

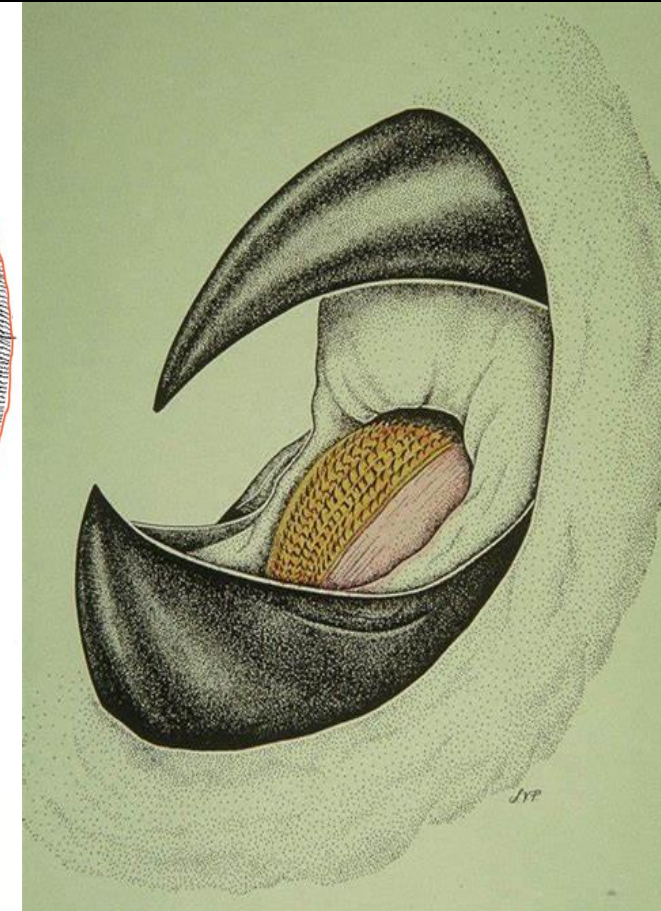
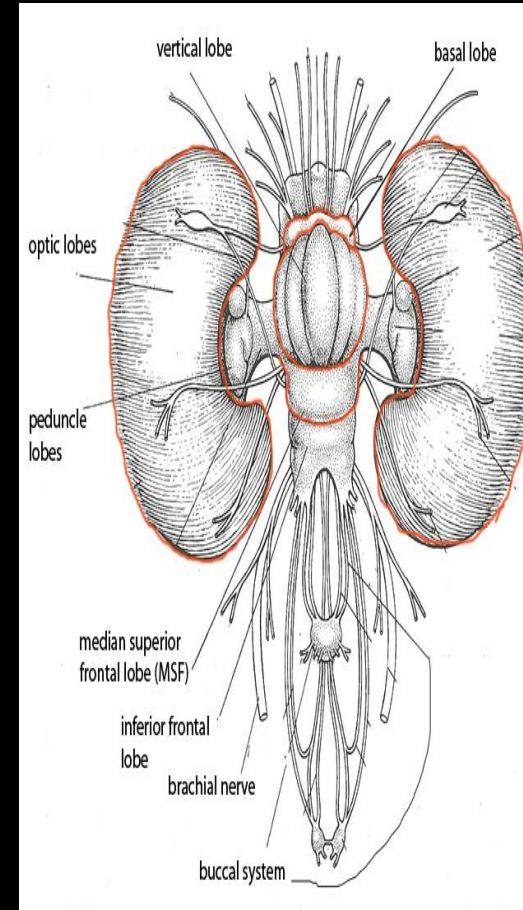


# OCTOPUS APPLICATIONS IN BIOMEDICAL ENGINEERING

Jordan Clemens

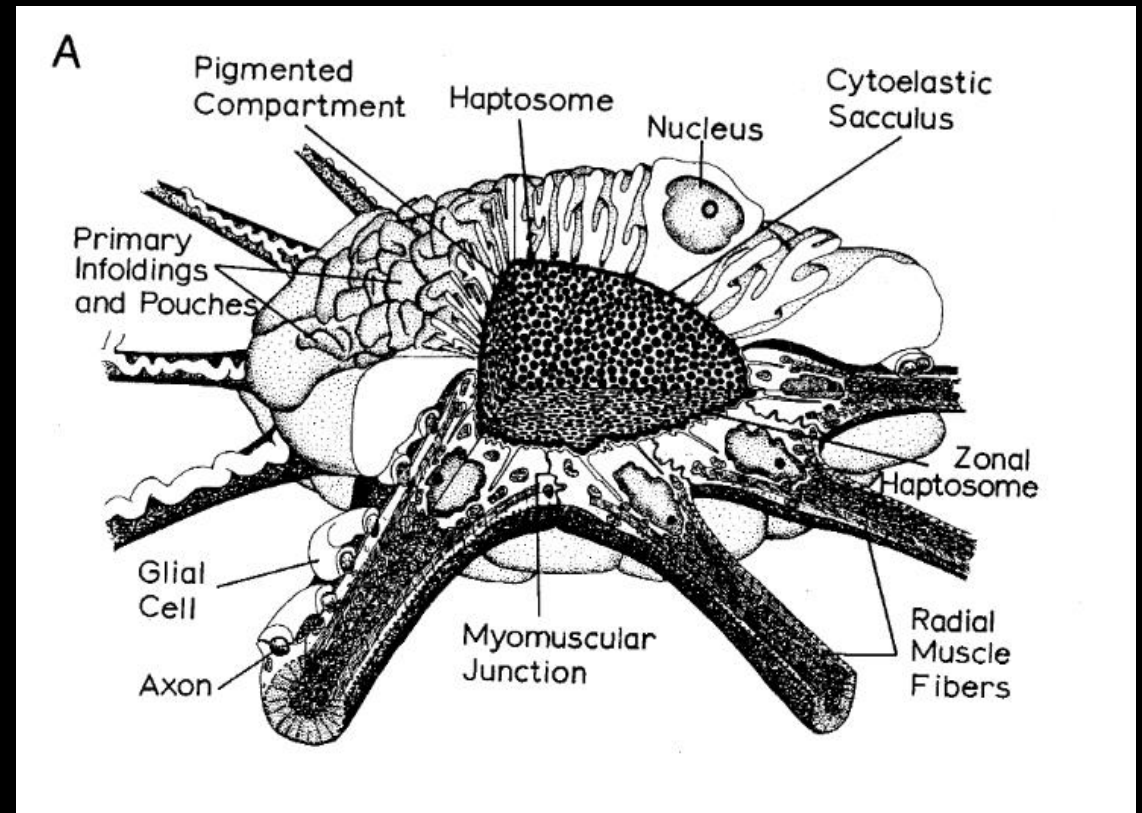
# OCTOPUS ANATOMY

- 9 brains
- Olfactory suction cups
- Radula
- 3 hearts
- Chromatophores
- Hemocyanin



