TEXAS INSTRUMENTS

LF155, LF156, LF256, LF257
LF355, LF356, LF357

SNOSBH0D – MAY 2000 – REVISED NOVEMBER 2015

LFx5x JFET Input Operational Amplifiers

1 Features

- Advantages
  - Replace Expensive Hybrid and Module FET Op Amps
  - Rugged JFETs Allow Blow-Out Free Handling Compared With MOSFET Input Devices
  - Excellent for Low Noise Applications Using Either High or Low Source Impedance—Very Low 1/f Corner
  - Offset Adjust Does Not Degrade Drift or Common-Mode Rejection as in Most Monolithic Amplifiers
  - New Output Stage Allows Use of Large Capacitive Loads (5,000 pF) Without Stability Problems
  - Internal Compensation and Large Differential Input Voltage Capability
- Common Features
  - Low Input Bias Current: 30 pA
  - Low Input Offset Current: 3 pA
  - High Input Impedance: 10^{12} Ω
  - Low Input Noise Current: 0.01 pA/$\sqrt{Hz}$
  - High Common-Mode Rejection Ratio: 100 dB
  - Large DC Voltage Gain: 106 dB
- Uncommon Features
  - Extremely Fast Settling Time to 0.01%:
    - 4 µs for the LFx55 devices
    - 1.5 µs for the LFx56
    - 1.5 µs for the LFx57 (A_V = 5)
  - Fast Slew Rate:
    - 5 V/µs for the LFx55
    - 12 V/µs for the LFx56
    - 50 V/µs for the LFx57 (A_V = 5)
  - Wide Gain Bandwidth:
    - 2.5 MHz for the LFx55 devices
    - 5 MHz for the LFx56
    - 20 MHz for the LFx57 (A_V = 5)
  - Low Input Noise Voltage:
    - 20 nV/$\sqrt{Hz}$ for the LFx55
    - 12 nV/$\sqrt{Hz}$ for the LFx56
    - 12 nV/$\sqrt{Hz}$ for the LFx57 (A_V = 5)

2 Applications

- Precision High-Speed Integrators
- Fast D/A and A/D Converters
- High Impedance Buffers
- Wideband, Low Noise, Low Drift Amplifiers
- Logarithmic Amplifiers
- Photocell Amplifiers
- Sample and Hold Circuits

3 Description
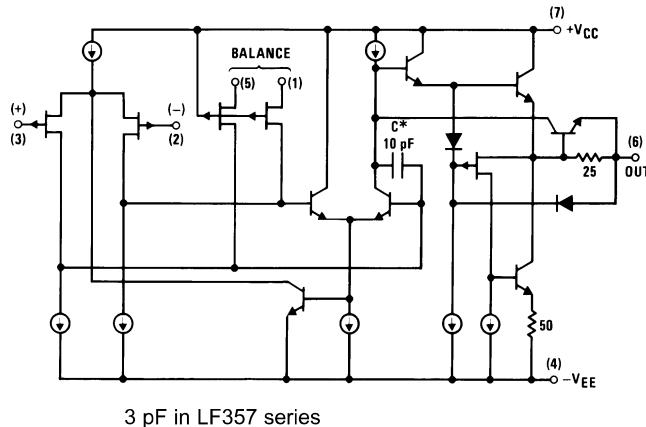
The LFx5x devices are the first monolithic JFET input operational amplifiers to incorporate well-matched, high-voltage JFETs on the same chip with standard bipolar transistors (BI-FET™ Technology). These amplifiers feature low input bias and offset currents/low offset voltage and offset voltage drift, coupled with offset adjust, which does not degrade drift or common-mode rejection. The devices are also designed for high slew rate, wide bandwidth, extremely fast settling time, low voltage and current noise and a low 1/f noise corner.

Device Information[1]

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LFx5x	SOIC (8)	4.90 mm × 3.91 mm
	TO-CAN (8)	9.08 mm × 9.08 mm
	PDIP (8)	9.81 mm × 6.35 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

3 pF in LF357 series

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.
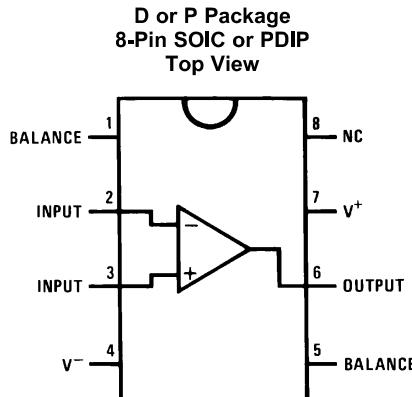
**Changes from Revision C (March 2013) to Revision D**   **Page**

- Added *Pin Configuration and Functions* section, *ESD Ratings* table, *Thermal Information* table, *Feature Description* section, *Device Functional Modes*, *Application and Implementation* section, *Power Supply Recommendations* section, *Layout* section, *Device and Documentation Support* section, and *Mechanical, Packaging, and Orderable Information* section 1
- Removed T_{HIGH} parameter as it is redundant to T_A maximum 4

Changes from Revision B (March 2013) to Revision C   **Page**

- Changed layout of National Data Sheet to TI format 31

5 Pin Configuration and Functions

LMC Package
8-Pin TO-99
Top View

Available per JM38510/11401 or
JM38510/11402

D or P Package
8-Pin SOIC or PDIP
Top View

Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
BALANCE	1, 5	I	Balance for input offset voltage
+INPUT	3	I	Noninverting input
–INPUT	2	I	Inverting input
NC	8	—	No connection
OUTPUT	6	O	Output
V+	7	—	Positive power supply
V–	4	—	Negative power supply

6   Specifications

6.1   Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) [1][2][3]

			MIN	MAX	UNIT
Supply voltage	LF155x, LF256x, LF356B			±22	V
	LF35x			±18	
Differential input voltage	LF15x, LF25x, LF356B			±40	V
	LF35x			±30	
Input voltage[4]	LF15x, LF25x, LF356B			±20	V
	LF35x			±16	
Output short circuit duration			Continuous		—
T_{JMAX}	LMC package	LF15x		150	°C
		LF25x, LF356B, LF35x		115	
	P package	LF25x, LF356B, LF35x		100	
	D package	LF25x, LF356B, LF35x		100	
Soldering information (lead temp.)	TO-99 package	Soldering (10 sec.)		300	°C
	PDIP package	Soldering (10 sec.)		260	
	SOIC package	Vapor phase (60 sec.) LF25x, LF356B, LF35x		215	
		Infrared (15 sec.) LF25x, LF356B, LF35x		220	
Storage temperature, T_{stg}			−65	150	°C

(1)   Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2)   The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{JMAX}, θ_{JA}, and the ambient temperature, T_A. The maximum available power dissipation at any temperature is $P_D = (T_{JMAX} − T_A) / \theta_{JA}$ or the 25°C P_{dMAX}, whichever is less.
(3)   If Military/Aerospace specified devices are required, contact the TI Sales Office/Distributors for availability and specifications.
(4)   Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

6.2   ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001[1][2]	±1000	V

(1)   JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2)   100 pF discharged through 1.5-kΩ resistor

6.3   Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Supply voltage, V_S	LF15x	±15	V_S	±20	V
	LF25x	±15	V_S	±20	
	LF356B	±15	V_S	±20	
	LF35x			±15	
T_A	LF15x	−55	T_A	125	°C
	LF25x	−25	T_A	85	
	LF356B	0	T_A	70	
	LF35x	0	T_A	70	

6.4 Thermal Information

THERMAL METRIC[1]		LF155, LF156, LF355, LF357			LF356	UNIT
		P (PDIP)	D (SOIC)	LMC (TO-99)	P (PDIP)	
		8 PINS	8 PINS	8 PINS	8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	130	195	—	55.2	°C/W
	Still Air	—	—	160	—	
	400 LF/Min Air Flow	—	—	65	—	
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	—	—	23	44.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	—	—	—	32.4	°C/W
ψ_{JT}	Junction-to-top characterization parameter	—	—	—	21.7	°C/W
ψ_{JB}	Junction-to-board characterization parameter	—	—	—	32.3	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, SPRA953.

6.5 AC Electrical Characteristics, $T_A = T_J = 25°C$, $V_S = \pm15$ V

PARAMETER		TEST CONDITIONS			MIN	TYP	MAX	UNIT
SR	Slew Rate	LF15x: $A_V = 1$		LFx55		5		V/µs
				LFx56, LF356B		7.5		
				LFx56, LF356B		12		
		LF357: $A_V = 5$		LFx57		50		
GBW	Gain Bandwidth Product	LFx55				2.5		MHz
		LFx56, LF356B				5		
		LFx57				20		
t_s	Settling Time to 0.01%[1]	LFx55				4		µs
		LFx56, LF356B				1.5		
		LFx57				1.5		
e_n	Equivalent Input Noise Voltage	$R_S = 100\ \Omega$	f = 100 Hz	LFx55		25		nV/√Hz
				LFx56, LF356B		15		
				LFx57		15		
			f = 1000 Hz	LFx55		20		nV/√Hz
				LFx56, LF356B		12		
				LFx57		12		
i_n	Equivalent Input Current Noise	f = 100 Hz		LFx55				pA/√Hz
				LFx56, LF356B		0.01		
				LFx57				
		f = 1000 Hz		LFx55				pA/√Hz
				LFx56, LF356B		0.01		
				LFx57				
C_{IN}	Input Capacitance	LFx55						pF
		LFx56, LF356B				3		
		LFx57						

(1) Settling time is defined here, for a unity gain inverter connection using 2-kΩ resistors for the LF15x. It is the time required for the error voltage (the voltage at the inverting input pin on the amplifier) to settle to within 0.01% of its final value from the time a 10-V step input is applied to the inverter. For the LF357, $A_V = -5$, the feedback resistor from output to input is 2 kΩ and the output step is 10 V (See *Settling Time Test Circuit*).

6.6 DC Electrical Characteristics, $T_A = T_J = 25°C$, $V_S = ±15$ V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply current	LF155		2	4	mA
	LF355		2	4	
	LFx56, LF356B		5	7	
	LF356		5	10	
	LF357		5	10	

6.7 DC Electrical Characteristics

See [1]

PARAMETER		TEST CONDITIONS			MIN	TYP	MAX	UNIT
V_{OS}	Input offset voltage	$R_S = 50$ Ω	$T_A = 25°C$	LF15x, LF25x, LF356B		3	5	mV
				LF35x		3	10	
			Over temperature	LF15x			7	
				LF25x, LF356B			6.5	
				LF35x			13	
$ΔV_{OS}/ΔT$	Average TC of input offset voltage	$R_S = 50$ Ω		LF15x, LF25x, LF356B, LF35x		5		µV/°C
$ΔTC/ΔV_{OS}$	Change in average TC with V_{OS} adjust	$R_S = 50$ Ω [2]		LF15x, LF25x, LF356B, LF35x		0.5		µV/°C per mV
I_{OS}	Input offset current	$T_J = 25°C$ [1] [3]		LF15x, LF25x, LF356B		3	20	pA
				LF35x		3	50	
		$T_J ≤ T_{HIGH}$		LF15x			20	nA
				LF25x, LF356B			1	
				LF35x			2	
I_B	Input bias current	$T_J = 25°C$ [1] [3]		LF15x, LF25x, LF356B		30	100	pA
				LF35x		30	200	
		$T_J ≤ T_{HIGH}$		LF15x			50	nA
				LF25x, LF356B			5	
				LF35x			8	
R_{IN}	Input resistance	$T_J = 25°C$		LF15x, LF25x, LF356B, LF35x		10^{12}		Ω
A_{VOL}	Large signal voltage gain	$V_S = ±15$ V, $V_O = ±10$ V, $R_L = 2$ kΩ	$T_A = 25°C$	LF15x, LF25x, LF356B	50	200		V/mV
				LF35x	25	200		
			Over temperature	LF15x, LF25x, LF356B	25			
				LF35x	15			
V_O	Output voltage swing	$V_S = ±15$ V, $R_L = 10$ kΩ		LF15x, LF25x, LF356B, LF35x	±12	±13		V
		$V_S = ±15$ V, $R_L = 2$ kΩ		LF15x, LF25x, LF356B, LF35x	±10	±12		

(1) Unless otherwise stated, these test conditions apply:

	LF15x	LF25x	LF356B	LF35x
Supply Voltage, V_S	±15 V ≤ V_S ≤ ±20 V	±15 V ≤ V_S ≤ ±20 V	±15 V ≤ V_S ≤ ±20 V	$V_S = ±15$ V
T_A	−55°C ≤ T_A ≤ +125°C	−25°C ≤ T_A ≤ +85°C	0°C ≤ T_A ≤ +70°C	0°C ≤ T_A ≤ +70°C
T_{HIGH}	+125°C	+85°C	+70°C	+70°C

and V_{OS}, I_B and I_{OS} are measured at $V_{CM} = 0$.

