

# MAE 158 Lecture 8

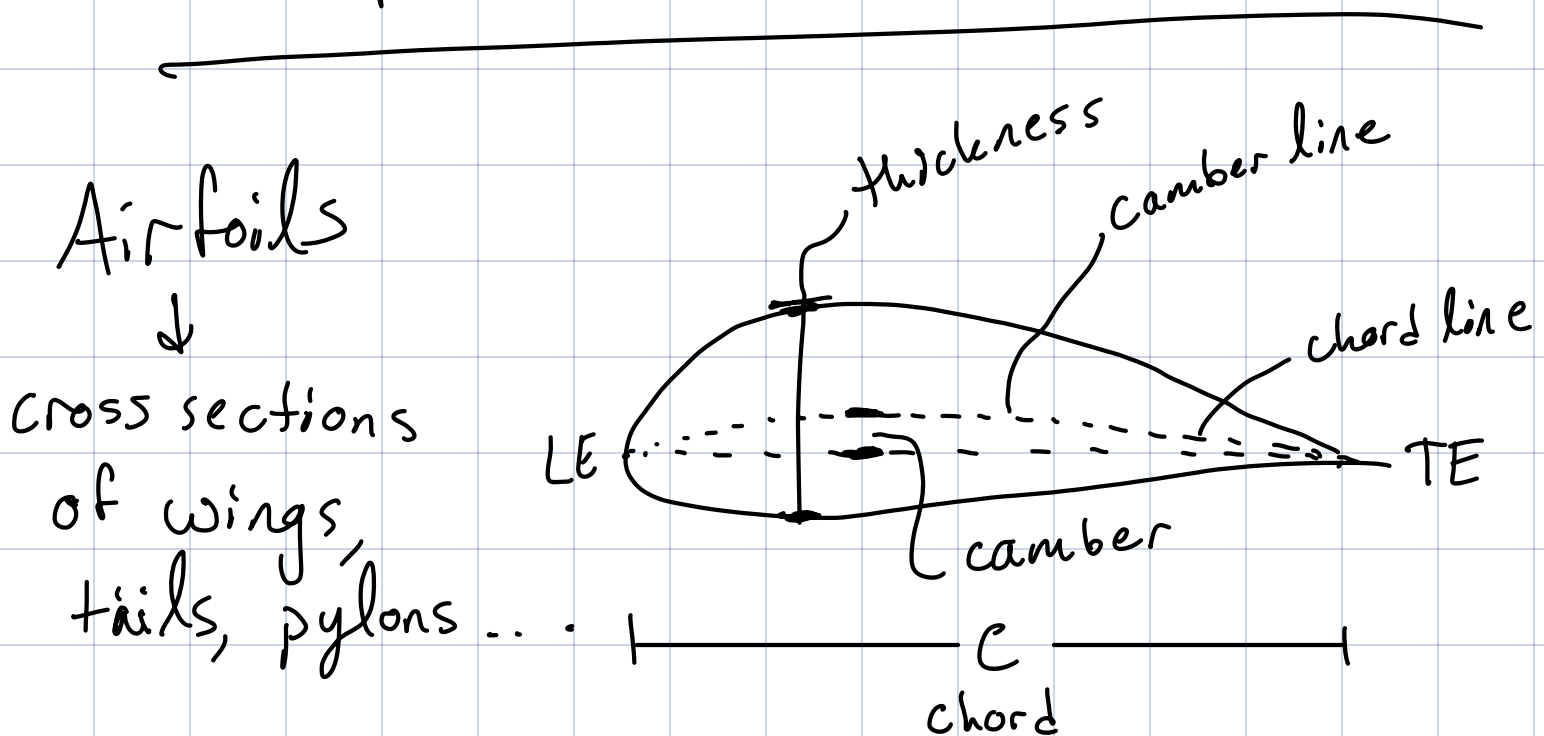
## Fall 2024

Announcements: Hw 5 posted

Today's Objectives: Airfoils

last time:

