

Tarea 3

Integrantes:

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Librerías que utilizaremos:

```
1 using Pkg, PlutoUI, Graphs, GLMakie, GraphMakie, Makie.Colors,  
   GraphMakie.NetworkLayout, Random, CSV, DataFrames, Plots, Statistics
```

Primer Punto

a) Use un algoritmo MCMC, para generar 100 muestras *aproximadas* ($X_{10^3}, X_{10^4}, X_{10^5}$) del modelo de Ising, con inversos de temperatura $\beta = 0, 0.1, \dots, 0.9, 1$

Solución:

Definamos el valor de k :

5

```
1 k
```

5

```
1 @bind k PlutoUI.Slider(5:20; default = 5, show_value = true) # Tamaño grilla
```

Inicialicemos el grafo reticular, haciendo uso de la librería *Graphs*:

```

▶[(0.0, 0.0), (0.0, 0.1), (0.0, 0.2), (0.0, 0.3), (0.0, 0.4), (0.1, 0.0), (0.1, 0.1), (0.1, 0.2), (0.1, 0.3), (0.1, 0.4), (0.2, 0.0), (0.2, 0.1), (0.2, 0.2), (0.2, 0.3), (0.2, 0.4), (0.3, 0.0), (0.3, 0.1), (0.3, 0.2), (0.3, 0.3), (0.3, 0.4), (0.4, 0.0), (0.4, 0.1), (0.4, 0.2), (0.4, 0.3), (0.4, 0.4)]

1 begin
2   g_1a = Graphs.grid([k, k]) # Grafo reticular k x k
3   vcolor_1a = [:white for i in 1:nv(g_1a)];
4   custom_layout_1a = [(i,j) for i = 0:0.1:(k-1)*0.1 ) for j = 0:0.1:(
5     (k-1)*0.1)];
6   end

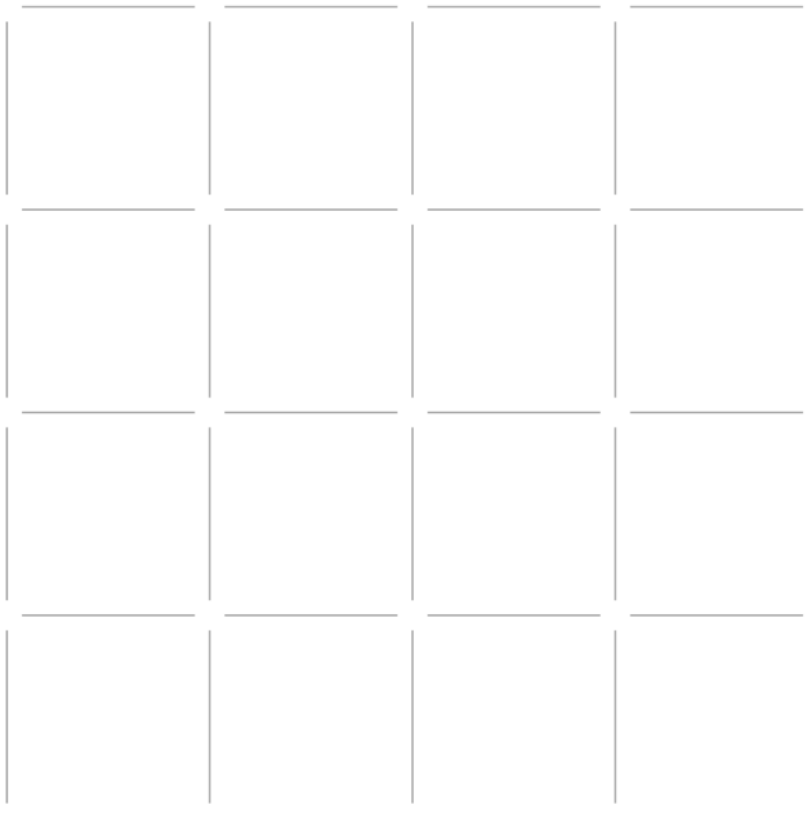
```

▶DataAspect()

```

1 begin
2   f_1a, ax_1a, p_1a = graphplot(g_1a; layout= custom_layout_1a,
3     node_color=vcolor_1a, edge_width=0.3, node_size=20);
4   hidedections!(ax_1a)
5   hidedspines!(ax_1a)
6   ax_1a.aspect = DataAspect()
7   # sup ilabels = 1:400
8 end

```



Definamos el valor de β :

```
beta_1a = 0.01
```

```
1 beta_1a = 0.01
```

neighbor_vertex (generic function with 1 method)

```
1 function neighbor_vertex(g, v, p)
2     k_plus = 0
3     k_minus = 0
4
5     for i in edges(g)
6         if src(i) == v
7             if p.node_color[][dst(i)] == :white
8                 k_minus += 1
9             elseif p.node_color[][dst(i)] == :black
10                k_plus += 1
11            end
12        elseif dst(i) == v;
13            if p.node_color[][src(i)] == :white
14                k_minus += 1
15            elseif p.node_color[][src(i)] == :black
16                k_plus += 1
17            end
18        end
19    end
20    return k_plus, k_minus
21 end
22
```

Implementamos el Gibbs sampler:

`gibbs_sampler` (generic function with 1 method)

```
1 # Construcción Gibbs Sampler
2
3 # -1 -> Blanco
4 # +1 -> Gris
5
6 function gibbs_sampler(g, p)
7     global k
8     v = rand( 1:k^2); # Seleccionar vértice aleatoriamente
9
10    k_plus_v, k_minus_v = neighbor_vertex(g, v, p) # Obtener número de vecinos
11                                           # con -1 y con +1.
12
13    u_n1 = rand()
14    # println(u_n1)
15    bound_upp = exp(2*beta_1a*(k_plus_v - k_minus_v)) / (exp(2*beta_1a*(k_plus_v -
16    k_minus_v)) + 1)
17    # println(bound_upp)
18
19    if u_n1 < bound_upp
20        p.node_color[][v] = :black
21        p.node_color = p.node_color[]
22    else
23        p.node_color[][v] = :white
24        p.node_color = p.node_color[]
25    end
26
27    # println(u_n1 < bound_upp)
28 end
```

Corremos la cadena con un total de 10^5 pasos:

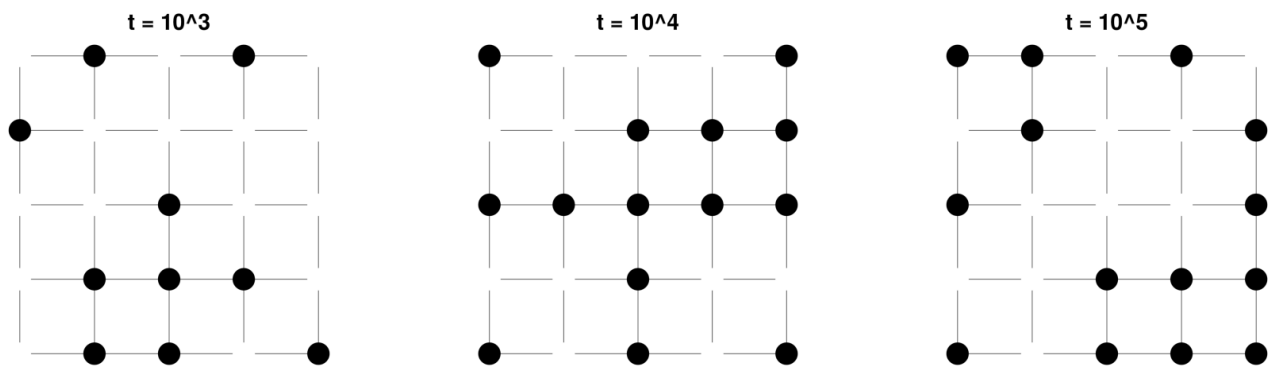
```
1 begin
2     states = []
3     Random.seed!(100) # Semilla para replicar resultados
4     for i in range(1, 10^5)
5         gibbs_sampler(g_1a, p_1a)
6         if i in [10^3, 10^4, 10^5]
7             push!(states, copy(p_1a.node_color[]))
8         end
9     end
10 end
```

