1.a) - load in the colour image

-create a second, grayscale copy -convert both of these images to doubles.

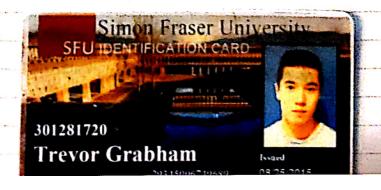
on the grayscale image, use canny edge detection to create a binary image of the edges - dilate the binary image

- use an array of 3 of the dilated binary images as a mask on the original image and set all of those values to zero.

- the original image should now look like this

We need to convert the original image to a second grayscale copy to use canny edge detection properly. We dilate the image to get the wide strong edges. We use an array of 3 of the dilated binary images so that we change all of the RGB values not just one.

- 1. b) Adjusting the algorithm to ensure that the binary mask that we use is changing all three of the RGB channels should fix the green patches
- 1.c) To create the output map of the noise, we would use a modified version of a median filter to move the centre pixel to the output array iff it is an outlier with respect to the local window.



for the child

for the tree

$$y=3m$$
 $y'=\frac{1}{2}*d$
 $z=8m$ $z=3/8*4000x$ $z=15000x$

Y'tree =
$$\frac{3}{(2 \text{kid} + 4)} \times d = 2 \text{y'kid}$$

= $2(\text{ykid}/2 \text{kid} \times d)$
= $2(\text{ykid}/2 \text{kid} \times d)$
= $2(\text{ykid} \times d)$
= $2(\text{ykid} \times d)$

$$3z_{kid} = 2z_{kid} + 8$$

$$(z_{kid} = 8m) \qquad (z_{2} \text{ should be 4m away} \\ from c_{1}$$

2. C)
$$y' kid = y'kid / \neq kid * d$$

$$100px = 8 * d$$

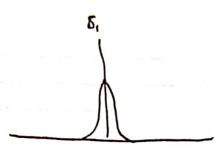
$$800px = d$$

$$5 = 400px$$

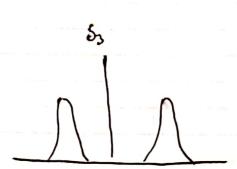
$$d = 25$$



3.0)

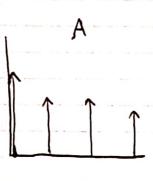


5₂

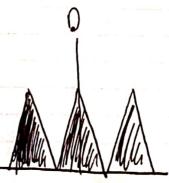


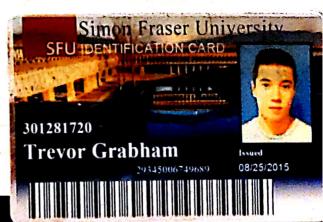
3. b) convolution in the spatial domain is equivalent to multiplication in the frequency domain and vice versa.

3. ()



3





our sampling rate like we did in graph C, or we use a low pass filter.

