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 % ENGR 130 Module 6.1 Report
 % Section E
 % November 16th, 2023

1. Report your group's filled in Table 1, Table 2, Table 3, and Table 4.

Table 1: Open Loop Control

Final Value (RPM)	Max Overshoot %	Rise Time (t_r)	Settling Time (t_s)
499.9935	25.5822 %	0.9836 s	5.4098 s

Table 2: P Control

P	Final Value (RPM)	Max Overshoot %	Rise Time (t_r)	Settling Time (t_s)
20	952.3930	67.7767	.2740	5
40	975.6128	75.7923	.1471	5.0490
60	983.6038	79.7028	.1207	5.3119
80	987.6655	82.1372	.1047	5.3054
100	990.0873	83.8530	.0938	5.0938

Table 4: D Control

D	Final Value (RPM)	Max Overshoot %	Rise Time (t_r)	Settling Time (t_s)
4	975.6098	32.0994	0.1799	1.1511
8	975.6098	16.5723	0.1615	0.6862
12	975.6098	9.7556	0.1267	0.5987
16	975.6098	6.3302	0.1099	0.4525
20	975.6098	4.4554	0.0874	0.1166

Table 3: I Control

I	Final Value (RPM)	Max Overshoot %	Rise Time (t_r)	Settling Time (t_s)
4	996.8911	2.3699	0.0971	0.1311
8	999.6897	2.2291	0.0970	0.1310
12	999.9783	2.3477	0.0969	0.1309
16	999.9992	2.4959	0.0969	0.1308
20	1000	2.6483	0.0968	0.1307

2. What waveform characteristic does the P gain of the controller affect most?

- The waveform characteristic that the P gain of the controller affects the most is max overshoot and rise time. These characteristics have the most significant change with the increase of P.

3. How does the D gain help the controller achieve our goal?

- D helps to calculate how much is left before reaching the goal value which helps it slow down as it approaches to decrease the overshoot and the settling time.

4. What was your deviation from the setpoint without the I gain? Is it beneficial to use the I gain in this scenario?

- The deviation from the setpoint was about 25 RPM without I, so it is beneficial to use the I gain in this scenario.

5. Can you think of any other devices where a PID controller is critical to use?

- PID controller devices like heaters for your house would be a beneficial use of a control system that can adapt and recognize change in the environment. A heater with an adaptive thermostat would be able to keep the house at a proper temperature while only using the optimal amount of energy to do so.

	ENGR 130 Module Planning		Module	6	Section	E	Team	1	
			Scheduled		Actual				
#	Task	Deadline	Start	End	Start	End	Primary	Secondary	% Complete
	Type teams code for Lab 1	11/14	11/14	11/14	11/14	11/14	Karis	Lily	100
	Write algorithm for Lab 1	11/14	11/14	11/14	11/14	11/14	Trevor	Jack, Lily	100
	Double check function	11/14	11/14	11/14	11/14	11/14	Trevor	All	100
	Fill out table 1	11/14	11/14	11/14	11/14	11/14	Karis	n/a	100
	Type teams code for Lab 2	11/16	11/16	11/16	11/16	11/16	Trevor	Karis	100
	Fill out table 2	11/16	11/16	11/16	11/16	11/16	Jack	Trevor	100
	Fill out table 3	11/16	11/16	11/16	11/16	11/16	Karis	Trevor	100
	Fill out table 4	11/16	11/16	11/16	11/16	11/16	Lily	Trevor	100
	Test electrical componets	11/16	11/16	11/16	11/16	11/16	Trevor	Jack	100
	Build circuit for lab 2	11/16	11/16	11/16	11/16	11/16	Lily	Jack	100
	Discuss Lab 2 Questions	11/19	11/16	11/19	11/16	11/16	Jack	Lily	100
	Type teams responses for Lab 2	11/19	11/16	11/19	11/16	11/16	Lily	Jack	100
	Assemble Module 6 Part 1 Report	11/20	11/19	11/20	11/16	11/16	Trevor	n/a	100
	Proofread Module 6 Part 1 Report	11/20	11/19	11/20	11/16	11/16	All	n/a	100
	Submit Module 6 Part 1 Report	11/20	11/19	11/20	11/16	11/16	Trevor	n/a	100
	Build the circuit for Lab 3	12/4	11/28	11/28			Jack	Lily	0
	Use the oscilloscope with the circuit	12/4	11/28	11/28			Karis	Trevor	0
	Calibrate the Infared Sensor	12/4	11/28	11/28			Trevor	Karis	0
	Build the Puck Levitation System	12/4	11/28	11/28			Lily	Jack	0
	Control the Puck manually	12/4	11/28	11/28			Trevor	all	0
	Type code for Lab 3	12/4	11/28	11/28			Lily	Karis	0
	Discuss Lab 3 Questions	12/4	11/28	11/30			all	n/a	0
	Type Responses for Lab 3	12/4	11/28	11/30			all	n/a	0
	Type Code for Lab 4	12/4	11/30	11/30			Karis	Jack	0
	Use Oscilloscope for Lab 4	12/4	11/30	11/30			Trevor	Karis	0
	Discuss Lab 4 Questions	12/4	11/30	12/2			Lily	Trevor	0
	Type teams responses for Lab 4	12/4	11/30	12/2			all	n/a	0
	Assemble Module 6 Part 2 Report	12/4	12/2	12/2			Karis	all	0
	Proofread Module 6 Part 2 Report	12/4	12/2	12/3			all	n/a	0
	Submit Module 6 Part 2 Report	12/4	12/2	12/3			Trevor	n/a	0
			Last Updated						
			Jack	11/16					