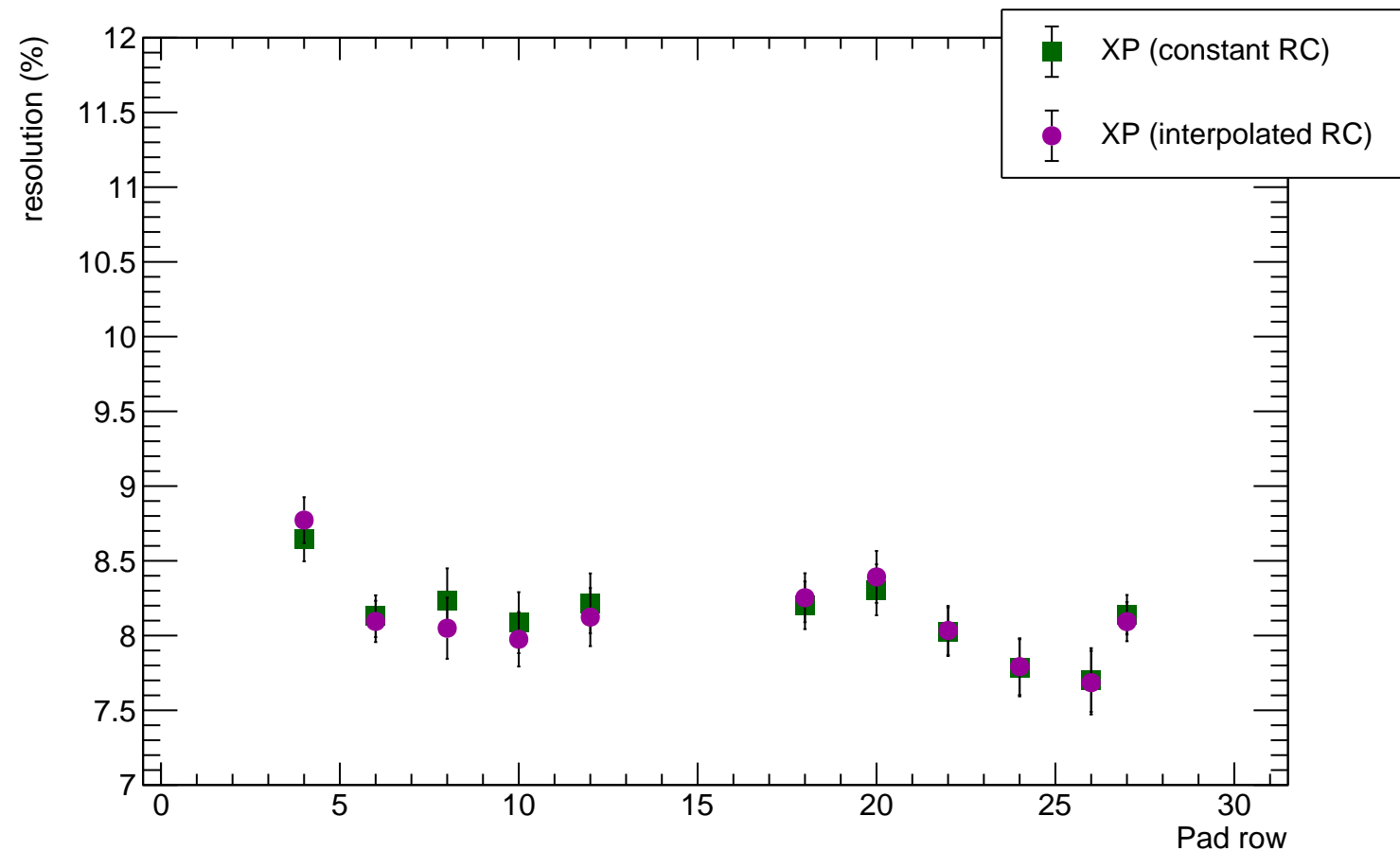
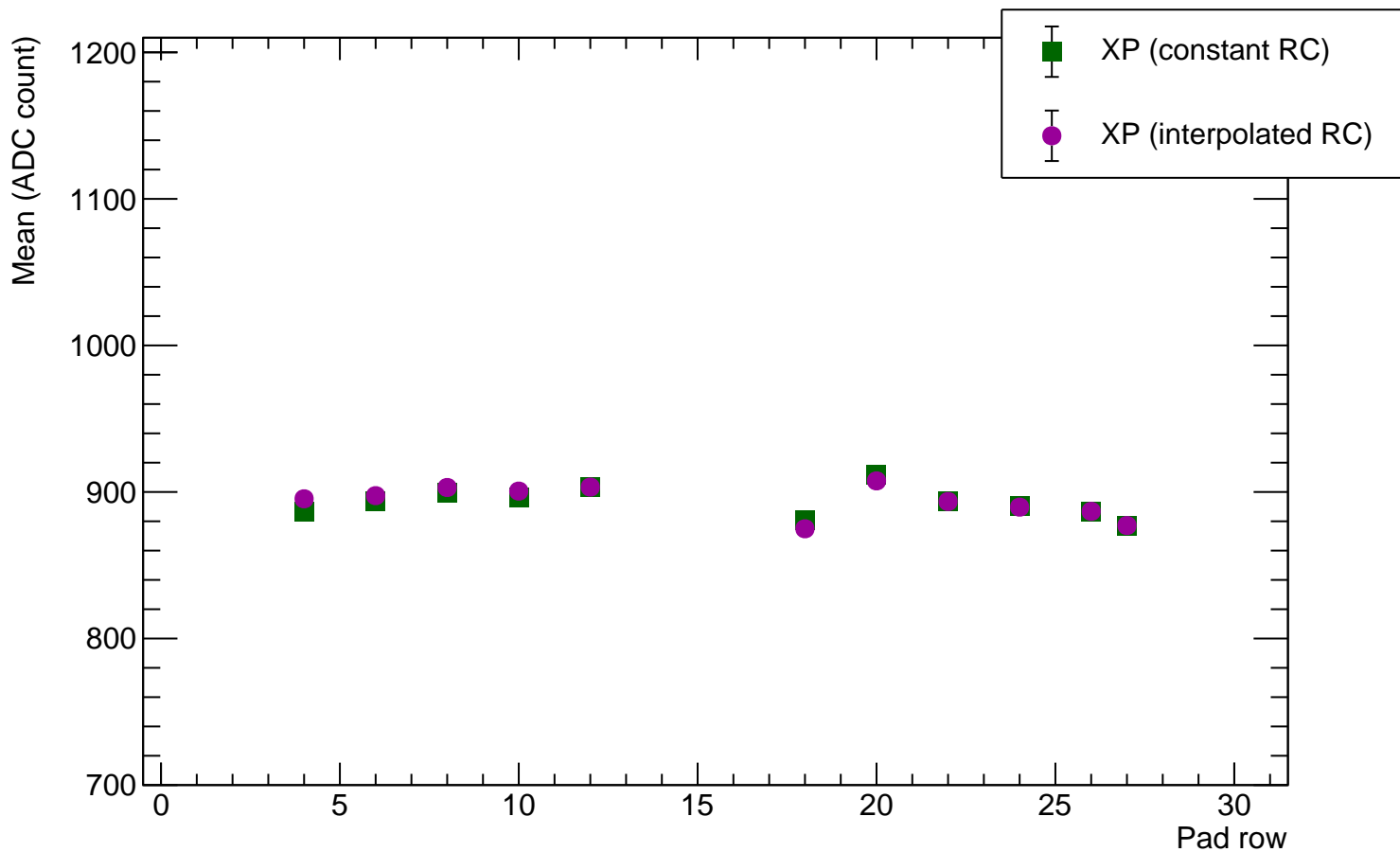


