# GALERKIN APPROXIMATIONS OF NONLINEAR DELAY DIFFERENTIAL EQUATIONS WITH MULTIPLE DELAYS

HONGHU LIU AND TREVOR NORTON

Abstract. Create abstract

- 1. Introduction. Points to be addressed:
  - Can we deal with time-dependent coefficients in the linear part? Treat them as nonlinear term?
- 2. Preliminaries.
- **2.1. DDEs covered by the proposed approach.** We consider systems of nonlinear DDEs involving multiple discrete or distributed delays, either in the linear term or in the nonlinearity. Such DDEs can be put into the following form:

(2.1) 
$$\frac{\mathrm{d}\boldsymbol{x}(t)}{\mathrm{d}t} = \boldsymbol{A}\boldsymbol{x}(t) + \sum_{i=1}^{p} \boldsymbol{B}_{i}\boldsymbol{x}(t-\tau_{i}) + \sum_{i=1}^{p} \boldsymbol{C}_{i} \int_{t-\tau_{i}}^{t} \boldsymbol{x}(s) \,\mathrm{d}s \\
+ \boldsymbol{F}\left(t, \boldsymbol{x}(t), \boldsymbol{x}(t-\tau_{1}), \cdots, \boldsymbol{x}(t-\tau_{p}), \int_{t-\tau_{1}}^{t} \boldsymbol{x}(s) \,\mathrm{d}s, \cdots, \int_{t-\tau_{p}}^{t} \boldsymbol{x}(s) \,\mathrm{d}s\right),$$

where the unknown function  $\boldsymbol{x}$  is a d-dimensional vector; p is a positive integer, representing the total number of delays; the  $\tau_i$ 's are distinctive positive scalars arranged in ascending order;  $\boldsymbol{A}$ ,  $\boldsymbol{B}_i$ , and  $\boldsymbol{C}_i$  ( $1 \leq i \leq p$ ) are given  $d \times d$  matrices; and  $\boldsymbol{F} \colon \mathbb{R}^{2+2p} \to \mathbb{R}^d$  is a given continuous vector function.

In order to simplify the presentation, we first articulate our main contribution in a simple setting of a scalar DDE with a single discrete delay  $\tau > 0$ :

(2.2) 
$$\frac{\mathrm{d}x(t)}{\mathrm{d}t} = ax(t) + bx(t-\tau) + F(x(t-\tau)),$$

where  $a, b \in \mathbb{R}$ , and  $F : \mathbb{R} \to \mathbb{R}$  is a given scalar function. Results for the general case of (2.1) is provided afterward in Section 4.

\*\*\*\*\*\*\*\*\*\*\*

- Explain in a short paragraph the main difficult compared with the case dealt with in [1].
- To cope with the difficulties, we restrict the initial data to  $C^2$  functions. Refer to Section 4 for results about existence and regularity.

**2.2.** The Abstract Formulation of the Linear Operator. It is appropriate to reformulate (2.2) into an abstract ordinary differential equation on the Hilbert space

(2.3) 
$$\mathcal{H} := L^2([-\tau, 0); \mathbb{R}) \times \mathbb{R},$$

where the inner product is defined for  $(f_1, \gamma_1), (f_2, \gamma_2) \in \mathcal{H}$ , as:

(2.4) 
$$\langle (f_1, \gamma_1), (f_2, \gamma_2) \rangle_{\mathcal{H}} := \frac{1}{\tau} \int_{-\tau}^0 f_1(\theta) f_2(\theta) d\theta + \gamma_1 \gamma_2.$$

However, it is not yet possible to represent F in this space, so we focus on the linear part of (2.2). Define the linear operator  $\mathcal{A}: D(\mathcal{A}) \to \mathcal{H}$  by

(2.5) 
$$[\mathcal{A}\Psi](\theta) := \begin{cases} \frac{\mathrm{d}^+ \Psi^D}{\mathrm{d}\theta}, & \theta \in [-\tau, 0), \\ a\Psi^S + b\Psi^D(-\tau), & \theta = 0, \end{cases}$$

for any  $\Psi = (\Psi^D, \Psi^S)$  that lives in the domain,  $D(\mathcal{A})$ , defined as

(2.6) 
$$D(\mathcal{A}) := \left\{ \Psi \in \mathcal{H} : \Psi^D \in H^1([-\tau, 0); \mathbb{R}^d), \lim_{\theta \to 0^-} \Psi^D(\theta) = \Psi^S \right\}.$$

It is clear that if  $x: [-\tau, \infty)$  satisfies the linear DDE

(2.7) 
$$\frac{\mathrm{d}x(t)}{\mathrm{d}t} = ax(t) + bx(t-\tau), \quad t > 0$$
$$x(0) = \alpha,$$
$$x(t) = f(t), \qquad t \in [-\tau, 0)$$

then  $u(t) = (x_t, x_t(0))$ , where  $x_t(\theta) = x(t + \theta)$  for  $\theta \in [-\tau, 0)$ , satisfies the linear, abstract ODE

(2.8) 
$$\frac{\mathrm{d}u}{\mathrm{d}t} = \mathcal{A}u, \quad t > 0$$
$$u(0) = u_0,$$

where  $u_0 = (f, \alpha)$ . From [2, Thm. 2.4.1], the DDE in (2.7) has a solution x(t). Furthermore, if we define  $T(t) : \mathcal{H} \to \mathcal{H}$  by

(2.9) 
$$T(t)(f,\alpha) := (x_t, x_t(0)), \quad t \ge 0,$$

then T(t) is a  $C_0$ -semigroup on  $\mathcal{H}$  and  $\mathcal{A}$  is its infinitesimal generator [2, Thm. 2.4.4; Thm. 2.4.6]. With this, we know that the solution to (2.8) is  $T(t)u_0$ .

