CTL Model Check

Esame di Metodi Formali per la Verifica di Sistemi

Marco Buracchi Stefano Martina marco.buracchi1@stud.unifi.it stefano.martina@stud.unifi.it



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Computation Tree Logic (CTL)

Grammatica

$$\begin{array}{ll} \Phi & ::= & \textit{true} |a| \Phi_1 \wedge \Phi_2 |\neg \Phi| \exists \varphi | \forall \varphi \\ \\ \varphi & ::= & \bigcirc \Phi |\Phi_1 \, \textbf{U} \, \Phi_2 \end{array}$$

- ✓ Φ sono "state formula"
- $\checkmark \varphi$ sono "path formula"

Operatori derivati

$$\exists \Diamond \Phi = \exists (true \mathbf{U} \Phi)
\forall \Diamond \Phi = \forall (true \mathbf{U} \Phi)
\exists \Box \Phi = \neg \forall \Diamond \neg \Phi$$

 $\forall \Box \Phi = \neg \exists \Diamond \neg \Phi$

CTL Existential Normal Form (ENF)

Grammatica

$$\Phi ::= true|a|\Phi_1 \wedge \Phi_2|\neg \Phi|\exists \bigcirc \Phi|\exists (\Phi_1 \mathbf{U} \Phi_2)|\exists \Box \Phi$$

Leggi

$$\begin{array}{cccc} \forall \bigcirc \Phi & \equiv & \neg \exists \bigcirc \neg \Phi \\ \forall (\Phi \ \mathbf{U} \ \Psi) & \equiv & \neg \exists (\neg \Psi \ \mathbf{U} \ (\neg \Phi \land \neg \Psi)) \land \neg \exists \Box \neg \Psi \\ \forall \Diamond \Phi & \equiv & \neg \exists \Box \neg \Phi \\ \forall \Box \Phi & \equiv & \neg \exists \Diamond \neg \Phi = \neg \exists (\textit{true} \ \mathbf{U} \ \neg \Phi) \end{array}$$

- $\checkmark \forall (\Phi \cup \Psi)$ comporta esplosione esponenziale della formula
- ✓ utile anche la formula vista prima: $\exists \Diamond \Phi = \exists (true \, \mathbf{U} \, \Phi)$

Weak Until

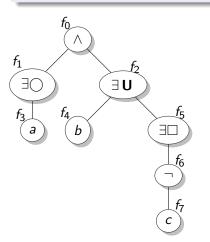
Equivalenza

$$\exists (\Phi \mathbf{W} \Psi) = \neg \forall ((\Phi \land \neg \Psi) \mathbf{U} (\neg \Phi \land \neg \Psi))
= \exists (\Phi \mathbf{U} \Psi) \lor \exists \Box \Phi
= \neg (\neg \exists (\Phi \mathbf{U} \Psi) \land \neg \exists \Box \Phi)
\forall (\Phi \mathbf{W} \Psi) = \neg \exists ((\Phi \land \neg \Psi) \mathbf{U} (\neg \Phi \land \neg \Psi))$$

Formula example

Formula

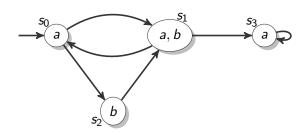
$$\Phi = \exists \bigcirc a \land \exists (b \cup \exists \Box \neg c) \equiv EX(a) \& (b EU (EG !c))$$



```
f2 EU
f3 ap a
f4 ap b
f6 !
f7 ap c
f5 f6
f6 f7
```

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Implementazione Transition System (TS)



```
1 s0 true a
2 s1 false a,b
3 s2 false b
4 s3 false a
5
6 s0 s1
7 s0 s2
8 s1 s0
9 s1 s3
10 s2 s1
11 s3 s3
```

CTL Model Checking

- ✓ Verificare se $TS \models \Phi$
 - calcolare ricorsivamente Sat(Φ)

$$Sat(true) = S$$

$$Sat(a) = \{s \in S | a \in L(s)\} \quad , \forall a \in AP$$

$$Sat(\Phi \land \Psi) = Sat(\Phi) \cap Sat(\Psi)$$

$$Sat(\neg \Phi) = S \setminus Sat(\Phi)$$

$$Sat(\exists \bigcirc \Phi) = \{s \in S | Post(s) \cap Sat(\Phi) \neq \emptyset\}$$

$$Sat(\exists (\Phi \mathbf{U} \Psi)) = \text{il più piccolo } T \subseteq S \text{ t.c.}$$

$$Sat(\Psi) \cup \{s \in Sat(\Phi) | Post(s) \cap T \neq \emptyset\} \subseteq T$$

