

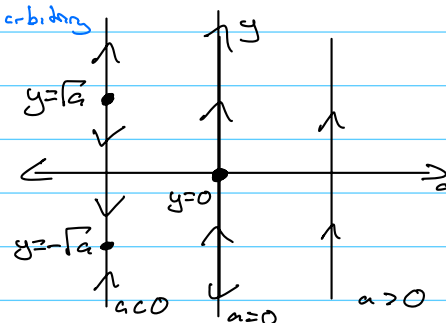
# Section 1.7: 1, 3, 5, 9, 13, 19

1.  $\frac{dy}{dt} = y^2 + a$  For these problems, the y-axis is orbiting

$$y^2 + a = 0 \quad y = \frac{0 \pm \sqrt{-4a}}{2} = \frac{\pm \sqrt{-4a}}{2} = \frac{\pm (2)\sqrt{-a}}{2} = \pm \sqrt{-a}$$

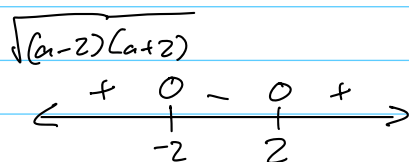
$\sqrt{-a}$ :  $a = 0 \rightarrow 1 \text{ eq.}$   
 $a < 0 \rightarrow 2 \text{ eq.}$   
 $a > 0 \rightarrow \text{no eq.}$

$y^2 = 0 \rightarrow y = 0$   
 $y^2 - 4 = (y+2)(y-2)$   
 $y^2 + 4 \rightarrow \text{none}$

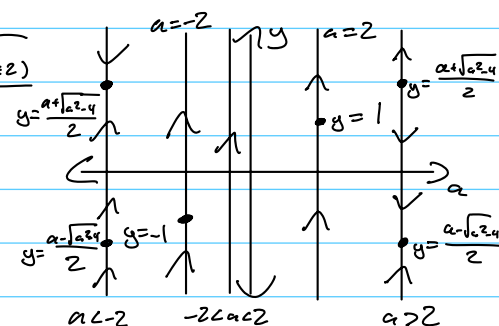


3.  $\frac{dy}{dt} = y^2 - ay + 1$

$$y^2 - ay + 1 = 0 \quad y = \frac{a \pm \sqrt{a^2 - 4}}{2} = \frac{a \pm \sqrt{(a-2)(a+2)}}{2}$$

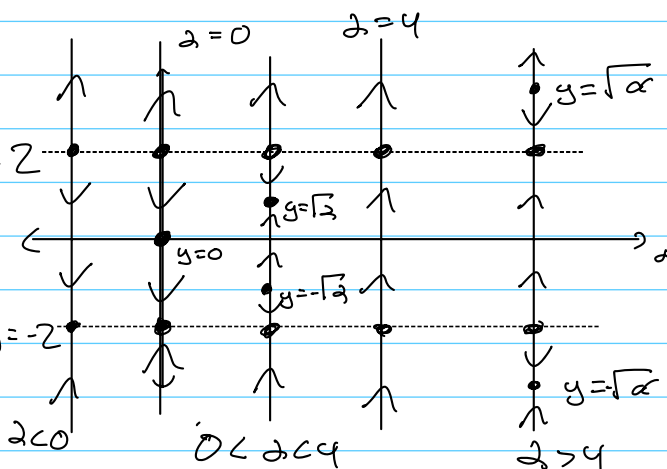


$a > 2$  or  $a < -2 \rightarrow 2 \text{ eq.}$   
 $a = 2$  or  $a = -2 \rightarrow 1 \text{ eq.}$   
 $-2 < a < 2 \rightarrow \text{no eq.}$



5.  $\frac{dy}{dt} = (y^2 - d)(y^2 - 4)$

$\sqrt{d}$ :  $d = 4 \rightarrow 2 \text{ eq.}$   $y = 2$   
 $d > 4 \rightarrow 4 \text{ eq.}$   
 $0 < d < 4 \rightarrow 4 \text{ eq.}$   
 $d = 0 \rightarrow 3 \text{ eq.}$   $y = -2$   
 $d < 0 \rightarrow 2 \text{ eq.}$



