

Markov Regenerative Process - steady-state analysis

MVT exam

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October 12, 2015



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Markov Regenerative Processes (MRPs)

Definition

A Markov Regenerative Process (MRP) is a stochastic process that sooner or later, with probability one, will reach a **regenerative** state (will be regenerated).

Regenerative state

A state where the process loses its memory.

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CTMC

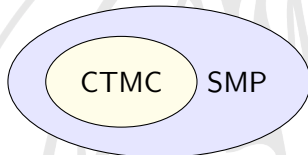
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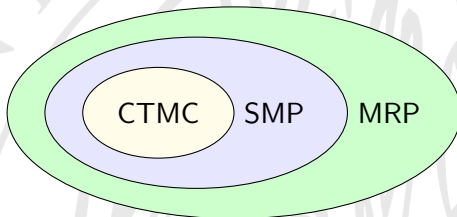
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The steady-state problem

Transient probabilities

The probability distribution that the process will be in a certain state, after given t time.

Steady-state

For ergodic systems, it represents the probability distribution that the process will be in a certain state, as time goes to infinity.

- ✓ ORIS current state:
 - Transient analysis for Markov Regenerative Processes (MRPs)
 - ▶ Steady-state analysis for Continuous Time Markov Processes (CTMCs)
- ✓ Until now! ☹
- ✓ **Warning:** we assume that the MRP is ergodic!

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MRP steady-state analysis - The theory

General idea:

1. Calculate the embedded DTMC steady-state on the regenerative states
2. Calculate the expected sojourn time in each marking, after reaching a regenerative state
3. Combine the two above in order to calculate the MRP steady-state

Embedded DTMC
steady-state

Sojourn times

MRP steady-state



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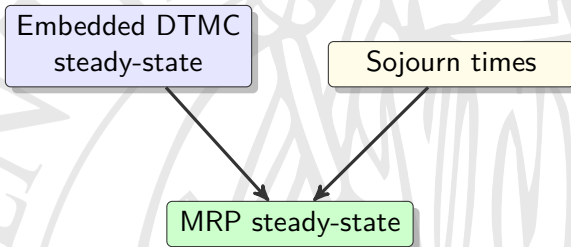
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Main classes implemented

- ✓ `class` EmbeddedDTMC
 - written from scratch
 - calculate embedded DTMC steady-state
- ✓ `class` RegenerativeSteadyStateAnalysis
 - based on `class` RegenerativeTransientAnalysis
 - calculate MRP steady-state

Steady-state of the embedded DTMC on regenerative states

Steady-state in Discrete Time Markov Process (DTMC)

If the steady-state of a Discrete Time Markov Process (DTMC) exists and is unique (if is ergodic), then it's calculated by solving for v the linear system:

$$\begin{cases} v = vP \\ |v| = 1 \end{cases}$$

- ✓ We want to calculate the steady-state of the embedded DTMC of the MRP in the regenerative states
- ✓ But we don't have P ! ☹

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Reaching probability feature

- ✓ We add a new **reaching probability feature** to each state:
`class ReachingProbabilityFeature`
- ✓ Inside `SteadyStateInitialStateBuilder`: set it to 1
- ✓ Inside `SteadyStatePostProcessor`: multiply the parent's reaching probability by the probability to chose a certain child

If we run a transient analysis on the Petri Net (PN) we get:

- ✓ `regenerationClasses`
- ✓ `Map<DeterministicEnablingState, Map<DeterministicEnablingState, Set<State>>>`
- ✓ sum reaching probability feature of each State to compute elements of **P**

Now we can solve the linear system:

$$\begin{cases} v = vP \\ |v| = 1 \end{cases} = \begin{cases} (P' - I)v' = 0 \\ \sum_i v_i = 1 \end{cases}$$

✓ RealMatrix & RealVector

✓ QR decomposition solver

- DecompositionSolver solver = `new` QRDecomposition(coefficients).getSolver();
- RealVector steadyState = solver.solve(constants);

✓ Convert steadyState into a

Map<DeterministicEnablingState, BigDecimal>

Sojourn time a_{ij}

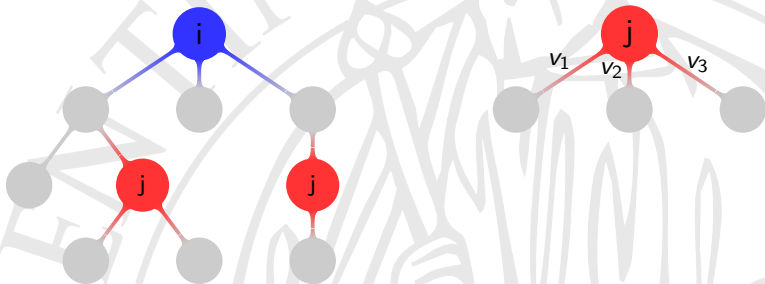
Definition

The sojourn time a_{ij} represents the average time spent in the j -th marking after the (last) i -th regeneration.

