

A SEARCH FOR SUPERSYMMETRY IN EVENTS WITH A Z
BOSON, JETS, AND MISSING TRANSVERSE ENERGY IN $p - p$
COLLISIONS WITH $\sqrt{s}=13$ TEV WITH THE ATLAS DETECTOR

TOVA RAY HOLMES



Physics Department
University of California, Berkeley

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ABSTRACT

PUBLICATIONS

Some ideas and figures have appeared previously in the following publications:

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ACKNOWLEDGEMENTS

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ACRONYMS

LHC	Large Hadron Collider
IBL	Insertable B-Layer
MS	Muon Spectrometer
ID	Inner Detector
SCT	Silicon Microstrip Tracker
TRT	Transition Radiation Tracker
NN	Neural Network
CCA	Connected Component Analysis
ToT	Time Over Threshold
MC	Monte Carlo simulation
SM	Standard Model
BSM	Beyond the Standard Model
SUSY	Supersymmetry
QCD	Quantum Chromodynamics
PDF	Parton Distribution Function
DM	Dark Matter
MC	Monte Carlo
AOD	Analysis Object Data
SR	Signal Region
VR	Validation Region
CR	Control Region
FS	Flavor Symmetric

Part I

INTRODUCTION

The centerpiece of this thesis is a search for Supersymmetry, but it also includes all the scaffolding and background necessary to understand the search. An overview of the Large Hadron Collider ([LHC](#)) and the ATLAS Detector are presented along with the theory that motivates the search.

INTRODUCTION

The pages that follow detail the author's work on the ATLAS experiment from 2011 through 2016, focusing on an analysis of 13TeV proton-proton collisions at the [LHC](#) looking for Supersymmetry with the ATLAS Detector.

CHAPTER 2 outlines the Standard Model of Particle Physics and the benefits of extending it to include Supersymmetry, then continues to describe the motivation behind searching for this particular model.

CHAPTER 3 describes the [LHC](#) and its operation.

CHAPTER 4 contains descriptions of the many pieces of the ATLAS detector, and how they serve to detect particles coming from [LHC](#) collisions.

CHAPTER 5 presents a neural network designed to improve tracking in the ATLAS Pixel Detector, and describes the benefits of its implementation.

Part II

THEORY AND MOTIVATION

This section describes the theoretical foundation for the analysis presented in [Part iv](#). It includes an overview of the Standard Model, including its phenomenology in a $p - p$ collider. The theory of Supersymmetry is explained, and the motivation for extending the Standard Model to include it is presented. In addition, this section includes an explanation of Monte Carlo generators and details about the specific form of Supersymmetry searched for in this analysis.

THEORY AND MOTIVATION

The Standard Model (SM) of particle physics represents all particles and interactions currently understood by the particle physics community. It is formulated using the principles of Quantum Field Theory, with the constraints of several symmetries and physical requirements to determine the rules for allowed interactions. [12] Developed in the 1960s and 70s, it has been immensely successful at predicting additional particles, and has held up to many high-precision tests. Despite this success, it has several shortcomings which point to its incompleteness. Though the SM is likely correct at the energies thus far probed, it may be missing key components that become more important at higher energies. Models supplementing the SM with additional particles and interactions are referred to as Beyond the Standard Model (BSM) theories.

One possible extension of the SM is Supersymmetry (SUSY), a theory which applies an additional symmetry between bosons and fermions to the SM, creating a spectrum of SUSY particles (sparticles) which interact with the particles of the SM. This theory motivates the search performed in Part iv, and its theoretical appeals are discussed in this section, along with specific simplified models considered in the search.

2.1 THE STANDARD MODEL

The SM of particle physics describes the interactions of all of the particles currently known to exist, and consists of both matter particles and force carriers. This model has been unprecedentedly successful in predicting new particles and phenomena, including the prediction of the Higgs particle almost 50 years before its discovery in 2012, which completed the SM. This section describes the components of the SM and how they interact, focusing on the environment of the LHC.

The particles of the SM are divided into two categories: fermions and bosons. The fermions comprise all the matter described by the SM, and are spin- $\frac{1}{2}$ particles. The bosons, integer-spin particles, are the force carriers. They provide a mechanism to explain three of the four forces known to particle physics, with gravity still lacking a quantum formalization. The Higgs boson, the only spin-0 particle in the SM, provides a mechanism for giving mass to the other particles. The full SM, with the addition of the hypothetical graviton, is presented in Figure 1.

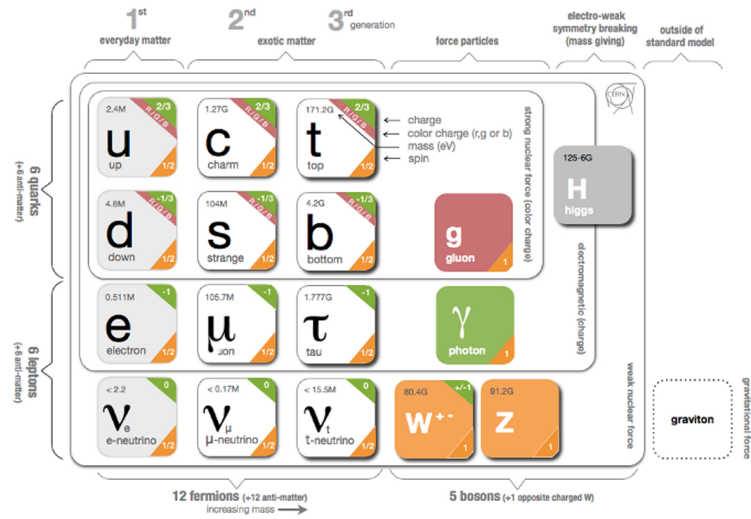


Figure 1: The Standard Model of particle physics, containing all known bosons and fermions, with the addition of the hypothetical graviton. [20]

2.1.1.1 Matter

The matter described by the SM is made up of fermions, spin- $\frac{1}{2}$ particles which can be broken into two groups, quarks and leptons. The leptons all interact weakly, while the quarks additionally interact strongly.

2.1.1.1.1 Leptons

Leptons, as seen in the bottom left of Figure 1, come in three generations, each labeled by a flavor: electron, muon, and tau. In the case of the massive leptons, these flavors are mass eigenstates, and the generations are placed in an order based on increasing mass. Each massive lepton is negatively charged and has a positively charged anti-particle.

The three neutrinos come in the same flavors as the massive leptons, but these flavor eigenstates do not correspond exactly to mass eigenstates. As a consequence, neutrinos oscillate between flavors as they propagate through space. These oscillations are the only evidence of neutrino mass, which is bound from below by the mass splittings determined from the oscillation. Though it is still uncertain if the masses of the neutrinos follow the same hierarchy as the massive leptons, that expected ordering is slightly preferred over the inverted hierarchy. [23]

Unlike the massive leptons, the neutrinos are uncharged, and it is not yet known whether each neutrino has a separate anti-particle, or if it is its own antiparticle. Because they are uncharged, they can only interact weakly, making them extremely difficult to detect. In the AT-

LAS detector, neutrinos pass through all layers undetected, and their presence can only be inferred from the non-conservation of momentum that results in the observed particles. As a consequence of their ability to evade detection, neutrinos are the least understood particles of the SM.

The SM conserves lepton number, L , which is defined as the number of leptons minus the number of anti-leptons in a state. While this conservation is not theoretically required, its violation has not yet been observed. As a consequence of this conservation, the lightest massive lepton, the electron, is stable.

2.1.1.2 Quarks

Quarks, as seen in the top left of Figure 1, are also charged particles that interact weakly, but are differentiated from the leptons by their strong interactions. They are also organized in three generations ordered by mass, and come in pairs of “up-type” and “down-type” quarks, named after the lightest generation. Though the up quark is lighter than the down, that rule is reversed in the subsequent two generations. Up-type quarks are charged $+\frac{2}{3}$, while the down-type quarks are charged $-\frac{1}{3}$. Quarks are also charged under the strong interaction, whose three charges are often characterized by colors: red, green, and blue. Each quark has an anti-particle with the opposite charges.

These fractional charges and individual colors are never seen in nature because of the requirement (discussed further in Section 2.1.2.2) that stable particle states be color-neutral. To accomplish this, quarks can create two-particle bound states called *mesons* consisting of one quark and one anti-quark with the same color charge or three-particle bound states of quarks or anti-quarks with the three different color charges, which are called *baryons*. The lightest color neutral state containing only quarks, the proton (uud), is stable. Extremely unstable bound states consisting of higher numbers of quarks can also exist, such as the pentaquark discovered in 2015 at the LHC. [29] Collectively, these multi-quark bound states are called *hadrons*.

Like leptons, the number of quarks in a state is conserved. However, because quarks cannot exist in an isolated state, that conservation described as a conservation of baryon number (B) defined similarly to lepton number. Mesons, because they have one quark and one anti-quark, have $B = 0$.

2.1.2 Forces

The fermions in the previous section interact via the electromagnetic, weak, and strong forces. In a perturbative quantum field theory, interactions via these forces are represented by mediating bosons. These force carriers interact only with particles charged with their force's

quantum numbers. The photon, for example, interacts only with electromagnetically charged particles. Gluons, mediators of the strong force, interact only with color charged particles, quarks and gluons. All fermions are weakly charged and interact with the weak force's mediators, the W and Z bosons.

The formulation for each of these forces is developed by requiring that the [SM](#) lagrangian be locally gauge invariant. [22] This can be accomplished by adding gauge fields to the lagrangian, whose behavior under gauge transformations cancels out the gauge dependence of the free lagrangian. However, adding a mass term for these fields reintroduces gauge dependence, so this mechanism only creates forces mediated by massless particles.

2.1.2.1 The Electromagnetic Force

The simplest example of gauge invariance requirements generating a description of a force can be found in electromagnetism. It has one massless mediator, the photon, which interacts with all electromagnetically charged particles. What follows is a brief description of how enforcing this invariance generates a lagrangian of the same form as the classical electromagnetic lagrangian, which can be easily incorporated into the [SM](#).

The particles in [Section 2.1.1](#) are fermions, and so their free lagrangians are Dirac lagrangians and all follow the form

$$\mathcal{L} = i\bar{\psi}\gamma^\mu\partial_\mu\psi - m\bar{\psi}\psi. \quad (1)$$

Requiring that the free lagrangians for these particles be invariant under a $U(1)$ local gauge transformation, $e^{iq\lambda(x)}$, can be accomplished by adding a term to the lagrangian which cancels the derivative term arising from λ 's dependence on x :

$$\mathcal{L} = i\bar{\psi}\gamma^\mu\partial_\mu\psi - m\bar{\psi}\psi - (q\bar{\psi}\gamma^\mu\psi)A_\mu \quad (2)$$

where A_μ is a “gauge field” that transforms according to

$$A_\mu \rightarrow A_\mu + \partial_\mu\lambda. \quad (3)$$

This vector field must also come with a free term,

$$\mathcal{L} = -\frac{1}{16\pi}F^{\mu\nu}F_{\mu\nu} + \frac{1}{8\pi}m_A^2A^\nu A_\nu. \quad (4)$$

The mass term for this field would not itself be invariant under the transformation, but the field can simply be made massless to avoid this problem. The final lagrangian, then, is

$$\mathcal{L} = i\bar{\psi}\gamma^\mu\partial_\mu\psi - m\bar{\psi}\psi - \frac{1}{16\pi}F^{\mu\nu}F_{\mu\nu} - (q\bar{\psi}\gamma^\mu\psi)A_\mu \quad (5)$$

which is precisely the original lagrangian with the addition of terms replicating the form of the Maxwell lagrangian. In a quantized interpretation, it describes a field that interacts with particles with non-zero electromagnetic charge q via interactions with a massless spin-1 boson, the photon.

For the purpose of succinct notation, this lagrangian is often rewritten in terms of the “covariant derivative”

$$\mathcal{D}_\mu = \partial_\mu + iq\lambda A_\mu \quad (6)$$

which immediately cancels the gauge dependent term created by the transformation. This mechanism is mathematically simple in the $U(1)$ case, but can be replicated for more complicated gauge transformations with perturbative approximations.

2.1.2.2 Quantum Chromodynamics

Quantum Chromodynamics (QCD), the theory describing the strong force, can be formulated similarly to the electromagnetic force, but with a $SU(3)$ transformation replacing $U(1)$. This transformation acts on a vector of equal mass quarks, the three different colors of a given flavor. The transformation is written as follows,

$$\psi \rightarrow e^{-iq\lambda \cdot \phi(x)} \psi \quad (7)$$

where ϕ gives a vector of coefficients to be multiplied by the Gell-Mann matrices, λ . Though the math is more complicated than the $U(1)$ case in this higher dimensional rotation, the cancellation is ultimately similar.

