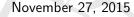
Markov Regenerative Process - steady-state analysis

MVT exam

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Definition

A Markov Regenerative Process (MRP) is a stochastic process that sooner or later, with probability one, will reach a regenerative state (will be regenerated).

Regenerative state

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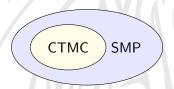
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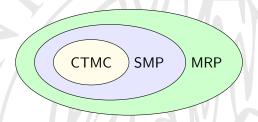
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Transient probabilities

The probability distribution that the process will be in a certain state, after given t time.

Steady-state

- √ ORIS current state
 - Transient analysis for Markov Regenerative Processes (MRPs)
 - Steady-state analysis for Continuous Time Markov Processes (CTMC
- ✓ Until how :
- √ Warning: we assume that the MRP is ergodic!

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General idea:

- 1. Calculate the embedded DTMC steady-state on the regenerative states
- 2. Calculate the expected sojourn time in each marking, after reaching a regenerative state
- 3. Combine the two above in order to calculate the MRP steady-state

Embedded DTMC steady-state

Sojourn times

MRP steady-state

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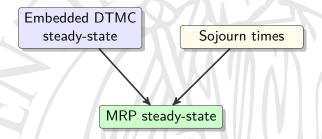
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Main classes implemented

- √ class EmbeddedDTMC
 - written from scratch
 - calculate embedded DTMC steady-state
- √ class RegenerativeSteadyStateAnalysis
 - based on class RegenerativeTransientAnalysis
 - calculate MRP steady-state

Steady-state of the embedded DTMC on regenerative states

Steady-state in Discrete Time Markov Process (DTMC)

If the steady-state of a Discrete Time Markov Process (DTMC) exists and is unique (if is ergodic), then it's calculated by solving for v the linear system:

$$\begin{cases} v = vP \\ |v| = 1 \end{cases}$$

- ✓ We want to calculate the steady state of the embedded DTMC of the MRP in the regenerative states
- ✓ But we don't have P! △

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Reaching probability feature

- √ We add a new reaching probability feature to each state: class ReachingProbabilityFeature
- ✓ Inside SteadyStateInitialStateBuilder: set it to 1
- ✓ Inside SteadyStatePostProcessor: multiply the parent's reaching probability by the probability to chose a certain child

If we run a transient analysis on the Petri Net (PN) we get:

- √ regenerationClasses
- √ Map<DeterministicEnablingState,Map<DeterministicEnablingState,Set<State>>>
- √ sum reaching probability feature of each State to compute elements
 of P

Now we can solve the linear system:

$$\begin{cases} v = vP \\ |v| = 1 \end{cases} = \begin{cases} (P' - I)v' = 0 \\ \sum_{i} v_{i} = 1 \end{cases}$$

- ✓ RealMatrix & RealVector
- √ QR decomposition solver
 - DecompositionSolver solver = new QRDecomposition(coefficients).getSolver();
 - RealVector steadyState = solver.solve(constants);
- ✓ Convert steadyState into a Map<DeterministicEnablingState,BigDecimal>

Sojourn time aij

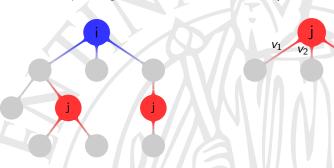
Definition

The sojourn time a_{ij} represents the average time spent in the j-th marking after the (last) i-th regeneration.

How to compute a_{ij} ?

a_{ij} is:

- √ sum of avg time spent in marking j occurrences
 - sum of avg time before each variable fires
 - ★ condition each variable to be the minimum (i.e. the one that fires)
 - ★ compute avg time before that variable fires (thanks Marco!)



When to compute a_{ij} ?

During the transient analysis!