$$Sat(\exists \Box \Phi) = \text{il più grande } T \subseteq S \text{ t.c.}$$

$$T \subseteq \{s \in Sat(\Phi) | Post(s) \cap T \neq \emptyset\}$$

▶ $TS \models \Phi \Leftrightarrow I \subseteq Sat(\Phi)$

Implementazione costruttore

```
def __init__(self, transitionSystem):
            A ctlChecker is linked to a certain transition system. When
13
            you build a CtlChecker you need to pass a TransitionSystem to
14
15
16
            self._syntax = syntax.Syntax()
            self._conv = conversions.Conversions()
18
            self. ts = transitionSystem
19
            self._callDic = {
                self. svntax.true
                                            : self. satTrue.
                self._syntax.ap
                                            : self._satAp,
                self._syntax.land
                                            : self._satAnd,
24
                self._syntax.lor
                                            : self. satConversionTwoSons.
25
                self. svntax.lnot
                                            : self. satNot.
26
                self._syntax.implies
                                            : self._satConversionTwoSonsOrdered,
                self._syntax.equals
                                            : self._satConversionTwoSons,
28
                self. svntax.exNext
                                            : self. satExNext.
29
                self._syntax.exUntil
                                            : self._satExUntil,
30
                self._syntax.exAlways
                                            : self._satExAlways,
31
                self. svntax.exEventually
                                            : self. satConversionOneSon.
32
                self._syntax.faNext
                                            : self._satConversionOneSon,
33
                self._syntax.faUntil
                                               self._satConversionTwoSonsOrdered,
34
                self. svntax.faAlwavs
                                            : self. satConversionOneSon.
35
                self._syntax.faEventually : self._satConversionOneSon,
36
                self._syntax.exWeakUntil
                                          : self._satConversionTwoSonsOrdered,
37
                self. svntax.faWeakUntil
                                            : self. satConversionTwoSonsOrdered.
38
                self. svntax.phiNode
                                            : self. satPhi.
39
            }
```

```
def sat(self, ctlFormule):

201

"""

202

The function that compute the satisfaction set of a formula

203

and is callable by outside the class. Basically it calls _sat

204

initializing the current node with the root of the formula.

205

"""

206

return self._sat(ctlFormule.graph.copy(), [s for s,a in

condition of the current of the formula.

207

ctlFormule.graph.nodes(data=True) if a['root'] ==True][0])
```

```
def _satTrue(self, tree, currNode):

"""

Return satisfation set for 'true', that is all the nodes of

the transition system.

"""

return set(self._ts.graph.nodes())
```

```
48
        def _satAp(self, tree, currNode):
49
50
            Return satisfation set for an atomic proposition, that is all
51
            the nodes of the transition system that contain that atom.
52
53
            retSet = set()
54
            for stato,att in self._ts.graph.nodes(data=True):
                 if tree.node[currNode]['val'] in att['att']:
56
                    retSet.add(stato)
57
58
            return retSet
```

```
60 def _satAnd(self, tree, currNode):
61 """
62 Return satisfation set for 'phi and psi', that is the
63 intersection of the satisfation sets of phi and psi.
64 """
65 sonA = tree.successors(currNode)[0]
66 sonB = tree.successors(currNode)[1]
67
68 return self._sat(tree, sonA).intersection(self._sat(tree, sonB))
```

```
def satExNext(self. tree. currNode):
78
             Return satisfation set for 'EX phi', that is the set of nodes that
             have a successor that satisfy phi.
81
82
             retSet = set()
83
             satPhi = self._sat(tree, tree.successors(currNode)[0])
84
85
            for stato in self._ts.graph.nodes():
86
                 if set(self._ts.graph.successors(stato)).intersection(satPhi): #true if

→ not empty

87
                     retSet.add(stato)
88
89
             return retSet
```

```
91
         def _satExUntil(self, tree, currNode):
92
93
             Return satisfation set for 'E(phi U psi)'. that is the set of nodes that
94
             have a track that satisfy phi ended by a state that satisfy
95
             psi. This set is calculated going backward starting from the
96
             states that satisfy psi, adding the states that satisfy phi
97
             and have an edge to the already found states.
98
99
             leftSon = [x for x in tree[currNode] if tree[currNode][x]['son'] ==
                   → self._syntax.leftSon][0]
100
             rightSon = [x for x in tree[currNode] if tree[currNode][x]['son'] ==

→ self._syntax.rightSon][0]
             S = self._sat(tree, leftSon)
             E = self._sat(tree, rightSon)
             T = E.copv()
104
105
106
             while E: #while not empty
                 r = E.pop()
                 for s in self._ts.graph.predecessors(r):
108
109
                     if s in S.difference(T):
                          E.add(s)
                         T.add(s)
             return T
```