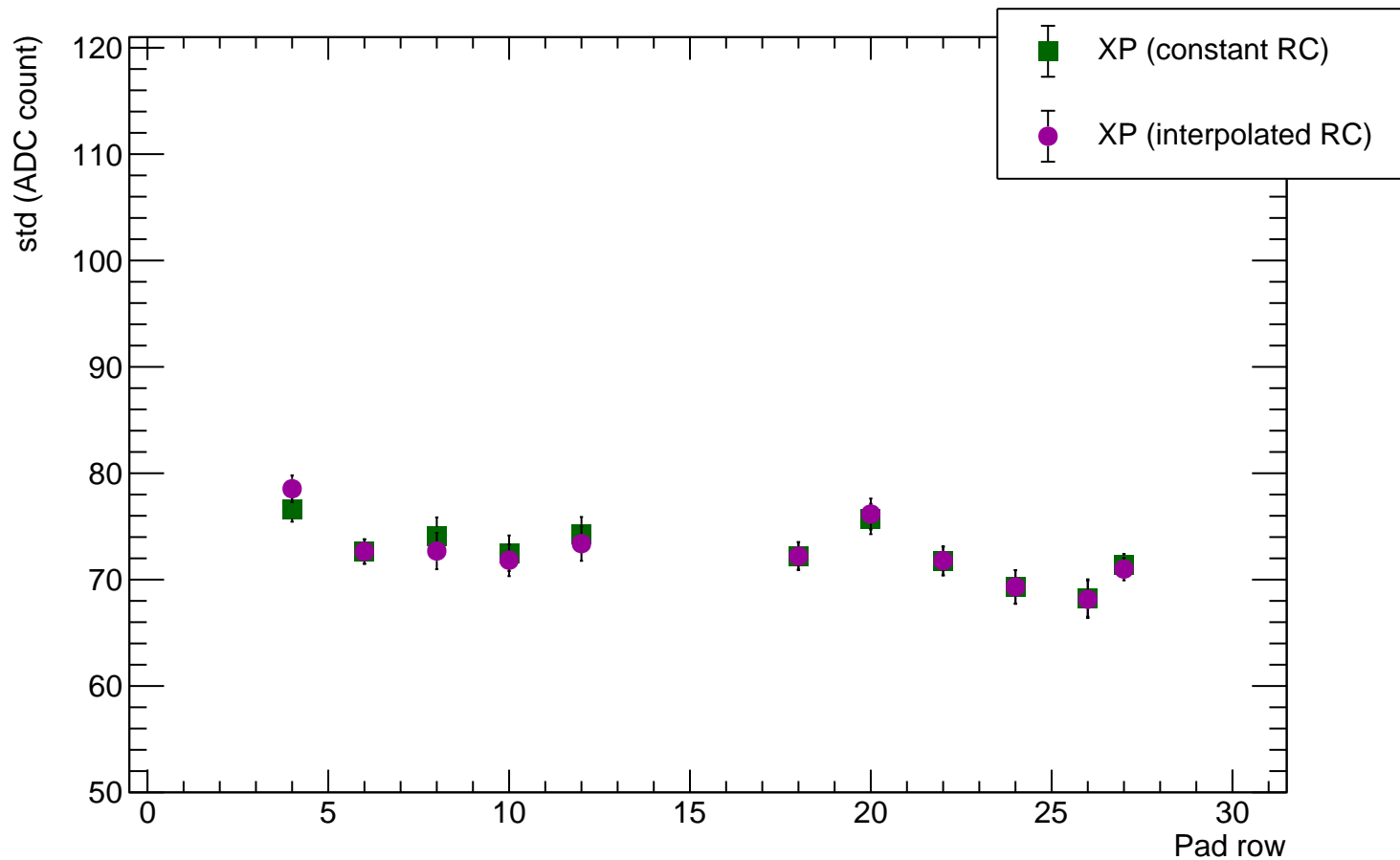
Resolution vs Y position



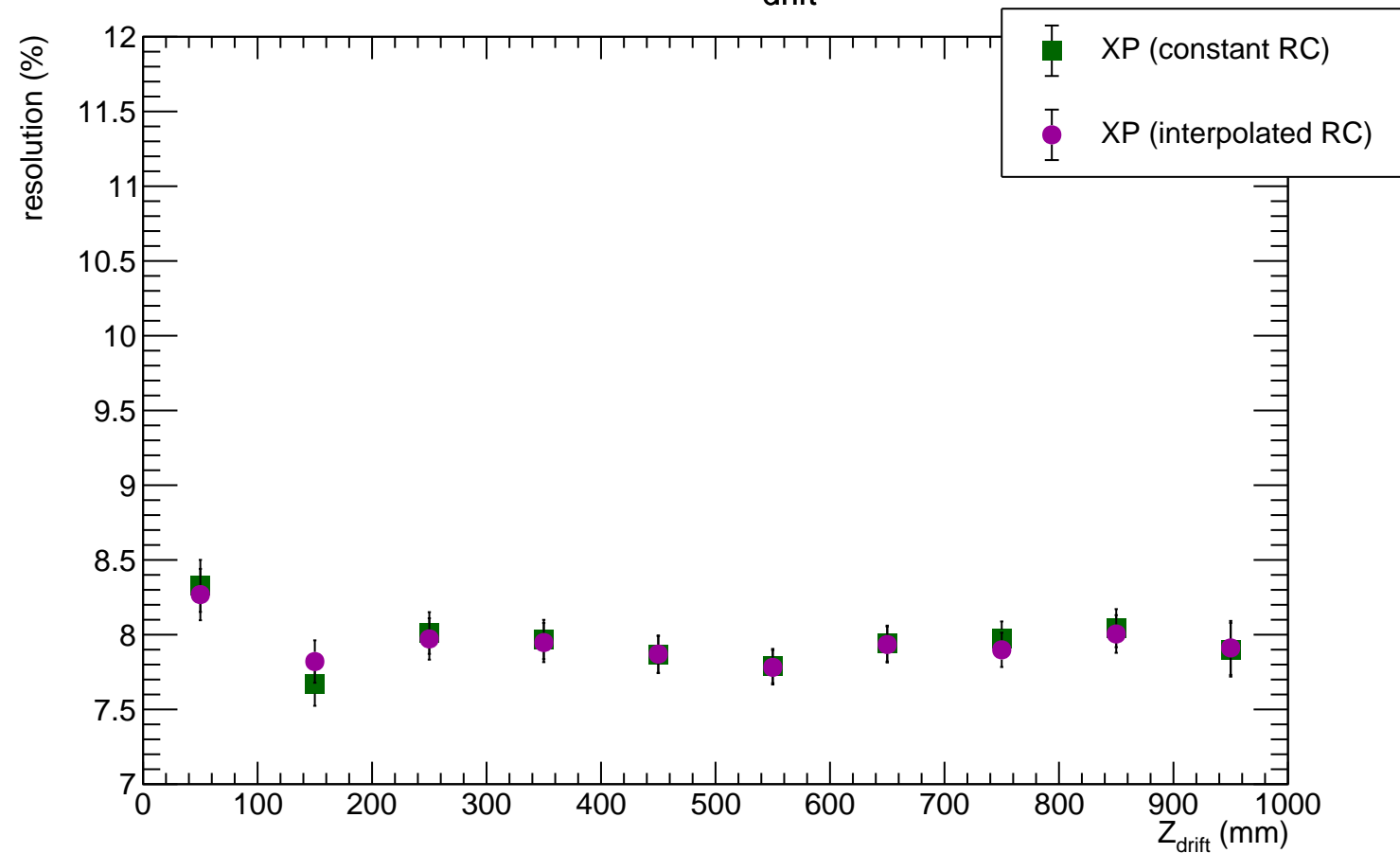
Mean vs Y position