Visualicemos X_{10^3} , X_{10^4} y X_{10^5} :

```
Makie.Label()
```

```
1 begin
2     fig_ = Figure(size = (900, 300))
3     axes_ = [Axis(fig_[1, i], aspect = DataAspect()) for i in 1:3]
4     for (i, state) in enumerate(states)
5         graphplot!(axes_[i], g_1a; layout=custom_layout_1a,
6             node_color=state, edge_width=0.3, node_size=20)
7         hidedecorations!(axes_[i])
8         hidespines!(axes_[i])
9         axes_[i].title = "t = 10^$(i+2)"
10    end
11    fig_[0, :] = Label(fig_, "Evolución modelo de Ising ( $\epsilon = 0.01$ )", fontsize = 20)
12 end
```

Evolución modelo de Ising ($\epsilon = 0.01$)



```
1 fig_
```

neighbor_vertex_ (generic function with 1 method)

gibbs_sampler_ (generic function with 1 method)

Para generar las 100 muestras, consideremos $\beta = 0.1, 0.4, 0.9$.

```
beta_values = ▶ [0.1, 0.4, 0.9]
```

```
1 beta_values = [0.1, 0.4, 0.9]
```

Inicializamos un diccionario para guardar las muestras:

```
samples = ▶ Dict{}
```

```
1 samples = Dict{Float64, Vector{Vector{Vector{Symbol}}}}{}
```

Generamos las muestras por cada valor de β :

```

1 for beta in beta_values
2   Random.seed!(100) # Semilla para replicar resultados
3   samples[beta] = Vector{Vector{Vector{Symbol}}}()
4
5   # Generar 100 muestras para cada beta
6   for _ in 1:100
7     node_colors = [:white for i in 1:nv(g_1a)]
8     sample_states = Vector{Vector{Symbol}}()
9
10    # Correr Gibbs sampler
11    for i in 1:10^5
12      node_colors = gibbs_sampler_(g_1a, node_colors, beta)
13
14      # Guardar estados
15      push!(sample_states, copy(node_colors))
16    end
17
18    # Guardar estados de la muestra
19    push!(samples[beta], sample_states)
20  end
21 end

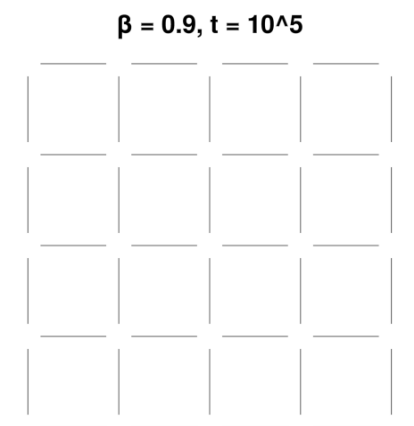
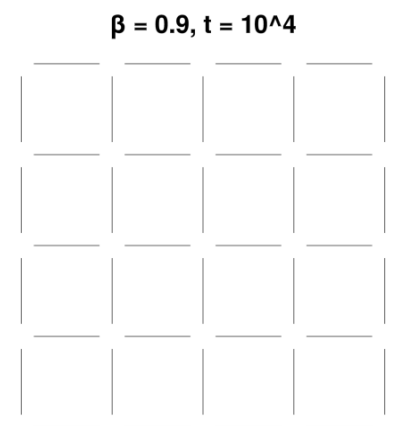
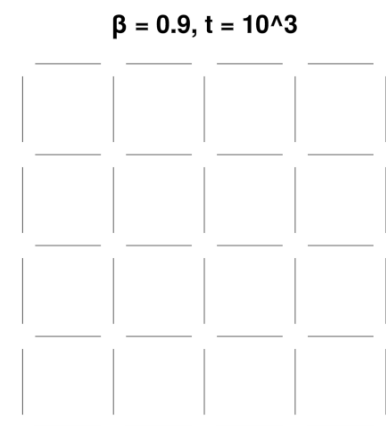
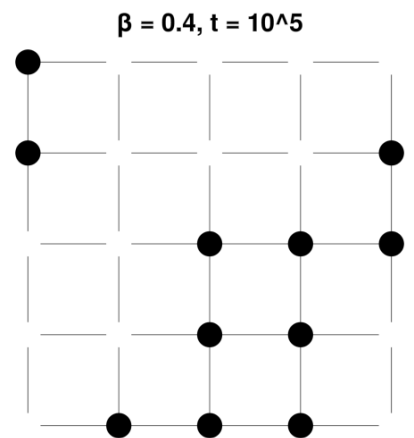
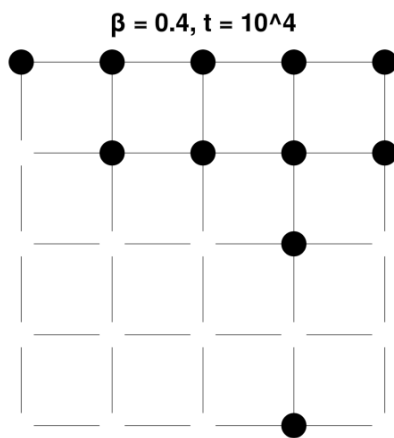
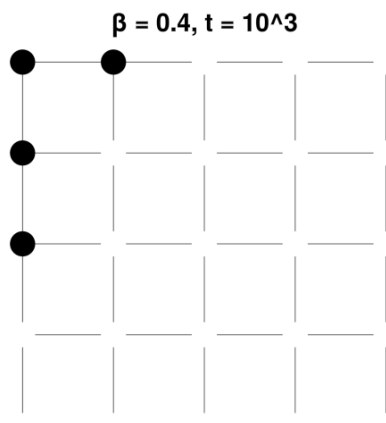
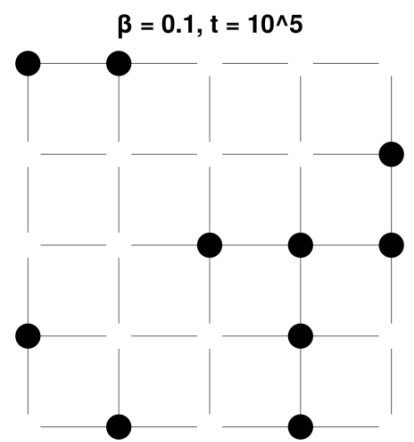
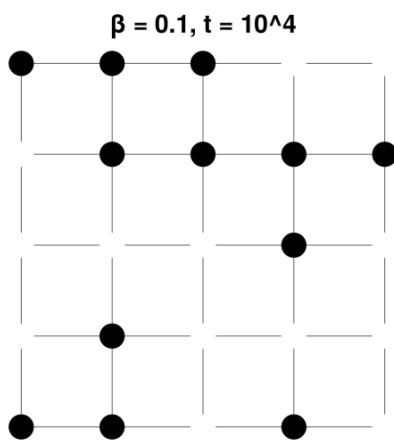
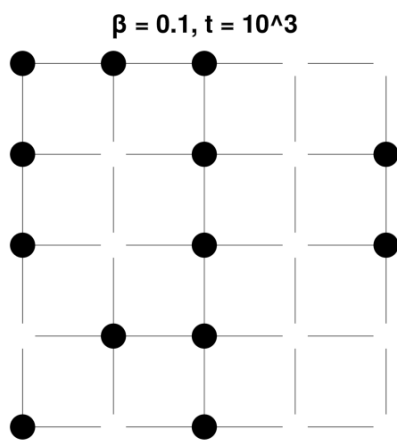
```