How to compute a_{ij} ?

a_{ij} is:

- ✓ sum of avg time spent in marking j occurrences
 - sum of avg time before each variable fires
 - ★ condition each variable to be the minimum (i.e. the one that fires)
 - ★ compute avg time before that variable fires (thanks Marco!)



When to compute a_{ij} ?

During the transient analysis!

- ✓ transient analysis generates succession trees for each regenerative state
 - regenerative state as root
 - following regenerative states as leaves
 - reachable markings as inner nodes
- ✓ during the tree generation compute and accumulate a_{ij} for each marking occurrence found

Markov Regenerative Process (MRP) steady-state

Let's combine the embedded DTMC steady-state and the sojourn times!

$$\pi_j = \frac{\sum_i v_i a_{ij}}{K}$$

- ✓ We multiply the sojourn time in the marking j after the regeneration i by the probability of reaching the i -th regeneration
- ✓ We do this for each regeneration that leads to the marking j before another regeneration
- ✓ K is a normalization factor calculated as the sum of π_j

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Test

Unit test

- ✓ Class `SteadyStateTest` with **JUnit** tests
- ✓ Three different models:
 - `TestCaseSMP`
 - `TestCase2ParallelTasks`
 - `TestCaseRejuvenation`
- ✓ For each test:
 1. launch MRP steady state **analysis**
 2. check if the result is comparable to the **expected** value (with a tolerance)

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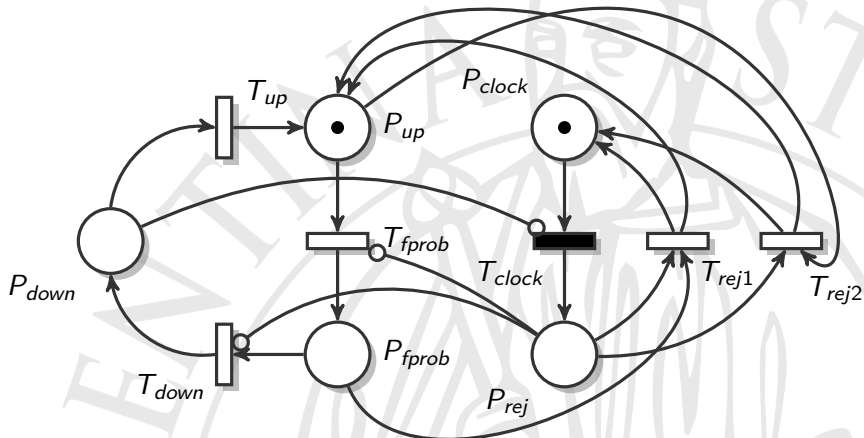
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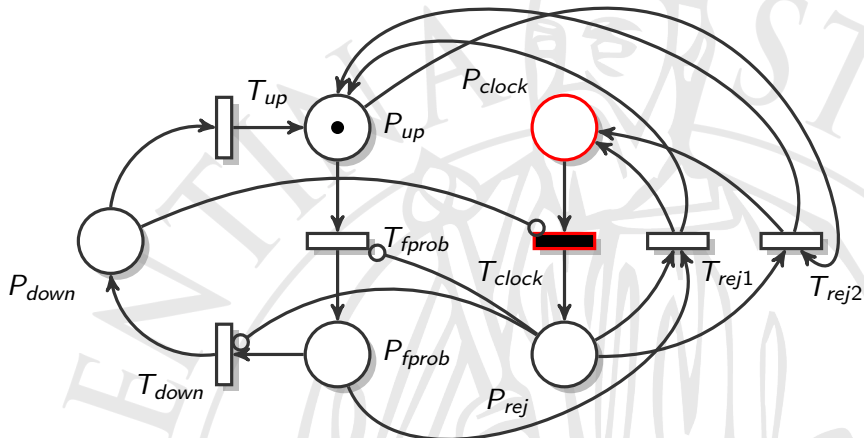
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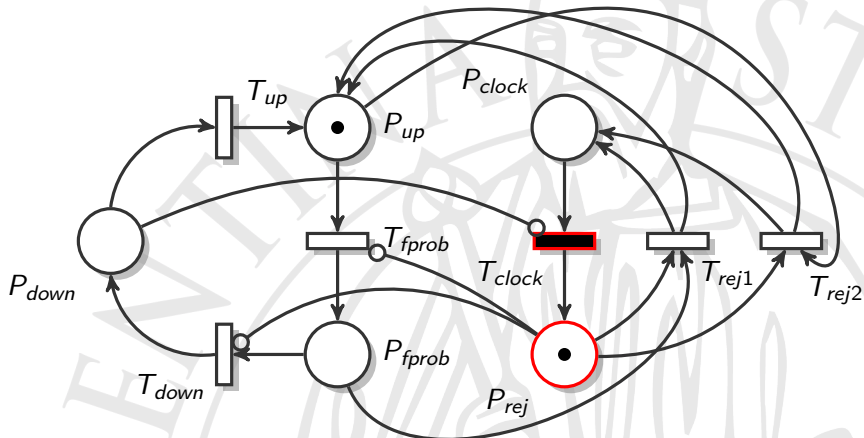
Rejuvenation