The main difference, corresponding to this more complicated basis of transformations, is that eight fields A_μ are required rather than the one needed in electromagnetism. These eight fields correspond to eight massless bosons, the different color states of the gluon, the carrier of the strong force.

All together, the total lagrangian for QCD is

$$\mathcal{L} = i\bar{\psi}\gamma^\mu\partial_\mu\psi - m\bar{\psi}\psi - \frac{1}{16\pi}\mathbf{F}^{\mu\nu}\mathbf{F}_{\mu\nu} - (q\bar{\psi}\gamma^\mu\psi)\mathbf{A}_\mu, \quad (8)$$

an equation identical in form to Equation 5, with the mathematical complications of the additional fields hidden by the vector notation. In addition to that change, the covariant derivative must accommodate a vector \mathbf{A} as well, changing only slightly to be defined as

$$\mathcal{D}_\mu = \partial_\mu + iq\lambda \cdot \mathbf{A}_\mu. \quad (9)$$

This canceling is actually only satisfied to a first order expansion of the transformation, guaranteeing its validity only for infinitesimally small ϕ . However, the strong coupling constant, α , depends on the energy scale of the interaction, decreasing at higher energy scales and asymptotically increasing at low energies. Figure 2 shows this effect translated to distance scales, demonstrating that QCD is weak and can be considered perturbatively at small distance scales, but at large distance scales this approximation breaks down, and the colorless hadrons introduced in Section 2.1.1.2 must be used to describe interactions instead. The boundary between these regimes is referred to as Λ_{QCD} .

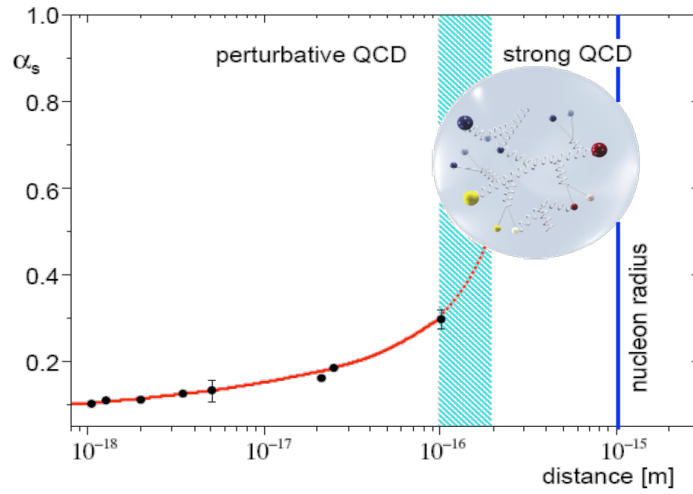


Figure 2: The running of the strong coupling constant, α . [27]

2.1.2.3 The Weak Force

A similar process, using an $SU(2)$ gauge transformation, can produce a lagrangian that would suffice to describe the W and Z bosons of the SM, if only they were massless. However, they are not, so an alternate mechanism must be used to add masses to the lagrangian.

Before a mechanism for their masses was understood, and before they were discovered, the large mass of the W and Z bosons were proposed in order to unify the electromagnetic and weak forces into the electroweak force. The large masses were crucial to explain the discrepancy in the strength of the two forces.

This unified theory resulted in a triplet, \mathbf{W} , with coupling g_W , and a singlet field B , with coupling $g'/2$. However, this electroweak symmetry is broken, and mixing between these states occurs. Rewritten in their mass basis, the more familiar electroweak force carriers are produced: W^\pm , two states with identical coupling, Z^0 , and A , the photon field.

2.1.2.4 The Higgs Mechanism

The reason for this symmetry breaking has to do with the final piece of the [SM](#), the Higgs boson. The Higgs mechanism presents an alternate way to generate a mass term, through an unexpected route. It is a scalar field, with a lagrangian

$$\mathcal{L} = \frac{1}{2}(\partial_\mu \phi)^*(\partial^\mu \phi) + \frac{1}{2}\mu^2 \phi^* \phi - \frac{1}{4}\lambda^4(\phi^* \phi)^2 \quad (10)$$

where ϕ is a complex scalar field, $\phi = \phi_1 + i\phi_2$. This looks very similar to the standard scalar field, but the signs on the mass and interaction terms are reversed, giving a result that looks like an imaginary mass. However, this lagrangian differs from all previously considered lagrangians in that its ground state does not occur at $\phi = 0$. Because this is a perturbative theory, its validity only holds when expanded around the ground states, which must satisfy

$$\phi_1^2 + \phi_2^2 = -\frac{\mu}{\lambda}. \quad (11)$$

Rewriting the original lagrangian in terms of fields centered around ground states chosen to satisfy that condition results in a reasonable mass term. However, in an effect called “spontaneous symmetry breaking”, the original $SO(2)$ rotational symmetry of the lagrangian is lost, resulting only in a $U(1)$ rotational symmetry; the lagrangian is invariant under a phase transformation.

As in [Section 2.1.2.1](#), it is possible to make the lagrangian invariant under a local $U(1)$ transformation, $\phi \rightarrow e^{i\theta(x)}\phi$ by adding a massless gauge field A^μ and using the covariant derivative. Due to the many cross terms from the non-zero ground state, terms for the mass of one of the bosons as well as the gauge field appear, leaving only one massless boson. The massless boson, it turns out, can be completely removed from the theory via local $U(1)$ transformations, ultimately producing a theory with one massive scalar (the Higgs) and a massive gauge field.

2.1.3 Phenomenology of Proton-Proton Collisions

As discussed in [Chapter 3](#), the [LHC](#) collides bunches of high-energy protons, and the interactions of these protons’ constituent quarks produce the wide array of particles seen in the ATLAS detector. The [LHC](#) typically cites its energy in terms of \sqrt{S} , the center of mass energy of protons in the two colliding beams. However, because the proton is not fundamental, this energy is divided among many particles that make up the proton.

To first order, a proton consists of three quarks: two up quarks and one down quark. However, a real quantum mechanical system is

much more chaotic, with other quarks popping into and out of existence and gluons flying between them. These additional quarks are called “sea” quarks. The particles inside the proton can have a wide range of energies depending on the internal dynamics at the moment of the collision. These cannot be predicted exactly, but probabilistic models called **PDFs** describe the likelihood of any given configuration. These models are determined using data from hard scattering experiments and give probabilistic estimates for how often a given type of particle appears with a fraction x of the total proton energy, as seen in Figure 3.

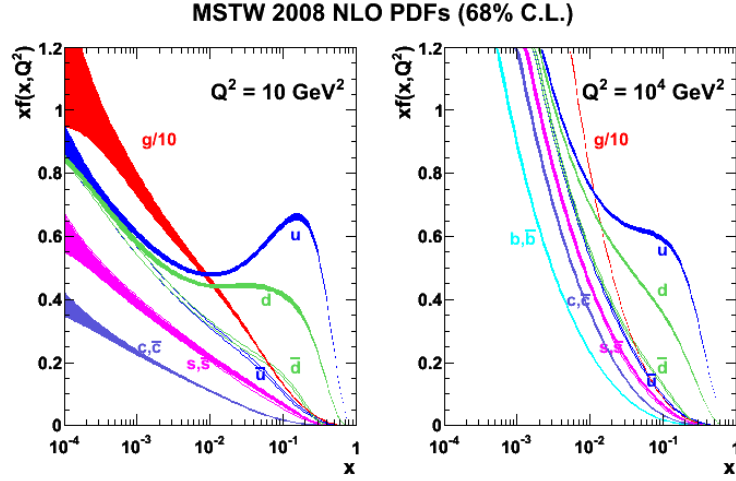


Figure 3: 2008 MSTW **PDFs** for various particle types. [26]

2.1.4 Problems in the Standard Model

Though the **SM** is a self-consistent theory that describes to great accuracy all of the particles and forces it includes, it does have certain shortcomings. The most glaring is the omission of gravity. Though the force is well understood at large scales via the theory of General Relativity, no satisfying quantum description of gravity has been accepted, much less proven. The Planck scale, the energy scale at which gravitational interactions become large enough that no sound theory can ignore gravity, is at about 10^{28} eV, 16 orders of magnitude above the electroweak scale.

Another clear omission of the **SM** is Dark Matter (**DM**). This matter was first identified in 1933 through the observation of galactic rotation curves. [28] The speed of rotation indicated both that there was more mass in the system than could be accounted for by observations made directly of the galaxy, and that this additional matter was distributed in a halo, not a disk like the typical luminous matter. This effect can be seen in Figure 4. Since then, the gravitational impact of **DM** has been observed in colliding clusters and many more rotational

curves, but it has never been directly detected or seen at a particle accelerator. As a consequence, very few details are known about the nature of the particles that make up this matter, only that it does not interact strongly or electromagnetically and its density throughout the universe.

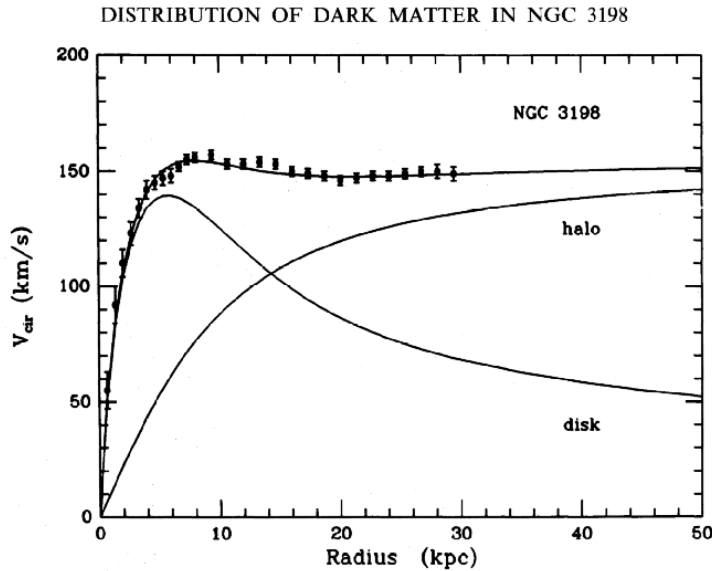


Figure 4: Galactic rotation curve showing that the discrepancy between the observed luminous matter and the total mass in the system can be described as a non-luminous halo of matter. [30]

Beyond the omissions of the SM, there are several aesthetic problems - things that could have no solution, but seem to suggest that the current SM are missing some pieces that could unify it and provide more order. The first is the sheer number of parameters in the SM. There are 26 independent parameters determining the mass of the particles and all the couplings between them. Besides the rough grouping of fermions into generations, there seems to be no order to masses of particles, and no way to predict the masses or couplings. Each, it seems, is independently provided by nature.

In the past, large numbers of seemingly unrelated parameters has indicated that a theory has a more fundamental form at shorter distance scales. The large number of elements, it turned out, could be explained by different groupings of three particles, the proton, neutron and electron. Later, the menagerie of hadrons became so large that a similar reimagining of what was fundamental took place, and the theory of quarks gave an order to the many mesons and baryons. This pattern leaves physicists suspicious of any theory with too many particles and free parameters, suggesting that perhaps, at a higher energy, there is a simpler model that can unify many of the seemingly disparate elements of the SM.

However, some of these seemingly independent parameters have suspicious symmetry. The Higgs mass, for example, has been measured to be 125 GeV. This mass is the sum of the bare mass, the one that appears in the lagrangian, and quantum corrections from interactions with other particles, which are proportional to the square of the particles' mass. Since new physics must exist at the Planck scale to account for gravity, these corrections could be up to 35 orders of magnitude larger than the Higgs mass. The bare mass could theoretically cancel out this massive correction, these parameters should be independent, and the odds that they would be precisely the same to 35 places are very, very small. This exact canceling is often called “fine-tuning”, an undesirable trait in a theory which suggests that some more fundamental symmetry has been missed. The word “naturalness” is used to describe the the extent to which a theory is free of fine-tuning.

2.2 SUPERSYMMETRY

2.2.1 *Supersymmetry Phenomenology*

2.2.2 *Solutions to Standard Model Problems*

Many believe that a complete [SM](#) would include a unification of the three forces, as electromagnetism and the weak force have already been unified. This requires that at some higher energy, the coupling constants of all three forces merge.

2.2.3 *Supersymmetry Signatures in $p - p$ Collisions*

2.2.3.1 *Simplified Models Used in This Analysis*

2.3 MONTE CARLO GENERATORS

Part III

THE EXPERIMENT

This section describes the [LHC](#) and the ATLAS detector, which collectively provide the physical environment and the data collection for the analysis discussed in [Part iv](#).

