

**Introduction to Sinusoidal Steady-State Analysis and Frequency response**

**Learning outcomes: Student**

- + is able to apply the Euler formula
- + knows how the time domain and frequency domain expressions are related to each other
- + know how the frequency response is defined and which information it contains

## Sinusoidal Steady-State Analysis

From Wikipedia: The Euler's formula

$$e^{ix} = \cos x + i \sin x,$$

indicates that sinusoids can be represented mathematically as the sum of two complex-valued functions

$$A \cdot \cos(\omega t + \phi) = A \cdot \frac{e^{i(\omega t + \phi)} + e^{-i(\omega t + \phi)}}{2},$$

or as the real part of one of the functions

$$A \cdot \cos(\omega t + \phi) = \operatorname{Re}\{A \cdot e^{i(\omega t + \phi)}\} = \operatorname{Re}\{A \cdot e^{i\phi} e^{i(\omega t)}\}.$$

The quantity  $Ae^{i\phi} \in \mathbb{C}(A, \phi \in \mathbb{R})$  is a complex number, the phasor representation of the signal. It can be expressed in the angle notation as

$$A\angle\phi.$$

So, in case of the cos –reference, transformation from time domain to phasors and back reads

$$A \cdot \cos(\omega t + \phi) \Leftrightarrow A\angle\phi.$$

Question: How do you determine  $\omega$  from a phasor?

Question: Consider  $y_1(t) = 20 \cos(\omega t - 30^\circ)$  and  $y_2(t) = 40 \cos(\omega t + 60^\circ)$ .

1. Find the phasors  $Y_1$  and  $Y_2$  that represent  $y_1$  and  $y_2$ , respectively.
2. Find sum of the two functions, use phasors, i.e. find  $Y = Y_1 + Y_2$ .
3. Find the time domain signal  $y(t) = y_1(t) + y_2(t)$  from  $Y$ .

Question: Let  $v_{in}(t) = v_1(t) + v_2(t)$  where

$$\begin{aligned}v_1(t) &= 5 \cos(\omega_1 t) \text{ and} \\v_2(t) &= 0.5 \cos(\omega_2 t)\end{aligned}$$

with  $f_1 = 3$  kHz and  $f_2 = 10$  kHz.

1. Find the phasors  $V_1$  and  $V_2$  that represent  $v_1$  and  $v_2$ , respectively.
2. Can you add the two phasors  $V_1$  and  $V_2$ ?

If **yes**, explain how to interpret the result. If **no**, what can you do?

**Review of Transfer function   Frequency response**

**Learning outcomes: Student**

- + knows how the transfer function and frequency response are defined,
- + is able to determine the transfer function of a circuit,
- + is able to interpret the amplitude plot and the phase angle plot.

## Transfer function & Frequency response

*Transfer function*  $H(\omega)$  of a system is defined in the frequency domain. Let

$X(\omega)$  denote the input in the frequency domain, see Fig. 1,

$Y(\omega)$  denote the output in the frequency domain, see Fig. 1,

then

$$H(\omega) = \frac{Y(\omega)}{X(\omega)}.$$

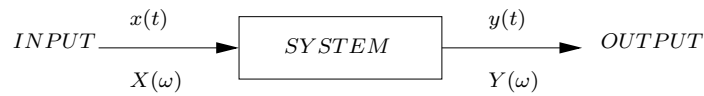


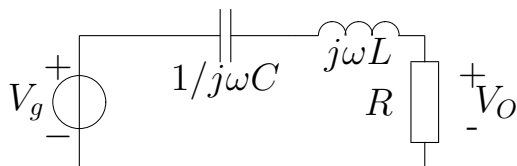
Figure 1: A general system with input and output in time and frequency domain.

Transfer function is commonly utilized, e.g, in

designing electronic filters, amplifiers,

signal processing, communication theory, ....

Example: Find transfer function, if  $V_g(\omega)$  is the input and voltage  $V_O(\omega)$  across the resistance is the output



Total *impedance*  $Z(\omega) = R + j\omega L + \frac{1}{j\omega C}$ , hence

$$V_g(\omega) = I(\omega) * Z(\omega) \Leftrightarrow I(\omega) = \frac{V_g}{Z} = \frac{V_g}{R + j\omega L + \frac{1}{j\omega C}}$$

and

$$V_O(\omega) = R * I = R * \frac{V_g}{R + j\omega L + \frac{1}{j\omega C}} \Leftrightarrow H(\omega) = \frac{V_O}{V_g} = \frac{\left(\frac{R}{L}\right) j\omega}{\left(\frac{R}{L}\right) j\omega + (j\omega)^2 + \frac{1}{LC}}$$

Once the transfer function of a system is known, also *frequency response* plots of the system are readily obtained

**magnitude plot:**  $|H(\omega)|$

**phase angle plot:**  $\text{angle}(H(\omega))$

Example continued: Let us return to the previous example, where the transfer function reads

$$H(\omega) = \frac{\left(\frac{R}{L}\right) * j\omega}{\left(\frac{R}{L}\right) * j\omega + (j\omega)^2 + \frac{1}{LC}},$$

and let us choose  $R = 20 \, \Omega$ ,  $C = 1 \, \mu\text{F}$ ,  $L = 50 \, \text{mH}$ . The frequency response with these values are shown in Figures 2 and 3.

