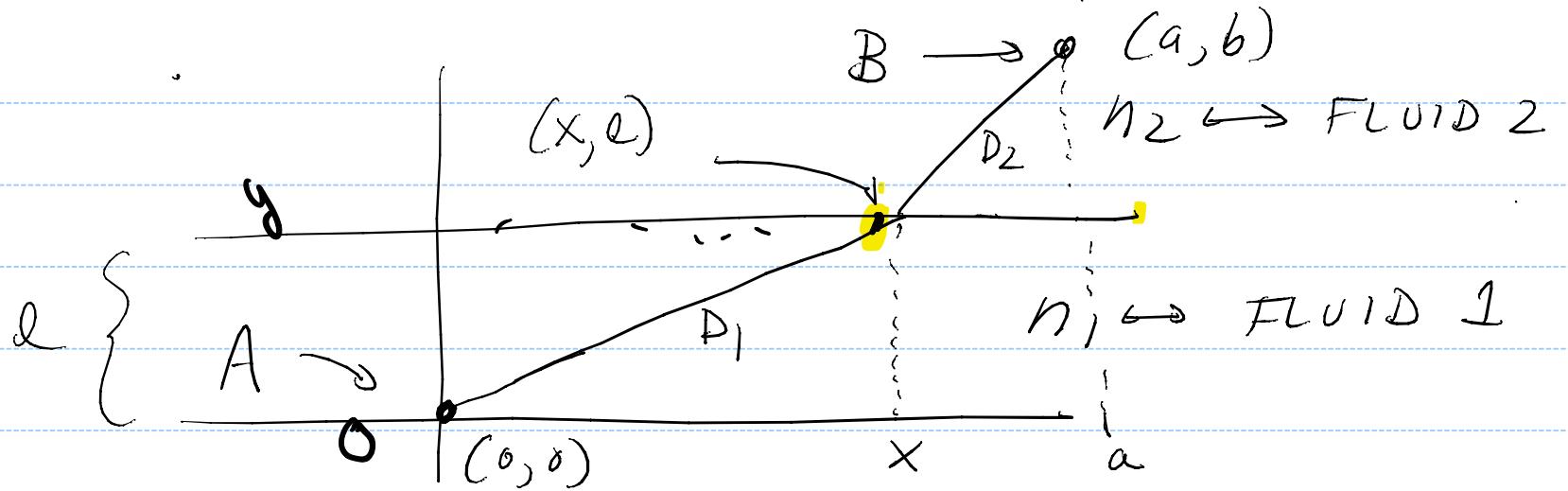


(1)

EX 1



LIGHT PATHS - GEOMETRIC OPTICS

SUPPOSE WE HAVE A TWO-LEVEL FLUID SYSTEM.

FROM FERMAT'S OBSERVATIONS OF LIGHT PATHS,
HE POSTULATED THAT



!"#\$

TIME OF TRAVEL IN HOMOGENEOUS FLUID

$$\textcircled{1} \quad T = \frac{\text{DISTANCE}}{\text{VELOCITY}} = \frac{D}{V}; \quad (\text{STRAIGHT LINE})$$

V IS A CHARACTERISTIC OF THE FLUID;

$$n = \frac{1}{V} = \text{INDEX OF REFRACTION}; \quad T = Dn$$

\textcircled{2} PATH IN TWO-LEVEL SYSTEM IS

PIECE-WISE LINEAR, SUCH THAT TIME OF TRAVEL IS MINIMIZED:

