Notes

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Contents

1	The type theory 1.1 UIP Layer	
2	Equational Theory	2
3	Algorithmic Definitions	2

1 The type theory

The type theory is a two-level type theory, meaning it contains two notions of equality.

1.1 UIP Layer

1.2 Cubical Layer

The cubical type theory is parameterized by a rich cofibration logic with the interval structure being that of a distributive lattice.

cofibration specification \dots

Definition 1.1. Partial types are defined by the following rules:

$$\begin{split} &\frac{\Gamma \vdash \mathbf{A} : \mathcal{U}_l}{\Gamma \vdash [\alpha] \to A} \text{ form } &\frac{\Gamma, \alpha \vdash a : A}{\Gamma \vdash \text{in}_{\psi}(f) : [\alpha] \to \mathbf{A}} \text{ intro} \\ &\frac{\Gamma \vdash f : [\alpha] \to A}{\Gamma \vdash \text{out}_{\psi}(f) : A} \text{ elim } &\frac{\Gamma \vdash f : [\alpha] \to \mathbf{A}}{\Gamma \vdash \text{out}_{\psi}(f) \equiv a} \text{ comp} \end{split}$$

Definition 1.2. Extension types are defined by the following rules:

$$\frac{\Gamma \vdash A : \mathcal{U}_l \qquad \Gamma \vdash \psi \operatorname{\mathbf{cof}} \qquad \Gamma \vdash t : [\psi] \to A}{\Gamma \vdash A[\psi \to t]} \text{ form}$$

$$\frac{\Gamma \vdash a : \mathbf{A} \qquad \Gamma \vdash \psi \ \mathbf{cof} \qquad \Gamma, \psi \vdash t : \mathbf{A} \qquad \Gamma, \psi \vdash t \equiv a}{\Gamma \vdash \mathrm{in}_{\psi}(a) : \mathbf{A}[\psi \to t]} \ \mathrm{intro}$$

$$\frac{\Gamma \vdash a : \mathbf{A}[\psi \to t]}{\Gamma \vdash \mathrm{out}_{\psi}(a) : \mathbf{A}} \ \mathrm{elim} \quad \frac{\Gamma \vdash a : A[\psi \to t] \qquad \Gamma \vdash \psi}{\Gamma \vdash \mathrm{out}_{\psi}(a) \equiv t} \ \mathrm{comp1} \quad \frac{\Gamma \vdash a : A}{\Gamma \vdash \mathrm{out}_{\psi}(\mathrm{in}_{\psi}(a)) \equiv a} \ \mathrm{comp2}$$

2 Equational Theory

Definition 2.1. The equational theory of disjunctions is as follows:

$$\frac{\Gamma \vdash \alpha}{\Gamma \vdash [e_1, e_2]_{\alpha,\beta} \equiv e_1} \hspace{0.1cm} \text{comp1} \hspace{0.1cm} \frac{\Gamma \vdash \beta}{\Gamma \vdash [e_1, e_2]_{\alpha,\beta} \equiv e_2} \hspace{0.1cm} \text{comp2}$$

$$\frac{\Gamma_{\Psi} \vdash \alpha \lor \beta \hspace{0.3cm} \Gamma, \alpha \vdash e \equiv f : A \hspace{0.3cm} \Gamma, \beta \vdash e \equiv f : A}{\Gamma \vdash e \equiv f : A} \hspace{0.1cm} \text{ext} \hspace{0.1cm} \frac{\Gamma_{\Psi} \vdash \alpha \lor \beta \hspace{0.3cm} \Gamma \vdash e : A}{e \equiv [e, e]_{\alpha,\beta} : A} \hspace{0.1cm} \text{eta}$$

$$\frac{\Gamma \vdash \alpha \Leftrightarrow \gamma \hspace{0.3cm} \Gamma \vdash \beta \Leftrightarrow \delta \hspace{0.3cm} \Gamma, \alpha \vdash e_1 \equiv f_1 : A \hspace{0.3cm} \Gamma, \beta \vdash e_2 \equiv f_2 : A}{\Gamma \vdash [e_1, e_2]_{\alpha,\beta} \equiv [f_1, f_2]_{\gamma,\delta} : A} \hspace{0.1cm} \text{cong}$$

3 Algorithmic Definitions

We present an algorithmic procedure for deciding the judgments of the type theory.

Definition 3.1. Head reduction is defined as follows:

$$\begin{split} \Gamma \rhd (\lambda x.e) f &\to e[f/x] \\ \Gamma \rhd ef &\to e'f \qquad \text{if } \Gamma \rhd e \to e' \\ \Gamma \rhd [\alpha \to e, \beta \to f] \to e \qquad \text{if } \Gamma \vdash \alpha \\ \Gamma \rhd [\alpha \to e, \beta \to e] \to f \qquad \text{if } \Gamma \vdash \beta \\ \Gamma \rhd \text{out}_{\psi}(a) \to t \qquad \text{if } \Gamma \rhd a \uparrow A[\psi \to t] \text{ and } \Gamma \vdash \psi \\ \Gamma \rhd \text{out}_{\psi}(in(a)) \to a \\ \Gamma \rhd \text{out}_{[\alpha]}(in(a)) \to a \\ \Gamma \rhd \text{out}_{[\alpha]}(in(a)) \to a \\ \Gamma \rhd \text{out}_{[\alpha]}(a) \to a' \qquad \text{if } \Gamma \rhd a \to a' \end{split}$$

Definition 3.2. Term equivalence is defined as follows:

$$\begin{array}{ll} \Gamma \rhd M \Leftrightarrow N : A[\psi \to t] & \text{if } \Gamma \rhd \operatorname{out}_{\psi}(M) \Leftrightarrow \operatorname{out}_{\psi}(N) : A \\ \Gamma \rhd M \Leftrightarrow N : [\alpha] \to A & \text{if } \Gamma, \alpha \rhd \operatorname{out}_{[\alpha]}(M) \Leftrightarrow \operatorname{out}_{[\alpha]}(N) : A \\ \Gamma \rhd M \Leftrightarrow N : (x : \mathbb{I}) \to A & \text{if } \Gamma, x : \mathbb{I} \rhd Mx \Leftrightarrow Nx : A(x) \\ \Gamma \rhd M \Leftrightarrow N : (x : \mathbf{cof}) \to A & \text{if } \Gamma, x : \mathbf{cof} \rhd Mx \Leftrightarrow Nx : A(x) \end{array}$$

Definition 3.3. Neutral equivalence is defined as follows:

 $\begin{array}{ll} \Gamma \rhd [\alpha \to p_1, \beta \to p_2] \leftrightarrow q \uparrow A & \text{if } \Gamma, \alpha \rhd p_1 \Leftrightarrow q : A \text{ and } \Gamma, \beta \rhd p_2 \Leftrightarrow q : A \\ \Gamma \rhd p \leftrightarrow [\alpha \to q_1, \beta \to q_2] \uparrow A & \text{if } \Gamma, \alpha \rhd p \Leftrightarrow q_1 : A \text{ and } \Gamma, \beta \rhd p \Leftrightarrow q_2 : A \\ \Gamma \rhd \operatorname{out}_\psi(p) \Leftrightarrow \operatorname{out}_\psi(q) \uparrow A & \text{if } \Gamma \rhd p \leftrightarrow q \uparrow A[\psi \to t] \\ \Gamma \rhd \operatorname{out}_{[\alpha]}(p) \Leftrightarrow \operatorname{out}_\psi(q) \uparrow A & \text{if } \Gamma \rhd p \leftrightarrow q \uparrow [\alpha] \to A \end{array}$