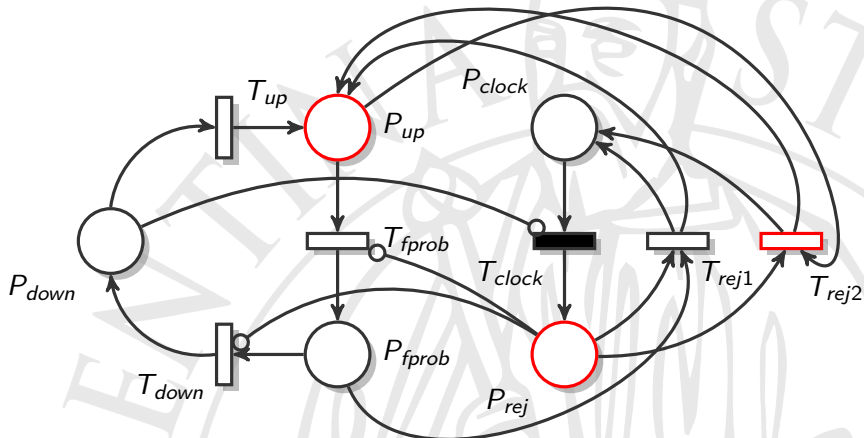
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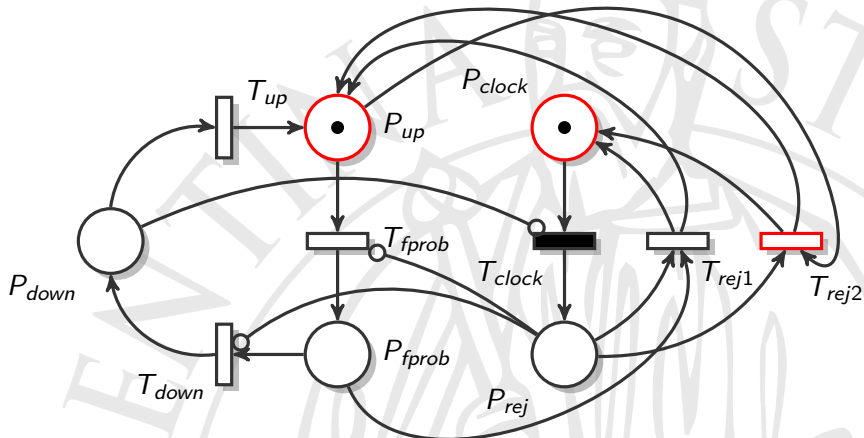
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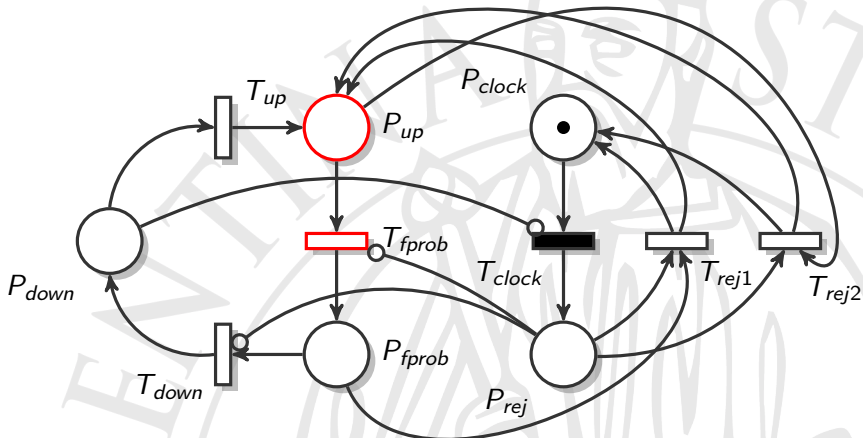


