

Region Proposal Network and Faster R-CNN

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MLBBQ



Outline

Fundamentals

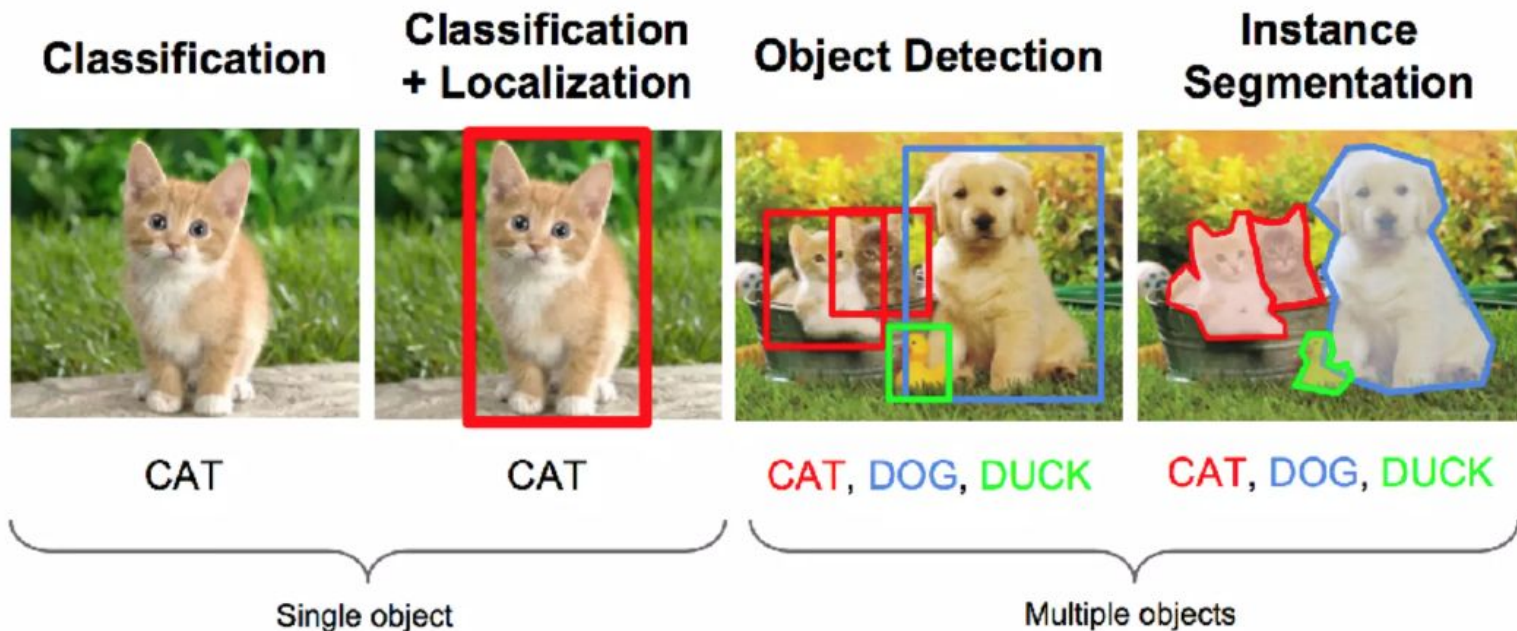
- Computer vision tasks
- Localization + Regression
- Intersection Over Union

R-CNNs family's

- R-CNN
- Fast R-CNN
- Faster R-CNN

Introduction

Computer Vision Tasks



Classification + Localization: Task

Classification: C classes

Input: Image

Output: Class label

Evaluation metric: Accuracy



→ CAT

Localization:

Input: Image

Output: Box in the image (x, y, w, h)

Evaluation metric: Intersection over Union

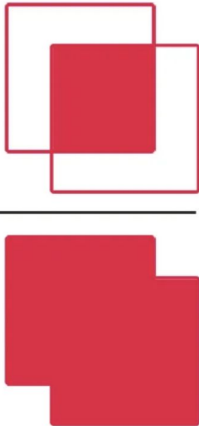


→ (x, y, w, h)