FERMAT

$$T = n_1 \sqrt{x^2 + l^2} + n_2 \sqrt{(a-x)^2 + (b-l)^2}$$

$$= n_1 D_1 + n_2 D_2$$

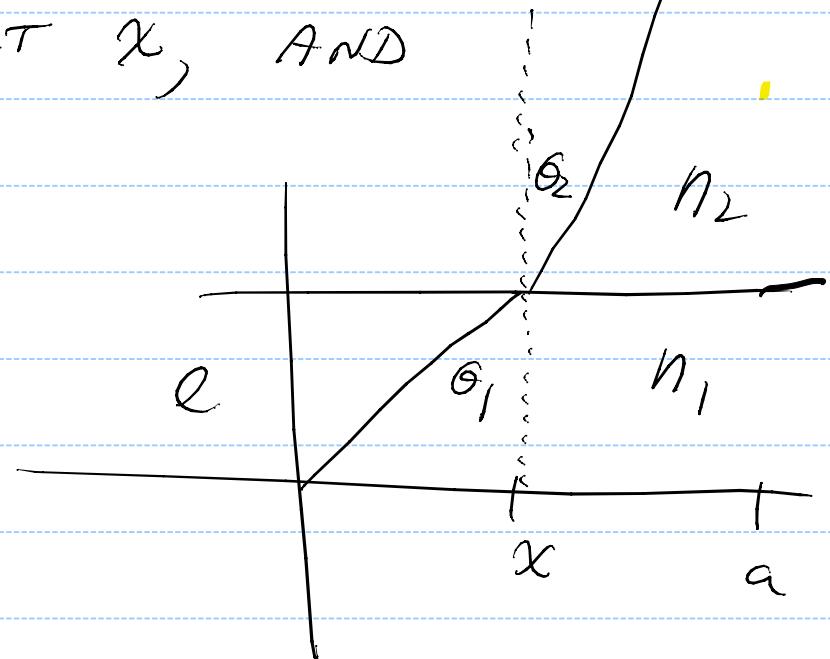
(a, b)

EXERCISE! MINIMIZE THIS WRT X, AND

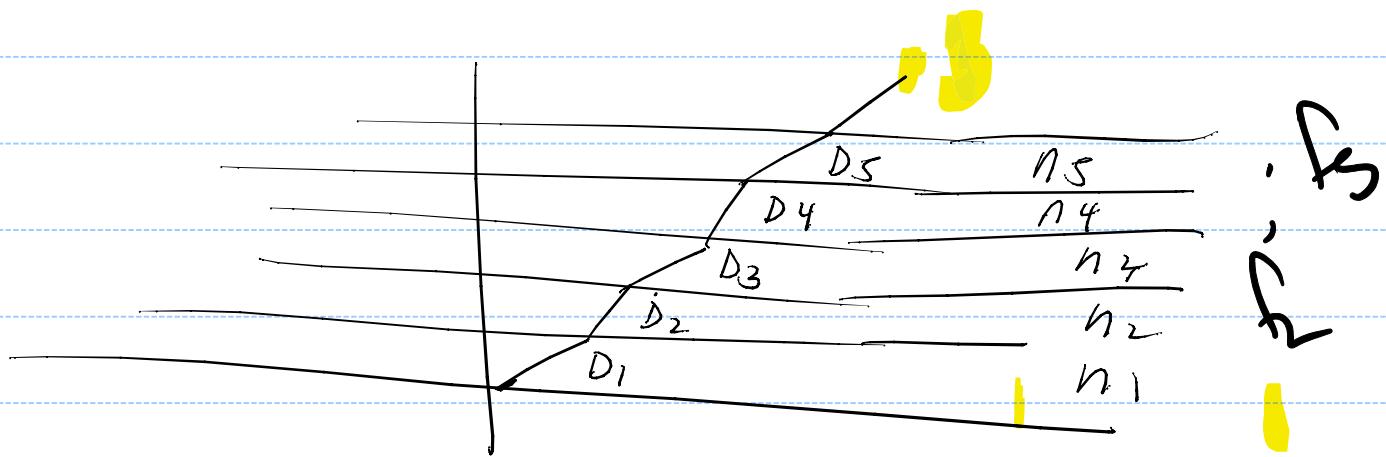
OBTAIN THE CONDITION

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

SNELL'S LAW.



CAN EXTEND THIS TO MULTI-LEVEL SYSTEM



$$T = \sum D_i n_i$$

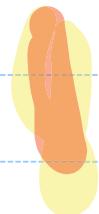
IN THE LIMIT OF A CONTINUOUSLY CHANGING

INDEX OF REFRACTION :

$$T = T(y(x)) = \int_a^b n(y(x)) \sqrt{1 + y'(x)^2} dx$$

WE SEEK $y(x)$ SO THAT T IS AS SMALL AS POSSIBLE
(FERMAT'S PRINCIPLE OF LEAST TIME)

NOTE 1: WE ARE IMPLICITLY ASSUMING THAT
THE DESIRED PATH IS THE GRAPH OF A
FUNCTION.