# CHROMATOPHORES

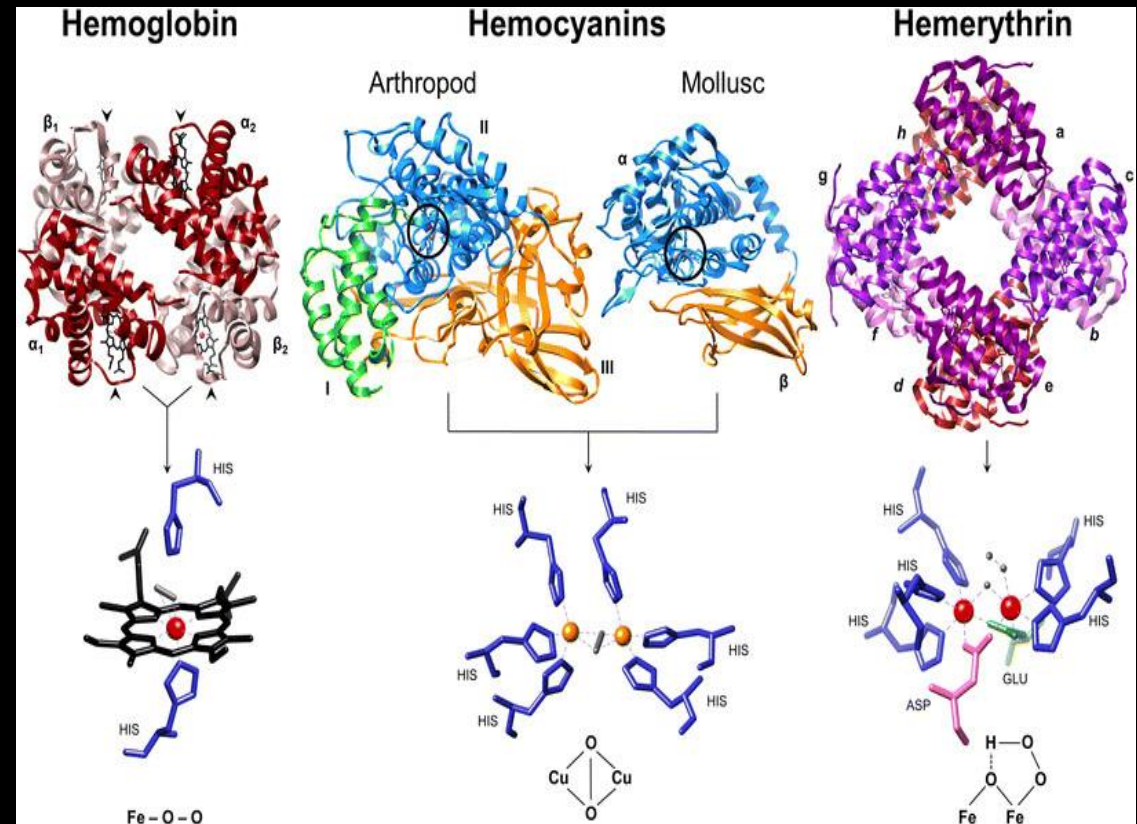
- 1970
- Neuromuscular ligand
- Pigment
- Depolarization
- Diverse
- Varying pigments
- Cluster-Density differs





# HEMOCYANIN

- Copper
- Orbital
- Dipole
- Direct oxygen bonding
- Optimized oxygen bonding at low temperature



# TENTACLES

- 4 different types of sensors
- Type 3 photosensitive
- GTK ligands
- Chemo-Tactile learning
- Longitudinal and transverse muscles
- Regenerative