(2) The Temperature Coefficient of the adjusted input offset voltage changes only a small amount (0.5 µV/°C typically) for each mV of adjustment from its original unadjusted value. Common-mode rejection and open-loop voltage gain are also unaffected by offset adjustment.

(3) The input bias currents are junction leakage currents which approximately double for every 10°C increase in the junction temperature, T_J. Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, Pd. $T_J = T_A + θ_{JA}$ Pd where $θ_{JA}$ is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

DC Electrical Characteristics (continued)

See [1]

PARAMETER		TEST CONDITIONS			MIN	TYP	MAX	UNIT
V_{CM}	Input common-mode voltage range	$V_S = \pm 15$ V	$V_{CM, High}$	LF15x, LF25x, LF356B	11	15.1		V
				LF35x	10	15.1		
			$V_{CM, Low}$	LF15x, LF25x, LF356B		−12	−11	
				LF35x		−12	−10	
CMRR	Common-mode rejection ratio	LF15x, LF25x, LF356B			85	100		dB
		LF35x			80	100		
PSRR	Supply voltage rejection ratio[4]	LF15x, LF25x, LF356B			85	100		dB
		LF35x			80	100		

(4) Supply Voltage Rejection is measured for both supply magnitudes increasing or decreasing simultaneously, in accordance with common practice.

6.8 Power Dissipation Ratings

			MIN	MAX	UNIT
Power Dissipation at $T_A = 25°C$ [1] [2]	LMC Package (Still Air)	LF15x		560	mW
		LF25x, LF356B, LF35x		400	
	LMC Package (400 LF/Min Air Flow)	LF15x		1200	
		LF25x, LF356B, LF35x		1000	
	P Package	LF25x, LF356B, LF35x		670	
	D Package	LF25x, LF356B, LF35x		380	

(1) The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{JMAX}, θ_{JA}, and the ambient temperature, T_A. The maximum available power dissipation at any temperature is $P_D = (T_{JMAX} - T_A) / \theta_{JA}$ or the 25°C P_{dMAX}, whichever is less.
(2) Maximum power dissipation is defined by the package characteristics. Operating the part near the maximum power dissipation may cause the part to operate outside specified limits.

6.9 Typical Characteristics

6.9.1 Typical DC Performance Characteristics

Curves are for LF155 and LF156 unless otherwise specified.
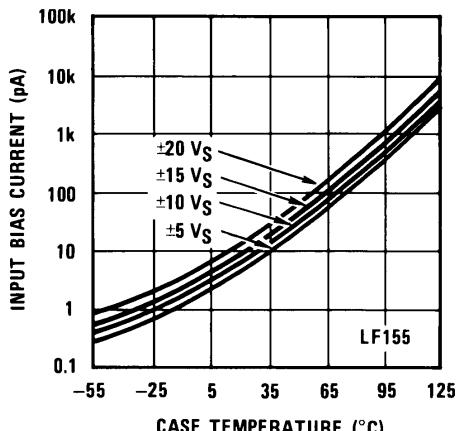
Figure 1. Input Bias Current
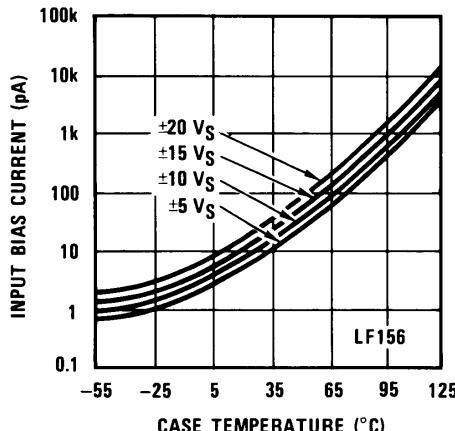
Figure 2. Input Bias Current
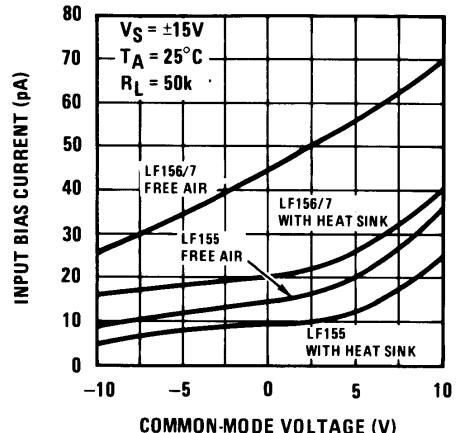
Figure 3. Input Bias Current
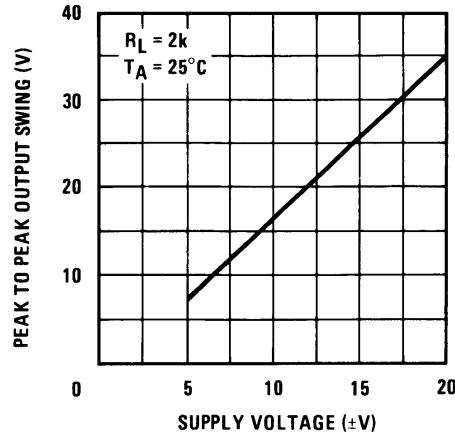
Figure 4. Voltage Swing
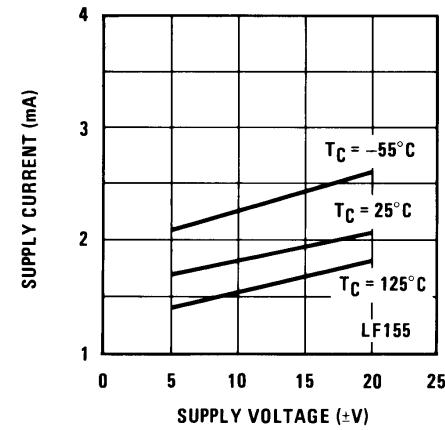
Figure 5. Supply Current
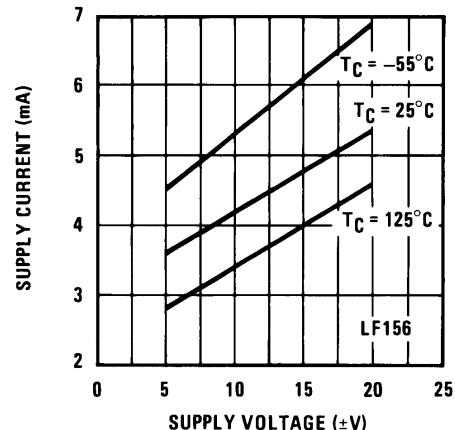
Figure 6. Supply Current

Typical DC Performance Characteristics (continued)

Curves are for LF155 and LF156 unless otherwise specified.
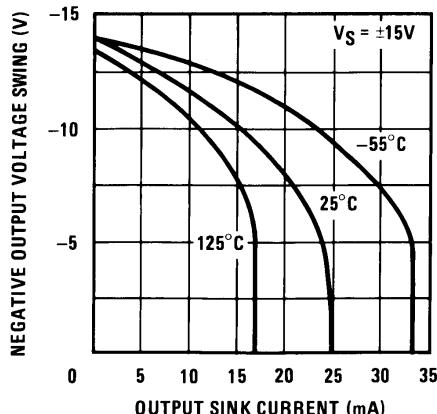
Figure 7. Negative Current Limit
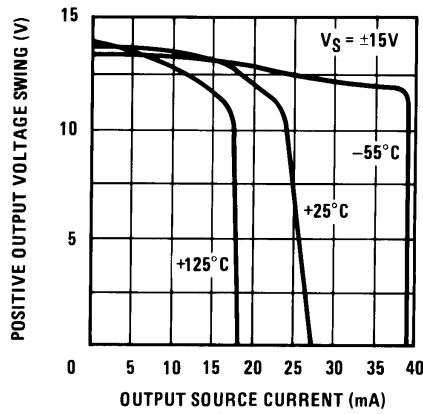
Figure 8. Positive Current Limit
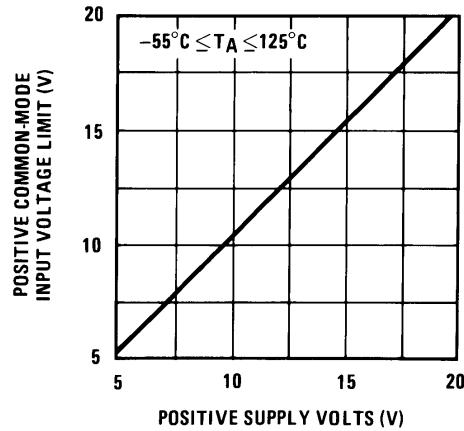
Figure 9. Positive Common-Mode Input Voltage Limit
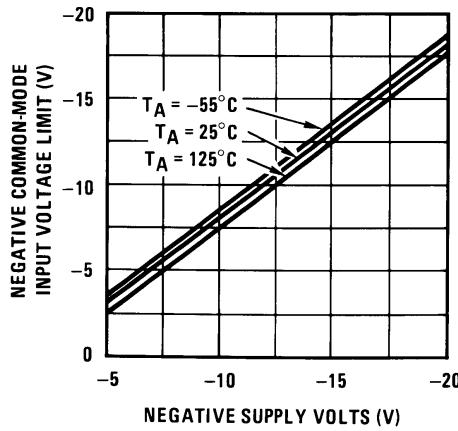
Figure 10. Negative Common-Mode Input Voltage Limit
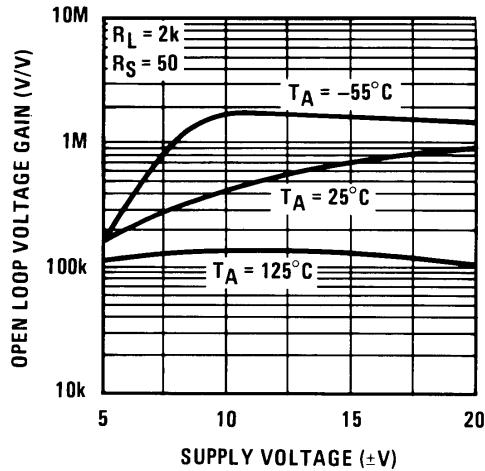
Figure 11. Open-Loop Voltage Gain
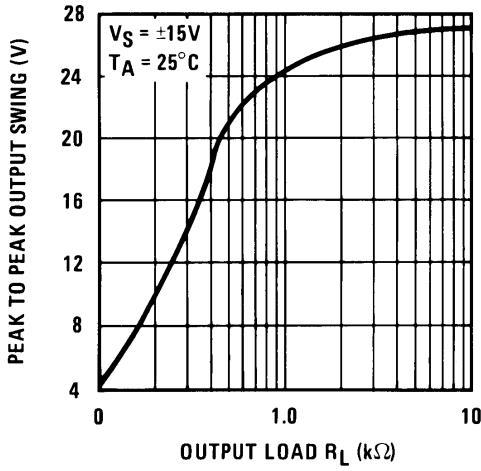
Figure 12. Output Voltage Swing