$$\text{Drag} = \underbrace{f \cdot q}_{\text{profile}} + \underbrace{\left(\frac{L}{b}\right)^2 \frac{1}{\pi q e}}_{\text{induced}} + \text{compressibility}$$



thickness - distance between top &

Bottom of Airfoil  $\perp$   
to the chord line

- $t/c \rightarrow$  thickness to chord  
Ratio  $\leadsto$  max thickness

camber - distance between camber line  
& chord line

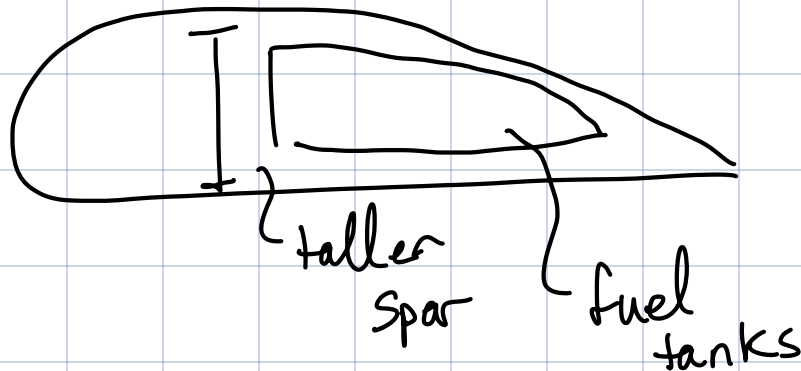
- camber line is the midpoint  
between the top & bottom  
of Airfoil

- Rounded LE  $\rightarrow$  keep attached flow  
for different  $\alpha$
- Sharp TE  $\leadsto$  established Kutta  
condition

camber  $\leadsto$  effect of changing lift  
curve

$\hookrightarrow$  increase  $C_l$  @ a  
given  $\alpha$

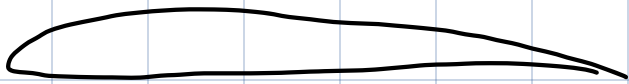
thickness  $\rightarrow$



thicker  $\leadsto$

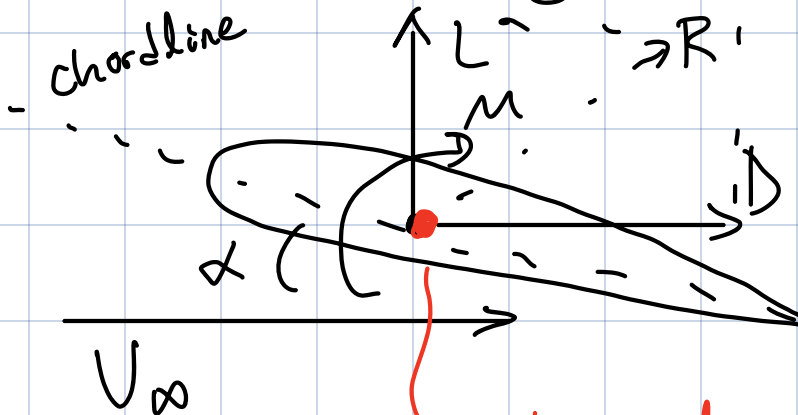
structures  $\rightarrow$   
more efficient  
for bending  
loads

thinner airfoil



better for  
compressibility  
drag

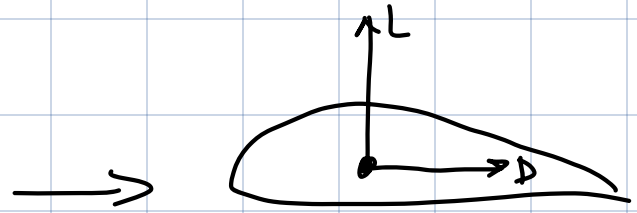
Lift, Drag, Moment



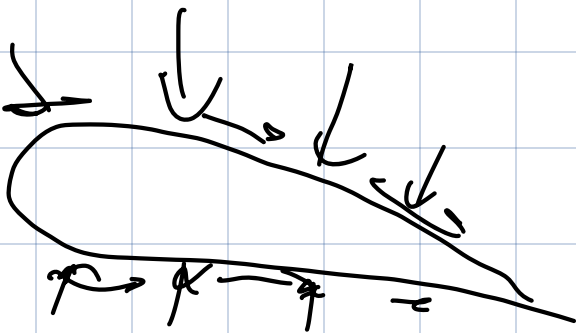
Moment ( $M$ ) is  
+ if it serves  
to increase  
 $\alpha$

where do you put  
the resulting forces?

