

### LINEAR INTEGRATED CIRCUITS

#### DESCRIPTION

The NE561B Phase Locked Loop (PLL) is a monolithic signal conditioner, and demodulator system comprising a VCO, Phase Comparator, Amplifier and Low Pass Filter, interconnected as shown in the accompanying block diagram. The center frequency of the PLL is determined by the free running frequency ( $f_0$ ) of the VCO. This VCO frequency is set by an external capacitor and can be fine tuned by an optional Potentiometer. The low pass filter, which determines the capture characteristics of the loop is formed by the two capacitors and two resistors at the Phase Comparator output.

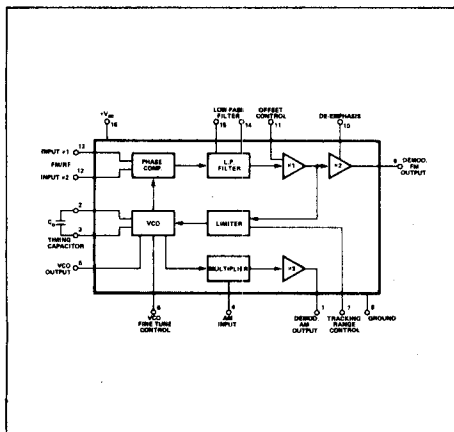
The PLL system has a set of self biased inputs which can be utilized in either a differential or single ended mode. The VCO output is available for signal conditioning, frequency synchronization, multiplication and division applications. Terminals are provided for optional external control of the tracking range, VCO frequency, and output DC level. An analog multiplier block is incorporated into the PLL system to provide frequency selective synchronous AM detection capability.

The monolithic signal conditioner-demodulator system is useful over a wide range of frequencies from less than 1 Hz to more than 15 MHz with an adjustable tracking range of  $\pm 1\%$  to  $\pm 15\%$ .

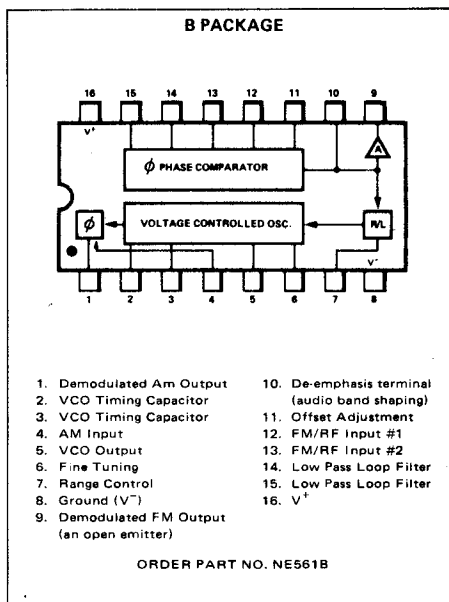
#### FEATURES

- FM DEMODULATION WITHOUT TUNED CIRCUITS
- SYNCHRONOUS AM DETECTION
- NARROW BAND PASS TO  $\pm 1\%$
- EXACT FREQUENCY DUPLICATION IN HIGH NOISE ENVIRONMENT
- ADJUSTABLE TRACKING RANGE
- WIDE TRACKING RANGE  $\pm 15\%$
- HIGH LINEARITY - 1% DISTORTION MAX
- FREQUENCY MULTIPLICATION AND DIVISION THROUGH HARMONIC LOCKING

#### BLOCK DIAGRAM



#### PIN CONFIGURATION



#### ABSOLUTE MAXIMUM RATINGS

Maximum Operating Voltage	26V
Input Voltage	1V RMS
Storage Temperature	-65°C to 150°C
Operating Temperature	0°C to 70°C
Power Dissipation	300mW

Limiting values above which serviceability may be impaired

#### APPLICATIONS

- TONE DECODERS
- AM-FM-IF STRIPS
- TELEMETRY DECODERS
- DATA SYNCHRONIZERS
- SIGNAL RECONSTITUTION
- SIGNAL GENERATORS
- MODEMS
- TRACKING FILTERS
- SCA RECEIVERS
- FSK RECEIVERS
- WIDE BAND HIGH LINEARITY DETECTORS
- SYNCHRONOUS DETECTORS
- AM RECEIVER

# SIGNETICS ■ 561 – PHASE LOCKED LOOP

## GENERAL ELECTRICAL CHARACTERISTICS

(15K $\Omega$  Pin 9 to GND, Input Pin 12 or Pin 13 AC Ground Unused Input, Optional Controls Not Connected, V+ = 18V Unless Otherwise Specified T<sub>A</sub> = 25°C)