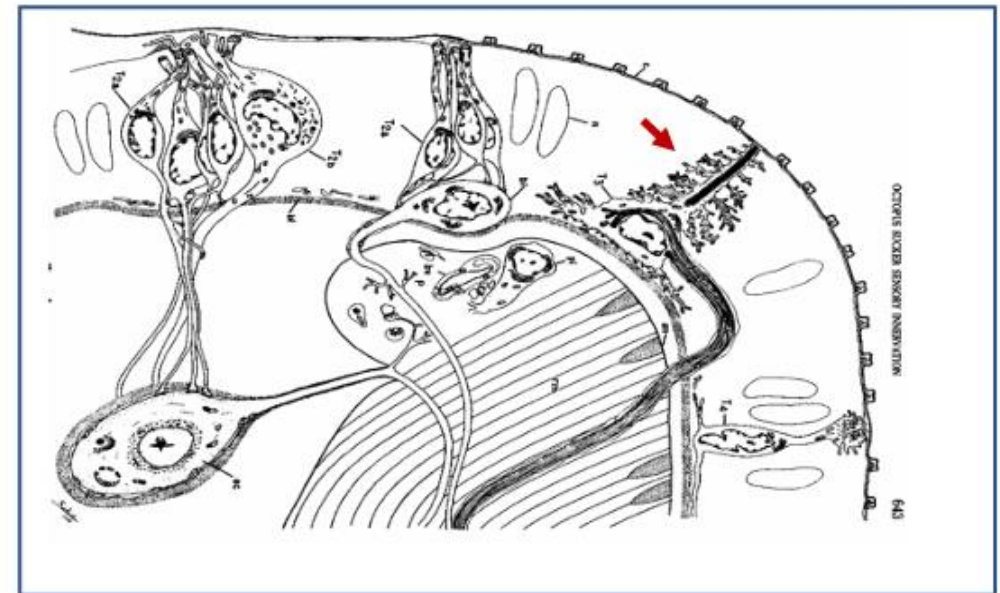


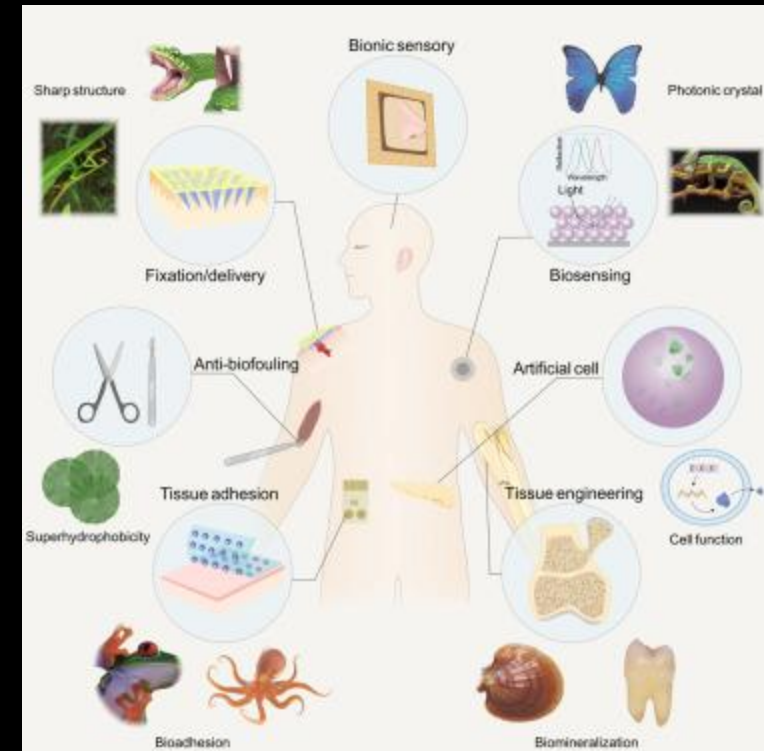
Figure.7. Summary of the four specialized sensory receptor cell types (T2a, T2b, T3 and T4) found in the epithelium rime of the sucker has been investigated by Graziadei and Gagne, 1976. The cell type with which we are concerned here is cell Type 3, which occurs in the epithelium over the infundibular muscle (indicated by arrow).



WHAT CONVERGENT  
EVOLUTIONARY FEATURES  
DO OCTOPUSES SHARE  
WITH WHAT OTHER  
ANIMALS?

# OCTOPUSES IN BIOMEDICAL SCIENCE

- 6<sup>th</sup> century BCE Alcmaeon of Croton
- Robotics
- Neuroscience (functional-structural)
- Regenerative medicine
- Interest increasing





# ROBOTICS

- Immunological
- Mechanical
- Biomechanical
- Hydrostatic skeleton reaching movement
- Nervous system control

Every muscle in the model exerts the following force

$$f(t) = A \left\{ a(t) F_a \left[ \frac{l(t)}{l_0^m} \right] F_v \left( \frac{v}{v_{max}} \right) + F_p \left[ \frac{l(t)}{l_0^m} \right] \right\} \quad (10)$$

where  $A$  is the cross-sectional area of the muscle,  $a \in [0, 1]$  is dimensionless activation function,  $l(t)$  is muscle length, and  $l_0^m$  is the specific length of the muscle at which active muscle force achieves its peak value (terminology after Zajac 1989). The active stress  $F_a$  equals the normalized active force (Fig. A) multiplied by the maximum stress. The dimensionless

$$A^{longitudinal} = \frac{1}{2} w_r d = \frac{1}{2} w_r^2$$

$$A^{transverse} = l_r d,$$

where  $w_r$  and  $l_r$  are the relaxed lengths<sup>6</sup> of the transverse and longitudinal segmental muscles, respectively; and  $d$  is the depth of the segment, which equals  $w_r$  at the initial relaxed shape of the arm. The factor of  $1/2$  in  $A^{longitudinal}$  is ascribed to the fact that there are a total of  $2n$  longitudinal muscles in the model for  $n$  segments (and only  $n + 1 \cong n$  transverse muscles in the model).

The activation dependency on time is expressed by  $a(t)$  and described below. Note that we assume a linear scaling of the force with the activation parameter. This is an approximation