One option:

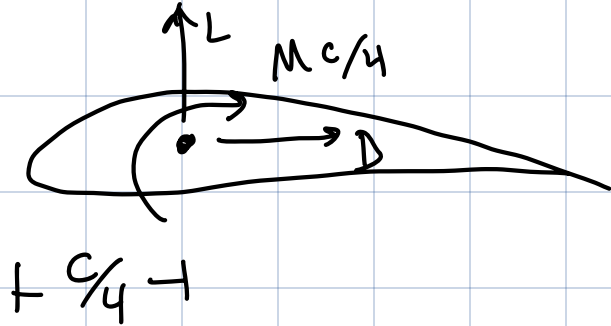


if sum, the  
 $P$  &  $S$  distribution  
the centroid  
is center of  
pressure



as  $\alpha$  -  
changes, then  
the location  
of center of  
pressure  
changes  $\rightarrow$   
not convenient

Option 2 (typically used)



put forces  
 & Resulting  
 moment @  $c/4$   
 point

→ because  $M_{c/4}$  stays  
 \* Relatively \* constant  
 with  $\alpha$

$c/4$  point is near aerodynamic  
center  
 for most Airfoils

aerodynamic  
 center: location where moment  
 is constant with  $\alpha$

2d airfoils

airfoiltools.com

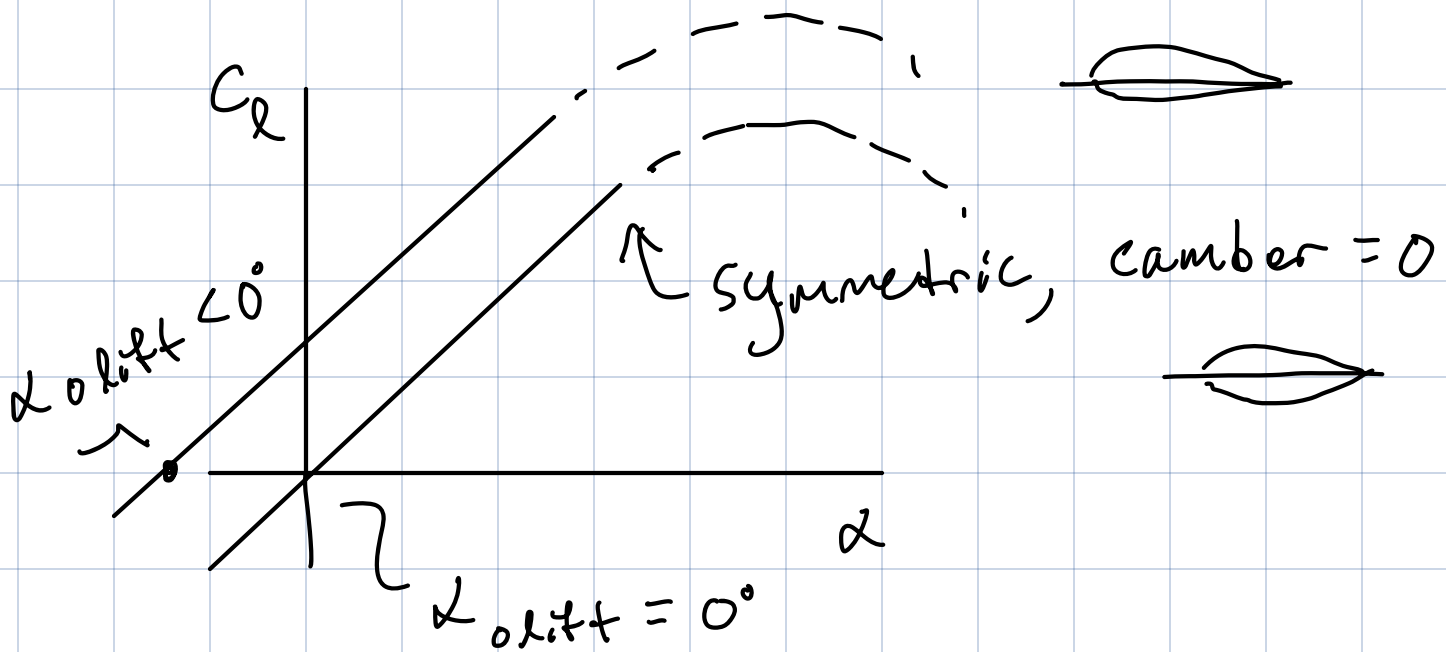
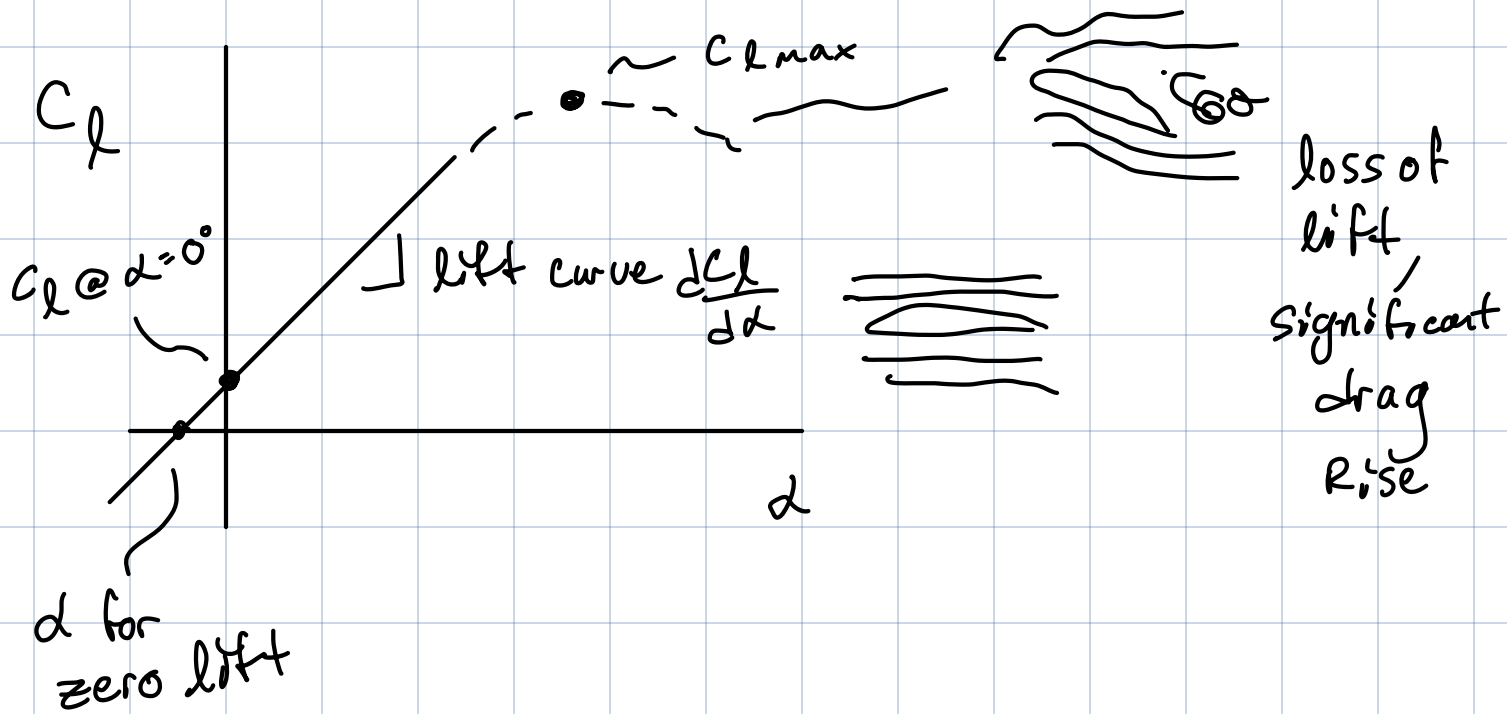
$$C_l = f(\alpha, Re, M)$$