- \checkmark transient analysis generates succession trees for each regenerative state
 - regenerative state as root
 - following regenerative states as leaves
 - reachable markings as inner nodes
- \checkmark during the tree generation compute and accumulate a_{ij} for each marking occurrence found

$$\pi_j = \sum_i v_i a_{ij}$$

- \checkmark We multiply the sojourn time in the marking i after the regeneration by the probability of reaching the i-th regeneration
- We do this for each regeneration that leads to the marking j before another regeneration
- \checkmark K is a normalization factor calculated as the sum of π_i

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- √ Class SteadyStateTest with JUnit tests
- √ Three different models:
 - TestCaseSMP
 - TestCase2ParallelTasks
 - TestCaseRejuvenation
- / For each test.
 - 1. launch MRP steady state analysis
 - 2. check if the result is comparable to the expected value (with a tolerance)

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Test

Unit test

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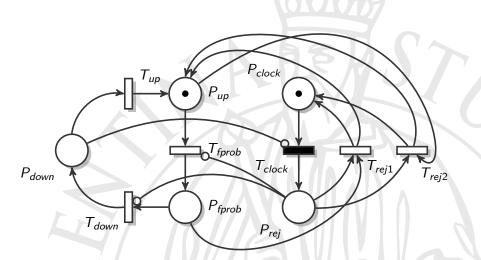
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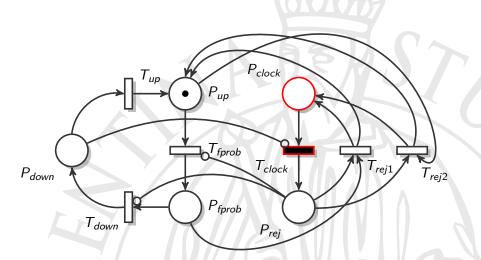
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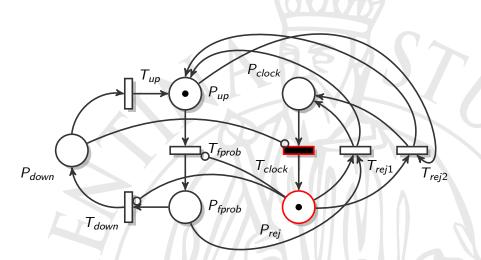
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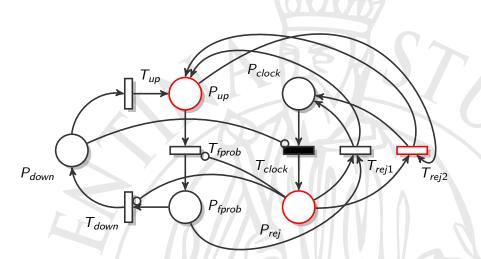
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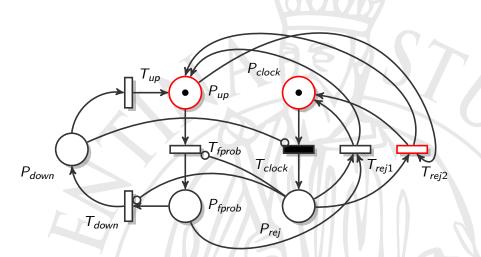
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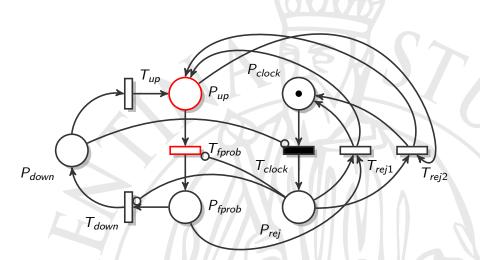