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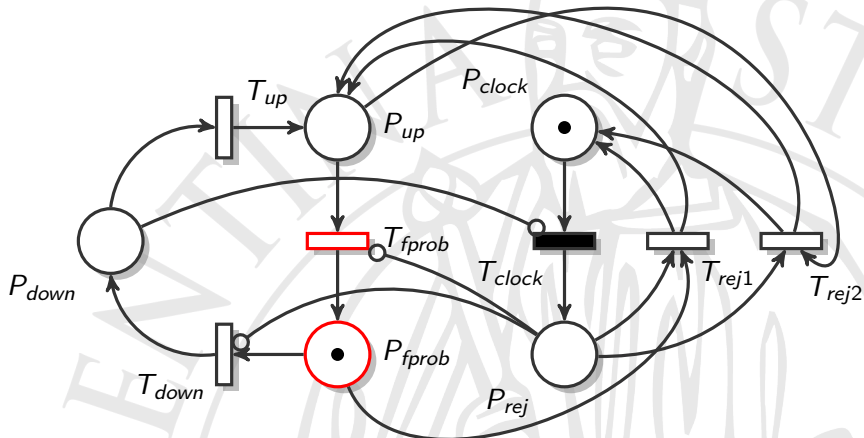


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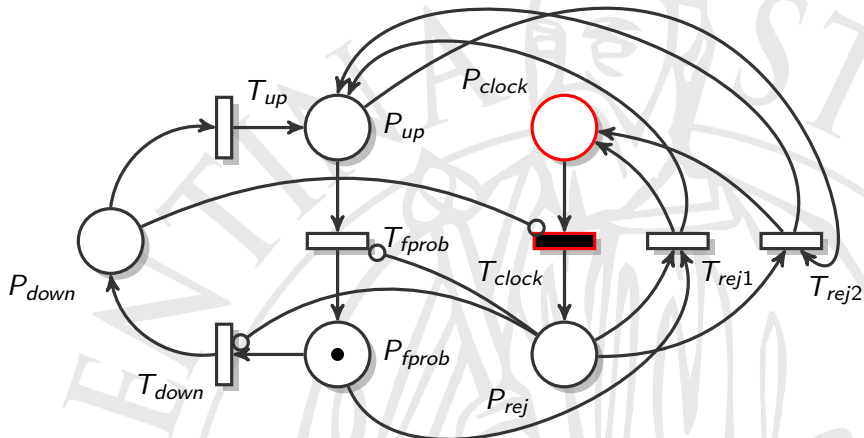