$$C_d = f(\alpha, Re, M)$$

$$C_m = f(\alpha, Re, M)$$

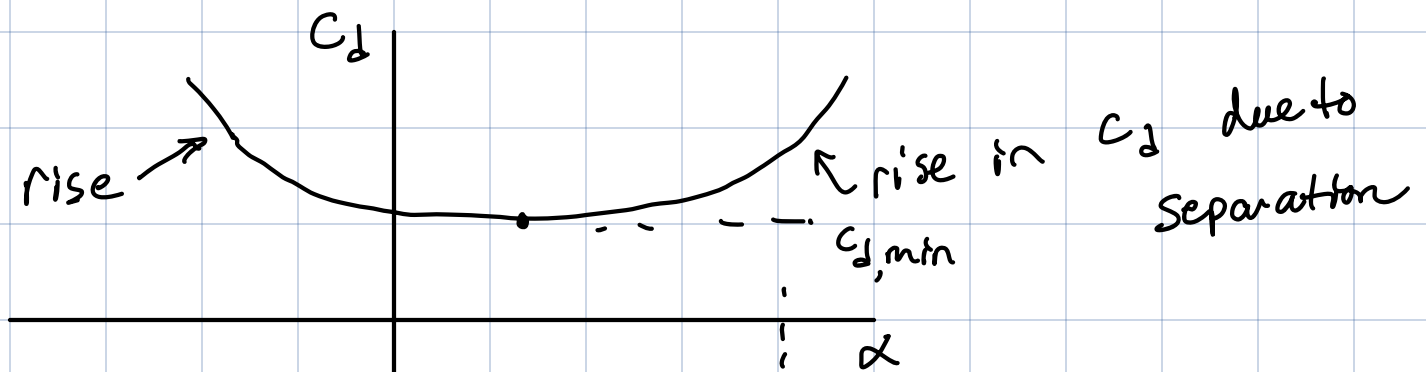
$Re, M$  are similarity parameters

if operate in conditions where  $Re$  &  $M$  are the same for 2 airfoils of the same shape but different  $c, V, \rho \dots$  then the coefficients will be the same



$\hookrightarrow$  2D  $C_L \rightarrow$  convert to 3D  $C_L$   
if you want to get  $C_{Di}$