6.9.2 Typical AC Performance Characteristics
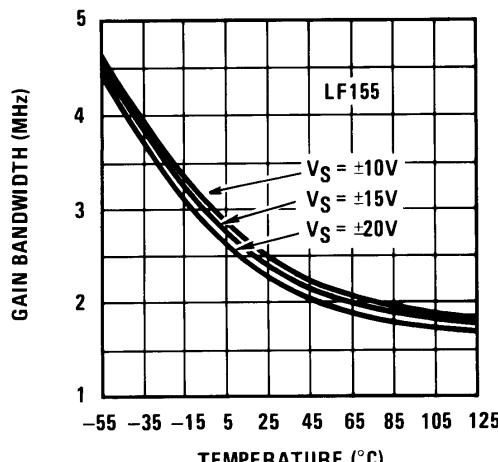
Figure 13. Gain Bandwidth
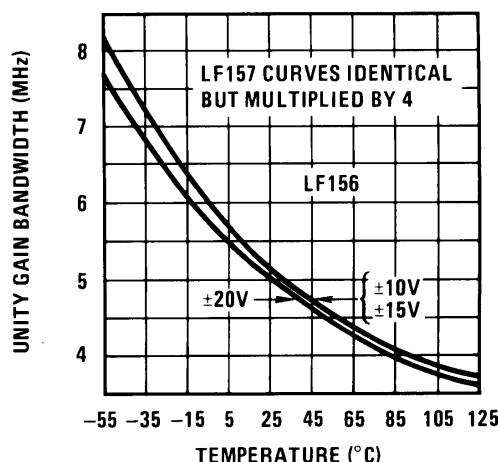
Figure 14. Gain Bandwidth
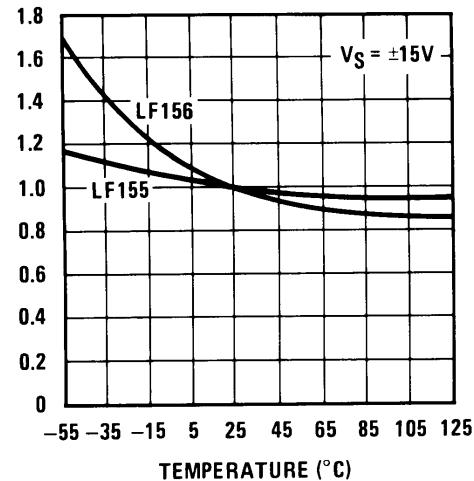
Figure 15. Normalized Slew Rate
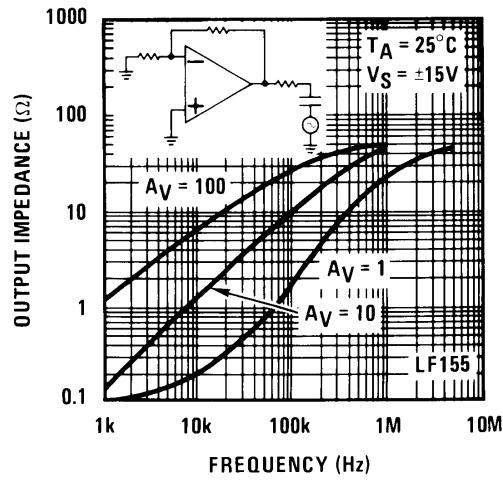
Figure 16. Output Impedance
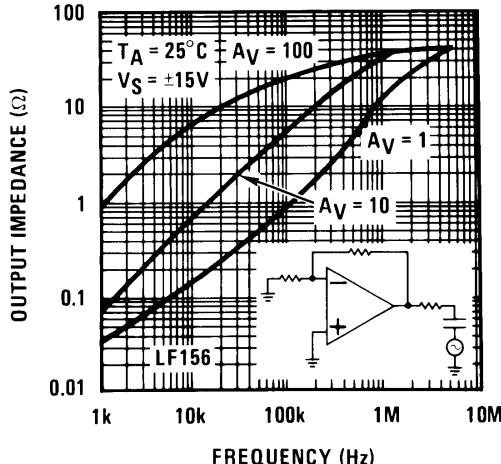
Figure 17. Output Impedance
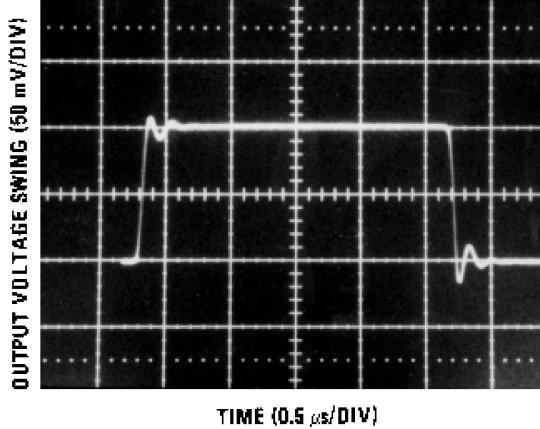
Figure 18. LF155 Small Signal Pulse Response, A_V = +1

Typical AC Performance Characteristics (continued)
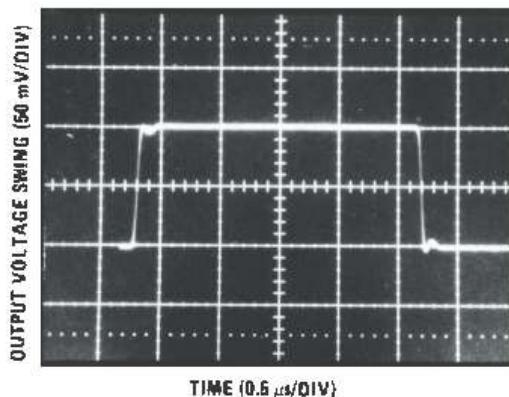
Figure 19. LF156 Small Signal Pulse Response, A_V = +1
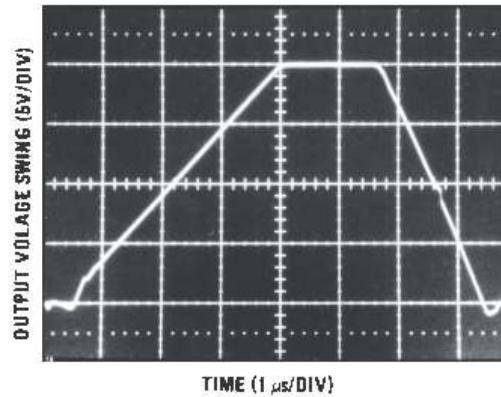
Figure 20. LF155 Large Signal Pulse Response, A_V = +1
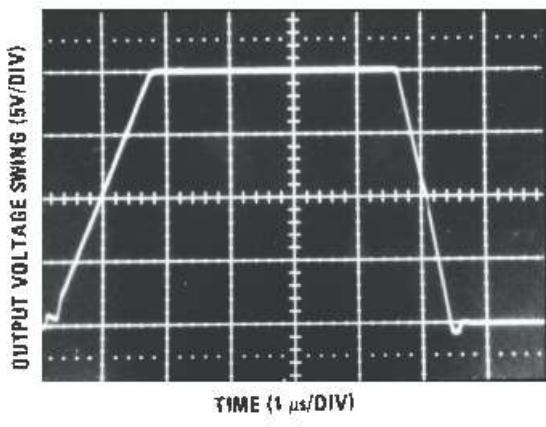
Figure 21. LF156 Large Signal Puls Response, A_V = +1
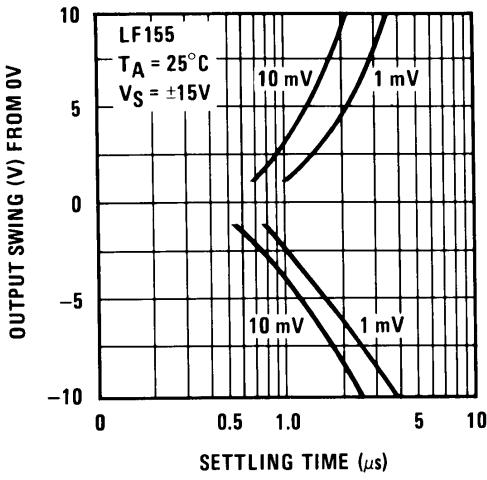
Figure 22. Inverter Settling Time
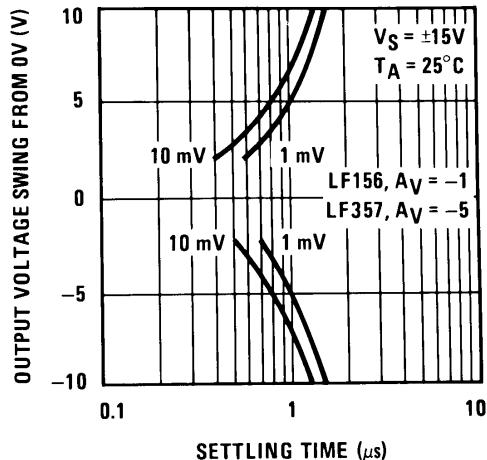
Figure 23. Inverter Settling Time
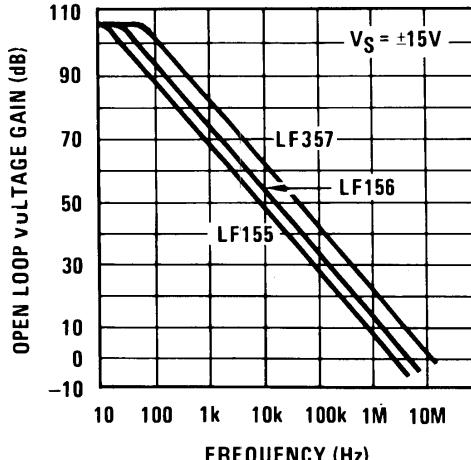
Figure 24. Open-Loop Frequency Response

