

Concurrency (Part 1) Overview

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CSE 2431: Introduction to Operating

Systems

Reading: Chap. 26 [OSTEP]



Remarks

- This is a programming-heavy topic
 - There will be three labs related to this topic
 - Writing a correct concurrent program is hard
- You will find what you learn in this topic will be frequently used in your future career (perhaps not now)



Outline: Concurrency (part 1)

- Revision: Threads
- Multi-threading and Multi-processing
- Reason why we need this topic: Sharing makes life more difficult



Why concurrent program?

- Moore's law: the number of transistors in a dense integrated circuit has doubled approximately every two years
- Before 2005, people use more transistors to build faster CPUs
 - The speed of a program can automatically increase with a faster CPU.
- Today people use more transistors to build more CPUs
 - The speed of a program does not automatically increase with more CPUs.
 - We have to parallelize our program.



Support concurrent program

- We have Thread (Thread Control Blocks – TCBs) → Multi-Threading
 - Multiple pieces of code (threads) in parallel
 - Multiple threads share the same address space
 - One PC per thread
- Sharing address space (single-threaded vs. multithreaded address space)

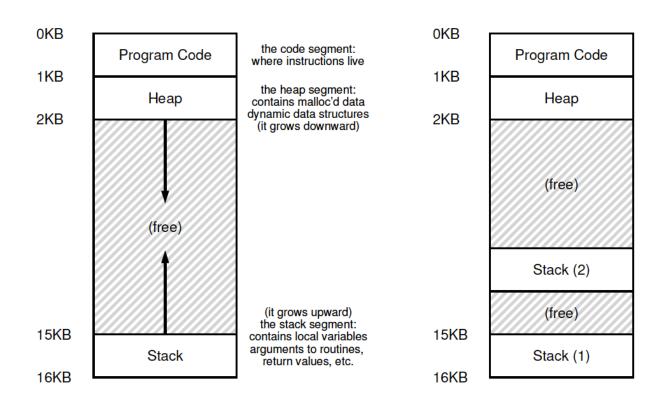


Figure 26.1: Single-Threaded And Multi-Threaded Address Spaces



Multi-threading vs., Multi-processing

- First, there is nothing multi-threading can do but multi-processing cannot do.
- Fundamental difference: threads share the memory address space, but processes do not
- Trade-offs:
 - Communication among processes are harder and less efficient, although possible (sockets, pipes, etc)
 - Processes provide better protection: if one process is faulty, others are not affected. If one thread has a bug, all threads can be affected.
 - If you need to parallelize a program on multiple machines (distributed systems), then multi-processing is necessary at this moment.



Revision: Thread Creation Workflow (1)

- First, define the function the thread is going to run:
 - void *fun_name(void *args)
 (function must have this format)
 - args contains all arguments necessary for this code
- If you want different threads to do different things:
 - Define several different functions
 - Or define one function, pass different arguments to it

```
void *mythread(void *arg) {
  printf("%s\n", (char *) arg);
  return NULL;
}
```

Revision: Thread Creation Workflow (2)

- Next, create the threads
- int pthread_create(pthread_t *pid, const pthread_attr_t *attr, void *(*routine)(void *), void *args);
 - Return value: whether creation succeeds
 - pid: Pthread ID, used to control the thread
 - attr: thread attributes (NULL works fine for now)
 - routine: the function the thread is going to run (see previous slide)
 - args: the arguments you want to pass to routine
- How do we pass multiple arguments? Define a struct.

```
#include<assert.h>
#include<pthread.h>
/* ..... */
rc = pthread_create(&p1, NULL, mythread "A"); assert(rc == 0);
rc = pthread_create(&p1, NULL, mythread "A"); assert(rc == 0);
```



Revision: Thread Creation Workflow (3)

- We can now run the threads
 - int pthread_join(pthread_t pid, void **value_ptr)
 - Wait until a thread completes
 - return value: success or not
 - pid: pthread_id you got from pthread_create()
 - value_ptr: assume NULL for now



Thread: Caution!

- pthread_create() only creates a thread; does not run it.
 - Usually, it returns quickly
 - There's no guarantee when a thread runs
- Threads can run in any order
 - Threads created earlier may start later.
 - They might run awhile, the OS may schedule them out awhile, and then continue to run (like processes)
- There is no function to cleanly terminate a thread (unlike processes, which we can kill easily)
 - If you need such functionality, you need to design the thread to handle certain signals (software interrupts)
 - More info: <u>Blaise Barney, "POSIX Threads Programming," Lawrence Livermore National Laboratory.</u>



- We want to create 10 threads
 - They are given unique IDs from 0 to 9.
 - Each of them outputs its ID.
- How would you write the program?



```
#define THREAD NO 10
void *mythread(void *arg) {
    int *id = (int *)arg;
    printf("my id is %d\n", *id);
int main(){
    pthread t p[THREAD NO];
    int i = 0;
    for(i=0; i<THREAD_NO; i++){</pre>
        pthread_create(&p[i], NULL,
mythread, &i);
    for(i=0; i<THREAD_NO; i++){</pre>
        pthread join(p[i], NULL);
    return 0;
```

Is it correct?

What is wrong with it?

