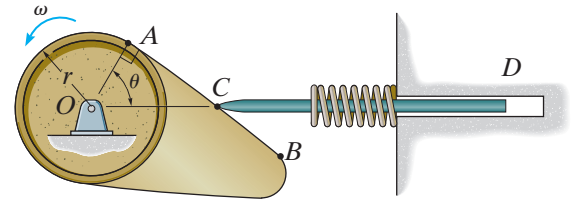


**\*16–44.**

Determine the velocity and acceleration of the follower rod  $CD$  as a function of  $\theta$  when the contact between the cam and follower is along the straight region  $AB$  on the face of the cam. The cam rotates with a constant counterclockwise angular velocity  $\omega$ .



**SOLUTION**

**Position Coordinate:** From the geometry shown in Fig.  $a$ ,

$$x_C = \frac{r}{\cos \theta} = r \sec \theta$$

**Time Derivative:** Taking the time derivative,

$$v_{CD} = \dot{x}_C = r \sec \theta \tan \theta \dot{\theta}$$

Here,  $\dot{\theta} = +\omega$  since  $\omega$  acts in the positive rotational sense of  $\theta$ . Thus, Eq. (1) gives

$$v_{CD} = r\omega \sec \theta \tan \theta \rightarrow$$

**Ans.**

The time derivative of Eq. (1) gives

$$a_{CD} = \ddot{x}_C = r[\sec \theta \tan \theta \ddot{\theta} + \dot{\theta}[\sec \theta (\sec^2 \theta \dot{\theta}) + \tan \theta (\sec \theta \tan \theta \dot{\theta})]]$$

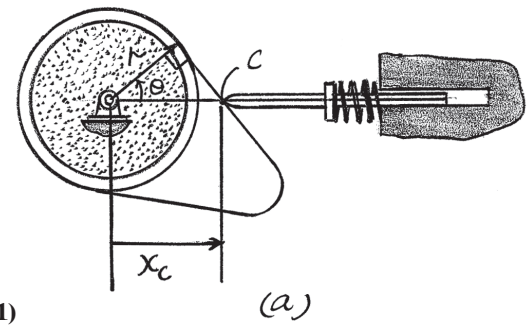
$$a_{CD} = r[\sec \theta \tan \theta \ddot{\theta} + (\sec^3 \theta + \sec \theta \tan^2 \theta) \dot{\theta}^2]$$

Since  $\dot{\theta} = \omega$  is constant,  $\ddot{\theta} = \alpha = 0$ . Then,

$$a_{CD} = r[\sec \theta \tan \theta (0) + (\sec^3 \theta + \sec \theta \tan^2 \theta) \omega^2]$$

$$= r\omega^2 (\sec^3 \theta + \sec \theta \tan^2 \theta) \rightarrow$$

**Ans.**



**Ans:**

$$v_{CD} = r\omega \sec \theta \tan \theta \rightarrow$$

$$a_{CD} = r\omega^2 (\sec^3 \theta + \sec \theta \tan^2 \theta) \rightarrow$$