#### **Bubble Sort and Quick-sort**

**EECS 233** 

## Recap

- □ Method 1: Selection Sort
  - > For each position of an array, find the element for it
  - O(n²) comparisons, O(n) moves

0	1	2	3	4	5	6
2	4	7	21	25	10	17

- Method 2: Insertion Sort
  - For each element, find a position to insert it
  - $\triangleright$  O(n<sup>2</sup>) comparisons, O(n<sup>2</sup>) moves
  - O(n) if the array is sorted or nearly sorted

0	1	2	3	4
6	14	19	9	

- □ Method 3: Shell Sort
  - Based on the observation that insertion sort requires O(n) running time for sorted or nearly sorted array
  - Generalization of insertion sort with larger "jumps", using strides larger than 1 (for insertion sort, the stride = 1)
  - Use a decreasing sequence of strides

0								
99	8	13	2	15	9	4	12	<b>24</b>

#### **Method 4: Bubble Sort**

- Perform a sequence of passes through the array.
- On each pass: proceed from left to right, swapping adjacent elements if they are out of order. Larger elements "bubble up" to the end of the array.
- ☐ At the end of the kth pass, the k rightmost elements are in their final positions.
- □ Example:

0	1	2	3
28	24	27	18

#### Implementation of Bubble Sort

```
static void bubbleSort(int[] arr) {
                                                                           3
    for (int i = arr.length - 1; i > 0; i--) {
                                                      28
                                                             24
                                                                   27
                                                                          18
         for (int j = 0; j < i; j++) {
              if (arr[j] > arr[j+1])
                                                      24
                                                             27
                                                                   18
                                                                          28
                swap(arr, j, j+1);
                                                             18
                                                                          28
                                                      24
                                                             24
                                                      18
                                                                          28
```

- The inner loop performs a single pass
- The outer loop governs the number of passes, and the ending point of each pass

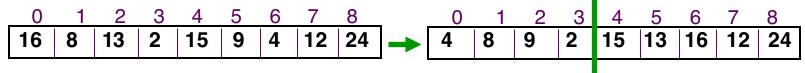
# **Running Time Analysis**

```
0
                3
28
     24
          27
               18
24
     27
          18
                28
24
     18
                28
18
     24
                28
```

- Number of comparisons
  - the k-th pass performs n-k comparisons, k=1,2,...,n-1
  - > so we get  $C(n) = (n-1) + (n-2) + ... + 1 = n^2/2 n/2 = O(n^2)$
- Moves: depends on the contents of the array
  - in the worst case: the array is in reverse order, and every comparison leads to a swap (3 moves), so  $M(n) = \frac{3C(n) = O(n^2)}{3C(n)}$
  - in the best case: the array is already sorted, and no moves are needed
  - Average: 50% chance a comparison leads to a swap
- $\square$  Total running time:  $O(n^2)$ 
  - $\triangleright$  C(n) is always  $O(n^2)$ , M(n) is never worse than  $O(n^2)$ .

#### **Method 5: Quick-Sort**

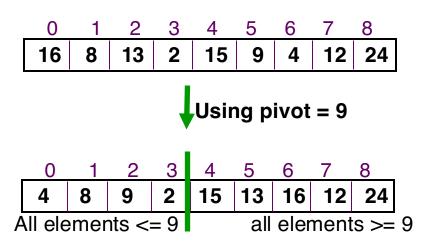
- Like bubble sort, quick-sort uses an approach based on exchanging out-of-place elements, but it's more efficient. Analogy:
  - Insertion sort to Shell sort: jump faster
  - Bubble sort to quick sort: bubble faster
- ☐ A divide-and-conquer method:
  - divide: rearrange the elements so that we end up with two sub-arrays such that: each element in the left array <= each element in the right array</p>
    - example:



- conquer: sort both sub-arrays (apply quick-sort recursively to the sub-arrays, stopping when a sub-array has a single element)
- combine: nothing needs to be done, because of the criterion used in forming the subarrays

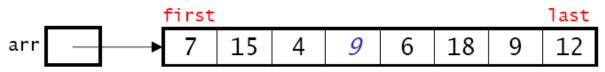
# **Partitioning An Array**

- The process that quick-sort uses to rearrange the elements is known as partitioning the array.
- Pick a value known as the *pivot*; rearrange the elements to produce two subarrays:
  - left subarray: all values <= pivot</p>
  - right subarray: all values >= pivot