## Typical AC Performance Characteristics (continued)
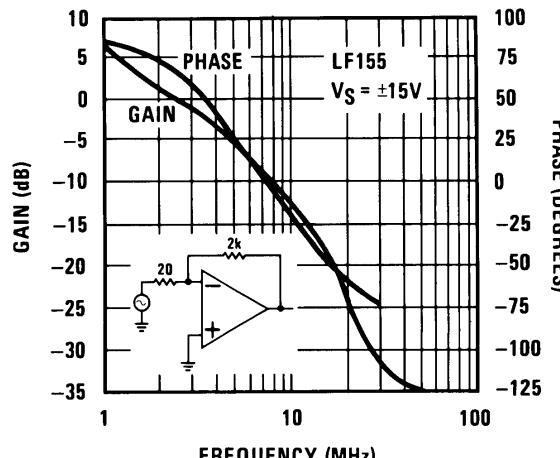

Figure 25. Bode Plot
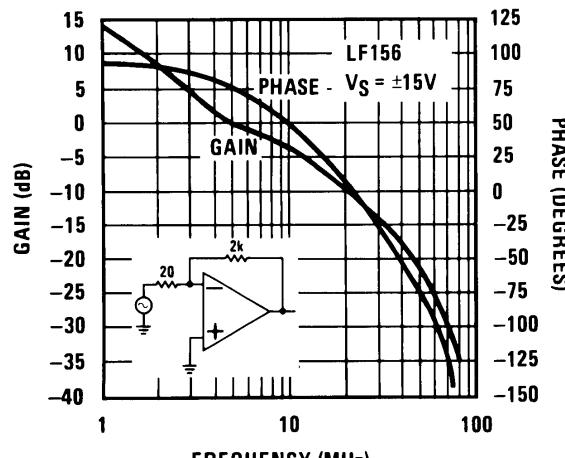
Figure 26. Bode Plot
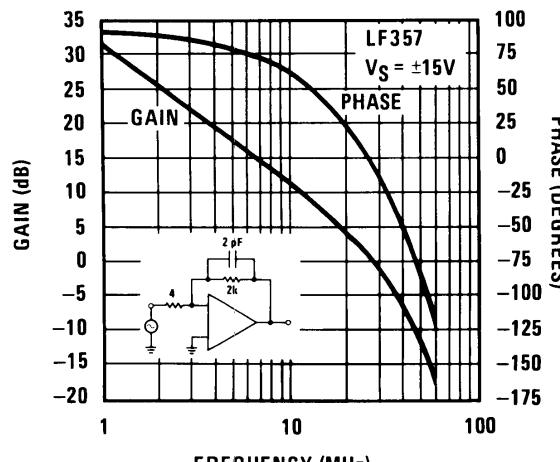
Figure 27. Bode Plot
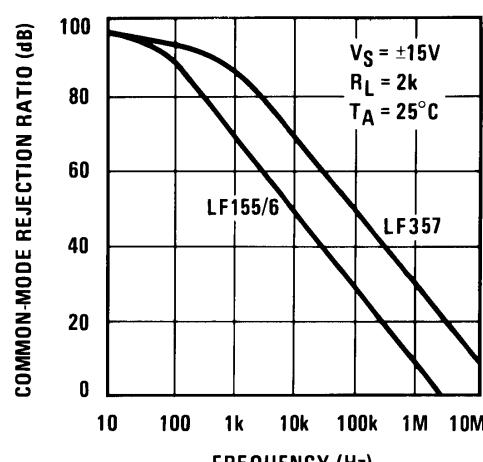
Figure 28. Common-Mode Rejection Ratio
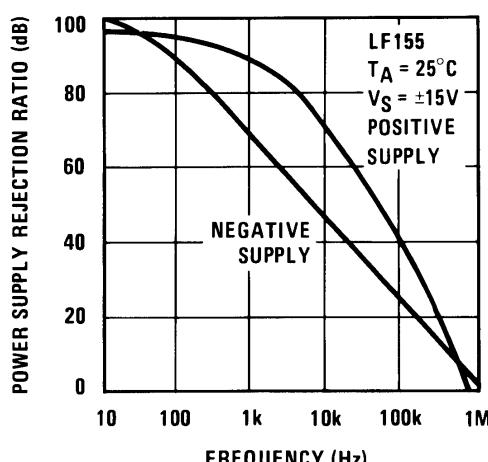
Figure 29. Power Supply Rejection Ratio
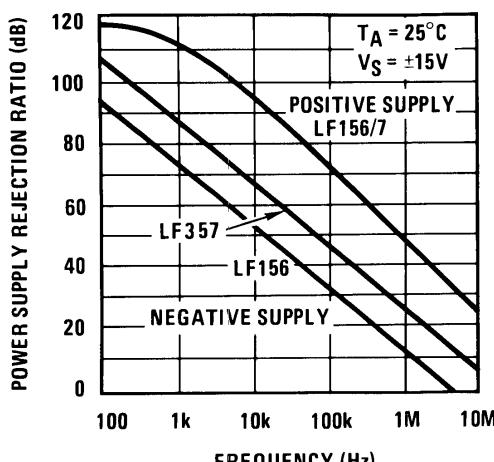
Figure 30. Power Supply Rejection Ratio

LF156 LF256 LF356

Typical AC Performance Characteristics (continued)
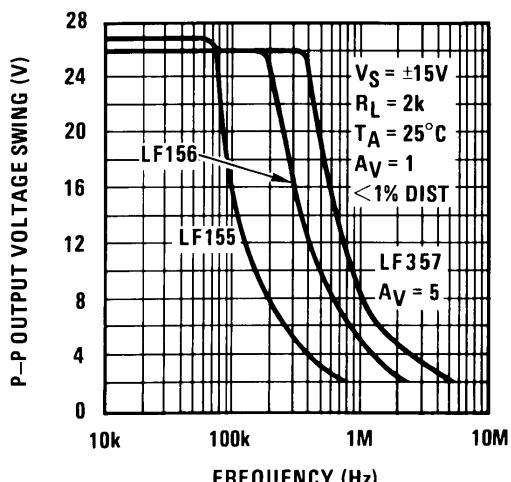
Figure 31. Undistorted Output Voltage Swing
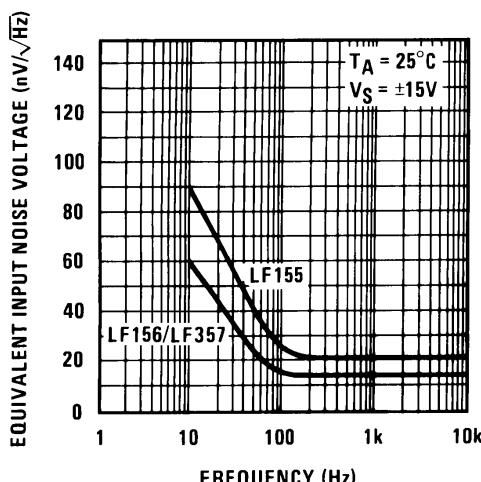

Figure 32. Equivalent Input Noise Voltage
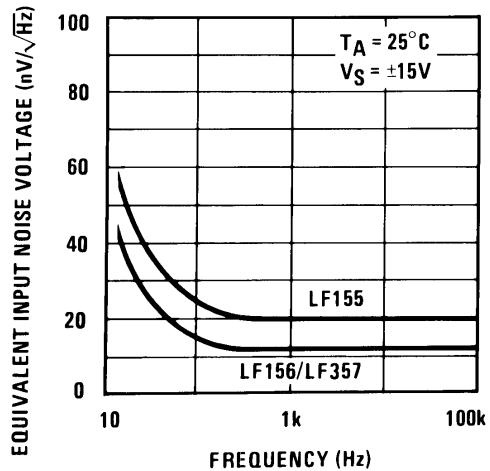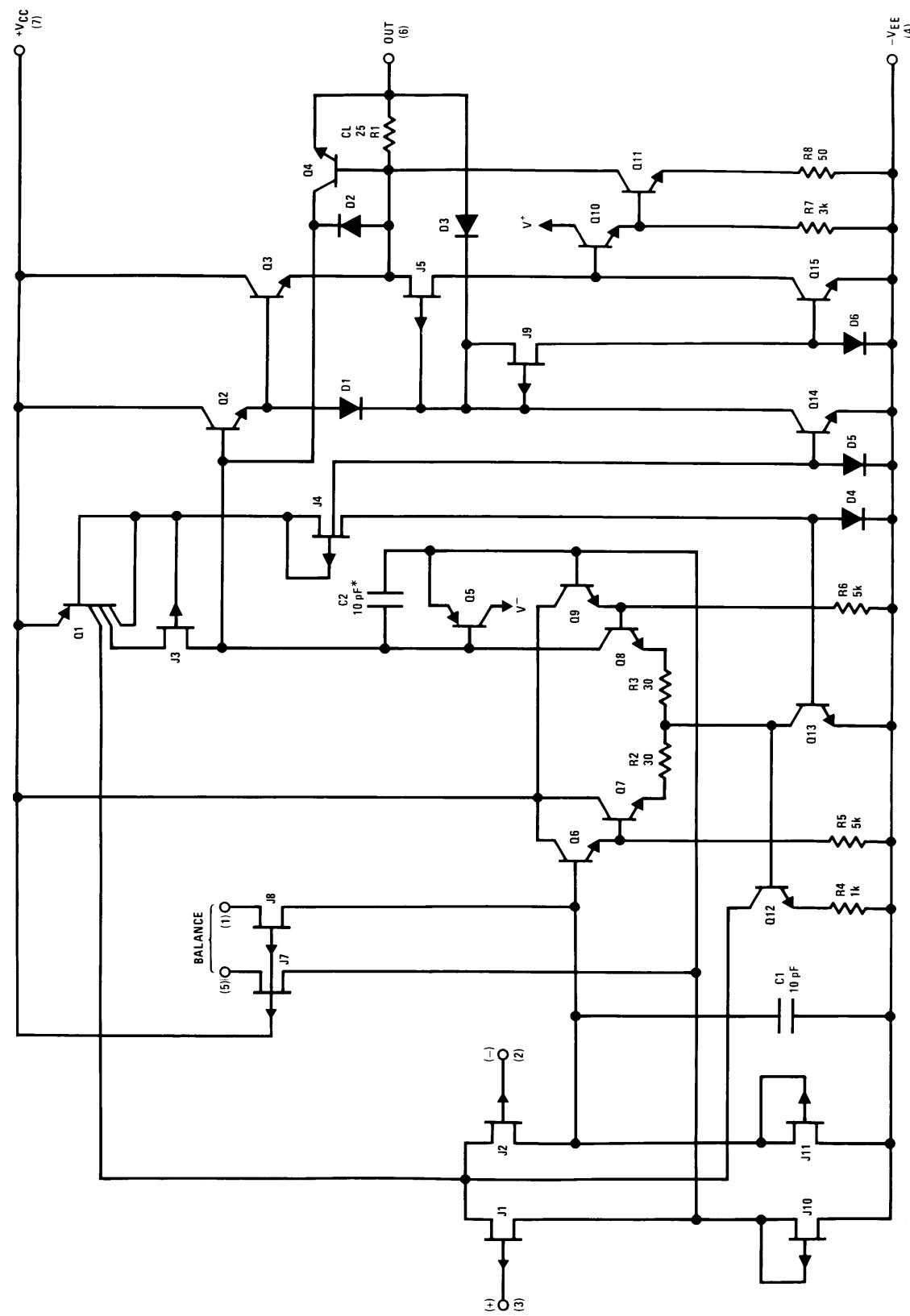
Figure 33. Equivalent Input Noise Voltage (Expanded Scale)

7 Detailed Description

7.1 Overview

These are the first monolithic JFET input operational amplifiers to incorporate well matched, high voltage JFETs on the same chip with standard bipolar transistors (BI-FET Technology). These amplifiers feature low input bias and offset currents, as well as low offset voltage and offset voltage drift, coupled with offset adjust which does not degrade drift or common-mode rejection. These devices can replace expensive hybrid and module FET operational amplifiers. Designed for low voltage and current noise and a low 1/f noise corner, these devices are excellent for low noise applications using either high or low source impedance.

7.2 Functional Block Diagram

Figure 34. Detailed Schematic

*C = 3 pF in LF357 series.

LF156 LF256 LF356

7.3 Feature Description

7.3.1 Large Differential Input Voltage

These are operational amplifiers with JFET input devices. These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

7.3.2 Large Common-Mode Input Voltage

These amplifiers will operate with the common-mode input voltage equal to the positive supply. In fact, the common-mode voltage can exceed the positive supply by approximately 100 mV independent of supply voltage and over the full operating temperature range. The positive supply can therefore be used as a reference on an input as, for example, in a supply current monitor and/or limiter.

7.4 Device Functional Modes

The LFx5x has a single functional mode and operates according to the conditions listed in the *Recommended Operating Conditions*.

8 Application and Implementation

> **NOTE**
>
> Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

These are op amps with JFET input devices. These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

Exceeding the negative common-mode limit on either input will force the output to a high state, potentially causing a reversal of phase to the output. Exceeding the negative common-mode limit on both inputs will force the amplifier output to a high state. In neither case does a latch occur since raising the input back within the common-mode range again puts the input stage and thus the amplifier in a normal operating mode.

Exceeding the positive common-mode limit on a single input will not change the phase of the output however, if both inputs exceed the limit, the output of the amplifier will be forced to a high state.

These amplifiers will operate with the common-mode input voltage equal to the positive supply. In fact, the common-mode voltage can exceed the positive supply by approximately 100 mV independent of supply voltage and over the full operating temperature range. The positive supply can therefore be used as a reference on an input as, for example, in a supply current monitor and/or limiter.

Precautions should be taken to ensure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed backwards in a socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

All of the bias currents in these amplifiers are set by FET current sources. The drain currents for the amplifiers are therefore essentially independent of supply voltage.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize pick-up and maximize the frequency of the feedback pole by minimizing the capacitance from the input to ground.

