

# PowerSGD: Practical Low-Rank Gradient Compression for Distributed Optimization

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# Why distributed SGD?

## Why Distributed?

- Data Privacy
- Resource Distribution
- Data Distribution

## Why dSGD?

- Gradients are Linear
- Gradients are Optimal
- Are gradients the smallest statistic?



$$\sum_{s=1}^S \nabla_{\mathbf{w}} \mathcal{L}^{(s)} = \nabla_{\mathbf{w}} \mathcal{L}$$

# Reducing Bandwidth

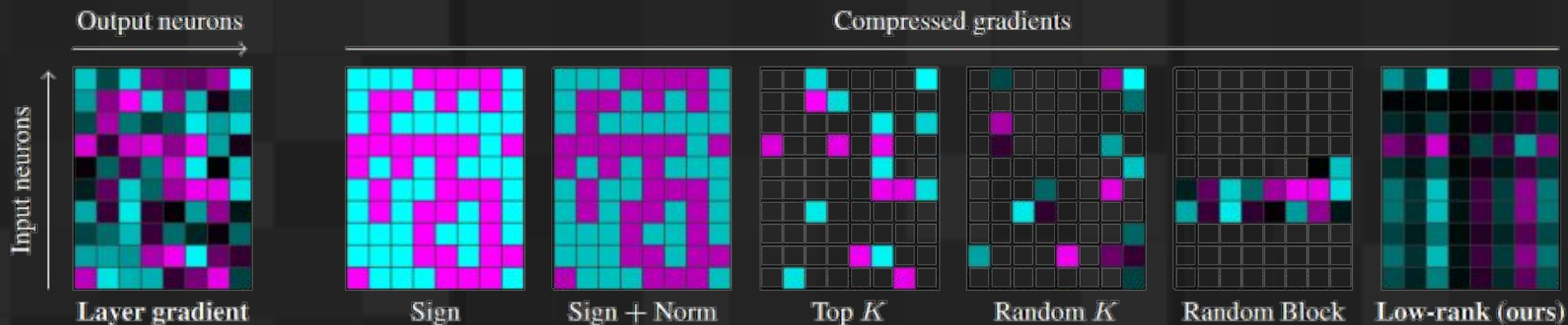


Figure 1: Compression schemes compared in this paper. Left: Interpretation of a layer's gradient as a matrix. Coordinate values are color coded (positive, negative). Right: The output of various compression schemes on the same input. Implementation details are in Appendix G.

# Low-Rank Decompositions

$$C_k = U \Sigma_k V^T$$

The diagram illustrates the low-rank decomposition  $C_k = U \Sigma_k V^T$ . Each matrix is represented by a 50x50 grid of dots. Dashed boxes indicate the matrix entries affected by "zeroing out" the smallest singular values. For  $C_k$ , the dashed box is at the bottom-left corner, labeled  $(50,50)$ . For  $U$ , the dashed box is at the bottom-left corner, labeled  $(30,50)$ . For  $\Sigma_k$ , the dashed box is at the bottom-left corner, labeled  $(50,30)$ . For  $V^T$ , the dashed box is at the bottom-left corner, labeled  $(50,50)$ .

► **Figure 18.2** Illustration of low rank approximation using the singular-value decomposition. The dashed boxes indicate the matrix entries affected by “zeroing out” the smallest singular values.