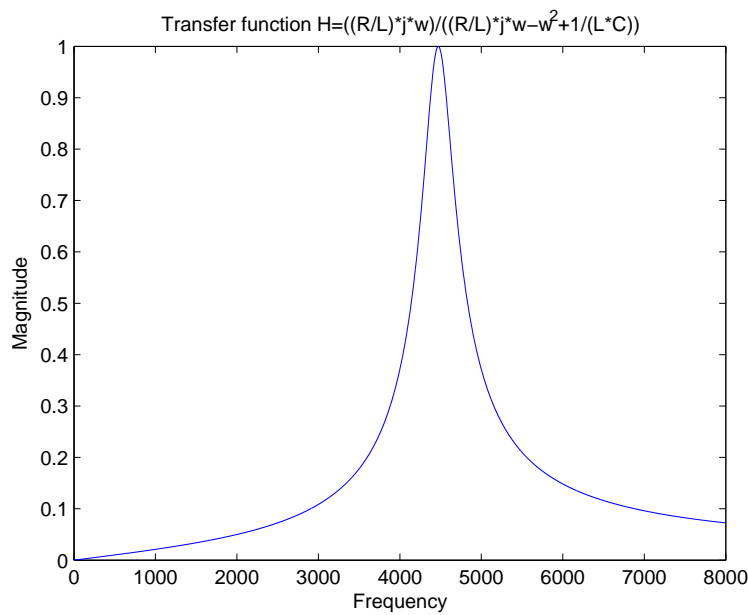


Figure 2: Magnitude plot of the transfer function.

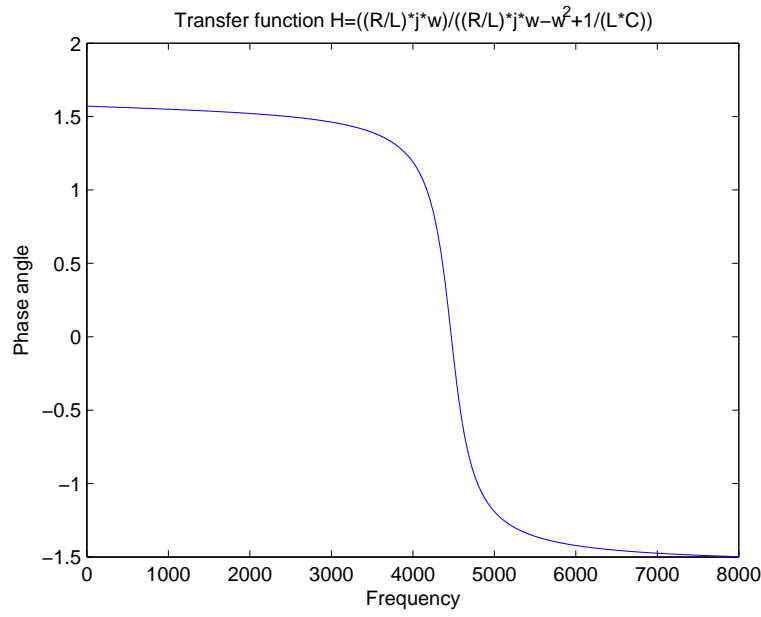


Figure 3: Phase angle plot of the transfer function.

The above is an example of a *bandpass filter*. To characterize response of such a system, we can use:

*Cutoff Frequency*: frequency/frequencies where magnitude of a transfer function is decreased by factor  $\frac{1}{\sqrt{2}}$  from its maximum value, i.e,

$$|H(\omega_C)| = \frac{1}{\sqrt{2}} H_{max}.$$

We obtain two frequencies  $\omega_{c1}$ ,  $\omega_{c2}$  (where  $\omega_{c1} < \omega_{c2}$ ) and find values for three parameters:

$$\text{center frequency } \omega_0 = \sqrt{\omega_{c1} * \omega_{c2}},$$

$$\text{bandwidth } BW = \omega_{c2} - \omega_{c1}$$

$$\text{quality factor } Q \approx \frac{\omega_0}{BW}$$

In our example  $\omega_1 = 4276.6$ ,  $\omega_2 = 4676.6$ ,

$$\omega_0 = 4472, BW = 400, Q \approx 11.183.$$

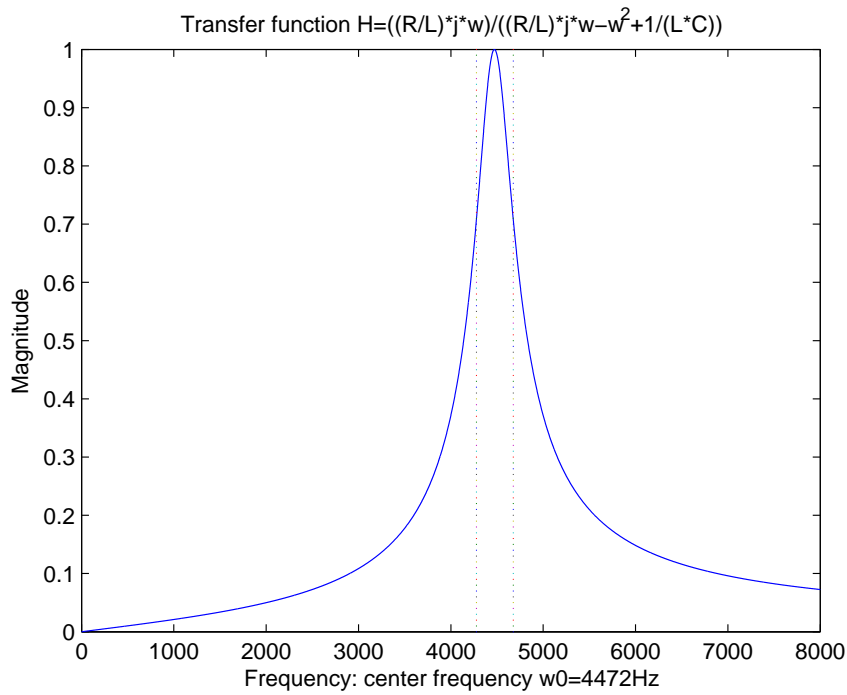


Figure 4: Magnitude plot of the transfer function. Half power cutoff frequencies marked on the plot.

### Use of the Transfer function: Some theory

It can be shown (see, for example, Nilsson & Riedel “*Electric Circuits*” 7th edition, chapter 13.7) that if a steady-state sinusoidal input

$$x(t) = A \cos(\omega t + \phi) \quad \Leftrightarrow \quad A \angle \phi$$

is applied to a circuit whose transfer function

$$H(\omega) = |H(\omega)| e^{j\theta(\omega)} = |H| e^{j\theta} \in \mathbb{C}$$

is known, the output is

$$y_{ss}(t) = A |H| \cos(\omega t + \phi + \theta). \quad (1)$$

Question:

1. How to interpret equation (1)?
2. Express  $y_{ss}(t)$  as a phasor.
3. Could you rewrite the phasor such that it includes a term related to the transfer function and a term related to the input?



## Notes on some more involved theory

If we analyze in mathematical rigour, we should apply the Laplace transform.

From Wikipedia: The Laplace transform of a function  $f(t)$ , defined for all real numbers  $t \geq 0$ , is the function  $F(s)$ , which is defined by

$$F(s) = \int_0^{\infty} f(t)e^{-st} dt,$$

where  $s$  is a complex number

$$s = \sigma + i\omega \text{ with } \sigma, \omega \in \mathbb{R}.$$

### Remarks

Equation (1) is derived using the Laplace transform.

In case of sinusoidal steady-state  $s$  is replaced by  $j\omega$ .

For example, after the Laplace transform “impedance of an inductor” is expressed as  $sL$  and in the sinusoidal steady-state case as  $j\omega L$ .

## TASKS

- Design a first-order passive low-pass filter, cutoff-frequency 340 Hz. Use 470 nF capacitor and choose suitable resistor from the list attached (Table 1).
  - Determine transfer function of the circuit by paper and pen. From it check
    - magnitude and phase at the cutoff-frequency.
    - magnitude and phase at low and at high frequencies.
- Lets use Multisim and myDAQ to work with the filter, in particular, use so called *Bode Analyzer*. We are going to (a) simulate and (b) measure the circuit. You use both Multisim and myDAQ such that their results can be easily compared.

For that you use *NI myDAQ design* in Multisim, you find guidelines in a video:  
[https://www.youtube.com/watch?v=ZpmAEj\\_biJ0](https://www.youtube.com/watch?v=ZpmAEj_biJ0)

- Simulate the circuit in Multisim.
- Construct and measure the circuit using breadboard and myDAQ.

Checklist:

AO-0 is used as the input source.

Analogue ground (AGND) is attached to the ground reference point of your circuit i.e. the bottom leg of the Capacitor.