NOTE 2: THE DISCUSSION ASSUMED THAT n
ONLY DEPENDS ON VERTICAL COMPONENT.

MORE GENERALLY, COULD HAVE:

$$\int_a^b n(x, y(x)) \sqrt{1 + (y'(x))^2} dx$$

?

(2) SO OUR PROBLEM REDUCES TO THE FOLLOWING (THE
FIRST PROBLEM IN THE CALCULUS OF VARIATIONS):

SUPPOSE $F(u, v, w)$ IS A SUFFICIENTLY
SMOOTH FUNCTION OF 3 VARIABLES; AND WE

CONSIDER THE QUANTITY

$$L(y) = \int_{x_0}^{x_1} F(x, y(x), y'(x)) dx$$

DEFINED FOR FUNCTIONS $y(x)$ WHICH ARE (i) C^1

{ $y + y'$ CONTINUOUS ON $[x_0, x_1]$ } AND FOR

LAGRANGE

(ii) $y(x_0) = y_{\square}$; $y(x_1) = y_1$. FIND

FUNCTIONS $y(x)$ SATISFYING THESE TWO CONDITIONS
WHICH MINIMIZES L . (OR EXTREMUM)

Comments: 1) EVEN FOR $G: \mathbb{R}^n \rightarrow \mathbb{R}$, THERE CAN

OF COURSE BE MULTIPLE MAX/MIN

2) EXTREMA CAN BE LOCAL;

3) CRITICAL POINTS ($\nabla G = 0$) GIVE

CANDIDATE SET FOR LOCATION OF EXTREMA.

DIRECTIONAL
DERIV:

$$\frac{d}{dt} G(\vec{p} + t\vec{v}) \Big|_{t=0} = D_{\vec{v}} G = \nabla G \cdot \vec{v}$$

!"#\$

4) EQUIVALENT TO 3) ALL DIRECTIONAL
DERIVATIVES VANISH.

FUNDAMENTAL CALCULATION:

$$L(y) = \int_{x_0}^{x_1} F(x, y(x), y'(x)) dx$$

$$y(x_0) = y_0$$

$$y(x_1) = y_1$$

CONSIDER "ANY" SMOOTH FUNCTION $n(x)$ WITH

$$n(x_0) = n(x_1) = 0.$$

THEN FOR ANY VALUE ϵ

$y(x) + \epsilon n(x)$ SATISFIES SAME BOUNDARY CONDITIONS

$y + \varepsilon n$ (THE VARIATION) is a "small" PERTURBATION
OF y .

NOW CONSIDER THE FUNCTION OF 1 VARIABLE:

$$g(\varepsilon) = \mathcal{L}(y + \varepsilon n) = \int_{x_0}^{x_1} F(x, y(x) + \varepsilon n(x), y'(x) + \varepsilon n'(x)) dx$$

IF $y(x)$ IS A LOCAL EXTREMUM FOR \mathcal{L} , THEN

$\varepsilon = 0$ IS A LOCAL EXTREMUM FOR g , AND HENCE

$g'(0) = 0$. THIS SHOULD BE TRUE FOR ANY $n(x)$.