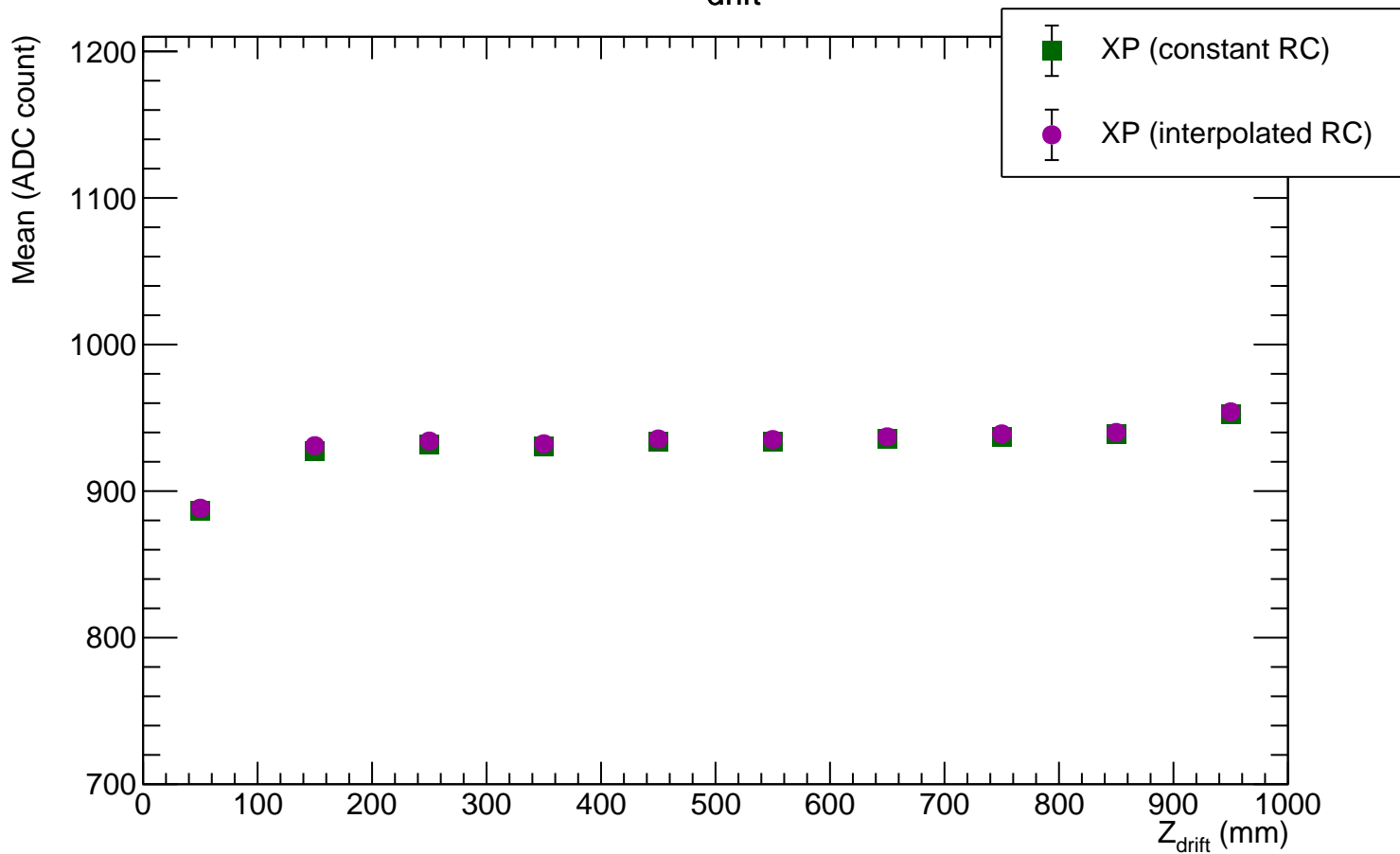
Std vs Y position



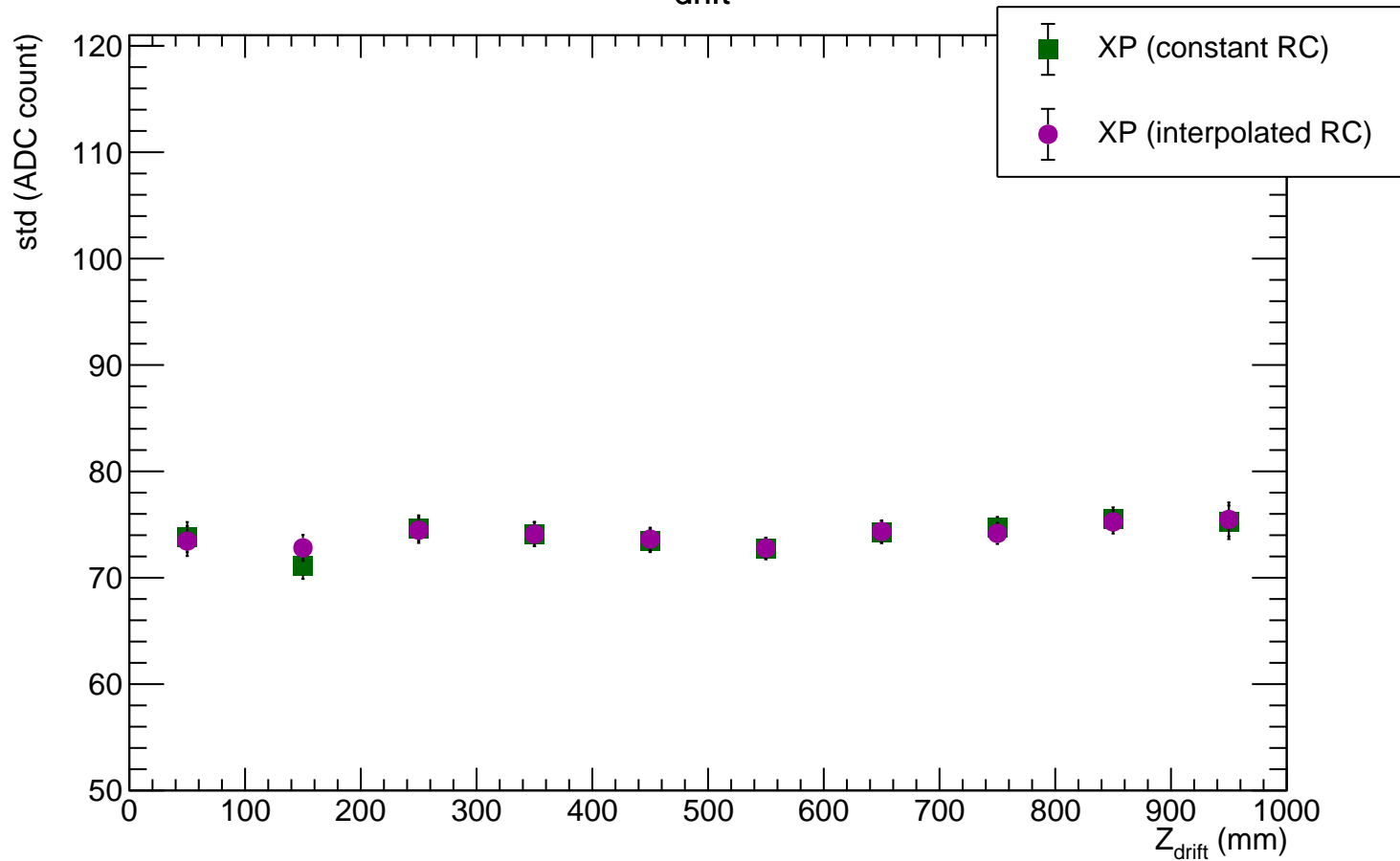
Resolution vs Z_{drift} (200 ns)



