

Midterm Review

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CSE 2431: Introduction to Operating

Systems



Midterm – What to expect

• Simply put, almost all the slides (except those mentioned in lectures as "optional") covering the following topics: Computer Architecture general, Processes, Threads, CPU Scheduling, Memory structure, Dynamic Relocation, Paging, Swapping.



Midterm – What to expect

- **NOT** the History of Computer. History should be learned, but this is not a History course.
- Processes
- CPU Scheduling (Process/Job Scheduling)
- Threads (notice the difference between Processes and Threads)
- Virtual Memory:
 - Overview, Bit Operations (don't forget this, as you will need to remember how to do the bit operations in the exam by yourself)
 - Dynamic Relocation
 - Paging
 - Swaping



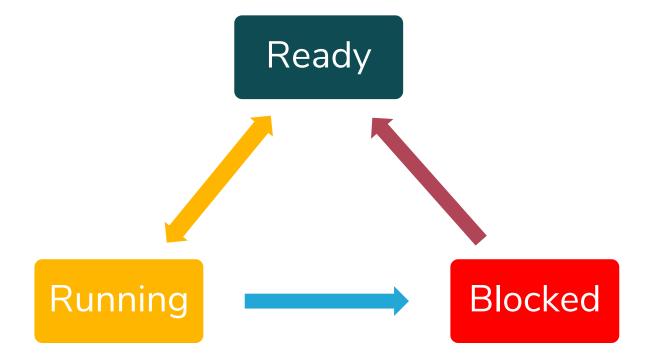
Process

- What is a process?
- What is time sharing?
- What does OS do to create/schedule a process?
 What is a context switch?
- What is a PCB? Process Control Block: storing process state, PID, program counter (PC), CPU registers info, PID of parents...
- Fork/exec/wait



Process

 Processes have different states: Running, Ready and Blocked.





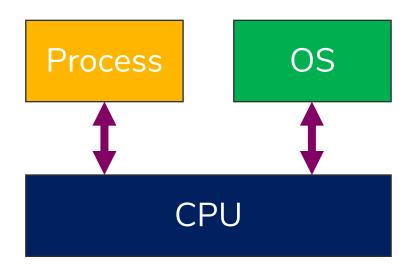
CPU Scheduling

- What is Limited Direct Execution?
 - Different between user-mode and kernel-mode
 - Trap- and return-from-trap instruction
- Difference between System call vs. Normal function call
- How to pause a process? How to resume a process? What is a context switch



Process scheduling

- Solution 2: Limited Direct Execution
 - A process sends its instructions directly to the CPU
 - OS collaborates with CPU to control the behavior(s) of the process.
 - Advantage: low overhead
 - <u>Disadvantages:</u> hard to control process behavior(s)
 - OS usually uses this approach





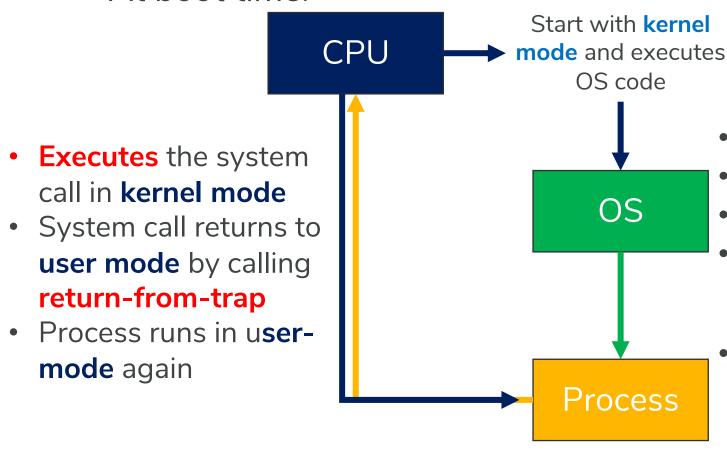
Process scheduling

- Trap- and return-from-trap instruction
 - Modern CPU provides a special trap instruction that performs the following two operations **atomically**.
 - Switch from user mode to kernel mode
 - Jump to an address defined in the trap table
 - Key idea: we <u>allow</u> user's code to change kernel bit, but **after** doing so, the user's code must jump to a system call!
 - Then it is safe to make trap non-restricted.
 - OS makes sure a system call switches to user mode before returning
 - CPU provides a special return-from-trap instruction to do that



Process scheduling

At boot time:



- Sets up trap table
- Performs other initializations
- Switches to user-mode
 - Starts a program/process in user-mode
- May make system call, jumping to a location in trap table and switching to kernel mode, by using the trap instruction

System call vs. normal function call

System call	Function call
Must run in kernel mode	Can run in any mode
Made by a trap instruction	Made by a jump instruction
Must be registered in the trap table	Can be put in any location (in mem)
Comes with two context switches	Only with one context switch



Context Switching

- Switches CPU from one process to another
- Performed by scheduler (dispatcher) with a special hardware support (timer)
- It includes:
 - Saving the state of the old process (such as registers);
 - Loading the state of the new process;
 - Flushing memory cache;
 - Changing memory mapping [Translation Lookaside Buffer (TLB)]



Context Switch (more)

- Context switches can occur when
 - A program makes a system call
 - A timer event is triggered
 - •
- Context switches have additional overhead
 - OS needs to save the state of current process and load the state of another process
 - Frequent context switches can be bad for performance



CPU Scheduling for a Process/Job

Non-preemptive scheduling:

The running process keeps the CPU until it voluntarily gives up the CPU (when? Process exits, Switches to waiting state) (No de-schedule)

Preemptive scheduling:

The running process can be interrupted and must release the CPU (it is forced to give up the CPU)





CPU Scheduling

- Type of Scheduling:
 - Preemptive / Non-preemptive
 - Priority / Non-priority
- Scheduling metrics: turnaround time; response time; fairness, ...
- Scheduling Algorithms:
 - Non-preemptive: FIFO/FCFS, SJF
 - Preemptive: Shortest-Time-to-Completion-First, Round Robin
 - Priority: Multi-level Feedback Queue (MLFQ)
 - More advanced? Multi-processor scheduling, Real-time scheduling

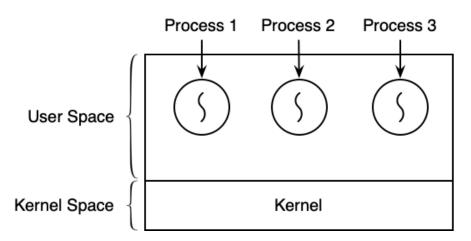


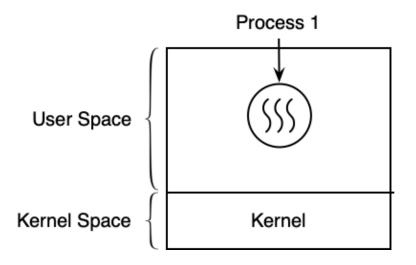
Threads

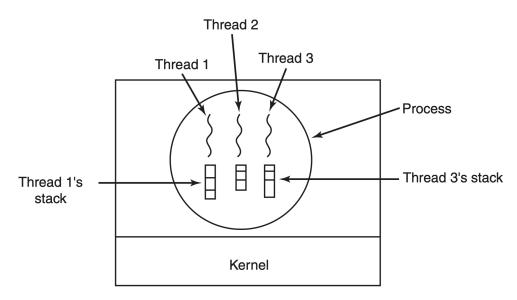
- What are threads?
- Difference between Threads and Processes?
- Different type of Threads and Thread Scheduling
 - User-level Threads
 - Kernel-level Threads
 - Hybrid Implementation
- Multi-Threading and Multi-Processing



Threads









Memory

- How is memory used by a program?
 - Jump/load/store ... instructions
 - Data/Code section; stack; heap, ...
- What does virtual memory mean?
 - Address space; virtual address; physical address
- malloc/free



Memory – Dynamic Relocation

- Address translation with contiguous allocation
 - Base and bounds registers
 - Internal and external fragmentation
- Segmentation
 - How to determine the correct segment?
- Free-space management
 - How to keep track of free slots?
 - Which slot to use? Best/Worst/First/Next fit



Memory – Paging

- Paging: basic idea and challenges
- How to do address translation?
- Single-array Page table:
 - Contents
 - How to calculate its size?
 - How to do translation?
 - What is its overhead?
 - What is TLB and MMU? Workflow with TLB; how to calculate TLB efficiency? How to handle TLB in a context switch?



Memory – Paging and Swapping

- Multi-level page tables
 - Basic idea
 - How to do the translation?
 - How to calculate its size?
- Swapping
 - Swap space, Present bit, and Page fault
 - Swapping policies: MIN, FIFO, LRU, Random
 - Thrashing