THE LARGE HADRON COLLIDER

The [LHC](#) is unique in the world, producing proton-proton collisions at energies an order of magnitude higher than any accelerator before. It provides unique environments at its collision points where massive, unstable particles can exist for an instant, then decay to the ordinary material of the universe. It is the goal of the ATLAS experiment to identify these short-lived particles, but [LHC](#)'s work of producing them is equally complex.

3.1 OPERATION OF THE LARGE HADRON COLLIDER

THE ATLAS DETECTOR

The ATLAS detector circumscribes the LHC's beam pipe, enclosing the collision point with a series of particle detecting layers, aimed at making as many measurements of the particles leaving the collision point as possible. Its goal is to get a precise measurement of all the stable or semi-stable particles flying from proton-proton collisions at its center, allowing analyzers to fully reconstruct the kinematics of the underlying processes.

The ATLAS detector is the largest detector of its kind, measuring 44 m in length and 25 m in height, as seen in Figure 5. The size is mainly determined by the constraints of the Muon Spectrometer (MS), discussed in Section 4.4, which is the largest and outermost subsystem. The MS is submerged in a spatially varying magnetic field provided by three toroidal magnets, while the Inner Detector (ID) (Section 4.2) is encased by a superconducting solenoid, which provides a uniform 2 T field throughout its volume [1].

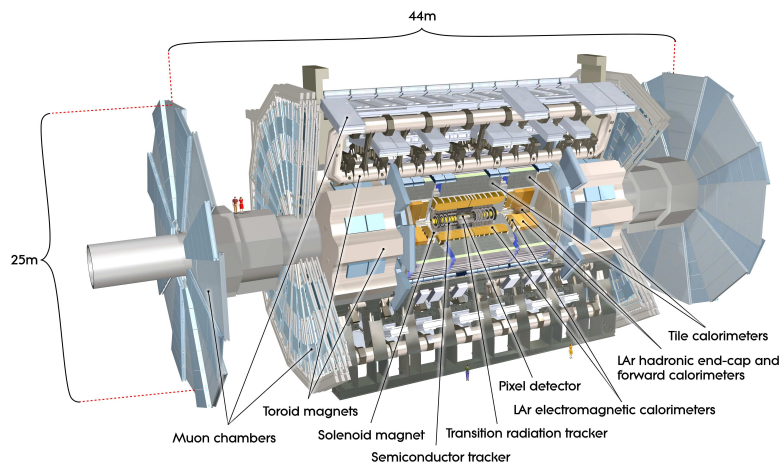


Figure 5: Diagram of the ATLAS detector, with subsystems and magnets identified.

4.1 COORDINATE SYSTEM USED IN THE ATLAS DETECTOR

The ATLAS detector is centered around the collision point in the beam pipe, and is built radially out from the pipe, maintaining as much rotational symmetry as possible. It is also symmetric in the forward-backward directions. Because of this geometry, a coordinate system using the collision point as the origin is used, with the beam

pipe defining the z -axis. The positive x direction is defined as pointing to the center of the LHC ring, while the positive y direction points upwards. For ease of reference, the side of the detector in the positive- z direction is referred to as the A side, and the other side is referred to as the C side.

Because of the radial design of the detector, angular coordinates are often used. The azimuthal angle ϕ defines the radial distance around the beam pipe and the polar angle θ defines the angle from the beam axis (z). However, a transformation of the polar angle called pseudorapidity (η) is used more often, and is defined as

$$\eta = -\ln\left[\tan\frac{\theta}{2}\right]. \quad (12)$$

Building on this variable definition, distance between objects is typically defined as

$$\Delta R = \sqrt{\Delta\eta^2 + \Delta\phi^2}. \quad (13)$$

Often variables are defined purely in the transverse plane, which is indicated by a subscripted T , as in p_T , which gives an object's transverse momentum. Another common usage is E_T^{miss} , which gives the negative vectorial sum of the energy in an event.

4.2 THE INNER DETECTOR

One goal of the ATLAS detector is to produce tracks, predictions of the paths particles take as they travel through the detector. Collisions in the detector produce about 1000 particles, so identifying and differentiating all these tracks is both a hardware and a computational challenge. The ID, also called the Tracker, is responsible for providing high enough resolution measurements that each of these tracks and its precise position can be recorded. This tracking system consists of three subdetectors which each produce electrical responses to charged particles passing through their active material. Each of these signals is called a hit. ATLAS tracking software considers all these hits and forms tracks, with the goal of minimizing fake tracks due to random noise. Some details of this process is discussed at length in Chapter 6. The full ID can be seen in Figure 6, while a schematic in Figure 7 demonstrates the η coverage of each detector.

4.2.1 The Pixel Detector

The Pixel detector lies closest to the beam pipe of the LHC, and has four layers comprising 92 million read-out channels. There are three

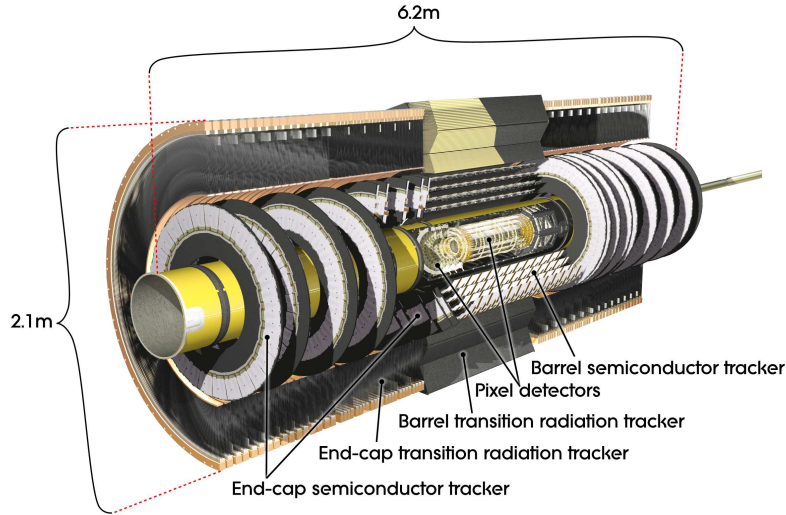


Figure 6: Diagram of the ATLAS Inner Detector, containing the Pixel, SCT, and TRT subsystems.

standard layers, referred to as Layers 1-3 (L1, L2, L3), and an additional layer added for the 2015 data-taking, called the Insertable B-Layer (IBL).

4.2.1.1 The Original Pixel Detector

The Pixel Detector consists of high-precision silicon chip pixel sensors, with 1744 sensors total. Each sensor is identical, containing 47232 pixels, which are typically each $50 \times 400 \mu\text{m}^2$.

As shown in Figure 7, the central η region (barrel) is covered by three concentric cylindrical layers of sensors, while the higher η region (endcap) is covered by a series of three disks positioned in the $x - y$ plane. Together, they give complete coverage out to $\eta = 2.5$, and a particle coming from the collision point will typically be measured by three layers. Each of these measurements is accurate in the barrel (endcap) to $10 \mu\text{m}$ in the $R - \phi$ direction and $115 \mu\text{m}$ in the z (R) direction.

4.2.1.2 Addition of the IBL

In 2015, the IBL was lowered into the ATLAS cavern and added to the Pixel Detector. This layer sits on top of the beam pipe, inside barrel L1, which was formerly responsible for the first measurement of charged particles coming from a collision. TODO: add info about precision

As the IBL's name suggests, it was added to improve detection of B mesons, whose non-trivial lifetimes create secondary vertices in ATLAS events, which allow them to be distinguished from other particles with precise track measurement. The IBL is closer to the interaction point and has a smaller resolution, giving it a better chance to see these slightly displaced vertices.

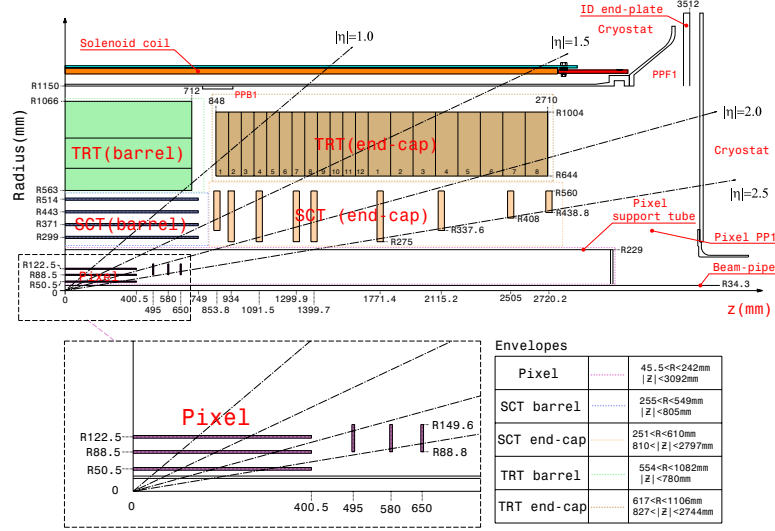


Figure 7: Diagram of one-quarter of the ATLAS Inner Detector, with lines drawn to indicate various η locations. The labels PP1, PPB1 and PPF1 indicate the patch-panels for the ID services. TODO: what is that.

4.2.2 The Silicon Microstrip Tracker

The Silicon Microstrip Tracker (SCT) employs similar technology to the Pixel Detector, with 15912 sensors and 6.3 million readout channels. Its difference from the Pixel Detector is in the readout, which is performed by a series of 12 cm long strips with a width of $80 \mu\text{m}$. These layers are paired, placed on top of one another at a small (40 mrad) angle to allow for position determination in both directions, giving 4 spatial measurements for each particle passing through the SCT. In the barrel, these strips run parallel to the beam pipe, while in the endcap, they are arranged radially. These strips have a resolution in the barrel (endcap) of $17 \mu\text{m}$ in the $R - \phi$ direction and $580 \mu\text{m}$ in the z (R) direction.

4.2.3 The Transition Radiation Tracker

The Transition Radiation Tracker (TRT) uses 4mm diameter gas-filled tubes, each with a high voltage wire suspended along the center of the tube. The tubes run the length of the barrel, with a separate wire in the positive and negative z direction. In the endcap, the tubes are arranged radially. In total, there are about 351,000 readout channels in the TRT. This detector makes measurements only in the $R - \phi$ direction, where the resolution of each measurement is $130 \mu\text{m}$. Each particle typically creates about 36 hits as it passes through the TRT.

TODO is any of this right? Particles passing through the gas mixture of the TRT ionize the gas, producing electrons which drift towards

the wire due to a potential difference applied between it and the straw. This process takes about 48 ns, and the signal can be directly read out, giving the fastest measurement of particles in the ID. This speedy readout is essential to triggering, discussed more in Section 4.6.

The TRT also responds to low-energy transition radiation photons, which produce a much larger signal than charged particles passing through the detector. Because of this strong difference in signals, hits from the TRT are used to help differentiate between electrons and photons in the detector.

4.3 THE CALORIMETERS

Unlike the tracking detectors, which aim to take measurements of a particle with minimal alterations of its trajectory, the calorimeters measure the energy of objects by stopping them entirely. The calorimeters, which can be seen in Figure 8, provide coverage out to $\eta < 4.9$. Higher granularity electromagnetic measurements are made within $|\eta| < 2.5$, where the ID provides tracking capability, in order to give precision measurements of the energy of photons and electrons, and provide reduced resolution measurements at higher η . The hadronic calorimeters provides coarser granularity, which is sufficient to determine the energy of jets.

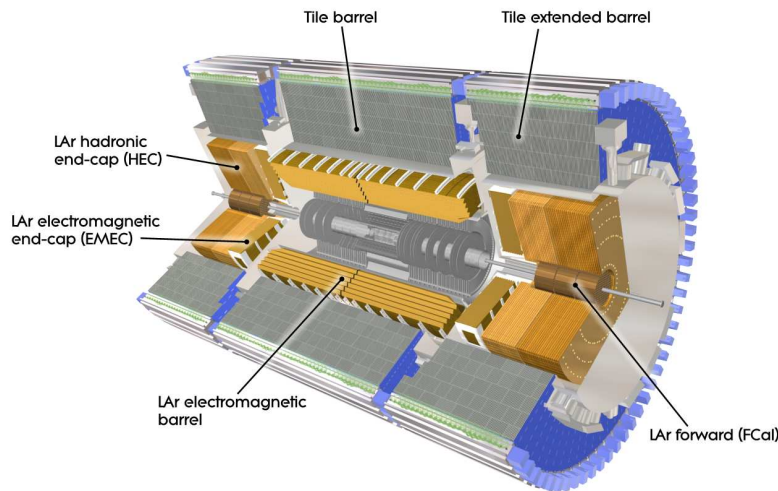


Figure 8: The calorimeter system of the ATLAS detector.

TODO make sure jets are in theory.