CHARACTERISTICS	LIMITS				TEST CONDITIONS
	MIN	TYP	MAX	UNITS	
Lowest Practical Operating Frequency	15	0.1		Hz	Measured at 2 MHz, with both inputs AC grounded Measured at 2 MHz
Maximum Operating Frequency		30		MHz	
Supply Current	8	10	12	Ma	
Minimum Input Signal for Lock		100		$\mu$ V	
Dynamic Range		60		dB	
VCO Temp Coefficient*		$\pm 0.06$	$\pm 0.12$	%/°C	
VCO Supply Voltage Regulation		$\pm 0.3$	$\pm 2$	%/V	
Input Resistance		2		k $\Omega$	
Input Capacitance		4		pF	
Input DC Level		+4		V	
Output DC Level	+12	+14	+16	V	Measured at Pin 9 See Figure 3
Available Output Swing		4		V <sub>p-p</sub>	
AM Rejection*	30	40		dB	
De-emphasis Resistance		8		k $\Omega$	

\*ACC Test Sub Group C.

## ELECTRICAL CHARACTERISTICS (For FM Applications, Figure 2) (15K $\Omega$ Pin 9 to GND, Input Pin 12 or 13, AC Ground Unused Input, Optional Controls Not Connected, V+ = 18V Unless Otherwise Specified T<sub>A</sub> = 25°C)

CHARACTERISTICS	LIMITS				TEST CONDITIONS
	MIN	TYP	MAX	UNITS	
10.7 MHz Operation                      Deviation 75 kHz    Source Impedance = 50Ω					
Detection Threshold	30	120	300	μV	Vin = 1 mv Rms    Modulation Frequency 1 kHz Vin = 1 mv Rms    Modulation Frequency 1 kHz Vin = 1 mv Rms    Modulation Frequency 1 kHz
Demodulated Output Amplitude		60		mV	
Distortion*		.3	1	% T.H.D.	
Signal to Noise Ratio $\frac{S + N}{N}$		35		dB	
4.5 MHz Operation                      Deviation = 25 kHz, Source Impedance = 50Ω					
Detection Threshold	30	120	300	μV	Vin = 1 mv Rms    Modulation Frequency 1 kHz Vin = 1 mv Rms    Modulation Frequency 1 kHz Vin = 1 mv Rms    Modulation Frequency 1 kHz
Demodulated Output Amplitude		60		mV	
Distortion		0.3	1.0	% T.H.D.	
Signal to Noise Ratio $\frac{S + N}{N}$		35		dB	
Wide Deviation                      ΔF/f <sub>0</sub> = 5% Input = 4.5 MHz    Deviation = 225 kHz @ 1 kHz modulation rate					
Detection Threshold	0.2	1	5	mV	Vin = 5 mv Rms Vin = 5 mv Rms Vin = 5 mv Rms
Demodulated Output		0.5		Vrms	
Distortion		0.8		% T.H.D.	
Signal to Noise Ratio $\frac{S + N}{N}$		50		dB	

\*ACC Test Sub Group C.

## ELECTRICAL CHARACTERISTICS (For Tracking Filter, Figure 1) (15K $\Omega$ Pin 9 to GND, Input Pin 12 or Pin 13 AC Ground Unused Input, Optional Controls Not Connected, V+ = 18V Unless Otherwise Specified T<sub>A</sub> = 25°C)

CHARACTERISTICS	LIMITS				TEST CONDITIONS
	MIN	TYP	MAX	UNITS	
Tracking Range	$\pm 5$	$\pm 20$		% of f <sub>0</sub>	Vin 5 mv Rms Input 2 MHz - See Characteristic Curves
Minimum Signal to Sustain Lock 0°C to 70°C		0.8		mv Rms	
VCO Output Impedance		1		k $\Omega$	Input 2 MHz Measured with high impedance. Probe with less than 10 pF capacitance.
VCO Output Swing	0.4	0.6		V <sub>p-p</sub>	
VCO Output DC Level		+6.5		V	Input 2 MHz with $\pm 100$ kHz Sideband Separation and 3 kHz Low Pass Filter. Input 1 mv Peak for Carrier and each Sideband C <sub>1</sub> = 0.01 $\mu$ F R <sub>1</sub> = 0
Side Band Suppression		35		dB	

**ELECTRICAL CHARACTERISTICS** (For AM Synchronous Detector, Figure 4) (15K $\Omega$  Pin 9 to GND, Input Pin 12 or Pin 13 AC Ground Unused Input, Optional Controls Not Connected,  $V_+ = 18V$  Unless Otherwise Specified  $T_A = 25^\circ C$ )

CHARACTERISTICS	LIMITS				TEST CONDITIONS
	MIN	TYP	MAX	UNITS	
Input Impedance		3		k $\Omega$	See Definition of Terms See Definition of Terms
Output Impedance		8		k $\Omega$	
Output DC Level	+10	+14	+17	V	
AM Conversion Gain	3	12		dB	
Out of Band Rejection		30		dB	
Distortion		1*		% T.H.D.	