"mythread" may not run immediately

If one "mythread" does not start until the next iteration, "i" will be changed



```
#define THREAD NO 10
void *mythread(void *arg) {
   int *id = (int *)arg;
   printf("my id is %d\n", *id);
int main(){
      pthread_t p[THREAD_NO];
      int i = 0;
      for(i=0; i<THREAD_NO; i++){</pre>
            pthread_create(&p[i], NULL,
mythread, &i);
      for(i=0; i<THREAD_NO; i++){
    pthread_join(p[i], NULL);</pre>
      return 0;
```

Solution 1

Create an array of 10 "i"s. This is fine if there are "join" after "create". Otherwise, the local array may be deallocated when the function returns

Defining "i" as a global array will be fine, although this is usually considered a bad practice



```
#define THREAD NO 10
void *mythread(void *arg) {
    int *id = (int *)arg;
printf("my id is %d\n", *id);
int main(){
     pthread_t p[THREAD_NO];
     int i = 0;
     for(i=0; i<THREAD NO; i++){</pre>
          pthread_create(&p[i], NULL,
mythread, &i);
     for(i=0; i<THREAD_NO; i++){
    pthread_join(p[i], NULL);</pre>
     return 0;
```

Solution 2
malloc each "i"
Be careful where to call free.



Multi-threading programming is hard

- Reasoning is harder:
 - In a single-threaded program, when you call a function, you know the next statement will be executed after the function call finishes.
 - In a multi-threaded program, when you start a thread, the thread may not even start when the program executes the next statement.
- Testing is harder: bug is usually not deterministic.
 - How can I test it? Unfortunately, it is still an open problem. The only thing you can do is to run it multiple times.
- Multi-threading + memory allocation is even harder.



- Suppose you have the following:
- Assume your program has one global variable counter
- Assume the program has two threads, each doing num=num+1
- What is your expected value of num after two threads terminate?
 - Obviously 2 right?
- But if you run the following program, you may get surprised.

```
void *mythread(void *arg) {
    printf("%s: begin\n", (char *) arg);
    int i;
    for (i = 0; i < 1e7; i++) {
        counter = counter + 1;
    printf("%s: done\n", (char *) arg);
    return NULL;
// main()
// Just launches two threads (pthread_create)
// and then waits for them (pthread_join)
int main(int argc, char *argv[]) {
    pthread_t p1, p2;
    printf("main: begin (counter = %d)\n", counter);
    Pthread_create(&p1, NULL, mythread, "A");
    Pthread_create(&p2, NULL, mythread, "B");
    // join waits for the threads to finish
    Pthread_join(p1, NULL);
    Pthread_join(p2, NULL);
    printf("main: done with both (counter = %d) \n",
            counter);
    return 0:
```



- Reason:
 - counter = counter + 1 is not a single instruction when compiled

```
mov 0x8049a1c, %eax add $0x1, %eax mov %eax, 0x8049a1c
```

When running in one thread, no problem

```
void *mythread(void *arg) {
    printf("%s: begin\n", (char *) arg);
    int i;
    for (i = 0; i < 1e7; i++) {
        counter = counter + 1;
    printf("%s: done\n", (char *) arg);
    return NULL;
// main()
// Just launches two threads (pthread_create)
// and then waits for them (pthread_join)
int main(int argc, char *argv[]) {
    pthread_t p1, p2;
    printf("main: begin (counter = %d)\n", counter);
    Pthread_create(&p1, NULL, mythread, "A");
    Pthread_create(&p2, NULL, mythread, "B");
    // join waits for the threads to finish
    Pthread_join(p1, NULL);
    Pthread join(p2, NULL);
    printf("main: done with both (counter = %d)\n",
            counter);
    return 0:
```

 This run may have no problem. But can you imagine how a problem can happen? Remember that a context switch can happen at any time.

Thread 1

Thread 2

```
mov 0x8049a1c, %eax add $0x1, %eax mov %eax, 0x8049a1c
```

```
mov 0x8049a1c, %eax add $0x1, %eax mov %eax, 0x8049a1c
```



 This run may have no problem. But can you imagine how a problem can happen? Remember that a context switch can happen at any time.

```
Thread 1 Thread 2

walue = 0

mov 0x8049a1c, %eax
add $0x1, %eax

walue = 0

mov 0x8049a1c, %eax
add $0x1, %eax

value = 1

mov %eax, 0x8049a1c

walue = 1

mov %eax, 0x8049a1c
```



Atomicity and Synchronization

• In many cases, we hope our piece of code can act like a single atomic instruction that is never interrupted in the middle

- We will learn synchronization mechanisms to achieve atomicity
- If multiple threads access shared data without synchronization, it is called a data race
 - It is usually bad. You should avoid that.



Another problem

 Sometimes one thread needs to wait for another thread to complete something first

This is related to but not the same as synchronization

 We will learn how to do that with semaphores and condition variables.



Things to keep in mind

- Whenever you do multi-threaded programming, you should ask yourself "do I need to do synchronization?"
 - The answer is usually YES.
 - Two exceptions: threads don't share data; shared-data are read-only.

- Even simple statement like "a=1" may not be atomic
 - So do not assume anything is atomic
 - Always rely on proper synchronization for atomicity