Creamos una figura para mostrar los resultados, visualizaremos los estados X_{10^3} , X_{10^4} y X_{10^5} de la última muestra obtenida para cada β .

```

1 begin
2   fig = Figure(size = (800, 800))
3   axes = [Axis(fig[i, j], aspect = DataAspect()) for i in 1:3, j in 1:3]
4   for (i, beta) in enumerate(beta_values)
5     for (j, j1) in enumerate([10^3, 10^4, 10^5])
6       state_index = j1 # 1 -> 10^3, 2 -> 10^4, 3 -> 10^5
7       node_colors = samples[beta][end][state_index]
8
9       graphplot!(axes[i, j], g_1a; layout=custom_layout_1a,
10        node_color=node_colors, edge_width=0.3, node_size=20)
11
12       hidedecorations!(axes[i, j])
13       hidespines!(axes[i, j])
14       axes[i, j].title = "β = $beta, t = 10^$(j+2)"
15     end
16   end
17 end

```



1 [fig](#)

Veamos algunas estadísticas:

```

1 for beta in beta_values
2   for (j, j1) in enumerate([10^3, 10^4, 10^5])
3     state_index = j1
4     avg_black = mean([count(x -> x == :black, sample[state_index]) for sample
in samples[beta]])
5     println("Para  $\beta = \$beta$ ,  $t = 10^{$(j+2)}$ , el promedio de nodos negros es:
$avg_black")
6   end
7 end

```

```

>
Para  $\beta = 0.1$ ,  $t = 10^3$ , el promedio de nodos negros es: 12.51
Para  $\beta = 0.1$ ,  $t = 10^4$ , el promedio de nodos negros es: 12.91
Para  $\beta = 0.1$ ,  $t = 10^5$ , el promedio de nodos negros es: 12.49
Para  $\beta = 0.4$ ,  $t = 10^3$ , el promedio de nodos negros es: 12.17
Para  $\beta = 0.4$ ,  $t = 10^4$ , el promedio de nodos negros es: 12.59
Para  $\beta = 0.4$ ,  $t = 10^5$ , el promedio de nodos negros es: 11.8
Para  $\beta = 0.9$ ,  $t = 10^3$ , el promedio de nodos negros es: 0.38
Para  $\beta = 0.9$ ,  $t = 10^4$ , el promedio de nodos negros es: 0.82
Para  $\beta = 0.9$ ,  $t = 10^5$ , el promedio de nodos negros es: 2.96

```

Podemos construir también una cadena Metropolis, y comparar los dos procedimientos.

metropolis_step (generic function with 1 method)

```

1 function metropolis_step(g, node_colors, beta)
2   v = rand(1:nv(g))
3   current_color = node_colors[v]
4   proposed_color = (current_color == :white) ? :black : :white
5
6   # Calcular el cambio en la energía
7   delta_E = 0
8   for neighbor in neighbors(g, v)
9     if node_colors[neighbor] == current_color
10      delta_E += 2
11    else
12      delta_E -= 2
13    end
14  end
15
16  # Calcular la probabilidad de aceptación
17  acceptance_prob = min(1, exp(-beta * delta_E))
18
19  # Decidir si aceptar el cambio
20  if rand() < acceptance_prob
21    node_colors[v] = proposed_color
22  end
23
24  return node_colors
25 end

```



```

run_metropolis (generic function with 1 method)
1 function run_metropolis(g, beta, num_steps)
2     node_colors = [:white for _ in 1:nv(g)]
3     samples = Vector{Vector{Symbol}}{]()
4
5     for step in 1:num_steps
6         node_colors = metropolis_step(g, node_colors, beta)
7
8         push!(samples, copy(node_colors))
9
10    end
11
12    return samples
13 end
14

```

Generamos las muestras:

```

1 begin
2     Random.seed!(100) # Semilla para replicar resultados
3     samples_m = Dict{Float64, Vector{Vector{Vector{Symbol}}}}{]()
4
5     for beta in beta_values
6         samples_m[beta] = [run_metropolis(g_1a, beta, 10^5) for _ in 1:100]
7     end
8 end

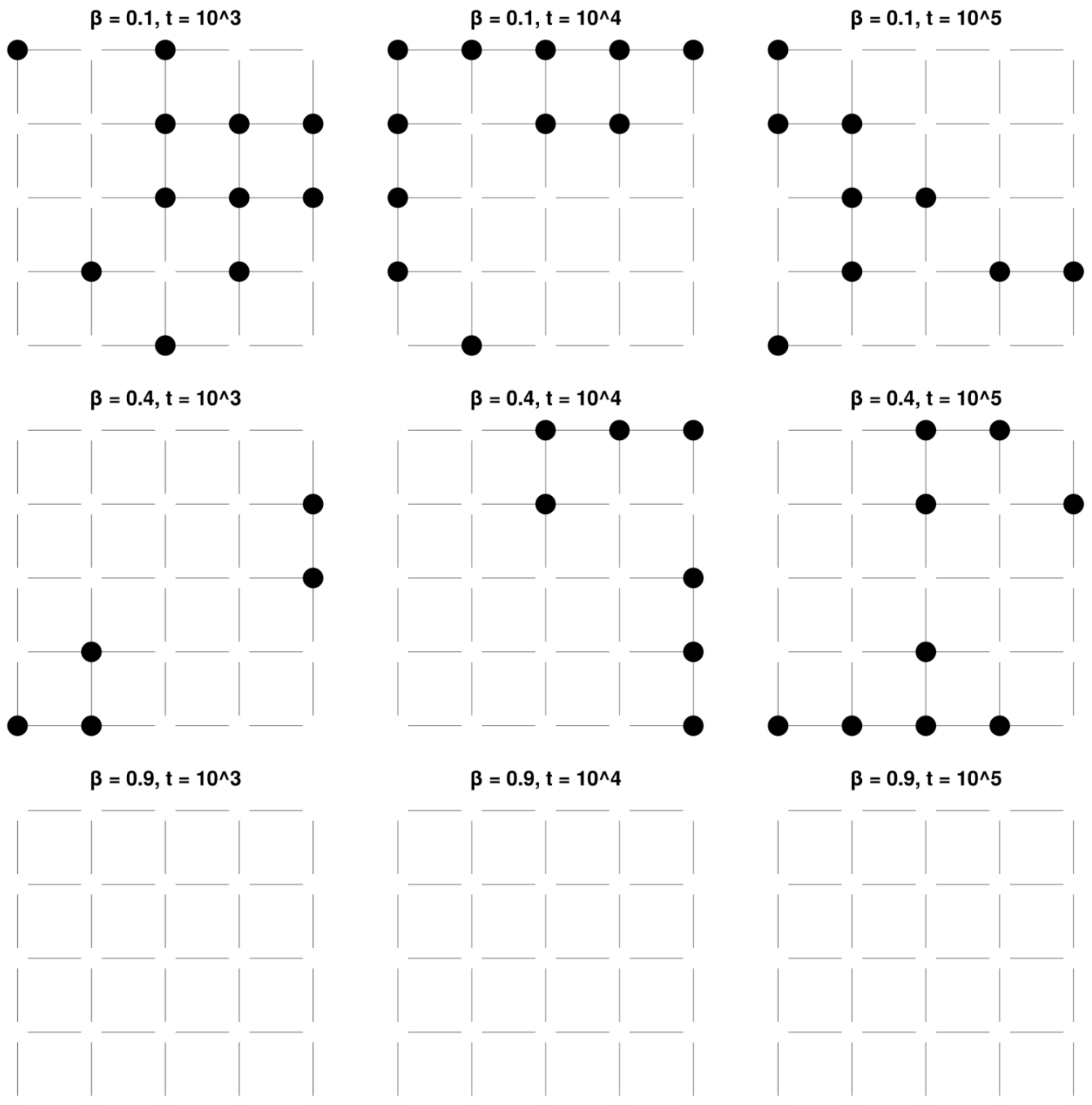
```

