# Markov Regenerative Process - steady-state analysis

MVT exam

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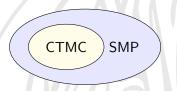
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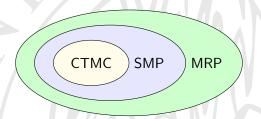
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### Transient probabilities

The probability distribution that the process will be in a certain state, after given t time.

### Steady-state

- √ ORIS current state:
  - Transient analysis for Markov Regenerative Process (MRP)
  - Steady-state analysis for everything else
- ✓ Until now
- ✓ Warning: we assume that the MRP is ergodic!

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#### General idea:

- 1. Calculate the embedded DTMC steady-state on the regenerative states
- Calculate the sojourn times in each marking, after each regenerative state
- 3. Combine the two above in order to calculate the MRP steady-state

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Sojourn times

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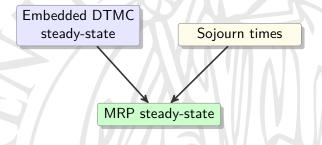
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## Main classes implemented

- √ class EmbeddedDTMC
  - written from scratch
  - calculate embedded DTMC steady-state
- √ class RegenerativeSteadyStateAnalysis
  - based on class RegenerativeTransientAnalysis
  - calculate MRP steady-state

# Steady-state of the embedded DTMC on regenerative states

## Steady-state in Discrete Time Markov Process (DTMC)

If the steady-state of a Discrete Time Markov Process (DTMC) exists and is unique (if is ergodic), then it's calculated by solving for  $\nu$  the linear system:

$$\begin{cases} v = vP \\ |v| = 1 \end{cases}$$

- ✓ We want to calculate the steady-state of the embedded DTMC of the MRP in the regenerative states
- ✓ But we don't have P!  $\Rightarrow$

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### Reaching probability feature

- √ We add a new reaching probability feature to each state: class ReachingProbabilityFeature
- ✓ Inside SteadyStateInitialStateBuilder: set it to 1
- ✓ Inside SteadyStatePostProcessor: multiply the parent's reaching probability by the probability to chose a certain child

If we run a transient analysis on the Petri Net (PN) we get:

- √ regenerationClasses
- √ Map<DeterministicEnablingState,Map<DeterministicEnablingState,Set<State>>>
- √ sum reaching probability feature of each State to compute elements
  of P

Now we can solve the linear system:

$$\begin{cases} v = vP \\ |v| = 1 \end{cases} = \begin{cases} (P' - I)v' = 0 \\ \sum_{i} v_{i} = 1 \end{cases}$$

- √ RealMatrix & RealVector
- √ QR decomposition solver
  - DecompositionSolver solver = new QRDecomposition(coefficients).getSolver();
  - RealVector steadyState = solver.solve(constants);
- √ Convert steadyState into a

  Map<DeterministicEnablingState,BigDecimal>

# Sojourn time aij

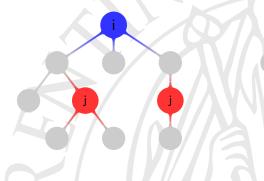
### Definition

The sojourn time  $a_{ij}$  represents the average time spent in the j-th marking after the (last) i-th regeneration.

# How to compute $a_{ij}$ ?

### a<sub>ij</sub> is:

- $\checkmark$  sum of avg time spent in marking j occurrences
  - sum of avg time before each variable fires
    - ★ condition each variable to be the minimum (i.e. the one that fires)
    - ★ compute avg time before that variable fires (thanks Marco!)





# When to compute $a_{ij}$ ?

## During the transient analysis!

- $\checkmark\,$  transient analysis generates succession trees for each regenerative state
  - regenerative state as root
  - following regenerative states as leaves
  - reachable markings as inner nodes
- $\checkmark$  during the tree generation compute and accumulate  $a_{ij}$  for each marking occurrence found

$$v_j = \frac{\sum_i v_i a_{ij}}{K}$$

- ✓ We multiply the sojourn time in the marking j after the regeneration by the probability of reaching the i-th regeneration
- $\checkmark$  We do this for each regeneration that leads to the marking j before another regeneration
- $\checkmark$  K is a normalization factor calculated as the sum of  $\pi_i$

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- √ Three different models:
  - Test CaseSMF
  - TestCase2ParallelTasks
  - TestCaseRejuvenation
- √ For each test:
  - 1. launch MRP steady state analysis
  - 2. check if the result is comparable to the expected value (with a tolerance

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# Rejuvenation