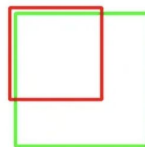
Classification + Localization: Do both



Accuracy of the predicted bounding boxes with **Intersection Over Union (IoU)**

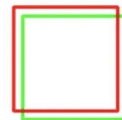
$$\text{IoU} = \frac{\text{Area of Overlap}}{\text{Area of Union}}$$


IoU: 0.4034



Poor

IoU: 0.7330



Good

IoU: 0.9264



Excellent



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- Classification + Localization

R-CNNs

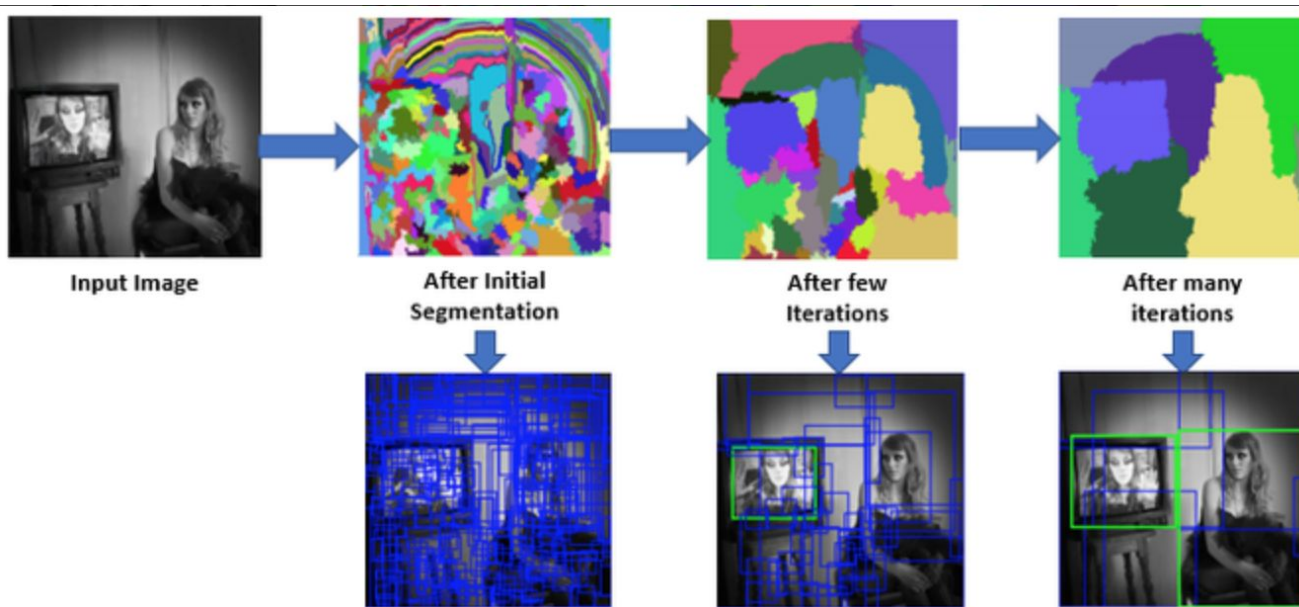
- R-CNN
- Fast R-CNN
- Faster R-CNN

Conclusion

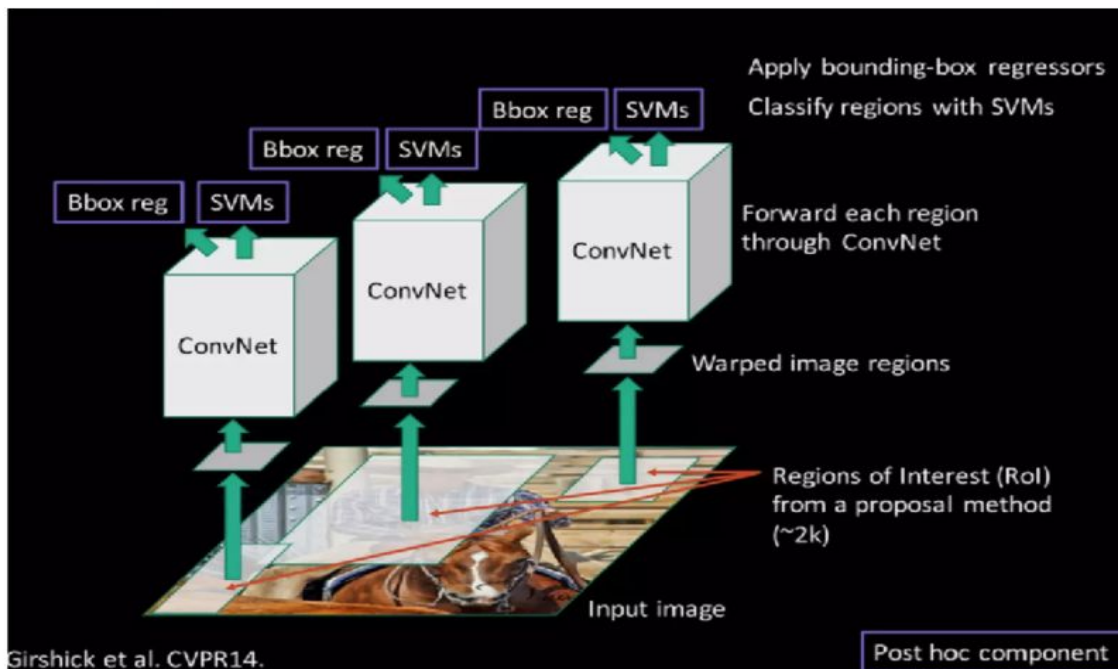


R-CNN

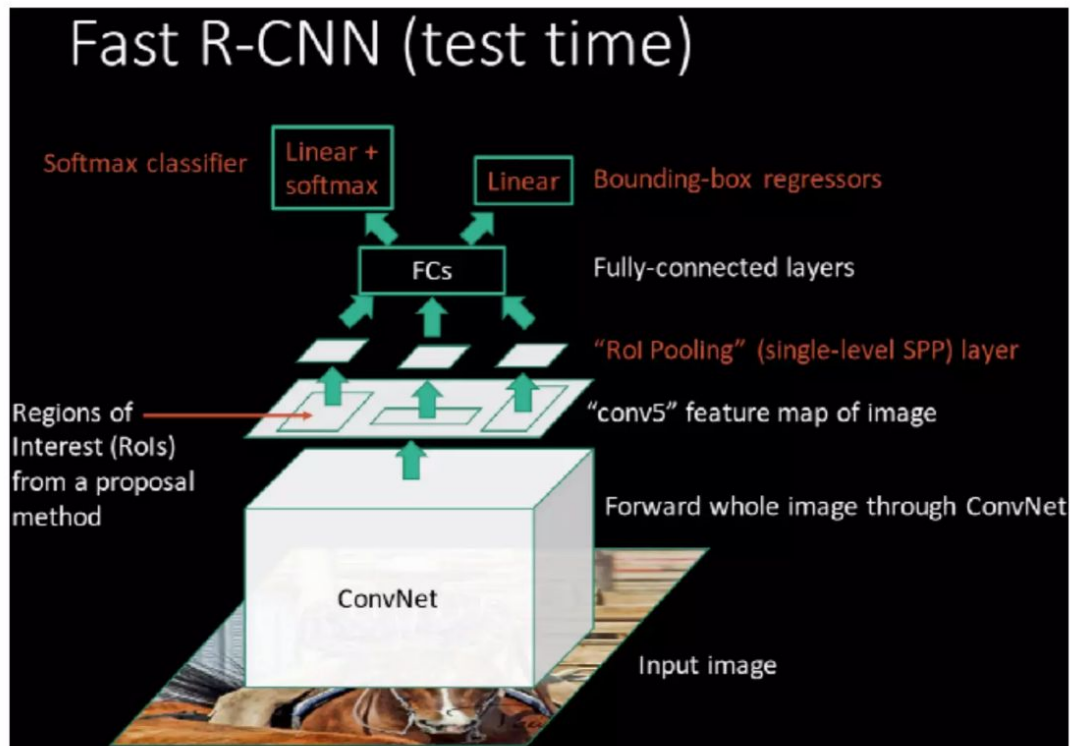
Selective search:



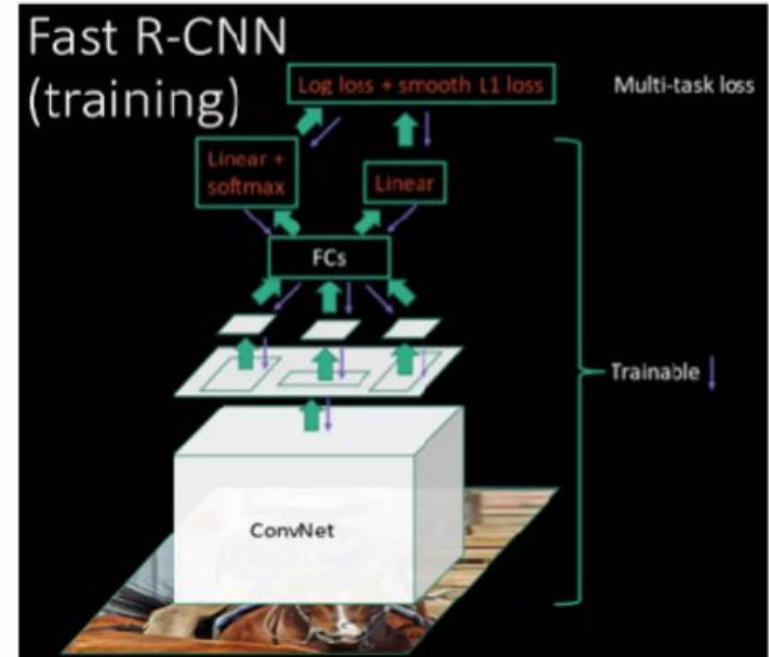
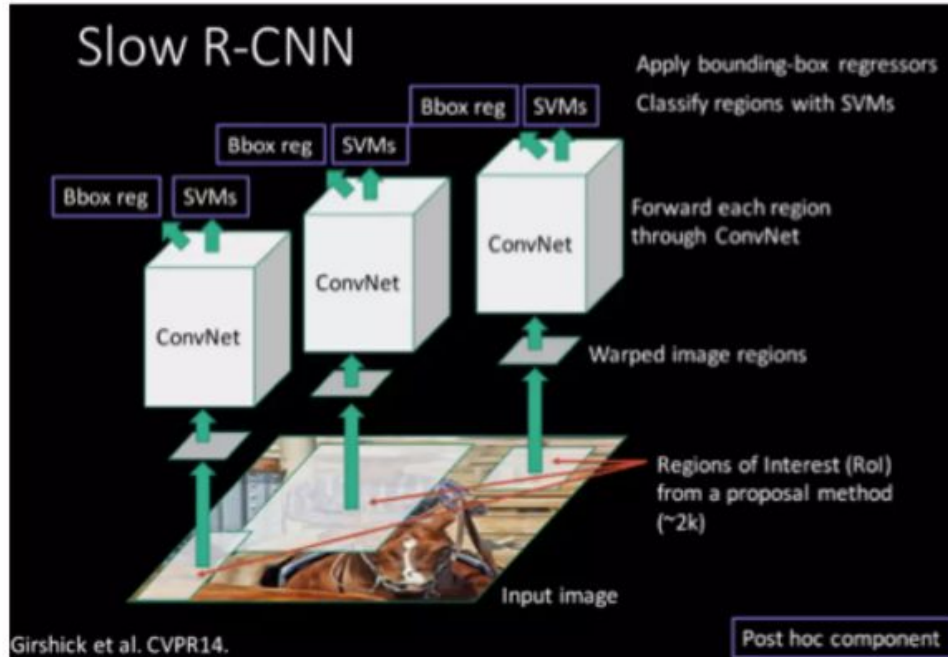
R-CNN architecture