**2.3.** The Space X. In order for us to make sense of the nonlinear part of (2.2), we look at a certain subset of the space  $\mathcal{H}$ . We define the following inner product space with elements in

$$(2.10) X := \mathcal{C}^+([-\tau, 0); \mathbb{R}) \times \mathbb{R} \subseteq \mathcal{H},$$

where  $C^+([-\tau,0))$  denotes the set of bounded right-continuous functions on the interval  $[-\tau,0)$ , and the inner product defined by

$$(2.11) \qquad (\Phi, \Psi)_X := \Phi^S \Psi^S + \frac{1}{\tau} (\Phi^D, \Psi^D)_{L^2([-\tau, 0)} + \Phi^D(-\tau) \Psi^D(-\tau), \quad \Phi, \Psi \in X.$$

Note that this is defined since if  $f \in C^+([-\tau, 0)$  then  $f \in L^2([-\tau, 0)]$ . It is relatively straight-forward to verify that  $(\cdot, \cdot)_X$  is symmetric, bilinear, and positive definite and thus an inner product. We will also make use of the norm  $\|\cdot\|_X$  induced from this inner product. Note that X is **not** a Banach space since Cauchy sequences might not converge in X.

We can then define  $\mathcal{F}: X \to X \subseteq \mathcal{H}$  by

(2.12) 
$$[\mathcal{F}(\Psi)](\theta) := \begin{cases} 0, & \theta \in [-\tau, 0), \\ F(\Psi^D(-\tau)), & \theta = 0, \end{cases} \quad \forall \, \Psi = (\Psi^D, \Psi^S) \in X.$$

From [2, Thm. 2.4.1], if  $u_0 \in X$ , then the solution x(t) of (2.2) with initial conditions  $x_0 = u_0^D$  and  $x(0) = u_0^S$  is continuous on  $[0, \infty)$ . Therefore,  $x_t$  is in  $C^+([-\tau, 0))$  and  $u(t) \in X$  for any  $t \in [0, \infty)$ . Now if we set  $u(t) = (x_t, x_t(0))$  where x is the solution to (2.2), then u satisfies the following abstract ODE:

(2.13) 
$$\frac{\mathrm{d}u}{\mathrm{d}t} = \mathcal{A}u(t) + \mathcal{F}(u(t)),$$
$$u(0) = u_0.$$

From the above, we can derive the variation of constants formula:

(2.14) 
$$u(t) = T(t)u_0 + \int_0^t T(t-s)\mathcal{F}(u(s)) \, \mathrm{d}s.$$

For a derivation c.f. [4, pg. 105].

**2.4.** Properties and Basic Results of Koornwinder Polynomials. From [3, Eq. (2.1)], the sequence of Koornwinder polynomials  $\{K_n\}$  can be built from the Legendre polynomials  $L_n$  by

(2.15) 
$$K_n(s) := -(1+s)\frac{d}{ds}L_n(s) + (n^2+n+1)L_n(s), \quad s \in [-1,1], \ n \in \mathbb{N}_0.$$

Furthermore, we reproduce from [1, Prop. 3.1] some simple properties that  $\{K_n\}$  satisfy.

PROPOSITION 2.1. The polynomial  $K_n$  defined in (2.15) is of degree n and admits the following expansion in terms of the Legendre polynomials:

(2.16) 
$$K_n(s) = -\sum_{j=0}^{n-1} (2j+1)L_j(s) + (n^2+1)L_n(s), \qquad n \in \mathbb{N}_0;$$

and the following normalization property holds:

$$(2.17) K_n(1) = 1, n \in \mathbb{N}_0.$$

Moreover, the sequence given by

$$\{\mathcal{K}_n := (K_n, K_n(1)) : n \in \mathbb{N}_0\}$$

forms an orthogonal basis of the product space

$$(2.19) \mathcal{E} := L^2([-1,1);\mathbb{R}) \times \mathbb{R},$$

where  $\mathcal{E}$  is endowed with the following inner product:

(2.20) 
$$\langle (f,a), (g,b) \rangle_{\mathcal{E}} = \frac{1}{2} \int_{-1}^{1} f(s)g(s) \, \mathrm{d}s + ab, \quad (f,a), (g,b) \in \mathcal{E}.$$

Finally,  $\left\{\frac{\mathcal{K}_n}{\|\mathcal{K}_n\|_{\mathcal{E}}}\right\}$  forms a Hilbert basis of  $\mathcal{E}$  where the norm  $\|\mathcal{K}_n\|_{\mathcal{E}}$  of  $\mathcal{K}_n$  induced by  $\langle\cdot,\cdot\rangle_{\mathcal{E}}$  possesses the following analytic expression:

(2.21) 
$$\|\mathcal{K}_n\|_{\mathcal{E}} = \sqrt{\frac{(n^2+1)((n+1)^2+1)}{2n+1}}, \qquad n \in \mathbb{N}_0.$$

Suppose that  $\Pi_N^{\mathcal{E}}$  is the N-dimensional standard projection into span $\{\mathcal{K}_n : n \leq N\} \subset \mathcal{E}$ . It will be relevant to discuss when we have convergence of  $[\Pi_N^{\mathcal{E}} u]^D$  for  $u \in \mathcal{E}$ . In particular, we will focus on uniform convergence.

PROPOSITION 2.2. Let  $f \in \mathcal{C}^2([-1,1];\mathbb{R})$  and denote  $\psi = (f,f(0)) \in \mathcal{E}$ . Then the series

$$[\Pi_N^{\mathcal{E}}\psi]^D = \sum_{n=0}^N \frac{\langle \psi, \mathcal{K}_n \rangle_{\mathcal{E}}}{\|\mathcal{K}_n\|_{\mathcal{E}}^2} K_n$$

converges uniformly to f.

See Appendix A for a proof.

It will also be necessary to prove certain properties of the series of Koornwinder polynomials

(2.23) 
$$S_N(x) := \sum_{n=0}^N \frac{K_n}{\|K_n\|_{\mathcal{E}}^2}, \quad N \in \mathbb{N}_0, \ x \in [-1, 1].$$

If we were to denote  $\psi = (0,1) \in L^2([-1,1]) \times \mathbb{R}$ , then  $S_N$  would simply be the functional part of  $\Pi_N \psi$ . The following lemma allows us to express  $S_N$  in terms of Legendre Polynomials. Now that we have this expression, we can prove the properties of  $S_N$  that will be useful when showing the main result.

LEMMA 2.1. The functions  $S_N$  defined in (2.23) can be expressed as

(2.24) 
$$S_N(x) = \frac{1}{(N+1)^2 + 1} \sum_{n=0}^{N} (2n+1)L_n, \quad x \in [-1, 1].$$

Moreover,

$$(2.25) |S_N(x)| < 1, \quad \forall N \in \mathbb{N}_0, \ \forall x \in [-1, 1],$$

and

(2.26) 
$$\lim_{N \to \infty} S_N(x) = 0, \quad \forall x \in (-1, 1).$$

See Appendix A for a proof.