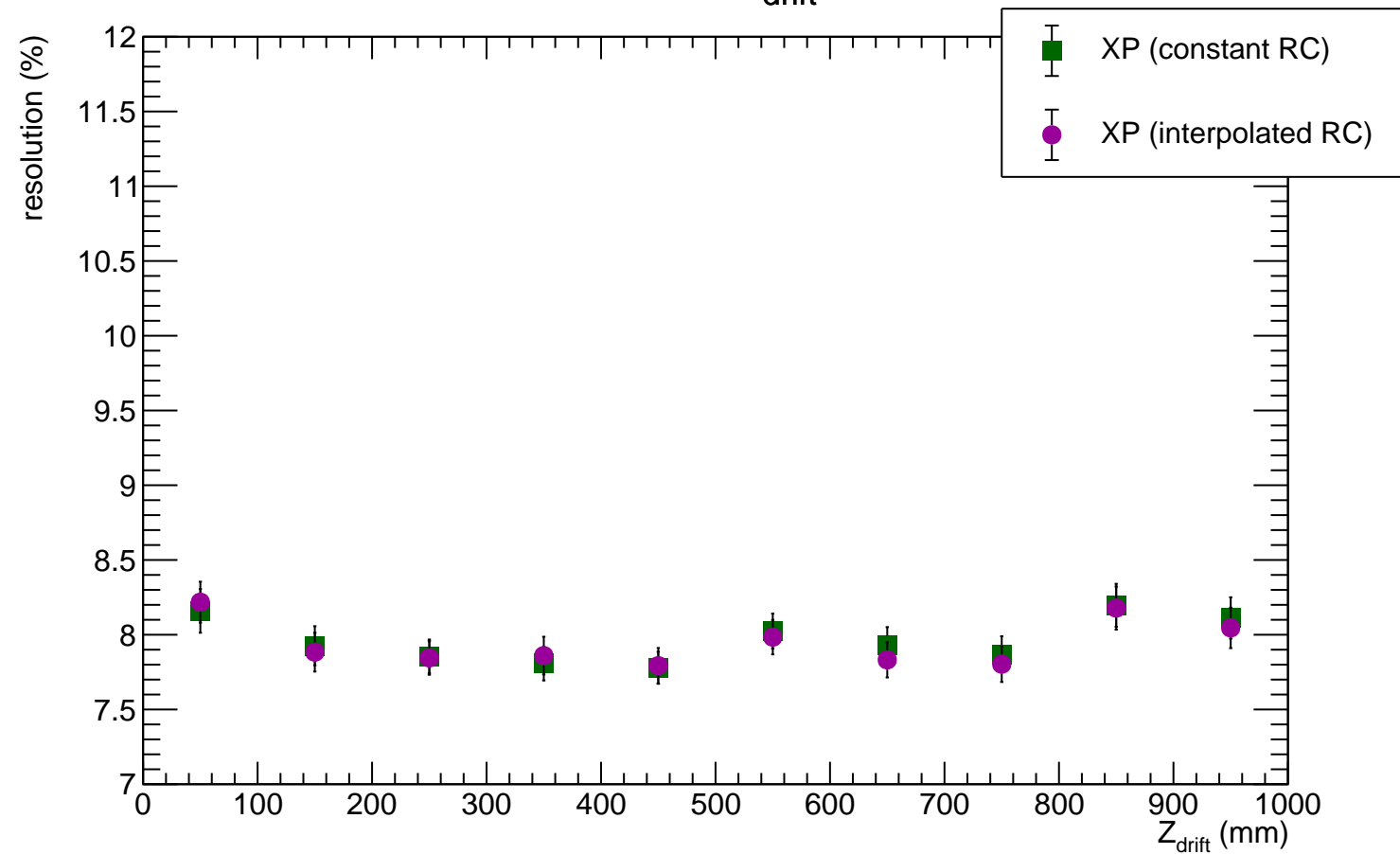
Mean vs Z_{drift} (200 ns)



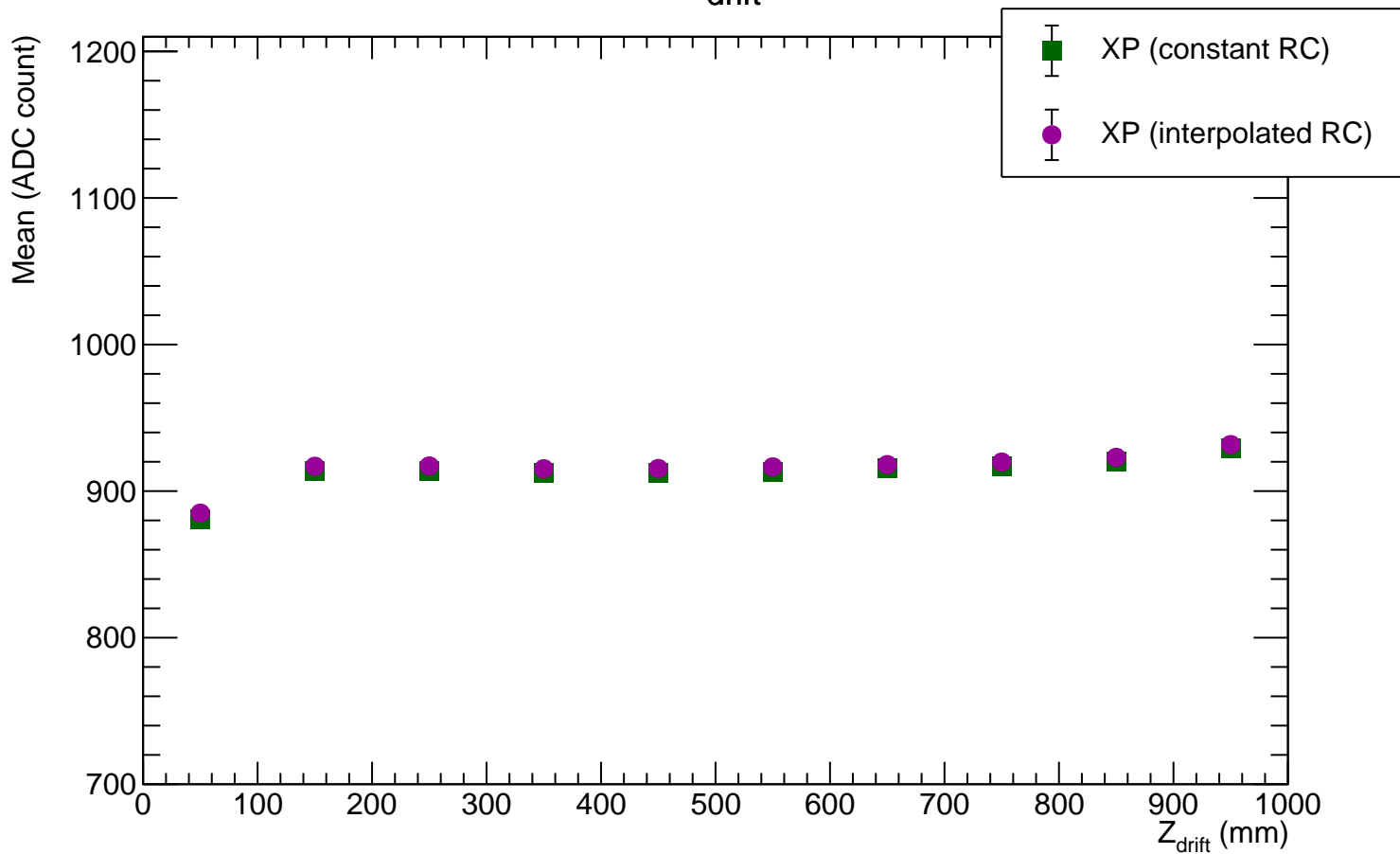
Std vs Z_{drift} (200 ns)