Another task of the calorimeter system is to limit punch-through to the MS, described in Section 4.4. All other particles must be fully stopped by the calorimeters to allow for clean signals from muons, and to measure the total energy of the particle. This requirement sets minimum sizes for each of the calorimeters.

THE LAR ELECTROMAGNETIC CALORIMETER uses liquid argon as its active detector medium alternating with layers of lead acting as the absorber. The layers are shaped like accordions, which allows for complete coverage with multiple layers of active material, three in central η ($0 < |\eta| < 2.5$) and two at higher η ($2.5 < |\eta| < 3.2$). At $|\eta| < 1.8$, an instrumented liquid argon presampler provides a measurement of energy lost prior to reaching the calorimeters.

THE TILE CALORIMETER is a hadronic calorimeter which surrounds the LAr Calorimeter. It uses layers of steel as its absorber with scintillating tiles as the active material between them, which are read out by photomultiplier tubes. The Tile Calorimeter covers $|\eta| < 1.7$.

THE LAR HADRONIC ENDCAP CALORIMETER covers the hadronic calorimetry for higher η . It uses liquid argon active material and copper plate absorbers. This calorimeter covers $1.5 < |\eta| < 3.2$, overlapping with the hadronic calorimeters in either direction of its η range.

THE FCAL or forward calorimeter provides electromagnetic and hadronic coverage at very high η ($3.1 < |\eta| < 4.9$). This calorimeter also uses liquid argon as its active material, and uses copper-tungsten as the absorber.

4.4 THE MUON SPECTROMETER

4.5 THE MAGNET SYSTEM

4.6 THE TRIGGER SYSTEM

OBJECT RECONSTRUCTION IN THE ATLAS DETECTOR

5.1 ELECTRONS

5.2 PHOTONS

5.3 MUONS

5.4 JETS

5.5 MISSING TRANSVERSE ENERGY

5.6 MONTE CARLO SIMULATION

APPLICATION OF A NEURAL NETWORK TO PIXEL CLUSTERING

6.1 CLUSTERING IN THE PIXEL DETECTOR

Creating tracks from individual hits in the Inner Detector is one of most computationally challenging parts of the reconstruction of ATLAS events. Each event typically contains thousands of hits in the pixel detector alone, which must be combined into one coherent picture of which particles traversed the detector, and how they moved and lost energy as they traveled. A typical particle deposits charge in several pixels per layer, forming a series of clusters which can be connected together to form a track. This track can in turn be used to measure the charge, momentum, and trajectory of the particle, and in many cases, provides ATLAS's most precise measurement of a charged particle.

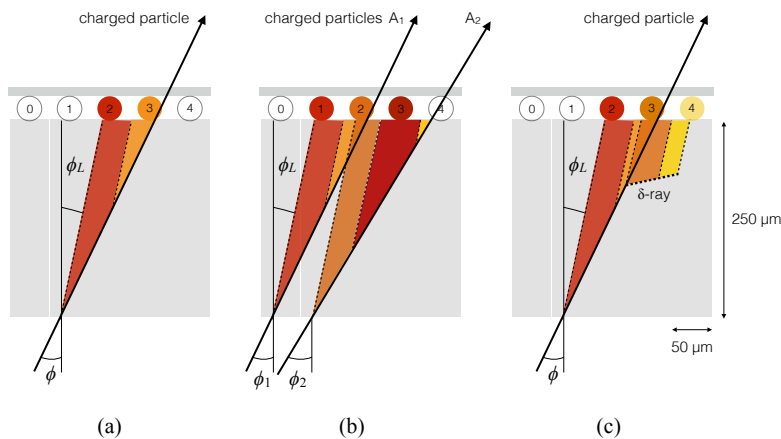


Figure 9: A few possible types of clusters in the Pixel Detector. (a) shows a single particle passing through a layer of the detector, (b) shows two particles passing through the detector, creating a single merged cluster, and (c) shows a single particle emitting a δ -ray as it passes through the detector.

The process of going from clusters to track is relatively simple in an isolated environment in which one particle travels cleanly through all the layers, but can be complicated by multiple close-by tracks and by a single particle's emission of low energy particles, called δ -rays. In these cases, it can be hard to tell how many particles were involved in creating a cluster, and where exactly each of those particles passed through the layer. A few examples of these cases can be seen in [Fig-](#)

ure 9 . The process of determining which pixels with charge deposits belong to a single particle is called clustering, and it has recently been updated from a charge interpolation method to a method using a NN.

6.1.1 Charge Interpolation Method

A typical cluster contains a few pixel hits spanning in the x and y directions, each with its own measurement of charge deposition, or Time Over Threshold (ToT). The extent of the cluster is defined by grouping together any pixels with a shared edge or corner. In the charge interpolation method, also called the CCA clustering algorithm, these individual hits are combined to make one estimation of the position a single particle which passed through them, using the following equation:

$$x_{cluster} = x_{center} + \Delta_x(\phi, N_{row}) \cdot \left[\Omega_x - \frac{1}{2} \right] \quad (14)$$

$$x_{cluster} = x_{center} + \Delta_x(\phi, N_{row}) \cdot \left[\Omega_x - \frac{1}{2} \right] \quad (15)$$

where $\Omega_{x(y)}$ is defined by

$$\Omega_{x(y)} = \frac{q_{last\ row(col)}}{q_{first\ row(col)} + q_{last\ row(col)}} \quad (16)$$

and q represents the ToT of a given pixel, and $\Delta_{x(y)}$ is a function derived from either data or MC and produces an output related to the projected length of the particles track on the pixel sensor and is measured as a function of ϕ , the incident angle of a particle on the sensor, and $N_{row(col)}$, the number of pixels in the x and y direction.

In a simple case, such as (a) of Figure 9 , this method works quite effectively. However, in cases like (b), it has no ability distinguish two-particle from one-particle clusters, and can only assign a cluster center between the two particles' locations, despite that intermediate pixel having the lowest ToT. Furthermore, because this method can't differentiate two-particle clusters, the tracking software can't use that information to preferentially allow multiple tracks to be fit to the cluster. In cases like (c), the δ -ray will bias the measurement of the particle's position in whichever direction it is emitted.

6.1.2 Improving Measurement with Neural Networks

To address these problems, a series of NNs were created [3]. The first determines the number of particles in a given cluster, the second predicts their positions within the cluster, and the third assesses the uncertainty of the position measurement.

These NNs are all trained with:

- a 7×7 grid of cluster ToT information¹
- a 7-element vector containing the y -size of the pixels in the grid
- the layer of the pixel detector that the cluster was observed in
- a variable indicating whether the cluster is located in the barrel or endcap
- θ and ϕ variables projecting the incident angles of the particle on the sensor, assuming it comes from the interaction point
- the η index of the pixel module

After the Number NN predicts a number of particles associated with the cluster, required to be between 1 and 3, the same inputs are fed to one of three Position NNs based on the determined number of particles, which then outputs the x and y positions of each of the particles. Then, the same inputs combined with the output of the Position NN are fed into one of three Error NNs (also distinguished by number of particles), which outputs an uncertainty for each of the position predictions made. An example of the output of this process can be seen in Figure 10, where the improved position resolution from the ability to identify a multi-particle cluster is evident. The particle location predictions from the NNs are then handed to the tracking software, which is able to independently consider multiple locations from a given cluster to find the best fit.

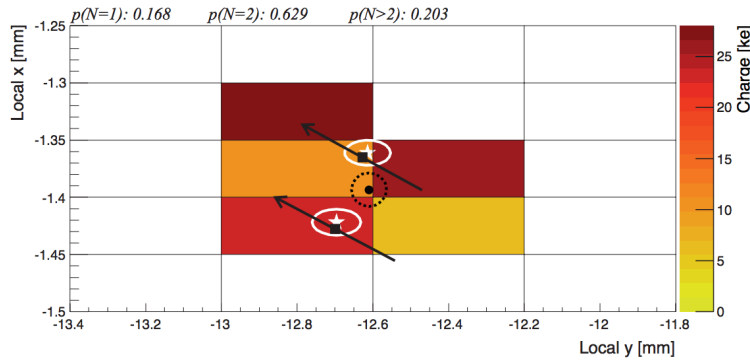


Figure 10: One example of a two-particle cluster and its truth information compared with the output of the NNs. At top, the $p(N = i)$ values give the output of the Number NN, the probabilities that the cluster contains 1, 2, and 3 particles. Given the highest probability is for $N = 2$, the other NNs predict the position and errors of the two particles (in white). The black arrows and squares represent the truth information from the cluster, and the black dot and dotted line show the position measurement for the un-split cluster.

¹ Clusters spanning more than seven pixels in either direction are split into multiple clusters.

6.2 IMPACT OF THE NEURAL NETWORK

The [NN](#) was first applied to 7 TeV data, where it improved position resolution for particles in small and large clusters. [Figure 11](#) shows the improvement from the addition of the [NN](#) in x resolution in different cluster sizes. The improvement from [CCA](#) clustering is particularly evident in the 4-pixel case, where the double peaked structure of the interpolation method has been completely removed with the [NN](#).

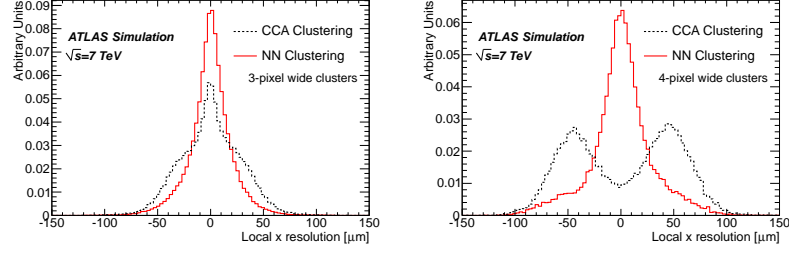


Figure 11: x resolutions for clusters with 3 (left) and 4 (right) pixels in the x direction in 7 TeV data for [CCA](#) and [NN](#) clustering.

6.2.1 The Neural Network in 13 TeV Data

In Run 2, the tracking algorithm is first run on the [CCA](#) clusters, where it constructs loose tracks that allow shared clusters, clusters to which multiple tracks are fit [4]. The [NN](#) is then used to identify which clusters are likely to have had multiple particles pass through them, and to identify the positions of those particles. In the case that the cluster is determined to have resulted only from one particle, tracks that share that cluster are penalized.

With this configuration, studies were done to determine how accurately [MC](#) could model the [NN](#)'s response to data. [Figure 12](#) shows a comparison of how often the [NN](#) identifies different types of clusters in data and [MC](#). Very good agreement was seen between the two samples.

With this confirmation that studies performed in [MC](#) would be good indicators for performance on data, the robustness of the [NN](#) was investigated with 13 TeV [MC](#) [5]. The goal of these studies was to determine which variables the [NN](#)'s predictions were most sensitive to, and whether it was likely that these variables could be mismodeled enough to produce unexpected results. One example of a sensitive variable is the overall charge scale, and the impact of its scaling can be seen in [Figure 13](#). In this case, the likelihood to misidentify multi-particle clusters and single particle clusters depended significantly on this scaling. Overall, it was found that variations on the cluster charge produced a significant impact on predictions, while all other variations had a minimal effect.

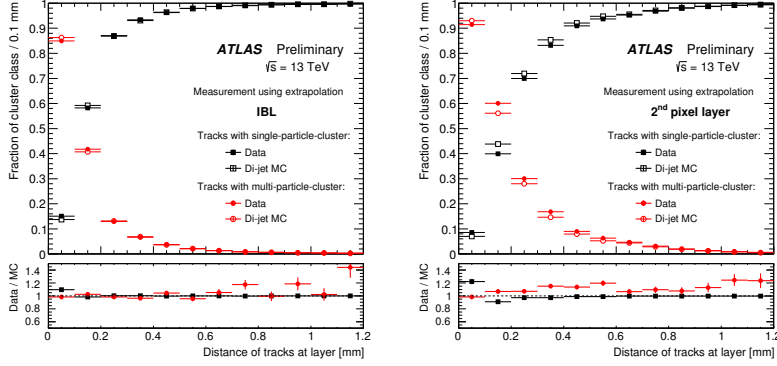


Figure 12: Fraction of cluster classes as a function of the distance between tracks for (a) IBL and (b) 2nd pixel layer.

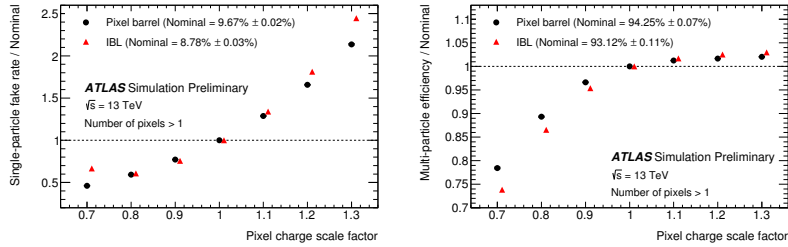


Figure 13: Performance of the pixel neural network used to identify clusters created by multiple charged particles, as a function of constant coherent scaling of the charge in each pixel in the cluster. The left figure shows the rate at which the neural network wrongly identifies clusters with one generated particle as clusters with multiple particles. The right figure shows the rate at which the neural network correctly identifies clusters generated by multiple particles as such.