Remark 2.1. It can easily be shown that  $\lim_{N\to\infty} S_N(-1) = 0$  and  $\lim_{N\to\infty} S_N(1) = 1$ , which both follow from the expression (2.24) when evaluated at  $\pm 1$ . However, for our main results we need only that  $S_N \to 0$  almost everywhere on [-1,1]. Therefore we omit the proof of this.

Applying a linear transformation to the orthogonal polynomials on [-1,1] will give us a set of orthogonal polynomials on  $[-\tau,0]$ , from which we can construct an orthogonal basis on  $\mathcal{H}$ . We define a linear transformation  $\mathcal{T}$  by

(2.27) 
$$\mathcal{T}: [-\tau, 0] \to [-1, 1], \qquad \theta \mapsto 1 + \frac{2\theta}{\tau}.$$

We can now define the polynomial  $K_n^{\tau}$  by

(2.28) 
$$K_n^{\tau} \colon [-\tau, 0] \to \mathbb{R},$$
$$\theta \mapsto K_n \left( 1 + \frac{2\theta}{\tau} \right), \qquad n \in \mathbb{N}.$$

Since the sequence  $\{K_n = (K_n, K_n(1)) : n \in \mathbb{N}\}$  forms an orthogonal basis for  $\mathcal{E}$  (cf. Proposition 2.1), it follows then that the polynomial sequence  $K_n^{\tau} := (K_n^{\tau}, K_n^{\tau}(0)) : n \in \mathbb{N}\}$  forms an orthogonal basis for the space  $\mathcal{H} = L^2([-\tau, 0); \mathbb{R}) \times \mathbb{R}$  endowed with the inner product  $\langle \cdot, \cdot \rangle_{\mathcal{H}}$  defined in (2.4). We define  $S_N^{\tau}$  similarly. It can be verified that Lemma 2.1 and Proposition 2.2 are preserved in  $\mathcal{H}$ .

We are now able to define

(2.29) 
$$\mathcal{H}_N := \operatorname{span}\{\mathcal{K}_0^{\tau}, \dots, \mathcal{K}_N^{\tau}\}.$$

Let  $\Pi_N$  be the associated orthogonal projector of  $\mathcal{H}_N$ . By the construction of the orthogonal basis  $\{\mathcal{K}_n^{\tau}\}$ , we have that  $\mathcal{H}_N \subset D(\mathcal{A})$ . The N-dimensional Galerkin approximation of (2.13) is

(2.30) 
$$\frac{\mathrm{d}u_N}{\mathrm{d}t} = \mathcal{A}_N u_N + \Pi_N \mathcal{F}(u_N),$$
$$u_N(0) = \Pi_N u_0,$$

where  $A_N := \prod_N A \prod_N$ . The linear operator  $A_N$  on the finite dimensional space  $\mathcal{H}_N$  defines the  $C_0$ -semigroup  $e^{A_N t}$ . This can be extended to a  $C_0$ -semigroup on  $\mathcal{H}$ :

$$(2.31) T_N(t)u = e^{\mathcal{A}_N t} \Pi_N u + (I - \Pi_N)u, \ u \in \mathcal{H}.$$

From (2.30), we derive the variation of constants formula for the Galerkin approximation:

(2.32) 
$$u_N(t) = T_N(t)\Pi_N u_0 + \int_0^t T_N(t-s)\Pi_N \mathcal{F}(u_N(t)) \,\mathrm{d}s.$$

By [1, Lemma 4.3] and the proof of [1, Thm. 4.1], the results about T(t) and  $T_N(t)$  hold. PROPOSITION 2.3. For t > 0 and  $N \in \mathbb{N}_0$ ,

$$(2.33) ||T_N(t)||_{\mathcal{H}}, ||T(t)||_{\mathcal{H}} \le Me^{\omega t}.$$

Also, for any T > 0,

(2.34) 
$$\lim_{N \to \infty} \sup_{t \in [0,T]} ||T(t)u - T_N(t)\Pi_N u||_{\mathcal{H}} = 0, \quad \forall u \in \mathcal{H}.$$

The proof of (2.34) relies on a version of the Trotter-Kato theorem [4, Thm. 4.5, p. 88].

### 3. Uniform Convergence of Galerkin Solutions.

**3.1. Pointwise Convergence in** X. From [2, Thm. 2.4.1], if  $u_0 \in X$ , then the solution x(t) of (2.7) with initial conditions  $u_0^D$  and  $u_0^S$  is continuous on  $[0, \infty)$ . This is sufficient to say that  $T(t)u_0 = (x_t, x_t(0)) \in X$  and that T(t) maps X into X. Similarly, we have that  $\Pi_N$  maps  $X \subseteq \mathcal{H}$  into  $\mathcal{H}_N$  and  $T_N(t)$  maps  $\mathcal{H}_N$  into  $\mathcal{H}_N$ . Hence  $T_N(t)\Pi_N$  maps X into  $\mathcal{H}_N$ , which is a subset of X. We summarize these results in the following lemma.

LEMMA 3.1. For any  $t \geq 0$ , the operators T(t) and  $T_N(t)\Pi_N$  map X into itself.

This justifies the later use of the norm  $\|\cdot\|_X$  on certain functions. It will also be helpful to prove the following lemma.

LEMMA 3.2. Let u be the solution for (2.13) and  $u_N$  the solution for (2.30) for some initial value  $u_0 \in X$ . There is C > 0 such that for any  $N \in \mathbb{N}_0$ .

$$(3.1) ||T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))||_X \le C||u(s) - u_N(s)||_X,$$

where  $t \in [0, T]$  and  $s \in [0, t]$ .