WHAT DOES THIS SAY ABOUT $y(x)$?

$$\begin{aligned}
 g'(\varepsilon) &= \int_{x_0}^{x_1} \left(\frac{\partial F}{\partial V} n(x) + \frac{\partial F}{\partial W} n'(x) \right) dx \\
 &= \int_{x_0}^{x_1} \frac{\partial F}{\partial V} n(x) dx + \int_{x_0}^{x_1} \frac{\partial F}{\partial W} n'(x) dx \\
 &\quad \textcircled{1} \qquad \qquad \qquad \textcircled{2} \quad \overbrace{\hspace{10em}}
 \end{aligned}$$

$$\begin{aligned}
 \textcircled{2} = \text{BP} &= \frac{\partial F}{\partial W} n(x) \Big|_{x=x_0} - \int_{x_0}^{x_1} n(x) \underbrace{\frac{d}{dx} \frac{\partial F}{\partial W}}_{} dx
 \end{aligned}$$

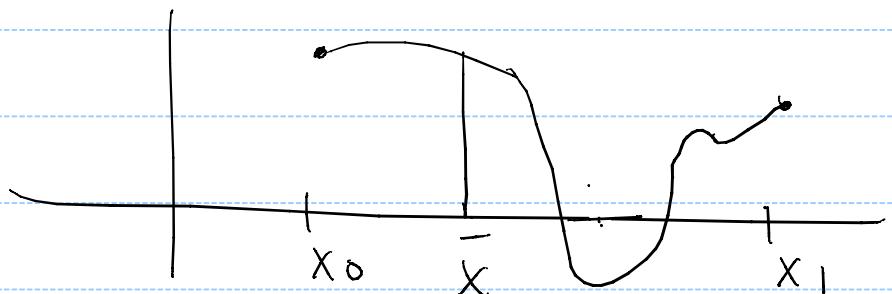
$$\begin{aligned}
 g'(\varepsilon) &= \int_{x_0}^{x_1} n(x) \left[F_V(x, y+\varepsilon, y'+\varepsilon n') - \frac{d}{dx} F_W(\cdot, \cdot, \cdot) \right] dx \\
 g'(\delta) &= \int_{x_0}^{x_1} n(x) \left[\frac{\partial F}{\partial V}(x, y/x, y'(x)) - \frac{d}{dx} F_W(x, y(x), y'(x)) \right] dx
 \end{aligned}$$

$= 0$, INDEPENDENT OF $n(x)$.

LET $h(x) = \frac{\partial F}{\partial v}(x, y(x), y'(x)) - \frac{d}{dx} F_w(x, y(x), y'(x))$

CLAIM: $h(x) \equiv 0$! IF NOT, THEN ASSUMING
 $h(x) \not\equiv 0$, THERE IS SOME POINT \bar{x} WITH $h(\bar{x}) \neq 0$