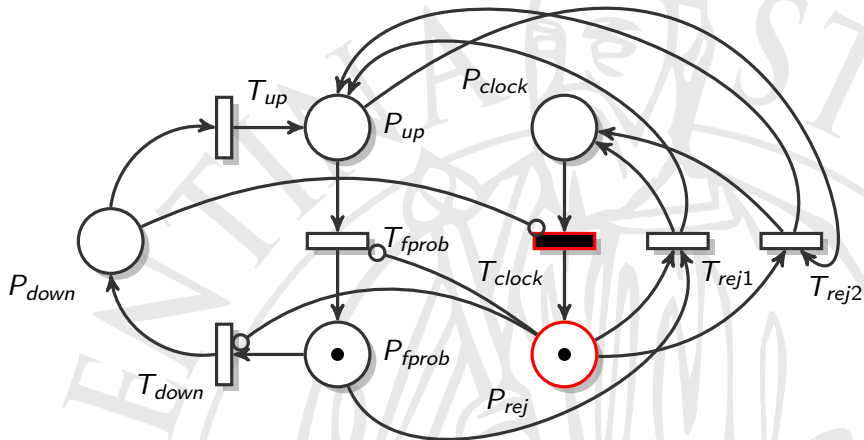
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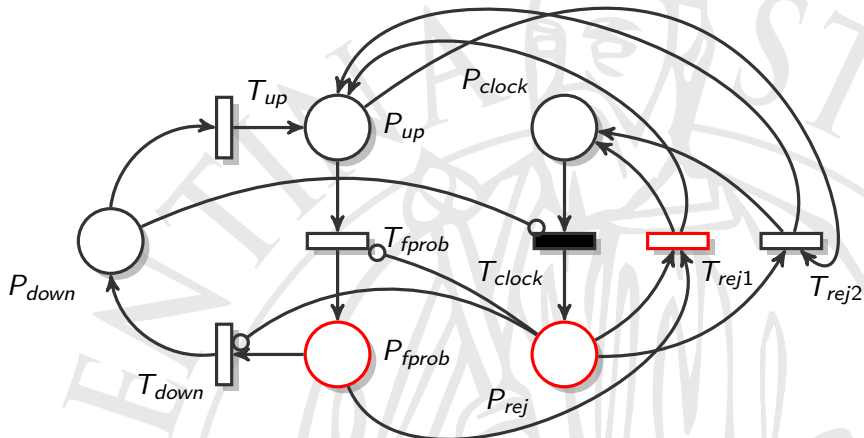
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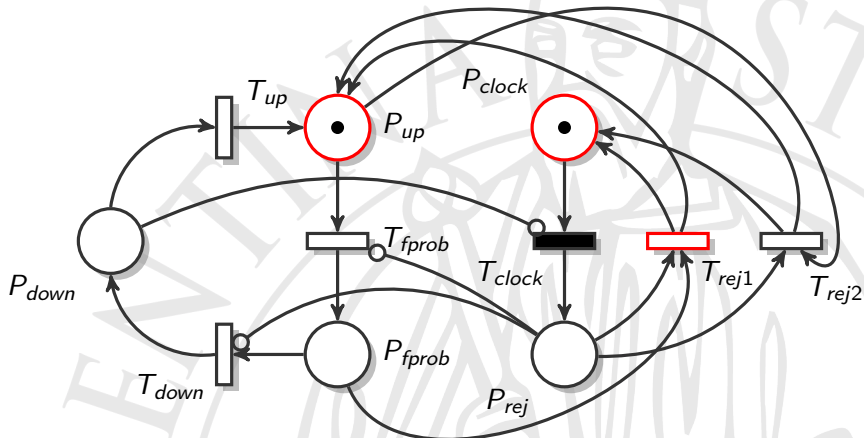
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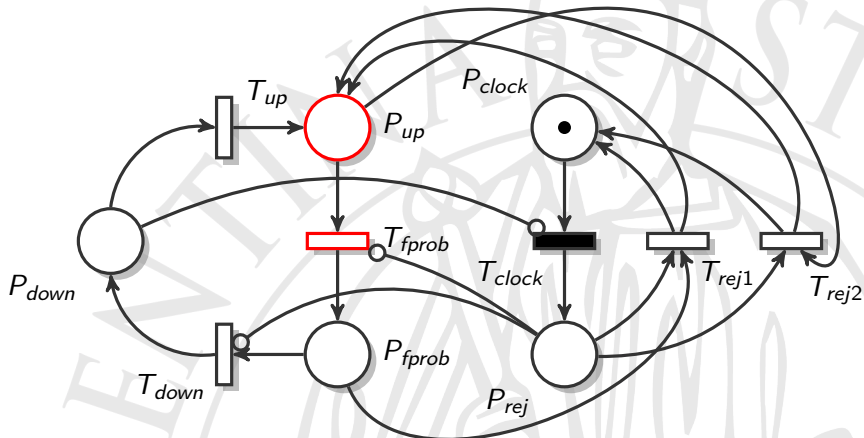
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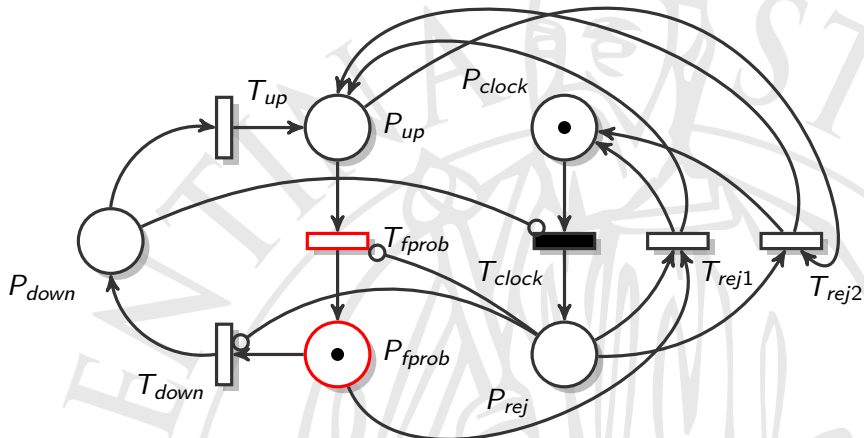
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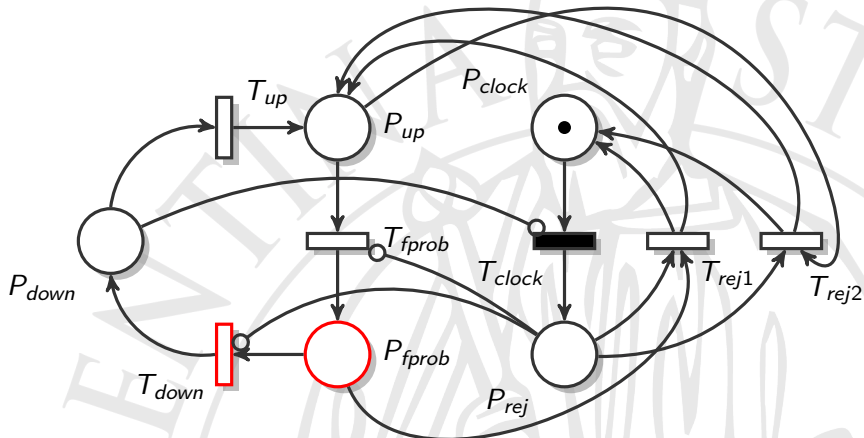