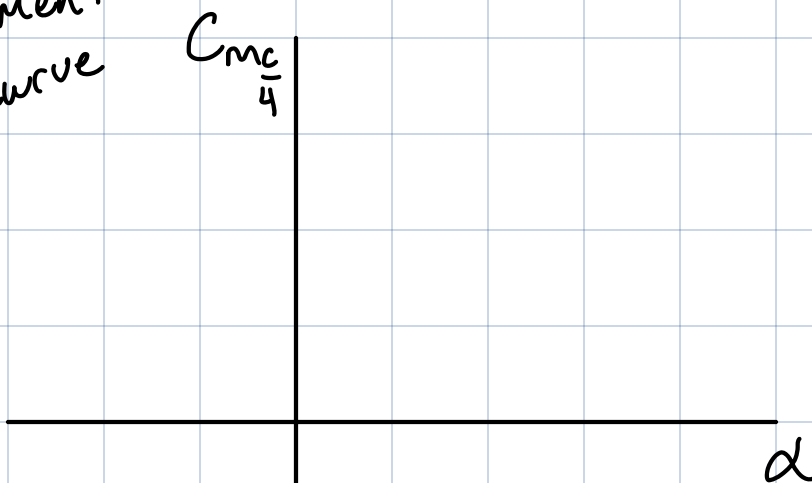
drag curve



drag bucket  $\leadsto$  Range of  $\alpha$  where  $C_d$  is low

moment curve

$C_{m\frac{\pi}{4}}$



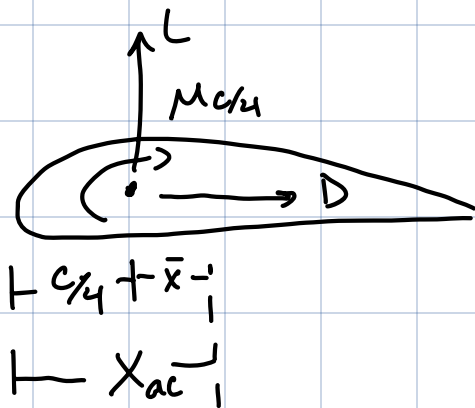
Negative  $C_m$   
 $\rightarrow$  stability

$\sim$  separated flow  
 $\sim$  moment curve

Slope  $\frac{dC_{m_{c/4}}}{d\alpha} = m_0$

~ constant over a Reasonable  $\alpha$  Range

Aerodynamic Center: can find it knowing  $m_0, a_0$



$$M = C_m \cdot q \cdot S_{REF} \cdot C$$

$$\frac{M_{ac}}{q S_{REF} C} = \frac{L \bar{x}}{q S_{REF} C} + \frac{M_{c/4}}{q S_{REF} C}$$

$$\rightarrow C_{mac} = C_L \cdot \frac{\bar{x}}{C} + C_{m_{c/4}}$$

if you want location of AC  $\rightarrow$  find where  $C_{mac}$  is a const with  $\alpha$

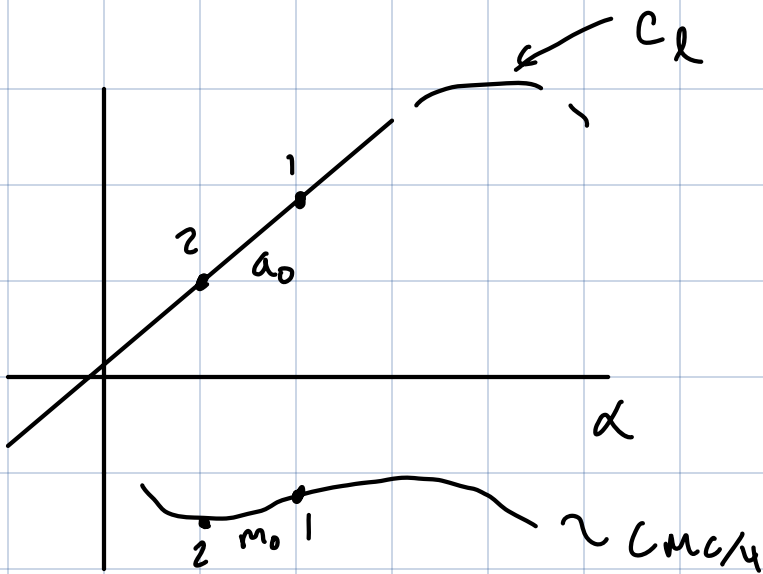
$$\hookrightarrow \frac{dC_{mac}}{d\alpha} = 0$$



differentiate  
with  $\alpha$

$$\frac{dC_{mac}}{d\alpha} = \frac{dC_L}{d\alpha} \bar{\frac{x}{C}} + \frac{dC_{mc/4}}{d\alpha} = 0$$

thus:  $\bar{\frac{x}{C}} = - \frac{dC_{mc/4}/d\alpha}{dC_L/d\alpha} = - \frac{m_0}{a_0}$



$$a_0 = \frac{C_{L1} - C_{L2}}{\alpha_1 - \alpha_2}$$

$$m_0 = \frac{C_{mc/4,1} - C_{mc/4,2}}{\alpha_1 - \alpha_2}$$

$C_L \leadsto$

$$a_0 = 2\pi\eta$$

$\hookrightarrow$  for  $\frac{dC_L}{d\alpha}$

then  $\frac{dC_L}{d\alpha} = \frac{a_0}{1 + \frac{a_0}{\pi R}}$   $\leftarrow$  in 3D

include  $M$  &  $\Delta$  affect

$$\frac{dC_L}{d\alpha} = \frac{2\pi R}{\left[2 + \sqrt{\left(\frac{R}{\eta}\right)^2 (1 + \tan^2 \Delta - M_\infty^2)}\right]}$$