ASSUME WLOG $h(\bar{x}) > 0$. CONSTRUCT $n(x)$ WITH

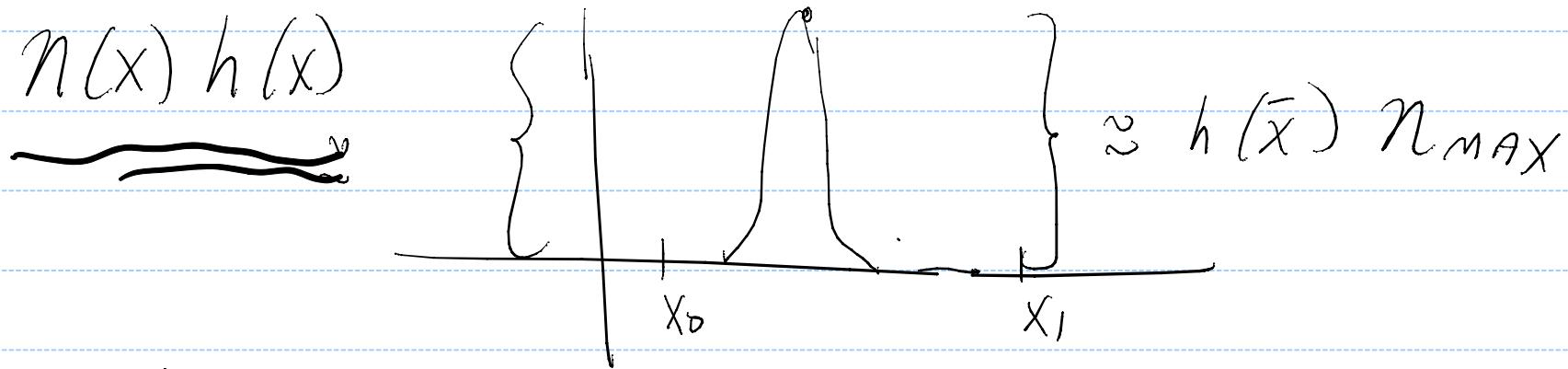
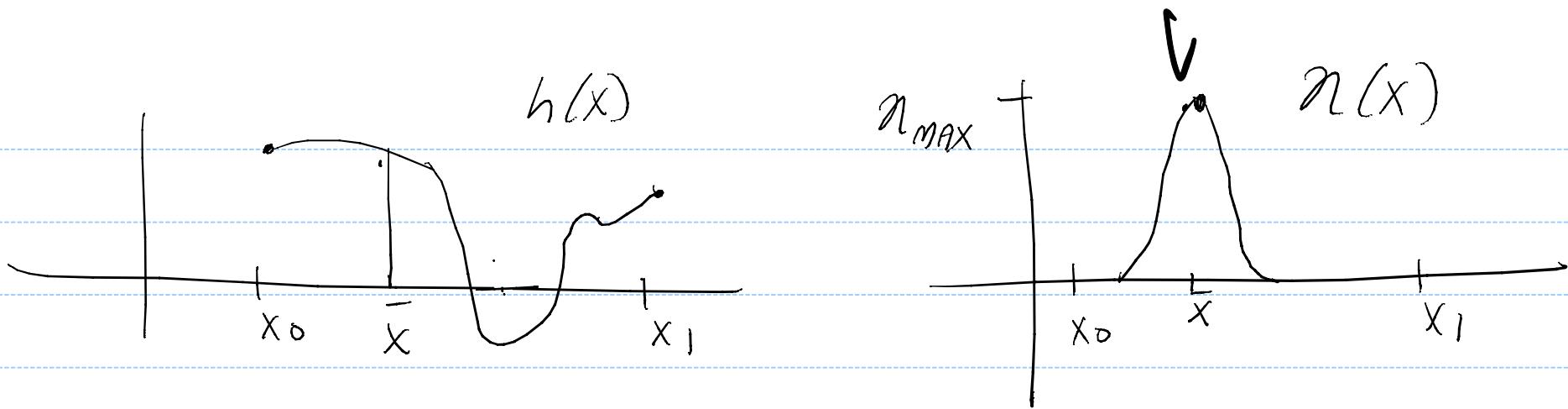


$$n(x_0) = n(x_1) = 0 ;$$

$$n(x) \geq 0 ;$$



$n(x) \equiv 0$ OUTSIDE SMALL NBD \bar{x}



$$\int_{x_0}^{x_1} n(x) h(x) dx > 0 \quad \text{if} \quad \text{.}$$

! " # \$ &

THUS, IF $y(x)$ IS AN EXTREMUM FOR L ,

AND IF y HAS CONTINUOUS FIRST AND 2ND

DERIVATIVES, THEN $y(x)$ SATISFIES THE SECOND

ORDER DIFFERENTIAL EQUATION

EULER-
LAGRANGE EQU.

$$F_r(x, y(x), y'(x)) - \frac{d}{dx} F_w(x, y(x), y'(x)) = 0$$

THIS EQUATION IS ABSOLUTELY ESSENTIAL TO
THE SUBJECT!

$$\int_a^b F(x, y(x), y'(x)) dx \quad ; \quad F(u, v, w).$$

!"#\$'

COMMENTS:

① TECHNICALLY, WE HAVE SHOWN THAT IF $y(x)$ IS AN EXTREMUM FOR \mathcal{L} (WHICH ONLY REQUIRES CONTINUOUS FIRST DERIVATIVE TO BE DEFINED) AND IF $y''(x)$ EXISTS, THEN $y(x)$ SATISFIES E-L. CAN SHOW THAT, FOR SUITABLE F , y AN EXTREMUM $\Rightarrow y''(x)$ EXISTS. WE'LL AVOID SUCH TECHNICAL DETAILS.