Fast R-CNN architecture



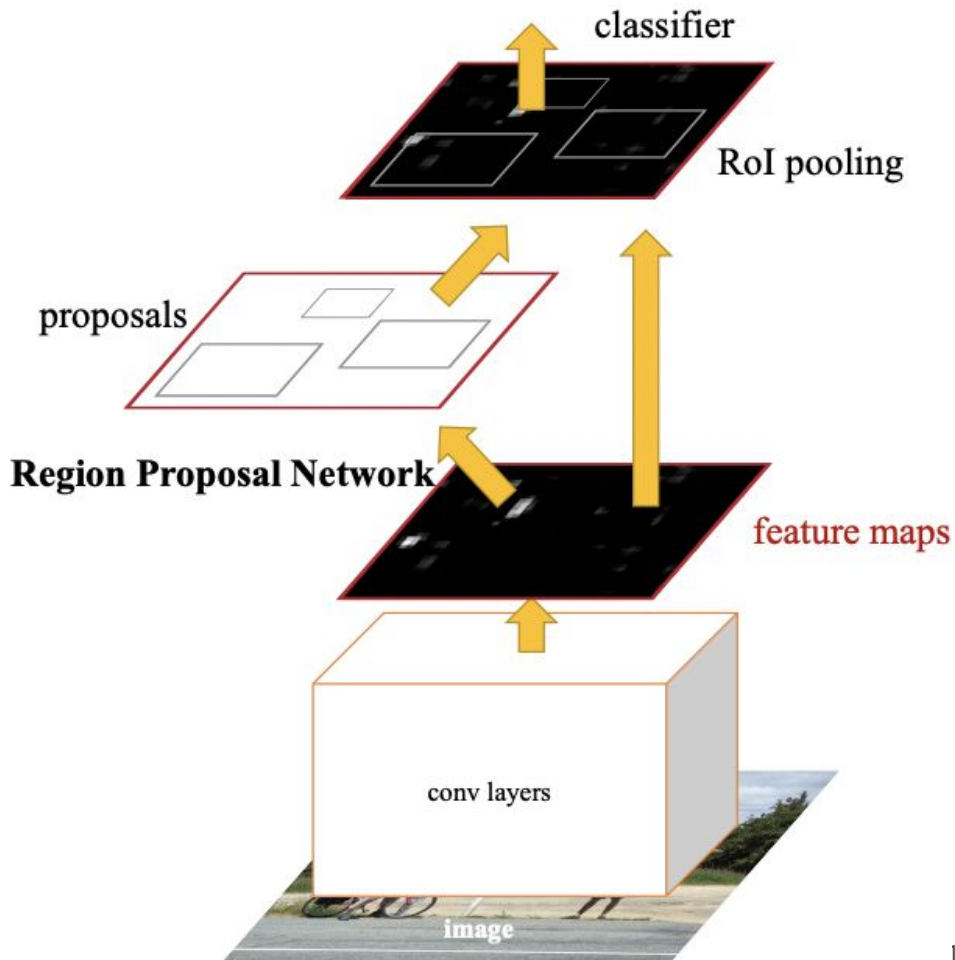
Architecture comparison between R-CNN and Fast R-CNN