Part IV

SEARCHING FOR SUPERSYMMETRY

This section describes an analysis of the ATLAS data carried out by the author and her analysis team. The analysis was performed on events from $p - p$ collisions provided by the [LHC](#) at $\sqrt{s}=13$ TeV. It searches for events like those described in [Section 2.2.3.1](#), which contain a Z boson decaying to leptons, jets, and missing transverse energy. The selection of a signal region in which to search for these events, background estimates, systematic uncertainty estimates, results, and interpretations are all discussed.

BACKGROUND PROCESSES

This analysis is fundamentally a search for Supersymmetry in events with two leptons whose invariant mass is consistent with a Z boson. Additional event selections are made to reduce Standard Model processes relative to potential Supersymmetric processes, defined by simplified models discussed in [Section 2.2.3.1](#). Supersymmetric events typically have large amounts of E_T^{miss} , H_T (the scalar sum of the p_T of objects in the event), and many jets. All of these features can help isolate these events from backgrounds. To understand what cuts would optimize the sensitivity of the search, it is essential to first understand what these Standard Model backgrounds are.

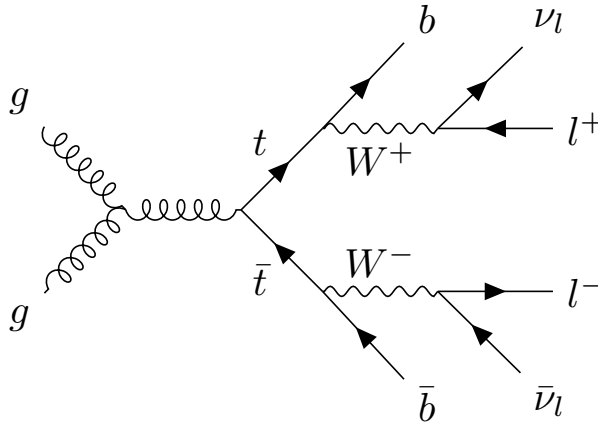


Figure 14: An example Feynman diagram of $t\bar{t}$ production and decay.

$t\bar{t}$ is the largest background for this search. [Figure 14](#) shows an example of this process, which can decay to many jets, leptons, and neutrinos, which are seen in the detector as E_T^{miss} . Thus, $t\bar{t}$ naturally has high E_T^{miss} and H_T , jets, and leptons from two different W boson decays, which may coincidentally form an invariant mass on the Z peak. These events are very difficult to separate from potential signals, though keeping the mass window small and increasing E_T^{miss} and H_T above the typical values for $t\bar{t}$ events can help reduce them.

DIBOSON production is the next leading background. These events can contain real Z bosons and will peak on-Z like a signal. In addition, in events like [Figure 15](#), an additional W boson can decay to another lepton and a neutrino, providing E_T^{miss} . The pictured process can occur with associated jets, but at reduced rates, so adding a jet requirement to the signal region can help reduce these events. If the

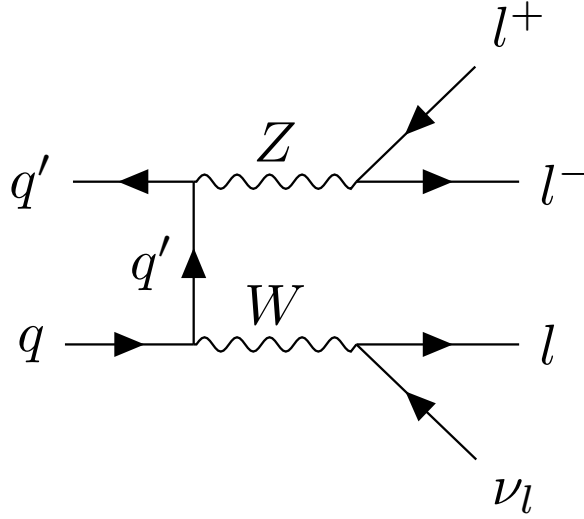


Figure 15: An example Feynman diagram of the production and decay of a WZ event.

W boson in this diagram instead decayed to two jets, there would be no true E_T^{miss} from a neutrino, so a E_T^{miss} cut in conjunction with a jet cut is very effective in reducing the total diboson background.

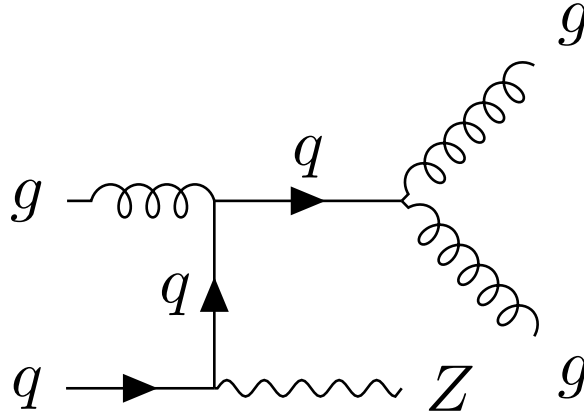


Figure 16: An example Feynman diagram of the production and decay of a $Z/\gamma^* + \text{jets}$ event.

$Z/\gamma^* + \text{JETS}$ processes are very common but, as shown in [Figure 16](#), don't produce any true E_T^{miss} or a very large number of jets. Thus a high H_T cut can help reduce this background, but a E_T^{miss} cut is the most powerful. Events with very mismeasured jets or leptons can fake high E_T^{miss} , but these drastic mismeasurements are rare.

Other processes can contribute to the Standard Model background at lower rates. Processes similar to $Z/\gamma^* + \text{jets}$ but with a W boson instead of a Z have real E_T^{miss} from leptonic W decays, but only one

lepton. However, a fake or non-prompt lepton can cause these events to look very similar to simulated signals. Additionally, there are rare processes such as $t\bar{t}$ in association with bosons that will also be difficult to separate from signal processes.

7.1 MONTE CARLO SAMPLES

To precisely compare simulated signal to backgrounds, MC samples are generated for each of these processes. [Table 1](#) details the method used to produce each sample. With these and the simulated background, optimizations on a signal region can be made to maximize potential for discovery or exclusion of simplified Supersymmetric models. These comparisons and the signal region definition can be found in [Section 9.1](#).

Table 1: Simulated background event samples used in this analysis with the corresponding matrix element and parton shower generators, cross-section order in α_s used to normalise the event yield, underlying-event tune and PDF set.

Physics process	Generator	Parton Shower	Cross section	Tune	PDF set
$t\bar{t} + W$ and $t\bar{t} + Z$ [7, 21]	MG5_AMC@NLO	Pythia 8.186	NLO [14, 25]	A14	NNPDF23LO
$t\bar{t} + WW$ [7]	MG5_AMC@NLO	Pythia 8.186	LO [11]	A14	NNPDF23LO
$t\bar{t}$ [10]	Powheg Box v2 r3026	Pythia 6.428	NNLO+NNLL [18, 19]	Perugia2012	NLO CT10
Single-top (Wt) [10]	Powheg Box v2 r2856	Pythia 6.428	Approx. NNLO [24]	Perugia2012	NLO CT10
WW ,	SHERPA 2.1.1	SHERPA 2.1.1	NNLO [13, 15]	SHERPA default	NLO CT10
WZ and ZZ [9]	SHERPA 2.1.1	SHERPA 2.1.1	NNLO [16, 17]	SHERPA default	NLO CT10
$Z/\gamma^*(\rightarrow \ell\ell) + \text{jets}$ [8]	SHERPA 2.1.1	SHERPA 2.1.1	NNLO [16, 17]	SHERPA default	NLO CT10

OBJECT IDENTIFICATION AND SELECTION

8.1 ELECTRONS

8.2 MUONS

8.3 JETS

8.4 PHOTONS

EVENT SELECTION

Table 2: Overview of all signal, control and validation regions used in the on-shell Z search. More details are given in the text. The flavour combination of the dilepton pair is denoted as either “SF” for same-flavour or “DF” for different flavour. All regions require at least two leptons, unless otherwise indicated. In the case of CR γ , VR-WZ, VR-ZZ, and VR-3L the number of leptons, rather than a specific flavour configuration, is indicated. The main requirements that distinguish the control and validation regions from the signal region are indicated in bold. Most of the kinematic quantities used to define these regions are discussed in the text. The quantity $m_T(\ell_3, E_T^{\text{miss}})$ indicates the transverse mass formed by the E_T^{miss} and the lepton which is not assigned to either of the Z-decay leptons.

On-shell Z regions	E_T^{miss} [GeV]	H_T^{incl} [GeV]	n_{jets}	$m_{\ell\ell}$ [GeV]	SF/DF	$\Delta\phi(\text{jet}_{12}, p_T^{\text{miss}})$	$m_T(\ell_3, E_T^{\text{miss}})$ [GeV]	$n_{\text{b-jets}}$
Signal region								
SRZ	> 225	> 600	≥ 2	$81 < m_{\ell\ell} < 101$	SF	> 0.4	—	—
Control regions								
CRZ	$< \mathbf{60}$	> 600	≥ 2	$81 < m_{\ell\ell} < 101$	SF	> 0.4	—	—
CR-FS	> 225	> 600	≥ 2	$\mathbf{61} < m_{\ell\ell} < \mathbf{121}$	DF	> 0.4	—	—
CRT	> 225	> 600	≥ 2	$> \mathbf{40}, m_{\ell\ell} \notin [\mathbf{81}, \mathbf{101}]$	SF	> 0.4	—	—
CR γ	—	> 600	≥ 2	—	0 ℓ , 1 γ	—	—	—
Validation regions								
VRZ	$< \mathbf{225}$	> 600	≥ 2	$81 < m_{\ell\ell} < 101$	SF	> 0.4	—	—
VRT	$\mathbf{100-200}$	> 600	≥ 2	$> \mathbf{40}, m_{\ell\ell} \notin [\mathbf{81}, \mathbf{101}]$	SF	> 0.4	—	—
VRS	$\mathbf{100-200}$	> 600	≥ 2	$81 < m_{\ell\ell} < 101$	SF	> 0.4	—	—
VR-FS	$\mathbf{100-200}$	> 600	≥ 2	$\mathbf{61} < m_{\ell\ell} < \mathbf{121}$	DF	> 0.4	—	—
VR-WZ	$\mathbf{100-200}$	—	—	—	3 ℓ	—	< 100	0
VR-ZZ	< 100	—	—	—	4 ℓ	—	—	0
VR-3L	$\mathbf{60-100}$	$> \mathbf{200}$	≥ 2	$81 < m_{\ell\ell} < 101$	3 ℓ	> 0.4	—	—

9.1 SIGNAL REGION

9.2 CONTROL AND VALIDATION REGIONS

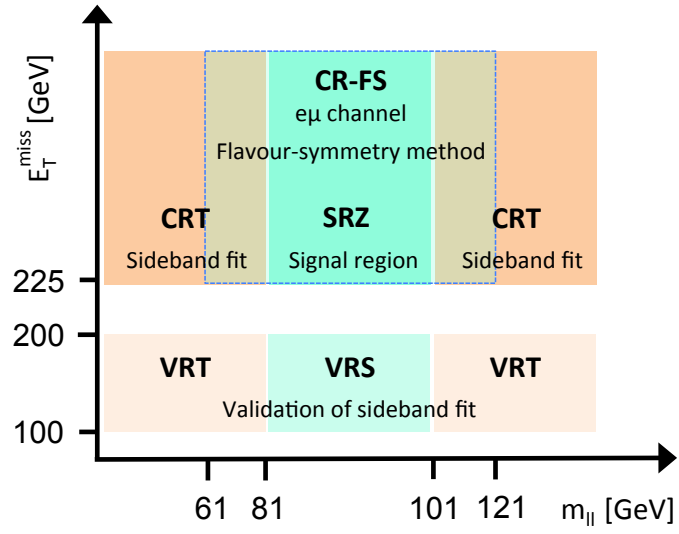


Figure 17: Schematic diagrams of the control, validation and signal regions for the on-shell Z (top) and edge (bottom) searches. For the on-shell Z search the various regions are shown in the $m_{\ell\ell} - E_T^{\text{miss}}$ plane, whereas in the case of the edge search the signal and validation regions are depicted in the $H_T - E_T^{\text{miss}}$ plane.