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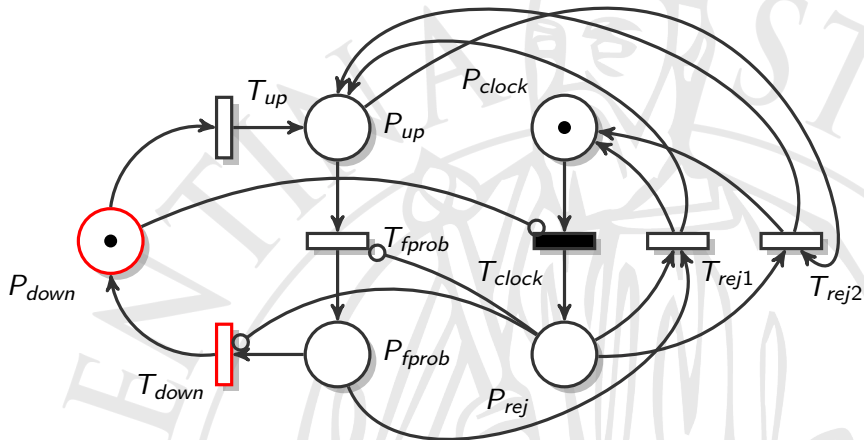
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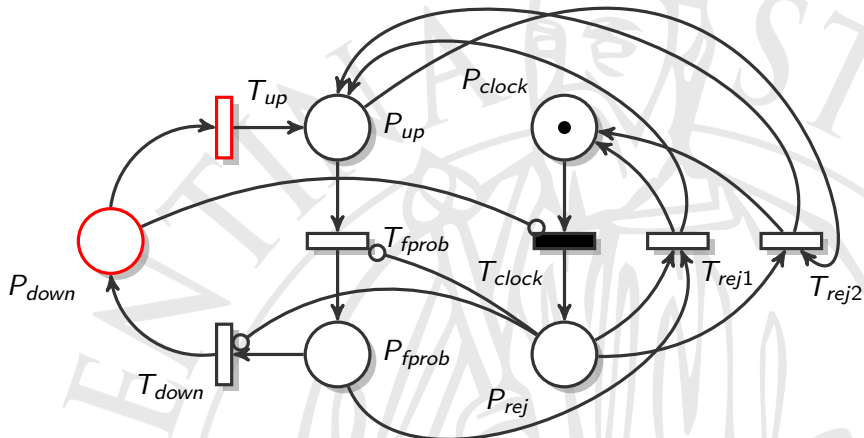
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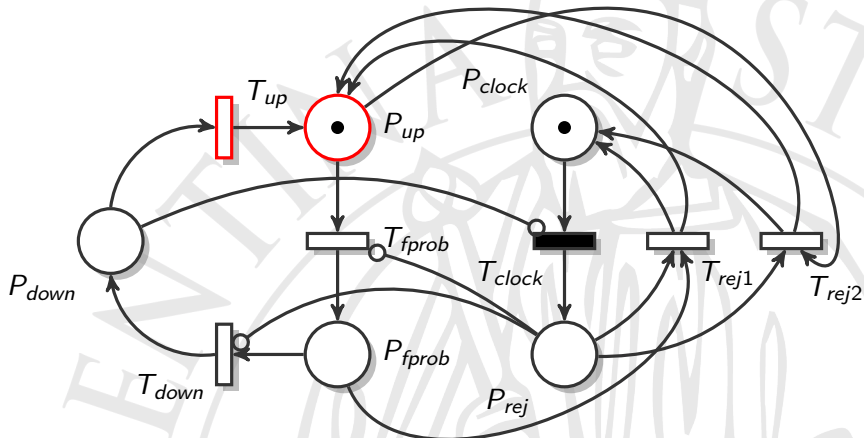
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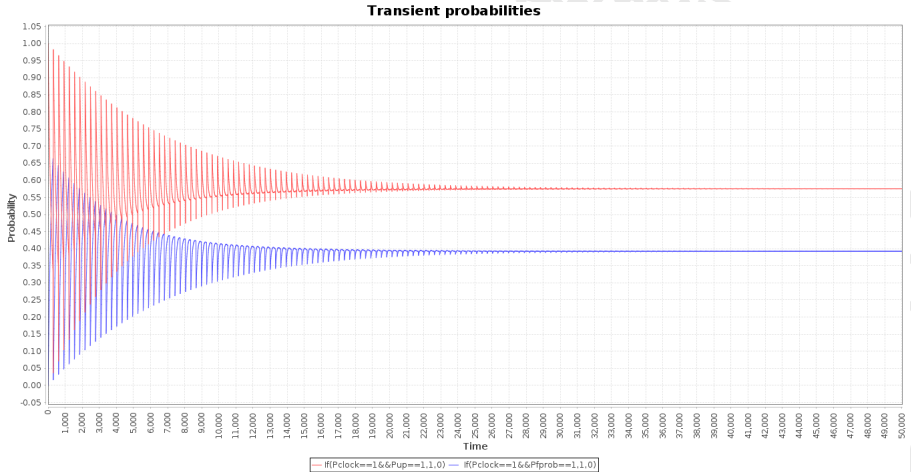
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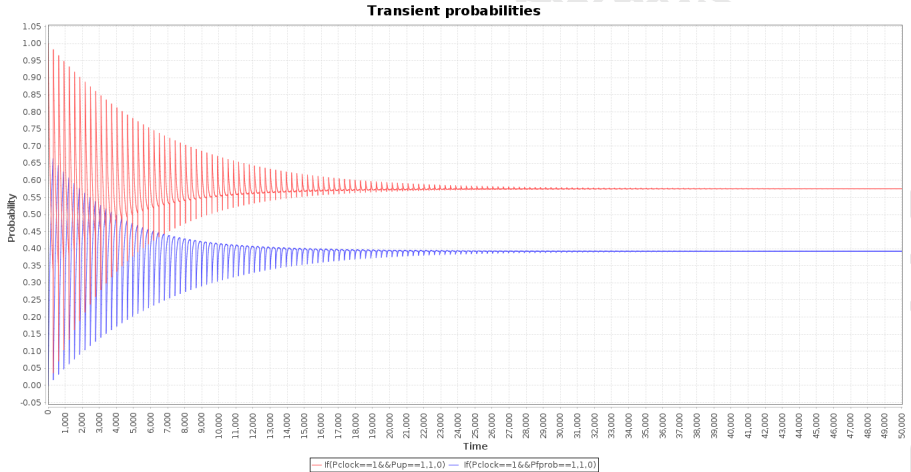


