d_c = (\sum_{i=1}^m |x_i|^n - |x_i \cap (\bigcup_{j=1, i \neq j}^n x_j)|)^{1/n}.$$

Distance measures are used in shortest path and least cost path search algorithms with various applications, including machine learning. For example, intersecting domain sets allow neural networks to generalize a response across the intersecting domain sets, x_i and x_j .

- (3) Compare the distance sum inequality (4.4),

$$(6.1) \quad (\sum_{i=1}^m (a_i^n + b_i^n))^{1/n} \leq (\sum_{i=1}^m a_i^n)^{1/n} + (\sum_{i=1}^m b_i^n)^{1/n},$$

used to prove that all Minkowski distances satisfy the metric space triangle inequality property (4.5), to Minkowski's sum inequality:

$$(6.2) \quad (\sum_{i=1}^m (a_i^n + b_i^n)^n)^{1/n} \leq (\sum_{i=1}^m a_i^n)^{1/n} + (\sum_{i=1}^m b_i^n)^{1/n}$$

[Min53]. Note the difference in the left side of each equation:

$$(6.3) \quad \forall n > 1, 0 < a_i, b_i < 1: (\sum_{i=1}^m (a_i^n + b_i^n))^{1/n} > (\sum_{i=1}^m (a_i^n + b_i^n)^{\mathbf{n}})^{1/n}.$$

$$(6.4) \quad \forall n > 1, a_i, b_i > 1: (\sum_{i=1}^m (a_i^n + b_i^n))^{1/n} < (\sum_{i=1}^m (a_i^n + b_i^n)^{\mathbf{n}})^{1/n}.$$

The distance sum inequality is a more fundamental inequality because its proof does not require the assumptions required to prove the Minkowski sum inequality. And the distance sum inequality is derived from the definitions of volume and distance, which makes it more directly related to geometry.

- (4) From the 3D proof (4.12), more intervals than the 3 dimensions of distance intervals must have different types with lengths that are related to a 3-dimensional distance interval length, r , via constant, unit-factoring, conversion ratios (both direct and inverse proportion ratios). The direct proportion ratios for time, mass, and charge are: $r = (r_c/t_c)t = ct = (r_c/m_G)m = (r_c/q_C)q$. An inverse proportion ratio is the work ratio: $m_p r_c = k_W$. In SI units:

$$c_l = r_c/t_c \approx 2.99792458 \cdot 10^8 m s^{-1}.$$

$$c_m = r_c/m_G \approx 7.4261602691 \cdot 10^{-28} m kg^{-1}.$$

$$c_q = r_c/q_C \approx 8.6175172023 \cdot 10^{-18} m C^{-1}.$$

$$k_W = m_p r_c \approx 2.2102190943 \cdot 10^{-42} kg m.$$

- (5) The gravity, charge, and Planck constants are not fundamental constants because they are all derived from more basic constant ratios.
- (6) The derivations in this article show that the spacetime, gravity force, charge force, and Einstein-Planck equations all depend on time being proportionate to distance: $r = (r_c/t_c)t = ct$. For example, from the derivation of Newton's gravity equation (5.9), where $v = 0$: $G = (r_c/m_G)c^2$. Likewise, from the derivation of Coulomb's charge force equation (5.13) the constant, where $v = 0$: $k_e = (m_G/q_C)(r_c/q_C)c^2$. And from the derivation of the Planck constant (5.16): $h = (m_p r_c)c = k_W c$.
- (7) The derivation of the speed of light, work, and Einstein-Planck equations shows that all wave, frequency, displacement, particle sizes, and wave-particle duality are due to the relations between conversion ratios. The ratios make all sizes relative (no absolute sizes > 0).
- (8) The derivations of the spacetime equations and Lorentz transformations, here (5.1), differ from all other derivations and provide insights that the other derivations cannot provide.
- (a) The derivations, here, are much shorter and simpler.
- (b) The derivations of the spacetime equations, here, do not rely on the Lorentz transformations or Einsteins' postulates [Ein15]. The derivations do not even require the notion of light.