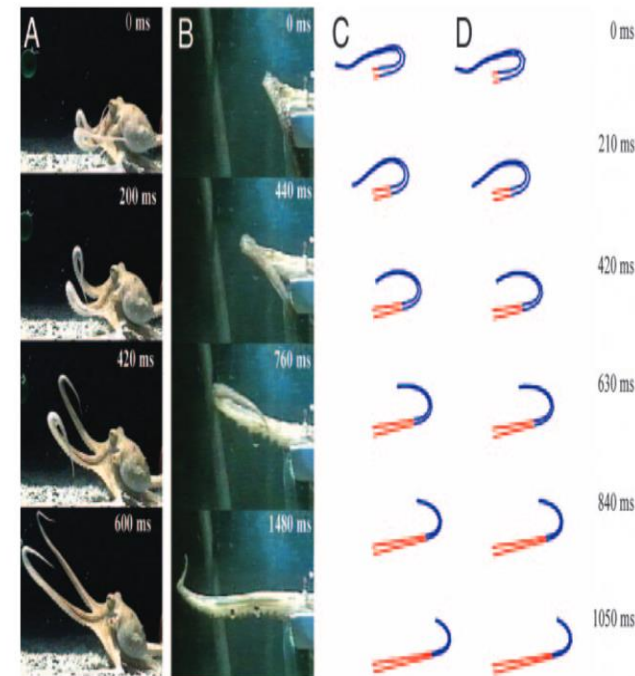
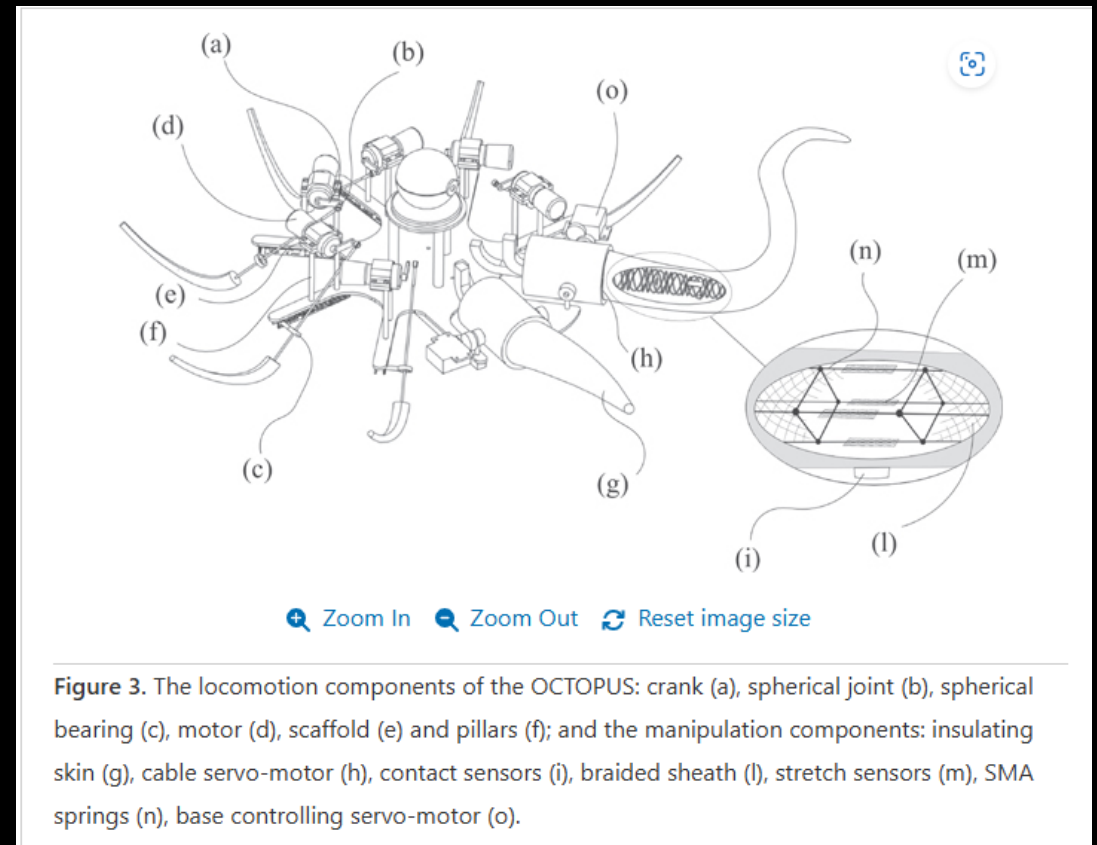


FIG. 6. A: sequence of frames showing a freely behaving octopus reaching toward a target. B: electrically evoked bend propagation in the denervated arm of a decerebrated animal. C: sequence from a simulated arm extension using the linear muscle model. Red represents fully activated arm segments. Blue represents all segments not yet activated. D: as in C using the nonlinear muscle model.



# BIOINSPIRED LOCOMOTION AND GRASPING IN WATER: THE SOFT EIGHT-ARM OCTOPUS ROBOT

- Electrolycra
- 8 servo's
- Visual control, central control and peripheral control
- 260 cm × 170 cm × 20 cm fresh water
- Object 1: rectangular cross-section wooden bar, 25 × 30 mm, 75 g weight. – Object 2: round polymeric cylinder, 25 mm outer diameter, 58 g weight. – Object 3: round polymeric cylinder tube, 60 mm outer diameter, 250 g weight. – Object 4: round aluminium tube, outer diameter 25 mm, 478 g weight.



# OCTOPUS RESULTS

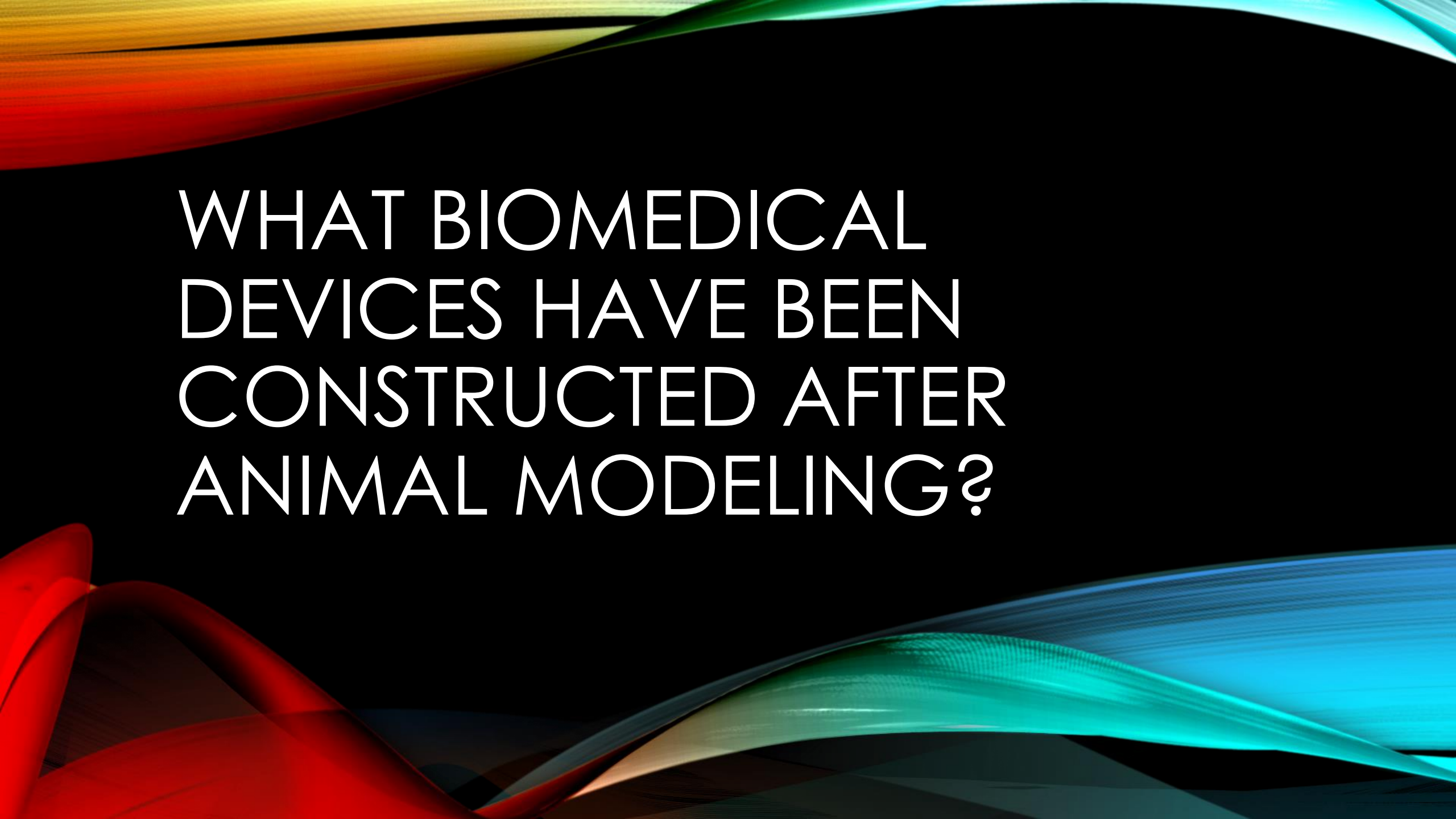
- Not omni-directional
- Independent of terrain
- One of first soft robotics with push and manipulation
- Slightly slower than real octopuses
- Mimics hydrostatic movement