Trigger	L1	Notes
Single electron triggers		
HLT_e60_lhmedium	L1_EM22VHI	2015 and 2016
HLT_e60_lhmedium_nod0	L1_EM22VHI	2016 Only
HLT_e26_lhtight_nod0_ivarloose	L1_EM22VHI	Isolated; for evaluation in 2016
Di-electron triggers		
HLT_2e12_lhloose	L1_2EM13VH	2015 Only
HLT_2e17_lhvloose_nod0	L1_EM15VH	2016 Only
Single muon triggers		
HLT_mu50	L1_MU20	2015 and 2016
Di-muon triggers		
HLT_mu18_mu8noL1	L1_MU15	2015 Only
HLT_2mu14_nomucomb	L1_MU10	2016 Only
Electron-muon triggers		
HLT_e17_lhloose_mu14	L1_EM15VH_MU10	2015 Only
HLT_e7_lhmedium_mu24	L1_MU20	2015 Only
HLT_e17_lhloose_nod0_mu14	L1_MU10_EM15VH	2016 Only
HLT_e7_lhmedium_nod0_mu24	L1_MU20	2016 Only

Table 3: List of the triggers considered for this analysis. The corresponding L1 items are included for reference. The last column notes if the trigger is available in data.

Lepton p_T	Trigger in 2015	Trigger in 2016
Di-electron channel		
$p_T(e_1) > 65 \text{ GeV}$	HLT_e60_lhmedium	HLT_e60_lhmedium_nod0
$p_T(e_1) \leq 65 \text{ GeV}$	HLT_2e17_lhloose	HLT_2e17_lhvloose_nod0
Di-muon channel		
$p_T(\mu_1) > 52.5 \text{ GeV}$	HLT_mu50	HLT_mu50
$p_T(\mu_1) \leq 52.5 \text{ GeV}$	HLT_mu24_mu8noL1	HLT_2mu14_nomucomb
Electron-muon channel		
$p_T(e) > 65 \text{ GeV}$	HLT_e60_lhmedium	HLT_e60_lhmedium_nod0
$p_T(e) \leq 65 \text{ GeV}$ and $p_T(\mu) > 52.5 \text{ GeV}$	HLT_mu50	HLT_mu50
$p_T(e) \leq 65 \text{ GeV}$ and $p_T(\mu) \leq 52.5 \text{ GeV}$ and $p_T(e) < p_T(\mu)$	HLT_e7_lhmedium_mu24	HLT_e7_lhmedium_nod0_mu24
$p_T(e) \leq 65 \text{ GeV}$ and $p_T(\mu) \leq 52.5 \text{ GeV}$ and $p_T(\mu) < p_T(e)$	HLT_e17_lhloose_mu14	HLT_e17_lhloose_nod0_mu14

Table 4: Lepton trigger requirements used for the analysis in different regions of lepton- p_T phase space.

BACKGROUND ESTIMATION

This analysis requires two leptons that reconstruct to a Z mass, jets, E_T^{miss} , and H_T . Any standard model processes that produce this signature will appear as a background to the search. The most important task of the analysis is to identify and estimate these backgrounds, so that any excess of events appearing on top of the standard model background can be identified. The main backgrounds for this analysis are described in [Chapter 7](#). The largest background is from flavor symmetric processes, with smaller contributions coming from diboson processes, $Z/\gamma^* + \text{jets}$, rare top processes, and fake and non-prompt leptons.

10.1 FLAVOR SYMMETRIC PROCESSES

[FS](#) backgrounds include any processes that produce pairs of leptons with uncorrelated flavor in the final state. In this analysis, the largest contribution comes from $t\bar{t}$, with additional events from processes like WW and $Z \rightarrow \tau\tau$. In these processes, each lepton comes from a different decay. Unlike a $Z \rightarrow \ell\ell$ decay then, these leptons' flavors are completely independent.

10.1.1 Flavor Symmetry Method

As a consequence of the independence of the lepton flavors, any [FS](#) process should produce ee , $\mu\mu$, and $e\mu$ events in a 1:1:2 ratio. This ratio is taken advantage of by the flavor symmetry method by measuring $e\mu$ events in data and using them to predict the contribution of these processes in the ee and $\mu\mu$ channels. [[SUSY-2014-10](#)]

To estimate the number of events in SRZ, a control region called CR-FS is used. Both regions are defined in [Table 2](#). CR-FS is very similar to SRZ with two changes: it requires different-flavor leptons instead of the same-flavor leptons required by SRZ, and the $m_{\ell\ell}$ range it covers has been expanded by a factor of three, now ranging from 61 to 121 GeV. The expansion of the $m_{\ell\ell}$ window is done to increase the number of events in the control region, thus lowering the statistical uncertainty of the prediction¹.

¹ Though this statistical uncertainty is no longer dominant for the analysis, the method was developed for a smaller dataset for which this expansion dramatically decreased the total uncertainty on the background prediction. [[2](#)] Because of previous excesses seen, the signal region was not reoptimized for the larger dataset used in this search,

This control region is expected to be about 95% pure in [FS](#) processes, with most of the remaining events coming from fake or non-prompt leptons. The [FS](#) portion is made up primarily of $t\bar{t}$ ($\sim 80\%$), with additional contributions from Wt ($\sim 10\%$), WW ($\sim 10\%$), and $< 1\%$ $Z \rightarrow \tau\tau$.

After the number of data events are measured in CR-FS, correction factors are applied to account for trigger efficiencies, selection efficiencies, the $m_{\ell\ell}$ expansion, and the purity of the control region. Combining these factors, the estimate for number of events in the ee and $\mu\mu$ channels is as follows:

$$N_{ee}^{\text{est}} = \frac{1}{2} \cdot f_{\text{FS}} \cdot f_{Z\text{-mass}} \cdot \sum_{e\mu}^{N_{e\mu}^{\text{data}}} k_e(p_T^\mu, \eta^\mu) \cdot \alpha(p_T^{\ell_1}, \eta^{\ell_1}), \quad (17)$$

$$N_{\mu\mu}^{\text{est}} = \frac{1}{2} \cdot f_{\text{FS}} \cdot f_{Z\text{-mass}} \cdot \sum_{e\mu}^{N_{e\mu}^{\text{data}}} k_\mu(p_T^e, \eta^e) \cdot \alpha(p_T^{\ell_1}, \eta^{\ell_1}), \quad (18)$$

where $N_{e\mu}^{\text{data}}$ is the number of data events observed in CR-FS, $k_e(p_T, \eta)$ and $k_\mu(p_T, \eta)$ are relative selection efficiencies for electrons and muons, calculated in bins of p_T and η of the lepton to be replaced, and $\alpha(p_T, \eta)$ accounts for the different trigger efficiencies for events in each channel, binned based on the kinematics of the leading lepton. These k and α factors are calculated in an inclusive on- Z selection ($81 < m_{\ell\ell} / \text{GeV} < 101, \geq 2 \text{ jets}$), according to:

$$k_e(p_T, \eta) = \sqrt{\frac{N_{ee}^{\text{meas}}}{N_{\mu\mu}^{\text{meas}}}} \quad (19)$$

$$k_\mu(p_T, \eta) = \sqrt{\frac{N_{\mu\mu}^{\text{meas}}}{N_{ee}^{\text{meas}}}} \quad (20)$$

$$\alpha(p_T, \eta) = \frac{\sqrt{\epsilon_{ee}^{\text{trig}}(p_T, \eta) \times \epsilon_{\mu\mu}^{\text{trig}}(p_T, \eta)}}{\epsilon_{e\mu}^{\text{trig}}(p_T, \eta)} \quad (21)$$

where $\epsilon_{ee/\mu\mu}^{\text{trig}}$ is the trigger efficiency ² and $N_{ee/\mu\mu}^{\text{meas}}$ is the number of $ee/\mu\mu$ events in the inclusive on- Z region described above. Here $k_e(p_T, \eta) = 1/k_\mu(p_T, \eta)$, and this k factor is calculated separately for leading and sub-leading leptons, and the appropriate k value is selected based on the position of the lepton to be replaced.

but in future iterations of this analysis, the signal region have tighter cuts, making this decreased statistical uncertainty significant once again.

² This efficiency is defined by taking all events in the inclusive on- Z selection mentioned above and determining the fraction that passes the relevant trigger requirement defined by [Table 4](#). Because the offline selection made on these events already has some trigger dependence, this calculation of efficiency could be slightly biased. This effect is considered in [Section 11.1.1](#), and the uncertainty applied to the estimate as a result is described.

Region	ee prediction	$\mu\mu$ prediction	combined prediction
Prediction for 14.7 fb^{-1} of 2015+2016 Data			
SRZ	16.50 ± 2.11	16.67 ± 2.04	33.16 ± 3.94
VRS	49.70 ± 4.61	49.60 ± 4.56	99.31 ± 8.47

Table 5: Yields in signal and validation regions for the flavor symmetric background. Errors include statistical uncertainty, uncertainty from MC closure, uncertainty from the k and α factors, uncertainty due to deriving triggers efficiencies from a DAOD, and uncertainty on the MC shape used to correct for the $m_{\ell\ell}$ expansion.

Electron, muon, and trigger efficiencies are all quite close to one, and as a consequence, these correction factors are typically within 10% of unity, except in the region $|\eta| < 0.1$ where, because of the lack of coverage of the muon spectrometer, they are up to 50% from unity.

The estimate is corrected for contamination of non-FS backgrounds in CR-FS. A scaling factor is determined by subtracting these backgrounds from the number of $e\mu$ events measured in CR-FS, then determining the fraction of the original data events that this pure-FS number represents. The estimate for the other backgrounds is taken from MC for all processes except fakes, which are predicted from data using the matrix method described in Section 10.4.

A prediction is made both for the signal region, SRZ, and the lower- E_T^{miss} validation region, VRS. This process is performed separately for the two data taking periods, 2015 and 2016, because of the changing triggers and conditions. The results are then summed together, as shown in Table 5. The uncertainties in this table are discussed in Section 11.1.1.

10.1.2 Sideband Fit Method

As a crosscheck to the flavor symmetry method, a MC-based method is used. This method is called a “sideband fit,” and it begins with a MC estimate of the signal region across a $m_{\ell\ell}$ range that includes all values above 40 GeV. This region, excluding the on-Z range that makes up the Signal Region (SR), is used as a control region, defined as CRT in Table 2.

The total data yield is measured in CRT, and the MC is fit to match this yield with one normalization factor which scales the overall $t\bar{t}$ background. As mentioned in the previous section, $t\bar{t}$ is the dominant FS background, making up about 80% of the total events. All other backgrounds contributing to this control region are constrained by their uncertainties, which are used as nuisance parameters in the fit. The normalization factor from this fit is then applied to the $t\bar{t}$ MC

yield in the [SR](#), and combined with the [MC](#) predictions of the other [FS](#) processes in the [SR](#) to give a final estimate of this background. The results of the fit can be seen in [Table 6](#).

The method is repeated in VRS to validate the method. The normalization factors, listed in [Table 7](#), are significantly different for the two regions. This is expected because there is a known problem in which the $t\bar{t}$ [MC](#) over-predicts the high- E_T^{miss} tail. This effect can be seen in a data-[MC](#) comparison in [Figure 18](#). This is likely due to a mismodeling of the top quark p_T distribution, which does not match the spectrum seen in data [[Aad:2015hna](#), [Khachatryan:2016gxp](#)]. However, this method corrects for this mismodeling by performing fits in regions very kinematically similar to the signal region.

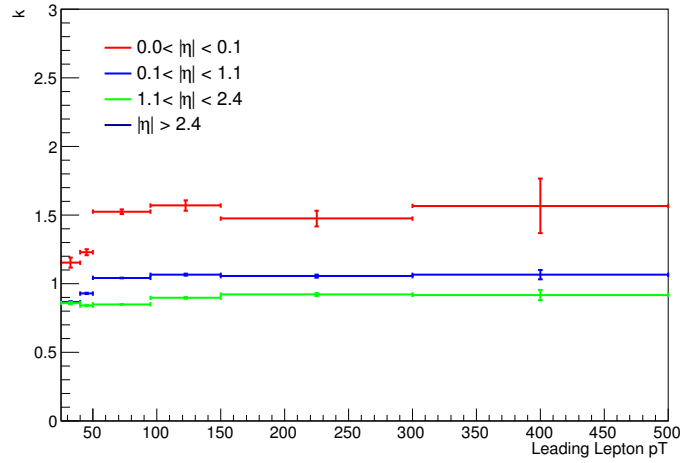


Figure 18: Comparison of data and [MC](#) in a selection like SRZ, without the E_T^{miss} cut.

This method is extremely effective as a crosscheck because it uses a completely independent dataset from the flavor symmetry method, and the two methods have very little overlap in dependence on [MC](#). They produce consistent results in both SRZ and VRS, as shown in [Table 8](#).