Y visualizamos los estados X_{10^3} , X_{10^4} y X_{10^5} de la última muestra obtenida para cada β :

```

1 begin
2     fig1 = Figure(size = (800, 800))
3     axes1 = [Axis(fig1[i, j], aspect = DataAspect()) for i in 1:3, j in 1:3]
4     for (i, beta) in enumerate(beta_values)
5         for (j, j1) in enumerate([10^3, 10^4, 10^5])
6             state_index1 = j1 # 1 -> 10^3, 2 -> 10^4, 3 -> 10^5
7             node_colors1 = samples_m[beta][end][state_index1]
8
9             graphplot!(axes1[i, j], g_1a; layout=custom_layout_1a,
10                 node_color=node_colors1, edge_width=0.3, node_size=20)
11
12             hidedeclarations!(axes1[i, j])
13             hidespines!(axes1[i, j])
14             axes1[i, j].title = "β = $beta, t = 10^$(j+2)"
15         end
16     end
17 end

```

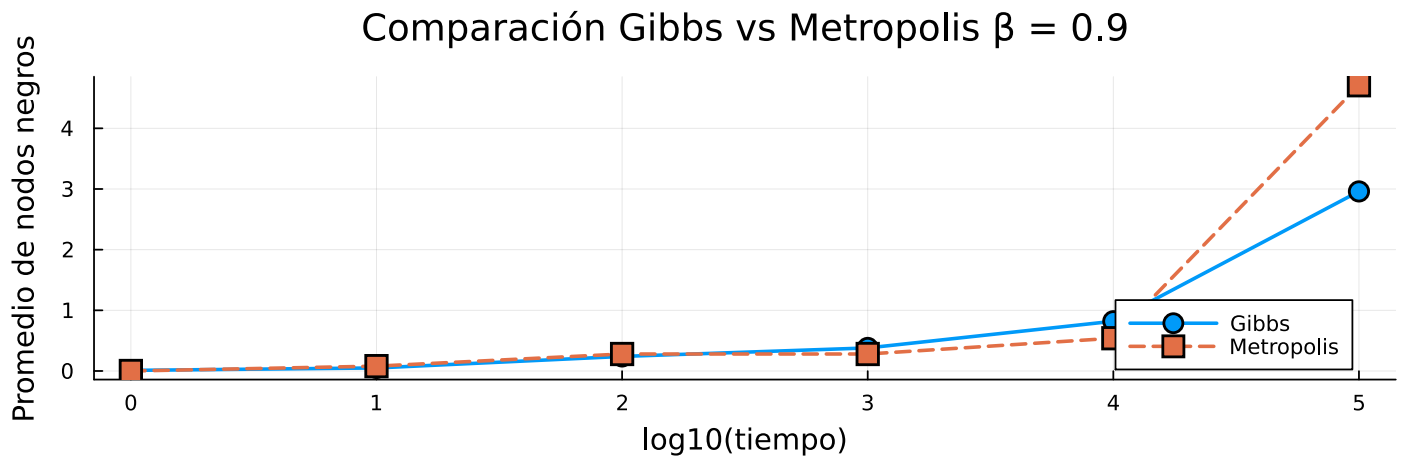
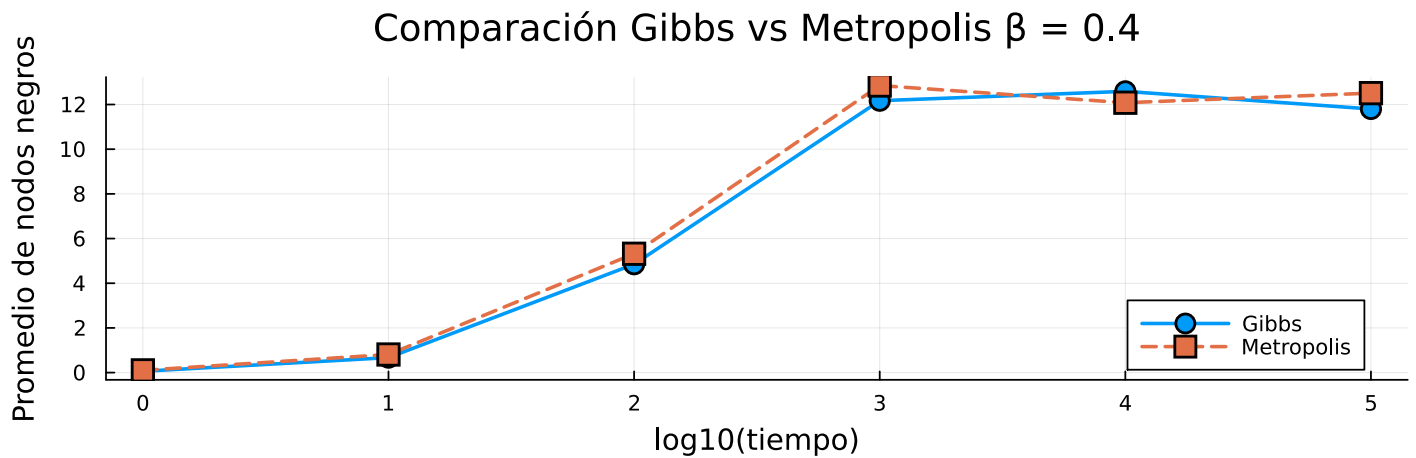
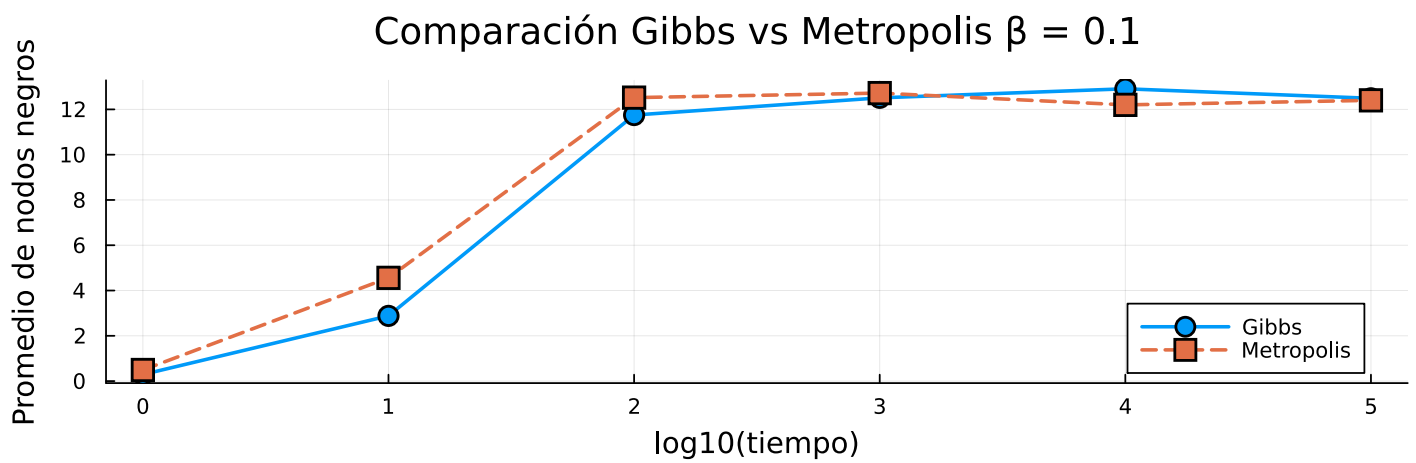