*Proof.* We have that

(3.2) 
$$||T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))||_X^2 = ||T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))||_{\mathcal{H}}^2 + |[T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))]^D(-\tau)|^2 .$$

Note that for the first term on the right-hand side of (3.2), we have that

$$||T_{N}(t-s)\Pi_{N}(\mathcal{F}(u(s)) - \mathcal{F}(u_{N}(s)))||_{\mathcal{H}} \leq Me^{\omega(t-s)}||\mathcal{F}(u(s)) - \mathcal{F}(u_{N}(s))||_{\mathcal{H}}$$

$$\leq Me^{\omega T}||\mathcal{F}(u(s)) - \mathcal{F}(u_{N}(s))||_{\mathcal{H}}$$

$$= Me^{\omega T}||F([u(s)]^{D}(-\tau)) - F([u_{N}(s)]^{D}(-\tau))||$$

$$\leq \operatorname{Lip}(F)Me^{\omega T}||u(s)|^{D}(-\tau) - [u_{N}(s)]^{D}(-\tau)||$$

$$\leq \operatorname{Lip}(F)Me^{\omega T}||u(s) - u_{N}(s)||_{X}.$$

For the second term on the right-hand side of (3.2), we consider first the case when  $t - s \ge \tau$ . Then

$$|[T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))]^D(-\tau)| \leq ||T_N(t-s-\tau)\Pi(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))||_{\mathcal{H}}$$

$$\leq Me^{\omega T}||\mathcal{F}(u(s)) - \mathcal{F}(u_N(s))||_{\mathcal{H}}$$

$$\leq \text{Lip}(F)Me^{\omega T}||u(s) - u_N(s)||_{X}.$$

Now consider the case when  $t - s < \tau$ . So we have that

$$|[T_{N}(t-s)\Pi_{N}(\mathcal{F}(u(s)) - \mathcal{F}(u_{N}(s)))]^{D}(-\tau)| = |[\Pi_{N}(\mathcal{F}(u(s)) - \mathcal{F}(u_{N}(s)))]^{D}(t-s-\tau)|$$

$$= |F([u(s)]^{D}(-\tau)) - F([u_{N}(s)]^{D}(-\tau))| \cdot |S_{N}^{\tau}(t-s-\tau)|$$

$$\leq \operatorname{Lip}(F) |[u(s)]^{D}(-\tau) - [u_{N}(s)]^{D}(-\tau)|$$

$$\leq \operatorname{Lip}(F) ||u(s) - u_{N}(s)||_{X}.$$

Note that since  $M \ge 1$  and  $\omega T \ge 0$ , so  $\text{Lip}(F) \le \text{Lip}(F) M e^{\omega T}$ . If we define

(3.6) 
$$C := \sqrt{2} \cdot \operatorname{Lip}(F) M e^{\omega T}$$

and apply (3.3), (3.4), and (3.5) to (3.2), then we get that

(3.7) 
$$||T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))||_X \le C||u(s) - u_N(s)||_X.$$

We introduce the following definitions:

(3.8) 
$$r_N(t) := ||u(t) - u_N(t)||_X,$$

$$\epsilon_N(t) := ||T(t)u_0 - T_N(t)\Pi_N u_0||_X,$$

$$d_N(t,s) := ||(T(t-s) - T_N(t-s)\Pi_N)\mathcal{F}(u(s))||_X.$$

One can apply the variation-of-constants formula and the above definitions to get that

(3.9) 
$$r_N(t) \le \epsilon_N(t) + \int_0^t d_N(t,s) \, \mathrm{d}s + \int_0^t \|T_N(t-s)\Pi_N(\mathcal{F}(u(s)) - \mathcal{F}(u_N(s)))\|_X \, \mathrm{d}s$$

$$\le \epsilon_N(t) + \int_0^t d_N(t,s) \, \mathrm{d}s + C \int_0^t r_N(s) \, \mathrm{d}s.$$

Applying Grönwall's inequality to (3.9) gives

$$(3.10) r_N(t) \le \left[ \epsilon_N(t) + \int_0^t d_N(t,s) \, \mathrm{d}s \right] + \int_0^t Ce^{C(t-s)} \left[ \epsilon_N(s) + \int_0^s d_N(s,r) \, \mathrm{d}r \right] \, \mathrm{d}s$$

$$\le \left[ \epsilon_N(t) + \int_0^t d_N(t,s) \, \mathrm{d}s \right] + Ce^{CT} \int_0^t \left[ \epsilon_N(s) + \int_0^s d_N(s,r) \, \mathrm{d}r \right] \, \mathrm{d}s.$$

We wish to show that  $r_N(t) \to 0$  as  $N \to \infty$  for each fixed  $t \in [0,T]$ . To this end, we show that each term on the right-hand side of (3.10) converges to 0 as  $N \to \infty$  and  $t \in [0,T]$  fixed. The following propositions will show this.

PROPOSITION 3.1. For fixed  $t \in [0, T]$ ,

(3.11) 
$$\epsilon_N(t) \to 0 \text{ and } \int_0^t \epsilon_N(s) \, \mathrm{d}s \to 0$$

as  $N \to \infty$ .

*Proof.* From the definition of the X norm, we have that

(3.12) 
$$\epsilon_N(t)^2 = \|T(t)u_0 - T_N(t)\Pi_N u_0\|_{\mathcal{H}}^2 + \|[T(t)u_0]^D(-\tau) - [T_N(t)\Pi_N u_0]^D(-\tau)\|^2.$$

The first term on the right-hand side converges uniformly to 0 by the Trotter-Kato theorem. For the second case, we again consider the case when  $t \geq \tau$ . Here we can apply the Trotter-Kato theorem again to  $||T(t-\tau)u_0 - T_N(t-\tau)\Pi_N u_0||_{\mathcal{H}}^2$  to get the term converges to zero. When  $t < \tau$ , the second term becomes

(3.13) 
$$|u_0^D(t-\tau) - [\Pi_N u_0]^D(t-\tau)|^2$$

which converges to 0 uniformly by Proposition 2.2. This gives that  $\epsilon_N(t) \to 0$ .

To show the other convergence, note that  $\epsilon_N(s)$  converges pointwisely to 0 on [0,t]. Furthermore, we may uniformly bound  $\epsilon_N(s)$  by again observing the equality (3.12) and applying the uniform bounds on  $||T_N(\cdot)||_{\mathcal{H}}$  and on  $[\Pi_N u_0]^D$ . Then by the Bounded Convergence Theorem, we have  $\int_0^t \epsilon_N(s) ds \to 0$ .

PROPOSITION 3.2. For fixed  $t \in [0, T]$ ,

(3.14) 
$$\int_0^t d_N(t,s) \, ds \to 0 \text{ and } \int_0^t \int_0^s d_N(s,r) \, dr \, ds \to 0,$$

as  $N \to \infty$ .