**Table 4.** Errors on the estimation of angles for pose reconstruction.

Virtual segment number	Angle error mean (deg)	Angle error max (deg)	Angle error min (deg)
1	5.67	14	2
2	7.44	24	1
3	6.11	14	0
4	5.78	27	1
5	6.67	29	0

**Table 3.** Sensors activation (hit ratio) while grasping different objects.

Sensor no.	Object 1	Object 2	Object 3	Object 4
1	13/20	17/20	18/20	17/20
2	17/20	18/20	19/20	20/20
3	18/20	18/20	20/20	20/20
4	17/20	20/20	20/20	20/20
5	13/20	17/20	17/20	18/20

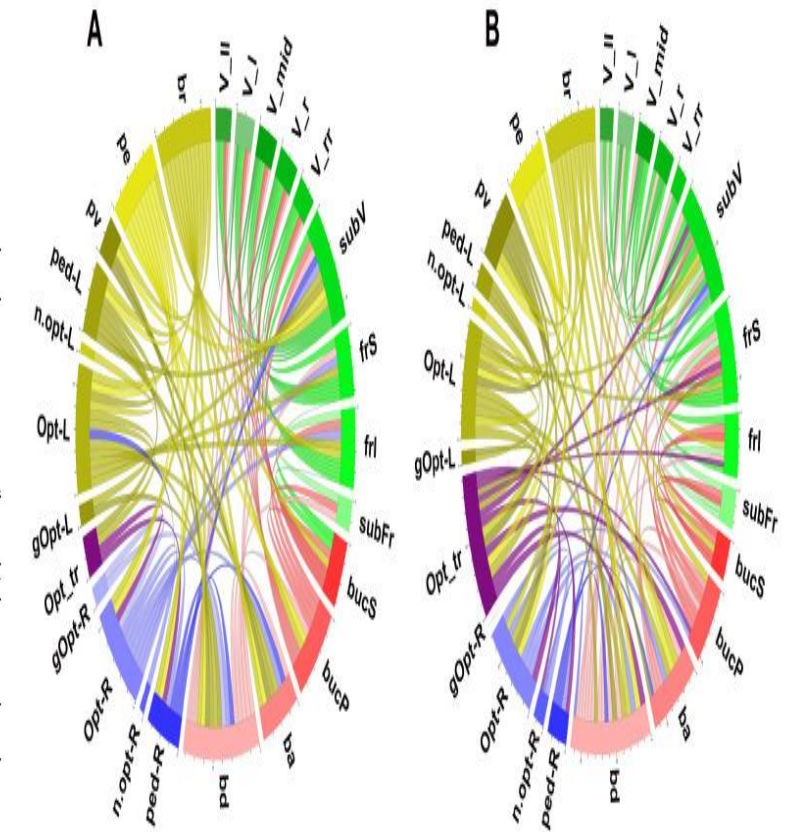
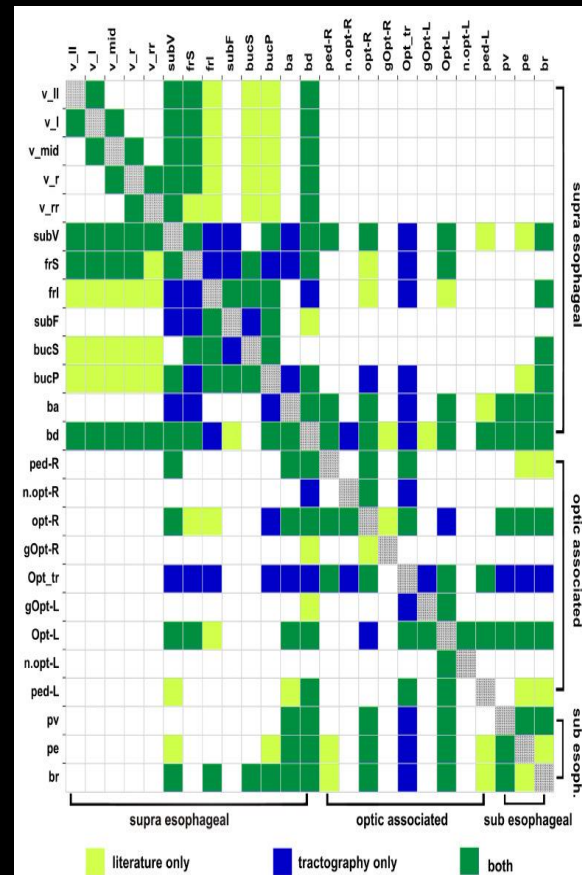


WHAT BIOMEDICAL  
DEVICES HAVE BEEN  
CONSTRUCTED AFTER  
ANIMAL MODELING?



