

Overview of Demo



(see Demo_Instructions.doc for further detail)

Given:

Clear and easily labeled training/validation sets to tune a model for a CV classification task (classes=ship, plane, empty seabed)

Training/Validation Data (80/20 random split)

- 239 Large Ships (military, logistic, etc)
- 38 Planes (single-engine, multi-engine, military, etc)
- 378 Empty Seabed/Seafloor images (no manmade objects in FOV)

Datasets:

1. Seabed_Objects_Demo/unbalanced_training_validation_set
2. Seabed_Objects_Demo/balanced_training_validation_set

Implement MLOps concepts and capabilities:

Continue the ML lifecycle and update

Addresses some/all of the following:

- Model management, version tracking, storage, CI/CD
- OOD and data drift detection
- Experiment tracking, hyperparameter search metadata/results
- Management of data provenance and quality

Train and Validate a model:

Achieve a nominal, acceptable level of performance (>95% e.g.)

Problems to address

- Imbalanced dataset, model bias
- Tuning
- Automated/User-friendly data pipeline
- Clear performance metrics

Assess model under test conditions

Possible issues that arise:

- Unacceptable performance degradation
- Incongruous data
- The need to retrain the model
- Contested/degraded operations

Initial test set results included in DIU_AMMO_Demo.ipynb notebook with saliency maps and T-SNE plots

Enter a "new environment":

Ingest test data and assess model

Test Data

- 138 Small or Limited-detail Ships
- 24 Fractured or Limited-detail Planes
- 199 New Empty Seabed/Seafloor images

Two trained and validated models and a PyTorch notebook

1. unbalanced_model.pth
2. balanced_model.pth
3. DIU_AMMO_Demo.ipynb

Test set:
Seabed_Objects_Demo/test_set