Transient analysis



- ✓ Steady-state analysis results:
 $\text{Prob}(P_{\text{clock}} P_{\text{up}}) \approx 0.58$
 $\text{Prob}(P_{\text{clock}} P_{\text{fprob}}) \approx 0.40$

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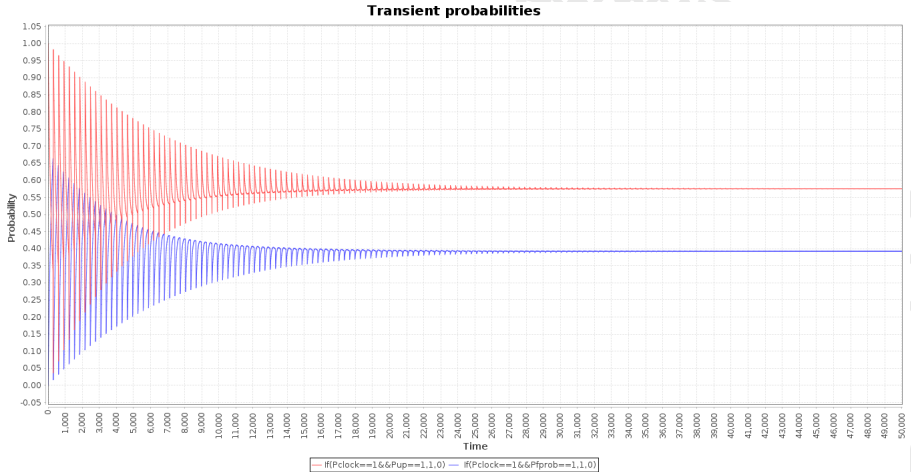


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- ✓ Steady-state analysis results:
- $\text{Prob}(\text{Pclock} \text{ Pup}) \approx 0.58$
 - $\text{Prob}(\text{Pclock} \text{ Pfprob}) \approx 0.40$

Steady state analysis

```
1 Map<String, Integer> tmpPlacesMarking = new HashMap<  
    ↪ String, Integer>();  
2 tmpPlacesMarking.put("Pup", Integer.parseInt("1"));  
3 tmpPlacesMarking.put("Pclock", Integer.parseInt("1"));  
4 getTestPlacesMarkings().put(tmpPlacesMarking, new  
    ↪ BigDecimal("0.58"));  
5  
6 tmpPlacesMarking = new HashMap<String, Integer>();  
7 tmpPlacesMarking.put("Pfprob", Integer.parseInt("1"));  
8 tmpPlacesMarking.put("Pclock", Integer.parseInt("1"));  
9 getTestPlacesMarkings().put(tmpPlacesMarking, new  
    ↪ BigDecimal("0.40"));
```