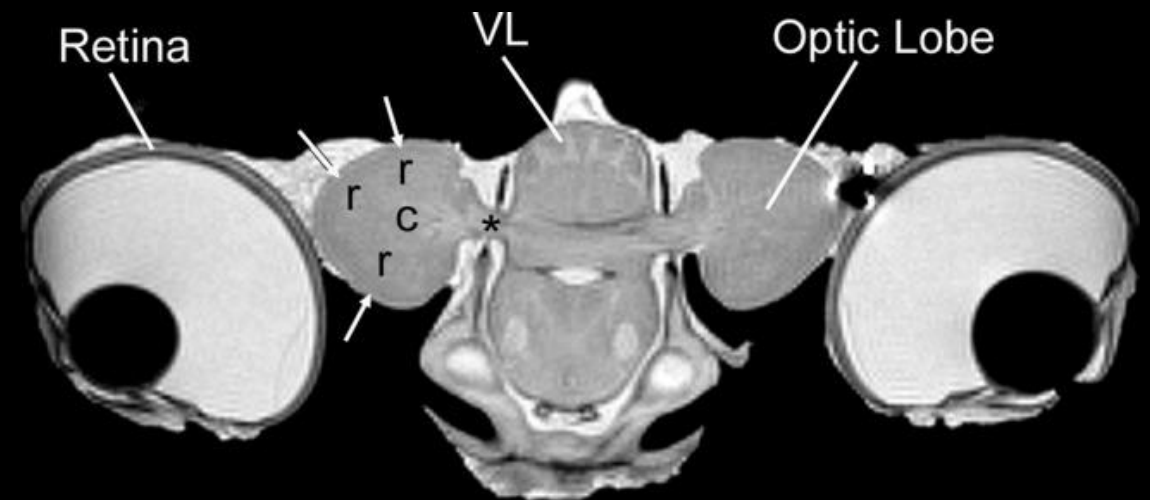
# NEUROSCIENCE

- Imaging
- Functional/structural
- Non-Myelinated
- Genomics
- Octopuses = Monkey rights



# OCTOPUS VISUAL SYSTEM: A FUNCTIONAL MRI MODEL FOR DETECTING NEURONAL ELECTRIC CURRENTS WITHOUT A BLOOD-OXYGEN-LEVEL-DEPENDENT CONFOUND

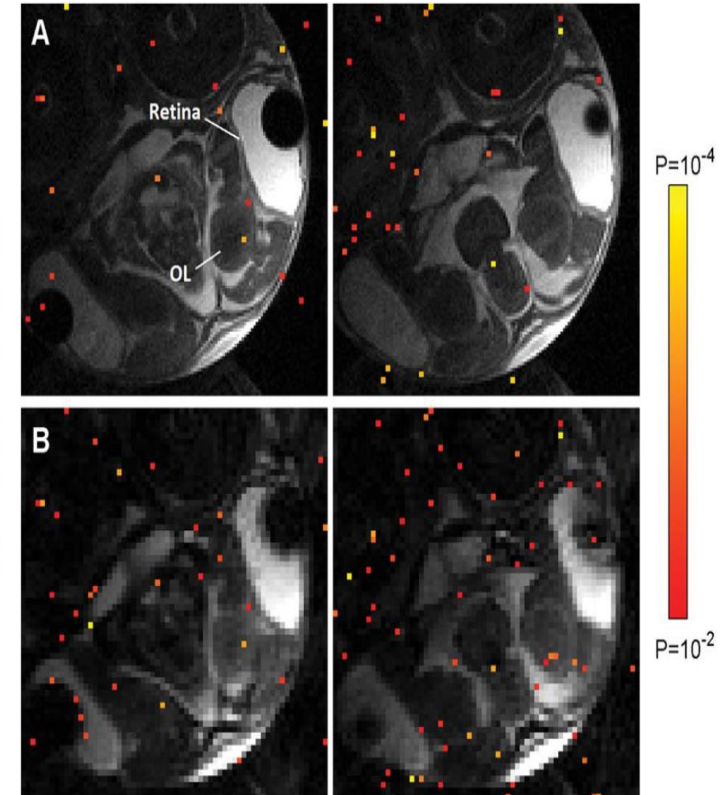
- 50 g and 110 g female
- White LED pulses
- Optic nerve and OL removed
- Single shot GE and EPI
- FOV = 2 x 2cm<sup>2</sup>, matrix size = 64 x 64 (in-plane resolution = 0.31 x 0.31 mm<sup>2</sup>), slice thickness = 1 mm, TR = 1 s and flip angle = 70 degrees (Ernst angle)
- T-test with GLM