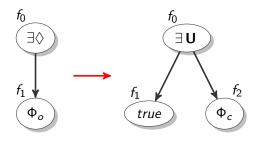
```
def _satExAlways(self, tree, currNode):
             Return satisfation set for 'EG phi', that is the set of nodes
118
             that have a track that satisfy always phi. This set is
             calculated using counters that start with the numbers of
119
120
             neighbours for each state that satisfy phi, and then remove a
             state from the set only if every neighbour don't satisfy phi.
123
124
             T = self._sat(tree, tree.successors(currNode)[0])
125
             E = set(self._ts.graph.nodes()).difference(T)
126
             count = dict()
             for s in T:
128
                  count[s] = len(self._ts.graph.successors(s))
129
130
             while E:
                 r = E.pop()
                 for s in self. ts.graph.predecessors(r):
                      if s in T:
134
                          count[s] = count[s]-1
135
                          if count[s] == 0:
136
                              T.remove(s)
                              E.add(s)
138
139
             return T
```

Implementazione $TS \models \Phi$

Ma non finisce qui . . .

Formule non ENF

- √ Alberi di conversione generici
 - ► Foglie speciali per agganciarci alla formula originale



- 1. Calcolo di $Sat(\Phi_o)$
- 2. Salva risultato in nodo speciale Φ_c
 - ► Evita esplosione della formula \forall (Φ **U** Ψ)
- 3. Calcolo di $Sat(\exists U)$ su albero di conversione

Complessità CTL Model Checking

Algoritmi di base $Sat(\cdot)$, formula ENF

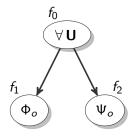
$$\mathcal{O}((N+K)\cdot|\Phi|)$$

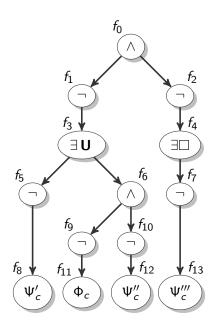
- √ N numero di stati del TS
- √ K numero di transizioni del TS
- √ |Φ| lunghezza della formula Φ

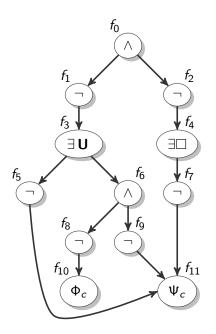
Complessità $TS \models \Phi$

- ✓ La trasformazione da formula CTL generica a CTL ENF sarebbe esponenziale, però:
 - Esistono algoritmi lineari analoghi a quelli per formule ENF
- Implementata conversione/calcolo lineare di $Sat(\cdot)$ per formule generiche
- √ La complessità totale rimane invariata

$\forall U$ explosion





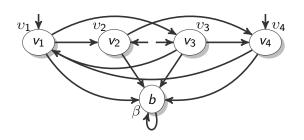


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Complessità rispetto a Linear Temporal Logic (LTL)

- 1. Problema Hamiltoniano (HP) è NP-Completo
 - ► Trovare un percorso in un certo grafo *G* che passa esattamente una volta per ogni nodo
- 2a. è possibile descrivere TS_G e una formula LTL Φ_{LTL} di lunghezza polinomiale nel numero di stati del grafo del problema
 - ▶ tali che $TS_G \not\models \Phi_{LTL} \iff G$ contiene un percorso hamiltoniano
- 2b. il model checking di Linear Temporal Logic (LTL) ha complessità esponenziale in $|\Phi|$
- 3a. è possibile descrivere un TS_G e una formula CTL Φ_{CTL} di lunghezza esponenziale nel numero di stati del grafo
 - ▶ tali che $TS_G \not\models \neg \Phi_{CTL} \Leftrightarrow G$ contiene un percorso hamiltoniano
- 3b. il model checking di CTL ha complessità lineare in $|\Phi|$
 - 4. se $P \neq NP$ non esiste una formula Φ_{CTL} equivalente a Φ_{LTL} e non esponenzialmente più lunga.

Implementazione TS_G , Φ_{LTL} , Φ_{CTL}



$$\Phi_{LTL} = \neg \bigwedge_{v \in V} (\lozenge v \land \Box (v \to \bigcirc \Box \neg v))$$

$$\Phi_{CTL} = \bigvee_{(i_1, \dots, i_n)} \Psi(v_{i_1}, \dots, v_{i_n}) \in \mathcal{O}(n!)$$

dove n è il numero di stati, e

$$\Psi(v_i) = v_i; \quad \Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n}) = v_{i_1} \wedge \exists \bigcirc \Psi(v_{i_2}, \dots, v_{i_n}).$$

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Questions? Thank you!