# Power Iterations

## Algorithm

- initial approximation - random unit vector  $x_0$
- $x_1 = Ax_0$
- $x_2 = AAx_0 = A^2x_0$
- $x_3 = AAAx_0 = A^3x_0$
- ...
- until converges

For large powers of  $k$ , we will obtain a good approximation of the dominant eigenvector

## Power Iterations (contd.)

We can just remove the dominant direction from the matrix and repeat

So:

- $A = Q\Lambda Q^T$ , so  $A = \sum_{i=1}^n \lambda_i \mathbf{q}_i \mathbf{q}_i^T$
- use power iteration to find  $\mathbf{q}_1$  and  $\lambda_1$
- then let  $A_2 \leftarrow A - \lambda_1 \mathbf{q}_1 \mathbf{q}_1^T$
- repeat power iteration on  $A_2$  to find  $\mathbf{q}_2$  and  $\lambda_2$
- continue like this for  $\lambda_3, \dots, \lambda_n$

# QR Decomposition

$$\begin{array}{c} \mathbf{A} \\ \left[ \begin{array}{c|c|c} | & | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 \\ | & | & | \end{array} \right] \end{array} = \begin{array}{c} \mathbf{Q} \\ \left[ \begin{array}{c|c|c} | & | & | \\ \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ | & | & | \end{array} \right] \end{array} \begin{array}{c} \mathbf{R} \\ \left[ \begin{array}{ccc} \mathbf{e}_1^T \cdot \mathbf{a}_1 & \mathbf{e}_1^T \cdot \mathbf{a}_2 & \mathbf{e}_1^T \cdot \mathbf{a}_3 \\ \mathbf{0} & \mathbf{e}_2^T \cdot \mathbf{a}_2 & \mathbf{e}_2^T \cdot \mathbf{a}_3 \\ \mathbf{0} & \mathbf{0} & \mathbf{e}_3^T \cdot \mathbf{a}_3 \end{array} \right] \end{array}$$

orthogonal unit vector      upper diagonal matrix

## QR Decomposition

### Algorithm:

- choose  $Q_0$  such that  $Q_0^T Q_0 = I$
- for  $k = 1, 2, \dots$ :
  - $Z_k = A Q_{k-1}$
  - $Q_k R_k = Z_k$  (QR decomposition)



# PowerSGD

**function** COMPRESS+AGGREGATE(update matrix  $M \in \mathbb{R}^{n \times m}$ , previous  $Q \in \mathbb{R}^{m \times r}$ )

$P \leftarrow MQ$

$P \leftarrow \text{ALL REDUCE MEAN}(P)$

$\hat{P} \leftarrow \text{ORTHOGONALIZE}(P)$

$Q \leftarrow M^\top \hat{P}$

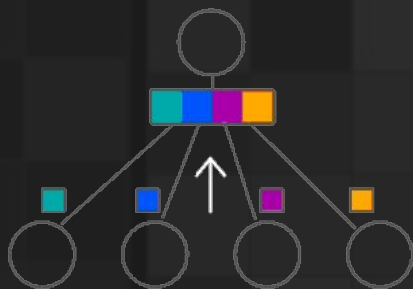
$Q \leftarrow \text{ALL REDUCE MEAN}(Q)$

**return** the compressed representation  $(\hat{P}, Q)$ .

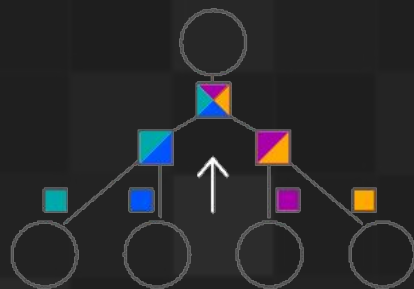
▷ Now,  $P = \frac{1}{W}(M_1 + \dots + M_W)Q$

▷ Orthonormal columns

▷ Now,  $Q = \frac{1}{W}(M_1 + \dots + M_W)^\top \hat{P}$



(a) Gather



(b) Reduce

# PowerSGD + Error Feedback

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**Algorithm 2** Distributed Error-feedback SGD with Momentum