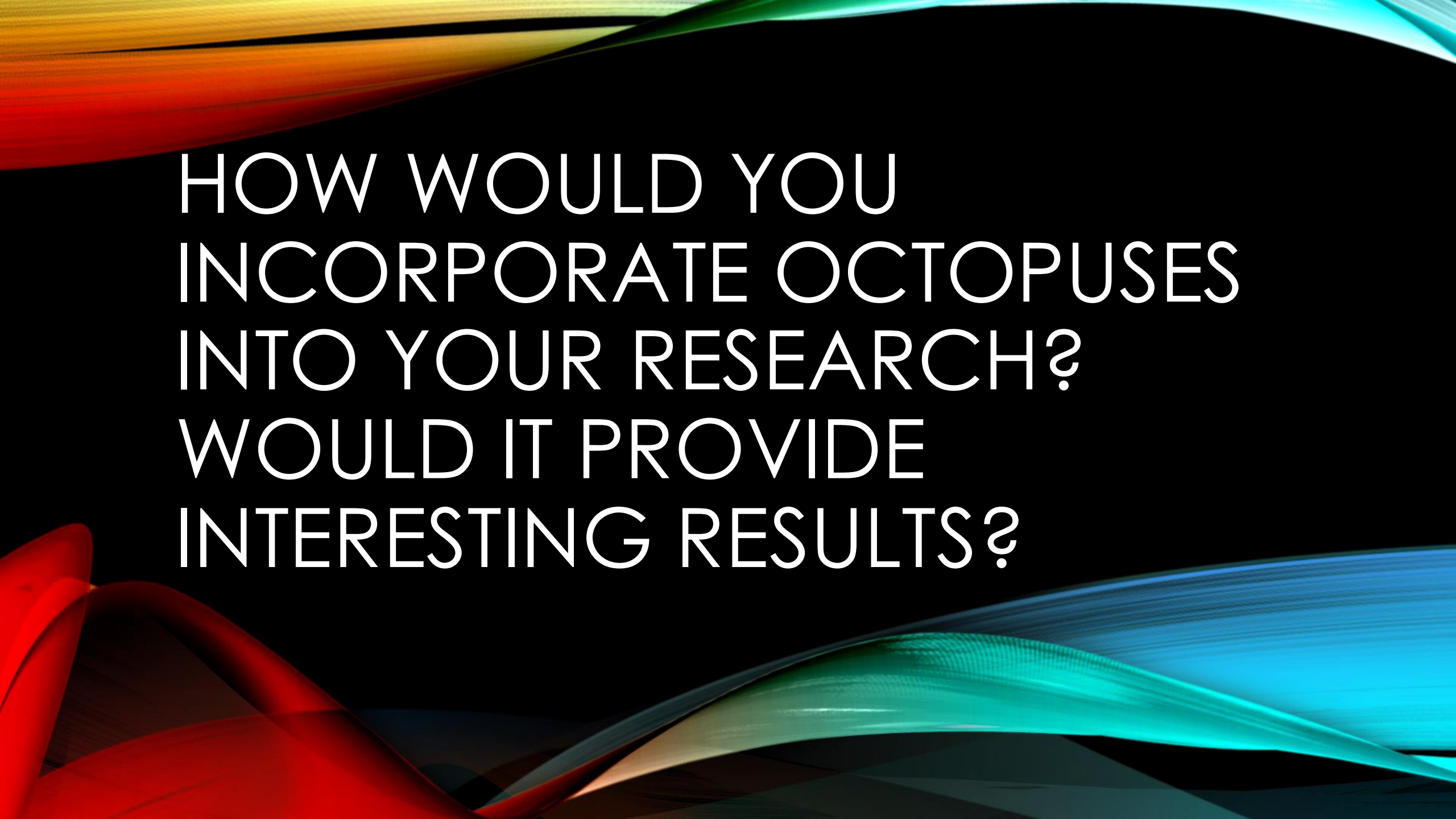
# OCTOPUS MRI RESULTS

- Monte Carlo cluster sizes
- findings (10,11,13,17), hemodynamic.
- RF coil few cm
- Dipole voltage gated ions
- “More sensitive superconducting quantum interference devices”

FIG. 5. **A:** RARE images from an in vivo nc-MRI scan. The color map shows the statistical test results using the GLM thresholded at the  $P < 0.01$  (uncorrected) level. **B:** EPI images for the nc-MRI scans of the two corresponding slices. The color maps show the statistical test results from the permutation test, thresholded at the  $P < 0.01$  (uncorrected) level. The acquisition windows of the first and second slices corresponded to the peak activity in the retina and the OL, respectively (see Fig. 2C and D). The  $B_0$  field was perpendicular to the slices and hence also perpendicular to the photoreceptor cells in the retina.