4.  $\frac{dy}{dt} = \sin(y) + d$  over  $[-\pi, \pi]$

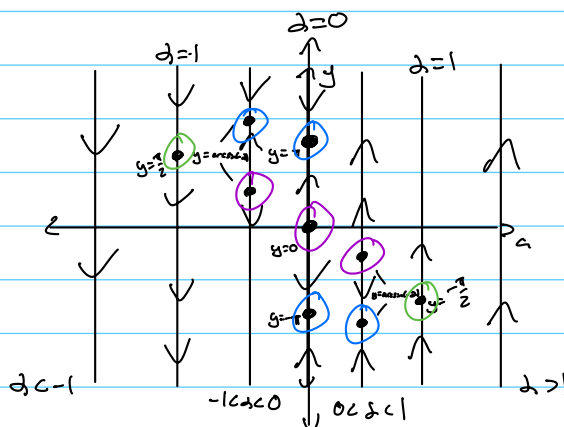
$0 = \sin(y) + d$

$d$ :  $d = 0 \rightarrow 3 \text{ eq. points}$

$d = \pm 1 \rightarrow 1 \text{ eq. point}$

$d > 1$  or  $d < -1 \rightarrow \text{none}$

$0 < d < 1$  or  $-1 < d < 0 \rightarrow 2$



• Nodes in blue

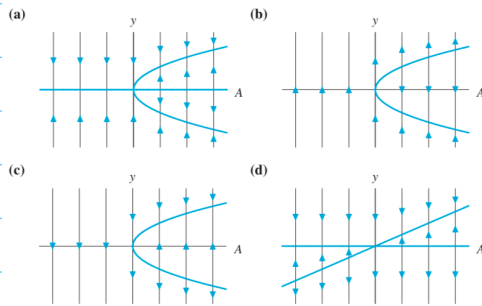
• Sinks in green

• Sources in purple

B. Direction vector  $d \in [-1, 1]$

13.

$$\begin{array}{lll} \text{(i)} \quad \frac{dy}{dt} = Ay - y^2 & \text{(ii)} \quad \frac{dy}{dt} = A + y^2 & \text{(iii)} \quad \frac{dy}{dt} = Ay - y^3 \\ \text{(iv)} \quad \frac{dy}{dt} = A - y^2 & \text{(v)} \quad \frac{dy}{dt} = y^2 - A & \text{(vi)} \quad \frac{dy}{dt} = Ay + y^2 \end{array}$$



i) cannot be A or B as its  $A=0$  derivative is always negative. when  $A < 0$ ,  $-1-y^2 \rightarrow -y(y+1) \rightarrow y=0$  and  $y=-1$

**d** must be the solution due to the above

ii) must be **b** as  $A=0$  is always positive

iii) must be **a** as  $A=0$  has different behavior around 0.

iv) must be **c** for the same reason as ii. It must follow similar behavior as well.

v) must be **b** for the same reason as ii and iii.

vii)  $\frac{dy}{dt} = Ay + y^2 \rightarrow \frac{dy}{dt} = y(y+A)$  must be **b** as derivative always positive for  $A=0$

$$19. \frac{dP}{dt} = 2P - \frac{P^2}{50} - 3l$$

where  $l$  is the # of licences issued

$$a) P = \frac{-2 \pm \sqrt{4 - 4(-\frac{1}{50})(-3l)}}{-\frac{2}{50}}$$

$$\sqrt{4 - \frac{2}{25}(3l)} > 0$$

$$-\frac{6l}{25} > -4$$

$$6l < 100 \quad l < 16.67$$

Need equilibrium points for population.