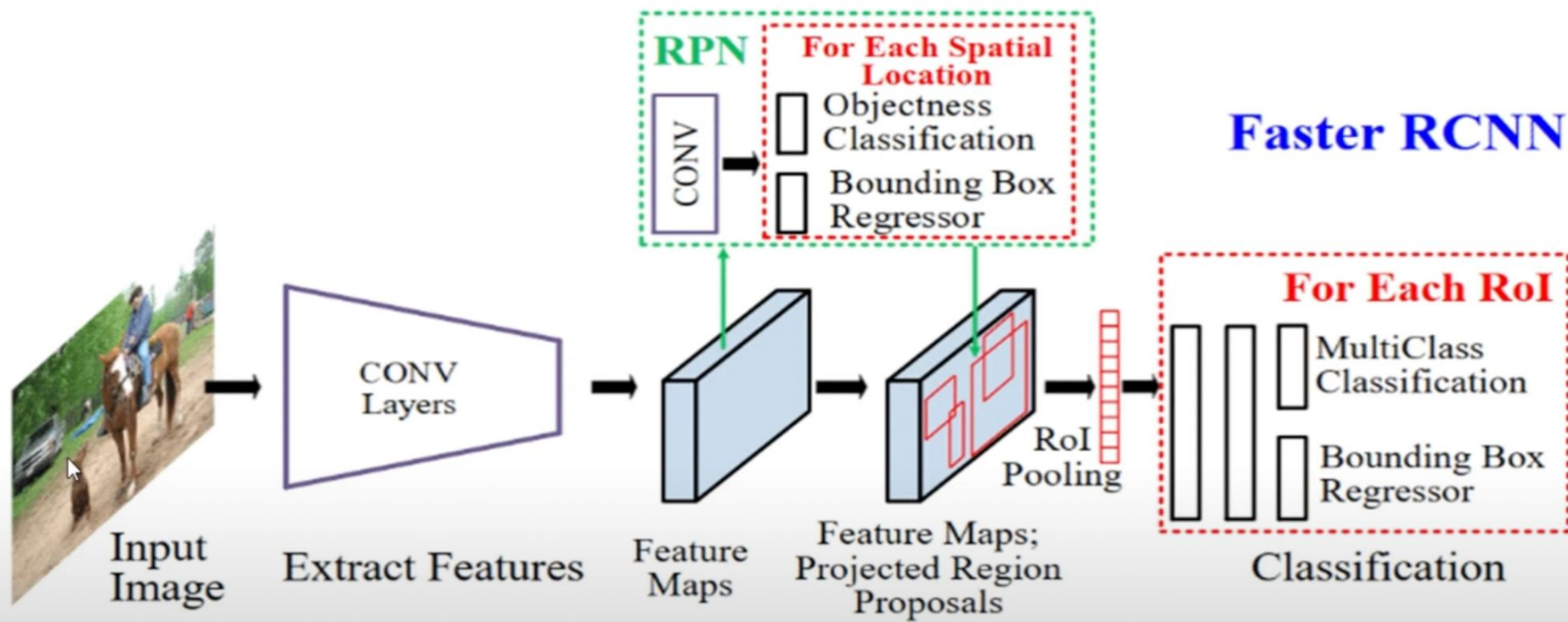




Faster R-CNN

Faster R-CNN=PRN+Fast R-CNN

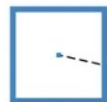






Anchor boxes

Generate 15 anchor boxes for each position



Feature Map

Scale 1

Scale 2

Scale 3

...

1:1



1:2



...

2:1



Anchor Boxes



Loss function

$$L(p_i, t_i) = \underbrace{\frac{1}{N_{cls}} \sum_i L_{cls}(p_i, p_i^*)}_{\text{object/not object classifier}} + \lambda \underbrace{\frac{1}{N_{reg}} \sum_i p_i^* L_{reg}(t_i, t_i^*)}_{\text{box regressor}}$$