$C_D \leadsto$  pressure + shear stress distribution

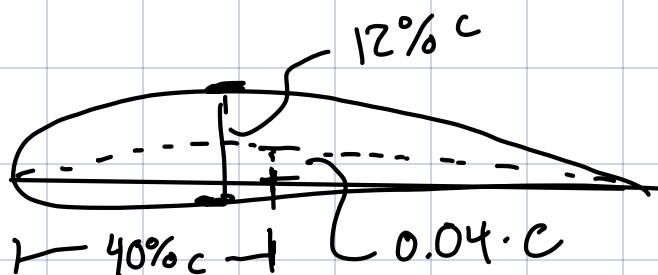
$$C_D \leadsto C_{Dp} + C_{Di} + \Delta C_{D,c}$$

$\uparrow$   
 $C_L$

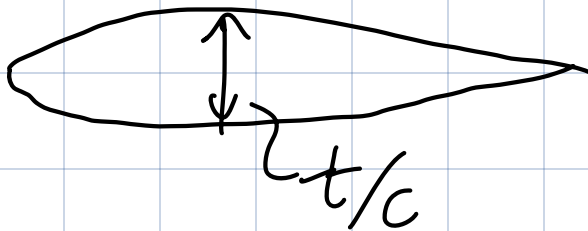
NACA 4 series (Naming Convention)

NACA 4412

max camber in % of chord (0.04 · c)  
 location of max camber in % of chord (40% chord)  
 max  $t/c$  in % chord (12%  $t/c$ )



- NACA 0012
  - max  $t/c$
  - symmetric, camber = 0



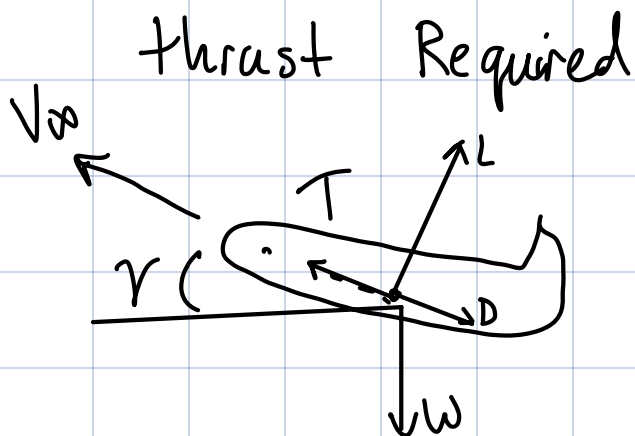
- NACA 5 Series

ex: NACA 23015

$\frac{20}{3}$  of the design  $C_L$

$t/c$

2x position of max camber, %C



if you are steady,  
level,  
 $\gamma = 0^\circ$ ,  $\Delta V = 0$

$$\hookrightarrow \omega = L$$
$$T = D$$

Thrust Required = Drag

$$\underline{W_{eng}} \cdot \frac{\text{Thrust}}{c_{ng}} = \text{Drag}$$

How do we get  $T_R$ ?

if you know  $W, R, S_{REF}$

if compressible  $C_D = C_{Dp} + C_{Di} + \Delta C_{D,c}$

if incompressible  $C_D = C_{Dp} + \frac{C_L^2}{\pi R}$

$$\frac{1}{\pi R_e} = K$$

$$= C_{DP} + K C_L^2$$

$$L = W = \frac{1}{2} \rho V^2 S C_L \rightarrow C_L = \frac{2W}{\rho V^2 S}$$

$$D = \frac{1}{2} \rho V^2 S C_D = \frac{1}{2} \rho V^2 S (C_{Dp} + K C_L^2)$$

$$= T_R$$

$$\sim V^2$$

$$\sim 1/V^2$$

