RBE3002 Lab3: Mobile Robot Path Planning

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Lab Sign-offs

TASK	SIGNED BY	DATE/TIME
Prelab		
RViz configuration	EL	4/30
Loading the map	1	
Coloring the map		
A*	- Mill	4/4
Waypoints	M	4/4
Extra Credit		
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Grading Rubric

[100 points] All pre-lab and in-lab procedures are completed and demonstrated prior to the deadline. All deliverables and sign-off sheet are submitted on time. The code is well commented and structured.