### TYPICAL TEST CIRCUITS

TEST CIRCUIT FOR TRACKING FILTER

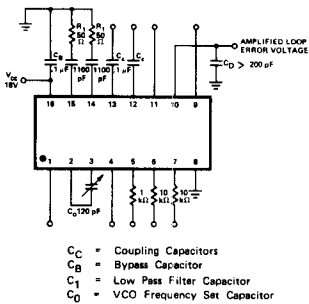


FIGURE 1

TEST CIRCUIT FOR AM REJECTION

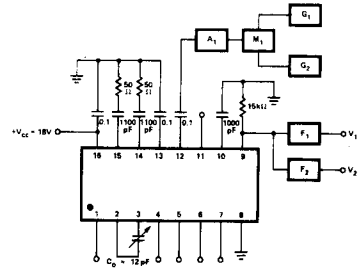


FIGURE 3

TEST CIRCUIT FOR FM DEMODULATION

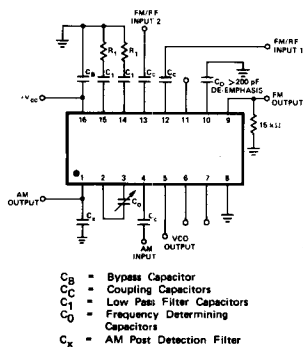


FIGURE 2

TEST CIRCUIT FOR AM SYNCHRONOUS DETECTOR

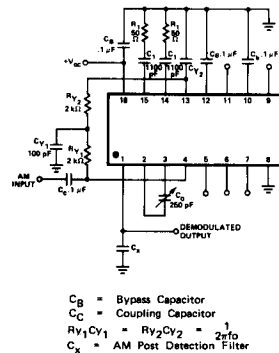
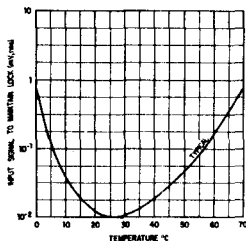


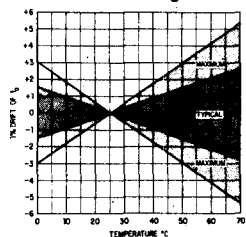
FIGURE 4

TYPICAL CHARACTERISTIC CURVES

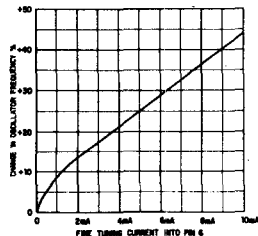
MINIMUM INPUT SIGNAL AMPLITUDE  
NECESSARY TO MAINTAIN LOCK AS A  
FUNCTION OF TEMPERATURE WITH  $f_{\text{signal}}$   
 $= f_{025^{\circ}\text{C}} = 2.0 \text{ MHz}$



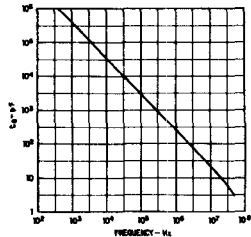
THERMAL DRIFT OF VCO FREE RUNNING  
FREQUENCY ( $f_0$ )



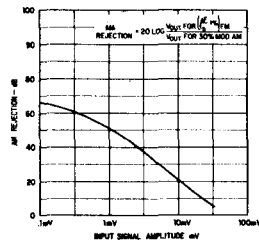
CHANGE OF FREE RUNNING OSCILLATOR  
FREQUENCY AS A FUNCTION OF RANGE  
CONTROL CURRENT



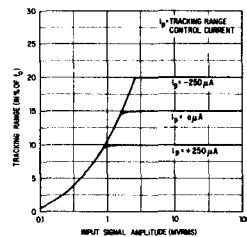
FREE RUNNING OSCILLATOR FREQUENCY  
AS A FUNCTION OF VCO TIMING CAPACITANCE



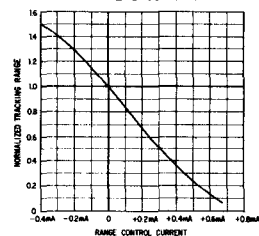
AM REJECTION AS A FUNCTION OF INPUT  
SIGNAL LEVEL  $f_0 = 10 \text{ MHz}$