Veamos algunas estadísticas y comparemos con los resultados obtenidos con Gibbs sampler:



```
Para  $\beta = 0.1$ ,  $t = 10^3$ , el promedio de nodos negros es: 12.72
Para  $\beta = 0.1$ ,  $t = 10^4$ , el promedio de nodos negros es: 12.2
Para  $\beta = 0.1$ ,  $t = 10^5$ , el promedio de nodos negros es: 12.4
Para  $\beta = 0.4$ ,  $t = 10^3$ , el promedio de nodos negros es: 12.85
Para  $\beta = 0.4$ ,  $t = 10^4$ , el promedio de nodos negros es: 12.08
Para  $\beta = 0.4$ ,  $t = 10^5$ , el promedio de nodos negros es: 12.51
Para  $\beta = 0.9$ ,  $t = 10^3$ , el promedio de nodos negros es: 0.28
Para  $\beta = 0.9$ ,  $t = 10^4$ , el promedio de nodos negros es: 0.54
Para  $\beta = 0.9$ ,  $t = 10^5$ , el promedio de nodos negros es: 4.71
```





b) Use el algoritmo de Propp-Wilson para obtener **100** muestras exactas del modelo de Ising, tomando los mismos valores para β que en el inciso **a)**

Solución:

Tomamos el mismo orden parcial que vimos en clase, y tomamos los retículos donde todos los vértices son blancos ($O -1$) y donde todos los vértices son negros ($O +1$).

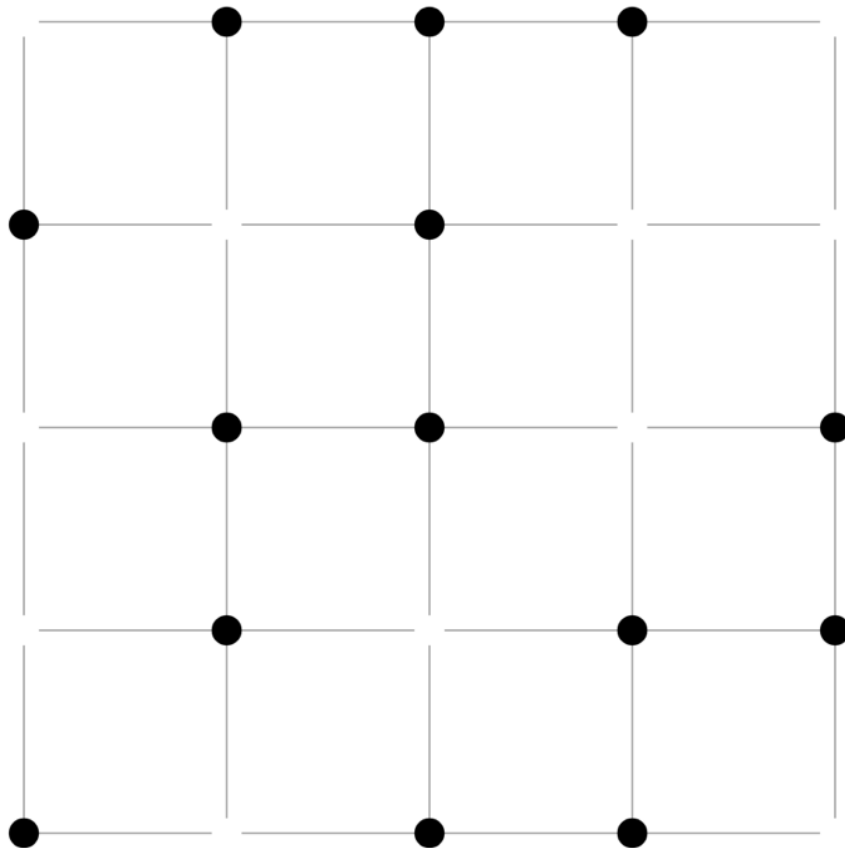
Propp_Wilson_iter (generic function with 1 method)

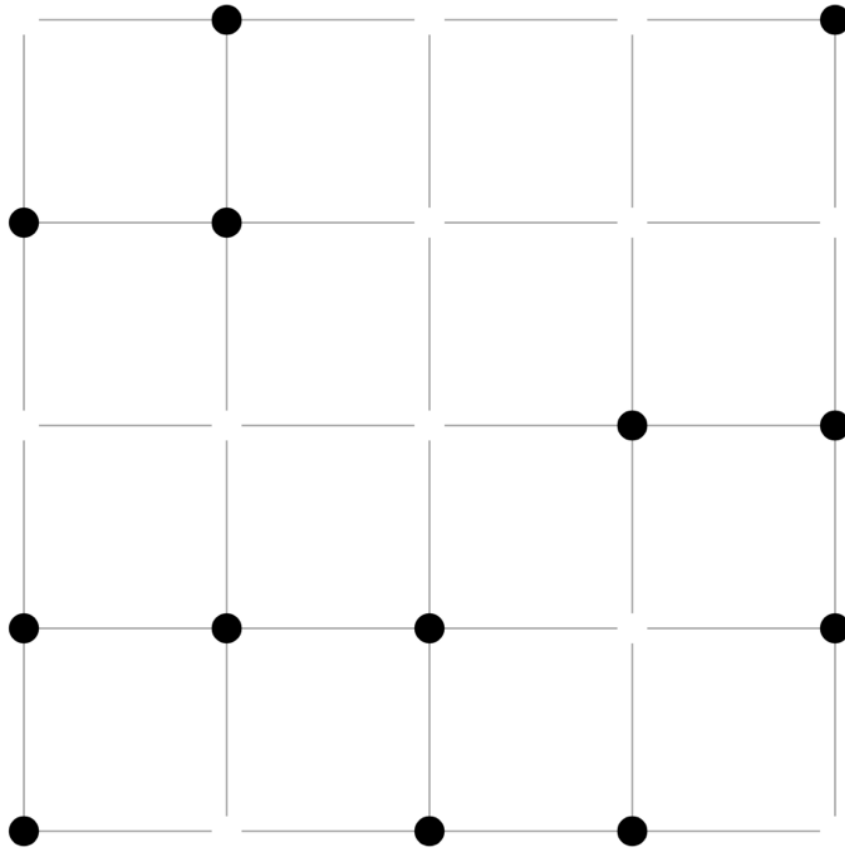
```
1 # Ejecutar Propp-Wilson con Sandwiching
2
3 function Propp_Wilson_iter(n) # time of starting: 2^n
4     g_min = Graphs.grid([k, k])
5
6     vcolor_min = [:white for i in 1:nv(g_min)]
7     custom_layout_min = [(i,j) for i = 0:0.1:( (k-1)*0.1 ) for j = 0:0.1:(
8         (k-1)*0.1 ) ]
9     f_min, ax_min, p_min = graphplot(g_min; layout= custom_layout_min,
10         node_color=vcolor_min, edge_width=0.3, node_size=20);
11
12     hidedecorations!(ax_min)
13     hidespines!(ax_min)
14     ax_min.aspect = DataAspect()
15
16     g_max = Graphs.grid([k, k])
17
18     vcolor_max = [:black for i in 1:nv(g_max)]
19     custom_layout_max = [(i,j) for i = 0:0.1:( (k-1)*0.1 ) for j = 0:0.1:( (k-1)*0.1
20         ) ]
21     f_max, ax_max, p_max = graphplot(g_max; layout= custom_layout_max,
22         node_color=vcolor_max, edge_width=0.3, node_size=20);
23
24     hidedecorations!(ax_max)
25     hidespines!(ax_max)
26
27     ax_max.aspect = DataAspect()
28
29     for i in -2^n:0
30         gibbs_sampler(g_min, p_min)
31         gibbs_sampler(g_max, p_max)
32     end
33
34     return (f_max, ax_max, p_max), (f_min, ax_min, p_min)
35
36 end
```

```

1 begin
2   m_ = 0
3   mi_ = 0
4   n = 1;
5   while true
6
7     Graph_max, Graph_min = Propp-Wilson_iter(n)
8
9     # println(Graph_max[3].node_color)
10    # println(Graph_min[3].node_color)
11
12    n += 1
13
14    if abs( count( i->(i == :black) , Graph_max[3].node_color[]) - count( i->
15      (i == :black), Graph_min[3].node_color[])) <= 1
16      m_ = Graph_max[1]
17      mi_ = Graph_min[1]
18      break
19    end
20  end
end