② TYPICALLY, FOR SECOND ORDER DE'S, YOU WANT

TO WRITE EQN AS $y''(x) = \dots$; CAN PROVE

EXISTENCE THEOREMS IN THIS FORM. BUT E-L IS

$$\overbrace{F_V(x, y(x), y'(x))} - \frac{d}{dx} F_W(x, y(x), \underline{y'}(x)) = 0$$

OR $\overbrace{F_V(x, y, y')} - F_{WU} - F_{WV} \underline{y'(x)} - F_{WW} \overbrace{y''(x)} = 0$

REQUIRE $F_{WW}(x, y(x), y'(x)) \neq 0$ ALONG CURVE

(MOST EASILY GUARANTEED IF $F_{WW} > 0$ EVERYWHERE)

③ BASIC EXISTENCE THEOREMS FOR DE's ARE
INITIAL VALUE PROBLEMS: $y''(x) = f(x, y(x), y'(x))$
 $y(x_0) = y_0 \quad y'(x_0) = y_P$

WE HAVE A BOUNDARY VALUE PROBLEM, FOR
WHICH THE FUNDAMENTAL THEOREM DOES NOT
APPLY.

④ THE STANDARD NOTATION (UNFORTUNATELY!)

I HAVE WRITTEN $F(u, v, w) : \mathbb{R}^3 \rightarrow \mathbb{R}$

$\mathcal{L} = \int F(x, y(x), \underline{y'(x)}) dx$ FUNCTION ON
FUNCTIONS: FUNCTIONAL

E-L: $F_v(x, y, y') - \frac{d}{dx} F_w(x, y, y') = 0$

IN STANDARD NOTATION, WRITE V AS Y,

AND W AS y' : $F(x, y, y')$:

$F_y(x, y, y') - \frac{d}{dx} F_{y'}(x, y, y') = 0$

MAXIMAL CONFUSION! NOTATION MEANS

PARTIAL DIFFERENTIATION WRT 2ND + 3RD

SLOTS. BUT $F_y(u, v, \omega) = \frac{\partial F}{\partial v} \Big|_{u, \omega, \text{fixed}}$

SO F_y "LOOKS" LIKE $\frac{\partial F}{\partial y} \Big|_{x, z, \text{fixed}}$. HOW
CAN YOU FIX y , AND VARY y' ? YOU CAN'T!

JUST ANOTHER NOTATION FOR PARTIAL DERIVATIVES

WRT THE VARIOUS SLOTS. THIS NOTATION HAS
CONFUSED GENERATIONS OF MATH / SCIENCE STUDENTS!

BACK TO LIGHT PATHS: $\mathcal{L}(y) = \int_a^b n(x, y) \sqrt{1 + (y'(x))^2} dx$

(3)

$$\text{Ex: } n \equiv 1 \quad \mathcal{L}(y) = \int_0^1 \sqrt{1 + (y'(x))^2} dx$$

$$F(u, v, w) = \sqrt{1 + w^2}$$

$$\mathcal{L}(y) = \int F(x, y(x), y'(x)) dx$$

$$F_v = 0 \quad F_w = \frac{w}{\sqrt{1+w^2}} = f_w(u, v, w)$$

E-L:

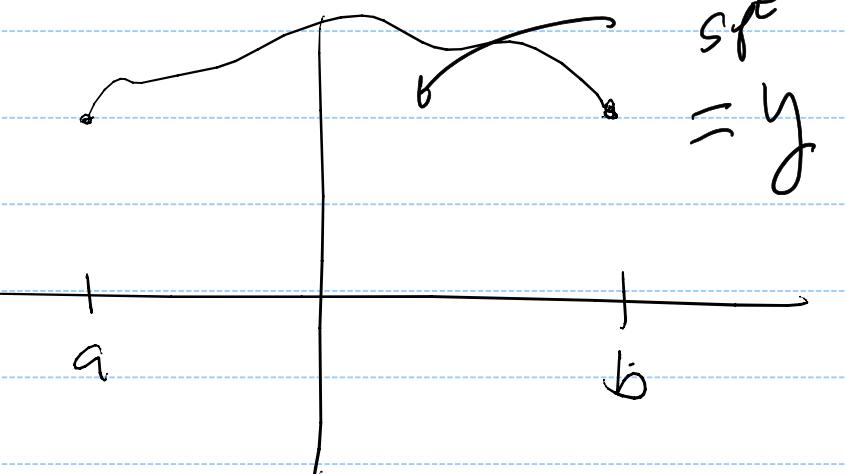
$$0 = F_w - \frac{d}{dx} f_w(x, y, y') = \frac{d}{dx} \frac{y'}{\sqrt{1+(y')^2}}$$