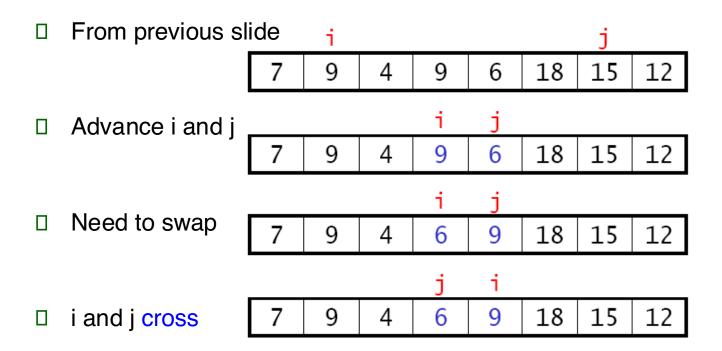


# **An Example of Partitioning An Array**

#### Pivot = middle element



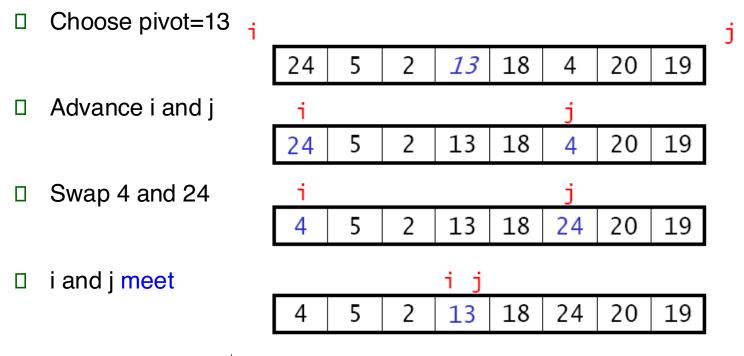
## **Partitioning An Array**



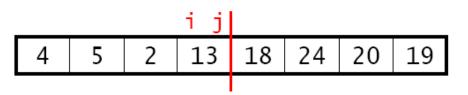
☐ Return j, indicating two subarrays: arr[first : j] and arr[j+1 : last]

first			j	i			last
7	9	4	6	9	18	15	12

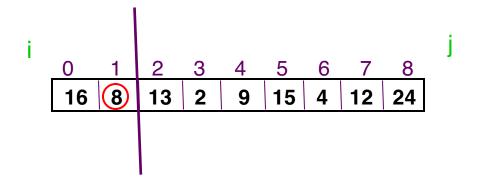
#### **Another Example**



☐ Return j and we have two subarrays: arr[first : j] and arr[j+1 : last]



#### An exercise



#### Implementation of Quick-Sort

```
static void quickSort(int[] arr) {
    myQuickSort(arr, 0, arr.length - 1);
static void myQuickSort(int[] arr, int first, int last) {
     if (first >= last) return;
    int split = partition(arr, first, last);
```

- quickSort() is the method provided by the Sort class, which calls a recursive method myQuickSort
- The recursive method myQuickSort() stops when the subarray size is 1

## Implementation of Quick-Sort

The helper method partition() static int partition(int[] arr, int first, int last) int pivot = arr[(first + last)/2]; int i = first - 1; // index going from left to right int j = last + 1; // index going from right to left while (true) {

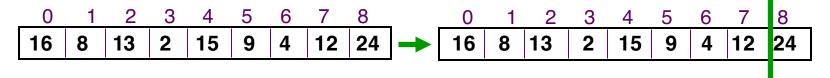
## Implementation of Quick-Sort

☐ The helper method partition()

```
static int partition(int[] arr, int first, int last)
     int pivot = arr[(first + last)/2];
     int i = first - 1; // index going from left to right
     int j = last + 1; // index going from right to left
     while (true) {
           do {
                İ++;
          } while (arr[i] < pivot);</pre>
          do {
          } while (arr[j] > pivot);
          if (i < j)
                swap(arr, i, j);
          else
                return j; // arr[j] = end of left array
```

# **Choosing Pivot Values (for Partitioning)**

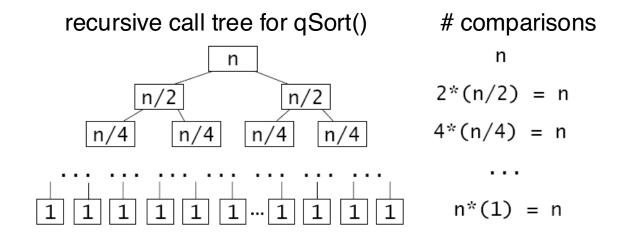
- □ First element or last element
  - risky, can lead to terrible worst-case behavior
  - especially poor if the array is almost sorted



- ☐ Middle element (good if the array is sorted)
- Randomly chosen element
- Median of three elements: to decrease the probability of getting a poor pivot
  - left, center, and right elements
  - three randomly selected elements

# **Running Time Analysis - Best Case**

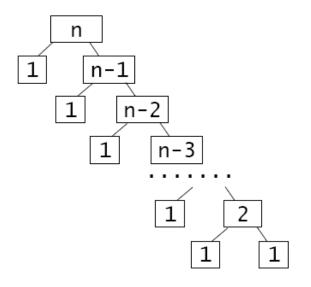
- Partitioning an array requires n comparisons, because each element is compared with the pivot.
- best case: partitioning always divides the array in half



- > at each level of the call tree, we perform n comparisons
- > There are  $log_2 n$  levels in the tree. So  $C(n) = nlog_2 n = O(nlog n)$
- Similarly, M(n) and running time are both O(nlog n)

# **Running Time Analysis - Worst Case**

- □ Worst case: pivot is always the smallest or largest element one subarray has 1 element, the other has n 1
  - call tree for qSort



# comparisons

n
$$1 + (n-1) = n$$

$$1 + (n-2) = n-1$$

$$1 + (n-3) = n-2$$

$$...$$

$$1 + 2 = 3$$

$$1 + 1 = 2$$

- $\triangleright$  C(n) is on the order of O(n<sup>2</sup>). What is M(n)?
- ☐ Average case: is harder to analyze. C(n) is still O(nlog n)