```





1 mi_

Propp_Wilson_iter_ (generic function with 1 method)

run_propp_wilson_ (generic function with 1 method)

Generamos las muestras utilizadas utilizando los valores β del punto anterior (0.1, 0.4, 0.9).

```

1 begin
2   samples_pw = Dict{Float64, Vector{Vector{Symbol}}}()
3   coalescence_times = Dict{Float64, Vector{Int}}()
4
5   for beta in beta_values # beta_values = [0.1, 0.4, 0.9]
6     samples_pw[beta] = Vector{Vector{Symbol}}()
7     coalescence_times[beta] = Vector{Int}()
8     for _ in 1:100
9       node_colors_, coalescence_time = run_propp_wilson_()
10      push!(samples_pw[beta], node_colors_)
11      push!(coalescence_times[beta], coalescence_time)
12    end
13  end
14 end

```

```

1 begin
2 igs = []
3 for beta in beta_values
4     avg_black_ = mean([count(x -> x == :black, sample) for sample in
5 samples_pw[beta]])
6     println("Para  $\beta$  = $beta, el número promedio de nodos negros es: $avg_black_")
7     push!(igs, histogram([count(x -> x == :black, sample) for sample in
8 samples_pw[beta]],
9         title="Distribución de nodos negros ( $\beta$  = $beta)",
10        xlabel="Número de nodos negros", ylabel="Frecuencia"))
11 savefig("propp_wilson_histogram_beta_$beta.png")
12 end
13 end

```



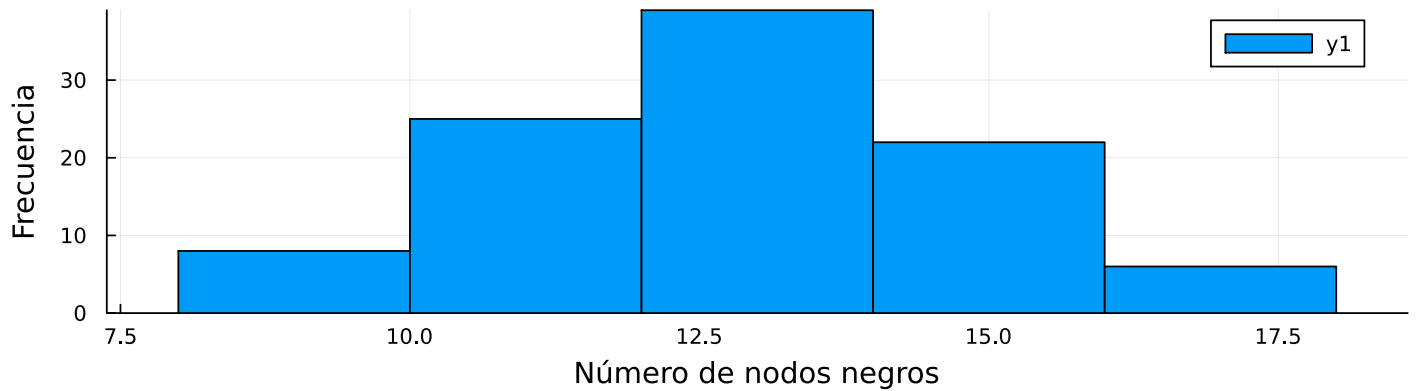
```

Para  $\beta$  = 0.1, el número promedio de nodos negros es: 12.37
Para  $\beta$  = 0.4, el número promedio de nodos negros es: 12.58
Para  $\beta$  = 0.9, el número promedio de nodos negros es: 12.15

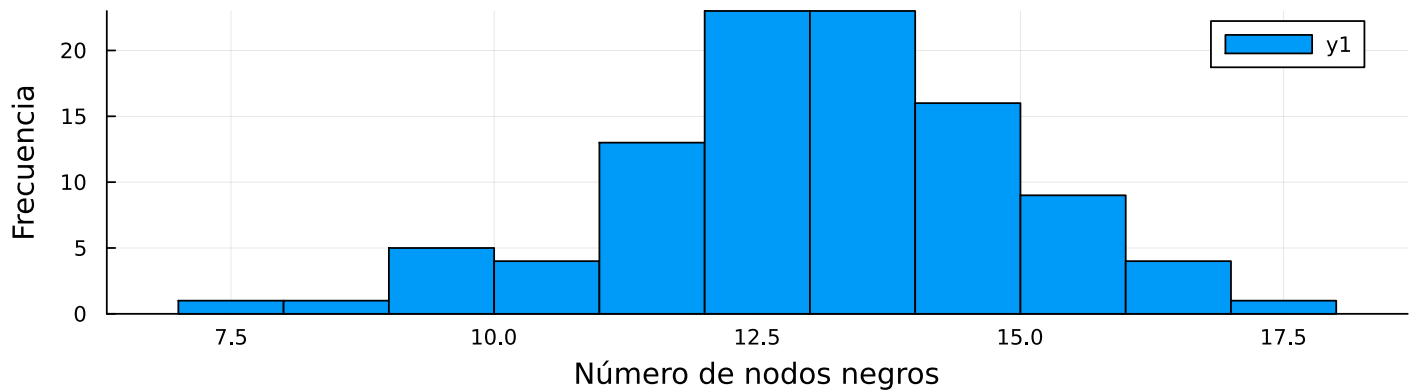
```



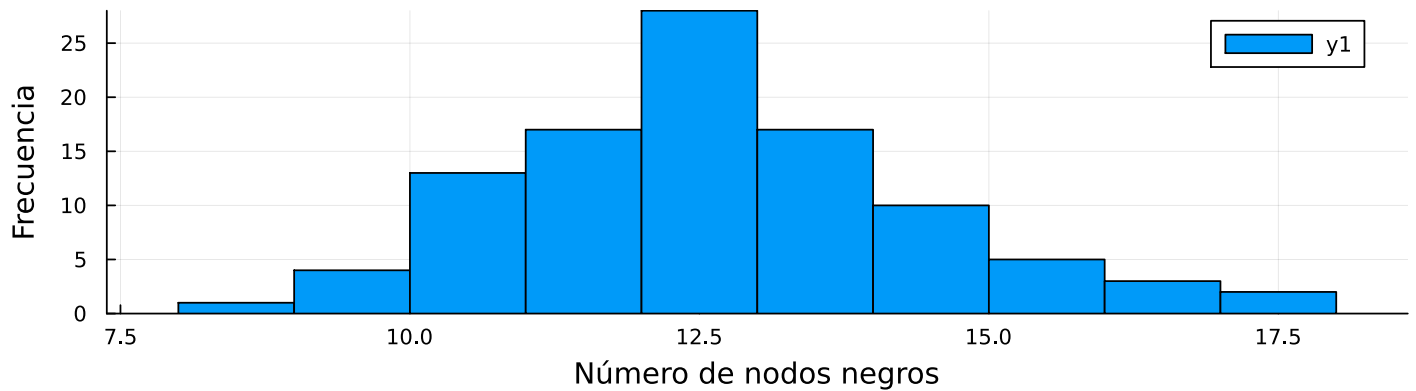
Distribución de nodos negros ($\beta = 0.1$)