17 licences too much. Max is 16.

$$b) l = 16$$

$$\left( \frac{dP}{dt} = 2P - \frac{P^2}{50} - 48 \right) \times 50$$

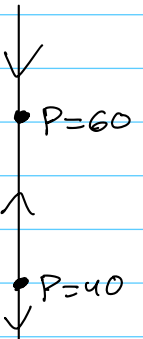
$$\frac{dP}{dt} = -P^2 + 100P - 2400$$

$$= -(P^2 - 100P + 2400)$$

$$= -(P-60)(P-40)$$

Initial  $> 60 \rightarrow$  decrease to 60. Initial  $(40, 60)$

increase to 60. Initial  $< 40 \rightarrow$  decrease to 0.



c) It can be concluded that the fish population should be fine as long as the total population is well above 40 fish. If it is too close the amount of catches combined with the random environmental changes could possibly lead to extinction. It may be wise to consider reducing licences so our model has a lower minimum equilibrium point to counteract environmental factors.

Section 1.8: 3, 9, 11, 21, 25

$$3. \quad \frac{dy}{dt} = -3y + 4\cos 2t \quad (\text{NH}) \quad \left| \quad \frac{dy}{dt} = -3y \quad (\text{H}) \right.$$

$$y_h(t): \quad y_h(t) = K e^{\int a(t) dt}, K \in \mathbb{R} \Rightarrow y_h(t) = K e^{-3t}$$

$$y_p(t): \quad \text{Guess} \quad y_p(t) = A \cos(2t) + B \sin(2t)$$

$$y_p'(t) = -2A \sin(2t) + 2B \cos(2t)$$

$$\therefore -2A \sin(2t) + 2B \cos(2t) = -3A \cos(2t) - 3B \sin(2t) + 4 \cos(2t)$$

$$-2A = -3B$$

$$\text{Solve system: } A = \frac{3B}{2}$$

$$2B = -3A + 4$$

$$2B = -3\left(\frac{3B}{2}\right) + 4$$

$$2B = -\frac{9B}{2} + 4$$

$$\frac{13B}{2} = 4 \Rightarrow B = \frac{8}{13} \quad \text{and} \quad A = \frac{24}{26} = \frac{12}{13}$$

$$y_p(t) = \frac{8}{13} \cos(2t) + \frac{12}{13} \sin(2t)$$

$$\therefore \text{general solution} = y_h(t) + y_p(t)$$

$$y(t) = K e^{-3t} + \frac{12}{13} \cos(2t) + \frac{8}{13} \sin(2t)$$

$$9. \quad \frac{dy}{dt} + y = \cos 2t, y(0) = 5 \quad (\text{NH}) \quad \frac{dy}{dt} = -y + \cos(2t) \quad (\text{H}) \quad \frac{dy}{dt} = -y$$

$$y_h(t) = K e^{\int -1 dt} \Rightarrow y_h(t) = K e^{-t}$$

$$y_p(t): \quad \text{Guess} \quad y_p(t) = A \cos(2t) + B \sin(2t)$$

$$y_p'(t) = -2A \sin(2t) + 2B \cos(2t)$$

$$\therefore -2A \sin(2t) + 2B \cos(2t) = -A \cos(2t) - B \sin(2t) + \cos(2t)$$

$$-2A = -B$$

$$\text{Solve system: } A = \frac{1}{2} B$$

$$2B = -A + 1$$

$$2B = -\frac{1}{2} B + 1$$

$$\frac{5}{2} B = 1 \Rightarrow B = \frac{2}{5}, A = \frac{1}{5}$$

$$y_p(t) = \frac{1}{5} \cos(2t) + \frac{2}{5} \sin(2t)$$

$$\therefore \text{general solution} = y_h(t) + y_p(t)$$

$$y(t) = K e^{-t} + \frac{1}{5} \cos(2t) + \frac{2}{5} \sin(2t)$$

$$(\text{VP: } 5 = K e^0 + \frac{1}{5} \cos 0 + \frac{2}{5} \sin 0$$

$$5 = K + \frac{1}{5} \quad K = \frac{24}{5}$$

$$\therefore y(t) = \frac{24}{5} e^{-t} + \frac{1}{5} \cos(2t) + \frac{2}{5} \sin(2t)$$