*Proof.* We can again apply the definition of  $\|\cdot\|_X$  to get that

(3.15) 
$$d_N^2(t,s) = \| (T(t-s) - T_N(t-s)\Pi_N) \mathcal{F}(u(s)) \|_{\mathcal{H}}^2 + \| [T(t-s)\mathcal{F}(u(s))]^D(-\tau) - [T_N(t-s)\Pi_N\mathcal{F}(u(s))]^D(-\tau) \|^2.$$

For fixed t and s, the first term of the right-hand side converges to zero. For  $t - s \ge \tau$  the second term will similarly converge to 0. For  $t - s < \tau$ , the second term will become

$$(3.16) |0 - [\Pi_N \mathcal{F}(u(s))]^D(t - s - \tau)| = |F([u(s)]^D(-\tau))| \cdot |S_N(t - s - \tau)|,$$

which converges a.e. to 0 by (2.26). So for fixed t,  $d_N(t,s)$  converges a.e. to 0 for  $s \in [0,t]$ . Furthermore, we can uniformly bound  $d_N(t,s)$  by (2.25). Thus by the Bounded Convergence Theorem, we have  $\int_0^t d_N(t,s) ds \to 0$  as  $N \to \infty$ .

The second convergence follows by the observations that  $\int_0^{\cdot} d_N(\cdot, r) dr$  converges pointwise to 0 by our earlier work and can uniformly bounded on [0, t]. This allows us to apply the Bounded Convergence Theorem to get that  $\int_0^t \int_0^s d_N(s, r) dr ds \to 0$  as  $N \to \infty$ .

We may now state our result.

THEOREM 3.3. For  $t \in [0, T]$ ,

(3.17) 
$$\lim_{N \to \infty} ||u(t) - u_N(t)||_X = 0.$$

*Proof.* Apply propositions (3.1) and (3.2) to the inequality in (3.10).

### 3.2. Uniform Convergence.

Lemma 3.3. The following convergences hold:

(3.18) 
$$\lim_{N \to \infty} \int_{0}^{T} \left| [u_{N}(s)]^{D}(-\tau) - [u(s)]^{D}(-\tau) \right|^{2} ds,$$

and

(3.19) 
$$\lim_{N \to \infty} \int_0^T \|\mathcal{F}(u_N(s)) - \mathcal{F}(u(s))\|_{\mathcal{H}} \, \mathrm{d}s = 0.$$

*Proof.* Note that

(3.20) 
$$\int_0^T \left| [u_N(s)]^D(-\tau) - [u(s)]^D(-\tau) \right|^2 ds \le \sum_{k=0}^m \int_{-\tau}^0 \left| [u_N(k\tau)]^D(\theta) - [u(k\tau)]^D(\theta) \right|^2 d\theta,$$

for m such that  $T - \tau \leq m\tau < T$ . In other words,

It is a simple corollary of Theorem 3.3 that  $||[u_N(t)]^D - [u(t)]^D]||_{L^2([0,T];\mathbb{R})} \to 0$  as  $N \to \infty$  for any  $t \in [0,T]$ . This gives that the right side of (3.21) converges to 0 as  $N \to \infty$ , and thus the left side of (3.21) also converges to 0 as  $N \to \infty$ . This proves (3.18).

To prove the other convergence, note that

(3.22) 
$$\int_{0}^{T} \|\mathcal{F}(u_{N}(s)) - \mathcal{F}(u(s))\|_{\mathcal{H}} ds = \int_{0}^{T} \left| f\left( [u_{N}(s)]^{D}(-\tau) \right) - f\left( [u(s)]^{D}(-\tau) \right) \right| ds$$
$$\leq \operatorname{Lip}(F) \int_{0}^{T} \left| [u_{N}(s)]^{D}(-\tau) - [u(s)]^{D}(-\tau) \right| ds$$
$$= \operatorname{Lip}(F) \|[u_{N}(\cdot)]^{D}(-\tau) - [u(\cdot)]^{D}(-\tau) \|_{L^{1}([0,T];\mathbb{R})}.$$

Noting that  $L^2([0,T];\mathbb{R})$  is continuously embedded in  $L^1([0,T];\mathbb{R})$  and applying (3.18) proves that (3.19) holds.

THEOREM 3.4. The sequence of functions  $\{u_N\}_{N=0}^{\infty}$ , where

$$(3.23) u_N: [0,T] \mapsto \mathcal{H}, N \in \mathbb{N}_0,$$

is uniformly equicontinuous.

*Proof.* Suppose  $t_0, t_1 \in [0, T]$  and  $t_0 \leq t_1$ . Denote  $\delta := t_1 - t_0$ . Applying the variation-of-constants formula, we have that for  $N \in \mathbb{N}_0$ 

$$||u_{N}(t_{0}) - u_{N}(t_{1})||_{\mathcal{H}} \leq \underbrace{\|(T_{N}(t_{0}) - T_{N}(t_{0} + \delta))\Pi_{N}u_{0}\|_{\mathcal{H}}}_{I(\delta,N)} + \underbrace{\|\int_{0}^{t_{0}} [T_{N}(t_{0} - s) - T_{N}(t_{0} + \delta - s)]\Pi_{N}\mathcal{F}(u_{N}(s)) \,\mathrm{d}s\|_{\mathcal{H}}}_{II(\delta,N)} + \underbrace{\|\int_{t_{0}}^{t_{0}+\delta} T_{N}(t_{0} + \delta - s)\Pi_{N}\mathcal{F}(u_{N}(s)) \,\mathrm{d}s\|_{\mathcal{H}}}_{III(\delta,N)}.$$

We show that for each of these terms, the dependence on  $\delta$  and N can be separated.