- (c) The derivations, here, rely only on geometry: the Euclidean volume proof (3.2), the Minkowski distances proof (4.2), and the 3D proof (4.12), which provides the insight that the geometry of physical space creates: 1) a maximum speed, c ; 2) the spacetime equations; and 3) the Lorentz transformations.
- (9) Applying the ratios to derive Newton's gravity force (5.3) and Coulomb's charge force (5.4) equations provide some firsts and some new insights into physics:
- (a) These are the first derivations of Newton's gravity and Coulomb's charge force equations to not assume the inverse square law or Gauss's flux divergence theorem. Note: the components of the Ricci and metric tensors in Einstein's field (general relativity) equations have the units, $1/\text{distance}^2$ [Wey52], which is an assumption of the inverse square law.
 - (b) These are the first derivations to show that the inverse square law and the property of force as mass times acceleration are the result of the conversion ratios, $r = (r_c/t_c)t = (r_c/m_G)m$.
 - (c) Using Occam's razor, those versions of constants like: Gauss' gravity and charge constants, vacuum magnetic permeability, etc. that contain the value 4π might be incorrect because those constants are based on the less parsimonious assumption that the inverse square law is due to Gauss's flux divergence on a sphere having the surface area, $4\pi r^2$.
 - (d) The derivations predict that values G and k_e are constants, in a local frame of reference, only where the local velocity is zero. The derived relativistic gravity and charge force equations are:

$$F = (r_c/m_G)(c^2 - v^2)m_1m_2/r^2 \quad (5.9)$$

$$F = (m_G/q_C)(r_c/q_C)(c^2 - v^2)q_1q_2/r^2 \quad (5.13).$$
 Note: the common use of the Lorentz factor, $\gamma = 1/\sqrt{1 - v^2/c^2}$, in Newton's equation, $F = Gm_1m_2/r^2\gamma$, is not derivable (is incorrect).
- (i) Einstein's gravity constant, $k = 8\pi G/c^4$ [Wey52], is only valid when the local velocity is 0. Otherwise, $k = 8\pi(r_G/m_G)(c^2 - v^2)/c^4$. As $v \rightarrow c \Rightarrow F \rightarrow 0$, implies a universe expanding faster than predicted by a constant k and also predicts an accelerating expansion.
 - (ii) From the spacetime equation 5.2, the distance r is a constant in the coordinate frame of reference, where $r = ct$. In Newton's gravity and Coulomb's charge equations, r , is local frame of reference. Therefore, $r' = ct$ would be the coordinate frame of reference, where $r^2 = r'^2 - r_v^2 \Rightarrow \lim_{r \rightarrow 0} r^2 = \lim_{r \rightarrow 0} r'^2 - r_v^2 = \lim_{r \rightarrow 0} (r'/t)^2 - (r_v/t)^2 = \lim_{r \rightarrow 0} c^2 - v^2 = 0$. Therefore, the inverse square law and flux divergence are approximations that only holds where $r \gg 0$. The inverse square law not holding at very small distances reduces the mass density of black holes (increases the radius) and might allow black hole evaporation.
- (10) There is no unit-factoring ratio converting a constant state value to continuously varying distance, time, mass, and charge values. Therefore, the spin states of two quantum entangled particles and the polarization states

of two quantum entangled photons are independent of the amount of distance between the particles and independent of time (no [zero] time). This might indicate a “point” (measure 0 length) of time, where a particle has either: both states (Schrödenger’s cat), or a third state, or no state.

- (11) It was proved that sequencing through a set, having a strict linear order via the successor/predecessor relations in all n-at-a-time permutations limits $n \leq 3$ (4.12), which is why there are only 3 dimensions of physical space.
- (a) If there are higher dimensions of ordered and symmetric geometric space, then there is a set of at most three members (4.12), each member being an ordered and symmetric set of 3 dimensions (three 3-dimensional balls).
 - (b) Each of 3 ordered and symmetric dimensions of space can have at most 3 sequentially ordered and symmetric state values, for example, an ordered and symmetric set of: 3 vector orientations, $\{-1, 0, 1\}$, per dimension of space, or 3 polarization states (xy, xz, yz), or 3 spin states.

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