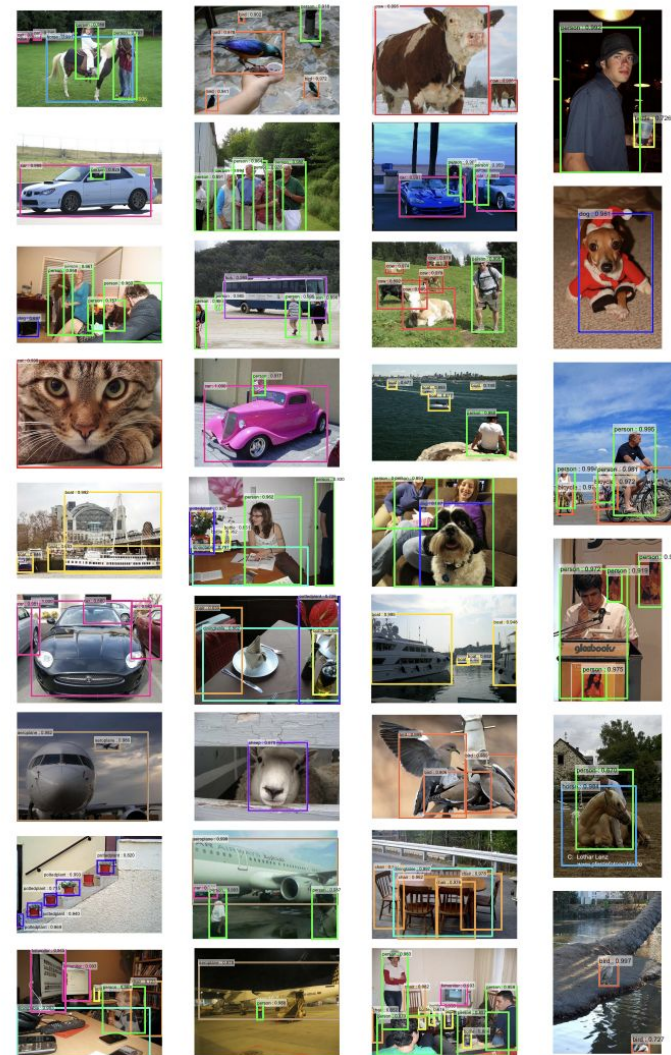


Faster R-CNN: Results

	R-CNN	Fast R-CNN	Faster R-CNN
Test time per image (with proposals)	50 seconds	2 seconds	0.2 seconds
(Speedup)	1x	25x	250x
mAP (VOC 2007)	66.0	66.9	66.9

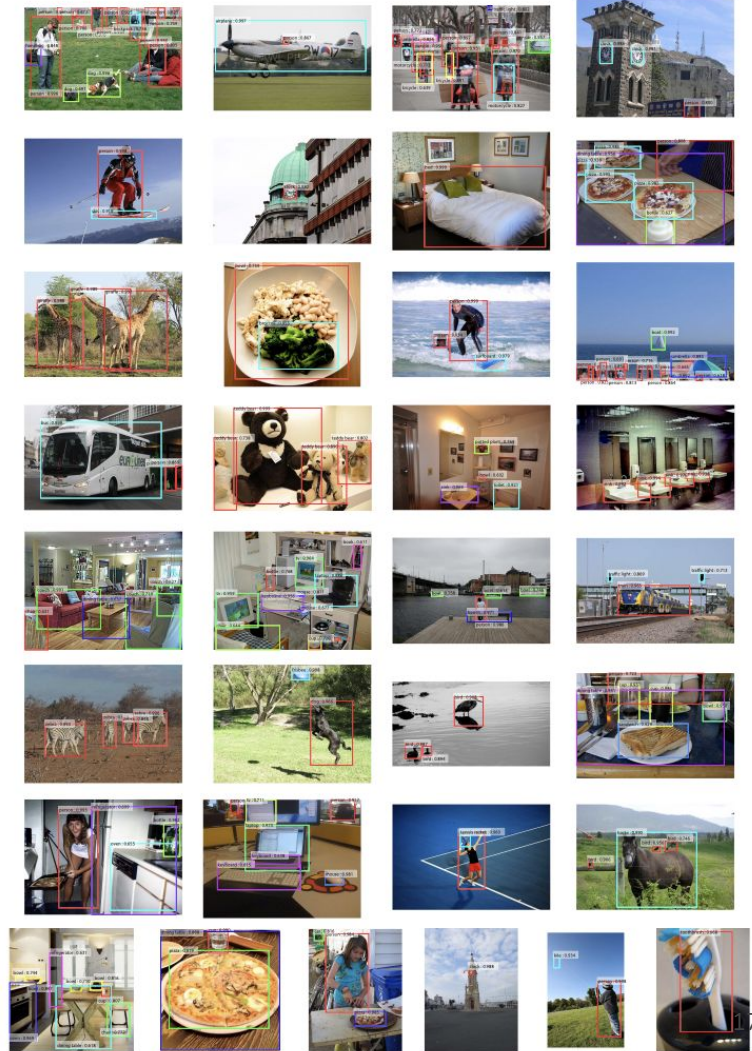
Object detection results on the PASCAL VOC 2007 test set using the Faster R-CNN system

- Selected examples of object detection results on the PASCAL VOC 2007 test set using the Faster R-CNN system. The model is VGG-16.



Object detection results on the MS COCO test-dev set using the Faster R-CNN

- Selected examples of object detection results on the MS COCO test-dev set using the Faster R-CNN system. The model is VGG-16 and the training data is COCO trainval.





References:

1. Ren, S., He, K., Girshick, R., & Sun, J. (2015). Faster r-cnn: Towards real-time object detection with region proposal networks. Advances in neural information processing systems, 28.
2. Girshick, R. (2015). Fast r-cnn. In Proceedings of the IEEE international conference on computer vision (pp. 1440-1448).
3. http://cs231n.stanford.edu/slides/2016/winter1516_lecture8.pdf