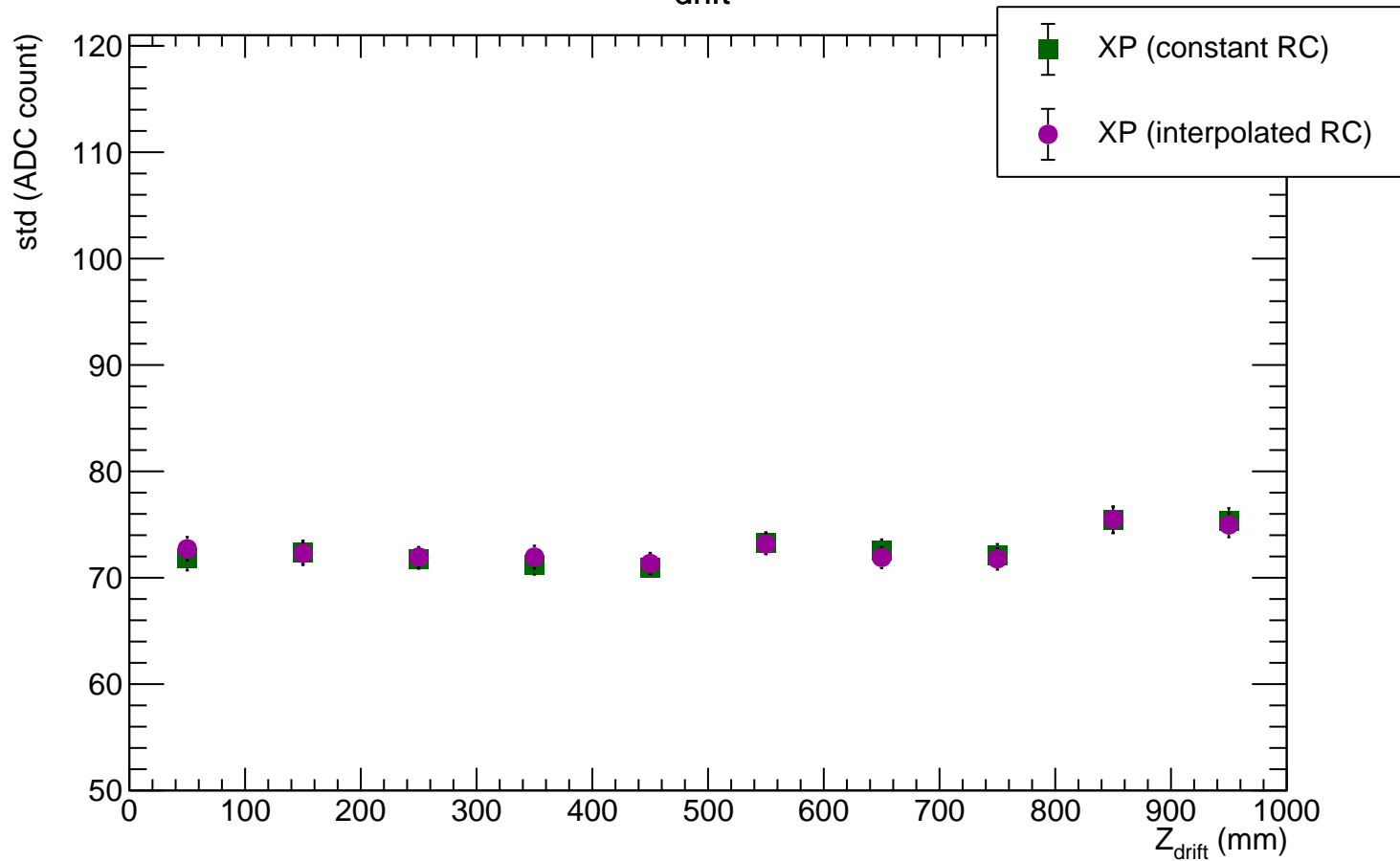
Resolution vs Z_{drift} (412 ns)



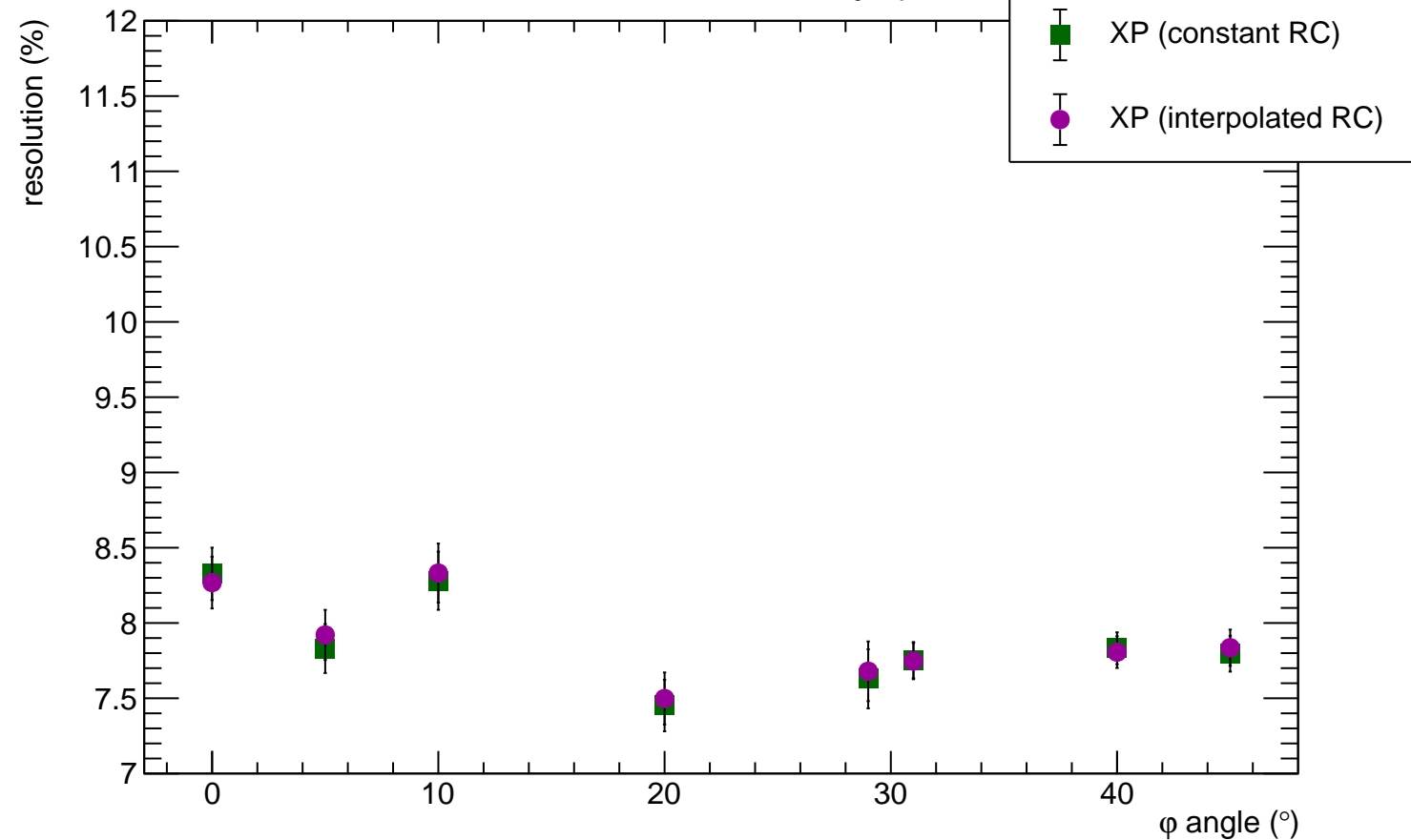
Mean vs Z_{drift} (412 ns)



Std vs Z_{drift} (412 ns)



Resolution vs ϕ angle ($Z_{\text{drift}} = 50$ mm)



Mean vs ϕ angle ($Z_{\text{drift}} = 50$ mm)

Mean (ADC count)

1200
1100
1000
900
800
700

0

10

20

30

40

ϕ angle ($^{\circ}$)



XP (constant RC)



XP (interpolated RC)