A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to AC ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3-dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately six times the expected 3-dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

8.2 Typical Application
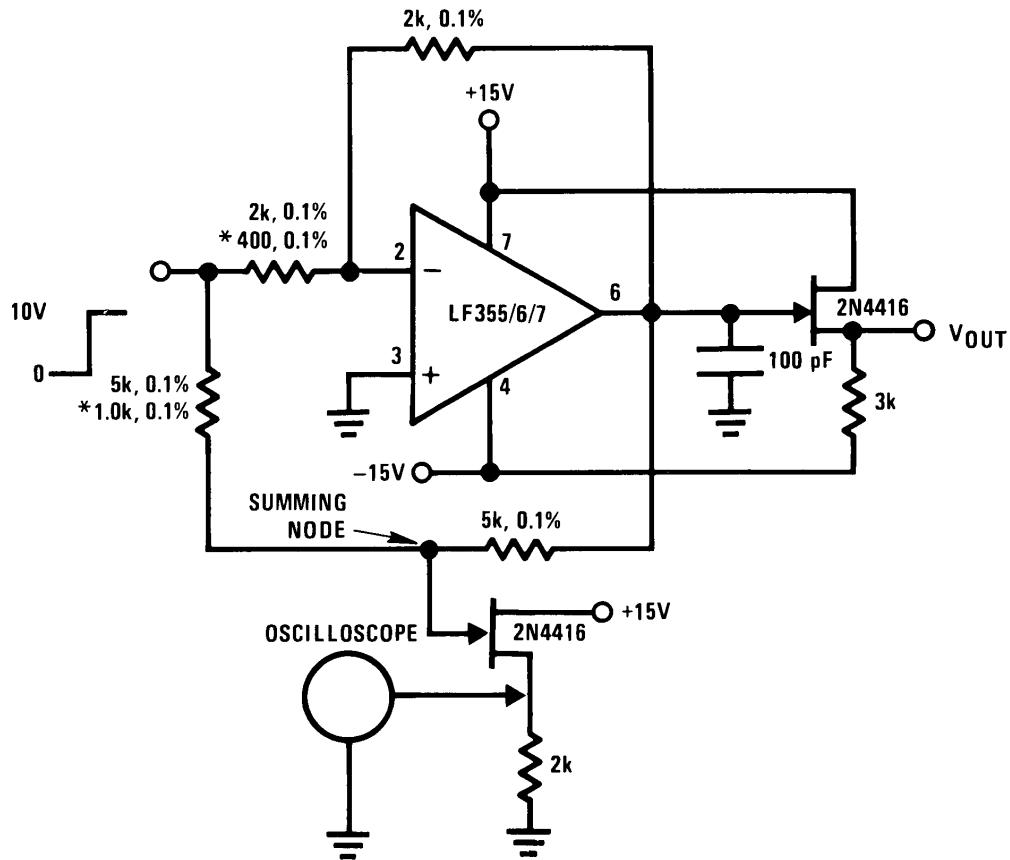
Figure 35. Settling Time Test Circuit

8.2.1 Design Requirements

Settling time is tested with the LF35x connected as unity gain inverter and LF357 connected for $A_V = -5$

8.2.2 Detailed Design Procedure

Connect the circuit components as shown in Figure 35. In particular, use FET to isolate the probe capacitance.

Apply a 10-V step function to the input.

Use an oscilloscope to probe the circuit as shown in Figure 35.

Typical Application (continued)

8.2.3 Application Curves

Large Signal Inverter Output, V_{OUT} (from Settling Time Circuit)
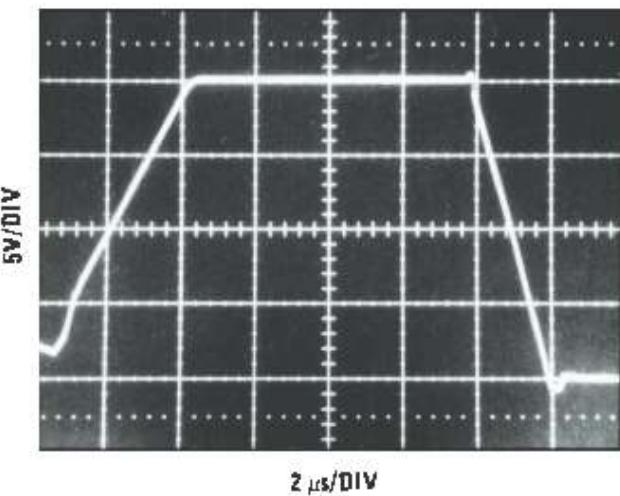
Figure 36. LF355
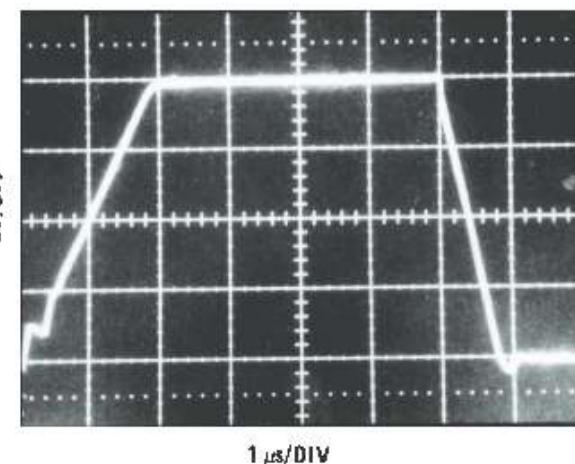

Figure 37. LF356
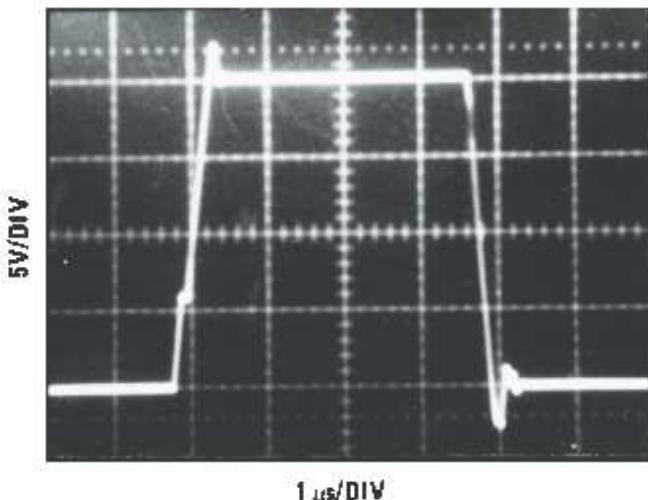
Figure 38. LF357

8.3 System Examples
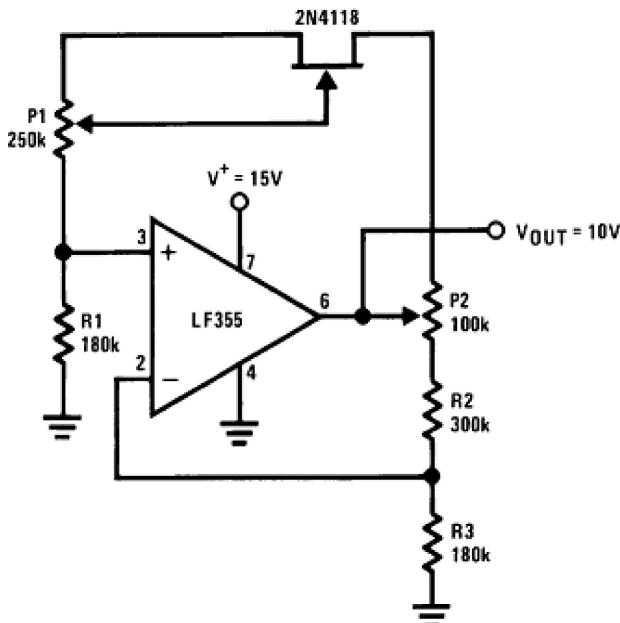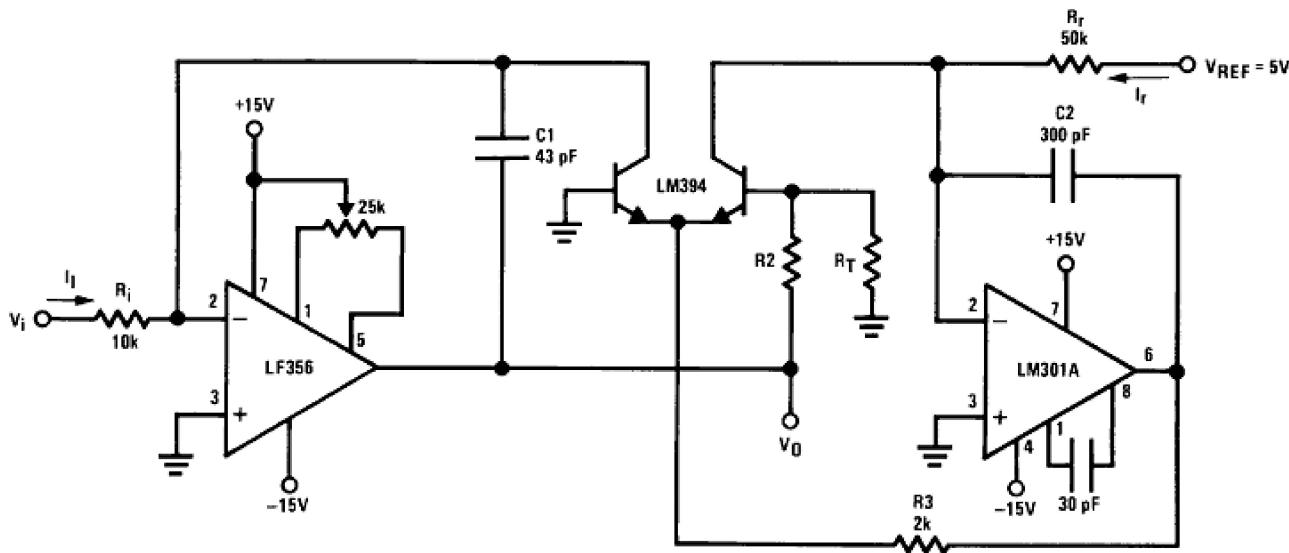
Figure 39. Low Drift Adjustable Voltage Reference

- $\Delta V_{OUT} / \Delta T = \pm 0.002\%/°C$
- All resistors and potentiometers should be wire-wound
- P1: drift adjust
- P2: V_{OUT} adjust
- Use LF155 for
    - Low I_B
    - Low drift
   - Low supply current

System Examples (continued)

Figure 40. Fast Logarithmic Converter

- Dynamic range: 100 μA ≤ I_i ≤ 1 mA (5 decades), $|V_O|$ = 1 V/decade
- Transient response: 3 μs for ΔI_i = 1 decade
- C1, C2, R2, R3: added dynamic compensation
- V_{OS} adjust the LF156 to minimize quiescent error
- R_T: Tel Labs type Q81 + 0.3%/°C

$$|V_{OUT}| = \left[1 + \frac{R2}{R_T} \right] \frac{kT}{q} \text{ in } V_i \left[\frac{R_r}{V_{REF} \; Ri} \right] = \log V_i \; \frac{1}{R_i I_r} \quad R2 = 15.7k, \; R_T = 1k, \; 0.3\%/°C \text{ (for temperature compensation)}$$

(1)

## System Examples (continued)
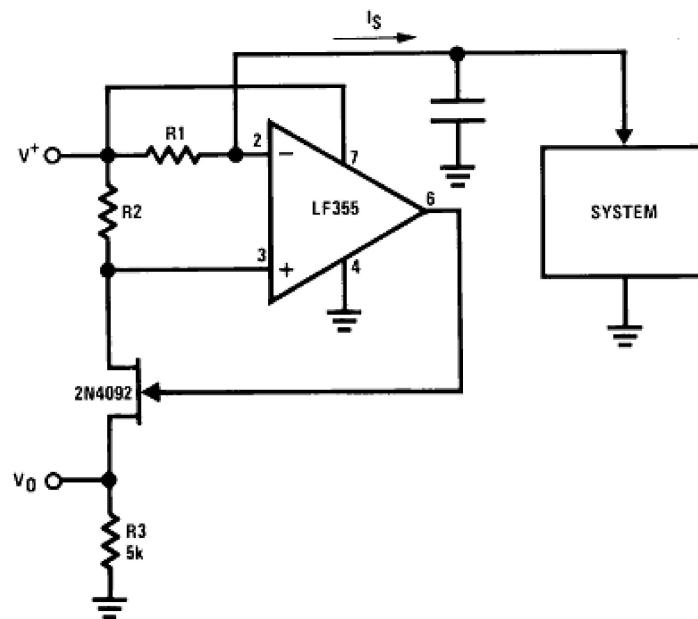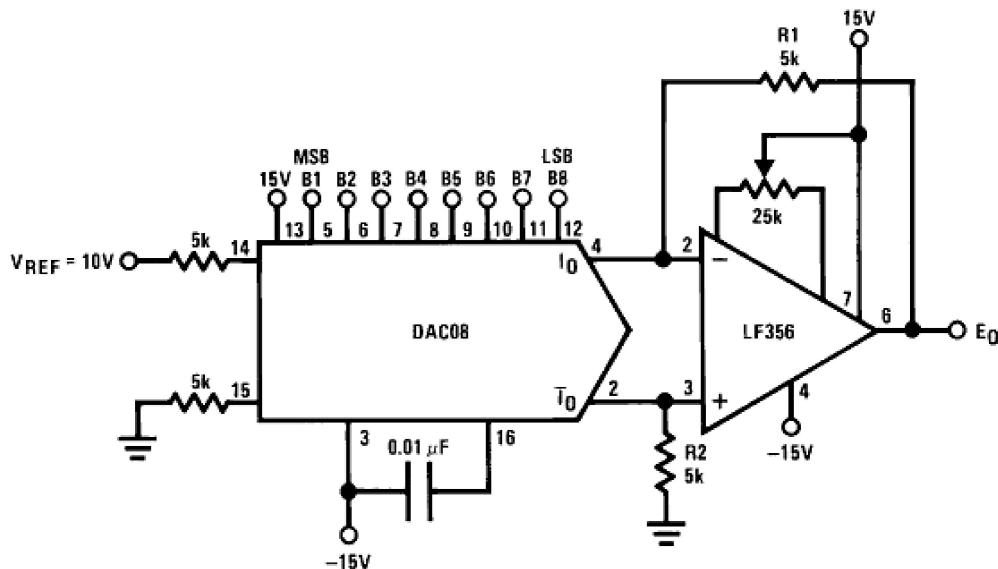
Figure 41. Precision Current Monitor