$$\rightarrow \frac{y'}{\sqrt{1+(y')^2}} = C \rightarrow \frac{(y')^2}{1+(y')^2} = C^2$$

$$\rightarrow y' = D \quad y = Dx + E$$

velocity
speed
 $= y$

Ex: $n = \frac{1}{y} \quad y > 0$



$$\mathcal{L}(y) = \int_a^b \frac{\sqrt{1+(y'(x))^2}}{y} dx$$

!"#\$'

$$F(a, v, \omega) = \frac{\sqrt{1 + \omega^2}}{v}$$

$$F_v = -\frac{\sqrt{1 + \omega^2}}{v^2} \quad F_\omega = \frac{1}{v} \frac{\omega}{\sqrt{1 + \omega^2}}$$

$$F_v(x, y(x), y'(x)) - \frac{d}{dx} F_\omega(x, y(x), y'(x)) = 0$$

$$-\frac{\sqrt{1 + (y')^2}}{y^2} - \frac{d}{dx} \frac{1}{y} \frac{y'}{\sqrt{1 + (y')^2}} = 0$$

$$D = \left(1 + (y')^2\right)^{1/2} \quad D' = \frac{y'y''}{D}$$

E-L:

$$\frac{-D}{y^2} - \frac{d}{dx} \frac{y'}{y D} = 0$$

$$\frac{-D}{y^2} - \underbrace{\left[y'' y D - y' \left[y' D + y \frac{y'y''}{D} \right] \right]}_{y^2 D^2} = 0$$

$$D^3 + y'' y D - (y')^2 D - \frac{(y')^2 y y''}{D} = 0$$

$$D^4 + y'' y D^2 - (y')^2 D^2 - (y')^2 y y'' = 0$$

$$(1 + (y')^2)^2 + y''y(1 + (y')^2) - (y')^2(1 + (y')^2)$$
$$-(y')^2 y y'' = 0$$

$$1 + 2(y')^2 + \cancel{(y')^4} + y''y + \cancel{y''y(y')^2}$$
$$-(y')^2 - \cancel{(y')^4} - \cancel{(y')^2 y y''} = 0$$

$$\boxed{1 + (y')^2 + y''y = 0}$$

$$E-L \text{ SIMPLIFIES TO } 1 + (y')^2 + y''y = 0$$

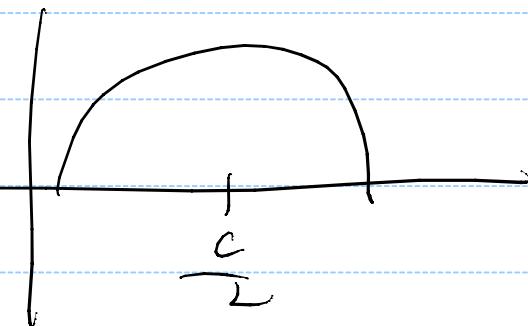
$$(yy')' = -1 \rightarrow yy' = -x + C$$

$$\left(\frac{y^2}{2}\right)' = -x + C \quad \frac{y^2}{2} = \frac{-x^2}{2} + CX + D$$

$$x^2 + y^2 = CX + D \rightarrow x^2 - CX + y^2 = D$$

$$\left(x - \frac{C}{2}\right)^2 + y^2 = D$$

CIRCLE ...



$$L(y) = \int \frac{\sqrt{1 + (y'(x))^2}}{y(x)} dx$$

IF YOU SEEK TO MAKE $L(y)$ AS SMALL

AS POSSIBLE, YOU ARE REWARDED IF $y(x)$
 IS LARGE