10.2 $Z/\gamma^* + \text{JETS}$ BACKGROUND

10.3 DIBOSONS

10.4 FAKES

The fakes background consists of processes that produce only one lepton, but whose events are otherwise kinematically similar to the [SR](#). These processes include semileptonic $t\bar{t}$, W +jets processes, and single top. Though these processes typically only produce one lepton, they can be reconstructed with two leptons due to a hadron being misiden-

channel	$ee/\mu\mu$ CRT	$ee/\mu\mu$ SRZ	ee SRZ	$ee/\mu\mu$ SRZ
Observed events	273	60	35	25
Fitted bkg events	272.76 ± 16.88	49.33 ± 8.04	27.09 ± 4.73	22.70 ± 3.80
Fitted flavour symmetry events	236.96 ± 21.66	28.96 ± 7.47	16.41 ± 4.33	12.55 ± 3.29
Fitted WZ/ZZ events	4.03 ± 1.13	14.27 ± 4.45	7.81 ± 2.45	6.46 ± 2.07
Fitted SHERPA $Z/\gamma^* + \text{jets}$ events	1.95 ± 0.14	0.00 ± 0.00	0.00 ± 0.00	0.00 ± 0.00
Data-driven $Z/\gamma^* + \text{jets}$ ($\gamma + \text{jets}$) events	0.00 ± 0.00	3.10 ± 2.25	$1.02^{+1.25}_{-1.02}$	2.08 ± 1.38
Fitted rare top events	4.04 ± 1.04	2.90 ± 0.76	1.39 ± 0.38	1.50 ± 0.40
Data-driven fake lepton events	25.78 ± 14.26	$0.10^{+0.18}_{-0.10}$	0.46 ± 0.45	0.10 ± 0.01
MC exp. SM events	366.71	61.01	33.73	27.74
MC exp. flavour symmetry events	331.32	40.72	23.09	17.63
MC exp. WZ/ZZ events	4.02	14.20	7.77	6.43
MC exp. SHERPA $Z/\gamma^* + \text{jets}$ events	1.94	0.00	0.00	0.00
Data-driven exp. $Z/\gamma^* + \text{jets}$ ($\gamma + \text{jets}$) events	0.00	3.10	1.02	2.08
MC exp. rare top events	4.04	2.89	1.39	1.50
Data-driven exp. fake lepton events	25.39	0.10	0.46	0.10

Table 6: Background fit results from the sideband fit method. The $\mu\mu$ MC's normalization is taken as a free parameter in the fit to data in CRT, then that normalization factor is applied in SRZ. The results are shown here both divided between the ee and $\mu\mu$ channels and summed together. All other backgrounds are taken from MC in CRT, while in SRZ, the $Z/\gamma^* + \text{jets}$ contribution is taken from the $\gamma + \text{jets}$ method. The uncertainties quoted include both statistical and systematic components.

Fit region	$t\bar{t}$ normalization
CRT	0.64 ± 0.18
VRT	0.80 ± 0.09

Table 7: Summary of the $t\bar{t}$ normalization factors calculated by the sideband fit to CRT and VRT for the 2015+2016 data.

Region	Flavour-symmetry	Sideband fit
SRZ	33 ± 4	29 ± 7
VR-S	99 ± 8	92 ± 25

Table 8: Comparison of [fS](#) background predictions from the nominal method, the flavor symmetry method, and the cross-check, the sideband fit method. Uncertainties include statistical and systematic uncertainties in both cases.

tified as a lepton or from real non-prompt lepton resulting from photon conversions or b -hadron decays. As such, it includes both events that have been properly reconstructed and many that are included in the [SR](#) due to imperfect reconstruction. As with the $Z/\gamma^* + \text{jets}$ background, it is very difficult to predict with [MC](#) because the flaws in reconstruction are typically less well described by the models used in [MC](#) production than the successes. Nonetheless, a rough estimate can be made of this background by using [MC](#), which indicates that the number of fake events in SRZ is consistent with zero.

Despite the small predicted contribution in the [SR](#), a data-driven method called the “matrix method” is employed to estimate these fake events [6]. This method is also used to estimate the fakes contribution to other control and validation regions where their effect is often more significant.

In the matrix method, the quality requirements for signal leptons are loosened to give a selection of baseline leptons, which consist of a higher fraction of fake leptons. In each CR, VR, or SR, the remaining kinematic selections are made on the baseline leptons, and the number of leptons in that region which pass the signal lepton requirements (N_{pass}) and the number which fail (N_{fail}) are measured. For a 1-lepton selection, these quantities can be used to predict the number of fake events that pass the selection according to:

$$N_{\text{pass}}^{\text{fake}} = \frac{N_{\text{fail}} - (1/\epsilon^{\text{real}} - 1) \times N_{\text{pass}}}{1/\epsilon^{\text{fake}} - 1/\epsilon^{\text{real}}}. \quad (22)$$

The efficiencies ϵ^{real} and ϵ^{fake} give the relative identification efficiency from baseline to signal for genuine, prompt leptons and fake

and non-prompt leptons, respectively. To calculate ϵ^{real} , the tag-and-probe method is performed a selection of $Z \rightarrow \ell\ell$ data events, CR-real, described in Table 9.

Fakes regions	E_T^{miss} [GeV]	H_T [GeV]	n_{jets}	$m_{\ell\ell}$ [GeV]	SF/DF	OS/SS	n_ℓ
CR-real	—	> 200	≥ 2	81–101	2ℓ SF	OS	2
CR-fake	< 125	—	—	> 12	2ℓ SF/DF	SS	≥ 2

Table 9: Control regions used to measure efficiencies of real and fake leptons. The flavour combination of the dilepton pair is denoted as either “SF” for same-flavour or “DF” for different flavour. The charge combination of the leading lepton pairs are given as “SS” for same-sign or “OS” for opposite-sign.

For a 2-lepton selection, the equation is more complicated, and it requires a 2x2 matrix

10.5 OTHER RARE PROCESSES

SYSTEMATIC UNCERTAINTIES

11.1 UNCERTAINTIES ON DATA-DRIVEN BACKGROUNDS

11.1.1 *Uncertainties on the Flavor Symmetry Method*

The flavor symmetry method is a data driven method that makes its primarily on based events populating an [SR](#)-like Control Region ([CR](#)) in the different-flavor channel. The statistical uncertainty on these events makes up the dominant uncertainty on the method. To reduce this uncertainty, the $m_{\ell\ell}$ range on the [CR](#) is expanded, tripling the number of events in CR-FS. Though this reduces the statistical uncertainty significantly, it is still significantly higher than any of the other systematic uncertainties on this method, as seen in [Table 10](#). Also included in the statistical uncertainty column is the uncertainty on the number of non-FS events in CR-FS, which is used to scale the prediction to remove any contamination in the [CR](#).

Reg.	Ch.	Pred.	Uncertainties					
			stat.	MC	k	dAOD	$m_{\ell\ell}$	total
				clos.	and α	usage	shape	
SRZ	ee	16.50	1.82	0.88	0.53	0.12	0.22	2.11
	$\mu\mu$	16.67	1.83	0.79	0.33	0.11	0.23	2.04
	$ee+\mu\mu$	33.16	3.66	1.07	0.86	0.23	0.45	3.94
VRS	ee	49.70	3.21	2.34	2.20	0.34	0.75	4.61
	$\mu\mu$	49.60	3.14	2.88	1.40	0.31	0.75	4.56
	$ee+\mu\mu$	99.31	6.34	4.00	3.60	0.65	1.49	8.47

Table 10: Uncertainties in the on-Z signal and validation regions. Nominal predictions are given with statistical uncertainty (including uncertainty from subtracted backgrounds), MC Closure uncertainty, uncertainty on the prediction from varying k and α by their statistical uncertainties, comparing the efficiencies from AODs to that of DAODs, and on the $m_{\ell\ell}$ widening, which includes MC statistics and a data/MC comparison in a loosened region.

The next largest contribution to the uncertainty comes from [MC](#) closure tests, which are used to determine how effective the method is in its prediction. If, for example, using weights derived from an inclusive selection at high E_T^{miss} lead to a bias, the closure test would indicate that and an appropriate uncertainty could be placed on the

estimate based on the difference between the MC and the prediction. In this test, the entire FS procedure is performed on $t\bar{t}$ MC, including a recalculation of weighting factors α and k . The prediction from $e\mu$ events in MC is compared to the MC ee and $\mu\mu$ events, as seen in Figure 19. The difference between the two predictions is then summed in quadrature with the statistical uncertainty on each prediction to give the total closure uncertainty seen in Table 10. In these closure tests, all predictions agree within the statistical uncertainty, so the bulk of the resulting error is due to MC statistics.

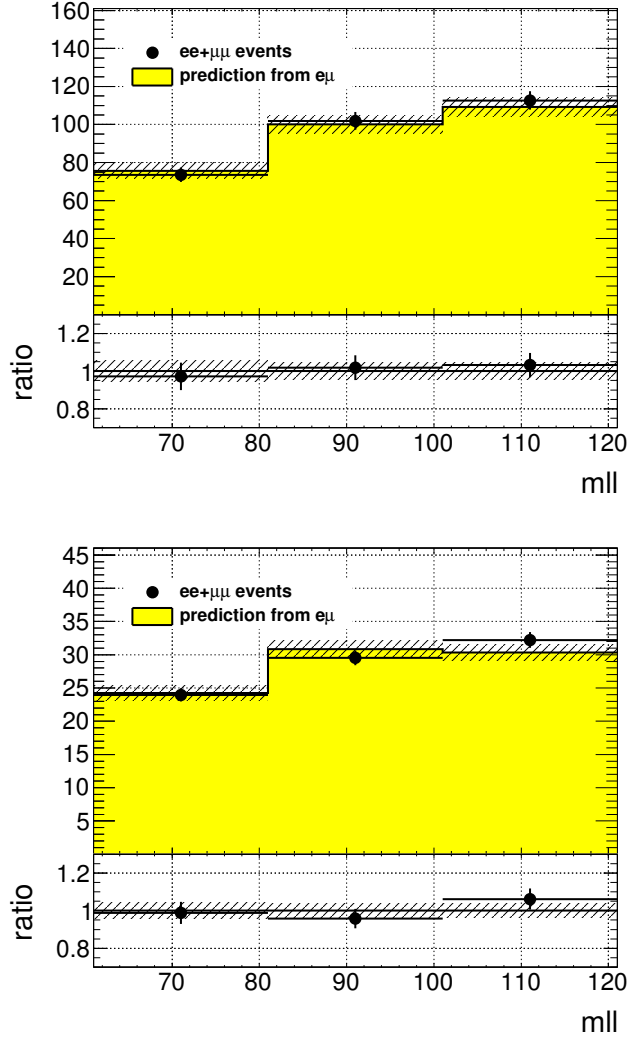


Figure 19: MC closure plots of VRS (top) and SRZ (bottom). The number of events from MC (black points) is compared to the number of events predicted from the flavor symmetry method (yellow histogram). The comparison is performed before the expanded $m_{\ell\ell}$ window is used to predict the on-Z bin.

A small uncertainty is added based on the statistical uncertainty on the k and α factors derived from data. These factors are measured

in many different bins (see, for example, the different measurements of k in Figure 20), and as a consequence, some bins can have very large statistical uncertainties. To assess the uncertainty on the total estimate, each measurement of these factors is varied by its uncertainty in order to produce the maximum and minimum possible prediction. This error is symmetrized, and the resulting change in the prediction is included in Table 10.

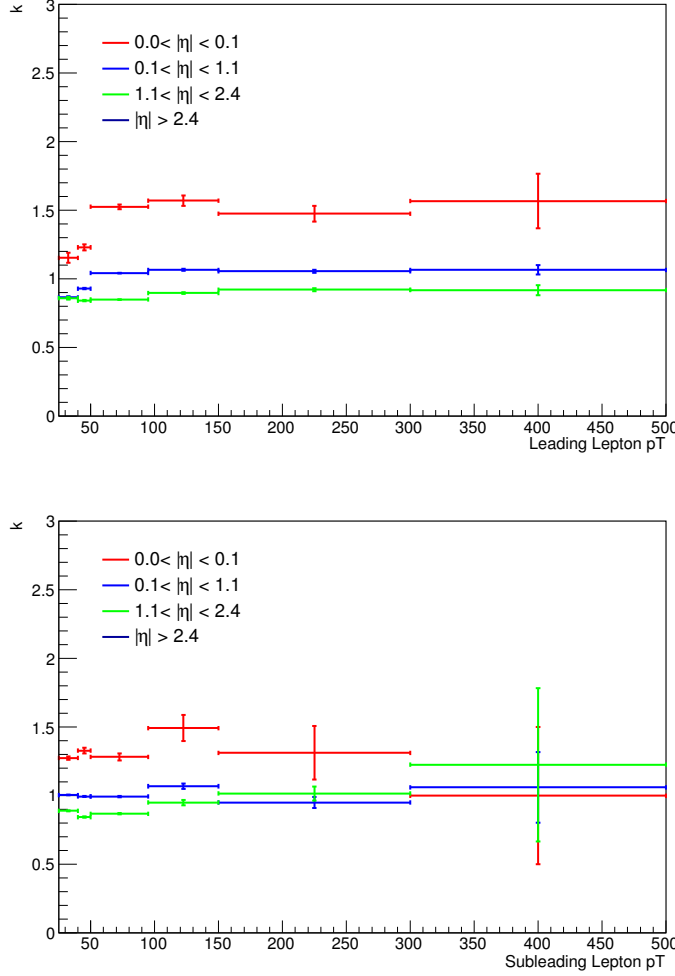


Figure 20: Measurements of k , the ratio of electron to muon events, in bins of p_T and η . On the top is the measurements indexed by the leading lepton, while the measurements indexed by the subleading lepton are on the bottom. These efficiencies are for the 2016 dataset.