Distribución de nodos negros ($\beta = 0.4$)



Distribución de nodos negros ($\beta = 0.9$)



```
1 Plots.plot(igs..., layout=plot_layout, size=(800, 800))
```

c) Estime con los incisos anteriores, $\mathbb{E}[M(\eta)]$, donde $M(\eta) = \frac{1}{|V_k|} \sum_{x \in V_k} \eta_x$

Reporte:

- Tiempo de coalescencia en P-W.
- Comparación de las estimativas obtenidas en c).

Solución:

Luego de realizar diferentes experimentos, obtuvimos los siguientes resultados:

- Tiempo de Coalescencia de Propp Wilson: Tomando varios tamaños para el grafo del modelo de Ising, tenemos los siguientes tiempos:

- * Para $k = 5$, el tiempo es
- * Para $k = 10$, el tiempo es
- * Para $k = 15$, el tiempo es

Podemos graficar los tiempos para los tamaños:

Segundo Punto

Una hormiga ha sido desajolada de su colonia ubicada en el punto $(0, 0)$ de la parcela $[0, 1] \times [0, 1]$. Decide entonces la hormiga visitar todas las otras 75 colonias de su parcela sin repetir.

Reporte:

- Esquema de enfriamiento usado.
- Distancia mínima obtenida.
- Mapa generado para la hormiga.

1 Enter cell code...

locations_ =

	Coordenada X	Coordenada Y
1	"0"	"0"
2	"0,640194804"	"0,8766190504"
3	"0,2934596053"	"0,3496503006"
4	"0,7900258247"	"0,9329749235"
5	"0,8887102598"	"0,240910138"
6	"0,9651210325"	"0,8005837321"
7	"0,6899746576"	"0,8337593556"
8	"0,240618119"	"0,2446297373"
9	"0,5374522203"	"0,1268334208"
10	"0,02671012213"	"0,299350216"
⋮ more		
76	"0,7520991723"	"0,07265280872"

```
1 locations_ = CSV.read("ant_points.csv", DataFrame)
```

```
► [0.0, 0.876619, 0.34965, 0.932975, 0.24091, 0.800584, 0.833759, 0.24463, 0.126833, 0.29935]
```

```
1 begin
2   locations__ = replace.(locations_, ",", ">");
3
4   x_points = parse.(Float64, locations__."Coordenada X");
5   y_points = parse.(Float64, locations__."Coordenada Y");
6 end
```

a) Use "simulated annealing" para ayudarle a la hormiga a encontrar el camino más corto que recorra todas las parcelas.

Solución:

dist_path (generic function with 1 method)

```
1 # function: distance of path.
2 function dist_path(x::Vector, y::Vector)
3
4     dist = 0.0
5     n = length(x_points)
6
7     for i in 1:(n-1)
8         dist += sqrt( (y[i+1] - y[i])^2 + ( x[i+1] - x[i] )^2 )
9     end
10
11     return dist
12
13 end
```

new_neighboor (generic function with 1 method)

```
1 # build a neighbor
2 function new_neighboor(x::Vector, y::Vector)
3
4     i = rand(2:76)
5     j = rand(i:76)
6
7     new_x = copy(x)
8     new_y = copy(y)
9
10    slice_reverse_x = reverse( new_x[i:j] )
11    slice_reverse_y = reverse( new_y[i:j] )
12
13    new_x[i:j] = slice_reverse_x
14    new_y[i:j] = slice_reverse_y
15
16    return new_x, new_y
17
18 end
```

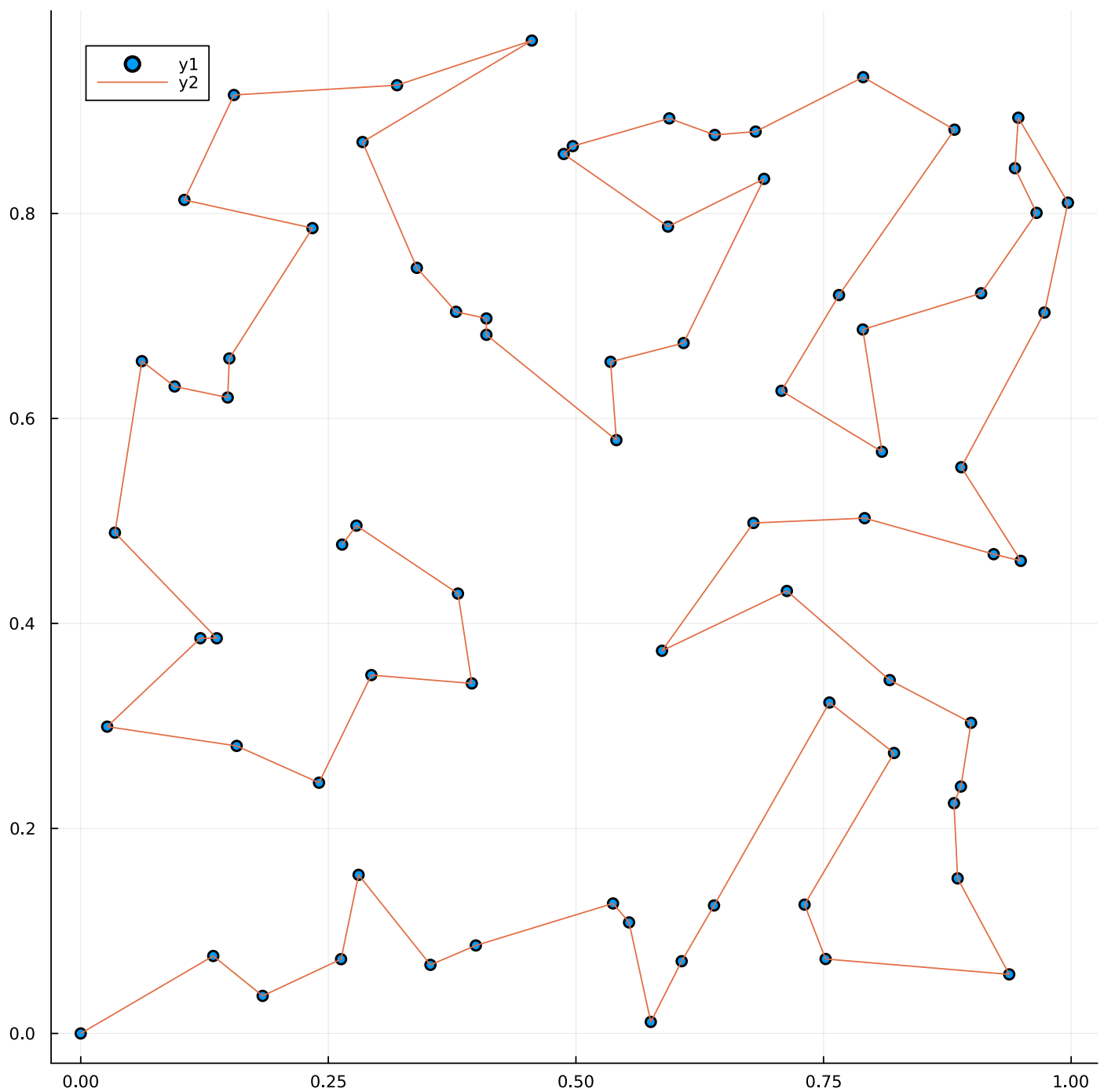
```

1 function simulated_annealing_1(x::Vector, y::Vector)
2
3     # Simulate Metropolis Chain
4     # cooling schedule (1, 1/10, 1/100, 1/1000, ...) and (1, 10, 100, 1000, ...)
5
6     curr_points = Dict( "x" => x, "y" => y )
7
8     # final_neighboor = (p2_x, p2_y)
9
10    n = 1
11
12    # execute markov chain with transition matrix given in class
13
14    while n < 7
15
16        for i in 1:10^n # max 10^6
17
18            T = 1/(10^n)
19
20            p2_x, p2_y = new_neighboor(curr_points["x"], curr_points["y"])
21
22            e = dist_path(curr_points["x"], curr_points["y"])
23            e_ = dist_path(p2_x, p2_y)
24
25            u = rand()
26
27            if u < min( 1, exp( (e - e_)/T ) )
28                curr_points = Dict( "x" => p2_x, "y" => p2_y )
29            #else
30            # final_neighboor = (curr_points["x"], curr_points["y"])
31            end
32
33        end
34        n += 1
35    end
36    return curr_points
37 end