0

10

20

30

40

700

800

900

1000

1100

1200

700

10

20

30

40

800

900

1000

1100

1200

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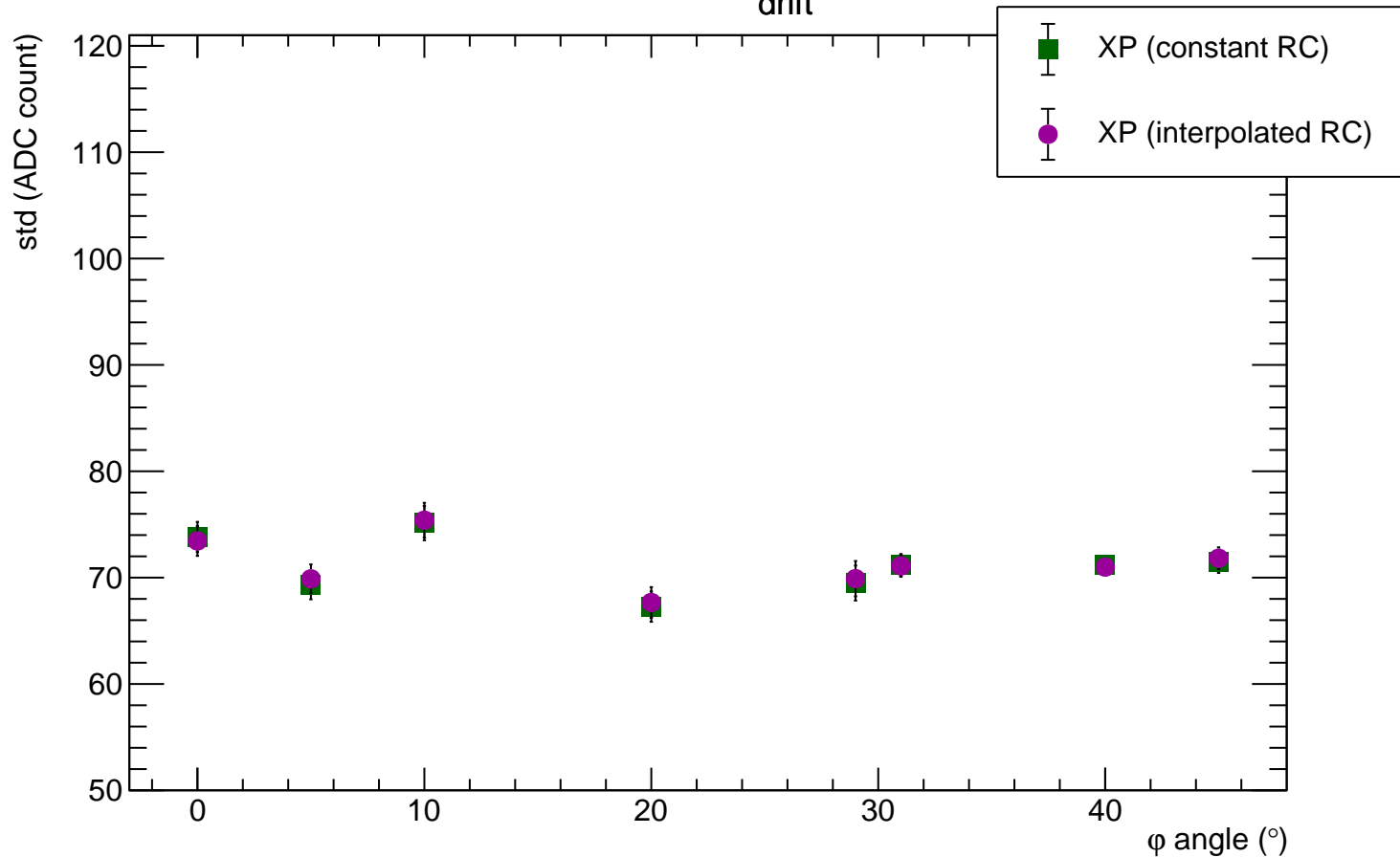
900