The next uncertainty considers a potential bias in the way the α factors are calculated. Because they are derived from data, there is already trigger dependence in data collection (only events passing a trigger are stored) and further dependences is introduced by the use of the “dAOD” data format. This is short for derived Analysis Object Data (AOD), and they provide smaller, more efficient versions of the complete ATLAS datasets. These dAODs are designed with spe-

cific analyses in mind, filtering on the triggers and objects required by the analyses. As a consequence, there are explicit requirements that lepton or E_T^{miss} triggers are passed before events are included in the dAODs used by this analysis. These requirements mean that the trigger efficiencies calculated from these samples do not include all possible events, and will have artificially high values. However, because the ratio of trigger efficiencies is the quantity needed for this analysis (see Equation 21), this will only bias the prediction if the different channels are differently impacted by the trigger preselection.

Calculating the FS prediction's dependence on these biases requires the use of MC. With a generated MC sample, there is no trigger dependence, so an unskimmed sample can be compared to a typical MC dAOD to identify the effect of the skimming. Figure 21 shows a comparison of the α factors calculated for different bins in E_T^{miss} from the nominal source, data, as well as these two MC sources. A E_T^{miss} dependence would be the most likely bias between the two MC-derived α factors because E_T^{miss} triggers are the only triggers besides lepton triggers that will allow an event to be accepted into the dAOD used by this analysis. Though there is some difference between the data-derived α and those taken from MC, it is clear from this plot that there is very little dependence on the choice of an unskimmed or skimmed sample. The actual calculation of the uncertainty is performed by repeating the flavor symmetric method in MC with each of the two α factors and observing the difference between the estimates.

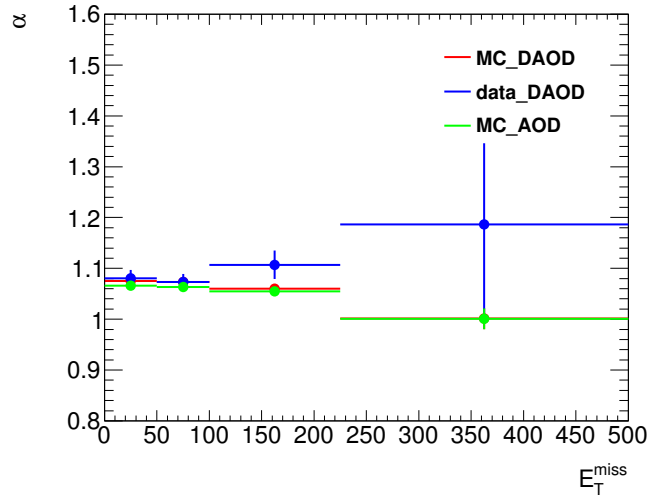


Figure 21: α , the trigger efficiency ratio, calculated as a function of E_T^{miss} from three different sources: data, the usual skimmed $t\bar{t}$ MC, and an unskimmed $t\bar{t}$ MC.

The last uncertainty relates to the main MC dependence of the method - the $m_{\ell\ell}$ shape of the FS background. A correction factor is taken from MC in order to account for the $m_{\ell\ell}$ widening, and the accuracy of that factor must be checked. Its shape is compared to that

of data in region similar to VR-FS, but with an H_T cut lowered to 300 GeV to increase statistics. The difference between the fraction of events on the Z mass peak in data and MC in this region is taken as a systematic uncertainty. To confirm that using this lowered H_T cut still gives a valid answer, the fractions are compared as a function of H_T in Figure 22. In these plots, especially in the higher-statistics 2016 plot, it is clear both that the data and MC agree very well and that there is no strong H_T dependence.

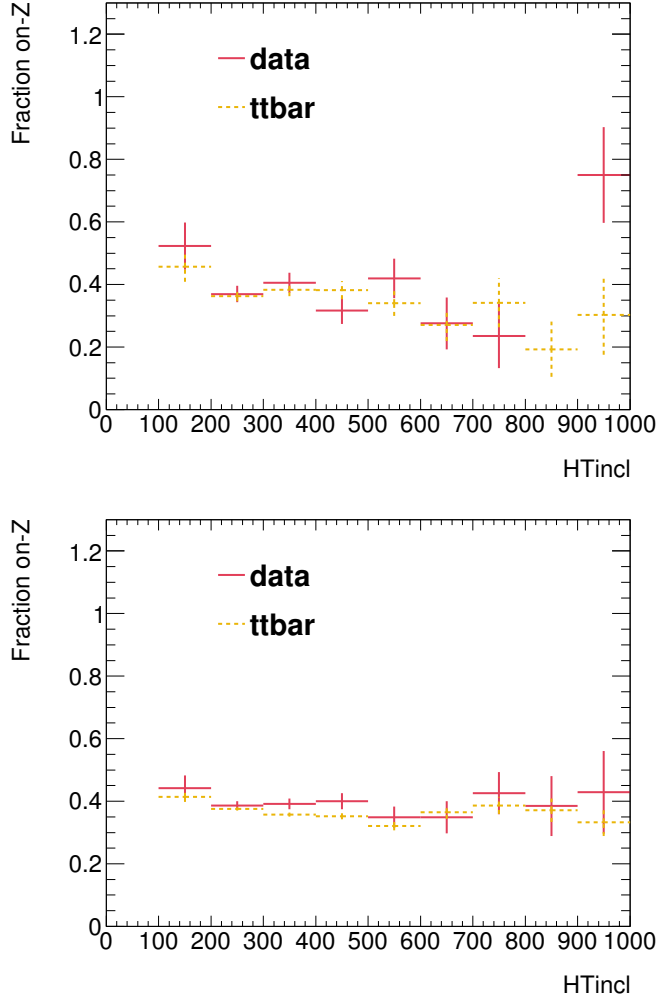


Figure 22: Plots of the fraction of on-Z events with a VR-FS-like selection as a function of H_T . The top figure shows 2015 data and MC while the bottom figure shows the same for 2016.

These uncertainties are each calculated independently for the two datasets then added. Statistical uncertainties, including the MC closure statistical uncertainties and the k and α uncertainties, are added in quadrature between the two years. Uncertainties that are more likely to be correlated, such as the difference between the two estimates in MC closure and the dependence on using a dAOD to cal-

culate trigger efficiencies, are added linearly. The total uncertainty is about 12% of the nominal prediction in the signal region and about 9% in the validation region.

11.1.2 *Uncertainties on the γ +jets Method*

11.1.3 *Uncertainties on the Fakes Background*

11.2 EXPERIMENTAL UNCERTAINTIES

11.3 THEORETICAL UNCERTAINTIES

11.4 SIGNAL UNCERTAINTIES

11.5 IMPACT OF UNCERTAINTIES ON THE SIGNAL REGION

RESULTS

Part V

CONCLUSIONS

This section presents conclusions and an outlook for future work.

CONCLUSIONS

Part VI

APPENDIX

APPENDIX TEST

Aliquam lectus. Vivamus leo. Quisque ornare tellus ullamcorper nulla. Mauris porttitor pharetra tortor. Sed fringilla justo sed mauris. Mauris tellus. Sed non leo. Nullam elementum, magna in cursus sodales, augue est scelerisque sapien, venenatis congue nulla arcu et pede. Ut suscipit enim vel sapien. Donec congue. Maecenas urna mi, suscipit in, placerat ut, vestibulum ut, massa. Fusce ultrices nulla et nisl.

Etiam ac leo a risus tristique nonummy. Donec dignissim tincidunt nulla. Vestibulum rhoncus molestie odio. Sed lobortis, justo et pretium lobortis, mauris turpis condimentum augue, nec ultricies nibh arcu pretium enim. Nunc purus neque, placerat id, imperdiet sed, pellentesque nec, nisl. Vestibulum imperdiet neque non sem accumsan laoreet. In hac habitasse platea dictumst. Etiam condimentum facilisis libero. Suspendisse in elit quis nisl aliquam dapibus. Pellentesque auctor sapien. Sed egestas sapien nec lectus. Pellentesque vel dui vel neque bibendum viverra. Aliquam porttitor nisl nec pede. Proin mattis libero vel turpis. Donec rutrum mauris et libero. Proin euismod porta felis. Nam lobortis, metus quis elementum commodo, nunc lectus elementum mauris, eget vulputate ligula tellus eu neque. Vivamus eu dolor.

A.1 APPENDIX SECTION TEST

Nulla in ipsum. Praesent eros nulla, congue vitae, euismod ut, commodo a, wisi. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Aenean nonummy magna non leo. Sed felis erat, ullamcorper in, dictum non, ultricies ut, lectus. Proin vel arcu a odio lobortis euismod. Vestibulum ante ipsum primis in faucibus orci luctus et ultrices posuere cubilia Curae; Proin ut est. Aliquam odio. Pellentesque massa turpis, cursus eu, euismod nec, tempor congue, nulla. Duis viverra gravida mauris. Cras tincidunt. Curabitur eros ligula, varius ut, pulvinar in, cursus faucibus, augue.

More dummy text

Nulla mattis luctus nulla. Duis commodo velit at leo. Aliquam vulputate magna et leo. Nam vestibulum ullamcorper leo. Vestibulum condimentum rutrum mauris. Donec id mauris. Morbi molestie justo et pede. Vivamus eget turpis sed nisl cursus tempor. Curabitur mollis sapien condimentum nunc. In wisi nisl, malesuada at, dignissim sit amet, lobortis in, odio. Aenean consequat arcu a ante. Pellentesque porta elit sit amet orci. Etiam at turpis nec elit ultricies imperdiet. Nulla facilisi. In hac habitasse platea dictumst. Suspendisse

LABITUR BONORUM PRI NO	QUE VISTA	HUMAN
fastidii ea ius	germano	demonstratea
suscipit instructor	titulo	personas
quaestio philosophia	facto	demonstrated

Table 11: Autem usu id.

viverra aliquam risus. Nullam pede justo, molestie nonummy, scelerisque eu, facilisis vel, arcu.

A.2 ANOTHER APPENDIX SECTION TEST

Curabitur tellus magna, porttitor a, commodo a, commodo in, tortor. Donec interdum. Praesent scelerisque. Maecenas posuere sodales odio. Vivamus metus lacus, varius quis, imperdiet quis, rhoncus a, turpis. Etiam ligula arcu, elementum a, venenatis quis, sollicitudin sed, metus. Donec nunc pede, tincidunt in, venenatis vitae, faucibus vel, nibh. Pellentesque wisi. Nullam malesuada. Morbi ut tellus ut pede tincidunt porta. Lorem ipsum dolor sit amet, consectetur adipiscing elit. Etiam congue neque id dolor.

Donec et nisl at wisi luctus bibendum. Nam interdum tellus ac libero. Sed sem justo, laoreet vitae, fringilla at, adipiscing ut, nibh. Maecenas non sem quis tortor eleifend fermentum. Etiam id tortor ac mauris porta vulputate. Integer porta neque vitae massa. Maecenas tempus libero a libero posuere dictum. Vestibulum ante ipsum primis in faucibus orci luctus et ultrices posuere cubilia Curae; Aenean quis mauris sed elit commodo placerat. Class aptent taciti sociosqu ad litora torquent per conubia nostra, per inceptos hymenaeos. Vivamus rhoncus tincidunt libero. Etiam elementum pretium justo. Vivamus est. Morbi a tellus eget pede tristique commodo. Nulla nisl. Vestibulum sed nisl eu sapien cursus rutrum.

There is also a useless Pascal listing below: [Listing 1](#).

Listing 1: A floating example (listings manual)

```

1 for i:=maxint downto 0 do
  begin
    { do nothing }
  end;
```

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