```

```
► Dict("x" ⇒ [0.0, 0.133813, 0.183704, 0.262884, 0.280562, 0.353121, 0.398956, 0.537452, (
```

```
1 #gr(size = (800,800))
2 # scatter(x, y)
3 final_neighbor = simulated_annealing_1(x_points, y_points)
```



```

1 begin
2   gr(size = (800, 800))
3   Plots.scatter(x_points, y_points)
4   Plots.plot!(final_neighboor["x"], final_neighboor["y"])
5 end

```

7.668190062252601

```

1 dist_path(final_neighboor["x"], final_neighboor["y"])

```

b) Repita el ítem a) si se sabe que la hormiga retornará a su colonia original, después de haber recorrido todas las otras colonias.

Solución:

`x_points_b =`

► `[0.0, 0.640195, 0.29346, 0.790026, 0.88871, 0.965121, 0.689975, 0.240618, 0.537452, 0.026`

```
1 x_points_b = copy(x_points)
```

`y_points_b =`

► `[0.0, 0.876619, 0.34965, 0.932975, 0.24091, 0.800584, 0.833759, 0.24463, 0.126833, 0.2993`

```
1 y_points_b = copy(y_points)
```

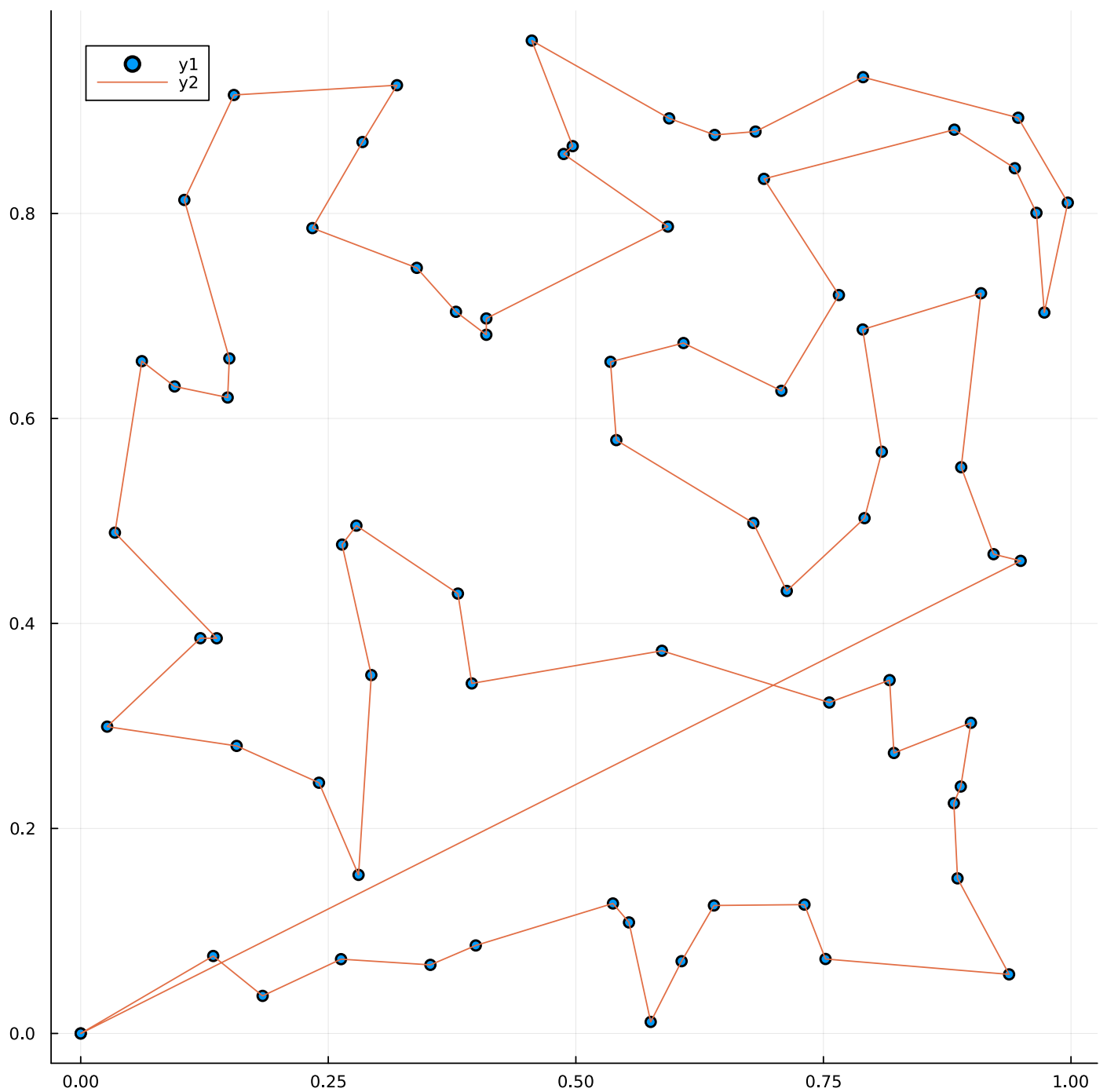
► `[0.0, 0.876619, 0.34965, 0.932975, 0.24091, 0.800584, 0.833759, 0.24463, 0.126833, 0.2993`

```
1 begin
2     push!(x_points_b, 0)
3     push!(y_points_b, 0)
4 end
```

`final_neighbor_b =`

► `Dict{"x" => [0.0, 0.133813, 0.183704, 0.262884, 0.353121, 0.398956, 0.537452, 0.553661, 0`

```
1 final_neighbor_b = simulated_annealing_1(x_points_b, y_points_b)
```



```

1 begin
2   gr(size = (800, 800))
3   Plots.scatter(x_points_b, y_points_b)
4   Plots.plot!(final_neighboor_b["x"], final_neighboor_b["y"])
5 end

```

7.3901119203276995

```

1 dist_path(final_neighboor_b["x"], final_neighboor_b["y"])
2
3 # Notar que para n = 7, ya no da un camino que minimice la distancia.

```

