## **EDA**

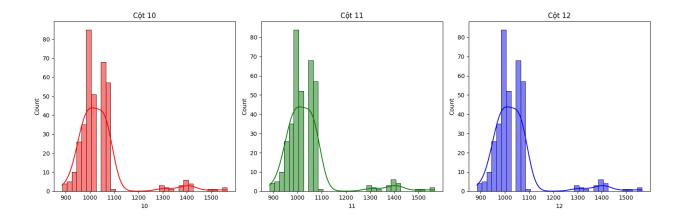
```
# Tryc quan hóa phân phối của cột 10,11,12
plt.figure(figsize=(15, 5))

plt.subplot(1, 3, 1)
sns.histplot(data=df, x=df.columns[10], kde=True, color='red')
plt.title('Cột ' + df.columns[10])

plt.subplot(1, 3, 2)
sns.histplot(data=df, x=df.columns[11], kde=True, color='green')
plt.title('Cột ' + df.columns[11])

plt.subplot(1, 3, 3)
sns.histplot(data=df, x=df.columns[12], kde=True, color='blue')
plt.title('Cột ' + df.columns[12])

plt.tight_layout()
plt.show()
```



```
# Tryc quan hóa mói quan hệ giữa các cột

columns_of_interest = ['10', '11', '12']

X = df[columns_of_interest].values

plt.figure(figsize=(15, 5))

#Biểu đô heatmap

correlation_matrix = df[columns_of_interest].corr()

plt.figure(figsize=(8, 6))

sns.heatmap(correlation_matrix, annot=True, cmop='summer', fmt='.2f')

plt.title('Heatmap of Correlation between Columns 10, 11, and 12')

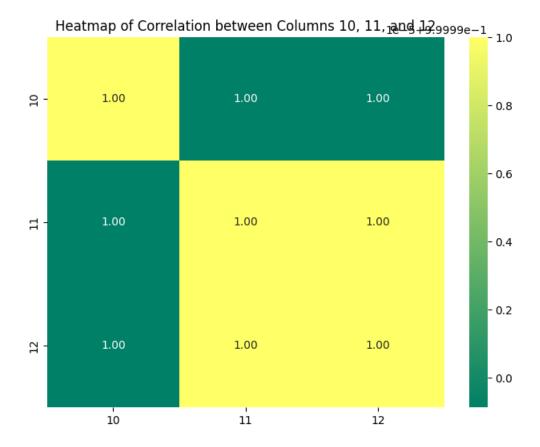
plt.show()

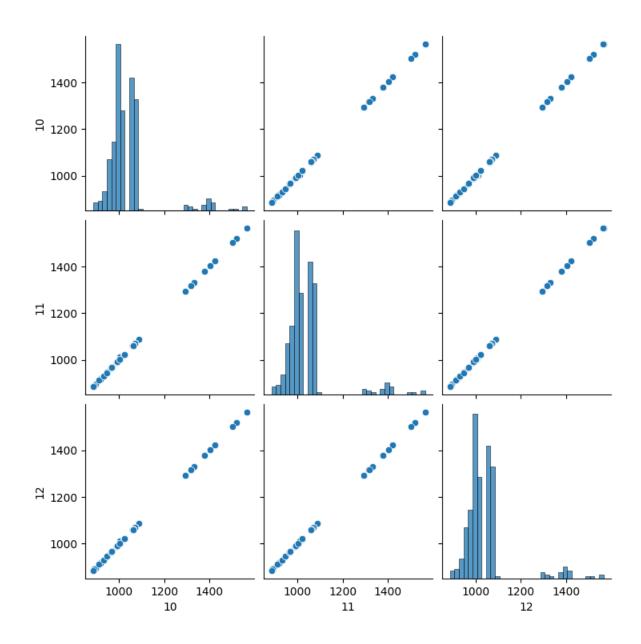
#Biểu đô scatter

sns.pairplot(df.iloc[:, [10, 11, 12]])

plt.show()

$\frac{26}{5}$
```