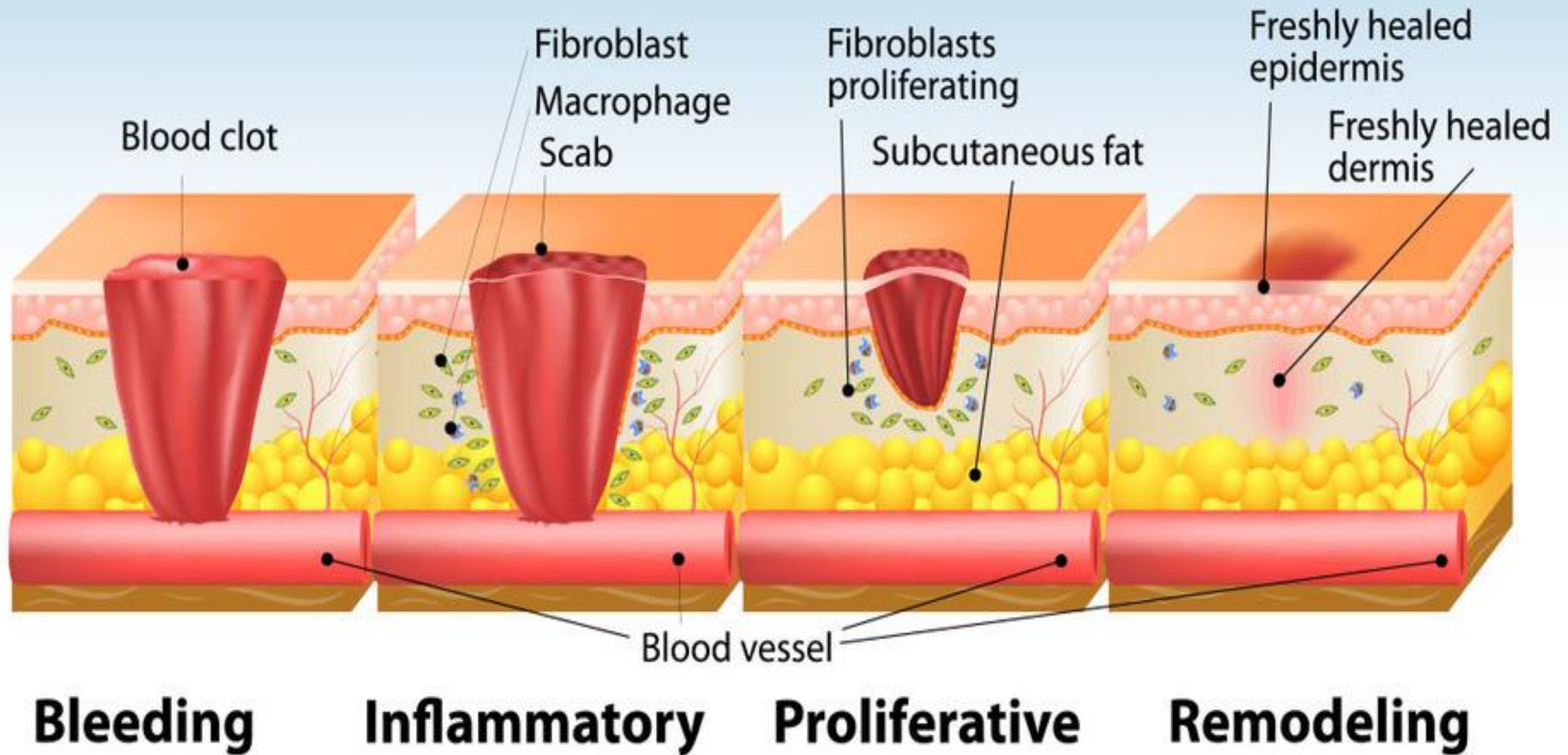






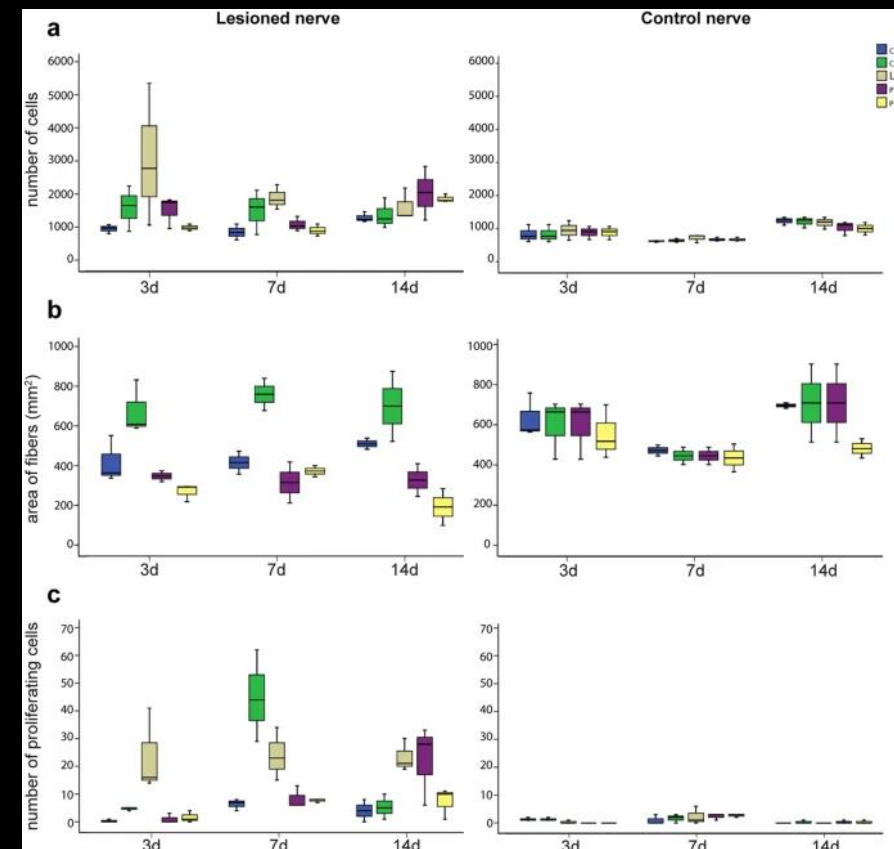
HOW WOULD YOU  
INCORPORATE OCTOPUSES  
INTO YOUR RESEARCH?  
WOULD IT PROVIDE  
INTERESTING RESULTS?

# Stages of Wound Healing



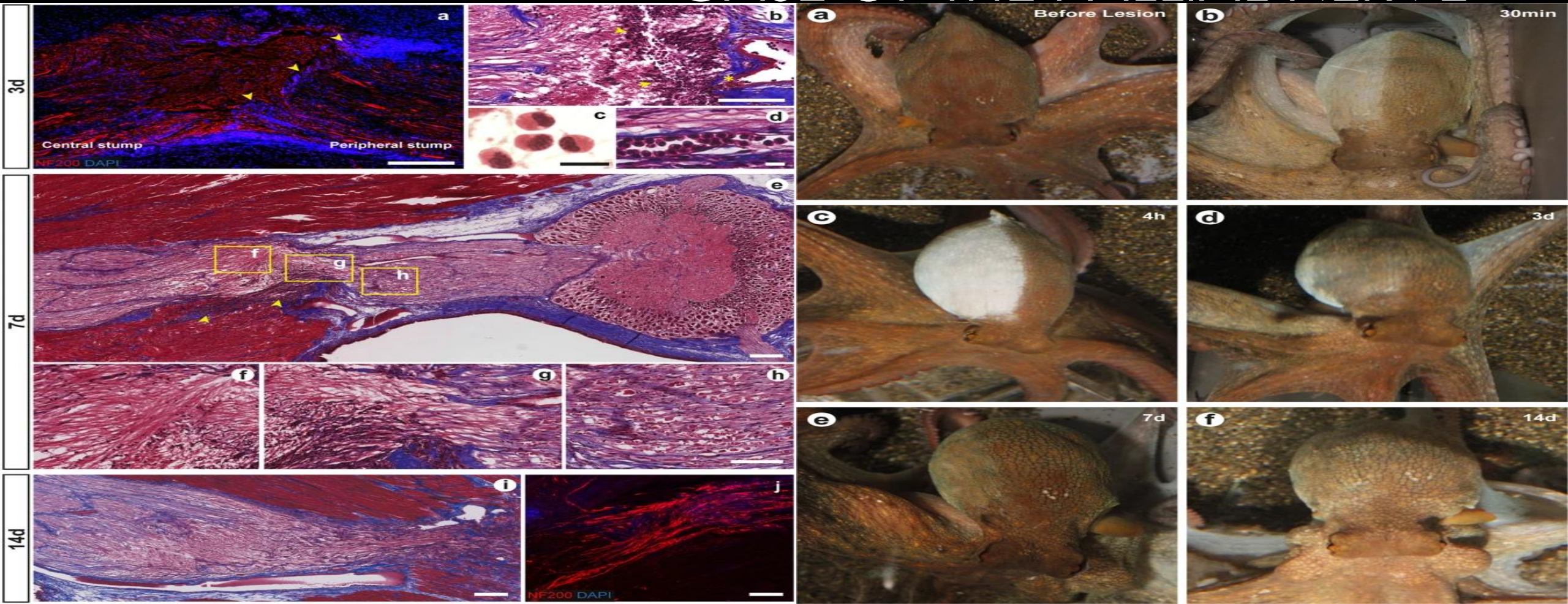
# REGENERATIVE MEDICINE

- Regenerates “cornea, peripheral nerves and neural pathways within the central nervous system”
- Lesions in octopuses (12 male, 5 female), 1800 cells per stack
- 60 seconds predatory behavior
- 1-2 days later brown pattern
- 3-5 days later full recovery





# NERVE DEGENERATION AND REGENERATION IN THE CEPHALOPOD MOLLUSK OCTOPUS VULGARIS: THE CASE OF THE PALLIAL NERVE







WHEN WERE OCTOPUSES  
GRANTED THE SAME RIGHTS  
AS PRIMATES?