$$11. \frac{dy}{dt} - 2y = 7e^{2t}, y(0) = 3 \quad (NH) \frac{dy}{dt} = 2y + 7e^{2t} \quad (H) \frac{dy}{dt} = 2y$$

$$y_h(t): y_h(t) = Ke^{2t} = Ke^{2t}$$

$$y_p(t): y_p(t) = Ce^{2t}$$

$$y_p'(t) = 2Ce^{2t}$$

$$2Ce^{2t} = 2Ce^{2t} + 7e^{2t} \text{ nope!}$$

add t factor

$$y_p(t) = tCe^{2t}$$

$$y_p'(t) = 2tCe^{2t} + Ce^{2t}$$

$$2tCe^{2t} + Ce^{2t} = 2tCe^{2t} + 7e^{2t}$$

$$2 \cdot C = 2 \cdot C$$

$$C = 7$$

$$y_p(t) = 7te^{2t} \Rightarrow y(t) = Ke^{2t} + 7te^{2t}$$

$$IVP: 3 = Ke^0 + 7(0)e^0$$

$$K = 3$$

$$\therefore y(t) = 3e^{2t} + 7te^{2t}$$

$$21. \frac{dy}{dt} + 2y = t^2 + 2t + 1 + e^{4t}, y(0) = 0$$

$$(NH) \frac{dy}{dt} = -2y + t^2 + 2t + 1 + e^{4t} \quad (H) \frac{dy}{dt} = -2y$$

$$y_h(t) = Ke^{-2t} = Ke^{-2t}$$

$$y_p(t): y_p(t) = at^2 + bt + c + de^{4t}$$

$$y_p'(t) = 2at + b + 4de^{4t}$$

$$2at + b + 4de^{4t} = -2at - 2bt - 2c - 2de^{4t} + t^2 + 2t + 1 + e^{4t}$$

$$2a = -2b + 2$$

$$b = -2c + 1$$

$$4d = -2d + 1$$

$$0 = -2a + 1$$

$$bd = 1 \Rightarrow d = \frac{1}{b}$$

$$2a = 1 \Rightarrow a = \frac{1}{2}$$

$$b = \frac{2a-2}{-2} \Rightarrow b = \frac{1}{2}$$

$$c = \frac{b-1}{2} = \frac{1}{4}$$

$$y_p(t) = \frac{1}{2}t^2 + \frac{1}{2}t + \frac{1}{4} + \frac{1}{6}e^{4t}$$

$$\text{general solution: } y = y_h + y_p$$

$$y(t) = Ke^{-2t} + \frac{1}{2}t^2 + \frac{1}{2}t + \frac{1}{4} + \frac{1}{6}e^{4t}$$

$$IVP: 0 = K + \frac{1}{4} + \frac{1}{6} \Rightarrow K = -\frac{5}{12} \therefore y(t) = -\frac{5}{12}e^{-2t} + \frac{1}{2}t^2 + \frac{1}{2}t + \frac{1}{4} + \frac{1}{6}e^{4t}$$

$$25. \frac{dy}{dt} + 2y = b(t) \text{ where } (-1 < b(t) < 2) \forall t$$

$$\text{Solve (H)} \frac{dy}{dt} + 2y = 0 \Rightarrow y' = -2y + b(t)$$

$$y_h(t) = Ke^{-2t} \Rightarrow y_h = Ke^{-2t}$$

$$y_p(t) + y_h(t) = y(t)$$

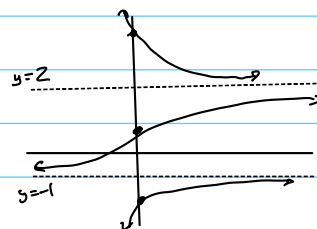
$$y(t) = Ke^{-2t} + y_p(t)$$

$$\text{If } y(0) = 4 \text{ then } \frac{dy}{dt} = -8 + (-1, 2) \text{ as } b(t) \text{ is bounded by } -1 \text{ and } 2.$$

• At  $y(0) > 2$  solution tends toward 2, upper limit of  $b$

• If  $-1 < y(0) < 2$  then  $t$  will tend towards 2 as  $t \rightarrow \infty$

• If  $y(0) < -1$  then solution tends towards -1.