## **KALMA**

```
from filterpy,kalman filter(data):

def apply_kalman.filter(data):

kf = KalmanFilter(data):

kf = KalmanFilter(data):

kf.x = np.array([[1, 0.])

kf.x = np.array([[1, 0.]))

kf.y = np.array([[1, 0.]))

kf.y = 1000.

kf.x = 5

kf.Q = np.array([[0.1, 0.1], [0.1, 0.1]))

filtered_data = []

for z in data:

kf.predict()

kf.update(z)

filtered_data.append(kf.x[0])

return filtered_data

# Ap dung Kalman Filter cho cot thúr 10 (Feature_10)

filtered_feature_10 = apply_kalman_filter(X[:, 0])

# So sánh dữ liệu gốc và dữ liệu dā loc

plt.figure(figsize=[10, 6])

plt.plott(X[:, 0], Lobel='Original ' + df.columns[10], color = 'red')

plt.plott(X[:, 0], Lobel='Original ' + df.columns[10], linestyle='dashed')

plt.tile('Kalman Filter cha cot ' + df.columns[10])

plt.vlabel('Index')

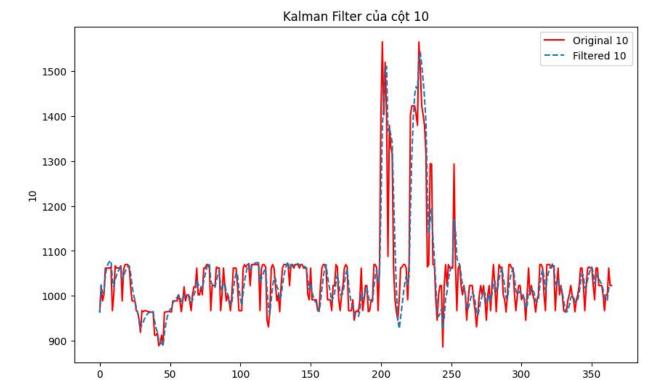
plt.vlabel('Index')

plt.legend()

plt.legend()

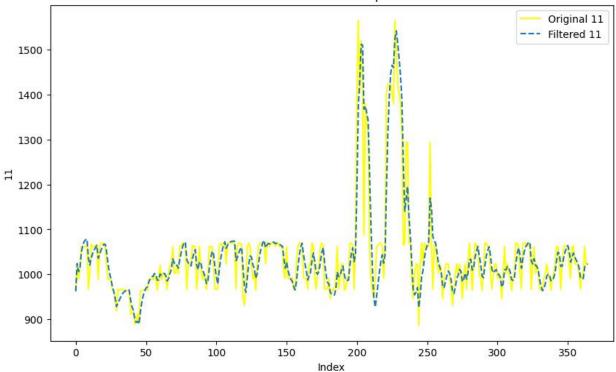
plt.legend()

plt.legend()
```



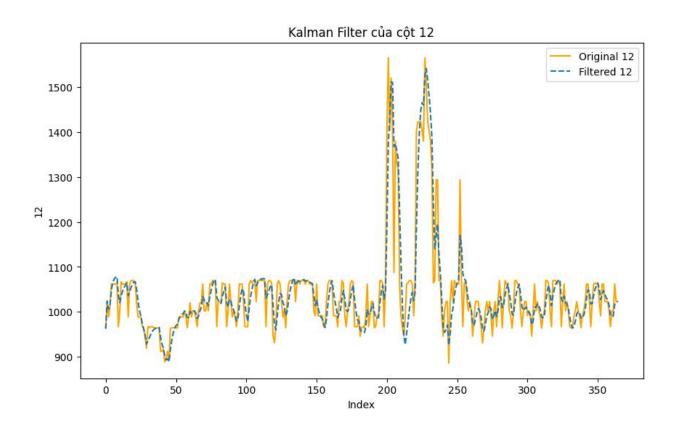
Index





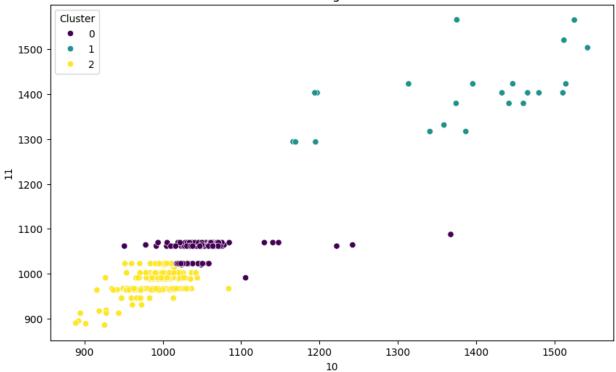
```
def apply_kalman_filter(data):
    kf = Kalmanfilter(dim_x=2, dim_z=1)
    kf.x = np.array([[1., 1.], [0., 1.]])
    kf.F = np.array([[1., 0.]])
    kf.F = np.array([[1., 0.]])
    kf.R = 1900.
    kf.R = 5
    kf.Q = np.array([[0.1, 0.1], [0.1, 0.1]])
    filtered_data = []
    for z in data:
        kf.predict()
        kf.padate(z)
        filtered_data.append(kf.x[0])
    return filtered_data

filtered_feature_12 = apply_kalman_filter(X[:, 2])
    plt.figure(figsize=(10, 6))
    plt.plot(X[:, 1], label='Original ' + df.columns[12], color='orange')
    plt.title('Kalman Filter cua cot ' + df.columns[12], linestyle='dashed')
    plt.title('Kalman Filter cua cot ' + df.columns[12])
    plt.tylabel('Index')
    plt.ylabel('df.columns[12])
    plt.ylabel(df.columns[12])
    plt.ylabel(df.columns[12])
```



## **KMEANS**

## K-means Clustering on Filtered Data



Link gihub: trinhdat24/ThucHanh3 TimeSeries (github.com)