Arduino	RPi
Start	Start.
[Waits for initialize command from RPi of predetermined form.	[Opens serial and sends command string
Continuously regulates motor speeds @ values currently holding @ unknown rate	Sends commands to Arduino as fast or slow as it wants
reports speeds to RPi w/ time stamps. at rate specified @ Start Command.	thread dedicated to catching these messages and running dead reckoning @ each update.
	At rate it sends commands to Arduino, updates its desired motor speeds: abs → Local frame