- V_O = 5 R1/R2 (V/mA of I_S)
- R1, R2, R3: 0.1% resistors
- Use LF155 for
  - Common-mode range to supply range
  - Low I_B
  - Low V_{OS}
 - Low Supply Current

System Examples (continued)
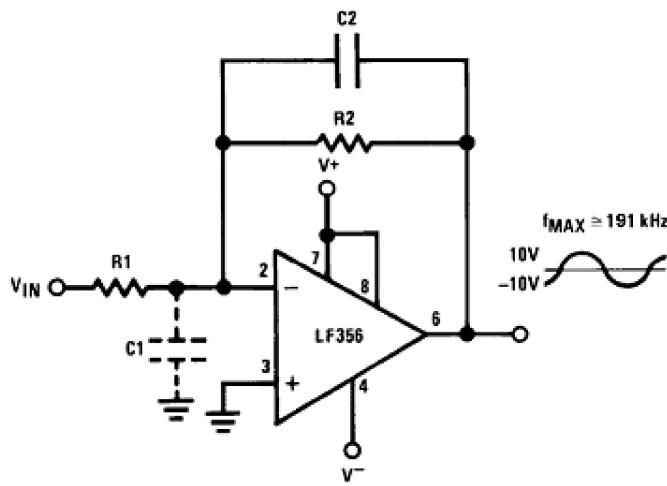
Figure 42. 8-Bit D/A Converter With Symmetrical Offset Binary Operation

- R1, R2 should be matched within ±0.05%
- Full-scale response time: 3 µs

Table 1. Bit Illustration of the 8-Bit D/A Converter

| E_O	B1	B2	B3	B4	B5	B6	B7	B8	COMMENTS
+9.920	1	1	1	1	1	1	1	1	Positive Full-Scale
+0.040	1	0	0	0	0	0	0	0	(+) Zero-Scale
−0.040	0	1	1	1	1	1	1	1	(−) Zero-Scale
−9.920	0	0	0	0	0	0	0	0	Negative Full-Scale

Figure 43. Wide BW Low Noise, Low Drift Amplifier

- Power BW: $f_{MAX} = \dfrac{S_r}{2\pi V_P} \cong 191\,kHz$

(2)

Parasitic input capacitance C1 ≃ (3 pF for LF155, LF156 and LF357 plus any additional layout capacitance) interacts with feedback elements and creates undesirable high frequency pole. To compensate add C2 such that: R2 C2 ≃ R1 C1.
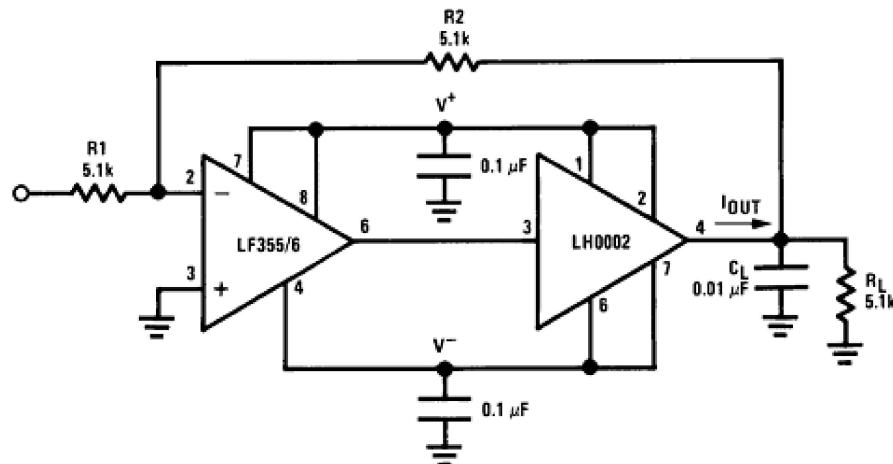

Figure 44. Boosting the LF156 With a Current Amplifier

- $I_{OUT(MAX)} \simeq 150$ mA (will drive $R_L \geq 100\ \Omega$)
  - $\dfrac{\Delta V_{OUT}}{\Delta T} = \dfrac{0.15}{10^{-2}}$ V/μs (with C_L shown)

(3)

- No additional phase shift added by the current amplifier
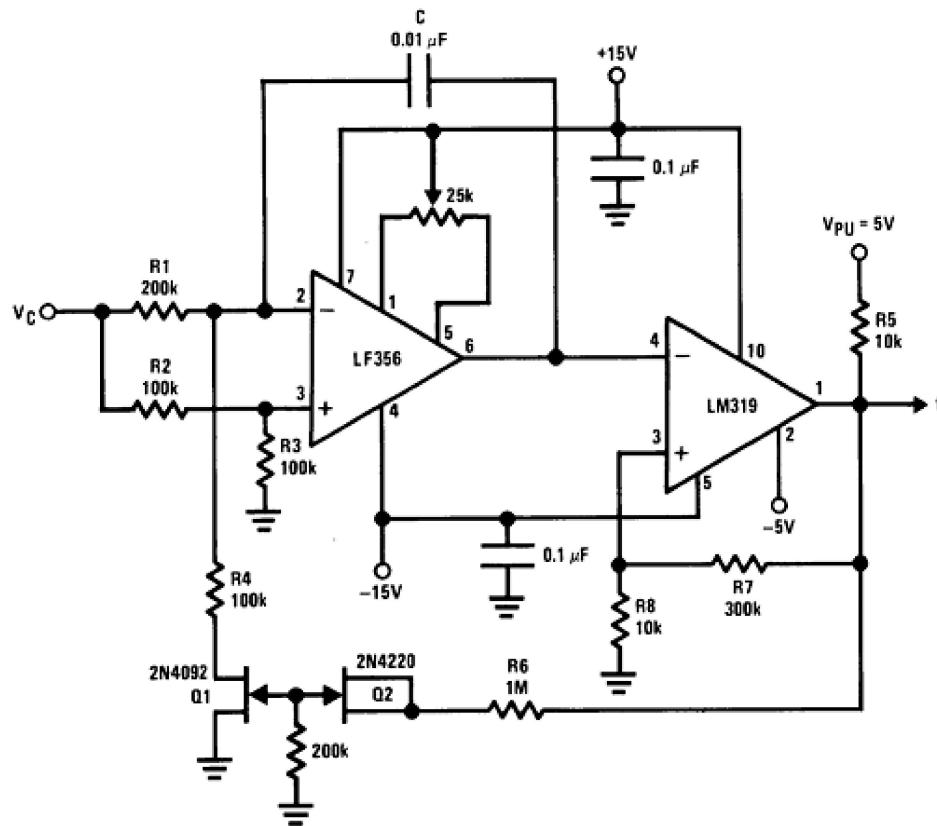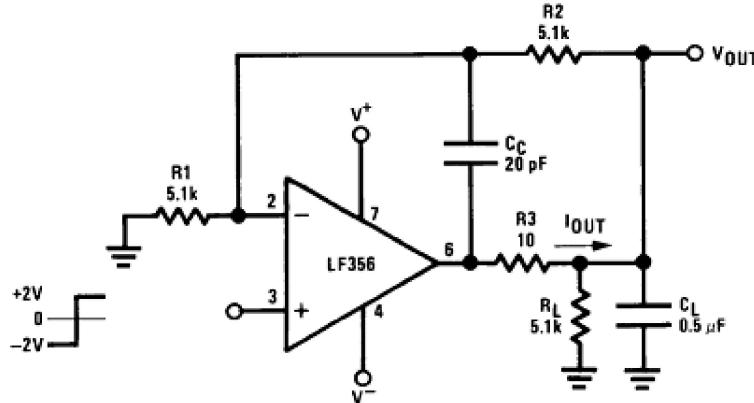
**Figure 45. Decades VCO**

R1, R4 matched. Linearity 0.1% over 2 decades.
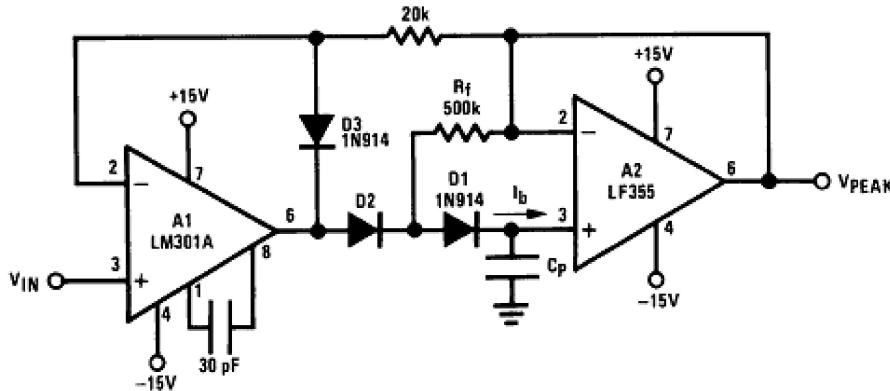
$$f = \frac{V_C \, (R8 + R7)}{(8 \, V_{PU} \, R8 \, R1) \, C'} \quad 0 \leq V_C \leq 30V, \; 10\,Hz \leq f \leq 10\,kHz \tag{4}$$

Figure 46. Isolating Large Capacitive Loads
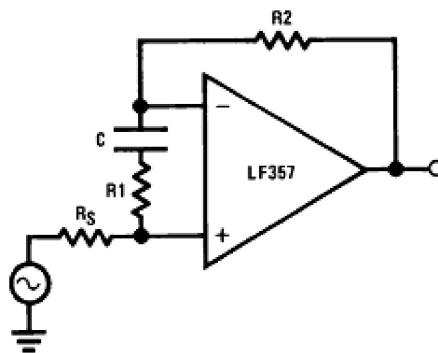
- Overshoot 6%
- t_s 10 µs
- When driving large C_L, the V_{OUT} slew rate determined by C_L and $I_{OUT(MAX)}$:

$$\frac{\Delta V_{OUT}}{\Delta T} = \frac{I_{OUT}}{C_L} \cong \frac{0.02}{0.5}\, V/\mu s = 0.04\, V/\mu s \; (\text{with } C_L \text{ shown}) \tag{5}$$

Figure 47. Low Drift Peak Detector

- By adding D1 and R_f, $V_{D1} = 0$ during hold mode. Leakage of D2 provided by feedback path through R_f.
- Leakage of circuit is essentially I_b (LF155, LF156) plus capacitor leakage of Cp.
- Diode D3 clamps V_{OUT} (A1) to $V_{IN} - V_{D3}$ to improve speed and to limit reverse bias of D2.
- Maximum input frequency should be $\ll \frac{1}{2}\pi R_f C_{D2}$ where C_{D2} is the shunt capacitance of D2.