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1: hyperparameters: learning rate  $\gamma$ , momentum parameter  $\lambda$ 
2: initialize model parameters  $\mathbf{x} \in \mathbb{R}^d$ , momentum  $\mathbf{m} \leftarrow \mathbf{0} \in \mathbb{R}^d$ , replicated across workers
3: at each worker  $w = 1, \dots, W$  do
4:   initialize memory  $\mathbf{e}_w \leftarrow \mathbf{0} \in \mathbb{R}^d$ 
5:   for each iterate  $t = 0, \dots$  do
6:     Compute a stochastic gradient  $\mathbf{g}_w \in \mathbb{R}^d$ .
7:      $\Delta_w \leftarrow \mathbf{g}_w + \mathbf{e}_w$  ▷ Incorporate error-feedback into update
8:      $\mathcal{C}(\Delta_w) \leftarrow \text{COMPRESS}(\Delta_w)$ 
9:      $\mathbf{e}_w \leftarrow \Delta_w - \text{DECOMPRESS}(\mathcal{C}(\Delta_w))$  ▷ Memorize local errors
10:     $\mathcal{C}(\Delta) \leftarrow \text{AGGREGATE}(\mathcal{C}(\Delta_1), \dots, \mathcal{C}(\Delta_W))$  ▷ Exchange gradients
11:     $\Delta' \leftarrow \text{DECOMPRESS}(\mathcal{C}(\Delta))$  ▷ Reconstruct an update  $\in \mathbb{R}^d$ 
12:     $\mathbf{m} \leftarrow \lambda \mathbf{m} + \Delta'$ 
13:     $\mathbf{x} \leftarrow \mathbf{x} - \gamma (\Delta' + \mathbf{m})$ 
14:   end for
15: end at
```

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# Results

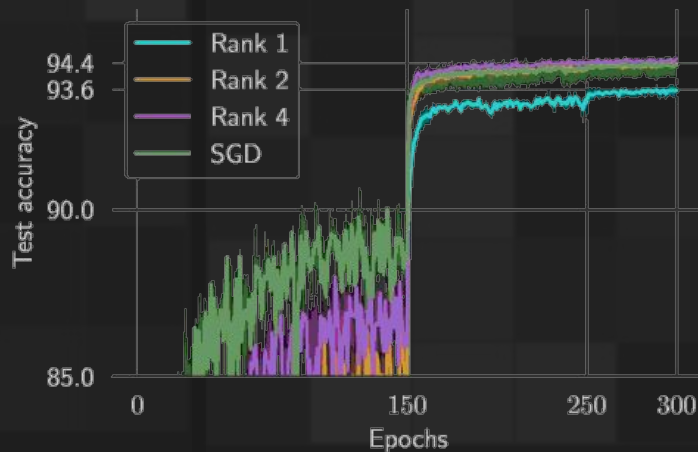
Image classification on CIFAR10



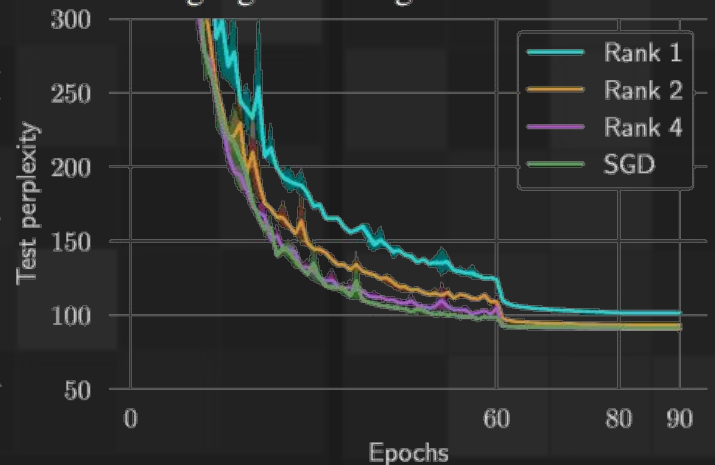
Language modeling with WIKITEXT-2



Image classification on CIFAR10



Language modeling with WIKITEXT-2



# Our Approach

- Use AD statistics instead of gradients for automatic bandwidth reduction
- Further use structured power iterations