# Section 1.9: 5, 9, 15, 19

$$5. \frac{dy}{dt} - \frac{2t}{1+t^2} y = 3$$

$$\mu(t) = e^{\int -\frac{2t}{1+t^2} dt} \quad \begin{matrix} y = 1+t^2 \\ \frac{dy}{dt} = 2t \end{matrix}$$

$$= e^{-\ln(1+t^2)} = \frac{1}{1+t^2}$$

$$\mu(t) = \frac{1}{1+t^2}$$

$$\frac{dy}{dt} \left( \frac{1}{1+t^2} \right) - \frac{2t}{(1+t^2)^2} y = \frac{3}{1+t^2}$$

$$\int \left( y \cdot \frac{1}{1+t^2} \right)' = \int \frac{3}{1+t^2}$$

$$\frac{y}{1+t^2} = 3 \tan^{-1}(t) + C$$

$$\therefore y = (1+t^2)(3 \tan^{-1}(t) + C)$$

$$4. \frac{dy}{dt} + \frac{y}{t} = 2, \quad y(1) = 3$$

$$\mu(t) = e^{\int \frac{1}{t} dt}$$

$$\mu(t) = e^{\ln t} = t$$

$$\frac{dy}{dt}(t) + \frac{y}{t} = 2t$$

$$\int (y \cdot t)' = \int 2t$$

$$y \cdot t = t^2 + C$$

$$y = t + \frac{C}{t}$$

$$3 = 1 + \frac{C}{1} \Rightarrow C = 2$$

$$y = t + \frac{2}{t}$$

$$15. \frac{dy}{dt} = \frac{y}{t^2} + 4 \cos t$$

$$\frac{dy}{dt} - \frac{y}{t^2} = 4 \cos t$$

$$\mu(t) = e^{-\int \frac{1}{t^2} dt} = e^{\frac{1}{t}}$$

$$\frac{dy}{dt} e^{\frac{1}{t}} - \frac{y}{t^2} e^{\frac{1}{t}} = 4 e^{\frac{1}{t}} \cos t$$

$$\int (y \cdot e^{\frac{1}{t}})' = \int 4 e^{\frac{1}{t}} \cos t$$

$$y \cdot e^{\frac{1}{t}} = \int 4 e^{\frac{1}{t}} \cos t dt$$

$$\therefore y = 4 e^{-\frac{1}{t}} \int e^{\frac{1}{t}} \cos t dt + C \quad \text{b. back into } \int$$

$$14. \frac{dy}{dt} = a t y + 4 e^{-t^2}$$

$$\frac{dy}{dt} - a t y = 4 e^{-t^2}$$

$$\mu(t) = e^{-\int a t dt} = e^{-\frac{a t^2}{2}}$$

$$\frac{dy}{dt} e^{-\frac{a t^2}{2}} - a t y e^{-\frac{a t^2}{2}} = 4 e^{-t^2} e^{-\frac{a t^2}{2}}$$

$$\int (y \cdot e^{-\frac{a t^2}{2}})' = \int 4 e^{-t^2 - \frac{a t^2}{2}}$$

$$y \cdot e^{-\frac{a t^2}{2}} = 4 \int e^{-t^2 - \frac{a t^2}{2}} dt$$

$$\text{No integrals req'd: } -t^2 - \frac{a t^2}{2} = 0$$

$$\frac{a}{2} = -1$$

$$a = -2$$

$$a = -2 \text{ eliminates integral solution}$$