<<Java Class>>

RegenerativeSteadyStateAnalysis<R>

it.unifi.oris.oris.sirio.models.stpn

- reachableMarkings: Set<Marking>
- alwaysRegenerativeMarkings: Set<Marking>
- neverRegenerativeMarkings: Set<Marking>
- regenerativeAndNotRegenerativeMarkings: Set<Marking>
- sojournMap: Map<R, Map<Marking, BigDecimal>>
- steadyState: Map<Marking, BigDecimal>
- initialRegeneration: R
- petriNet: PetriNet
- truncationPolicy: EnumerationPolicy
- absorbingCondition: MarkingCondition
- absorbingMarkings: Set<Marking>
- localClasses: Map<R, Map<Marking, Set<State>>>
- regenerationClasses: Map<R, Map<R, Set<State>>>
- regenerations: Set<R>

- geteDTMC() EmbeddedDTMC<R>
- getSojournMap() Map<R, Map<Marking, BigDecimal>>
- getSteadyState() Map<Marking, BigDecimal>
- getReachableMarkings() Set<Marking>
- getAlwaysRegenerativeMarkings() Set<Marking>
- getNeverRegenerativeMarkings() Set<Marking>
- getRegenerativeAndNotRegenerativeMarkings() Set<Marking>
- getInitialRegeneration()
- getRegenerations() Set<R>
- getPetriNet() PetriNet
- getTruncationPolicy() EnumerationPolicy
- getAbsorbingCondition() MarkingCondition
- getAbsorbingMarkings() Set<Marking>
- getLocalClasses() Map<R, Map<Marking, Set<State>>>
- getRegenerationClasses() Map<R, Map<R, Set<State>>>
- RegenerativeSteadyStateAnalysis()
- canAnalyze(PetriNet, ValidationMessageCollector) boolean
- calculateSteadyState(RegenerativeSteadyStateAnalysis<R>) Map<Marking, BigDecimal>
- compute(PetriNet, R, StateBuilder<R>, SuccessionProcessor, EnumerationPolicy, MarkingCo...

<<Java Class>>

EmbeddedDTMC<R>

it.unifi.oris.oris.sirio.models.stpn

- reachingProbabilities: Map<R, Map<R, BigDecimal>>
- steadyState: Map<R, BigDecimal>

EmbeddedDTMC()

compute(Set<R>, Map<R, Map<R, Set<State>>>) EmbeddedDTMC<R>

mapRegenerativeStates(Set<R>) Map<R, Integer>

computeReachingProbabilities(Map<R, Integer>, Map<R, Map<R, Set<State>>>) RealMatrix

computeSteadyState(Map<R, Integer>, RealMatrix) RealVector

getReachingProbabilities() Map<R, Map<R, BigDecimal>>

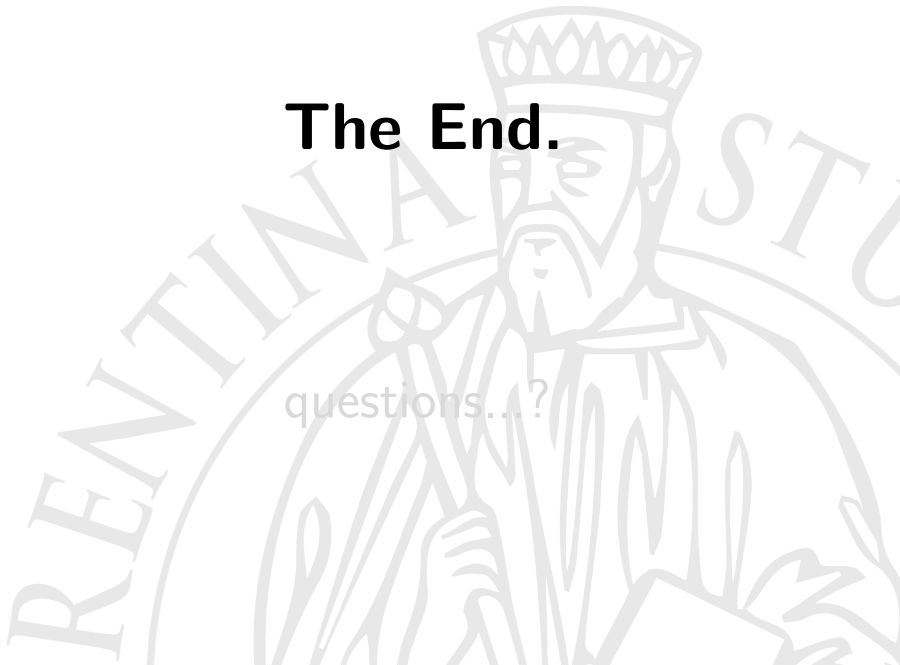
getSteadyState() Map<R, BigDecimal>

-eDTMC 0..1



The End.

questions...?



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