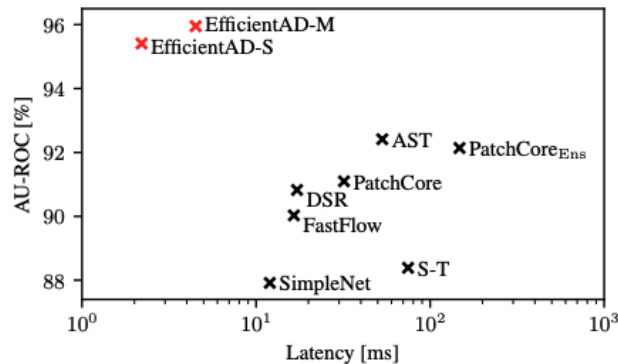


Paper Review

EfficientAD: Accurate Visual Anomaly Detection at Millisecond-Level Latencies

Why is this paper interesting?

The proposed EfficientAD method achieves high standards in both Anomaly Detection (AD) and Anomaly Localization (AD) (implementation code can be found [here](#)). It operates at a latency of two milliseconds and a throughput of 600 images per second, making it an economical and efficient solution for real-world applications. More details are shown in the sections below.



High-level summary

They have 3 main contributions they combine to achieve a proposedly new state-of-the-art on AD/AS:

1. Efficient network architecture (Patch Descriptor Network) for fast inference/extraction of features
2. Use a specific loss-function/regularization to actually avoid the problem of “overgeneralization to anomalies” for student-teacher approaches.

Notes: might be worth checking papers that propose a similar approach.

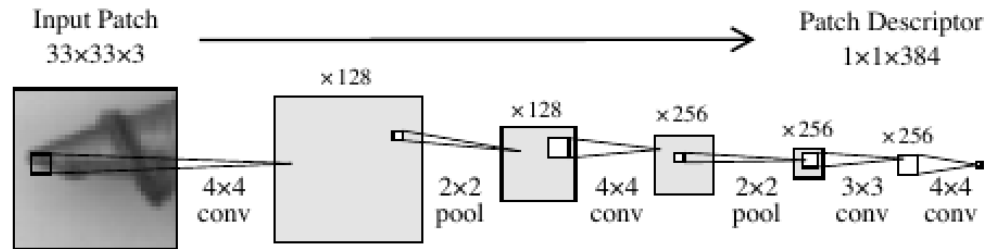
- a. [DR/EM – A discriminatively trained reconstruction embedding for surface anomaly detection](#)
 - b. [Asymmetric Student-Teacher Networks for Industrial Anomaly Detection](#)
3. Proposal for an auto-encoder that tackles logical (i.e global) anomalies by learning the identify-function on the combination of teacher and student features.
 4. Last, they propose a way to combine the auto-encoder and student-teacher scores to detect both logical/semantic and structural/textural anomalies.

Overall, the authors seem to do a lot of engineering optimisation, especially for the run-time and memory analyses.

Core steps of the paper

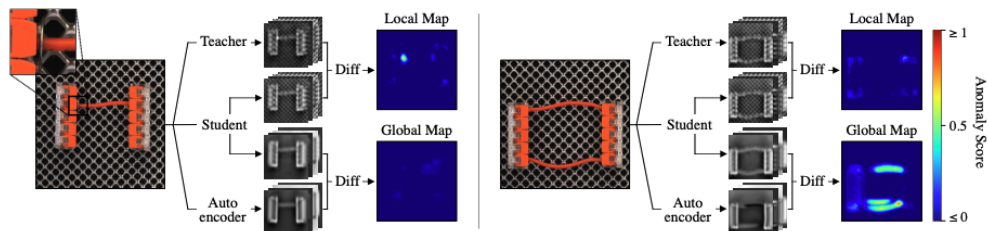
1. Patch Descriptor Network

a. Architecture



- b. Main benefit: we enforce short-range connections/limit the Effective Receptive Field size.
=> What happens if the defect is split between two patches?

2. Student-Teacher loss function has two components:
 - a. Hard-negative mining loss for the knowledge distillation (i.e. only compute gradients on the X% most disagreeing feature vectors between student and teacher).
 - b. Regularization term for the student on ImageNet (make the student predict all zeros to ensure that there is no generalization).
3. Auto-encoder for logical anomalies:
 - a. On images with logical anomalies, the autoencoder usually fails to generate the correct latent code for reconstructing the image in the teacher's feature space.
4. Normalization of Maps
 - a. Since Student Teacher loss as well as Auto-encoder Student loss are of different scales, we need a set of defect-free validation images to estimate the value ranges that can be used to normalize. This is necessary because we otherwise get False Positives
 - b. Architecture



Limitations

1. They don't evaluate in the few-many shot settings, which we are mainly interested in
2. Even the method is very fast during inference, it's training step takes long time
 - a. 20 mins on a strong GPU to train the whole model for each dataset.
 - b. Do one-time global effort of Knowledge Distillation from a deep pre-trained classification network into the Patch Descriptor Network.
3. The method is somehow a bit complex:
 - a. We don't know which hyper-parameters were hard-coded.
 - b. These hyper-parameters might change depending on the different datasets.