Figure 48. Noninverting Unity Gain Operation for LF157
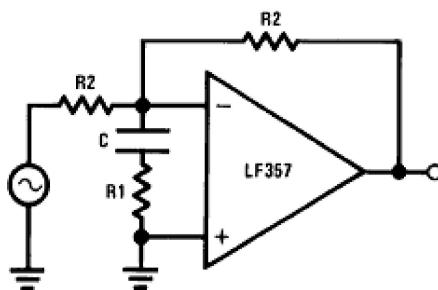
$$R1C \geq \frac{1}{(2\pi)\,(5\text{ MHz})}$$

$$R1 = \frac{R2 + R_S}{4}$$

$$A_{V(DC)} = 1$$

$$f_{-3\text{ dB}} \approx 5\text{ MHz}$$

(6)

Figure 49. Inverting Unity Gain for LF157
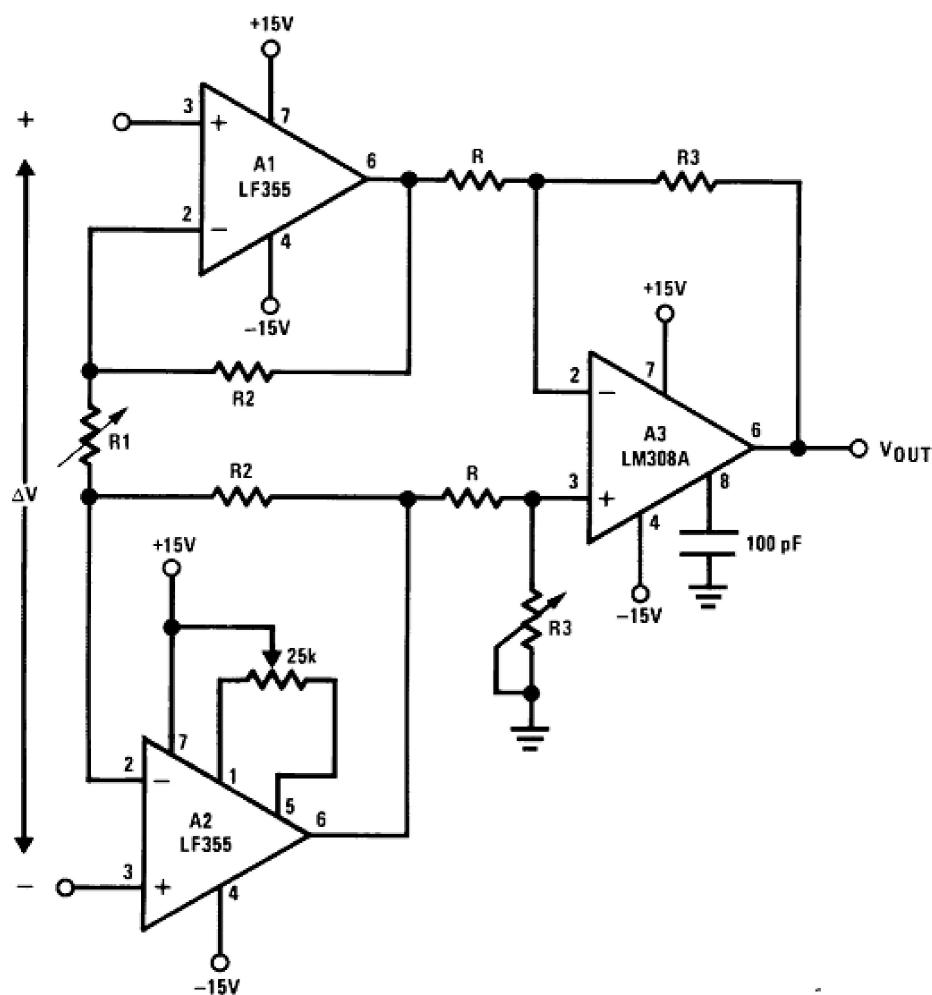
$$R1C \geq \frac{1}{(2\pi)\,(5\text{ MHz})}$$

$$R1 = \frac{R2}{4}$$

$$A_{V(DC)} = -1$$

$$f_{-3\text{ dB}} \approx 5\text{ MHz}$$

(7)

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Figure 50. High Impedance, Low Drift Instrumentation Amplifier

- System V_{OS} adjusted via A2 V_{OS} adjust
- Trim R3 to boost up CMRR to 120 dB. Instrumentation amplifier resistor array recommended for best accuracy and lowest drift

$$\bullet\; V_{OUT} = \frac{R3}{R}\left[\frac{2R2}{R1} + 1\right]\Delta V, \; V^- + 2V \leq V_{IN} \text{ common-mode} \leq V^+$$

(8)

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LF156 LF256 LF356
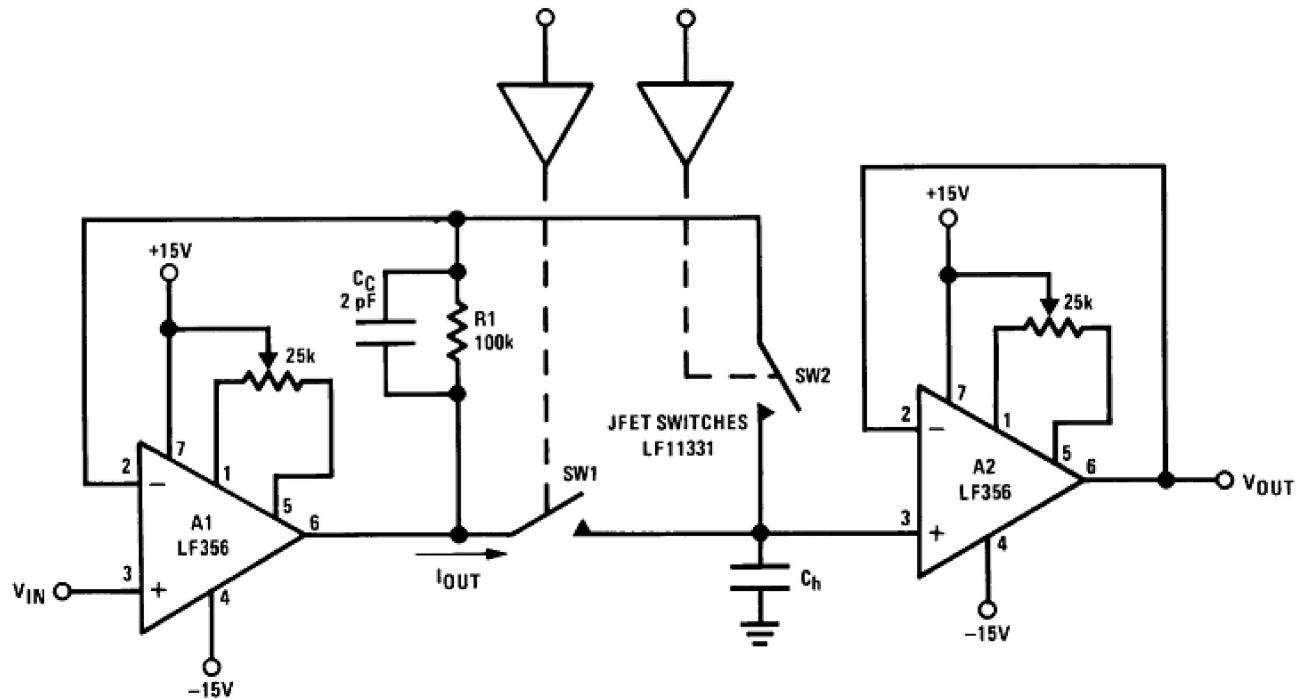
Figure 51. Fast Sample and Hold
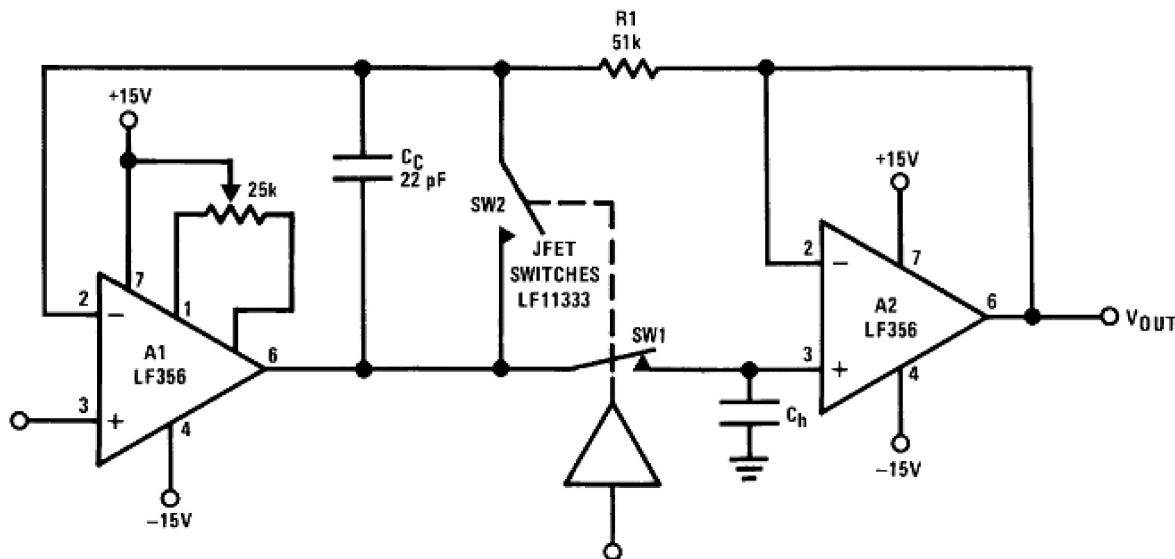
- Both amplifiers (A1, A2) have feedback loops individually closed with stable responses (overshoot negligible)
- Acquisition time T_A, estimated by:

$$T_A \cong \left[\frac{2R_{ON}, V_{IN}, C_h}{S_r} \right] \, 1/2 \text{ provided that:}$$

$$V_{IN} < 2\pi S_r R_{ON} C_h \text{ and } T_A > \frac{V_{IN} C_h}{I_{OUT(MAX)}}, \, R_{ON} \text{ is of SW1}$$

$$\text{If inequality not satisfied: } T_A \cong \frac{V_{IN} C_h}{20 \, mA}$$

(9)

- LF156 develops full S_r output capability for $V_{IN} \geq 1$ V
- Addition of SW2 improves accuracy by putting the voltage drop across SW1 inside the feedback loop
- Overall accuracy of system determined by the accuracy of both amplifiers, A1 and A2

Figure 52. High Accuracy Sample and Hold

- By closing the loop through A2, the V_{OUT} accuracy will be determined uniquely by A1.
  - No V_{OS} adjust required for A2.
- T_A can be estimated by same considerations as previously but, because of the added
  - propagation delay in the feedback loop (A2) the overshoot is not negligible.
- Overall system slower than fast sample and hold
- R1, C_C: additional compensation
- Use LF156 for
 - Fast settling time
  - Low V_{OS}
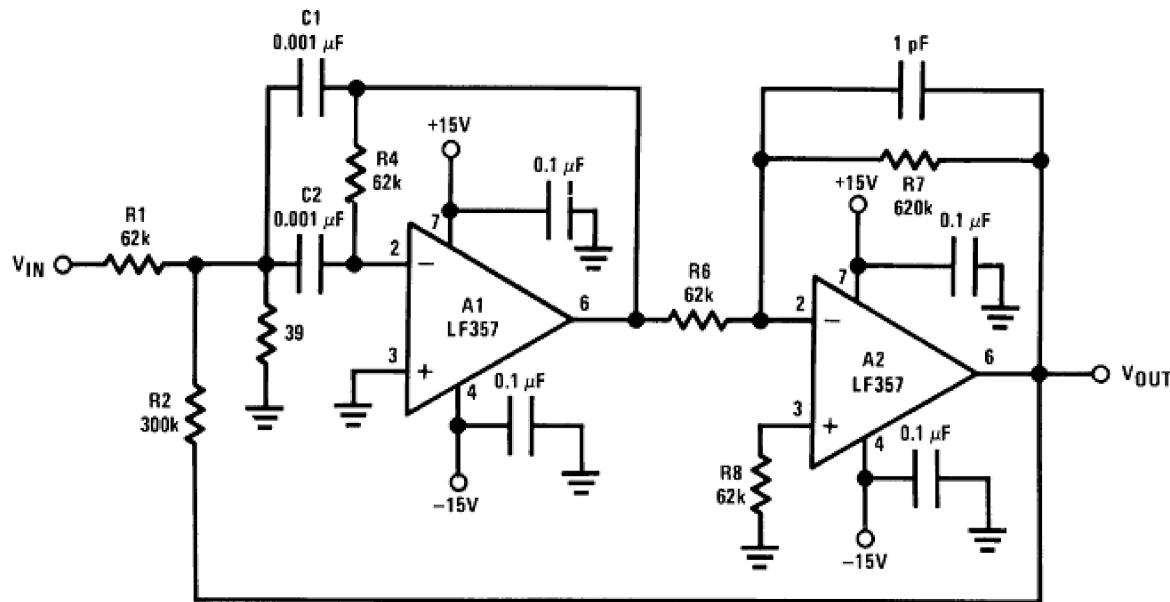
Figure 53. High Q Band Pass Filter