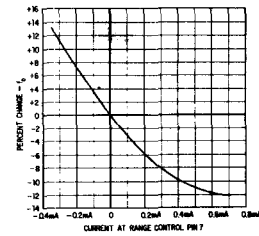
TYPICAL TRACKING RANGE AS A FUNCTION  
OF INPUT SIGNAL



CHANGE OF FREE RUNNING OSCILLATOR  
FREQUENCY AS A FUNCTION OF FINE  
TUNING CIRCUIT



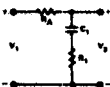
NORMALIZED TRACKING RANGE AS A  
FUNCTION OF RANGE CONTROL CURRENT



## EXTERNAL CONTROLS

## 1. Loop Low Pass Filter (Pins 14 and 15)

The equivalent circuit for the loop low-pass filter can be represented as:



where  $R_A$  ( $8k\Omega$ ) is the effective resistance seen looking into Pin #14 or Pin #15.

The corresponding filter transfer characteristics are:

$$\frac{V_2(s)}{V_1(s)} = F(s) = \frac{1 + sR_1C_1}{1 + s(R_1 + R_A)C_1}$$

where  $s$  is the complex frequency variable.

## 2. Loop Gain (Threshold) Control

The overall Phase Lock of loop gain can be reduced by connecting a feedback resistor,  $R_F$ , across the low-pass filter terminals, Pins #14 and #15. This causes the loop gain and the detection sensitivity to decrease by a factor ( $\alpha < 1$ ), where

$$\alpha = \frac{R_F}{2R_A + R_F}$$

Reduction of loop gain may be desirable at high input signal levels ( $V_{in} > 30$  mV) and at high frequencies ( $f_p > 5$  MHz) where excessively high PLL loop gain may cause instability within the loop.

## 3. Tracking Range Control (Pin 7)

Any bias current,  $I_p$ , injected into the tracking range control, reduces the tracking range of the PLL by decreasing the output of the limiter. The variation of the tracking range and the center frequency, as a function of  $I_p$ , are shown in the characteristic curves with  $I_p$  defined positive going into the tracking range control terminal. This terminal is normally at a DC level of +0.8 Volts and presents an impedance of  $800\Omega$ .

## 4. External Fine Tuning (Pin 6)

Any bias current injected into the fine tuning terminal increases

the frequency of oscillation,  $f_o$ , as shown in the characteristic curves. This current is defined Positive into the fine tuning terminal. This terminal is at a typical DC level of +1.3 Volts and has a dynamic impedance of  $100\Omega$  to ground.

## 5. Offset Adjustment (Pin 11)

Application of a bias voltage to the offset adjustment terminal modifies the current in the output amplifier setting the DC level at the output. The effect on the loop is to modify the relationship between the VCO free running frequency and the lock range, allowing the VCO free running frequency to be positioned at different points throughout the lock range.

Nominally this terminal is at +4V DC and has an input impedance of  $3k\Omega$ . The offset adjustment is optional. The characteristics specified correspond to operation of the circuit with this terminal open circuited.

## 6. De-emphasis Filter (Pin 10)

The de-emphasis terminal is normally used when the PLL is used to demodulate Frequency Modulated Audio signals. In this application, a capacitor from this terminal to ground provides the required de-emphasis. For other applications, this terminal may be used for band shaping the output signal. The 3 dB bandwidth of the output amplifier in the system block diagram (see Figure 2) is related to the de-emphasis capacitor,  $C_D$ , as:

$$f_{3dB} = \frac{1}{2\pi R_D C_D}$$

where  $R_D$  is the  $8000$  ohm resistance seen looking into the de-emphasis terminal.

When the PLL system is utilized for signal conditioning, and the loop error voltage is not utilized, de-emphasis terminal should be AC grounded.

## 7. AM Post-Detection Filter (Pin 1)

The capacitor  $C_X$  connected between Pin #1 and ground serves as a low-pass filter for synchronous AM detection with a transfer characteristic,  $F_2(s)$ , given as:

$$F_2(s) = \frac{1}{1 + sR_X C_X}$$

where  $R_X = 8k\Omega$  is the resistance seen looking into Pin #1.