

# NTK - The Kernel Bible 2

## Jacobian Analysis

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10. febrúar 2024

### 1 Introduction

The last Kernel bible failed to account for all ANNs where the output is not a scalar. In the Kernel Bible 2, we will observe how the NTK kernel is computed if our network function can be written as:

$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m \quad (1)$$

### 2 Setup

If equation 1 holds true, then  $f_\theta$  can be modeled as such:

$$f(x) = \begin{bmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_m(x_1, \dots, x_n) \end{bmatrix} \quad (2)$$

Where each  $f_i$   $i = 1, 2, \dots, n$  is a function described by the model's parameters. All parameters (individual weights and biases) are stored in the  $\theta$  vector:

$$\theta = \begin{bmatrix} W_{1,1}^{[1]} \\ \vdots \\ B_{1,1}^{[1]} \\ \vdots \\ W_{1,1}^{[p]} \\ \vdots \\ B_{[1]}^{[p]} \\ \vdots \\ B_{[m]}^{[p]} \end{bmatrix} \quad (3)$$

Where  $p - 1$  is number of hidden layers

## 2.1 Premise

Previously, the model returned a scalar so our Kernel was constructed from individuals gradients:

$$K_{i,j} = \nabla f_{\theta}(x_i)^T \nabla f_{\theta}(x_j)$$

But if our model can be written to the format of equation 2, our entry for the Kernel becomes:

$$K_{i,j} = \begin{bmatrix} \sum_k \frac{\partial f_1(x_i)}{\partial \theta_k} \frac{\partial f_1(x_j)}{\partial \theta_k} & \cdots & \sum_k \frac{\partial f_1(x_i)}{\partial \theta_k} \frac{\partial f_m(x_j)}{\partial \theta_k} \\ \vdots & \ddots & \vdots \\ \sum_k \frac{\partial f_m(x_i)}{\partial \theta_k} \frac{\partial f_1(x_j)}{\partial \theta_k} & \cdots & \sum_k \frac{\partial f_m(x_i)}{\partial \theta_k} \frac{\partial f_m(x_j)}{\partial \theta_k} \end{bmatrix} \quad (4)$$

Where  $k$  is the number of parameters in  $\theta$ .

So  $K$  is defined to be a Block matrix with each  $K_{i,j} \in \mathbb{R}^{m \times m}$ .

Let  $N$  represent the number of datapoints. Then  $K \in \mathbb{R}^{N(m \times m)}$

## 2.2 Jacobian Approach

Let  $Df_{\theta}(x)$  represent the Jacobian matrix of our model  $f$  with respect to all parameters  $\theta$ , evaluated at datapoint  $x$ :

$$Df_{\theta}(x) = \underbrace{\begin{bmatrix} \frac{\partial f_1(x)}{\partial \theta_1} & \cdots & \frac{\partial f_m(x)}{\partial \theta_1} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_1(x)}{\partial \theta_k} & \cdots & \frac{\partial f_m(x)}{\partial \theta_k} \end{bmatrix}}_{k \times m} \quad (5)$$

Then each entry of  $K$  can greatly simplified:

$$K_{i,j} = [Df_{\theta}(x_i)]^T Df_{\theta}(x_j) \quad (6)$$

And therefore:

$$K = \begin{bmatrix} [Df_{\theta}(x_1)]^T Df_{\theta}(x_1) & \cdots & [Df_{\theta}(x_1)]^T Df_{\theta}(x_N) \\ \vdots & \ddots & \vdots \\ [Df_{\theta}(x_N)]^T Df_{\theta}(x_1) & \cdots & [Df_{\theta}(x_N)]^T Df_{\theta}(x_N) \end{bmatrix} \quad (7)$$