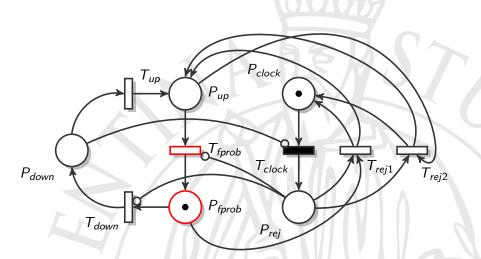


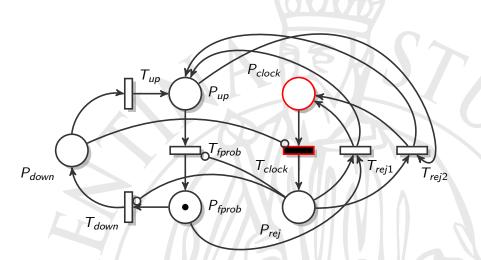


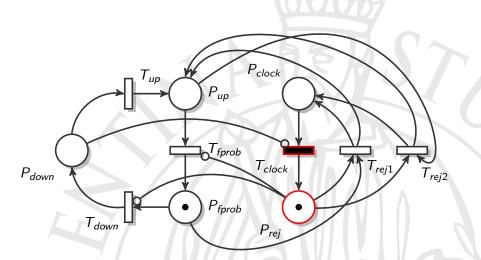


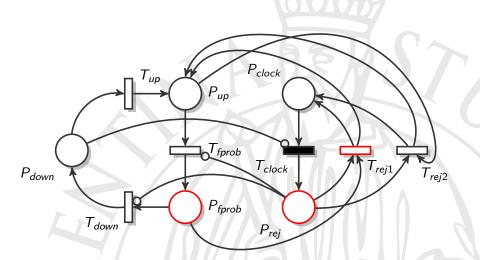


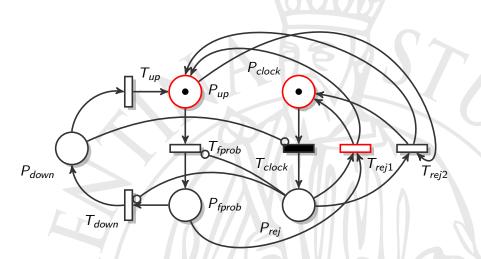


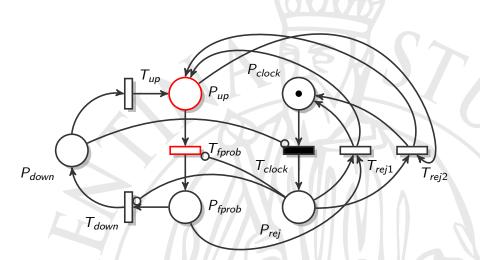


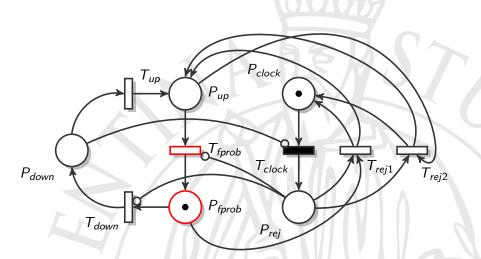


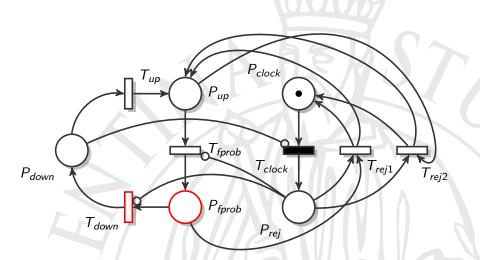


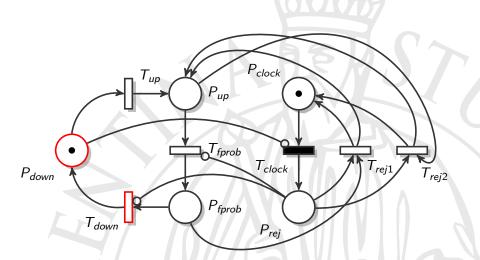


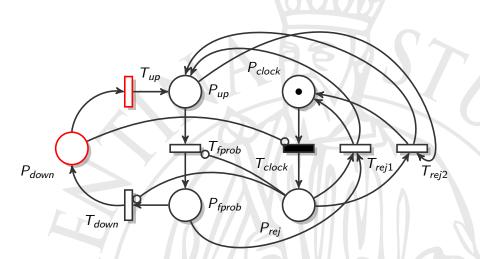


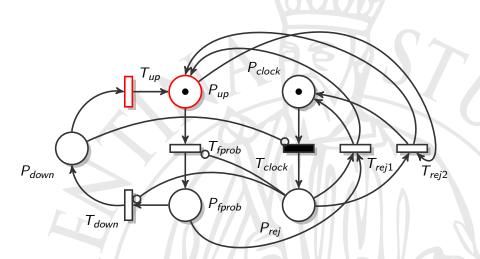




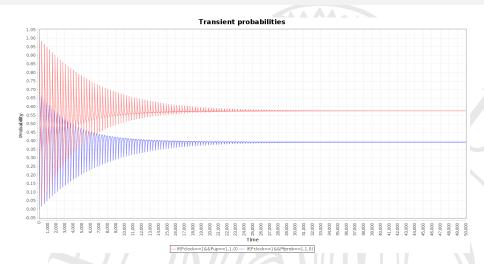








Transient analysis

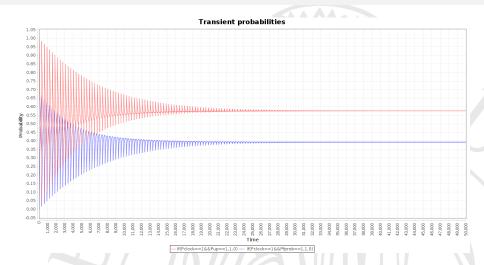


✓ Steady-state analysis results:

Prob(Ptlock Pup) ≈ 0.58

Prob(Fclock Pfprob) ≈ 0.58

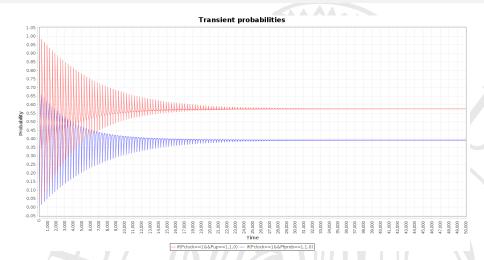
Transient analysis



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Transient analysis



- √ Steady-state analysis results:
 - Prob(Pclock Pup) ≈ 0.58
 - Prob(Pclock Pfprob) ≈ 0.40

Steady state analysis

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cc lava Classoo RegenerativeSteadyStateAnalysis<R> it .unifi.oris .oris .sirio .models .stpn reachableMarkings: Set<Marking> reachingProbabilities: Map<R_Map<R_BigDecimal>> alwaysRegenerativeMarkings: Set<Marking> neverRegenerativeMarkings: Set<Marking> regenerativeAndNotRegenerativeMarkings: Set<Marking> sojournMap: Map<R,Map<Marking,BigDecimal>> steadyState: Map<Marking.BigDecimal> p initialRegeneration; R truncationPolicy: EnumerationPolicy absorbingCondition: MarkingCondition absorbingMarkings: Set<Marking> localClasses: Map<R_Map<Marking.Set<State>>> regenerationClasses: Map<R, Map<R, Set<State>>> regenerations: Set<R> aeteDTMC():EmbeddedDTMC<R> ⊚ getSoiournMap():Map<R.Map<Marking.BigDecimal>> getSteadyState():Map<Marking.BigDecimal> getReachableMarkings():Set<Marking> getAlwaysRegenerativeMarkings();Set<Marking> getNeverRegenerativeMarkings():Set<Marking> getRegenerativeAndNotRegenerativeMarkings():Set<Marking> getInitialRegeneration() getRegenerations():Set<R> getPetriNet():PetriNet getTruncationPolicy():EnumerationPolicy getAbsorbingCondition():MarkingCondition getAbsorbingMarkings():Set<Marking> getLocalClasses():Map<R.Map<Marking.Set<State>>>

steadyState: Map<R.BigDecimal> EmbeddedDTMC() Scompute(Set<R>.Map<R.Map<R.Set<State>>>):EmbeddedDTMC<R> SmapRegenerativeStates(Set<R>):Map<R.Integer> ■ScomputeReachingProbabilities(Map<R.Integer>.Map<R.Map<R.Set<State>>>):RealMatrix ScomputeSteadyState(Map<R.Integer>.RealMatrix):RealVector getReachingProbabilities():Map<R.Map<R.BigDecimal>> getSteadvState():Map<R.BigDecimal> -eDTMC 0..1 <<Java Class>> it.unifi.oris.oris.sirio.models.stpn reachingProbability: BigDecimal getValue():BigDecimal o toString():String << lava Class>> cclava Class>> it .unifi.oris .oris .sirio .models .stpn it .unifi.oris .oris .sirio .models .stpn sb: DeterministicEnablingStateBuilder es: EnablingSyncsEvaluator SteadyStateInitialStateBuilder(PetriNet) SteadyStatePostProcessor() build(DeterministicEnablingState):State process(Succession):Succession

<<.lava Class>>

● EmbeddedDTMC <R > it unifi oris oris sirio models ston

getRegenerationClasses():Map<R,Map<R,Set<State>>>

ScanAnalyze(PetriNet.ValidationMessageCollector):boolean

CalculateSteadvState(RegenerativeSteadvStateAnalvsis<R>):Map<Marking.BigDecimal> Scompute(PetriNet,R,StateBuilder<R>,SuccessionProcessor,EnumerationPolicy,MarkingCo

FregenerativeSteadyStateAnalysis()

petriNet: PetriNet

The End.

questions...?

The End.

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