AI-0+ is used to measure the input voltage

AI-1+ is used to measure the output voltage across the Capacitor

All voltages are measured across two points, in this case with respect to ground -> connect AI-0- and AI-1- to analogue ground (AGND)

- Let transfer function of a circuit be  $H(\omega) = \frac{1}{1+j\omega*4*10^{-5}}$ , see Fig. 5.  
Define output of the circuit, if  $v_{in}(t) = 5 \cos(\omega_1 t) + 0.5 \cos(\omega_2 t)$  where  $f_1 = 3$  kHz and  $f_2 = 10$  kHz.

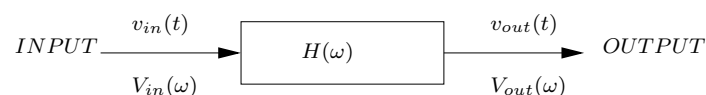


Figure 5: A circuit whose transfer function  $H(\omega)$  is known.

#### 4. **OPTIONAL Extra task**, if time allows

- First, paper-and-pen:
  - Design a first-order passive high-pass filter (HP), cutoff-frequency 300 Hz. Use a 100 nF capacitor and select resistor from the list attached (Table 1).

- ii. Design a first order passive low-pass filter (LP), cutoff-frequency 3000 Hz. Use a 470 pF capacitor and select resistor from the list attached (Table 1).
- (b) Second, simulations (see the guidelines below about simulations):
  - i. Simulate the high-pass filter using Multisim.
  - ii. Simulate the low-pass filter using Multisim.
- (c) Then connect the two filters in cascade in Multisim to have a band-pass filter.
  - i. Connect first HP->LP.
  - ii. Connect then LP->HP.

Do you notice any differences between the outputs in these two cases? If so, could you think of a reason for that.

HINTS: It is likely easier to use the AC Analysis in Multisim:

Open a new “Blank” design, place the components by selecting Place -> Component.

Place the voltage source by selecting

- Group: Sources,
- Family: POWER\_SOURCES, Component: AC\_POWER (default values will be ok for now, since we aim to sweep over a range of frequencies).

Label parts appropriately by double-clicking a wire to refer to them when setting up a simulation (see the Fig. 6 where labels IN1 and OUT1 have been added). You may need to tick 'Show net name' to get the label visible.

Once the circuit is ready, select Simulate -> Analysis -> AC Analysis. For settings use:

- Set “Frequency parameters” appropriately (e.g. 10 Hz - 100 kHz)
- Under Output select Add Expression and set expression where you use labels to define ratio between input and output voltages e.g. “V(OUT1)/V(IN1)” -> you get frequency response of the filter(s).

Item	Type	Needed
<b>Capacitor</b>	100nF	
	47nF	
	470pF	
	220pF	
<b>Resistor</b>	360k	
	330k	
	240k	
	180k	
	110k	
	100k	
	91k	
	82k	
	75k	
	68k	
	56k	
	16k	
	11k	
	8.2k	
	6.8k	
	5.6k	
	4.7k	
	3.6k	
	2.7k	
	1.0k	
	820	
	680	

Table 1: Filter part list

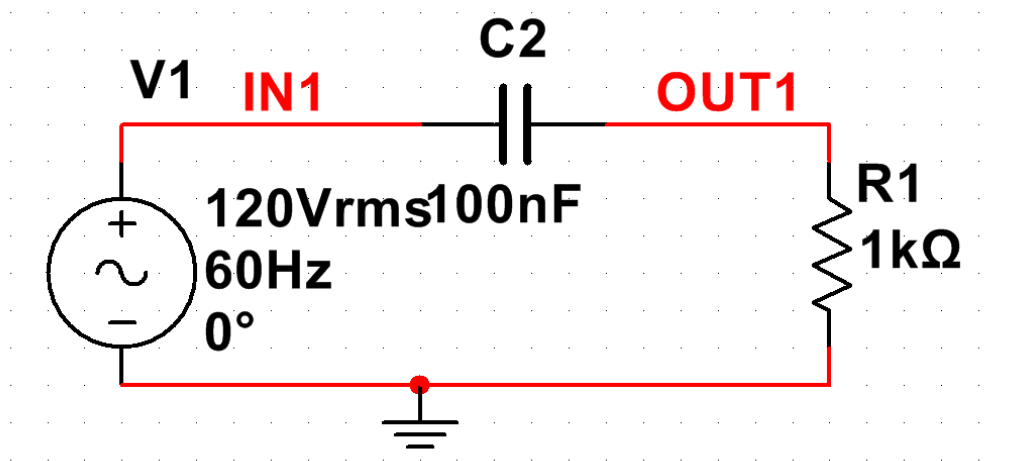


Figure 6: Example of labeling parts of a circuit.