## I. We have that

$$I(\delta, N) = \|T_{N}(t_{0})(I - T_{N}(\delta))\Pi_{N}u_{0}\|_{\mathcal{H}}$$

$$\leq Me^{\omega t_{0}}\|(I - T_{N}(\delta))\Pi_{N}u_{0}\|_{\mathcal{H}}$$

$$= Me^{\omega t_{0}}\|(\Pi_{N} - T_{N}(\delta)\Pi_{N})u_{0}\|_{\mathcal{H}}$$

$$\leq Me^{\omega t_{0}}\|(I - T_{N}(\delta)\Pi_{N})u_{0}\|_{\mathcal{H}}$$

$$\leq Me^{\omega T}\|(I - T_{N}(\delta)\Pi_{N})u_{0}\|_{\mathcal{H}}$$

$$\leq Me^{\omega T}\|(I - T_{N}(\delta)u_{0}\|_{\mathcal{H}} + \|(T(\delta) - T_{N}(\delta)\Pi_{N})u_{0}\|_{\mathcal{H}}]$$

$$\leq Me^{\omega T}\left[\|(I - T(\delta))u_{0}\|_{\mathcal{H}} + \sup_{t \in [0,T]}\|(T(t) - T_{N}(t)\Pi_{N})u_{0}\|_{\mathcal{H}}\right].$$

Now define the following functions:

(3.26) 
$$I^*(\delta) := Me^{\omega T} \times \|(I - T(\delta))u_0\|_{\mathcal{H}}$$

and

(3.27) 
$$I^{**}(N) := Me^{\omega T} \times \sup_{t \in [0,T]} \| (T(t) - T_N(t)\Pi_N) u_0 \|_{\mathcal{H}}$$

Note that  $\lim_{\delta \to 0^+} I^*(\delta) = 0$  by the continuity of T(t) and  $\lim_{N \to \infty} I^{**}(N) = 0$  by the Trotter-Kato theorem.

#### II. We have that

$$II(\delta, N) \leq \int_{0}^{t_{0}} \| (T_{N}(t_{0} - s) - T_{N}(t_{0} + \delta - s)) \Pi_{N} \mathcal{F}(u_{N}(s)) \|_{\mathcal{H}} ds 
\leq M e^{\omega T} \int_{0}^{t_{0}} \| (I - T_{N}(\delta) \Pi_{N}) \mathcal{F}(u_{N}(s)) \|_{\mathcal{H}} ds 
\leq M e^{\omega T} \left[ \underbrace{\int_{0}^{t_{0}} \| (I - T_{N}(\delta) \Pi_{N}) \mathcal{F}(u(s)) \|_{\mathcal{H}} ds}_{A} \right] 
+ \underbrace{\int_{0}^{t_{0}} \| (I - T_{N}(\delta) \Pi_{N}) (\mathcal{F}(u_{N}(s)) - \mathcal{F}(u(s))) \|_{\mathcal{H}} ds}_{B} \right].$$

From here, we can note that

(3.29) 
$$A \leq \int_{0}^{T} \|(I - T(\delta))\mathcal{F}(u(s))\|_{\mathcal{H}} ds + \int_{0}^{T} \|(T(\delta) - T_{N}(\delta))\mathcal{F}(u(s))\|_{\mathcal{H}} ds \\ \leq \int_{0}^{T} \|(I - T(\delta))\mathcal{F}(u(s))\|_{\mathcal{H}} ds + \int_{0}^{T} \sup_{t \in [0,T]} \|(T(t) - T_{N}(t))\mathcal{F}(u(s))\|_{\mathcal{H}} ds,$$

where both of these terms can easily be shown to converge to zero as  $\delta \to 0$  and  $N \to \infty$ , respectively. Namely, we can apply the Lebesgue Dominated Convergence Theorem. Also note that

(3.30) 
$$B \leq (1 + Me^{\omega T}) \int_0^T \|\mathcal{F}(u_N(s)) - \mathcal{F}(u(s))\|_{\mathcal{H}} \, \mathrm{d}s,$$

where the right-hand side converges to zero as  $N \to \infty$  by (3.19). Now we set

(3.31) 
$$II^*(\delta) := Me^{\omega T} \int_0^T \|(I - T(\delta))\mathcal{F}(u(s))\|_{\mathcal{H}} ds$$

and

(3.32) 
$$II^{**}(N) := Me^{\omega T} \left[ \int_0^T \sup_{t \in [0,T]} \| (T(t) - T_N(t)) \mathcal{F}(u(s)) \|_{\mathcal{H}} \, \mathrm{d}s + \left( 1 + Me^{\omega T} \right) \int_0^T \| \mathcal{F}(u_N(s)) - \mathcal{F}(u(s)) \|_{\mathcal{H}} \, \mathrm{d}s \right].$$

#### III. We have that

$$(3.33) \quad || III(\delta, N) \leq \int_{t_0}^{t_0 + \delta} || T_N(t_0 + \delta - s) \Pi_N \mathcal{F}(u_N(s)) ||_{\mathcal{H}} ds$$

$$\leq M e^{\omega T} \int_{t_0}^{t_0 + \delta} || \mathcal{F}(u_N(s)) ||_{\mathcal{H}} ds$$

$$\leq M e^{\omega T} \left[ \int_{t_0}^{t_0 + \delta} || \mathcal{F}(u(s)) ||_{\mathcal{H}} ds + \int_{t_0}^{t_0 + \delta} || \mathcal{F}(u_N(s)) - \mathcal{F}(u(s)) ||_{\mathcal{H}} ds \right]$$

$$\leq M e^{\omega T} \left[ \delta \times \sup_{t \in [0, T]} || \mathcal{F}(u(t)) ||_{\mathcal{H}} + \int_0^T || \mathcal{F}(u_N(s)) - \mathcal{F}(u(s)) ||_{\mathcal{H}} ds \right].$$

Note that  $\sup_{t\in[0,T]} \|\mathcal{F}(u(t))\|_{\mathcal{H}}$  is finite since  $\|\mathcal{F}(u(t))\|_{\mathcal{H}}$  is a continuous function. Now let

(3.34) 
$$III^*(\delta) := Me^{\omega T} \delta \times \sup_{t \in [0,T]} \|\mathcal{F}(u(t))\|_{\mathcal{H}}$$

and

(3.35) 
$$III^{**}(N) := Me^{\omega T} \int_0^T \|\mathcal{F}(u_N(s)) - \mathcal{F}(u(s))\|_{\mathcal{H}} \, \mathrm{d}s.$$

Clearly  $\lim_{\delta\to 0^+} \mathrm{III}^*(\delta) = 0$ . Also from (3.19) we have that  $\lim_{N\to\infty} \mathrm{III}^{**}(N) = 0$ . Thus,

