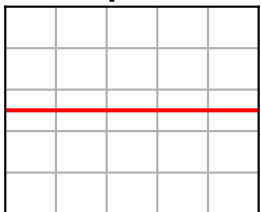


Track position



angle  
[°]



0

impact  
[mm]



-0.0

RC  
[ns/mm<sup>2</sup>]



120

Drift  
[mm]



250

Reset

Signal [ADC counts/cm]

800

600

400

200

0

0

500

1000

1500

2000

2500

3000

Time [ns]

- 2nd top neighbor
- 1st top neighbor
- Central pad
- 1st bottom neighbor
- 2nd bottom neighbor
- Vertical cluster
- True signal