1000

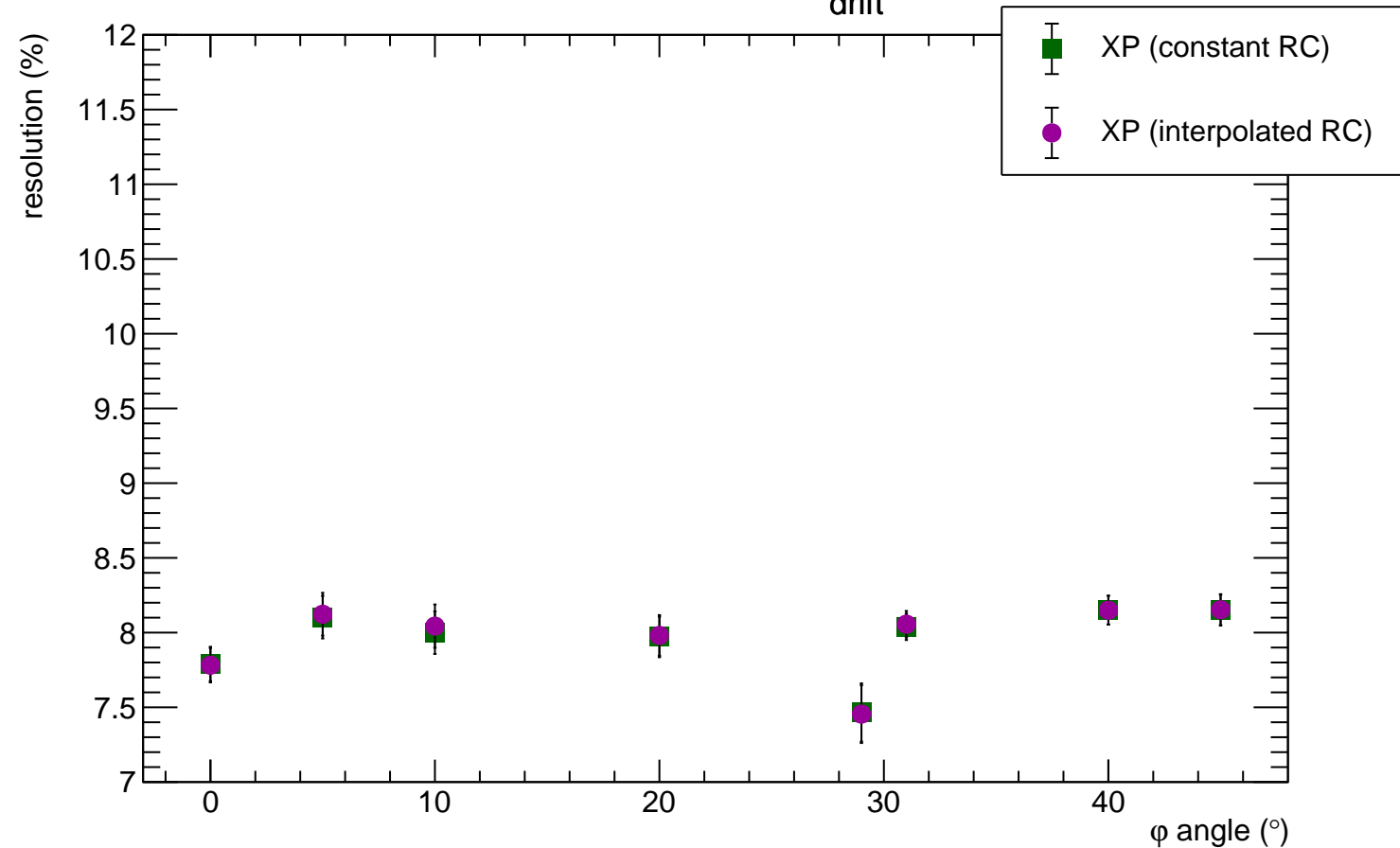
1100

1200

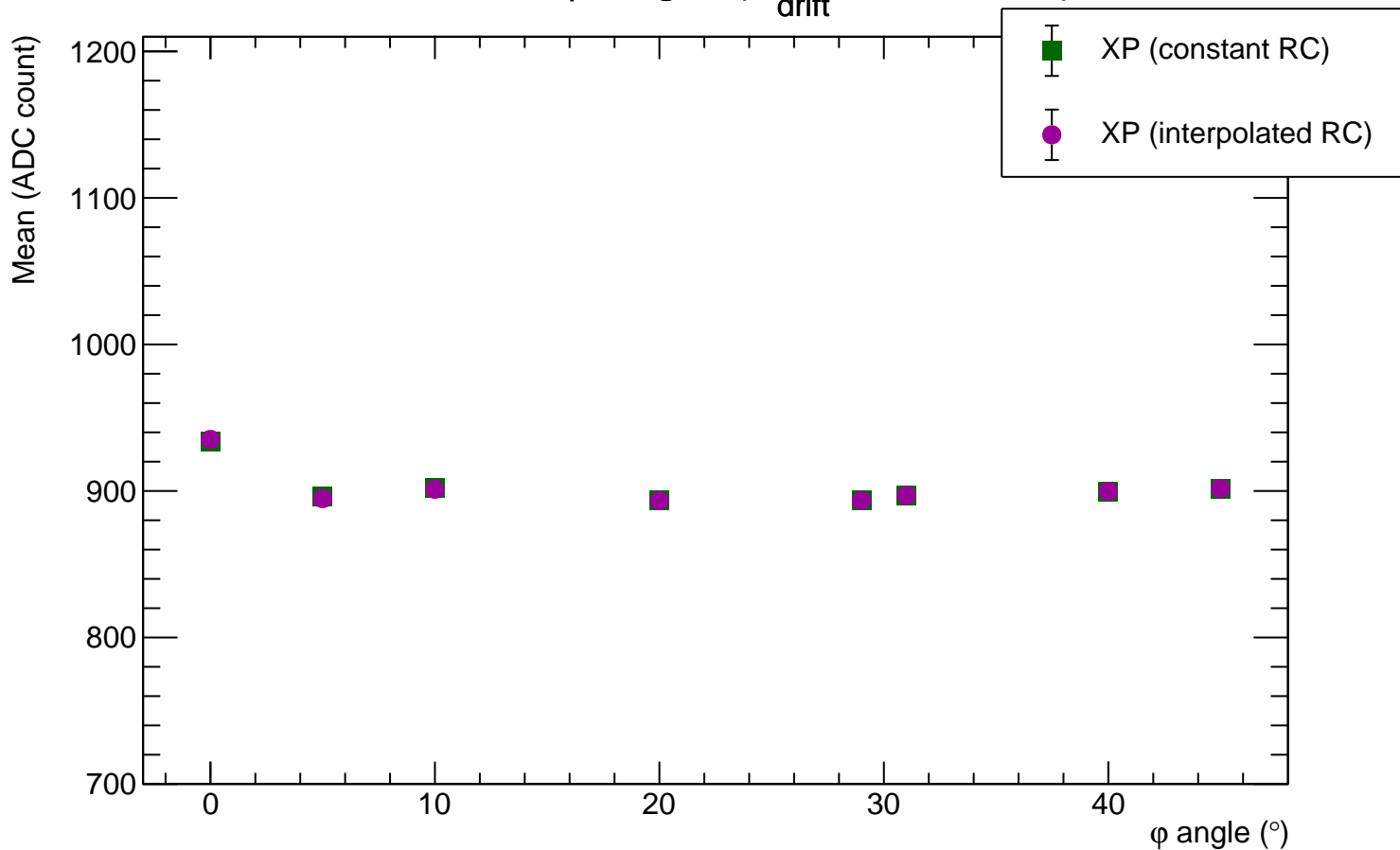
Std vs ϕ angle ($Z_{\text{drift}} = 50$ mm)



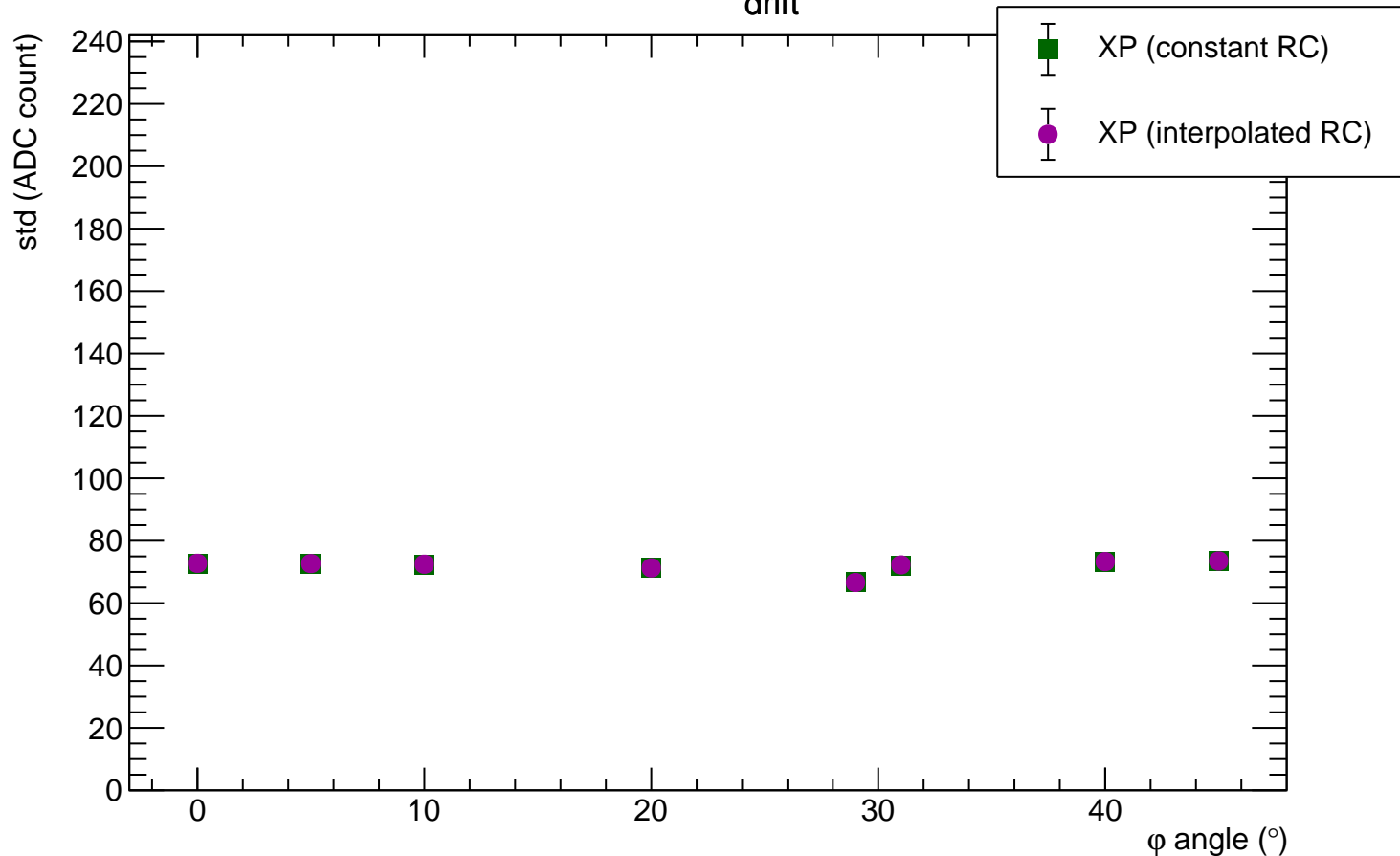
Resolution vs ϕ angle ($Z_{\text{drift}} = 550$ mm)