(3.36) 
$$||u_N(t_0) - u_N(t_1)||_{\mathcal{H}} \le I(\delta, N) + III(\delta, N) + III(\delta, N)$$

$$\le [I^*(\delta) + III^*(\delta)] + [I^{**}(N) + III^{**}(N) + III^{**}(N)].$$

Let  $\epsilon > 0$ . We wish to choose  $\delta > 0$  such that  $||u_n(t) - u_n(t')||_{\mathcal{H}} < \epsilon$  for any  $n \in \mathbb{N}_0$  and  $t, t' \in [0, T]$  with  $|t - t'| < \delta$ . Choosing  $\delta^*$  small enough so that  $I^*(\delta^*) + III^*(\delta^*) + III^*(\delta^*) < \epsilon/2$  and N large enough such that  $I^{**}(N) + III^{**}(N) + III^{**}(N) < \epsilon/2$ , we get that

where  $|t-t'| < \delta^*$  and  $n \ge N$ . For each  $n \in \mathbb{N}_0$  that are less than N, we pick  $\delta_n > 0$  such that  $||u_n(t) - u_n(t')||_{\mathcal{H}} < \epsilon$  for  $|t-t'| < \delta_n$ . This is possible since  $u_n$  is uniformly continuous on [0,T]. Let  $\delta = \min\{\delta^*, \delta_0, \ldots, \delta_{N-1}\}$ . Then  $\delta$  satisfies the challenge from  $\epsilon$ . This proves uniform equicontinuity.

Theorem 3.5. For T > 0, we have that

(3.38) 
$$\lim_{N \to \infty} \sup_{t \in [0,T]} ||u_N(t) - u(t)||_{\mathcal{H}} = 0.$$

*Proof.* The above result follows directly from Theorem 3.3 and Theorem 3.4.

4. Uniform Convergence of Galerkin Solutions: System of DDEs case. Some points to be addressed:

\*\*\*\*\*\*\*\*\*

• Formulate a results about existence and regularity of solutions for the system of DDE (2.1).

## Appendix A. Proofs of preparatory Lemmas.

Proof of Proposition 2.2. We define for  $f \in L^2([-1,1],\mathbb{R})$  the following:

(A.1) 
$$a_n(f) := \frac{2n+1}{2} \int_{-1}^1 f(x) L_n(x) \, \mathrm{d}x.$$

It is easy to show based on (2.16) we have for  $\theta \in [-1, 1]$ 

$$|K_n(\theta)| \le (n^2 + 1)|L_n(\theta)| + \sum_{j=0}^{n-1} (2j+1)|L_j(\theta)|$$

$$\le (n^2 + 1) + \sum_{j=0}^{n-1} (2j+1)$$

$$= 2n^2 + 1,$$

i.e.,  $||K_n||_{\infty} \le 2n^2 + 1$ .

By the definition of  $\langle \cdot, \cdot \rangle_{\mathcal{E}}$  and the Koornwinder polynomials, we have that for  $n \in \mathbb{N}_0$ 

(A.3) 
$$\langle \psi, \mathcal{K}_n \rangle_{\mathcal{E}} = \frac{1}{2} \int_{-1}^1 f(x) K_n(x) \, \mathrm{d}x + f(1) \\ = \frac{1}{2} \left[ -\int_{-1}^1 f(x) (1+x) L'_n(x) \, \mathrm{d}x + (n^2+n+1) \int_{-1}^1 f(x) L_n(x) \, \mathrm{d}x \right] + f(1).$$

If we use integration by parts, we find that

(A.4) 
$$-\int_{-1}^{1} f(x)(1+x)L'_n(x) dx = -2f(1) + \int_{-1}^{1} f'(x)(1+x)L_n(x) dx + \int_{-1}^{1} f(x)L_n(x) dx.$$

Applying (A.4) to (A.3) gives that

(A.5) 
$$\langle \psi, \mathcal{K}_n \rangle_{\mathcal{E}} = \frac{1}{2} \int_{-1}^1 f'(x)(1+x)L_n(x) \, \mathrm{d}x + \frac{n^2+n+2}{2} \int_{-1}^1 f(x)L_n(x) \, \mathrm{d}x \\ = \frac{1}{2} \int_{-1}^1 f'(x)(1+x)L_n(x) \, \mathrm{d}x + \frac{n^2+n+2}{2n+1} a_n(f).$$

We can also note that by applying the Holder inequality we get

(A.6) 
$$\left| \int_{-1}^{1} f'(x)(1+x)L_n(x) \, \mathrm{d}x \right| \le \|f'\|_{\infty} \left( \int_{-1}^{1} (1+x) \, \mathrm{d}x \right)^{1/2} \|L_n\|_{L^2} \\ = \frac{4\|f'\|_{\infty}}{\sqrt{6n+3}}.$$

Furthermore, from [6, Thm. 2.1] we have

(A.7) 
$$|a_n(f)| \le \frac{V_1}{n - \frac{1}{2}} \sqrt{\frac{\pi}{2n}}$$

where  $V_1 := \int_{-1}^{1} \frac{f''(x)}{\sqrt{1-x^2}} dx < \infty$ . Thus,

(A.8) 
$$|\langle \psi, \mathcal{K}_n \rangle_{\mathcal{H}}| \leq \frac{2||f'||_{\infty}}{\sqrt{6n+3}} + V_1 \sqrt{2\pi} \frac{n^2 + n + 2}{\sqrt{n}(4n^2 + 1)},$$

and so

(A.9) 
$$\frac{|\langle \psi, \mathcal{K}_n \rangle_{\mathcal{H}}|}{\|\mathcal{K}_n\|_{\mathcal{H}}^2} \|K_n\|_{\infty} \leq \left[ \frac{2\|f'\|_{\infty}}{\sqrt{6n+3}} + V_1 \sqrt{2\pi} \frac{n^2 + n + 2}{\sqrt{n}(4n^2 + 1)} \right] \times \left[ \frac{(2n+1)(2n^2 + 1)}{(n^2 + 1)((n+1)^2 + 1)} \right] \\
= O\left(\frac{1}{n^{3/2}}\right).$$

By the Weierstrass M-test, the series (2.22) converges uniformly.

Note also that (2.22) is simply the functional part of the Koornwinder expansion of  $\psi$  in  $\mathcal{H}$ . So the series converges in  $L^2([-1,1];\mathbb{R})$  to  $\psi^D = f$ . Therefore, since the series converges uniformly, it must converge uniformly to f.