- By adding positive feedback (R2)
- Q increases to 40
- f_{BP} = 100 kHz
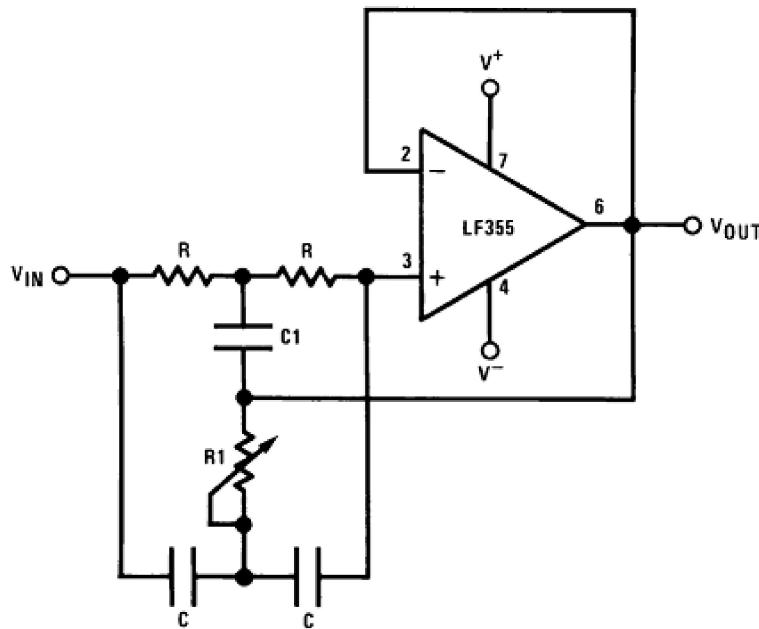
$$\frac{V_{OUT}}{V_{IN}} = 10\sqrt{Q}$$

(10)
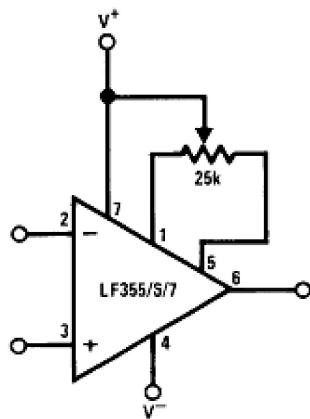
- Clean layout recommended
- Response to a 1-$V_{p\text{-}p}$ tone burst: 300 µs
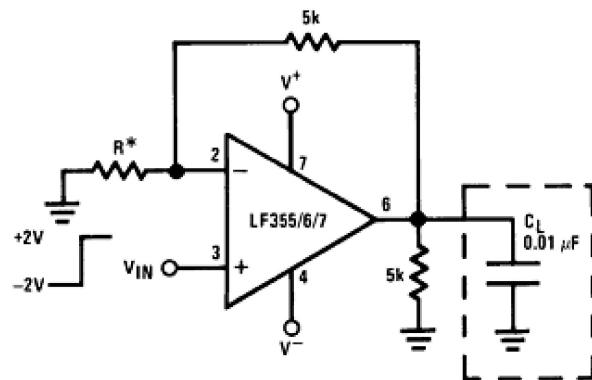
Figure 54. High Q Notch Filter

- $2R1 = R = 10\ M\Omega$
  - $2C = C1 = 300\ pF$
- Capacitors should be matched to obtain high Q
- $f_{NOTCH} = 120\ Hz$, notch $= -55\ dB$, $Q > 100$
- Use LF155 for
 - Low I_B
  - Low supply current
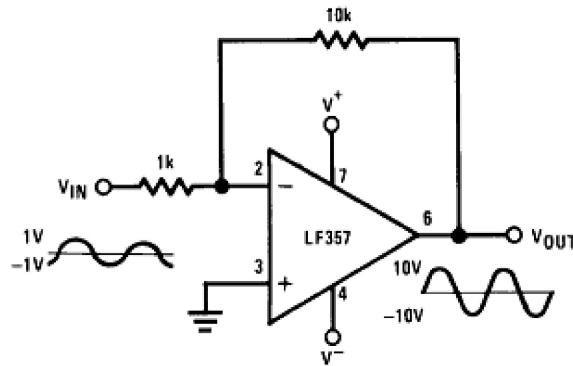
Figure 55. V_{OS} Adjustment

- V_{OS} is adjusted with a 25-k potentiometer
- The potentiometer wiper is connected to V^+
- For potentiometers with temperature coefficient of 100 ppm/°C or less the additional drift with adjust is $\approx 0.5\ \mu V/°C/mV$ of adjustment
- Typical overall drift: 5 $\mu V/°C$ ±(0.5 $\mu V/°C/mV$ of adj.)

Figure 56. Driving Capacitive Loads

- *LF15x R = 5k, LF357 R = 1.25 k
- Due to a unique output stage design, these amplifiers have the ability to drive large capacitive loads and still maintain stability. $C_{L(MAX)} \simeq 0.01\ \mu F$.
- Overshoot ≤ 20%, Settling time (t_s) $\simeq$ 5 μs

**Figure 57. LF357 - A Large Power BW Amplifier**

For distortion ≤ 1% and a 20 Vp-p V_{OUT} swing, power bandwidth is: 500 kHz.

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9 Power Supply Recommendations

See the *Recommended Operating Conditions* for the minimum and maximum values for the supply input voltage and operating junction temperature.
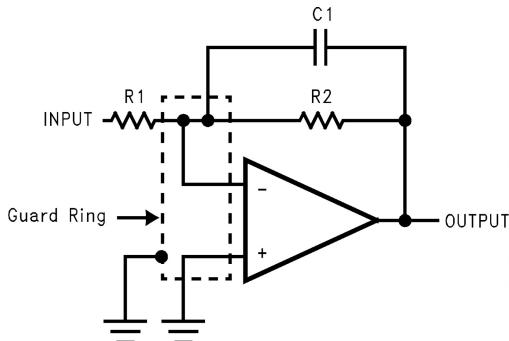
10 Layout

10.1 Layout Guidelines
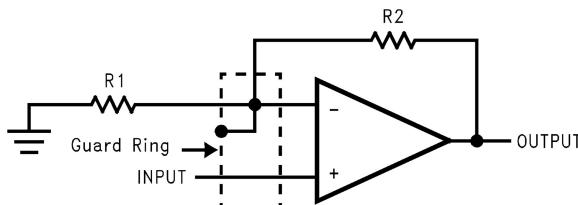
10.1.1 Printed-Circuit-Board Layout For High-Impedance Work

It is generally recognized that any circuit which must operate with less than 1000 pA of leakage current requires special layout of the PCB. When one wishes to take advantage of the low input bias current of the LFx5x, typically less than 30 pA, it is essential to have an excellent layout. Fortunately, the techniques of obtaining low leakages are quite simple. First, the user must not ignore the surface leakage of the PCB, even though it may sometimes appear acceptably low, because under conditions of high humidity or dust or contamination, the surface leakage will be appreciable.

To minimize the effect of any surface leakage, lay out a ring of foil completely surrounding the inputs of the LFx5x and the terminals of capacitors, diodes, conductors, resistors, relay terminals, and so forth, connected to the inputs of the op amp, as in Figure 62. To have a significant effect, guard rings must be placed on both the top and bottom of the PCB. This PC foil must then be connected to a voltage that is at the same voltage as the amplifier inputs, because no leakage current can flow between two points at the same potential. For example, a PCB trace-to-pad resistance of 10 TΩ, which is normally considered a very large resistance, could leak 5 pA if the trace were a 5-V bus adjacent to the pad of the input. If a guard ring is used and held close to the potential of the amplifier inputs, it will significantly reduce this leakage current.


Figure 58. Inverting Amplifier

Figure 59. Noninverting Amplifier

Layout Guidelines (continued)
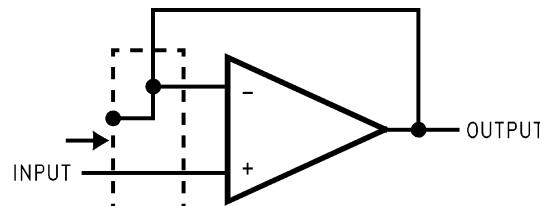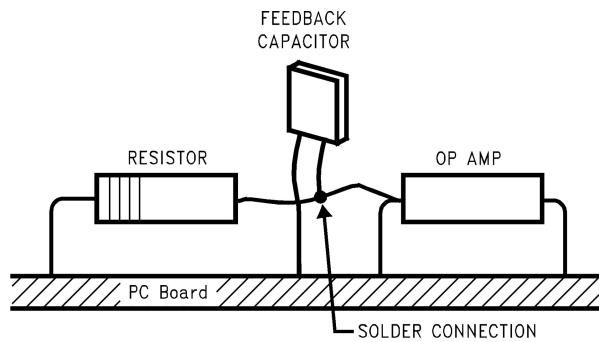
Figure 60. Typical Connections Of Guard Rings

The designer should be aware that when it is inappropriate to lay out a PCB for the sake of just a few circuits, there is another technique which is even better than a guard ring on a PCB: Do not insert the input pin of the amplifier into the board at all, but bend it up in the air and use only air as an insulator. Air is an excellent insulator. In this case you may have to forego some of the advantages of PCB construction, but the advantages are sometimes well worth the effort of using point-to-point up-in-the-air wiring. See Figure 61.

(Input pins are lifted out of PCB and soldered directly to components. All other pins connected to PCB).

Figure 61. Air Wiring

Another potential source of leakage that might be overlooked is the device package. When the LFx5x is manufactured, the device is always handled with conductive finger cots. This is to assure that salts and skin oils do not cause leakage paths on the surface of the package. We recommend that these same precautions be adhered to, during all phases of inspection, test and assembly.

10.2 Layout Example
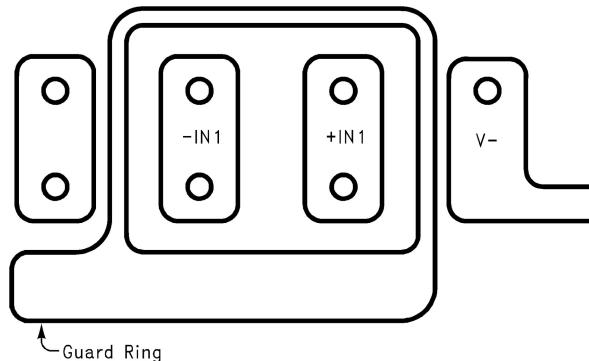
**Figure 62. Examples Of Guard
Ring In PCB Layout**

11   Device and Documentation Support

11.1   Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 2. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
LF156	Click here	Click here	Click here	Click here	Click here
LF256	Click here	Click here	Click here	Click here	Click here
LF356	Click here	Click here	Click here	Click here	Click here

11.2   Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.3   Trademarks

BI-FET, E2E are trademarks of Texas Instruments.
All other trademarks are the property of their respective owners.

11.4   Electrostatic Discharge Caution

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.5   Glossary

SLYZ022 — *TI Glossary*.
    This glossary lists and explains terms, acronyms, and definitions.

12   Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.