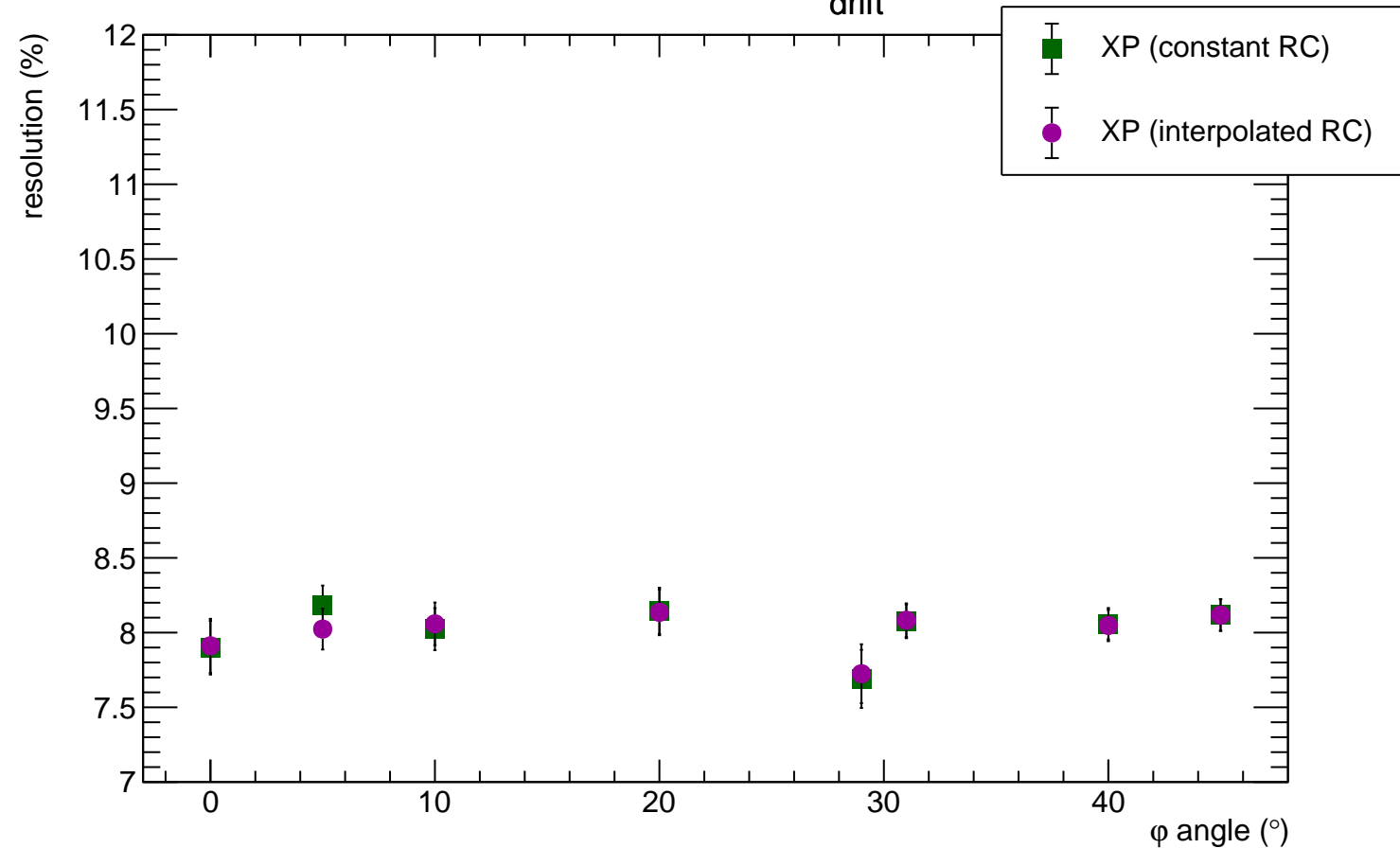
Mean vs ϕ angle ($Z_{\text{drift}} = 550$ mm)



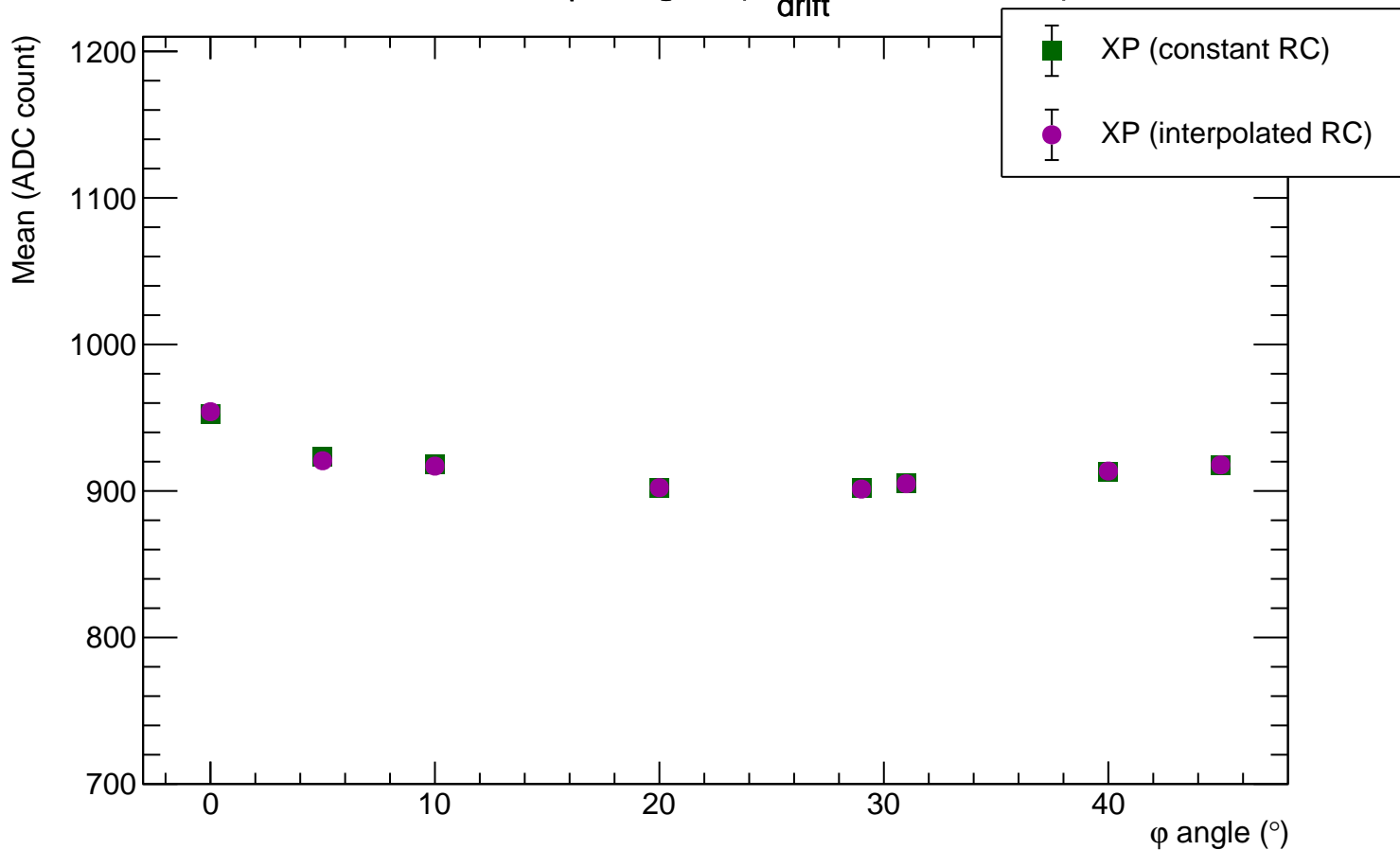
Std vs ϕ angle ($Z_{\text{drift}} = 550$ mm)



Resolution vs ϕ angle ($Z_{\text{drift}} = 950$ mm)



Mean vs ϕ angle ($Z_{\text{drift}} = 950$ mm)



Std vs ϕ angle ($Z_{\text{drift}} = 950$ mm)