Proof of Lemma 2.1. Using (2.16), we can show that for  $m \leq N \in \mathbb{N}_0$ 

(A.10) 
$$\int_{-1}^{1} S_{N}(x) L_{m}(x) dx = \sum_{n=0}^{N} \frac{1}{\|\mathcal{K}_{n}\|_{\mathcal{E}}^{2}} \int_{-1}^{1} K_{n}(x) L_{m}(x) dx$$
$$= \|L_{m}\|_{L^{2}([-1,1])}^{2} \left[ (m^{2} + 1) \frac{1}{\|\mathcal{K}_{m}\|_{\mathcal{E}}^{2}} - (2m + 1) \sum_{k=m+1}^{N} \frac{1}{\|\mathcal{K}_{k}\|_{\mathcal{E}}^{2}} \right],$$

and so

(A.11) 
$$S_N(x) = \sum_{n=0}^N \left[ \frac{n^2 + 1}{\|\mathcal{K}_n\|_{\mathcal{E}}^2} - (2n+1) \sum_{m=n+1}^N \frac{1}{\|\mathcal{K}_m\|_{\mathcal{E}}^2} \right] L_n(x).$$

It is easy to show that

(A.12) 
$$\sum_{n=0}^{N} \frac{1}{\|\mathcal{K}_n\|_{\mathcal{E}}^2} = \sum_{n=0}^{N} \frac{2n+1}{(n^2+1)((n+1)^2+1)}$$
$$= \sum_{n=0}^{N} \left[ \frac{1}{n^2+1} - \frac{1}{(n+1)^2+1} \right]$$
$$= 1 - \frac{1}{(N+1)^2+1}$$

and

(A.13) 
$$\sum_{m=n+1}^{N} \frac{1}{\|\mathcal{K}_m\|_{\mathcal{E}}^2} = \sum_{m=0}^{N} \frac{1}{\|\mathcal{K}_m\|_{\mathcal{E}}^2} - \sum_{m=0}^{n} \frac{1}{\|\mathcal{K}_m\|_{\mathcal{E}}^2} = \frac{1}{(n+1)^2 + 1} - \frac{1}{(N+1)^2 + 1}.$$

Applying (A.13) to (A.11) gives

$$S_N(x) = \sum_{n=0}^N \left[ \frac{n^2 + 1}{\|\mathcal{K}_n\|_{\mathcal{E}}^2} - (2n+1) \left( \frac{1}{(n+1)^2 + 1} - \frac{1}{(N+1)^2 + 1} \right) \right] L_n(x)$$

$$= \sum_{n=0}^N \left[ \frac{2n+1}{(n+1)^2 + 1} - \frac{2n+1}{(n+1)^2 + 1} + \frac{2n+1}{(N+1)^2 + 1} \right] L_n(x)$$

$$= \sum_{n=0}^N \frac{2n+1}{(N+1)^2 + 1} L_n(x).$$

It is known that

$$(A.15) |L_n(x)| \le 1, \quad \forall x \in [-1, 1], \ \forall n \in \mathbb{N}_0.$$

Thus for  $x \in [-1, 1]$  and  $N \in \mathbb{N}_0$ 

$$|S_N(x)| \le \frac{1}{(N+1)^2 + 1} \sum_{n=0}^N (2n+1)|L_n(x)|$$

$$\le \frac{1}{(N+1)^2 + 1} \sum_{n=0}^N (2n+1)$$

$$= \frac{N^2 + 1}{(N+1)^2 + 1}$$

$$< 1.$$

From [5, Thm. 61], we also have that for  $n \ge 1$  and  $x \in (-1, 1)$ 

(A.17) 
$$|L_n(x)| < \sqrt{\frac{\pi}{2n(1-x^2)}}.$$

Then for  $x \in (-1,1)$  and  $N \in \mathbb{N}_0$ 

$$|S_N(x)| \le \frac{1}{(N+1)^2 + 1} \left[ 1 + \sum_{n=1}^N (2n+1)|L_n(x)| \right]$$

$$\le \frac{1}{(N+1)^2 + 1} \left[ 1 + 3\sum_{n=1}^N n \cdot \sqrt{\frac{\pi}{2n(1-x^2)}} \right]$$

$$= \frac{1}{(N+1)^2 + 1} \left[ 1 + 3 \cdot \sqrt{\frac{\pi}{2(1-x^2)}} \cdot \sum_{n=1}^N \sqrt{n} \right].$$

We can note that

(A.19) 
$$\sum_{n=1}^{N} \sqrt{n} \le \int_{1}^{N+1} \sqrt{x} \, \mathrm{d}x = \frac{2}{3} (N+1)^{3/2} - \frac{2}{3}.$$

So

(A.20) 
$$|S_N(x)| \le \frac{1}{(N+1)^2 + 1} \left[ 1 + \sqrt{\frac{2\pi}{1-x^2}} \left( (N+1)^{3/2} - 1 \right) \right],$$

where the right-hand side converges to 0 as  $N \to \infty$  for fixed  $x \in (-1,1)$ . Thus  $S_N(x) \to 0$  as  $N \to \infty$  for  $x \in (-1,1)$ .

#### REFERENCES

- M. D. CHEKROUN, M. GHIL, H. LIU, AND S. WANG, Low-dimensional galerkin approximations of nonlinear delay differential equations, Discrete and Continuous Dynamical Systems, 36 (2016), pp. 4133–4177.
- R. F. Curtain, H. Zwart, and Springerlink, An Introduction to Infinite-Dimensional Linear Systems Theory, vol. 21, Springer New York, New York, NY, 1 ed., 1995, https://doi.org/10.1007/978-1-4612-4224-6.
- [3] T. H. KOORNWINDER, Orthogonal polynomials with weight function  $(1-x)^{\alpha}(1+x)^{\beta} + M\delta(x+1) + N\delta(x-1)$ , Canadian mathematical bulletin, 27 (1984), pp. 205–214.
- [4] A. PAZY, Semigroups of linear operators and applications to partial differential equations, vol. 44;44.;, Springer-Verlag, New York, 1983.
- [5] E. D. RAINVILLE, Special functions, Macmillan, New York, 1971.
- [6] H. Wang and S. Xiang, On the convergence rates of legendre approximation, Mathematics of Computation, 81 (2012), pp. 861–877.